

Integrated Unitarity for Scattering Amplitudes

[2403.18047](#) & [2408.06325](#)

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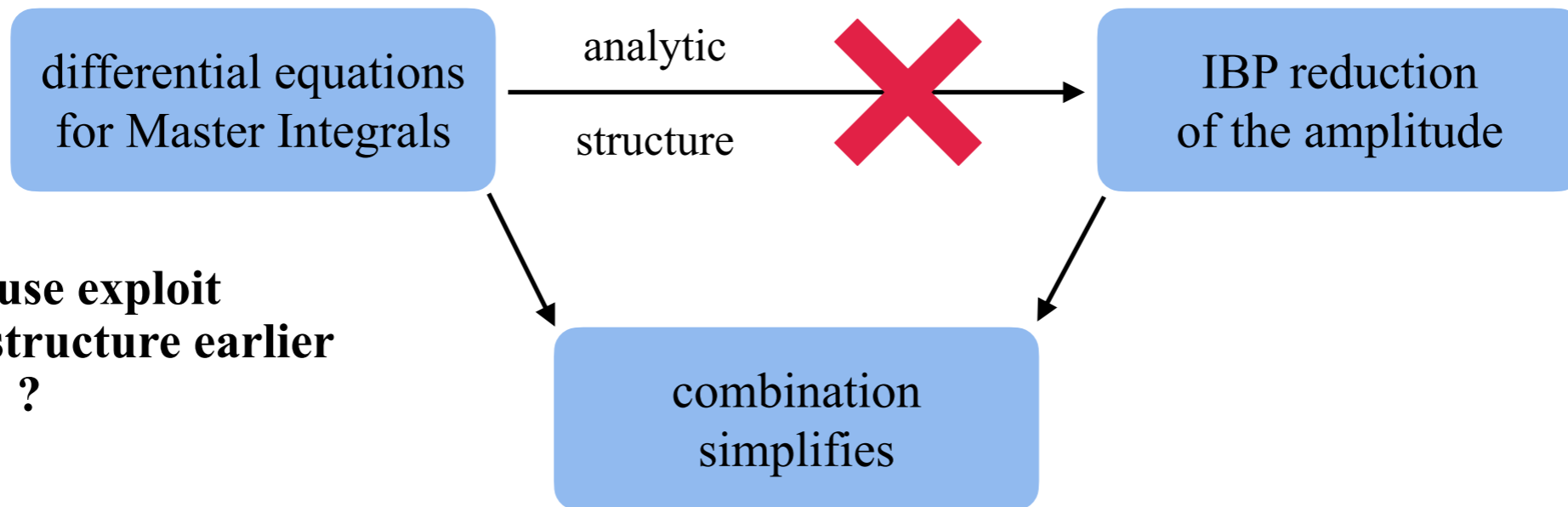
**Universität
Zürich**^{UZH}



European Research Council
Established by the European Commission

Introducing Integrated Unitarity

standard amplitude workflow



can we use exploit
the analytic structure earlier
?

YES : Integrated Unitarity

- dispersion relations : discontinuities algorithmic
- cut canonical differential equations (DEQ) : algorithmic in dimReg

[see Appendix for technical definitions]



- Generalized Unitarity @ integrated level : constrains both Master Integrals (MIs) and their coefficients using cuts
- less subsectors, less MIs, simpler DEQ and IBP system

Generalized VS Integrated Unitarity

consider a toy 1-loop amplitude

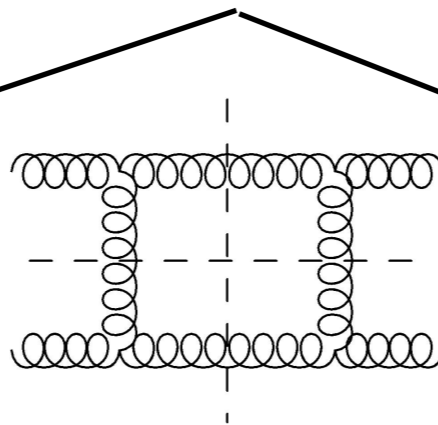
$$\mathcal{A}^{(1)} \sim \int \frac{d^d k}{(2\pi)^d} \frac{\mathcal{N}(k)}{\mathcal{D}_1(k) \mathcal{D}_2(k) \mathcal{D}_3(k) \mathcal{D}_4(k)} = r_{1234} \int \frac{d^d k}{(2\pi)^d} \frac{1}{\mathcal{D}_1(k) \mathcal{D}_2(k) \mathcal{D}_3(k) \mathcal{D}_4(k)} + \text{subsectors}$$

cut all 4 propagators

$$\text{Cut}_{1234} \mathcal{A}^{(1)} \sim \int \frac{d^d k}{(2\pi)^d} \mathcal{A}_1^{(0)}(k) \mathcal{A}_2^{(0)}(k) \mathcal{A}_3^{(0)}(k) \mathcal{A}_4^{(0)}(k) \delta^+(\mathcal{D}_1(k)) \delta^+(\mathcal{D}_2(k)) \delta^+(\mathcal{D}_3(k)) \delta^+(\mathcal{D}_4(k)) = r_{1234} \int \frac{d^d k}{(2\pi)^d} \delta^+(\mathcal{D}_1(k)) \delta^+(\mathcal{D}_2(k)) \delta^+(\mathcal{D}_3(k)) \delta^+(\mathcal{D}_4(k))$$

Generalized Unitarity

Integrated Unitarity



can compute integral coefficient

compute cut amplitude

$$r_{1234} = \frac{1}{2} \sum_{2 \text{ cut solns } k^*} \mathcal{A}_1^{(0)}(k^*) \mathcal{A}_2^{(0)}(k^*) \mathcal{A}_3^{(0)}(k^*) \mathcal{A}_4^{(0)}(k^*)$$

$$\text{Cut}_{1234} \mathcal{A}^{(1)} = r_{1234} \int \frac{d^d k}{(2\pi)^d} \delta^+(\mathcal{D}_1(k)) \delta^+(\mathcal{D}_2(k)) \delta^+(\mathcal{D}_3(k)) \delta^+(\mathcal{D}_4(k))$$

scalar integral remains to be computed

can reconstruct whole amplitude

$$\int \frac{d^d k}{(2\pi)^d} \frac{1}{\mathcal{D}_1(k) \mathcal{D}_2(k) \mathcal{D}_3(k) \mathcal{D}_4(k)}$$

$$\mathcal{A}^{(1)}(s, u) \sim \int_0^\infty \frac{ds'}{s' - s} \int_0^\infty \frac{du'}{u' - u} \text{Cut}_{1234} \mathcal{A}^{(1)}(s', u')$$

Dispersion relation

Cauchy's integral formula

$$x = -\frac{t}{s}$$

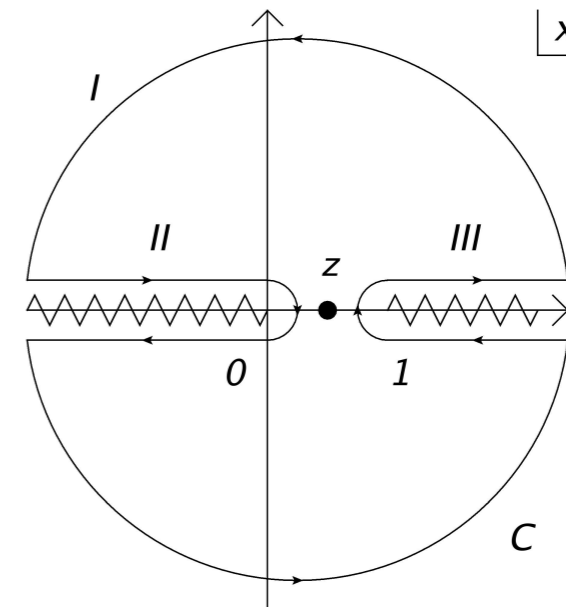
4-point massless

$$\mathcal{A}(z) = \frac{1}{2\pi i} \oint_C \frac{\mathcal{A}(x)dx}{x-z}$$

[Cutkosky, Mandelstam, Eden, Landshoff, Olive, Polkinghorne, Remiddi, van Neerven, Kniehl, Sirlin]

piecewise contour

$$\mathcal{A}(z) = c_\infty + \frac{1}{2\pi i} \left(\int_0^\infty \text{Disc}_0 + \int_1^\infty \text{Disc}_1 \right) \frac{\mathcal{A}(x)dx}{x-z}$$

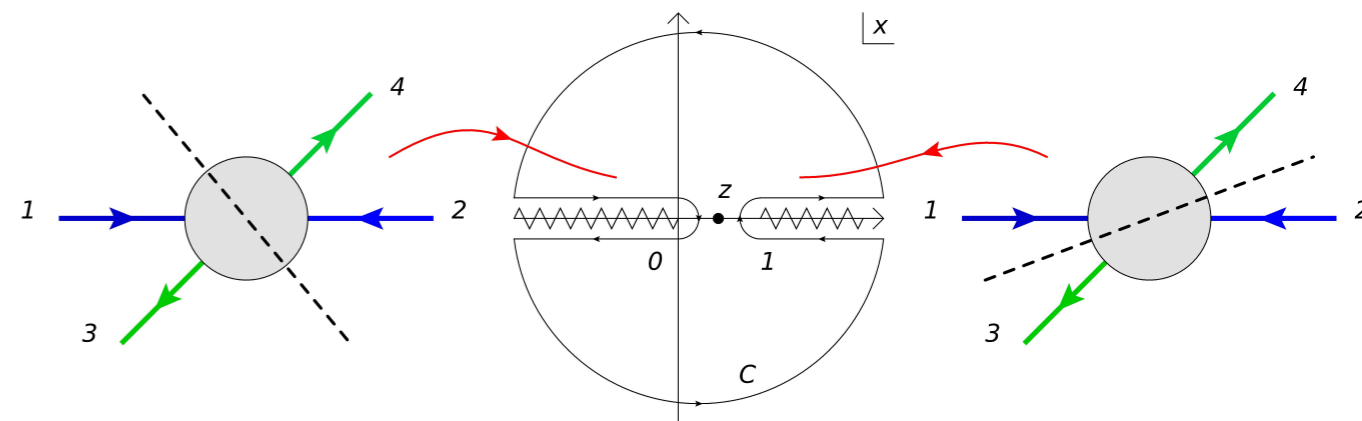


cancel constant from infinite arc

$$\mathcal{A}(z) = \mathcal{A}_0 + \frac{1}{2\pi i} \left(\int_0^\infty \text{Disc}_0 + \int_1^\infty \text{Disc}_1 \right) \left(\frac{1}{x-z} - \frac{1}{x-z_0} \right) \mathcal{A}(x)dx$$

unitarity

$$\mathcal{A}(z) = \mathcal{A}_0 + \frac{1}{2\pi i} \left(\int_0^\infty \text{Cut}_t + \int_1^\infty \text{Cut}_u \right) \left(\frac{1}{x-z} - \frac{1}{x-z_0} \right) \mathcal{A}(x)dx$$



Dispersion relation

$$\mathcal{A}(z) = \mathcal{A}_0 + \frac{1}{2\pi i} \left(\int_0^\infty \text{Cut}_t + \int_1^\infty \text{Cut}_u \right) \left(\frac{1}{x-z} - \frac{1}{x-z_0} \right) \mathcal{A}(x) dx$$

expressing cuts as phase space integrals

$$\begin{aligned} \mathcal{A}(z) = \mathcal{A}_0 + \frac{1}{2\pi i} & \left(\int_0^\infty \sum_{\{c_j\} \in \mathcal{C}_t} \int d\text{PS}_{t,\{c_j\}} \mathcal{A}_{t,\{c_j\},L} \mathcal{A}_{t,\{c_j\},R}^* \right. \\ & \left. + \int_1^\infty \sum_{\{c_j\} \in \mathcal{C}_u} \int d\text{PS}_{u,\{c_j\}} \mathcal{A}_{u,\{c_j\},L} \mathcal{A}_{u,\{c_j\},R}^* \right) \left(\frac{1}{x-z} - \frac{1}{x-z_0} \right) dx \end{aligned}$$

diagrammatically, in the planar case

Integrated Unitarity : 3 methods

$$\mathcal{A}(z) = \mathcal{A}_0 + \frac{1}{2\pi i} \left(\int_0^\infty \text{Cut}_t + \int_1^\infty \text{Cut}_u \right) \left(\frac{1}{x-z} - \frac{1}{x-z_0} \right) \mathcal{A}(x) dx$$

- A. explicit integration : convergent e.g. for canonical MIs
 subtraction terms needed for full amplitude

$$\mathcal{A}(x) \rightarrow S(x) \mathcal{A}(x) \quad S(x) = \frac{(1-x)^p x^q}{(x-z_1)^r} \quad -\text{Res}_{x \rightarrow z_1} \mathcal{A}(x) S(x) \left(\frac{1}{x-z} - \frac{1}{x-z_0} \right)$$

- B. ansatz reconstruction with 2 discontinuities + # evaluations :

$$\begin{cases} \text{Disc}_0 \mathcal{A} &= \text{Cut}_t \mathcal{A} \\ \text{Disc}_1 \mathcal{A} &= \text{Cut}_u \mathcal{A} \\ \mathcal{A}(z_i) &= \mathcal{A}_i \end{cases}$$

$$\mathcal{A}(z) = \epsilon^\# \sum_{n \geq 0} \epsilon^n \sum_{\vec{\alpha}: |\vec{\alpha}| \leq n} r_{n, \vec{\alpha}}(z) G(\vec{\alpha}, z)$$

↑
unknowns

- C. ansatz reconstruction with 3 discontinuities :

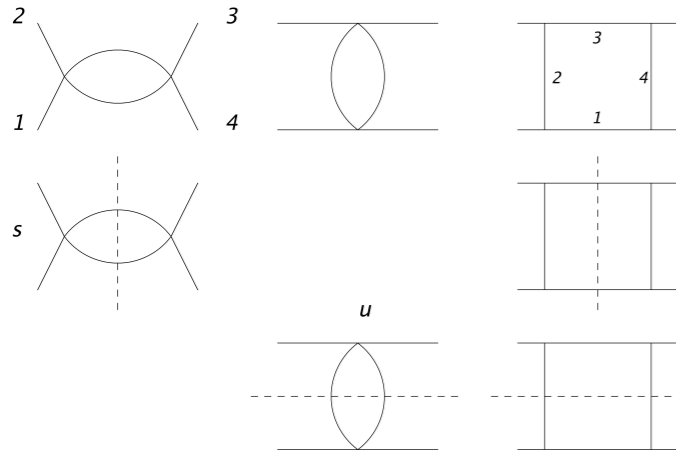
$$\begin{cases} \text{Disc}_0 \mathcal{A} &= \text{Cut}_t \mathcal{A} \\ \text{Disc}_1 \mathcal{A} &= \text{Cut}_u \mathcal{A} \\ \text{Disc}_\infty \mathcal{A} &= \text{Cut}_s \mathcal{A} \end{cases}$$

$$\mathcal{A}(z) = \epsilon^\# \sum_{n \geq 0} \epsilon^n \sum_{\vec{\alpha}: |\vec{\alpha}| \leq n} r_{n, \vec{\alpha}}(z) G(\vec{\alpha}, z)$$

Integrated Unitarity : example

cut MIs

cut DEQ



$$M_i^c \in \{\epsilon(2\epsilon - 1)I_{1,0,1,0}, \epsilon(2\epsilon - 1)I_{0,1,0,1}, \epsilon^2(x - 1)I_{1,1,1,1}\}$$

$$\partial_x M_i^c(x, \epsilon) = \epsilon A_{ij}^c(x) M_j^c(x, \epsilon)$$

$$\text{Cut}_s M_i^c \in \{\epsilon(2\epsilon - 1)I_{1,0,1,0;1,3}, 0, \epsilon^2(x - 1)I_{1,1,1,1;1,3}\}$$

$$\partial_x \text{Cut}_s M_i^c(x, \epsilon) = \epsilon A_{ij}^{c,s}(x) \text{Cut}_s M_j^c(x, \epsilon)$$

$$\text{Cut}_u M_i^c \in \{0, \epsilon(2\epsilon - 1)I_{0,1,0,1;2,4}, \epsilon^2(x - 1)I_{1,1,1,1;2,4}\}$$

$$\partial_x \text{Cut}_u M_i^c(x, \epsilon) = \epsilon A_{ij}^{c,u}(x) \text{Cut}_u M_j^c(x, \epsilon)$$

$$\text{Cut}_t M_i^c \in \{0, 0, 0\}$$

$$\partial_x \text{Cut}_t M_i^c(x, \epsilon) = 0$$

$$A^c(x) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & \frac{1}{1-x} & 0 \\ \frac{2}{x} & \frac{2}{x} + \frac{2}{1-x} & \frac{1}{x} + \frac{1}{1-x} \end{pmatrix}$$

3 methods

$$M_i^c(z) = e^{-2} \sum_{n \geq 0} e^n \sum_{\vec{\alpha}: |\vec{\alpha}| \leq n} c_{n, \vec{\alpha}} G(\vec{\alpha}, z) \quad \alpha_k \in \{0, 1\}$$

unknowns

A. explicit integration

B. ansatz + 2cuts + 1pt

C. ansatz + 3cuts

$$M_i^c(z) = M_{i,0}^c + \frac{1}{2\pi i} \int_1^\infty \left(\frac{dx}{x-z} - \frac{dx}{x} \right) \text{Cut}_u M_i^c(x)$$



ansatz	computed
$\text{Disc}_0 M_i^c$	$= \text{Cut}_t M_i^c$
$\text{Disc}_1 M_i^c$	$= \text{Cut}_u M_i^c$
$M_i^c(0)$	$= M_{i,0}^c$



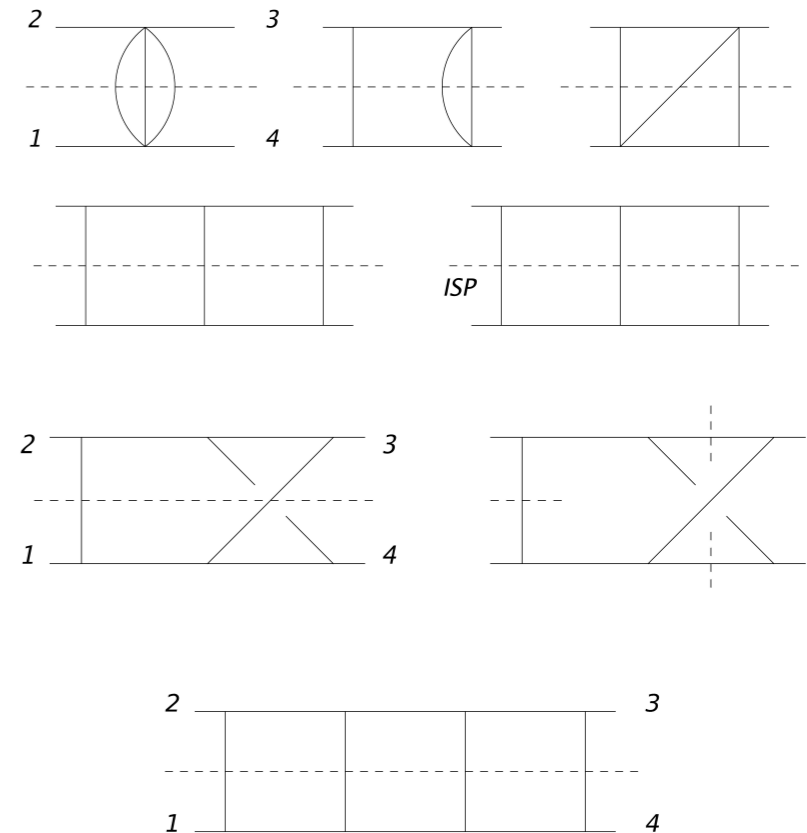
$\text{Disc}_0 M_i^c$	$= \text{Cut}_t M_i^c$
$\text{Disc}_1 M_i^c$	$= \text{Cut}_u M_i^c$
$\text{Disc}_\infty M_i^c$	$= \text{Cut}_s M_i^c$



Integrated Unitarity : further checks

Master Integrals (from DEQ)

- 2-loop planar (#MIs : 8 \rightarrow 5) ✓
- 2-loop nonplanar (#MIs : 12 \rightarrow 2+6) ✓
- 3-loop planar ladder (#MIs : 26 \rightarrow 17) ✓



Amplitudes (from form factor method)

- 1-loop gg \rightarrow gg (#INTs : ~ 2 per cut) ✓
- 2-loop gg \rightarrow gg planar (#INTs : ~ 8 per cut) ✓
- 2-loop gg \rightarrow gg nonplanar (#INTs : ~ 4 per cut) ✓

Application : four-loop ladder

procedure

- 22 generalized propagators = 13 denominators + 9 ISPs
- cut u : 5 propagators
- IBP : 59 MIs $\text{Cut}_u M_i^c$ (LiteRed + Kira)

- canonical DEQ : $A_{ij}^c(x) = \frac{a_{ij}}{x} + \frac{b_{ij}}{1-x}$ (CANONICA + MultivariateApart + FiniteFlow)

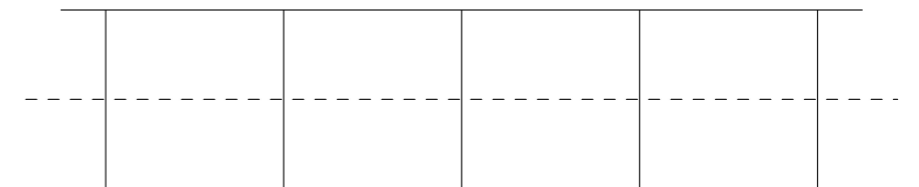
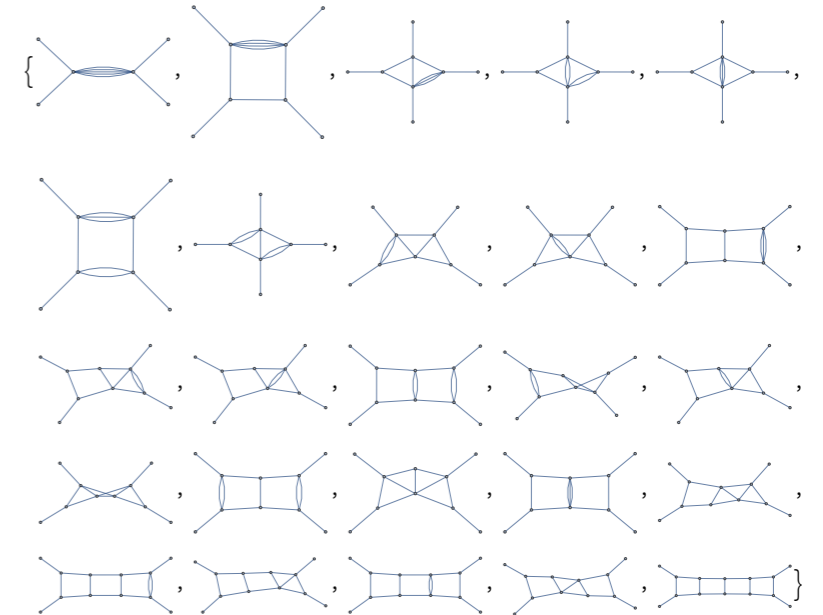
- canonical general solution : $M_u^c(x, \epsilon) = \mathbb{P} e^{\epsilon \int A^c(x) dx} M_{u,0}^c(\epsilon)$ (PolyLogTools + in-house)

- regularity constraints on BCs $M_{u,0}^c(\epsilon) : 59 \rightarrow 5$ (in-house)

- 5 remaining BCs : weight 7 (AMFlow)

- method B : $\text{Disc}_0 M_i^c = \text{Cut}_t M_i^c = 0$ & $\text{Disc}_1 M_i^c = \text{Cut}_u M_i^c$ (in-house)

fixed all HPL coefficients to weight 8



Further applications

kinematic limits

e.g. $\text{Disc}_1 \mathcal{A} = \text{Cut}_u \mathcal{A}$ alone gives $u \rightarrow 0$ limit at fixed Log accuracy to any subleading power

$$\lim_{x \rightarrow 1} \mathcal{A}(x) \sim c_{1,1}(x) G(1,1,x) + c_{0,1}(x) G(0,1,x) + c_{\dots,0}(x) G(\dots,0,x)$$

Leading Log
Next-to-Leading Log
suppressed

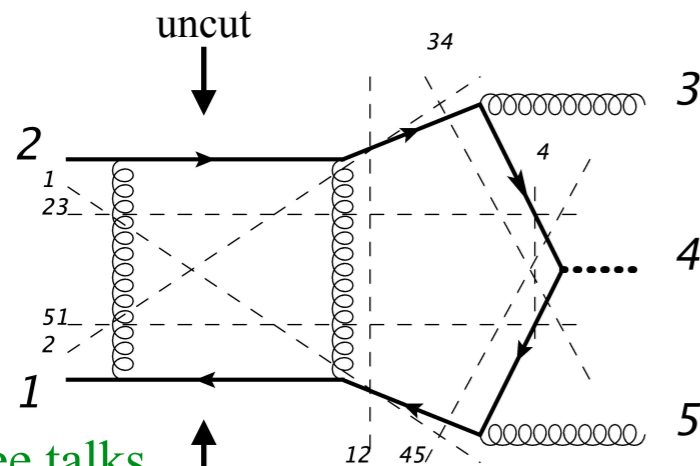
recursive approach

Multivariate Integrated Unitarity

Outlook into Multivariate Integrated Unitarity

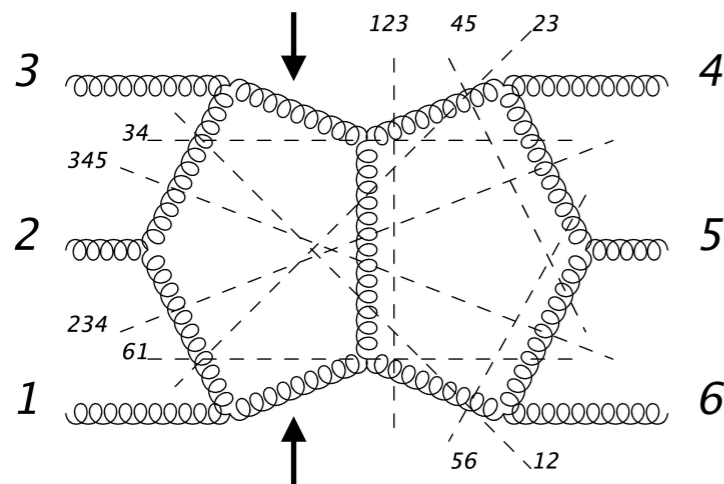
examples

$pp \rightarrow t\bar{t}H$ @ 2 loops



[see talks
by Anton, Guoxing]

$gg \rightarrow gggg$ @ 2 loops



properties

- many cut propagators \rightarrow simpler IBPs
- iterative Cauchy formula \rightarrow multivariate complex analysis
- Landau singularities \rightarrow nontrivial analytic structure
[Helmer, Papathanasiou, Tellander [2402.14787](#)] [Correia [2212.06157](#)]
- genealogical constraints \rightarrow possible simplifications
[Hannesdottir, Lippstreu, McLeod, Polackova [2406.05943](#)]

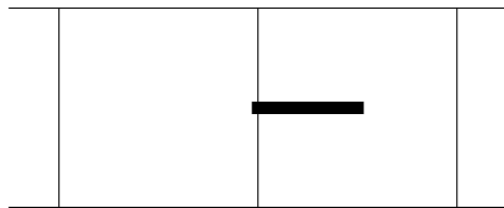
ongoing : 4-point 1-mass

[PB, collaborators in the group of Lorenzo Tancredi]

Analytic structure at 2 loops

5-point

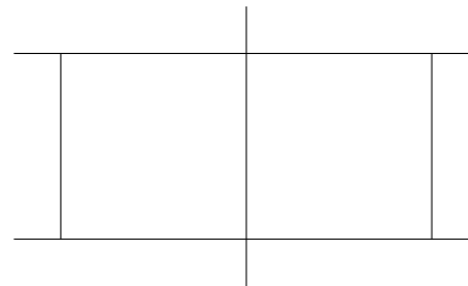
[Abreu, Chicherin, Ita, Page, Sotnikov, Tschernow, Zoia [2306.15431](#)]



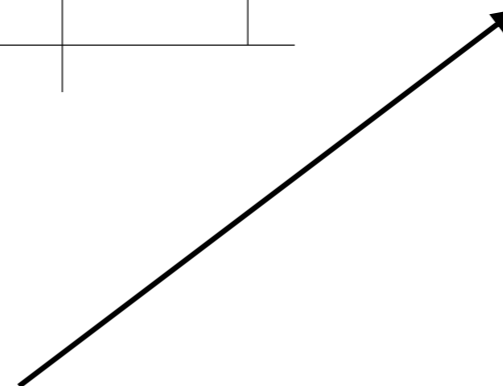
[see talks by Federico, Jungwon]

6-point

[Henn, Matijašić, Miczajka, Peraro, Xu, Zhang [2403.19742](#)]



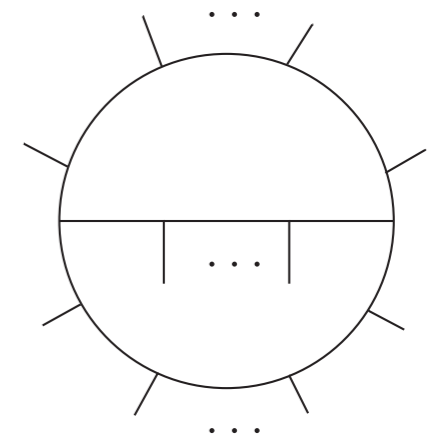
...



when does it **end** ?

a.k.a. the finite basis problem

n-point



The finite basis problem

1-loop n-point : linearly related to subsectors of 5-point

$$\mathcal{F}_{1,n} = \sum_{i_1=1}^n \frac{\mathcal{N}_{\text{tadpole},i_1}}{\mathcal{D}_{i_1}} + \sum_{\substack{i_1, i_2=1 \\ i_1 \neq i_2}}^n \frac{\mathcal{N}_{\text{bubble},i_1,i_2}}{\mathcal{D}_{i_1}\mathcal{D}_{i_2}} + \sum_{\substack{i_1, i_2, i_3=1 \\ i_j \neq i_m}}^n \frac{\mathcal{N}_{\text{triangle},i_1,i_2,i_3}}{\mathcal{D}_{i_1}\mathcal{D}_{i_2}\mathcal{D}_{i_3}} + \sum_{\substack{i_1, i_2, i_3, i_4=1 \\ i_j \neq i_m}}^n \frac{\mathcal{N}_{\text{box},i_1,i_2,i_3,i_4}}{\mathcal{D}_{i_1}\mathcal{D}_{i_2}\mathcal{D}_{i_3}\mathcal{D}_{i_4}} + \sum_{\substack{i_1, i_2, i_3, i_4, i_5=1 \\ i_j \neq i_m}}^n \frac{\mathcal{N}_{\text{pentagon},i_1,i_2,i_3,i_4,i_5}}{\mathcal{D}_{i_1}\mathcal{D}_{i_2}\mathcal{D}_{i_3}\mathcal{D}_{i_4}\mathcal{D}_{i_5}},$$

beyond 1-loop : new integrals with each new leg ?

- 1-loop : “no” i.e. up to 5-point [Passarino, Veltman, Ossola, Papadopoulos, Pittau]
- 2-loop massless planar in $d=4-2\epsilon$: “also no” i.e. up to 11 denominators [Gluza, Kajda, Kosower [1009.0472](#)]
- 2-loop in $d=d_0-2\epsilon$: “also no” [Kleiss, Malamos, Papadopoulos, Verheyen [1206.4180](#)]
- 2-loop in $d=4$: “also no” i.e. up to 8 denominators [Feng, Huang [1209.3747](#)]
- L-loop in $d=4$: “also no” [Bourjaily, Herrmann, Langer, Trnka [2007.13905](#)]
- **L-loop in $d=d_0-2\epsilon$: “also no”** **[PB, Tong-Zhi Yang [2408.06325](#)]**
(for integer d_0 & propagator powers)

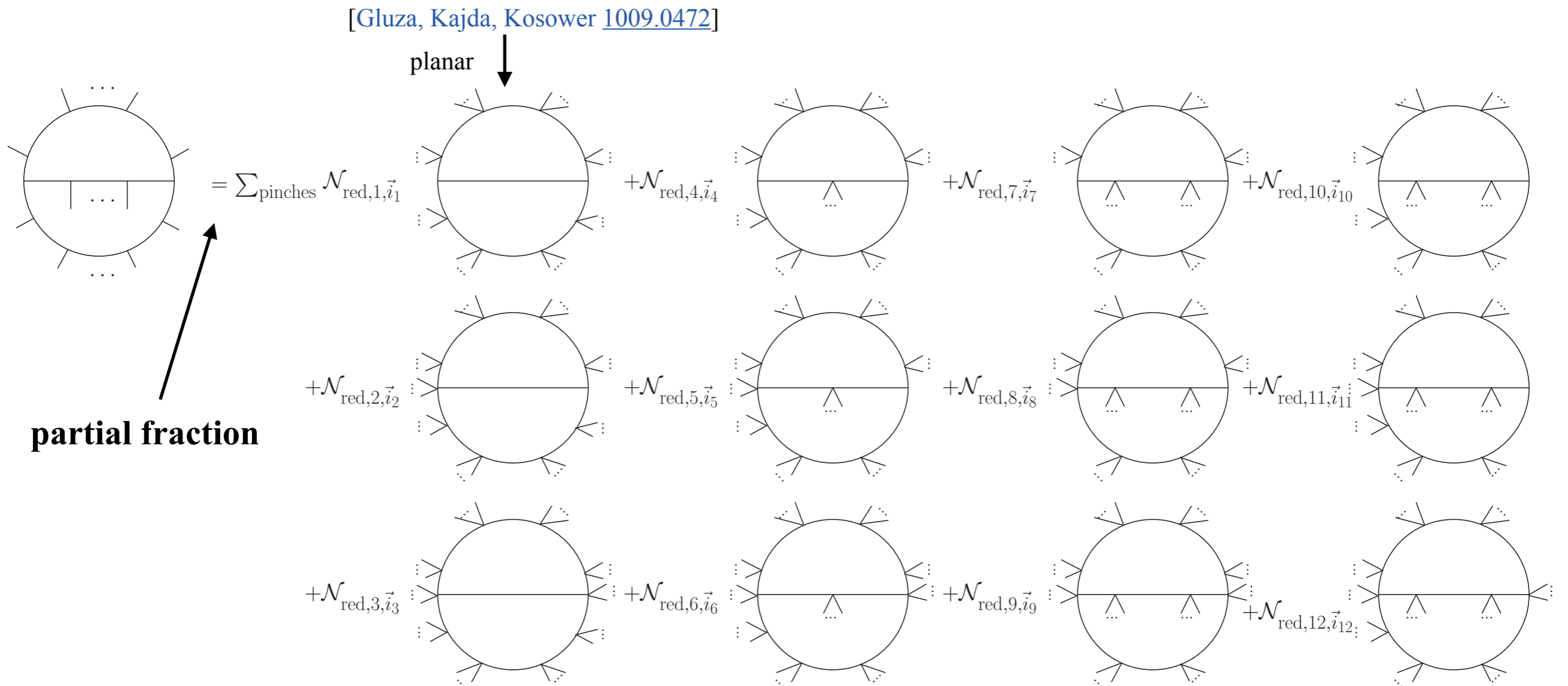
2 loops point-by-point

- independent external momenta $\{p_i\}$: (n-1) in Conventional Dimensional Regularization scheme (CDR)
only 4 in 't Hooft-Veltman scheme (tHV)
- scalar products $\{k_i \cdot k_j, k_i \cdot p_j\}$ involving loop momenta $\{k_1, k_2\}$: **at most 11** in tHV
- generalized propagators : denominators & Irreducible Scalar Products (ISPs)

kinematics	denominators	CDR ISPs	tHV ISPs	generalized CDR propagators	generalized tHV propagators
2-loop 4-point	7	2	2	9	9
2-loop 5-point	8	3	3	11	11
2-loop 6-point	9	4	2	13	11
2-loop 7-point	10	5	1	15	11
2-loop 8-point	11	6	0	17	11
2-loop 9-point	12	7	0	19	11

only 11 independent \Rightarrow **partial fraction**

Finite basis topologies at 2 loops



lower dimensions : less denominators e.g. 7 in $d=2-2\epsilon$

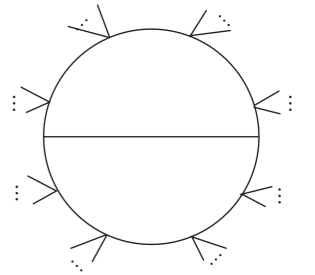
higher loops : 12p@3L, 17p@4L, ... (loop-by-loop approach analogous but many more topologies)

Immediate application : improving the IBP efficiency beyond 5-point

17 CDR generalized propagators

$$\{k_1 - k_2, k_1, k_2, k_1 + p_1, k_1 + p_{12}, k_1 + p_{123}, k_1 + p_{1234}, k_2 + p_{1234}, k_2 + p_{12345}, k_2 + p_{123456}, k_2 + p_{1234567}, k_1 - p_5, k_1 - p_6, k_1 - p_7, k_2 - p_1, k_2 - p_2, k_2 - p_3\}$$

momentum decomposition
$$p_{j>4} = \sum_{i=1}^4 p_i \frac{\det(\{p_1, \dots, \hat{p}_i, p_j, \dots, p_4\} \cdot \{p_1, \dots, p_4\})}{\det(\{p_1, \dots, p_4\} \cdot \{p_1, \dots, p_4\})}$$



⇒ 11 tHV generalized propagators

$$\{k_1 - k_2, k_1, k_2, k_1 + p_1, k_1 + p_{12}, k_1 + p_{123}, k_1 + p_{1234}, k_2 + p_{1234}, k_2 + \sum_{j=1}^4 p_j z_{9,j}, k_2 + \sum_{j=1}^4 p_j z_{10,j}, k_2 + \sum_{j=1}^4 p_j z_{11,j}\}$$

	CDR	tHV	R_t
D2	31.4m/3126MI/13.9G	6.8m/2368MI/1.88G	4.6
D3	51.5m/3302MI/18.19G	10.1m/2368MI/2.9G	5.1
N3	115.2m/4497MI/25.7G	5.7m/2358MI/2.59G	20.2
N4	321.3m/6742MI/56.4G	7.6m/2368MI/4.3G	42.3
N5	908.9m/9779MI/137G	12.5m/2368MI/7.35G	72.7
N6	-	20.1m/2368MI/10.34G	-

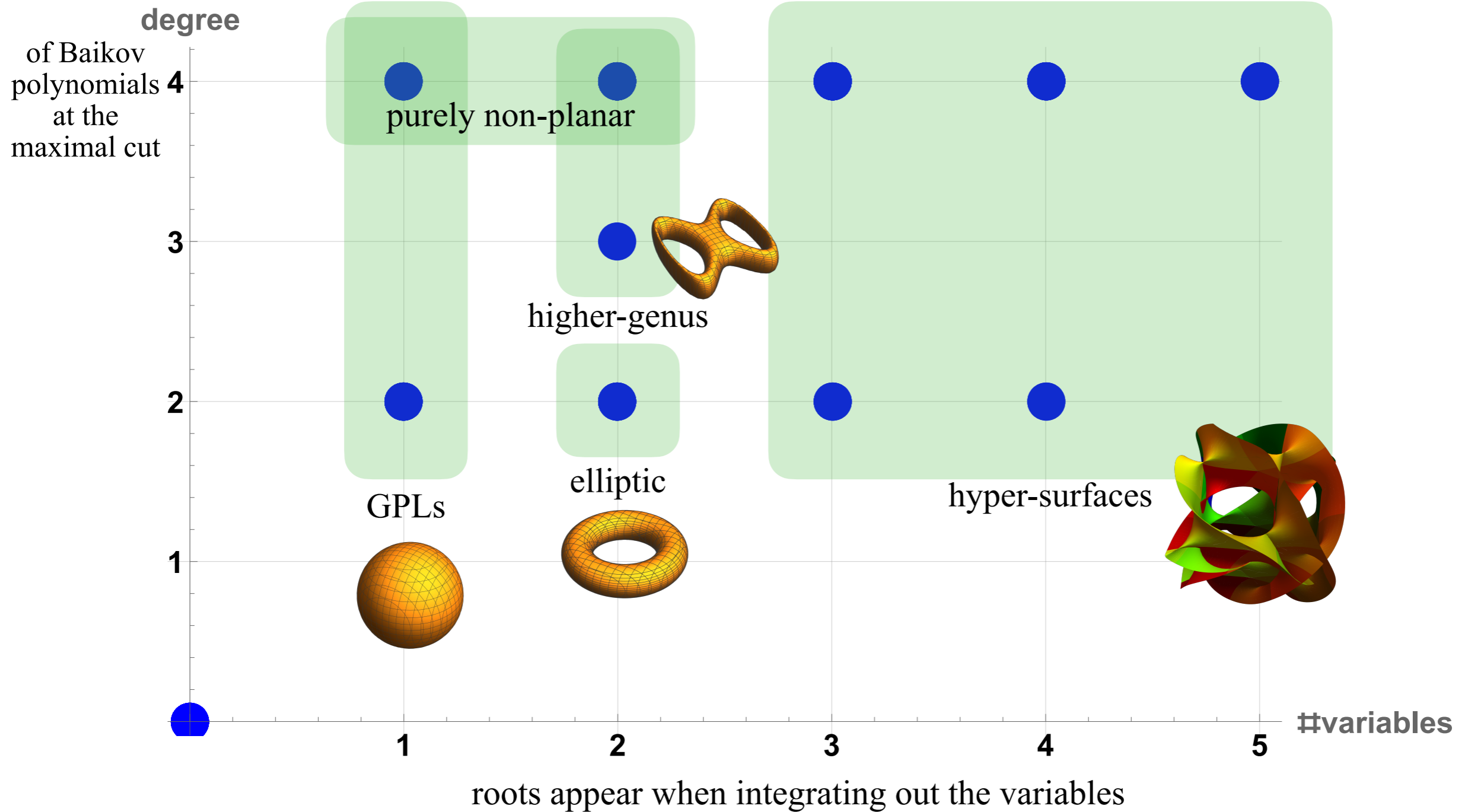
- no cut propagators
- one numerical probe
- one finite field
- with FIRE6



improves numerical AMFlow evaluation of Feynman integrals

Forthcoming application : spanning the space of special functions at 2 loops

all 84 subsectors of the 12 finite basis topologies

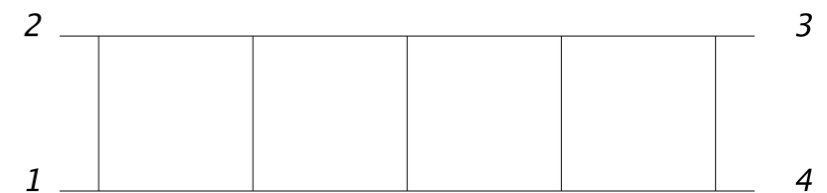


Conclusions

can **exploit** the analytic structure of amplitudes

$$\begin{array}{c} 2 \\ \diagup \\ \text{---} \circ (z) \\ \diagdown \\ 1 \end{array} \begin{array}{c} 3 \\ \diagdown \\ \text{---} \\ \diagup \\ 4 \end{array} = \begin{array}{c} 2 \\ \diagup \\ \text{---} \circ \\ \diagdown \\ 1 \end{array} \begin{array}{c} 1 \\ \diagdown \\ \text{---} \\ \diagup \\ 2 \end{array} + \frac{1}{2\pi i} \int_1^\infty \sum_{\{c_j\}} \left(\frac{1}{x-z} - \frac{1}{x-z_0} \right) dx \begin{array}{c} 3 \\ \diagdown \\ \text{---} \circ \text{---} \circ (x) \\ \diagup \\ 2 \end{array} \begin{array}{c} 4 \\ \diagdown \\ \text{---} \\ \diagup \\ 1 \end{array}$$

- **Integrated Unitarity** ~ Generalized Unitarity @ integrated level
 - allows algorithmic usage of dispersion relations in dimReg
 - **beneficial for IBP computational complexity**
 - **requires understanding of analytic structure**
- ↙ trade-off



can **constrain** the analytic structure of QCD amplitudes

- **finite basis exists** at any fixed loop order
- explicit reduction to lower points at 2 loops
- improves IBP efficiency (also numerical via AMFlow)
- upper bound on special functions spectrum

$$\begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} = \sum_{\text{pinches}} \mathcal{N}_{\text{red},1,\vec{i}_1} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},4,\vec{i}_4} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},7,\vec{i}_7} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},10,\vec{i}_{10}} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},2,\vec{i}_2} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},5,\vec{i}_5} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},8,\vec{i}_8} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},11,\vec{i}_{11}} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},3,\vec{i}_3} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},6,\vec{i}_6} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},9,\vec{i}_9} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array} + \mathcal{N}_{\text{red},12,\vec{i}_{12}} \begin{array}{c} \dots \\ \text{---} \circ \text{---} \circ \\ \text{---} \circ \text{---} \circ \\ \dots \end{array}$$

THANK YOU

Appendix

Cuts

- integral definition :

$$I_{\{n_i\}} = \int \left(\prod_{l=1}^L D^d k_l \right) \prod_{i=1}^N \mathcal{D}_i^{-n_i} \quad D^d k_l = e^{\epsilon \gamma_E} \frac{d^d k_l}{i\pi^{d/2}}$$

- cut propagator :

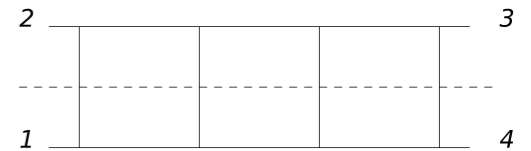
$$\frac{1}{\mathcal{D} + i\epsilon} \rightarrow 2\pi i \delta^+(\mathcal{D}) \quad \delta^+(q^2) = \delta(q^2) \theta(q_0)$$

- cut integral :

$$\text{Cut}_u I_{\{n_i\}} = \sum_{\{c_j\} \in \mathcal{C}_u} I_{\{n_i\}; \{c_j\}} = \sum_{\{c_j\} \in \mathcal{C}_u} \int \left(\prod_{l=1}^L D^d k_l \right) \left(\prod_{i \notin \{c_j\}} \mathcal{D}_i^{-n_i} \right) \prod_{m \in \{c_j\}} \delta_{1, n_m} 2\pi i \delta^+(\mathcal{D}_m)$$

- less subsectors :

$$/2^{\mathcal{C}}$$



- Integration-By-Parts identities (IBPs) :

[Laporta [0102033](#)]

$$\int \left(\prod_{l=1}^L D^d k_l \right) \frac{\partial}{\partial k_l^\mu} \left(q^\mu \prod_{i=1}^N \mathcal{D}_i^{-n_i} \right) = 0$$

[Chetyrkin, Tkachov 1981]

$$p_{j\mu} p_{l\nu} \left(p_n^\nu \frac{\partial}{\partial p_{n,\mu}} - p_n^\mu \frac{\partial}{\partial p_{n,\nu}} \right) I_{\{n_i\}} = 0$$

[Gehrmann, Remiddi [9912329](#)]

- Differential Equations (DEQ) : $\partial_{x_n} M_i(\vec{x}, \epsilon) = A_{ij}(\vec{x}, \epsilon) M_j(\vec{x}, \epsilon)$ $\xrightarrow{\text{canonical}}$ $\partial_{x_n} M_i^c(\vec{x}, \epsilon) = \epsilon A_{ij}^c(\vec{x}) M_j^c(\vec{x}, \epsilon)$

Master Integrals (MIs) \nearrow

[Kotikov 1991]

[Henn [1304.1806](#)]

\rightarrow can solve cut integrals with DEQ

Discontinuities

- discontinuity :

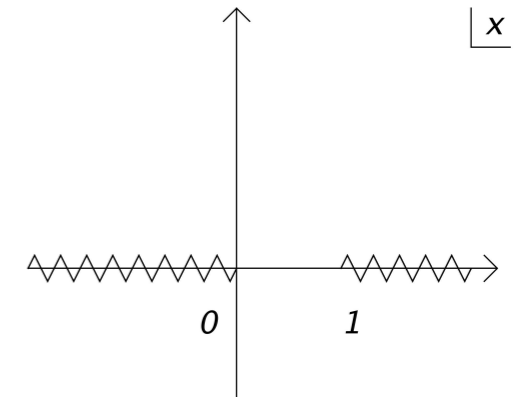
$$\text{Disc}_0 f(x) = f(x + i\epsilon) - f(x - i\epsilon)$$

- from now on, focus on specific kinematics :

$$x = -\frac{t}{s} \quad \text{4-point massless}$$

- branch cuts :

$$\begin{array}{lll} t > 0 & u > 0 & s > 0 \\ x < 0 & x > 1 & \text{pushed to } \infty \end{array}$$



- Harmonic Polylogarithms (HPLs) :
[Remiddi, Vermaseren 9905237]

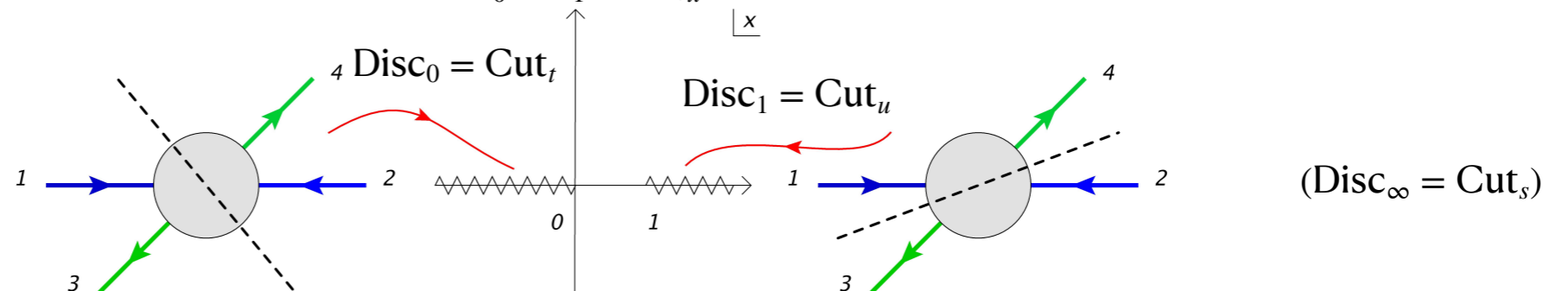
$$G(\alpha_n, \dots, \alpha_1; x) = \int_0^x \frac{dz}{z - \alpha_n} G(\alpha_{n-1}, \dots, \alpha_1; z) \quad \alpha_k \in \{0, 1\}$$

- discontinuities of HPLs algorithmic from monodromy matrices :

[Bourjaily, Hannesdottir, McLeod, Schwartz, Vergu 2007.13747]

$$\begin{aligned} \text{Disc}_0 &= (1 - \mathcal{M}_0) \cdot \mathcal{M}_{\rightarrow x}, \\ \text{Disc}_1 &= -(1 - \mathcal{M}_1) \cdot \mathcal{M}_{\rightarrow x}, \\ \text{Disc}_\infty &= (1 - \mathcal{M}_0 \cdot \mathcal{M}_1) \cdot \mathcal{M}_{\rightarrow x}. \end{aligned}$$

- unitarity :



Monodromies

- Harmonic Polylog :

$$G(\alpha_n, \dots, \alpha_1; x) \quad \alpha_k \in \{0,1\}$$

- vector of derivatives :

$$\mathcal{V}_i = \begin{cases} 1 & \text{if } i = 0, \\ (-1)^{\# \text{ of } 1} G(\alpha_{n+1-i}, \dots, \alpha_n, x) & \text{if } n \geq i > 0 \end{cases}$$

- connection matrix :

$$\omega_{ij} = \frac{dx}{x - \alpha_{n-i}} \delta_{i+1,j} \quad \text{s.t.} \quad d\mathcal{V} = \mathcal{V} \cdot \omega$$

- variation matrix :

$$\mathcal{M}_\gamma = \mathcal{P} e^{\int_\gamma \omega} \quad \text{collects all } n + 1 \text{ solutions for } \mathcal{V}$$

- general solution :

$$(\mathcal{M}_{\rightarrow x})_{ij} = \sum_{k=0}^n (-1)^{\# \text{ of } 1} G(\alpha_{n-i}, \dots, \alpha_{n-i-k+1}, x) \delta_{i+k,j}$$

$$G(x) = 1$$

- monodromy matrices :

$$\mathcal{M}_0 = \mathcal{M}_{\cup_0},$$

$$\mathcal{M}_1 = \mathcal{M}_{\rightarrow 1} \mathcal{M}_{\cup_1} \mathcal{M}_{\rightarrow 1}^{-1}.$$

- discontinuities :

$$\text{Disc}_0 = (1 - \mathcal{M}_0) \cdot \mathcal{M}_{\rightarrow x},$$

$$\text{Disc}_1 = -(1 - \mathcal{M}_1) \cdot \mathcal{M}_{\rightarrow x},$$

$$\text{Disc}_\infty = (1 - \mathcal{M}_0 \cdot \mathcal{M}_1) \cdot \mathcal{M}_{\rightarrow x}.$$

following :

[Bourjaily, Hannesdottir, McLeod, Schwartz, Vergu 2007.13747]

Ansatz matching

- example ansatz :

$$c_{1,1} G(1,1;x) + c_{1,0} G(1,0;x) + c_{0,1} G(0,1;x) + c_{0,0} G(0,0;x) + c_1 G(1;x) + c_0 G(0;x) + c$$
- impose e.g. $\text{Disc}_0 = 0$:

$$c_{1,1} G(1,1;x) + 0 + c_{0,1} G(0,1;x) + 0 + c_1 G(1;x) + 0 + c$$
- $\text{Disc}_1 = 2\pi i (2 G(1;x) + 3 G(0;x) + 5 \pi i)$ $= c_{1,1} (2\pi i (-G(1;x) + i\pi)) + c_{0,1} (-2\pi i G(0,x)) + c_1 (-2\pi i) + 0$
- now only constant unconstrained :

$$-2 G(1,1;x) - 3 G(0,1;x) - 7 i\pi G(1;x) + c$$
- impose fixed value e.g. ζ_2 at $x=0$:

$$-2 G(1,1;x) - 3 G(0,1;x) - 7 i\pi G(1;x) + \zeta_2$$

Explicit reduction coefficients

$$\mathcal{F}_{L,n} = \prod_{i=1}^{D(n,L)} \frac{1}{\mathcal{D}_i} = \sum_{\substack{i_1, \dots, i_A = 1 \\ i_j \neq i_m}}^{D(n,L)} \frac{c_{i_1, \dots, i_A}}{\mathcal{D}_1 \cdots \hat{\mathcal{D}}_{i_1} \hat{\mathcal{D}}_{i_2} \cdots \hat{\mathcal{D}}_{i_A} \cdots \mathcal{D}_{D(n,L)}}$$

with

$$c_{i_1, \dots, i_A} = \frac{(-B_{i_1, \dots, i_A})^A}{B_{0, \dots, i_A} B_{i_1, 0, \dots, i_A} \cdots B_{i_1, \dots, 0}}$$

$$A = D(n, L) - D(N(L, d_0), L)$$

$$B_{i_1, \dots, i_A} = \begin{vmatrix} \alpha_{D(N(L, d_0), L)+1, i_1} & \cdots & \alpha_{D(N(L, d_0), L)+1, i_A} \\ \alpha_{D(N(L, d_0), L)+2, i_1} & \cdots & \alpha_{D(N(L, d_0), L)+2, i_A} \\ \vdots & \vdots & \vdots \\ \alpha_{D(n, L), i_1} & \cdots & \alpha_{D(n, L), i_A} \end{vmatrix}$$

$$\begin{aligned} \mathcal{D}_{i > D(N(L, d_0), L)} &= \alpha_{i,0} + \sum_{j=1}^{D(N(L, d_0), L)} \alpha_{i,j} \mathcal{D}_j \\ \alpha_{i,i} &= -1 \\ \alpha_{i, j > D(N(L, d_0), L)} &= 0 \end{aligned}$$

partial fractions implemented in Mathematica package **Apart** [[Feng 1204.2314](#)]

Leading singularity

no ISPs \Rightarrow **maximal cut** localizes [Bosma, Sogaard, Zhang [1704.04255](#)]

true for finite basis topologies t

e.g. at 2 loops

$$I_{\max}^{(t)} = \int \frac{d^d k_1}{(2\pi)^d} \frac{d^d k_2}{(2\pi)^d} \prod_{i=1}^{11} 2\pi i \delta(\mathcal{D}_i^{(t)}) = c(d) \frac{G^{(5-d)/2}}{B_t^{(7-d)/2}}$$

with

$$c(d) = \frac{1}{4^d \pi^{9/2} \Gamma((d-4)/2) \Gamma((d-5)/2)}$$

$$G = \det(\{p_1, \dots, p_4\} \cdot \{p_1, \dots, p_4\})$$

$$B_t = \det(\{k_1, k_2, p_1, \dots, p_4\} \cdot \{k_1, k_2, p_1, \dots, p_4\})|_{\mathcal{D}_i^{(t)}=0, i=1, \dots, 11}$$

leading singularity for higher-loop finite basis topologies

$$\mathcal{S}_{t,L} = \frac{\sqrt{G}}{\left(\sqrt{B_{t,L}}\right)^{L+1}}$$