

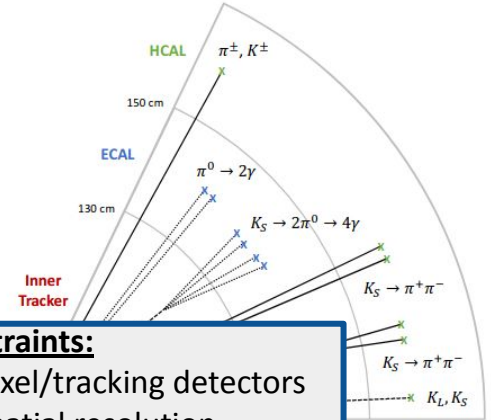
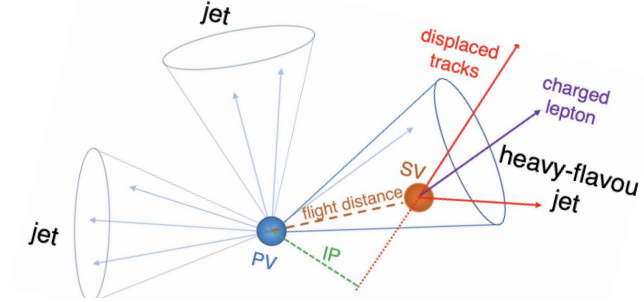
Event reconstruction using ML for FCC-ee

Dolores Garcia



Motivation, s & b tagging

- Flavour tagging essential for the e^+e^- program
 - Measure Higgs particle properties and interactions in challenging decay modes
 - Precise determination of top properties
 - QCD physics: modeling hadronization...
- **b-tagging:**
 - Large lifetime, (2-3) mm for ~ 50 GeV boost
 - Displaced vertices/tracks (Large impact parameters)
 - Large track multiplicity
 - Presence of non-isolated e/μ (20 (10)% in B (C) decays)
- **s-tagging:**
 - Large Kaon content:
 - as tracks (K/pi separation ToF, $dEdx$, $dNdx$)
 - Neutral Kaons:
 - K_S 2 tracks
 - K_L ToF vs n



Detector constraints:

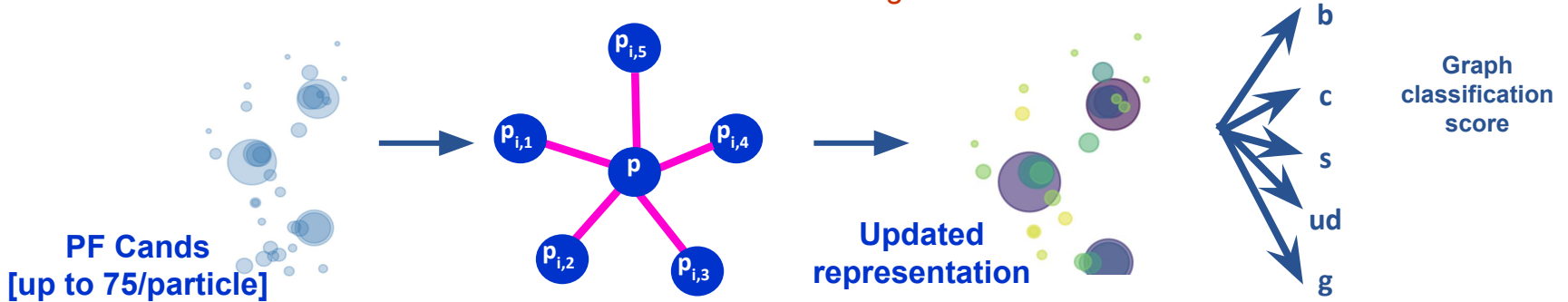
Need power pixel/tracking detectors

- Good spatial resolution
- As little material as possible
- Precise track alignment
- Timing detectors
- Charged energy loss (gas/silicon)

Graph based tagger

- Particle based jet tagging using all information from PF reconstruction
- Jet representation: “*Point Cloud*” → “*Particle Clouds*”
 - Treat the jet as an unordered set of particles
- Algorithm design: Graph Neural Networks
 - Particle cloud represented as a graph
 - Each particle: **node** of the graph; Connections between particles: the **edges**
- Follow a hierarchical learning approach
 - First learn local structures → then move to more global ones

[O(50) properties/particle]
x [~50-100 particles/jet]
~O(1000) inputs/jet



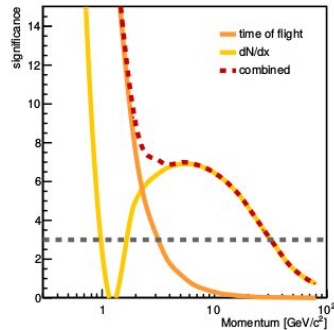
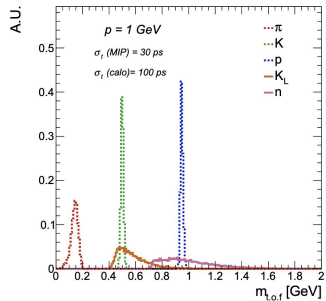
ACKS : Michele Selvaggi, Loukas Gouskos, Franco Bedeschi

[1] Qu, H., & Gouskos, L. (2020). Jet tagging via particle clouds. *Physical Review D*, 101(5), 056019.

[2] Qu, H., Li, C., & Qian, S. (2022, June). Particle transformer for jet tagging. In *International Conference on Machine Learning* (pp. 18281-18292). PMLR.

Input variables

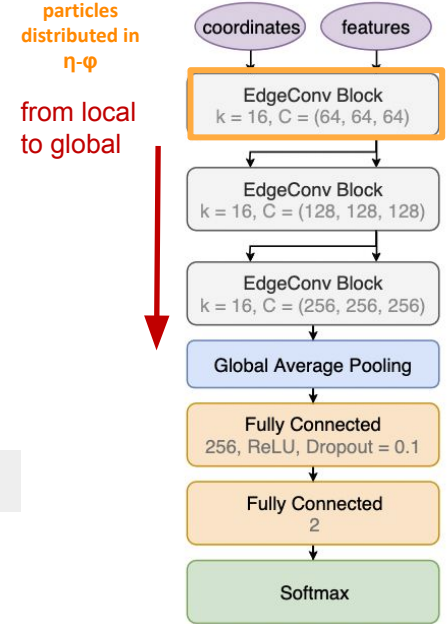
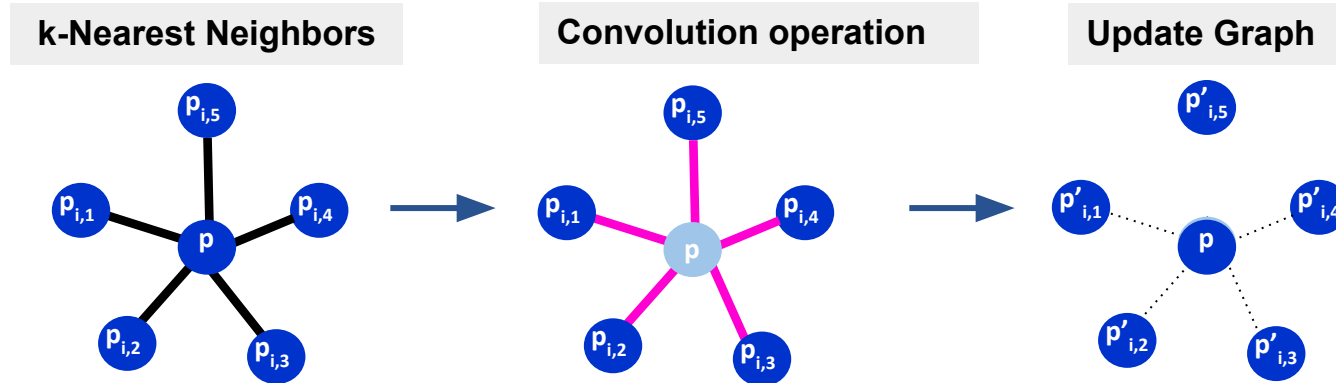
- Kinematic
- Displacement (important for b-tagging)
- Identification:
 - Number of ionization clusters (dN/dx)
 - ToF results in good K/ π separation at low-momenta
 - Module added to Delphes



Variable	Description
Kinematics	
$E_{\text{const}}/E_{\text{jet}}$	energy of the jet constituent divided by the jet energy
θ_{rel}	polar angle of the constituent with respect to the jet momentum
ϕ_{rel}	azimuthal angle of the constituent with respect to the jet momentum
Displacement	
d_{xy}	transverse impact parameter of the track
d_z	longitudinal impact parameter of the track
SIP _{2D}	signed 2D impact parameter of the track
SIP _{2D} / σ_{2D}	signed 2D impact parameter significance of the track
SIP _{3D}	signed 3D impact parameter of the track
SIP _{3D} / σ_{3D}	signed 3D impact parameter significance of the track
d_{3D}	jet track distance at their point of closest approach
$d_{3D}/\sigma_{d_{3D}}$	jet track distance significance at their point of closest approach
C_{ij}	covariance matrix of the track parameters
Identification	
q	electric charge of the particle
$m_{\text{t.o.f.}}$	mass calculated from time-of-flight
dN/dx	number of primary ionisation clusters along track
isMuon	if the particle is identified as a muon
isElectron	if the particle is identified as an electron
isPhoton	if the particle is identified as a photon
isChargedHadron	if the particle is identified as a charged hadron
isNeutralHadron	if the particle is identified as a neutral hadron

Architectures

- ParticleNeT [1]:
 - Find the **k -nearest neighbors** of each point
 - Design a permutation invariant **convolution operation**
 - Define an **edge feature** function \rightarrow **aggregate** edge features w/ a **symmetric func.**
 - Dynamically update graph
- Other architectures: Particle Transformer [2] FC transformer

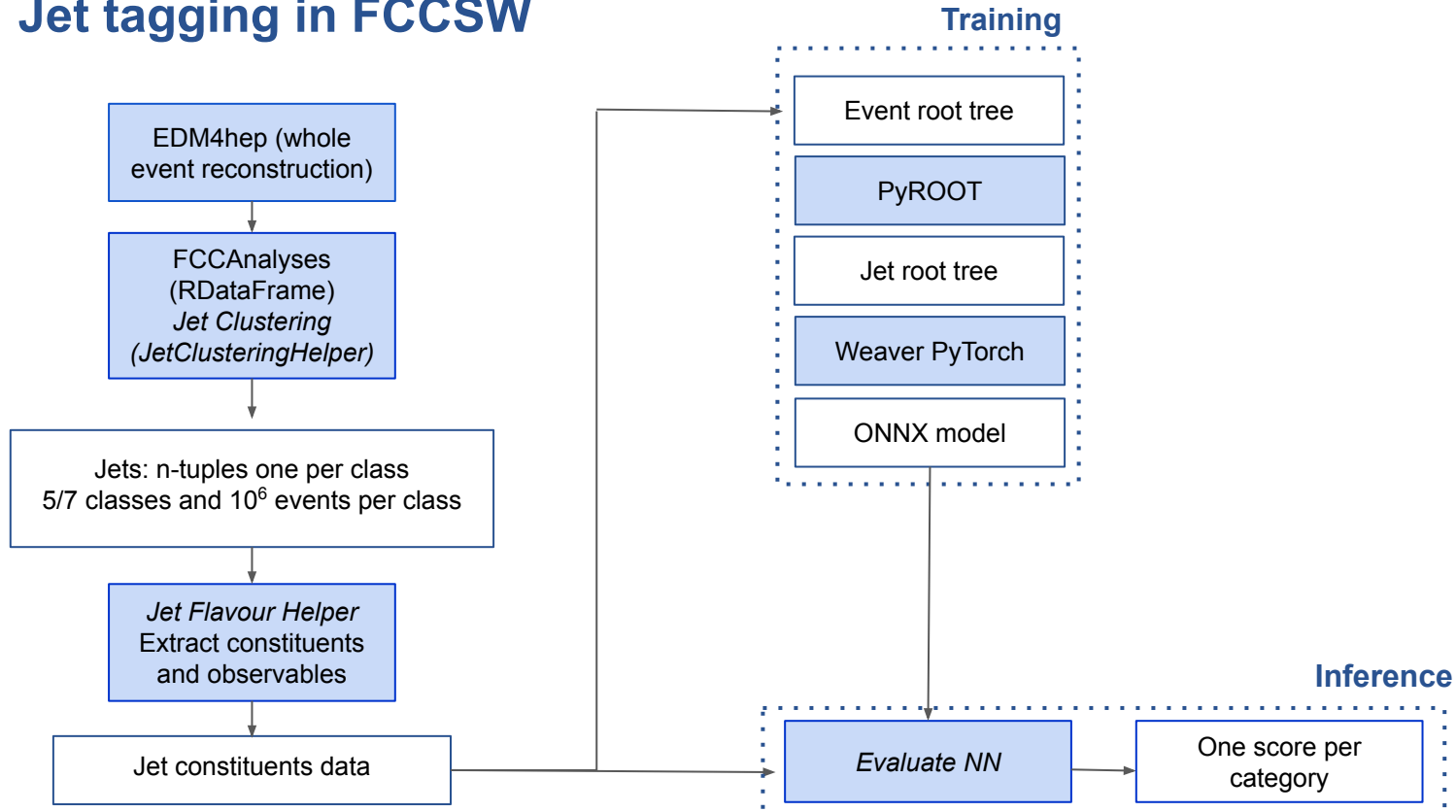


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[1] Qu, H., & Gouskos, L. (2020). Jet tagging via particle clouds. *Physical Review D*, 101(5), 056019.

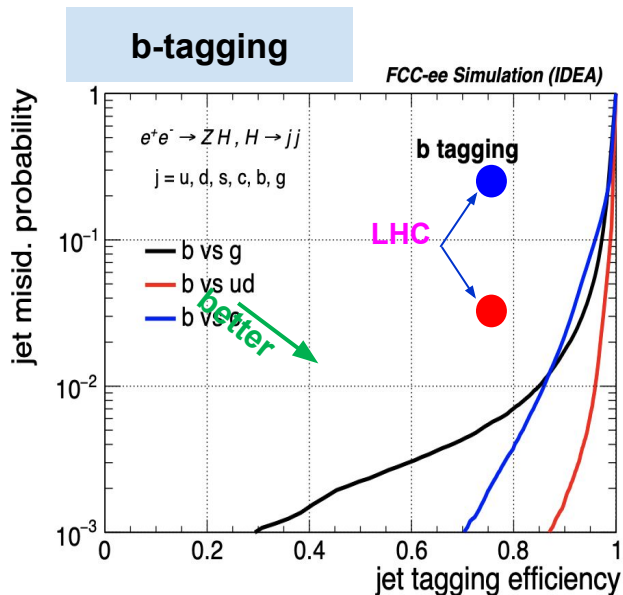
[2] Qu, H., Li, C., & Qian, S. (2022, June). Particle transformer for jet tagging. In *International Conference on Machine Learning* (pp. 18281-18292). PMLR.

Jet tagging in FCCSW

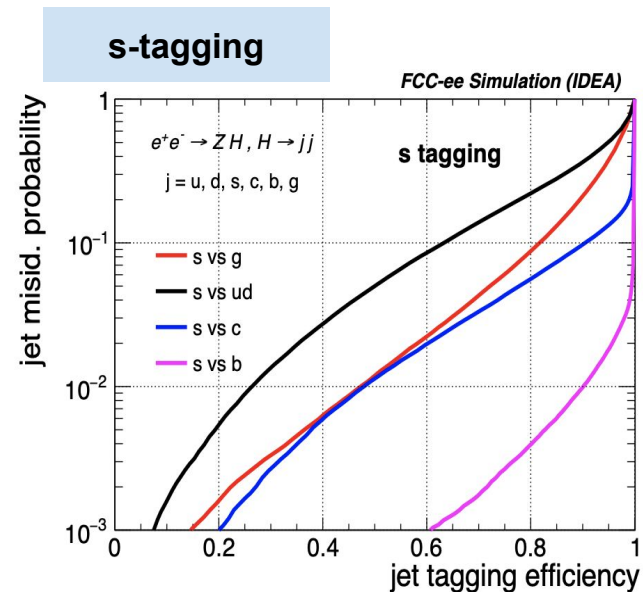


Results

Some examples: (Also new classes for u/d/tau and different detector configurations)



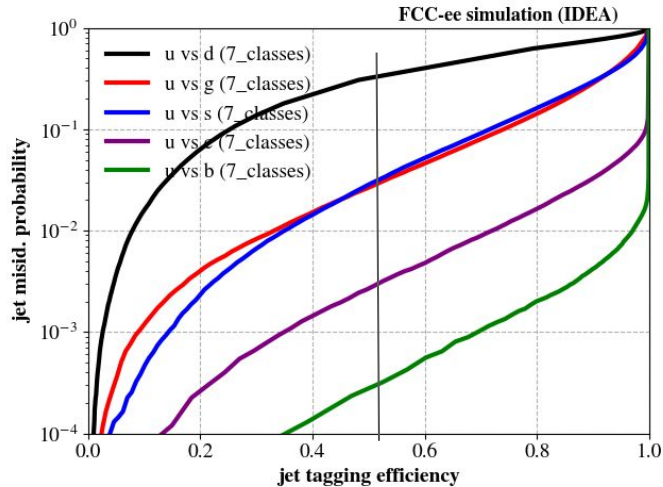
WP	Eff (b)	Mistag (g)	Mistag (ud)	Mistag (c)
Loose	90%	2%	0.1%	2%
Medium	80%	0.7%	<0.1%	0.3%



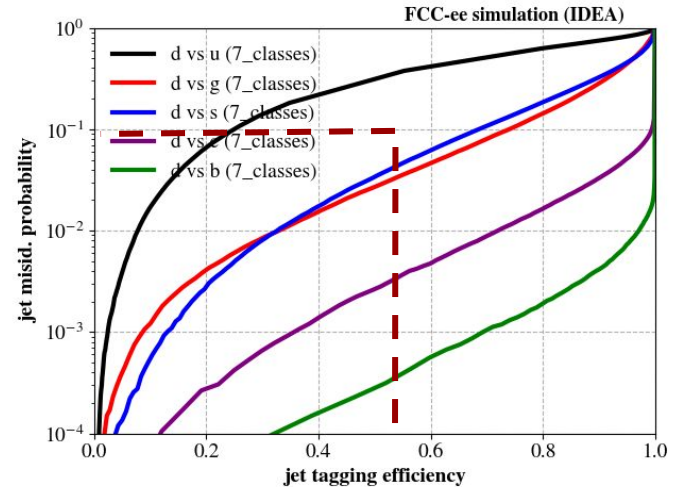
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Loose	90%	20%	40%	10%	1%
Medium	80%	9%	20%	6%	0.4%

Tagger update: up and down

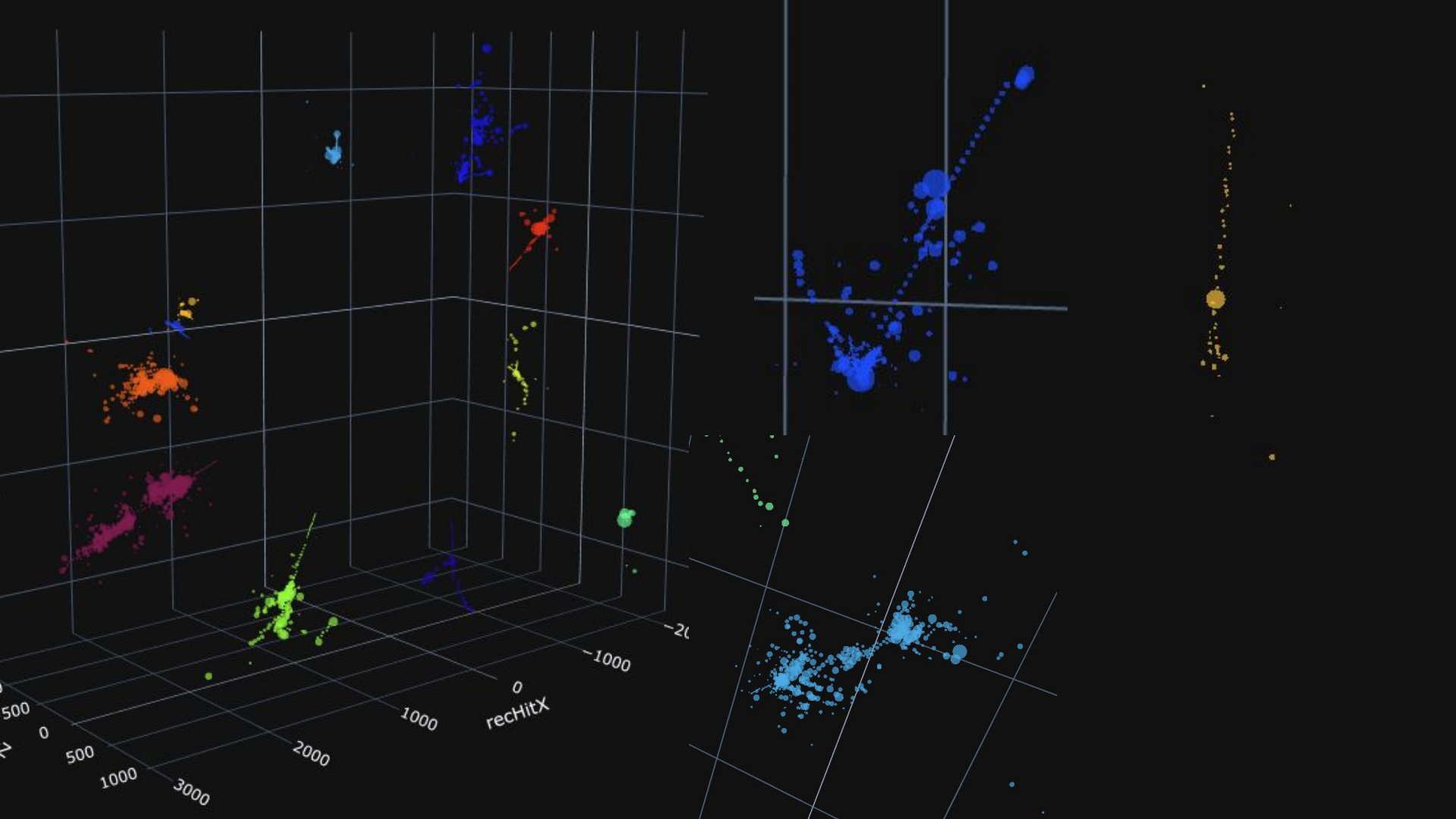
Up-tagging



Down-tagging

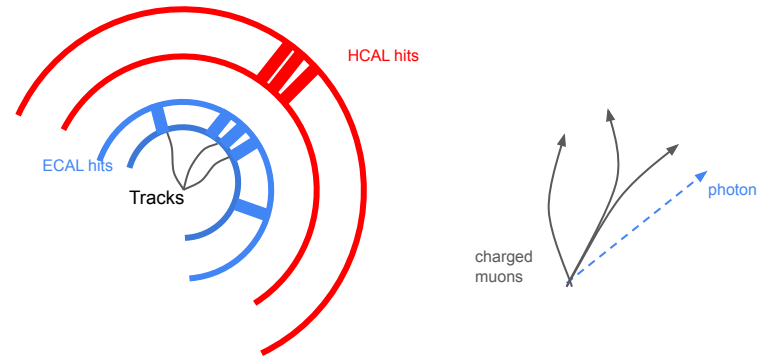


- Up vs Down discrimination seems possible thanks to jet charge
- 30% bkg eff at 50% signal (better than random coin toss)

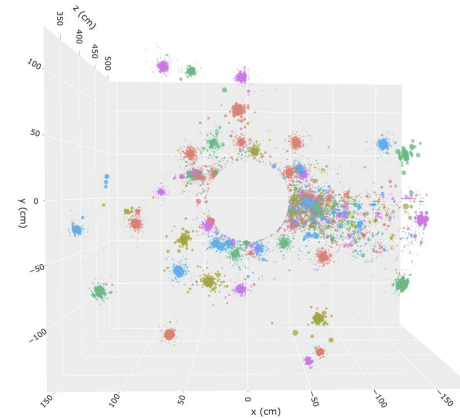


MLPF: Motivation

- The particle flow algorithm aims to identify the produced particles in a collision through the combination of the information from the entire detector and provide best combined energy/momentum resolution
- Hoping to achieve higher reconstruction performance: cluster merging, arbitration of track vs cluster energy
- First step: **focus on calorimeter clustering**



A Representation of the different layers, hits, tracks and resulting particles (reproduced from [1])



B Example of an event, the shower of secondary particles generated by an individual particle is labelled with one colour [2]



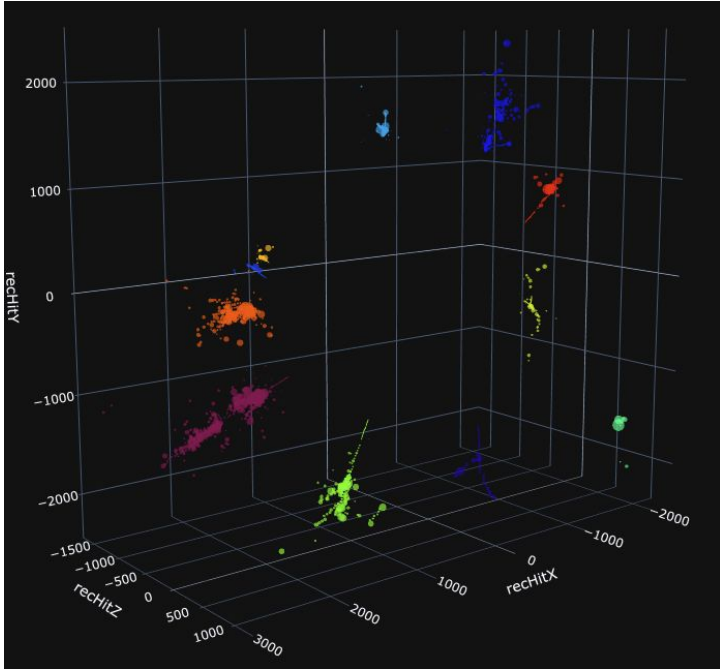
ACKS : Michele Selvaggi, **Gregor Krzmarc**, Jan Kieseler, Philipp Zehetner

[1] Pata, J. Machine learning for particle flow reconstruction at CMS, presentation at CDS.

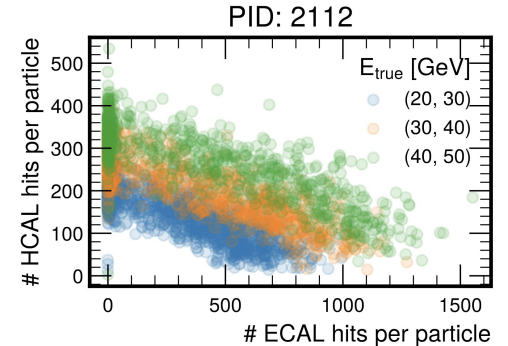
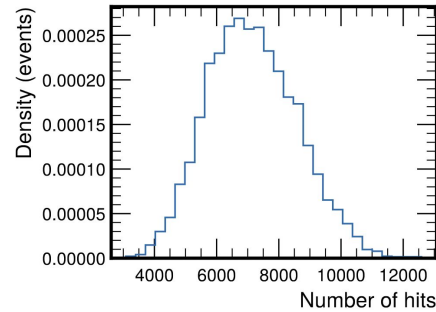
[2] Qasim, S. R., Chernyavskaya, N., Kieseler, J., Long, K., Viazlo, O., Pierini, M., & Nawaz, R. (2022). End-to-end multi-particle reconstruction in high occupancy imaging calorimeters with graph neural networks. *The European Physical Journal C*, 82(8), 753.

Training Data

A Example train event - 15 particles

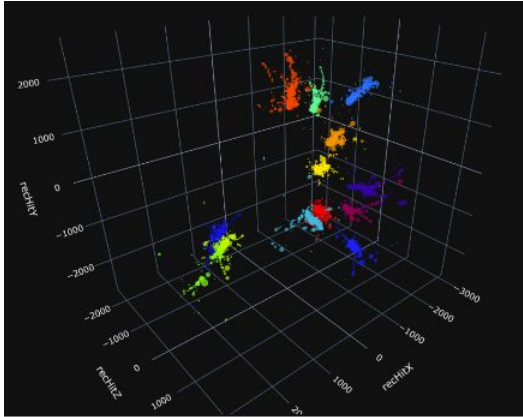


- Event generation:
 - Use particle gun (0-15 particles)
 - $E \in [0.5, 50]$ GeV
 - ρ, n, K_L, π
- FCC-ee O(100)
- Simulation and reconstruction: Key4HEP turnkey + Geant4 (CLIC pipeline)



B Number of hits per event (left) and #hits ECAL vs HCAL (right)

Architecture: Object condensation (End-to-End approach)



Input:

- A set of hits from different sensors (coordinates, type of hit, energy, A)
- Each one node in the graph $O(600)$ per particle

$$q_{\alpha k} = \max_i q_i M_{ik}.$$

$$\check{V}_k(x) = \|x - x_\alpha\|^2 q_{\alpha k}, \text{ and}$$

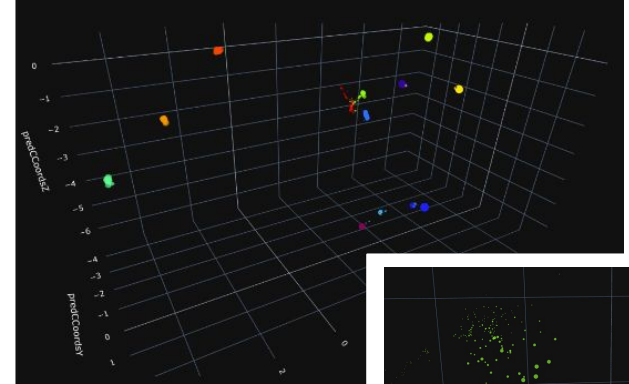
$$\hat{V}_k(x) = \max(0, 1 - \|x - x_\alpha\|) q_{\alpha k}.$$

$$L_V = \frac{1}{N} \sum_{j=1}^N q_j \sum_{k=1}^K (M_{jk} \check{V}_k(x_j) + (1 - M_{jk}) \hat{V}_k(x_j)).$$

CP

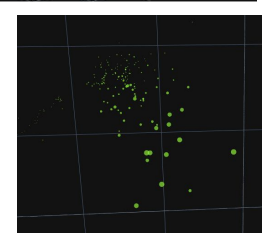


- **Each object 1 condensation point (CP)**
- **Repulsive + Attractive potentials for each CP**



Output:

- Coordinate in embedding space (3D)
- Beta (q)
- Use clustering space to build showers

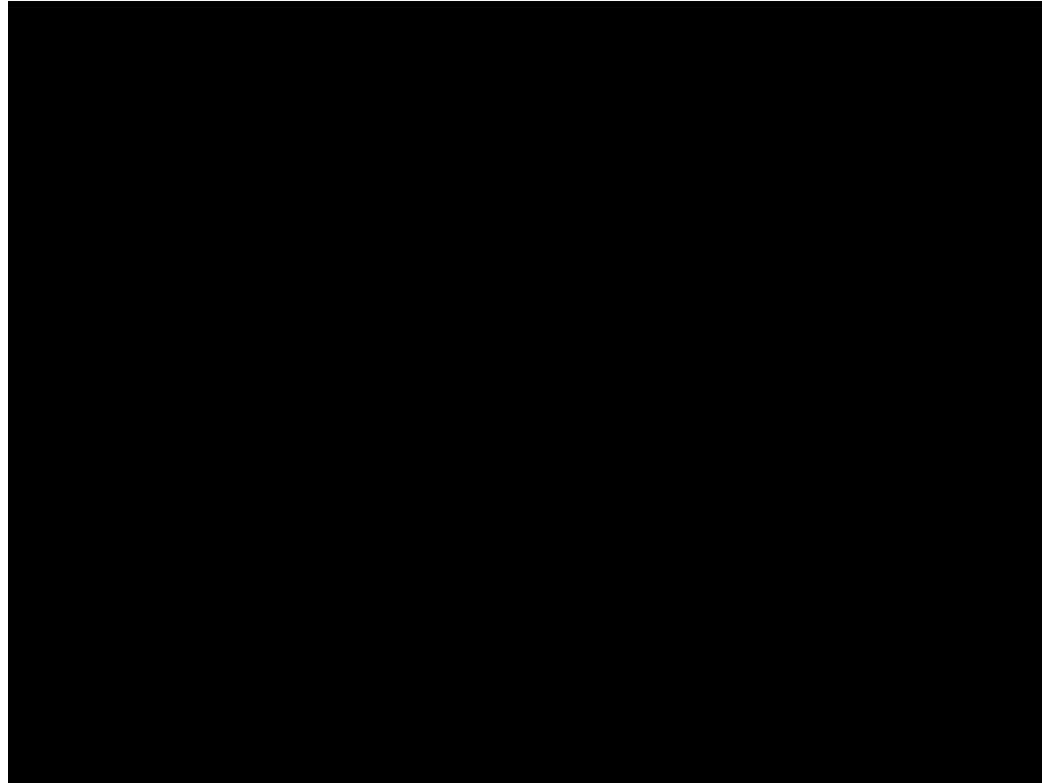


ACKS : Michele Selvaggi, Gregor Krzmann, Jan Kieseler, Philipp Zehetner

[1] Kieseler, J. (2020). Object condensation: one-stage grid-free multi-object reconstruction in physics detectors, graph, and image data. *The European Physical Journal C*, 80, 1-12.

[2] Qasim, Shah Rukh, et al. "Learning representations of irregular particle-detector geometry with distance-weighted graph networks." *The European Physical Journal C* 79.7 (2019): 1-11.

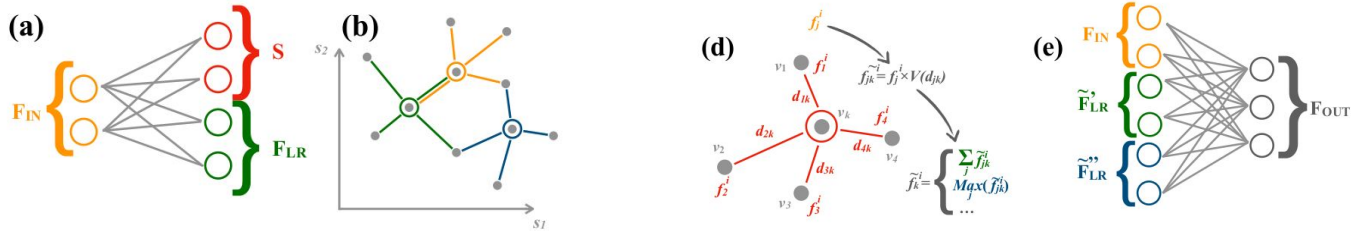
Architecture: Object condensation (End-to-End approach)



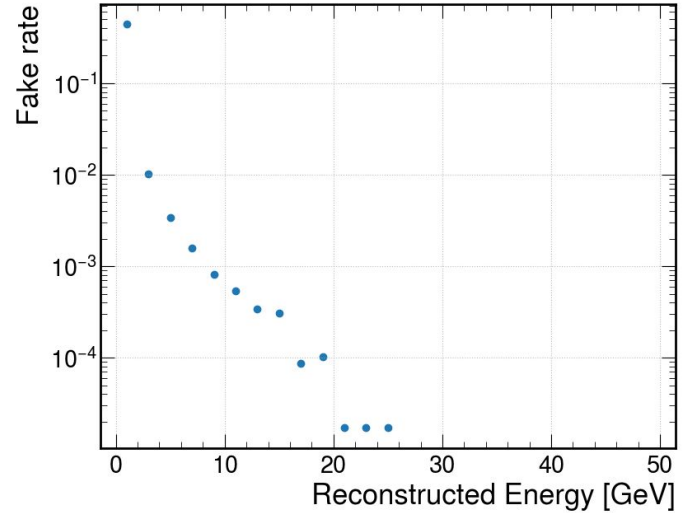
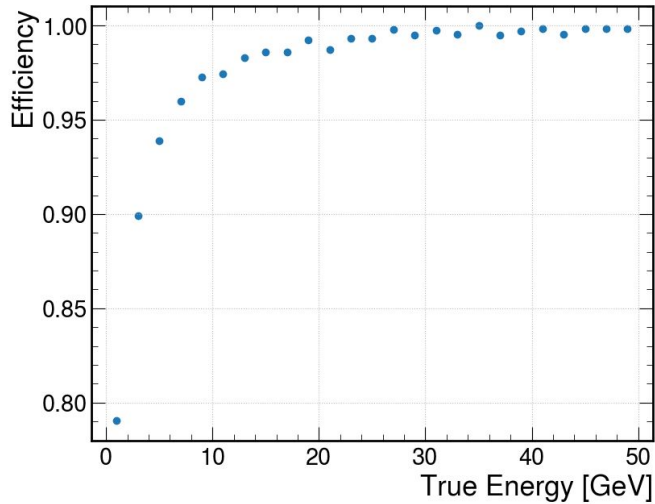
Architecture: Gravnet Model

- Input: a set of hits from different sensors (coordinates, type of hit, energy), each one node in the graph $O(600)$ per particle
- Graph representation with **no given graph structure**
- **Dynamically** compute edges in embedding space with knn

- Transform input features F_{IN} into
 - transformed features F_{LR}
 - latent coordinates S
- Build graph using coordinates S
- Aggregate weighted features
 - Weights depending on distance
 - Aggregation typically is *mean* or *max*
- Concatenate the new features



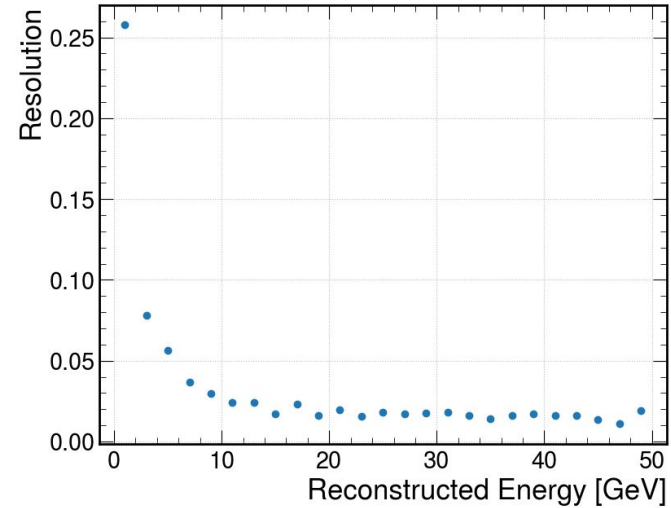
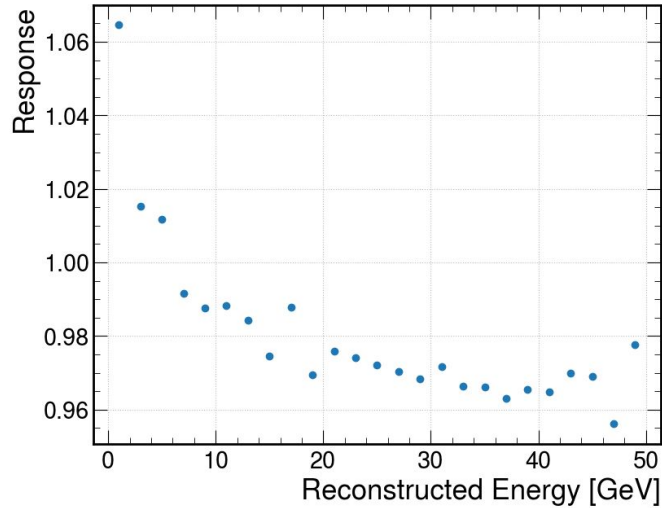
Efficiency and fake rate



- Efficiency approaches 100% with high p_T
- Adding tracks will improve efficiency

- Most fakes with $E < 1$ GeV
- Other clustering methods in the embedding space can improve fakes
- Resulting from bad beta distributions

Response and Resolution (clustering metrics)

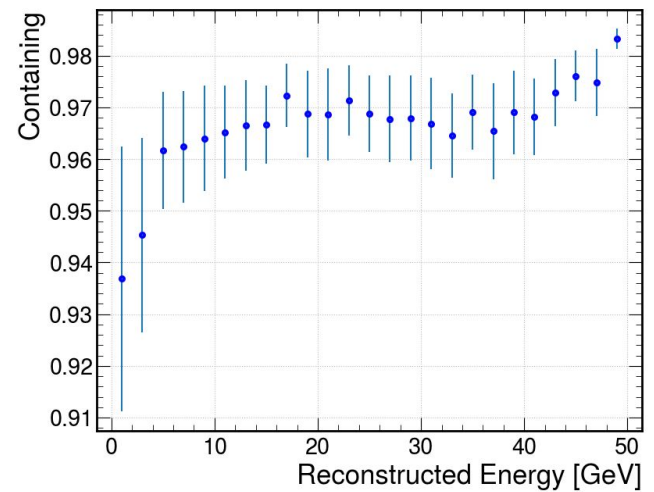
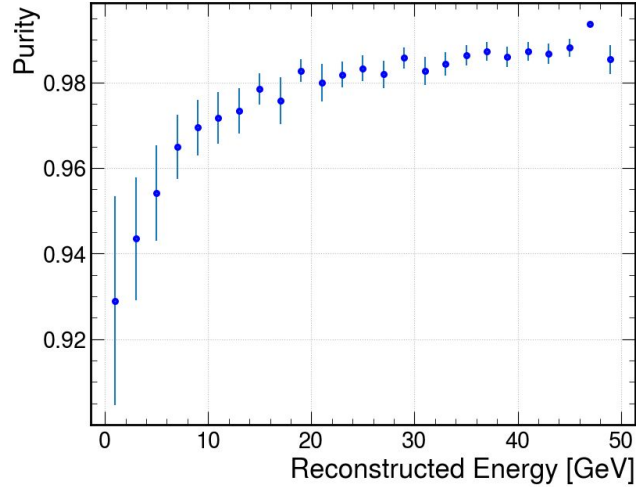
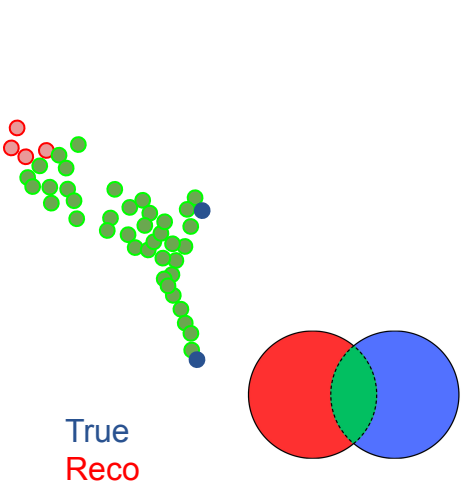


- Evaluated on reco values (for clustering evaluation)

- Resolution performance must be improved for low energies
- Can be improved with better clustering in embedding space

Calorimeter clustering - Results

- Containing: percentage of reco energy that belong to the reconstructed particle $(G+R)/(G+B)$
- Purity: Percentage of reco energy **contained** in reconstructed cluster $(G)/(G+R)$

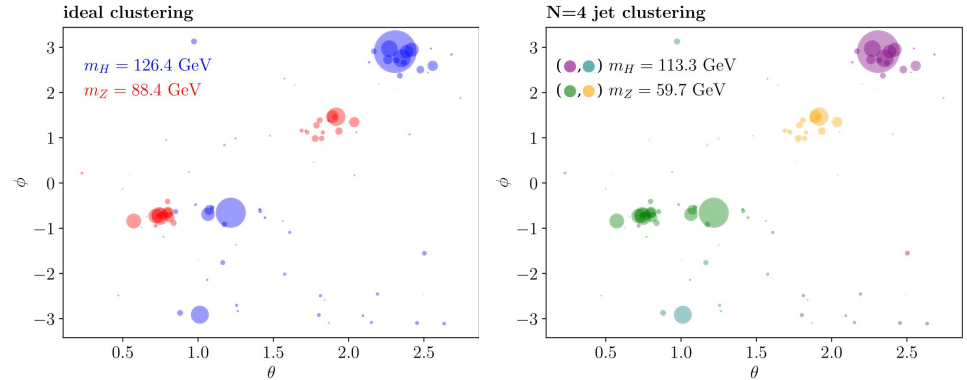


Clustering Color Singlets

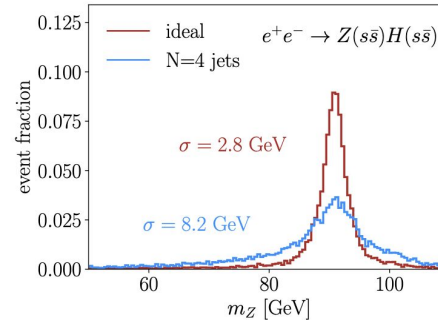
- Identification of color-neutral resonances relies on clustering final state into jets
- Calorimetry is expected to be much improved at future e+e- colliders, so that the 2-jet invariant mass resolution will be dominated not by detector resolution but rather by mis-clustering [1]
- Jets are not well defined but color connection is physical, this may help **improve the mass estimation for color singlets (H,Z,W) and remove more background**

Errors can be due to:

- Miss clustering of soft particles leading to degraded resolution
- Miss matching of bi-jets



A Miss clustering example ZH→sss



B Comparison of clustering performance vs ideal reconstruction



ACKS : Michele Selvaggi

[1] Fujii, K., Grojean, C., Peskin, M. E., Barklow, T., Gao, Y., Kanemura, S., ... & Murayama, H. (2020). ILC study questions for snowmass 2021. *arXiv preprint arXiv:2007.03650*.

[2] Gallicchio, J., & Schwartz, M. D. (2010). Seeing in color: jet superstructure. *Physical review letters*, 105(2), 022001.

Summary and Outlook

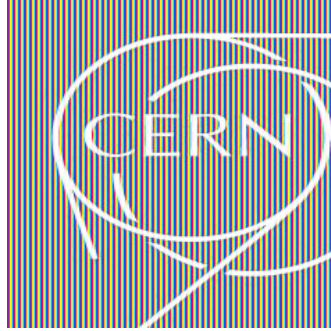
Summary:

- Promising performance, we will soon compare to PFA (baseline for CLD)
- Demonstrated generalization over different types of events (for now kept particle number low)
- Fast execution time, linear scaling with number of hits

Ongoing work and next steps:

- Add tracks as inputs to the graph
- Regress particle properties
- Try heterogeneous graph architectures
- Compare to the performance of PFA





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SUISSE
FRANCE

Genève

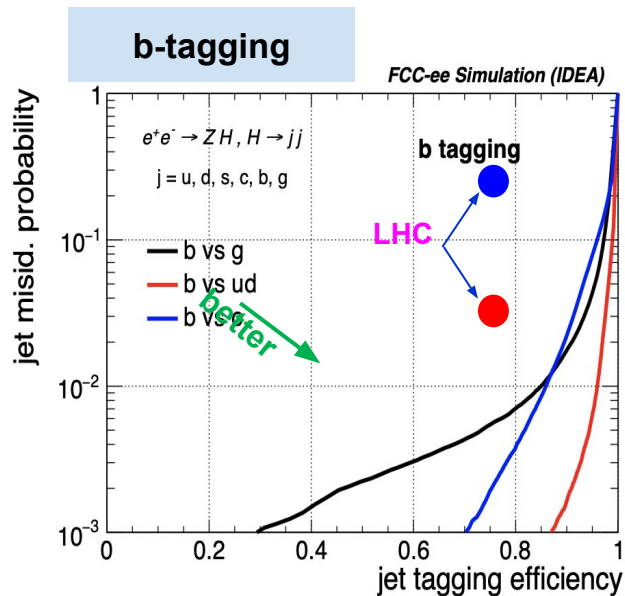
Annecy

LHC

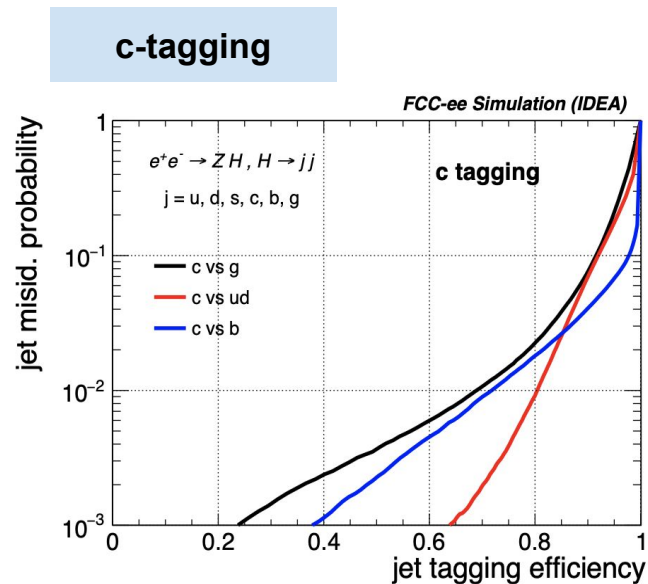
FCC



Results

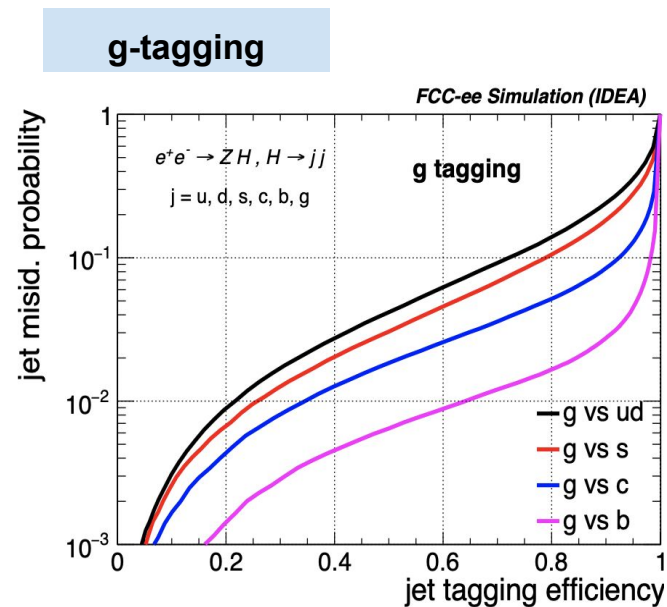
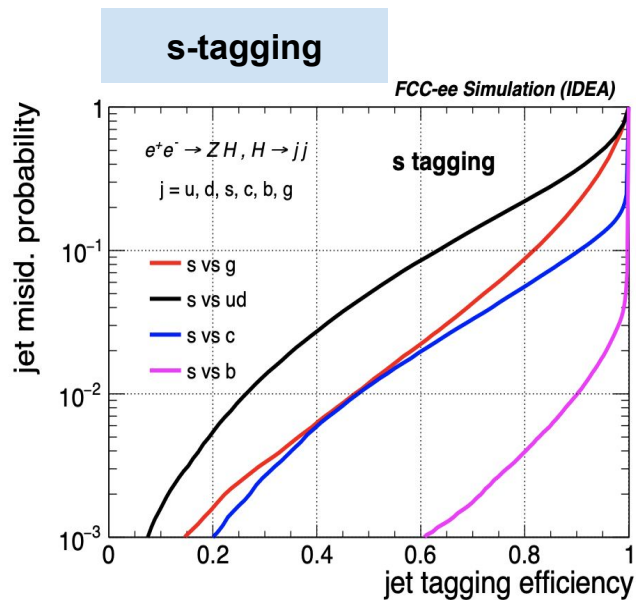


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Loose	90%	2%	0.1%	2%
Medium	80%	0.7%	<0.1%	0.3%



WP	Eff (c)	Mistag (g)	Mistag (ud)	Mistag (b)
Loose	90%	7%	7%	4%
Medium	80%	2%	0.8%	2%

Results



WP	Eff (s)	Mistag (g)	Mistag (ud)	Mistag (c)	Mistag (b)
Loose	90%	20%	40%	10%	1%
Medium	80%	9%	20%	6%	0.4%

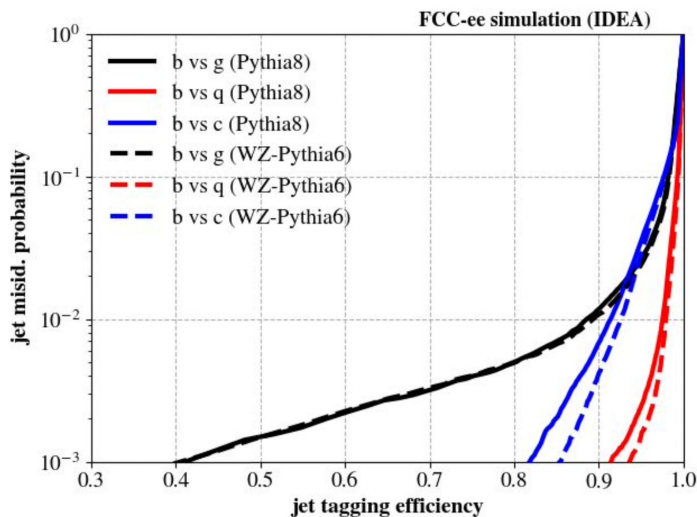
WP	Eff (g)	Mistag (ud)	Mistag (c)	Mistag (b)
Loose	90%	25%	7%	2.5%
Medium	80%	15%	5%	2%

Robustness

ParticleNet-ee trained using *Pythia 8* samples

- tested on *Pythia 8* [solid lines]
- tested on *WZ-Pythia6* [dashed lines]

b-tagging



gluon-tagging

