# Quantum measurement of weakly coupled fields

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### Introduction

- Q: How can we detect weakly coupled physics?
- Gravitational waves (black hole mergers, stochastic background, ...)
- Axions (dark matter, solar, terrestrially sourced, produced in situ, ...)

An A: Through weak, continuous measurement of quantum sensors

• PVM (
$$\{\mathscr{P}_i\}$$
 :  $\sum_i \mathscr{P}_i = 1$  and  $\mathscr{P}_i \mathscr{P}_j = \delta_{ij}$ ) vs POVM ( $\{\mathscr{O}_i\}$  :  $\sum_i \mathscr{O}_i = 1$ )

There's a simple theoretical framework in which to formulate these systems.

$$\hat{X} = \frac{1}{2}(\hat{a} + \hat{a}^{\dagger}),$$

$$H_{\text{light}} = \omega_c(\hat{x}_m) \left( \hat{X}^2 + \hat{Y}^2 \right)$$

How do physics systems couple to this?

#### Fabry-Pérot interferometer



#### Gravitational wave detection I

$$H_{\rm int} = -\frac{1}{2} \int d^3 \mathbf{x} \, h_{\mu\nu} T^{\mu\nu}$$

$$\begin{array}{l} \text{PD Frame} \quad \frac{1}{2} M L \ddot{h} \hat{x}_{m} \\ \dot{p}_{m} \supset i [H_{\text{int}}, p_{m}] \\ = -\frac{1}{2} M L \ddot{h} \\ \end{array}$$



Gravitational wave (GW) imprints as a force on the test mass (LIGO/VIRGO/...)

#### Gravitational wave detection II

$$H_{\rm int} = -\frac{1}{2} \int d^3 \mathbf{x} \, h_{\mu\nu} T^{\mu\nu}$$

$$\longrightarrow \langle \mathbf{B} \cdot \mathbf{h} \cdot \boldsymbol{\varepsilon} \rangle_V V^{1/2} (\sin \phi \, \hat{X} + \cos \phi \, \hat{Y})$$

Gravitational wave imprints directly on electromagnetic field (CAST, ...)



volume V

$$H_{\rm int} = g_{a\gamma\gamma} \int d^3 \mathbf{x} \, a \mathbf{E} \cdot \mathbf{B}$$

 $\longrightarrow g_{a\gamma\gamma} \langle \mathbf{B} \cdot \boldsymbol{\varepsilon} \rangle_V V^{1/2} a_0 \left( \sin \phi(t) \, \hat{X} + \cos \phi(t) \, \hat{Y} \right)$ 

Axion DM imprints on EM field with stochastic phase



volume V

# Input and output modes

How do we monitor what is happening inside the cavity?



If the in/outgoing modes are linearly coupled to cavity, we have I-O relations [Gardiner, Collett '84]

$$X_{\rm out}(t) = X_{\rm in}(t) + \sqrt{\kappa}X(t)$$

$$Y_{\rm out}(t) = Y_{\rm i}$$

 $V_{in}(t) + \sqrt{\kappa}Y(t)$ 

## I-O for GW I

Read  $Y_{out}$  via homodyne detection:

$$Y_{\text{out}}(\omega) = \underbrace{-2\kappa G^2 \chi_c^2 \chi_m}^{\chi_{YX}(\omega)} X_{\text{in}}(\omega) + \underbrace{\left(1 + \sqrt{\frac{\kappa}{2}} GML \omega^2 \chi_c \chi_m h(\omega)\right)}_{\chi_{Yh}(\omega)}$$

Estimator for gravitational wave strain:  $h_{est}(\omega) = \frac{1}{1}Y_{out}(\omega)$ 



 $\chi_{Yh}$ 

#### Noise in GW detector $10^{-21}$ $10^{-22}$ 2 H $S_{hh}$ $10^{-23}$ $10^{-24}$ $10^{2}$ $10^{1}$ Frequency [Hz]

$$S_{hh}(\omega) = \langle h_{est}(\omega)h_{est}(-\omega) \rangle$$
  
=  $|\chi_{Yh}|^{-2} \left( |\chi_{YX}|^2 S_{XX}^{in} + |\chi_{YY}|^2 S_{YY}^{in} \right)$   
shot-noise back-action

Increasing the optomechanical coupling G increases both  $\chi_{Yh}$  and  $\chi_{YX}$  — optimise!



#### A Quantum "Limit"

We measure an integrated signal, whose noise is char

Heisenberg Uncertainty Principle  $S_{XX}^{in} \cdot S_{YY}^{in} \ge \frac{1}{4} |\langle [$ are uncorrelated,

$$\Delta^2 Y(t) \ge \int_{-\infty}^{\infty} d\omega \, e^{i\omega t} \left( \left| \chi_{YX} \right|^2 S_{XX}^{\text{in}} + \frac{\left| \chi_{YY} \right|^2}{4S_{XX}^{\text{in}}} \right)$$

which is minimised for  $S_{XX}^{\text{in}} = \left|\frac{\chi_{YY}}{2\chi_{YX}}\right|$  [Caves '81]

The noise is bounded:  $\Delta^2$ 

The aracterized by 
$$\Delta^2 Y(t) = \int_{-\infty}^{\infty} d\omega \, e^{i\omega t} \, S_{YY}^{\text{out}}(\omega);$$

$$[X_{\rm in}, Y_{\rm in}]\rangle\Big|^2$$
 implies that, if  $X_{\rm in}$  and  $Y_{\rm in}$ 

$$Y(t) \ge \int_{-\infty}^{\infty} d\omega \, e^{i\omega t} \, |\chi_{YX} \, \chi_{YY}|$$

#### **Beyond the Standard Quantum Limit**

Two ways to beat the SQL:

#### 1. Squeeze/rotate: $S_{XY}^{in} \neq 0$



#### 2. Back-action evasion (BAE): $\chi_{YX} \rightarrow 0$

$$S_{YY}^{\text{out}} = |\chi_{YY}|^2 S_{YY}^{\text{in}}$$

 $S_{YY}^{\text{out}} \rightarrow 0$  in a Y-eigenstate

# Beyond SQL for GWs



# I-O for homodyne axion search

Measurement noise arises only from variance in  $Y_{in}$ :

 $S_{aa}$ 

Fixed cavities have no back-action.



$$=\frac{\chi_{YY}}{\chi_{Ya}}S_{YY}^{\rm in}$$



#### Homodyne detection as back-action evasion

Homodyne detection lets us measure the Schr

Since  $a_{\rm H}(t) = e^{-i\omega_0 t} a_{\rm S}$ , the observable is cons

No back-action when measuring conserved qui may be better to measure number operator (se

(If mirror is free to move,  $a_{\rm H}(t) = e^{-i \int \omega_c(\hat{x}) dt} a_{\rm S} \neq$ 

Födinger picture operator 
$$Y_{\rm S}(t) = \frac{1}{\sqrt{2}} \left( a^{i\omega_0 t} a_{\rm S} + e^{-i\omega_0 t} a_{\rm S}^{\dagger} \right)$$
  
served:  $\frac{dY_{\rm H}}{dt} = i[H, Y_{H}] + \partial_t Y_{\rm S} = 0$   
Uantities. Despite BAE, still  
see previous talks)!

$$\neq e^{-\iota\omega_0 t}a_{\rm S}$$
, so no BAE in general)



## Lossy cavities and axions

Cavity loss implies we have other input/output ports apart from measurement port:

$$Y_{\text{out}}^{m} = \chi_{mm} Y_{\text{in}}^{m} + \chi_{ml} Y_{\text{in}}^{l} + \chi_{m}$$
$$S_{aa} = |\chi_{ma}|^{-2} \left( |\chi_{mm}|^{2} S_{YY}^{m} \right)^{2}$$

The axion frequency/mass is unknown; maximise the Fisher information/scan rate by tuning  $\kappa_m = 2e^{-2r}\kappa_l$ 





### Conclusions

- Input-output theory gives a useful, unified framework in which to understand noise (including quantum, thermal, intrinsic losses, etc.) in weak, continuous measurements
- There are simple pipelines to go from physical couplings, to signal and noise, to physics reach of many detectors

Thank you!