

The South Pole Acoustic Test Setup

Pressure and shear wave speed vs. depth

Freija Descamps

IceCube **A**coustic **N**eutrino **D**etection working group

Rome, 26 June 2008

ARENA 2008

Outline

Introduction

- SPATS goals
- Previous results

Sound speed results

- Methodology
- Shear waves
- Sound speed results

Conclusions and outlook

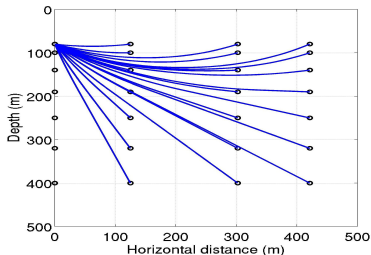
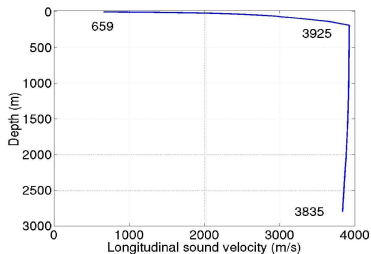
South Pole Acoustic Test Setup: goals

- What are the acoustic properties of the South Pole ice in the 1-100kHz region?

South Pole Acoustic Test Setup: goals

- What are the acoustic properties of the South Pole ice in the 1-100kHz region?
- **Noise**
- **Attenuation length**
- **Sound speed**

Speed-of-sound profile at South Pole



- **Neutrino astronomers**

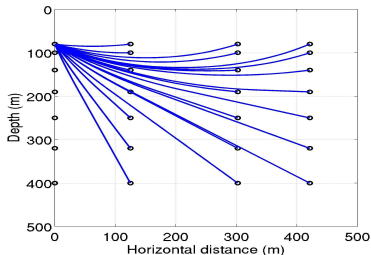
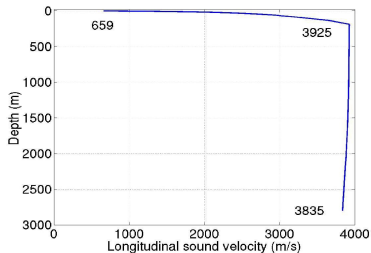
- ▶ What is the sound speed gradient?
- ▶ What is the resulting refraction?
 - pointing resolution
 - background-event rejection

Model

Assumed T-profile:

- predicted v_s profile
- ray tracing for source @-80m

Speed-of-sound profile at South Pole



- **Neutrino astronomers**

- ▶ What is the sound speed gradient?
- ▶ What is the resulting refraction?
 - pointing resolution
 - background-event rejection

- **Glaciologists**

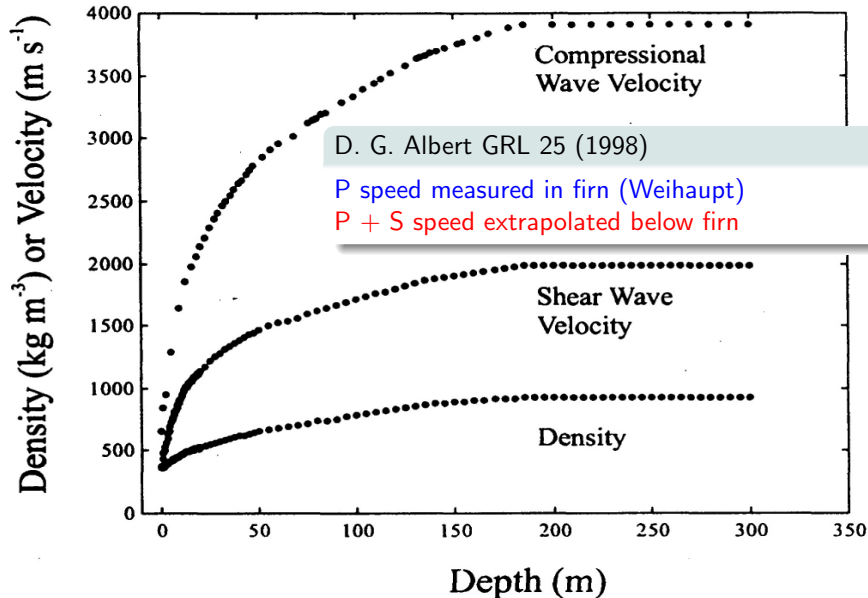
- ▶ How do natural seismic signal propagate?
- ▶ Ice Tomography: map ice-flow
- ▶ SPRESSO scientists have already expressed interest in our results

Model

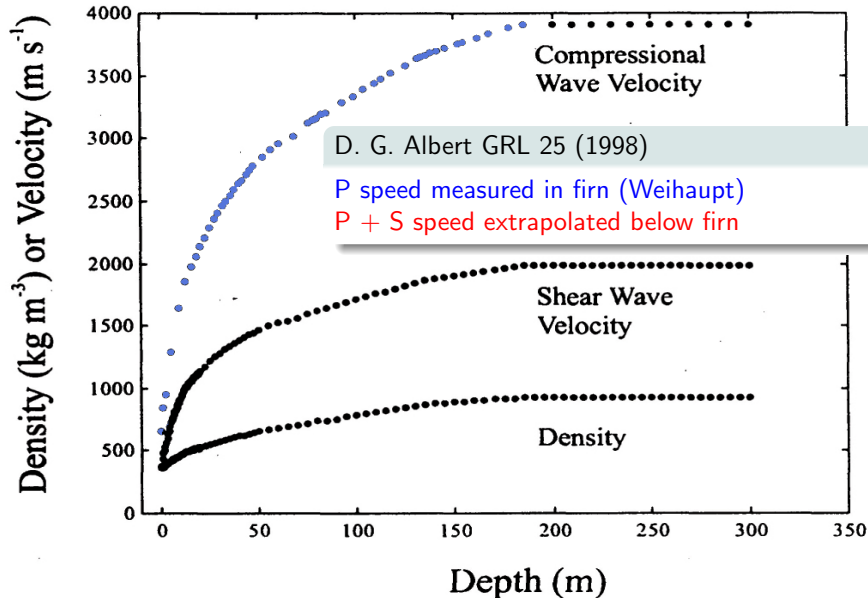
Assumed T-profile:

- predicted v_s profile
- ray tracing for source @-80m

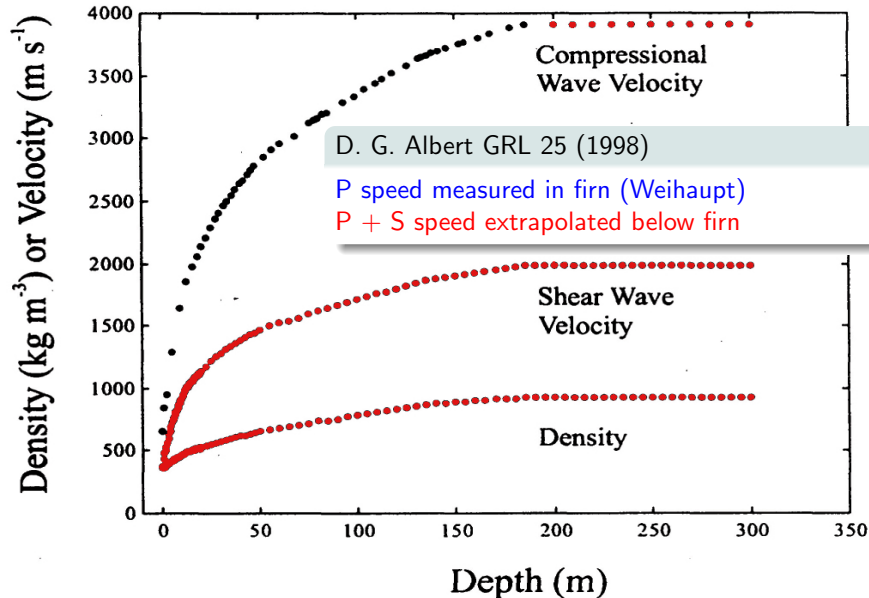
Previous sound speed measurements at South Pole



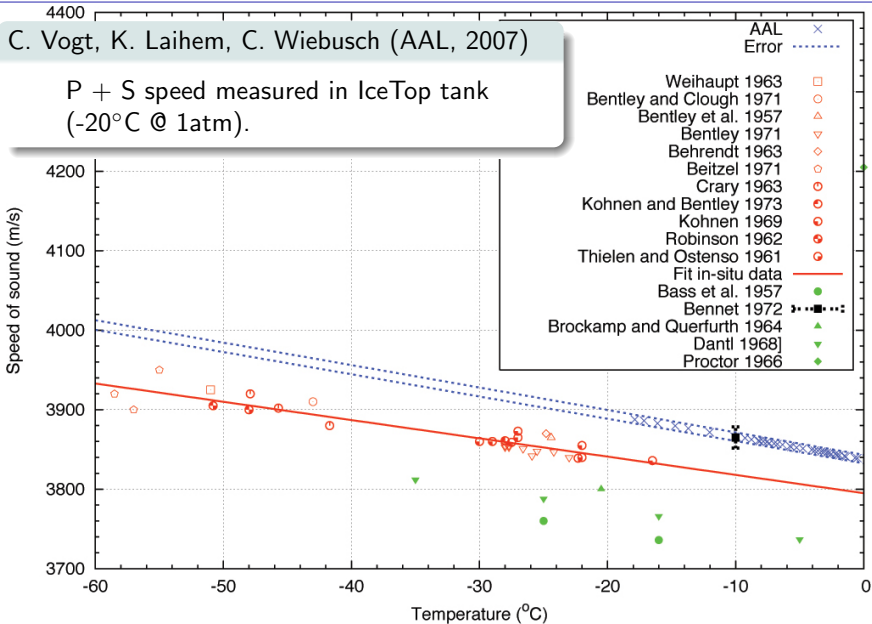
Previous sound speed measurements at South Pole



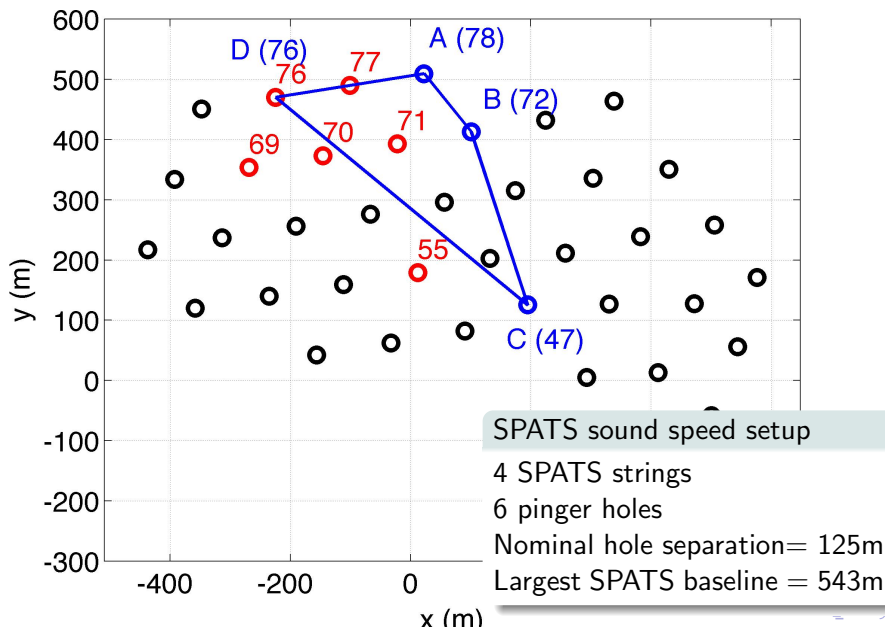
Previous sound speed measurements at South Pole



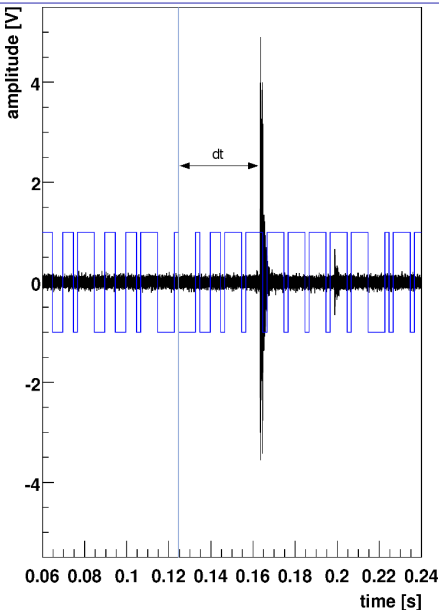
Lab and in-situ speed-of-sound measurements



SPATS: The retrievable pinger



SPATS sound speed: methodology



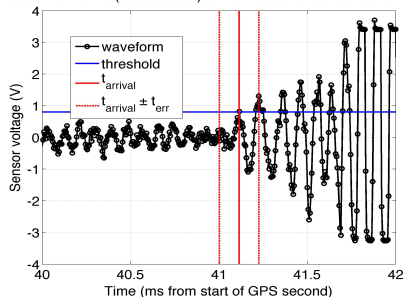
- Time from GPS second start to acoustic emission
- Automated determination of sensor pulse rising edge
- Measurement at all 9 SPATS instrumented depths (each using pinger + sensor at same depth)
- Fit for sound speed gradient in deep ice (250-500 m depth) gives radius of curvature
- All measurements currently for 125m horizontal distance

SPATS sound speed: error budget

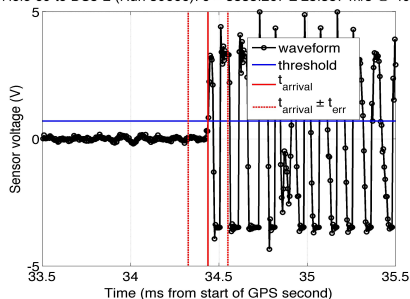
For 125 m baseline:
34 ms time-of-flight:

- $\delta t_{monostable} = \pm 0.1 \text{ ms} = 0.29\%$
- $\delta t_{arrival} = \pm 0.05 \text{ ms} = 0.15\%$
- $\delta r = \pm 0.5 \text{ m} \sqrt{2} = \sim 0.57\%$
 - ▶ because two holes, each 0.5 m in any direction

Hole 71 to BS1-0 (Run 312098): $c = 3173.296 \pm 20.156 \text{ m/s} @ 80 \text{ m}$



Hole 69 to DS5-2 (Run 30666): $c = 3835.267 \pm 25.387 \text{ m/s} @ 400 \text{ m}$



SPATS sound speed: error budget

For 125 m baseline:
34 ms time-of-flight:

- $\delta t_{monostable} = \pm 0.1 \text{ ms} = 0.29\%$
- $\delta t_{arrival} = \pm 0.05 \text{ ms} = 0.15\%$
- $\delta r = \pm 0.5 \text{ m} \sqrt{2} = \sim 0.57\%$
 - ▶ because two holes, each 0.5 m in any direction

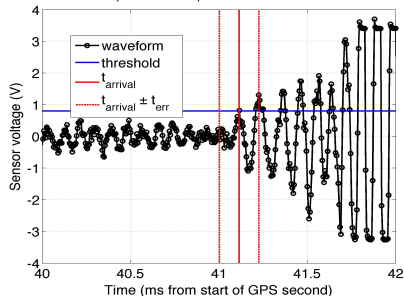
→ error is dominated by baseline

⇒ **Total error = 0.7% for 125 m baseline**

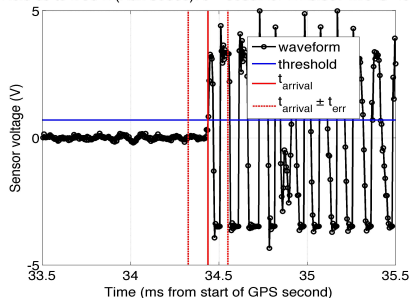
Best possible = 543 m

→ 0.1% or 0.2%

Hole 71 to BS1-0 (Run 312098): $c = 3173.296 \pm 20.156 \text{ m/s} @ 80 \text{ m}$

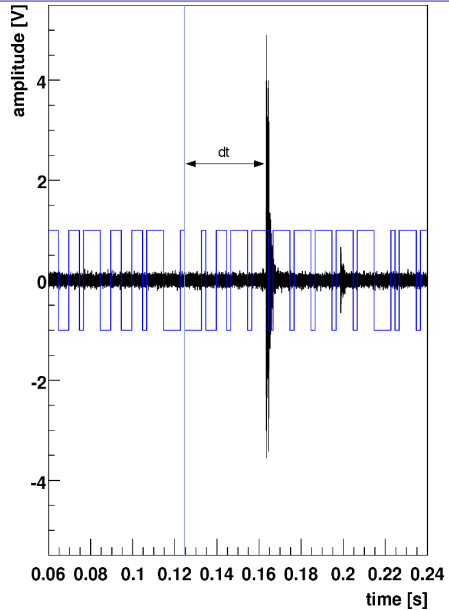


Hole 69 to DS5-2 (Run 30666): $c = 3835.267 \pm 25.387 \text{ m/s} @ 400 \text{ m}$



SPATS shear waves

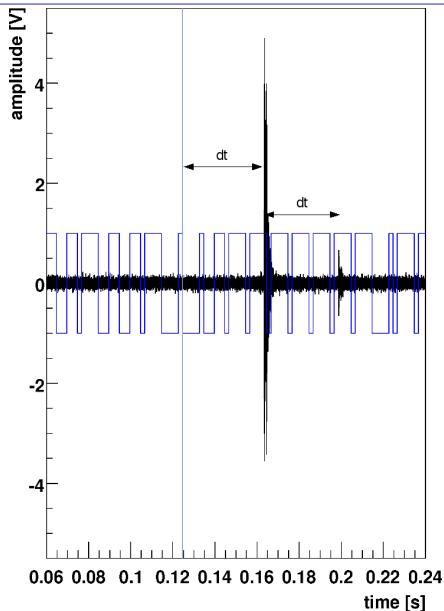
From both pinger and
SPATS transmitter data:



SPATS shear waves

From both pinger and SPATS transmitter data:

- afterpulse
- varying relative amplitude
- only present for $<200\text{m}$ paths
- speed consistent with half of pressure wave speed ...

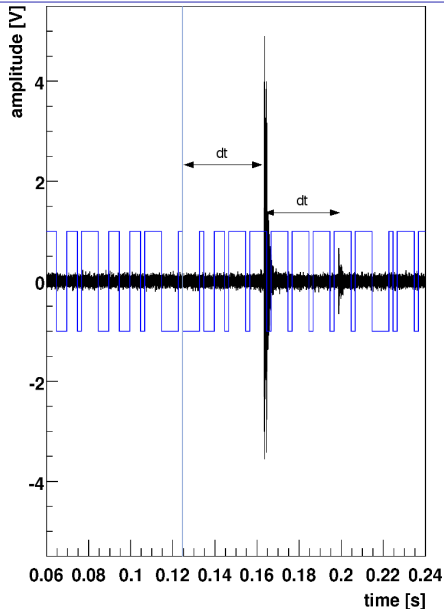
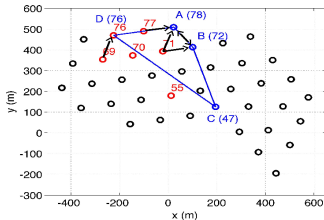


SPATS shear waves

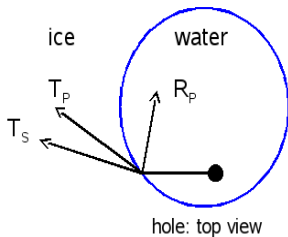
From both pinger and SPATS transmitter data:

- afterpulse
- varying relative amplitude
- only present for $< 200\text{m}$ paths
- speed consistent with half of pressure wave speed ...

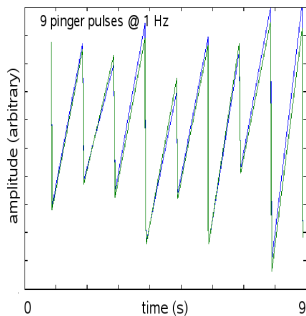
⇒ Detection of shear waves with SPATS!



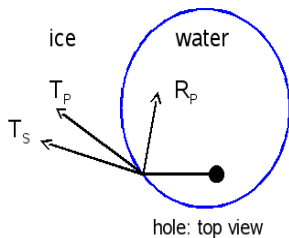
SPATS shear waves



Mode conversion at water/ice interface:



SPATS shear waves



Mode conversion at water/ice interface:

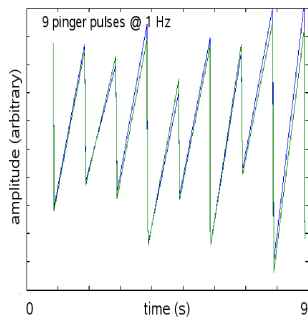
Large incident angle:

increase shear wave amplitude

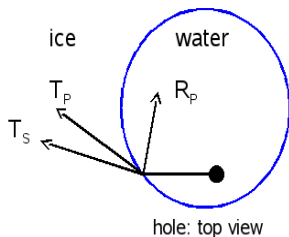
decrease pressure wave amplitude

→ 3D calculation of $\theta_{incident}$

→ $T_P(\theta_i)$, $R_P(\theta_i)$, $T_S(\theta_i)$



SPATS shear waves



Mode conversion at water/ice interface:

Large incident angle:

increase shear wave amplitude

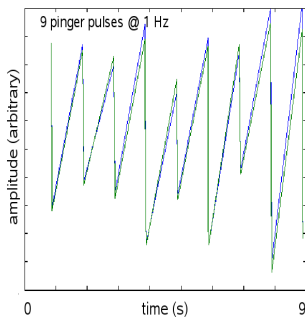
decrease pressure wave amplitude

→ 3D calculation of $\theta_{incident}$

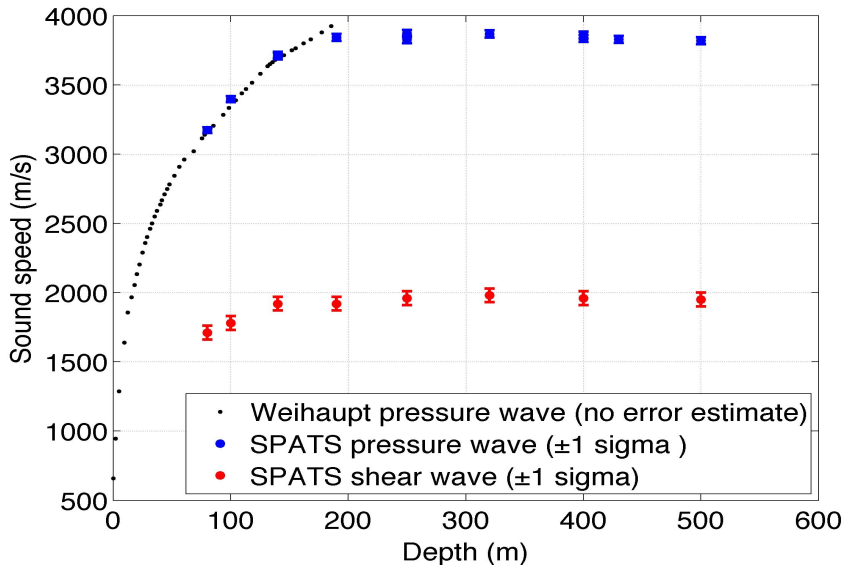
→ $T_P(\theta_i)$, $R_P(\theta_i)$, $T_S(\theta_i)$

Anticorrelation P/S wave amplitudes:

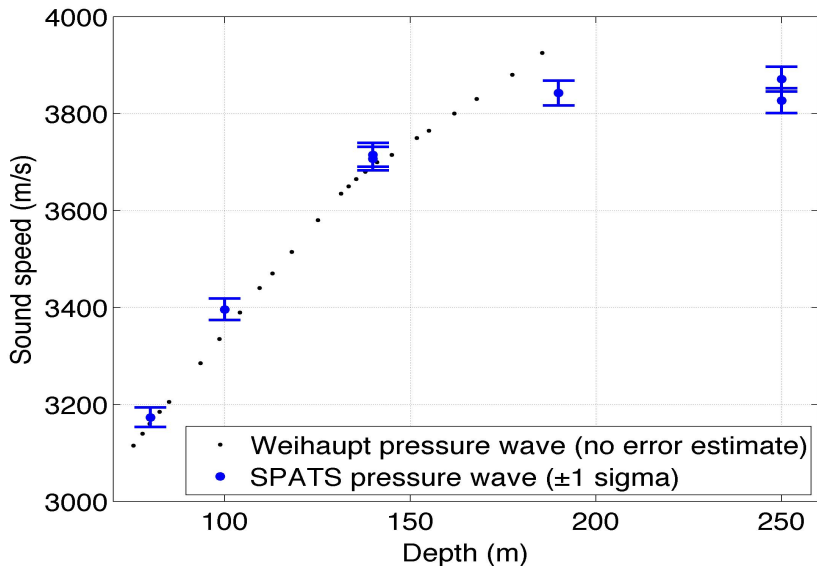
→ total energy is conserved?



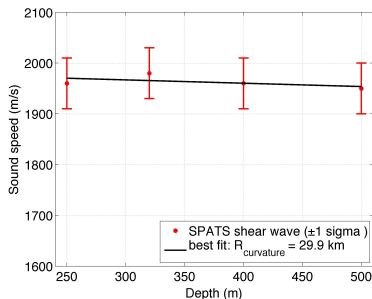
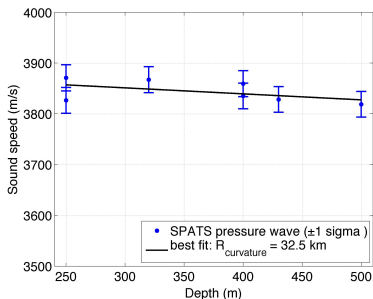
$v_{pressure}$ and v_{shear} vs. depth.



$V_{pressure}$ consistent with previous result in firn



$v_{pressure}$ and v_{shear} constant [250m,500m]



- consistent with no refraction, best fit gives slight refraction:
⇒ $R_{curv} = 32.5\text{km (P)}$ and 29.9km (S)

For a 32.5 km radius:

100 m path deflects 0.154 m, 3 km path deflects 138 m

1 km path deflects 15.4 m \sim acoustic pancake width

Conclusions and outlook

SPATS pressure and shear waves

Sound speed results

Outlook

Conclusions and outlook

SPATS pressure and shear waves

- SPATS pinger data: precise timing achieved
- Shear waves have been detected in SPATS emitters and pinger data.

Sound speed results

Outlook

Conclusions and outlook

SPATS pressure and shear waves

- SPATS pinger data: precise timing achieved
- Shear waves have been detected in SPATS emitters and pinger data.

Sound speed results

- Both P and S wave speeds have been mapped vs. depth in firn and bulk
 - First measurement of P speed in bulk ice
 - First measurement of S speed in both firn and bulk ice
- Refraction is consistent with 0 between 250 and 500m depth.

Outlook

Conclusions and outlook

SPATS pressure and shear waves

- SPATS pinger data: precise timing achieved
- Shear waves have been detected in SPATS emitters and pinger data.

Sound speed results

- Both P and S wave speeds have been mapped vs. depth in firn and bulk
 - First measurement of P speed in bulk ice
 - First measurement of S speed in both firn and bulk ice
- Refraction is consistent with 0 between 250 and 500m depth.

Outlook

- Precision can be improved:
 - Clock drift correction
 - Larger baselines
- New pinger-runs with larger baselines 2008/2009 polar season