

Generating Accurate Showers in Highly Granular Calorimeters Using Normalizing Flows

Thorsten Buss, Sascha Diefenbacher, Frank Gaede,
Gregor Kasieczka, Claudius Krause, David Shih

thorsten.buss@uni-hamburg.de

Institut für Experimentalphysik
Universität Hamburg

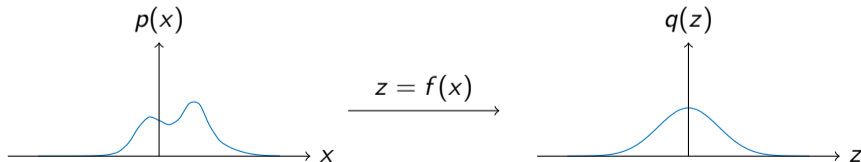
May 31, 2023

Normalizing Flows

- diffeomorphism between physics space and latent space
- transform physics space distribution into a simple prior distribution
- change of variables formula allows for physics space density estimation
- training: minimize negative log-likelihood
- generation: sample from latent distribution and apply inverse of function

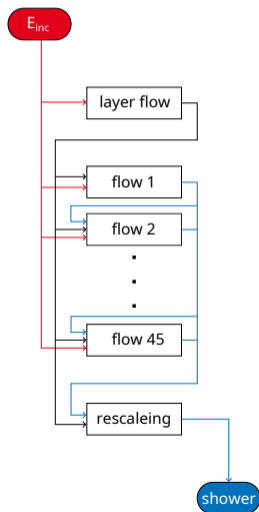
$$p(x) = q(f(x)) |J(x)|$$

$$\mathcal{L} = -\log q(f(x)) - \log|J(x)|$$



- based on CaloFlow¹ and L2L Flow²
- one layer flow
 - learns distribution of layer energies
 - conditioned on incident energy
- 45 multiple flows
 - learn shower shape in layer
 - conditioned on
 - incident energy
 - layer energy
 - previous layers (up to five)
 - convolutional architecture
- generation
 - sample layer energies using layer flow
 - sample shower shape using multiple flows
 - rescale voxel energies

Architecture



¹Claudius Krause and David Shih. *CaloFlow: Fast and Accurate Generation of Calorimeter Showers with Normalizing Flows*. 2021. arXiv: 2106.05285.

²Sascha Diefenbacher et al. *L2LFlows: Generating High-Fidelity 3D Calorimeter Images*. 2023. arXiv: 2302.11594.

Layer Flow

pre/post-processing:

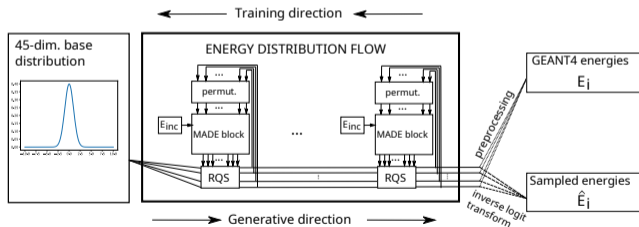
- $x \rightarrow \logit\left(\frac{x}{x_{max}}\right)$
- $c = 2 \log_{10}\left(\frac{e_{inc}}{\text{GeV}}\right) - 3$
- add gaussian noise
- veto high energy ratios

MADE block:

- masked NN
- guarantees invertibility
- gives spline parameters

training:

- initial learning rate: 10^{-3}
- optimizer: Adam
- scheduler: exponential
- batch size: 1024
- epochs: 2000



graphic modified from [2110.11377 and 2302.11594]

Multiple Flows Components

pre/post-processing:

- $x \rightarrow \text{logit}\left(\frac{x}{x_{\max}}\right)$
- $c_1 = 2 \log_{10}\left(\frac{e_{\text{inc}}}{\text{GeV}}\right) - 3$
- $c_2 = \log_{10}\left(\frac{e_i}{\text{GeV}}\right) + 1$
- add log normal noise
- apply cut at 1.5×10^{-5} GeV

squeezes³:

- exchange spacial dimensions for channels by stacking pixels
- use asymmetrical squeezes
- squeezes factors are prime factors of #dimensions

activation norm⁴:

- normalize to $\mu = 0$ and $\sigma = 1$
- initialize on batch one
- then trainable parameters

spline coupling block⁵:

- split along channels
- cubic spline
- convolutional subnet

1×1 convolution⁴:

- replaces permutation
- LU decomposed linear transformation

³Laurent Dinh, Jascha Sohl-Dickstein, and Samy Bengio. *Density estimation using Real NVP*. 2017. arXiv: 1605.08803.

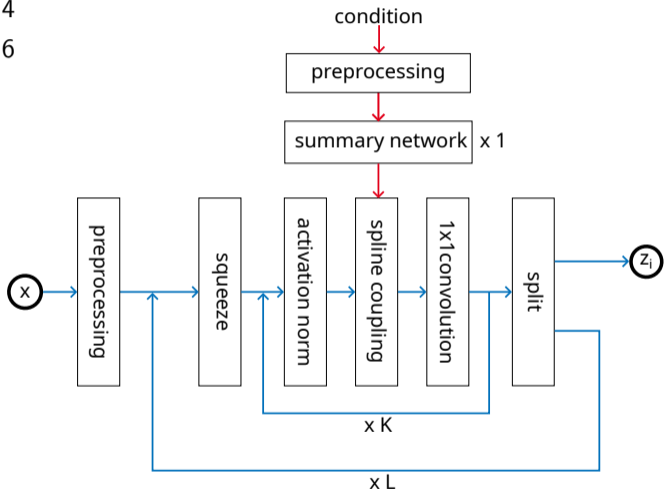
⁴Diederik P. Kingma and Prafulla Dhariwal. *Glow: Generative Flow with Invertible 1x1 Convolutions*. 2018. arXiv: 1807.03039.

⁵Conor Durkan et al. *Cubic-Spline Flows*. 2019. arXiv: 1906.02145.

Multi-scale Architecture

$$K = 4$$

$$L = 6$$



Subnets

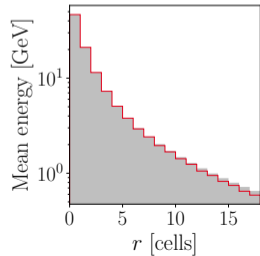
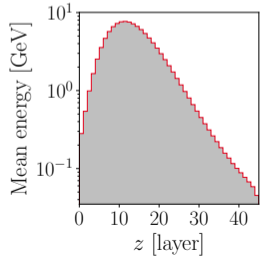
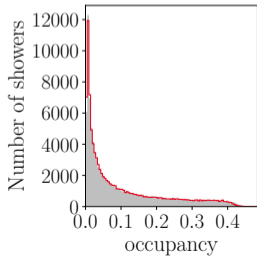
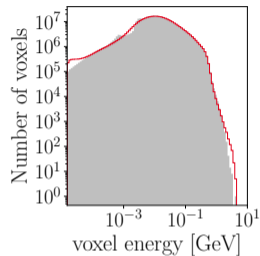
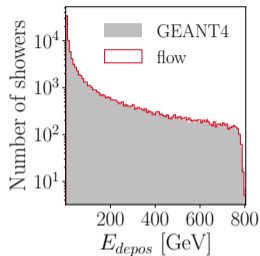
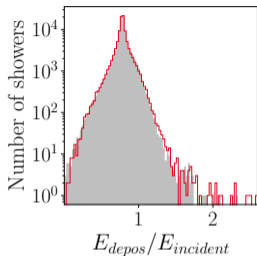
summary network:

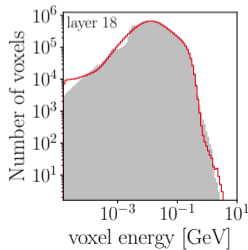
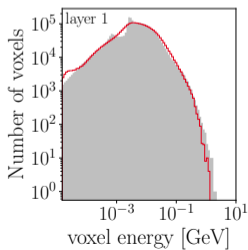
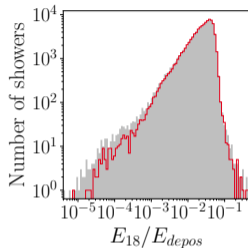
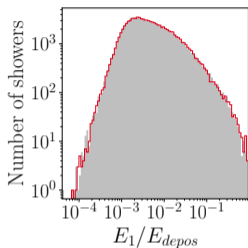
- input
 - five previous layers
 - incident energy
 - deposited energy in layer i
- output
 - one output per squeeze
 - shape: $8 \times n_\alpha \times n_r$
- network layer
 - 1×1 convolution
 - additional per squeeze
 - 3×3 convolution (cylindrical padding)
 - down sampling (max pooling or stride)
 - 3×3 convolution (cylindrical padding)
 - activation: LeakyReLU

subnets:

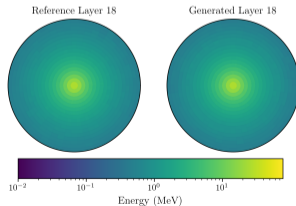
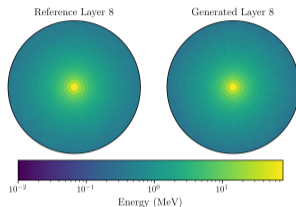
- input
 - untransformed channels
 - summarized condition
- output
 - spline parameters for transformed channels
- layer
 - 1×1 convolution
 - 3×3 convolution
 - cylindrical padding
 - 3×3
 - cylindrical padding
 - activation: LeakyReLU

Dataset 3





Dataset 3



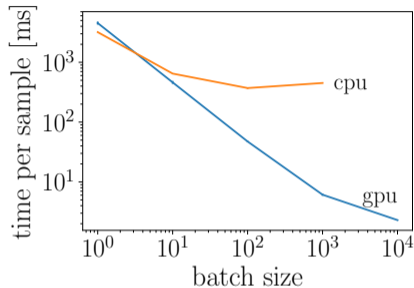
Metrics

LL-Classifier	AUC	JSD
dataset 2	0.81	0.22
dataset 3	0.80	0.22
HL-Classifier	AUC	JSD
dataset 2	0.79	0.20
dataset 3	0.87	0.35

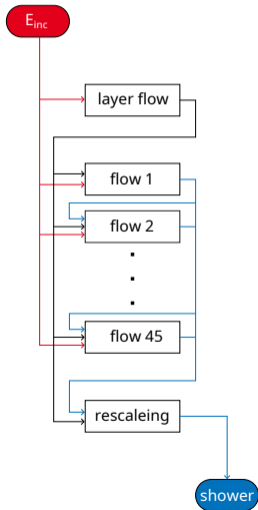
χ^2	dataset 2	dataset 3
Voxel spectrum	2.8×10^{-3}	4.6×10^{-3}
E_{tot}/E_{inc}	1.6×10^{-3}	1.7×10^{-3}
E_1	1.4×10^{-3}	8.7×10^{-4}
E_{10}	1.6×10^{-4}	3.5×10^{-4}
E_{30}	5.5×10^{-3}	7.5×10^{-3}
E_{45}	9.8×10^{-3}	1.7×10^{-2}
$\mu_{\eta 1}$	3.0×10^{-3}	2.9×10^{-3}
$\mu_{\eta 10}$	1.9×10^{-3}	2.1×10^{-3}
$\mu_{\eta 30}$	5.2×10^{-3}	8.8×10^{-3}
$\mu_{\eta 45}$	5.5×10^{-3}	5.9×10^{-3}

- results for dataset 3
- comparison of generation times
- hardware:
 - cpu: Intel[®] Xeon[®] E5-2640
 - gpu: NVIDIA[®] A100[®]
- #threads for cpu case: 1

Timing

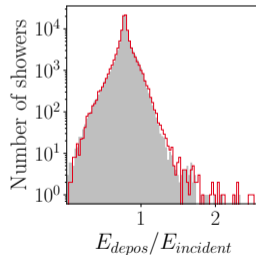
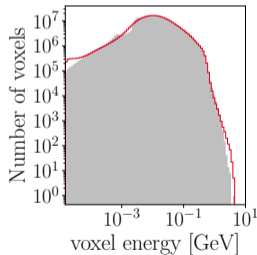


Hardware	Batch size	time [ms]
CPU	1	3194.46
	10	647.45
	100	370.86
GPU	1	4531.97
	1000	6.11



Conclusion

- convolutional flows scale well with input dimensions
- evaluation of inverse in almost same time
- flows can generate highly accurate showers



Regular ILD Dataset

