





# Numerical Scattering Amplitudes with pySecDec: towards $q\overline{q} \rightarrow t\overline{t}H$ at two loops



Based on 2305.19768, 2402.03301, 2409.xxxx:

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## Outline

- 1. Numerical scattering amplitudes with pySecDec
- 2. Application to  $q\overline{q} \rightarrow t\bar{t}H$  production
- 3. Constructing an amplitude grid

## 1. Numerical Scattering Amplitudes with pySecDec

# Calculating an amplitude

• **Generation:** Write amplitude as sum of Feynman diagrams

$$\mathcal{A}_{\mathcal{V}} = \mathcal{A}_{\mathcal{V}}^{\mathrm{LO}} + \mathcal{A}_{\mathcal{V}}^{\mathrm{NLO}} + \mathcal{A}_{\mathcal{V}}^{\mathrm{NNLO}} + \cdots \sim \mathcal{A}_{\mathcal{V}}^{\mathrm{NNLO}} + \mathcal{A}_{\mathcal{V}}^{\mathrm{NNLO}} + \mathcal{A}_{\mathcal{V}}^{\mathrm{NNLO}} + \cdots \sim \mathcal{A}_{\mathcal{V}}^{\mathrm{NNLO}} + \mathcal{A}_{\mathcal{V}}^{\mathrm{NNLO}} + \mathcal{A}_{\mathcal{V}}^{\mathrm{NNLO}} + \mathcal{A}_{\mathcal{V}}^{\mathrm{NNLO}} + \cdots \sim \mathcal{A}_{\mathcal{V}}^{\mathrm{NNLO}} + \mathcal{A}_$$

- This results in a very large number of *linearly dependent* Feynman integrals
- **Reduction:** Find basis of *linearly independent* **master integrals** through IBP relations
- Evaluation: Evaluate the master integrals
  - With many loops, scales and legs this is very hard analytically
  - Resort to numerical solutions (pySecDec)

# Evaluating with pySecDec

Targets dimensionally regulated Feynman integrals

$$I \sim \int_0^\infty \prod_{j=1}^N \mathrm{d}x_j x_j^{\nu_j - 1} \delta(1 - \sum_{i=1}^N x_i) \frac{\mathcal{U}(\bar{x})^{N_\nu - (L+1)D/2}}{\mathcal{F}(\bar{x}, p^2, m^2)^{N_\nu - LD/2}} \qquad D = 4 - 2\varepsilon$$
$$N_\nu = \sum_{j=1}^N \nu_j$$

L loops

- Two-step process:
  - 1. Sector decomposition: Isolate and extract singularities as expansion in the regulator, **do once**
  - 2. Quasi-Monte Carlo (QMC) integration, **do once for each phase space point**

#### Sector Decomposition

• Transforms integral into sums of expansions in the regulator

$$I \to \sum_{\text{Sectors}} \sum_{n=-r}^{2L} C_n(p^2, m^2) \frac{1}{\varepsilon^n} + \mathcal{O}(\varepsilon^{r+1})$$
Parameter integrals

• Singularities are extracted as poles in regulator with simple subtraction terms

$$\int_0^1 \mathrm{d}x \, x^{-1-\varepsilon} \mathcal{I}(x,\varepsilon) = \frac{-1}{\varepsilon} \mathcal{I}(0,\varepsilon) + \underbrace{\int_0^1 \mathrm{d}x \, x^{-1-\varepsilon} [\mathcal{I}(x,\varepsilon) - \mathcal{I}(0,\varepsilon)]}_{\text{Finite piece, integrate numerically!}} = \frac{C_1}{\varepsilon} + C_0$$

## **Contour Deformation**

- Sector decomposition extracts endpoint singularities only
  - Kinematic (bulk) singularities are avoided with contour deformation
- Contour deformation works in most cases, but is computationally very expensive
  - New ideas to avoid having to use contour deformation [2407.06973], (see talk by Stephen Jones)

$$0 = \oint_{c} \prod_{j=1}^{N} \mathrm{d}z_{j} \mathcal{I}(\vec{z}) = \int_{0}^{1} \prod_{j=1}^{N} \mathrm{d}x_{j} \mathcal{I}(\vec{x}) + \int_{\gamma} \prod_{j=1}^{N} \mathrm{d}z_{j} \mathcal{I}(\vec{z}(\vec{x})) \xrightarrow{\mathrm{Im}(z)} \int_{0}^{1} \mathcal{I}(\vec{z}(\vec{x})) = \mathcal{F}(\vec{x}) - i \lambda \sum_{j} x_{j}(1 - x_{j}) \left(\frac{\partial \mathcal{F}}{\partial x_{j}}\right)^{2} + \mathcal{O}(\lambda^{2}) \xrightarrow{0} \xrightarrow{\mathrm{Im}(z)} \int_{0}^{1} \mathcal{I}(\vec{z}(\vec{x})) \xrightarrow{\mathrm{Im}(z)} \int_{0}^{1} \mathcal{I}(\vec{z}(\vec{x})) = \mathcal{I}(\vec{x}) - i \lambda \sum_{j} x_{j}(1 - x_{j}) \left(\frac{\partial \mathcal{F}}{\partial x_{j}}\right)^{2} + \mathcal{O}(\lambda^{2})$$
Complicates integrand massively

# **QMC** Integration

- Observation:  $\varepsilon \leq \text{Discrepancy}\{x_i\} \cdot V[\mathcal{I}]$ , take  $\{x_i\}$  from a low discrepancy sequence (R1SL-rule)
- Estimate of integral is achieved through random shifts
- Error convergence:  $\varepsilon_{MC} \sim \mathcal{O}\left(\frac{1}{\sqrt{n}}\right)$  and  $\varepsilon_{RQMC} \sim \mathcal{O}\left(\frac{1}{n}\right)$  $I[\mathcal{I}] \approx \bar{Q}_{n,m}[\mathcal{I}] \equiv \frac{1}{m} \sum_{k=0}^{m-1} Q_n^{(k)}[\mathcal{I}], \quad Q_n^{(k)}[\mathcal{I}] \equiv \frac{1}{n} \sum_{i=0}^{n-1} \mathcal{I}\left(\left(\frac{i\mathbf{z}}{n} + \Delta_k\right) \mod 1\right)$

Random samples (MC)





Random shifts (RQMC)

# 2. Application to $t\bar{t}H$ production

## Motivation

- Why is this an interesting process?
  - Direct sensitivity to the top-quark Yukawa coupling y<sub>t</sub>
  - Probe CP properties of y<sub>t</sub> [2208.02686 (CMS) 2303.05974 (ATLAS)]
- Projected statistical uncertainties for HL-LHC ~2-3% [Snowmass '22]
  - Systematics will dominate
- At NLO QCD scale uncertainties ~10-15%
  - NNLO QCD amplitude necessary to match precision
  - Approximations exist [2210.07846, 2402.00431] (see talks by Chiara Savoini and Guoxing Wang)

## Generation

- Generate Feynman diagrams and insert Feynman rules (Qgraf [1])
- Project amplitude onto the Born

$$\langle \mathcal{A}^{0} | \mathcal{A} \rangle = \langle \mathcal{A}^{0} | \mathcal{A}^{0} \rangle + \left(\frac{\alpha_{s}}{2\pi}\right) \langle \mathcal{A}^{0} | \mathcal{A}^{1} \rangle + \left(\frac{\alpha_{s}}{2\pi}\right)^{2} \langle \mathcal{A}^{0} | \mathcal{A}^{2} \rangle + \mathcal{O}(\alpha_{s}^{3})$$
  
 
$$\quad \text{Also:} \quad + \left(\frac{\alpha_{s}}{2\pi}\right)^{2} \langle \mathcal{A}^{1} | \mathcal{A}^{1} \rangle$$

- Spinor and colour summations (Form [2], COLOR.H [3], Alibrary [4])
- For the N<sub>f</sub> part [2402.03301] of the amplitude, this yielded ~20 000 scalar integrals
  - For the full  $q\overline{q}$  channel ~90 000 integrals

# **Reduction and Evaluation**

- Generation produces many *linearly dependent* integrals
  - IBP reduction reveals linear relations and allows construction of a basis of master integrals
- Ideally: solve the system of IBP equations symbolically once and for all
- In reality:
  - we have  $s_{12}, s_{23}, s_{34}, s_{45}, s_{51}, \; m_{H}^2, m_{t}^2, \; arepsilon$
  - Symbolic reductions are at the moment not possible
- Solution: plug in numbers for each variable and solve system numerically [5-7]
  - Need to solve the IBP system repeatedly for each phase space point ~ O(minutes)
- Evaluate linear combination of reduced integrals with pySecDec ~ O(minutes)
  - New in 1.6: Optimized for sums of integrals [2305.19768]

## 3. Constructing an Amplitude Grid

# Amplitude Grids

• Amplitudes are used to compute physical observables

$$\langle \mathcal{O} \rangle_{\Phi} = \int_{\bar{x} \in \Phi} \mathcal{O}(\bar{x}) \mathrm{d}\sigma(\bar{x})$$

- These integrals require millions of MC samples
  - Evaluation time of amplitude at 1 point ~ O(minutes)
  - Evaluation time of 1 observable ~ O(years)
- The solution is to evaluate the amplitude at a few points and interpolate for values in between
  - This implies there will be interpolation/grid uncertainties
  - How do these uncertainties propagate to observables?



# The Interpolation Problem

- Our goal: approximate  $a = |\mathcal{A}|^2$  with some  $\tilde{a}$  defined on the whole phase space, based on the knowledge of a at some data points
  - When the approximation error of  $\,\widetilde{a}\,$  is "small enough", the calculation is finished
- Two main questions:
  - 1. What should  $ilde{a}$  be? (polynomial, spline, neural network etc.)
  - 2. Where to evaluate a? (selecting interpolation nodes)
- Promising approximation methods we have investigated:
  - Chebyshev polynomials (global)
  - Sparse grids
  - Spline interpolation
  - Neural networks (GATr) [2405.14806]



Spatially adaptive sparse grid

# Why is this difficult?

- $2 \rightarrow 2$ : Usually 2 phase space variables
- $2 \rightarrow 3$ : Usually 5 phase space variables
- Points with increasing dimension:
  - Curse of dimensionality

	$q\overline{q} \rightarrow t\overline{t}$	$q\overline{q} \rightarrow t\overline{t}H$
Points per dim $\backslash$ Dimension	$\mathbf{d}=2$	$\mathbf{d} = 5$
10	100	100000
20	400	3200000
30	900	24300000

## **Error Estimation**

- Naive estimate:  $\varepsilon = \frac{1}{N_{MC}} \sum_{i=1}^{N_{MC}} |a(x_i) \tilde{a}(x_i)|$ , this often *overestimates* the error
  - A flat MC over-samples physically irrelevant regions of phase space
- Weight samples toward "relevant" phase space regions
- Define the "error" as the variational distance of the probability distributions

$$\varepsilon = \frac{||f - \tilde{f}||_1}{||f||_1} \quad , \quad f(x) = \frac{a(x)}{2\hat{s}} \left| \frac{\mathrm{d}(\Phi, \rho)}{\mathrm{d}x} \right| \quad ; \text{target probability density for } \sigma^{tot}$$

• Ensures the error on  $\sigma^{\text{tot}} \leq \varepsilon \left(\frac{\alpha_s}{2\pi}\right)^k ||f||_1$ 

• If 
$$\langle \mathcal{O} \rangle_{\Phi} = \sigma^{tot}$$
 then take  $x \sim \frac{1}{2\hat{s}} \mathrm{d}\Phi \,\mathrm{d}\rho_{a,b}(\hat{s})$  and MC integrate:  $\varepsilon = \frac{\sum_{i} |\widetilde{a}_{i} - a_{i}|}{\sum_{i} |a_{i}|}$ 

### How many validation points are required?

• "Waste" as few points as possible on validation : errors defined as 1-norms stabilize quickly



#### Comparison of Interpolation Methods



# Summary

- pySecDec is used to compute scattering amplitudes numerically
  - Current goal is the virtual amplitude to  $\,q\overline{q}
    ightarrow t\overline{t}H$  at NNLO
- Amplitude grids are required for combination with MC event generators
  - Especially for  $2 \rightarrow 3$  processes with slow numerical evaluation times
  - This requires careful consideration of grid uncertainties
  - Grids can be optimized towards specific observables through physical arguments
- Our goal is to have an interpolation framework that can handle  $2 \rightarrow 3$  scattering problems
- Next: apply to  $t\bar{t}H$  production and other processes

# Backup: QMC Integration

- Classical QMC error bound:  $\varepsilon \leq \text{Discrepancy}\{x_i\} \cdot V[\mathcal{I}]$  (Star disc. ; Hardy and Krause variation)
- Smooth integrands have:  $\mathcal{O}((\log n)^d/n)$  (dimension dependent?!)
- In certain *weighted function spaces* convergence becomes independent of dimension
- Example: Korobov space of periodic smooth functions
  - Our integrands are usually smooth but not periodic: Apply Korobov transformation
  - Differentiable integrands after Korobov transformation have:  $\mathcal{O}\left(\frac{1}{n}\right)$
  - Convergence is independent of dimension

## Backup: Latest pySecDec Release

- New QMC integrator "Disteval" (distributed evaluation)
  - Code improvements on CPU and GPU side
  - Up to an order of magnitude performance increase compared to previous versions
- Median generating vectors (new QMC lattice rule)
  - Avoids unlucky lattices
- Automated detection and insertion of extra regulators in EBR
  - Resolves spurious singularities introduced by EBR
- Increased practicality of amplitude calculations (sums of integrals)

## Backup: Disteval speed-up sources

- Reasons for speedup:
  - Separated GPU and CPU code generation enable hardware specific optimizations
  - Integrand samples are summed up on the GPU using the Nvidia CUB library
  - Support for the *Single Instruction, Multiple Data* (SIMD) instruction set
  - Reduced overhead (very significant for small integrands)



# Backup: Selecting an IBP basis

- An IBP basis is not unique, which master integrals should be selected?
- Four criteria: 1. finiteness, 2. D-factorising, 3. fast to evaluate with pySecDec,
  4. simple denominators in IBP coefficients
- Finiteness and D-factorisation is achieved by dimension shifts and dotted propagators
  - d=4,6,8 for most integrals (d=2 for some easy ones with 4 propagators)
  - 2 dots in most sectors, in some lower sectors there are more dots (up to 6 for a three propagator integral)
- Fast evaluation and simple denominators is done through trial and error
  - Generate a basis that fulfills finiteness and D-factorisation
  - Perform reductions while neglecting sub-sectors for sets of master integrals, select the set with smallest denominator factors
  - Benchmark which master integrals in this set are fast to evaluate with pySecDec
  - Repeat the process while restricting the basis to include the fast to evaluate masters

# Backup: Training Data

- Interpolation nodes ("data points") can be selected freely
  - Depends on the interpolation method
- Also: target function can be freely modified, try to get as flat function as possible!
  - Include/exclude phase space factors, PDF weights, flux factor
  - Other flattening techniques such as Korobov transformations?
  - Use symmetries of amplitude to get rid of some peaks
- We are creating *amplitude* grids: Undo all modifications to target function at evaluation
  - This can be difficult if certain integral transformations have been applied

#### Backup: Low dimensional case



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## References for software used in ttH

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