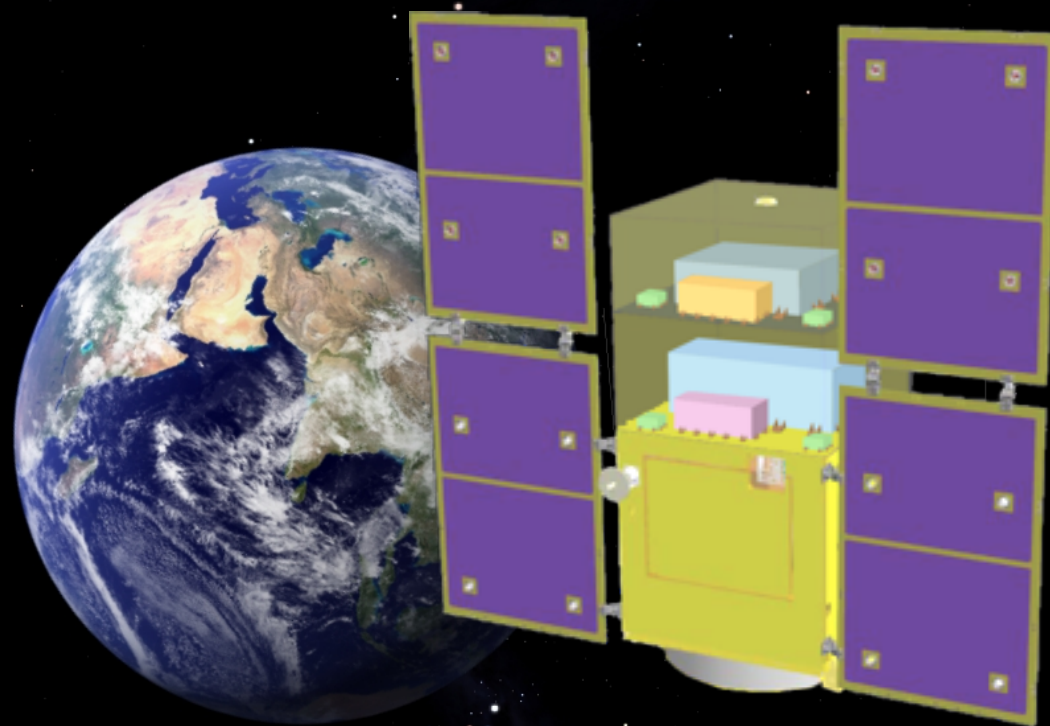


DECIGO and DECIGO Pathfinder



DPF Fig by M.Ando

Tomotada Akutsu
National Astronomical Observatory of Japan
on behalf of DECIGO Working Group

GWADW2011 in Isola d'Elba, Italy (24 May 2011)

Contents

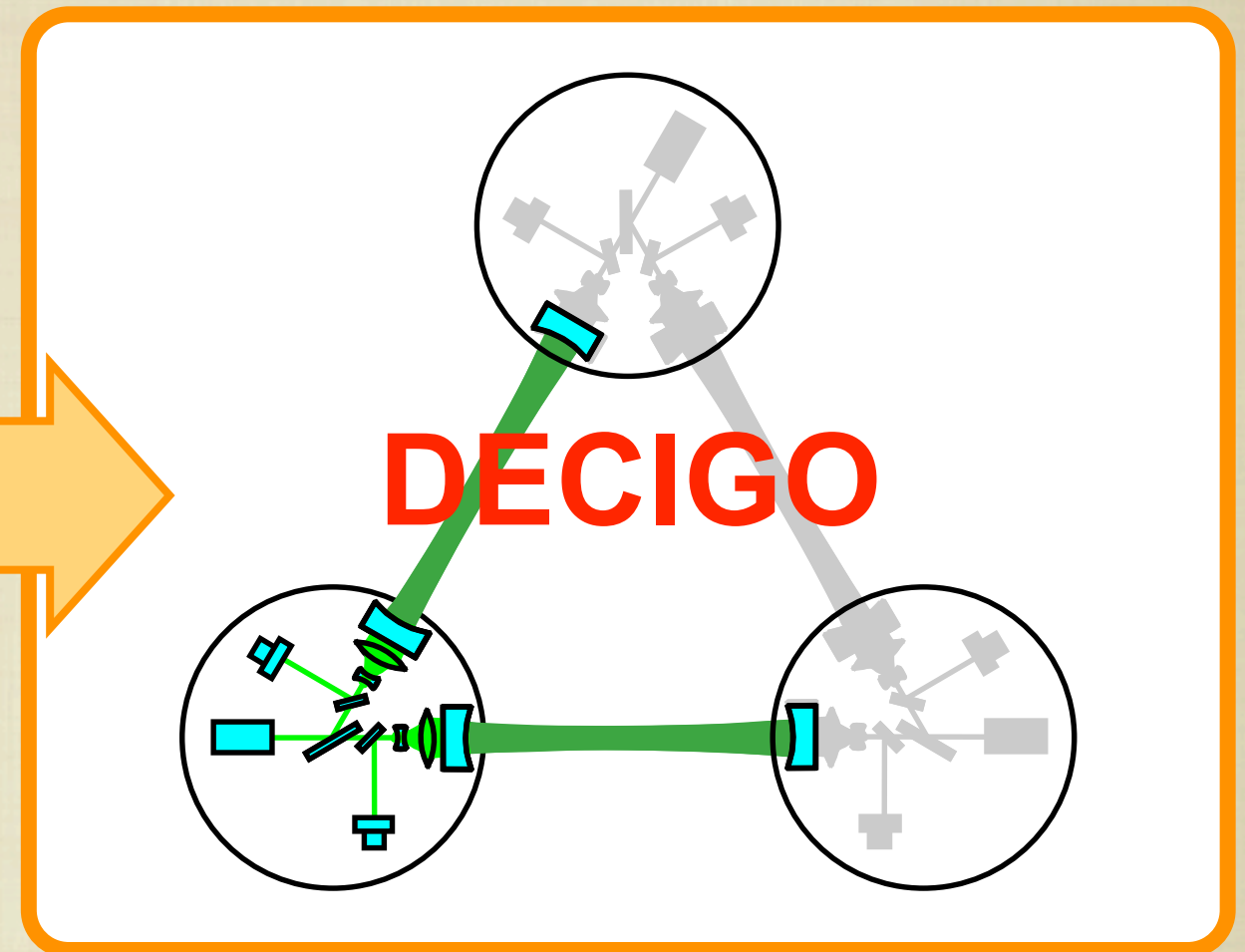
- 1. DECIGO**
- 2. DECIGO Pathfinder (DPF)**
- 3. Summary**

Some of the viewgraphs are owing to S. Kawamura, M. Ando, and other members of DECIGO Working Group.

Roadmap to GW astronomy of Japan



Detecting GW
International network



Opening a new window
(*after LISA*)

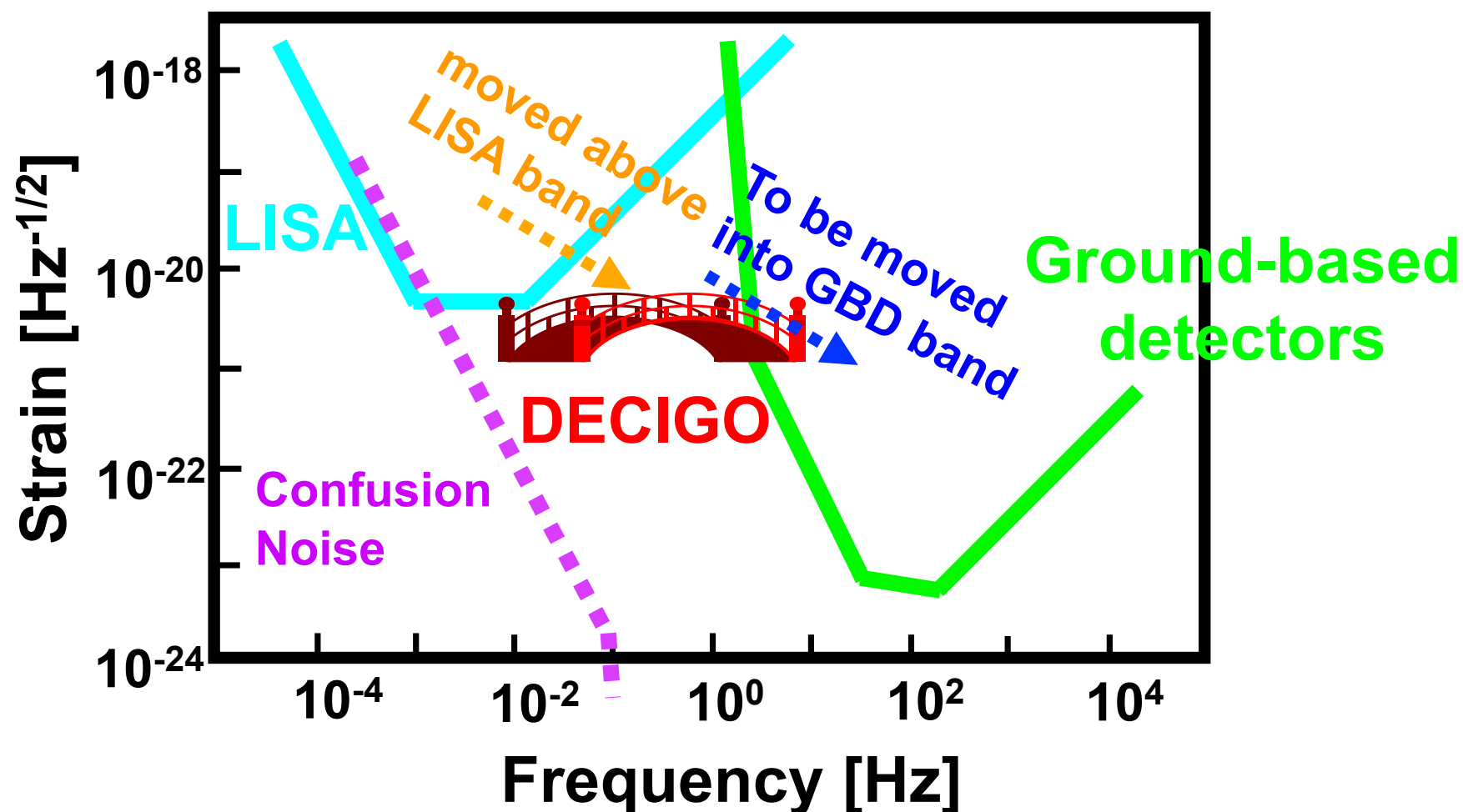
1. DECIGO

2. DECIGO Pathfinder (DPF)

3. Summary

DECIGO

- **Deci**-hertz interferometer **g**ravitational-wave **o**bservatory
 - * “**bridge**” the gap between **LISA** and **terrestrial detectors**
 - * Observation band: 0.1~10Hz
 - * **Space** GW antenna



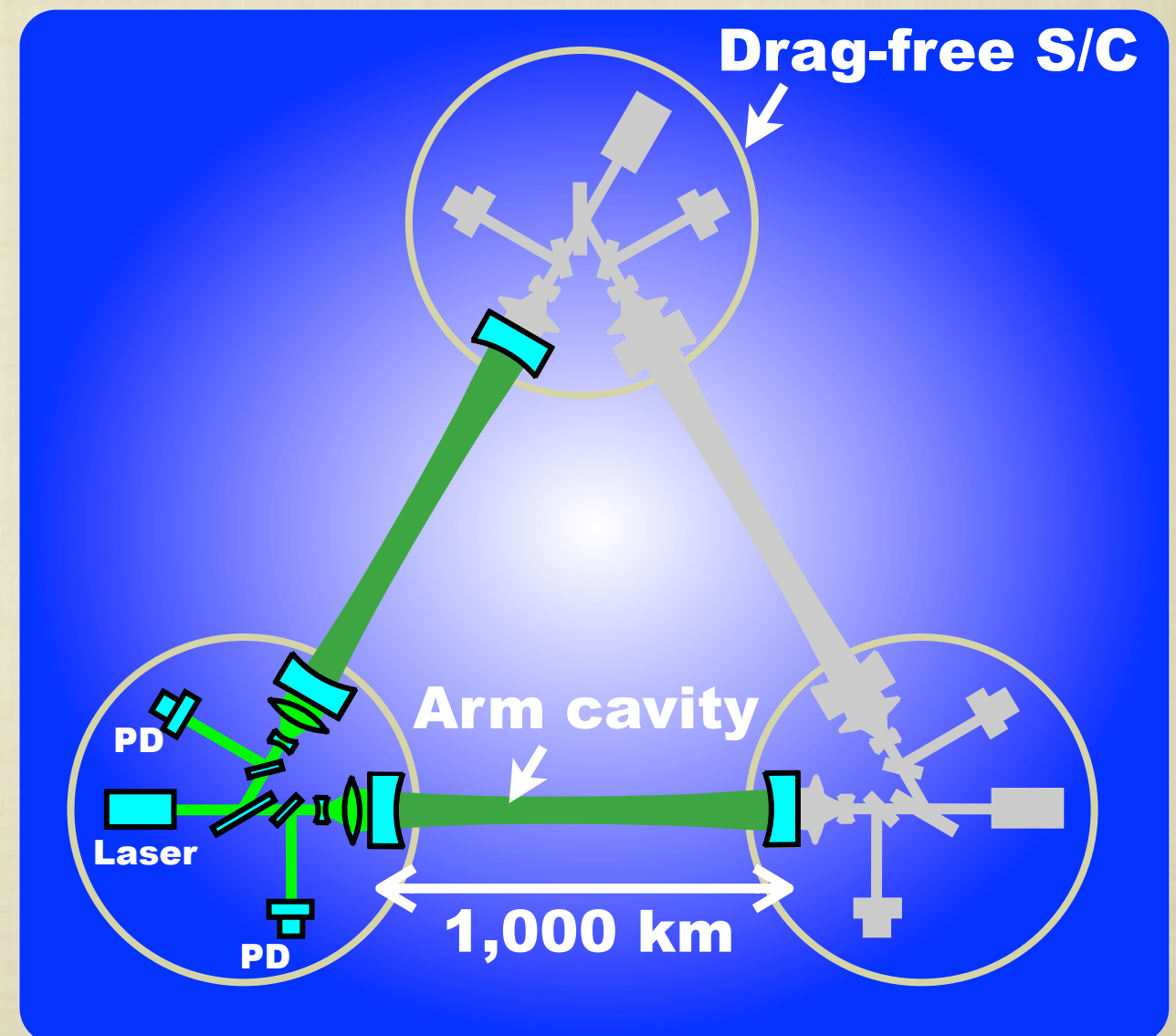
Design (pre-conceptual)

■ Interferometer Unit

* Differential Fabry-Perot interferometer

- * Baseline length: **1000km**
- * 3 S/Cs formation flight
- * 3 FPs (finesse: ~ 10)
- * Drag-free control

Arm length:	1000 km
Finesse:	10
Mirror diameter:	1 m
Mirror mass:	100 kg
Laser power:	10 W
Laser wavelength:	532 nm



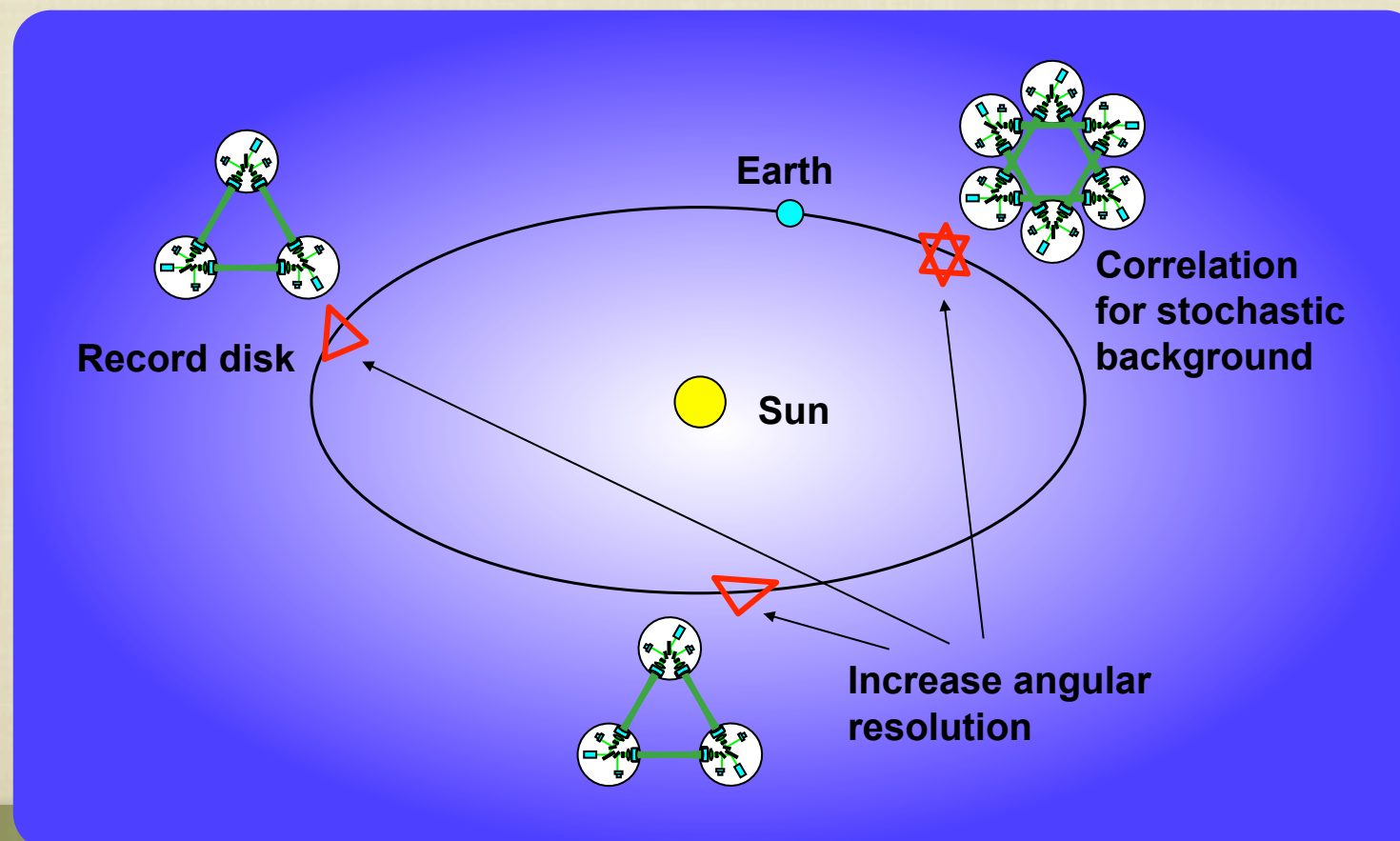
Orbit and constellation

■ Candidate Orbit

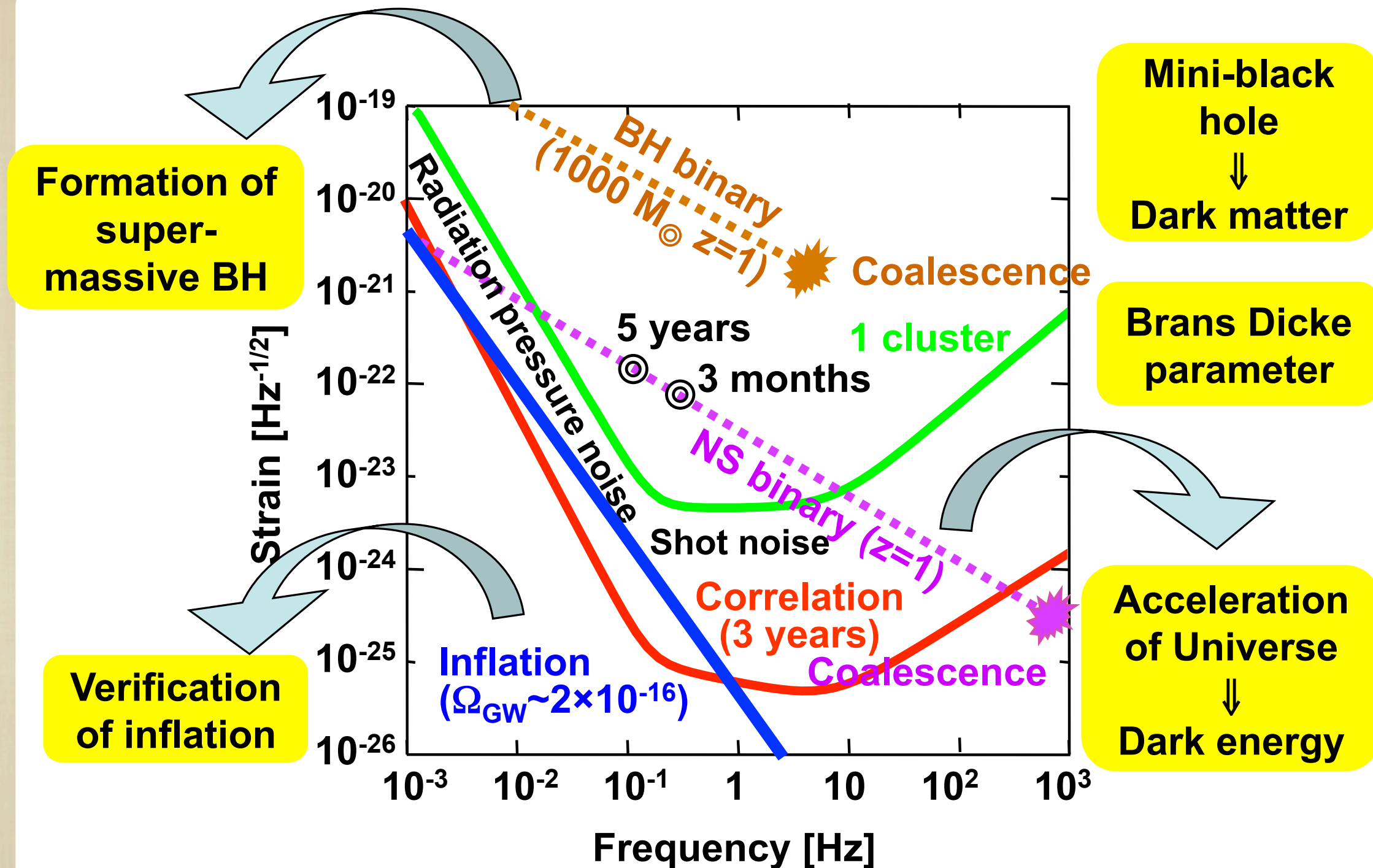
- * Record disk around the sun

■ Constellation

- * 4 interferometer units
 - * 2 overlapped units → Cross correlation
 - * 2 separated units → angular resolution



Science by DECIGO



Requirements

Sensor Noise

Shot noise $3 \times 10^{-18} \text{ m/Hz}^{1/2}$ (0.1 Hz)

⇒ x 10 of LCGT in phase noise

Other noises should be well below the shot noise

Laser freq. noise: $1 \text{ Hz/Hz}^{1/2}$ (1Hz)

Stab. Gain 10^5 , CMRR 10^5

Acceleration Noise

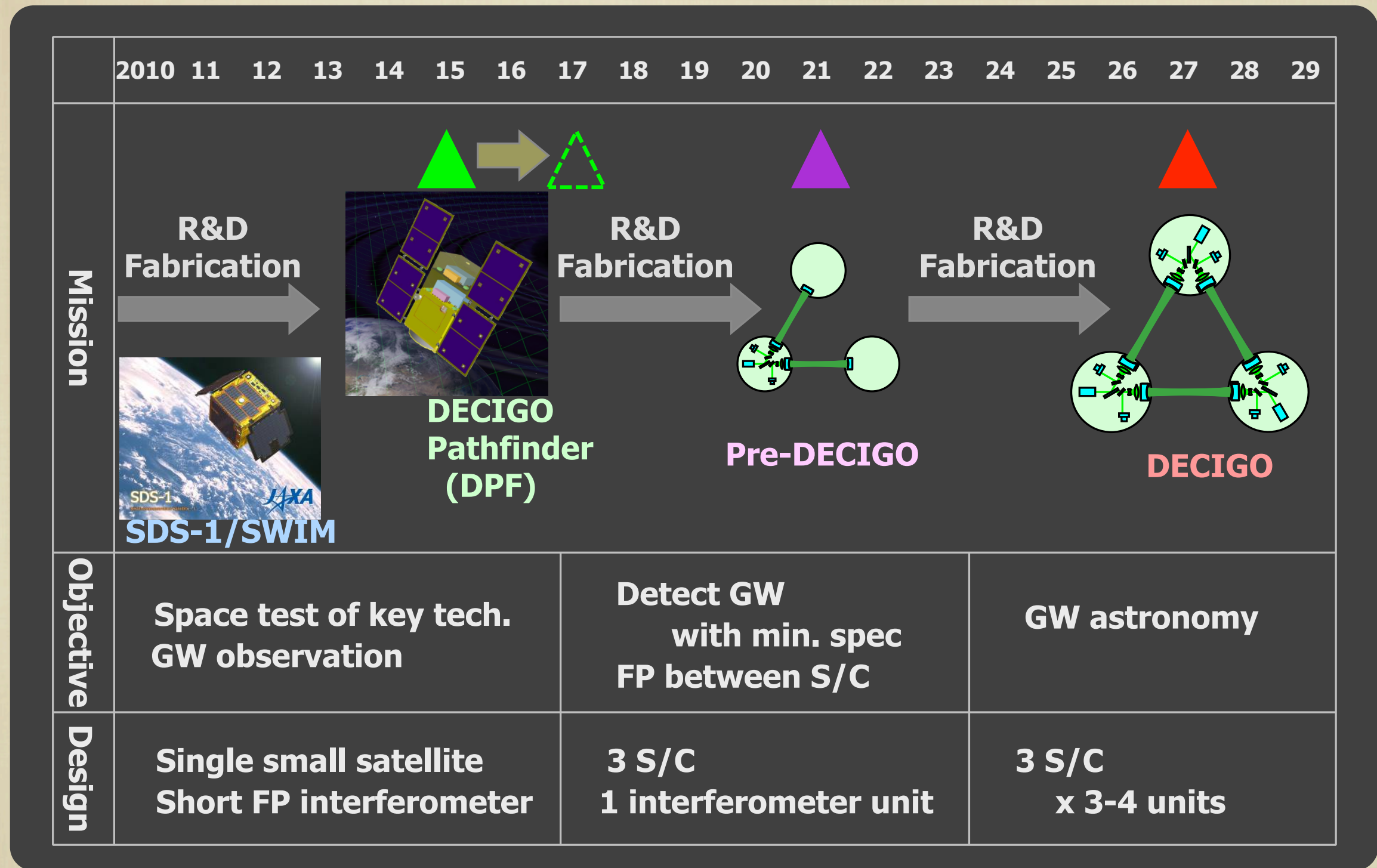
Force noise $4 \times 10^{-17} \text{ N/Hz}^{1/2}$ (0.1 Hz)

⇒ x 1/50 of LISA

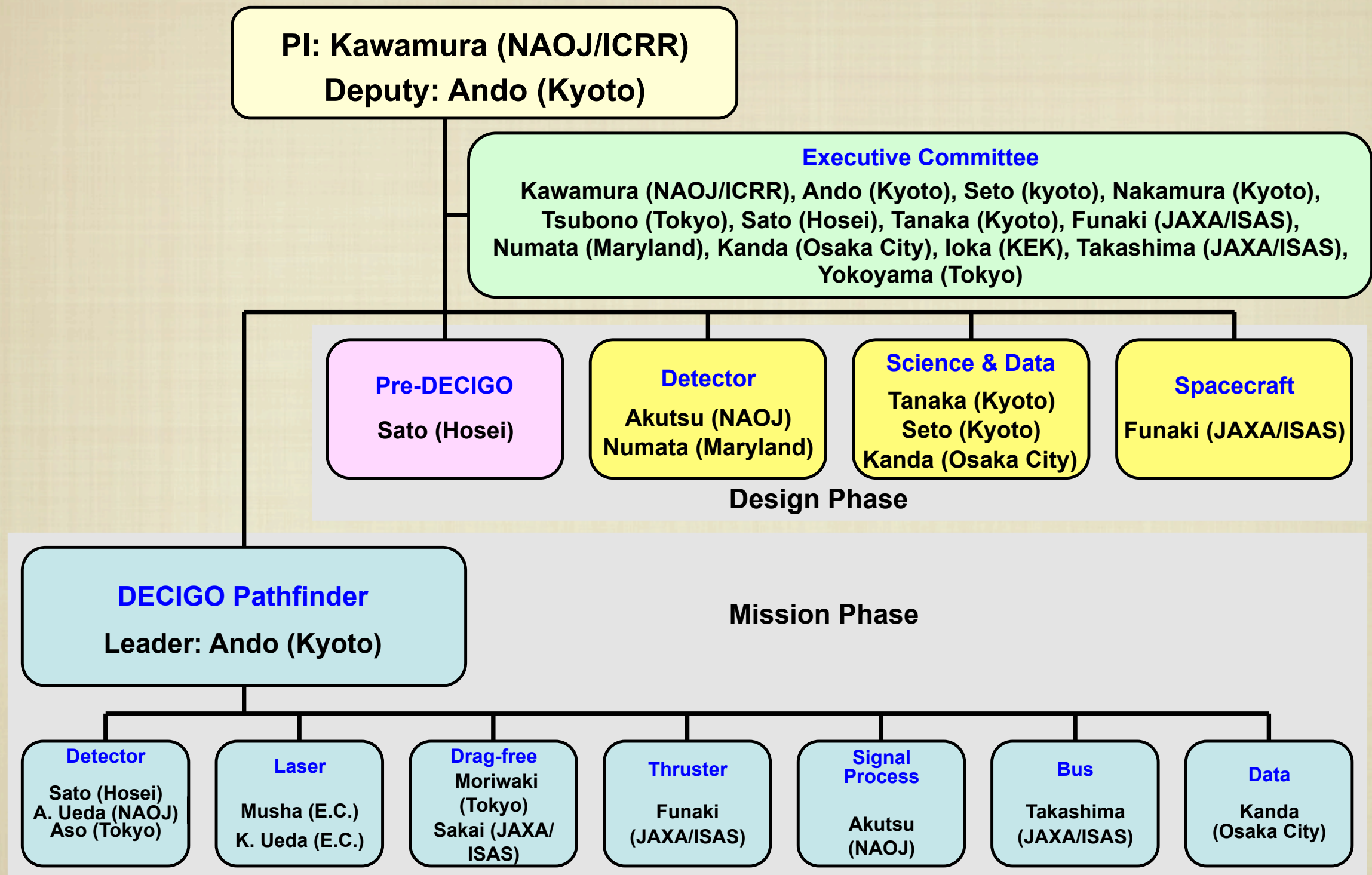
External force sources

Fluctuation of magnetic field, electric field,
gravitational field, temperature, pressure, etc.

Roadmap



DECIGO interim organization



Collaborations and supports

- Supports from LISA
 - * Technical advices from LISA/LPF experiences
 - * Support Letter for DECIGO/DPF, Joint workshop (2008.11)
- Stanford univ. group
 - * Discharge system for DPF, other R&D for DECIGO
- NASA
 - * Fiber laser, Joint observation with **GRACE**
- JAXA Navigation-control section
 - * Formation flight of DECIGO, DPF drag-free control
- Research Center for the Early Universe (RESCEU), Univ. of Tokyo
 - * supports DECIGO as ones of main projects (2009.4-)
- **Geo-gravity field group** (Kyoto, ERI, UEC, NAOJ)
 - * Geophysics by DPF obs. data
- Advanced Technology Center (ATC) of NAOJ

Calculating the sensitivity

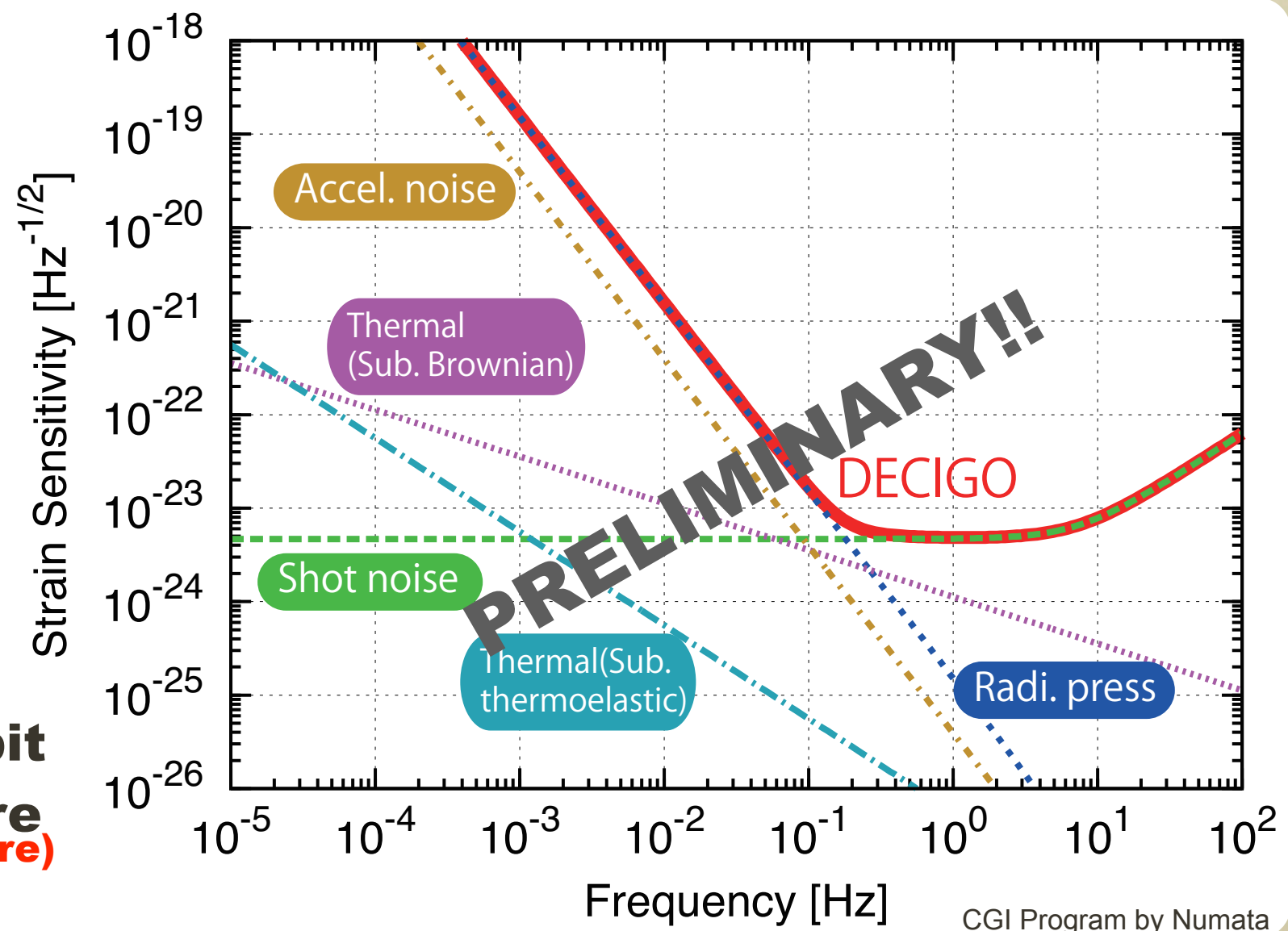
- Arm length: 1,000 km
- Laser power: 10 W
- Laser wavelength: 532 nm
- Mirror diameter: 1.0 m
- Mirror mass: 100 kg
- Mirror reflectivity: 77.3%
- Cavity g-param: 0.1

← “pre-conceptual design”

To detect **stochastic GWs** and observe *the early universe*, we should **clean off** any “foreground GW sources.”



Tune the parameters a little bit to improve the sensitivity more (~ 3 times more) in the obs. freq. band.



Considering “Conceptual design”

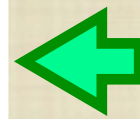
- Arm length: **1,500 km**
- Laser power: **30 W**
- Laser wavelength: **532 nm**
- Mirror diameter: **1.5 m**
- Mirror mass: **100 kg**
- Mirror reflectivity: **77.3%**
- Cavity g-param: **0.1**

This is the first step to considering the **conceptual design**.

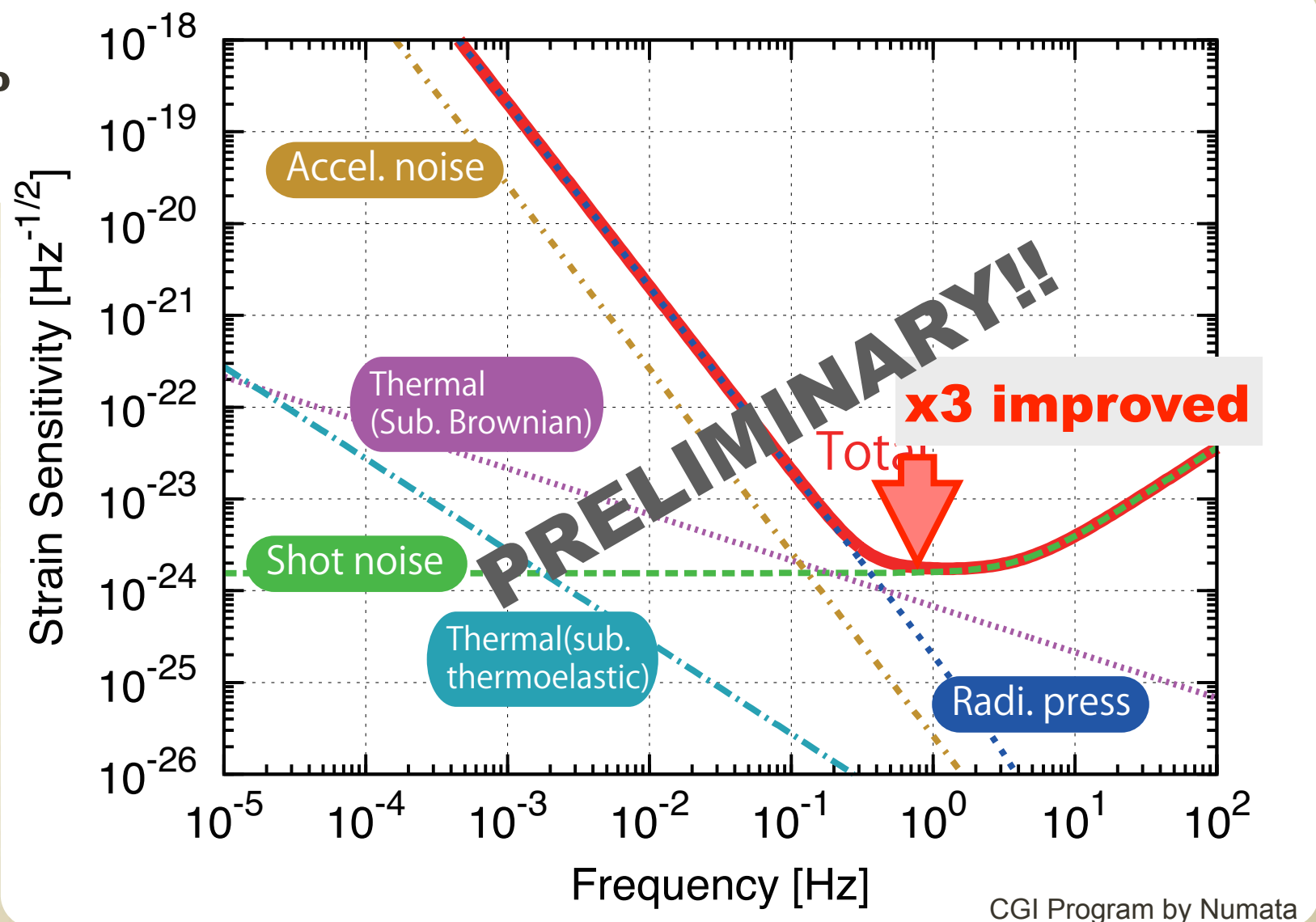
Next:

- ➔ **Confirm the calculations.**
- ➔ **Find the realistic way to realize this!**

Preliminary



Parameters tuned



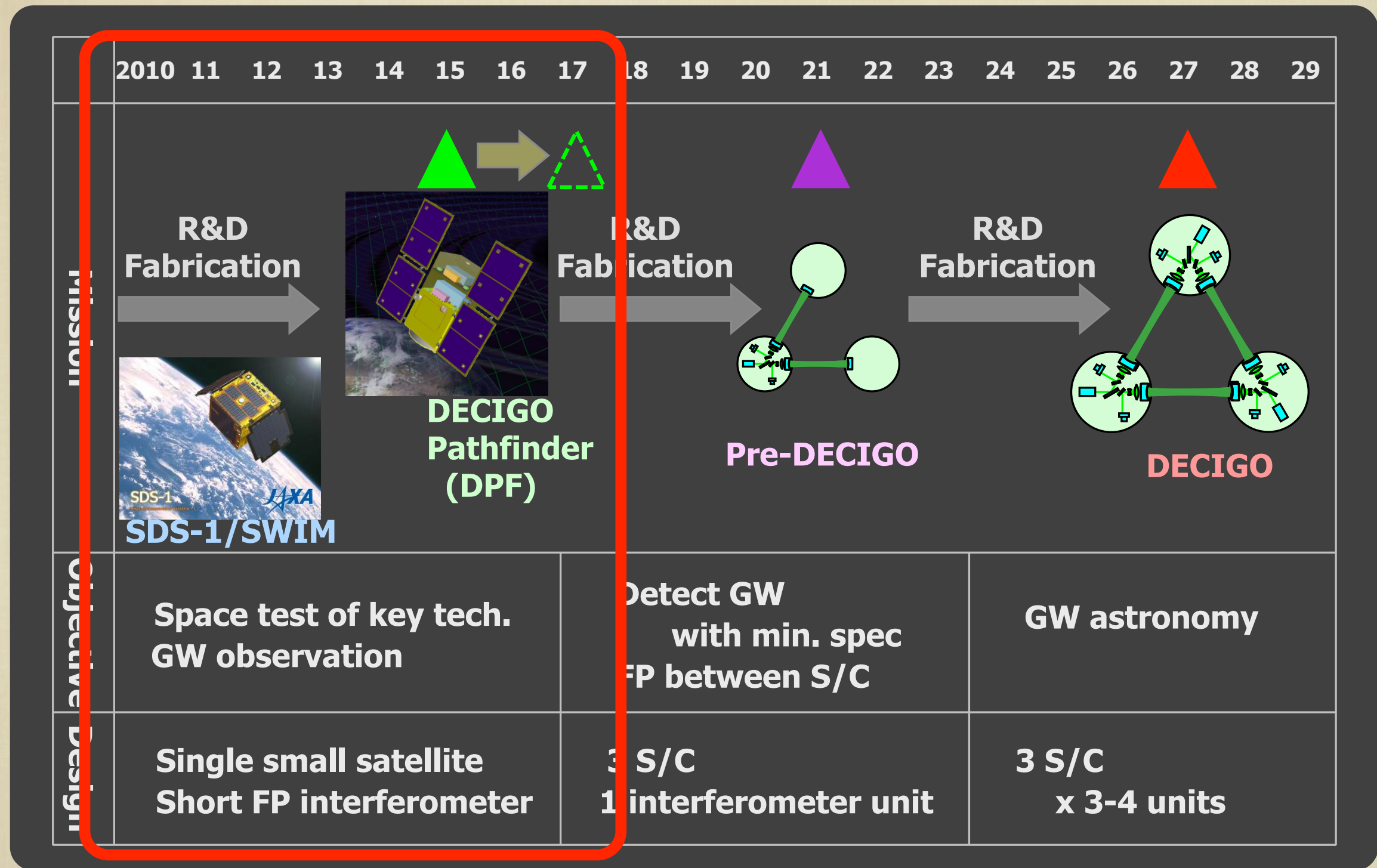
CGI Program by Numata

1. DECIGO

2. DECIGO Pathfinder (DPF)

3. Summary

DECIGO Pathfinder in the roadmap



DECIGO Pathfinder

DECIGO Pathfinder (DPF)

First milestone mission for DECIGO

Shrink arm cavity

DECIGO 1000km → DPF 30cm

Single satellite

(Payload $\sim 1\text{m}^3$, 350kg)

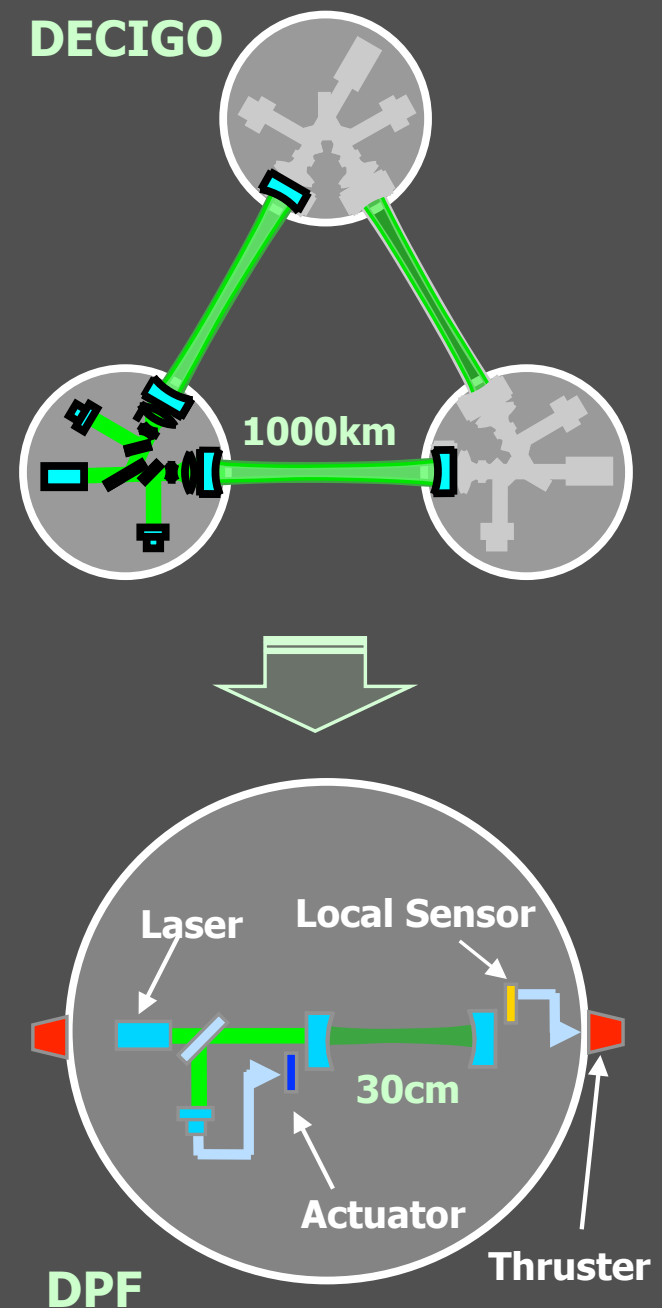
Low-earth orbit

(Altitude 500km, sun synchronous)

30cm FP cavity with 2 test masses

Stabilized laser source

Drag-free control



DPF Satellite design

DPF Payload

Size : 950mm cube
Weight : 150kg
Power : 130W
Data Rate: 800kbps
Mission thruster x12

Power Supply
SpW Comm.



Satellite Bus

('Standard bus' system)

Size :
950x950x1100mm
Weight : 200kg
SAP : 960W
Battery: 50AH
Downlink : 2Mbps
DR: 1GByte
3N Thrusters x 4

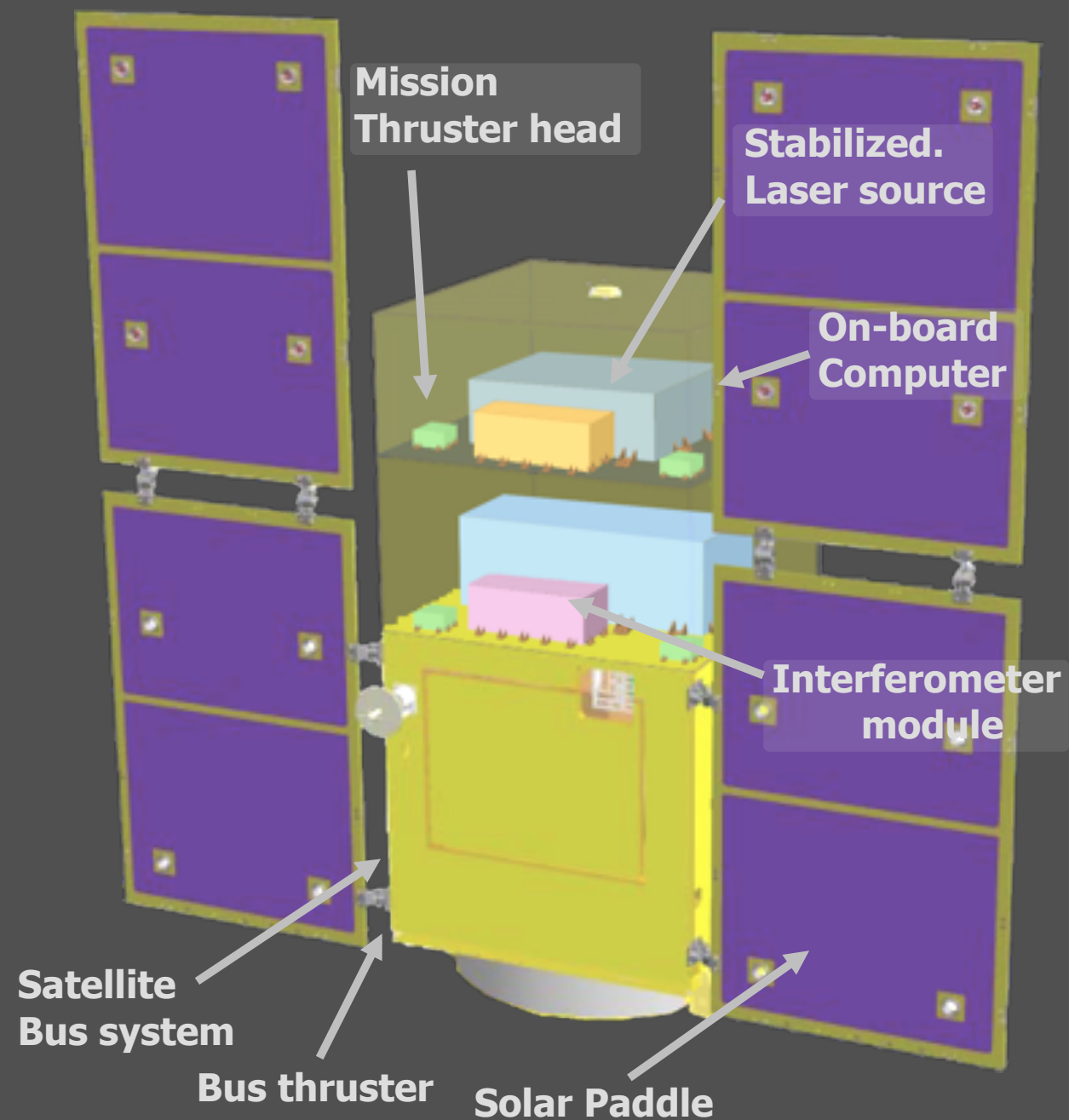


Fig. by Ando

DPF mission payload

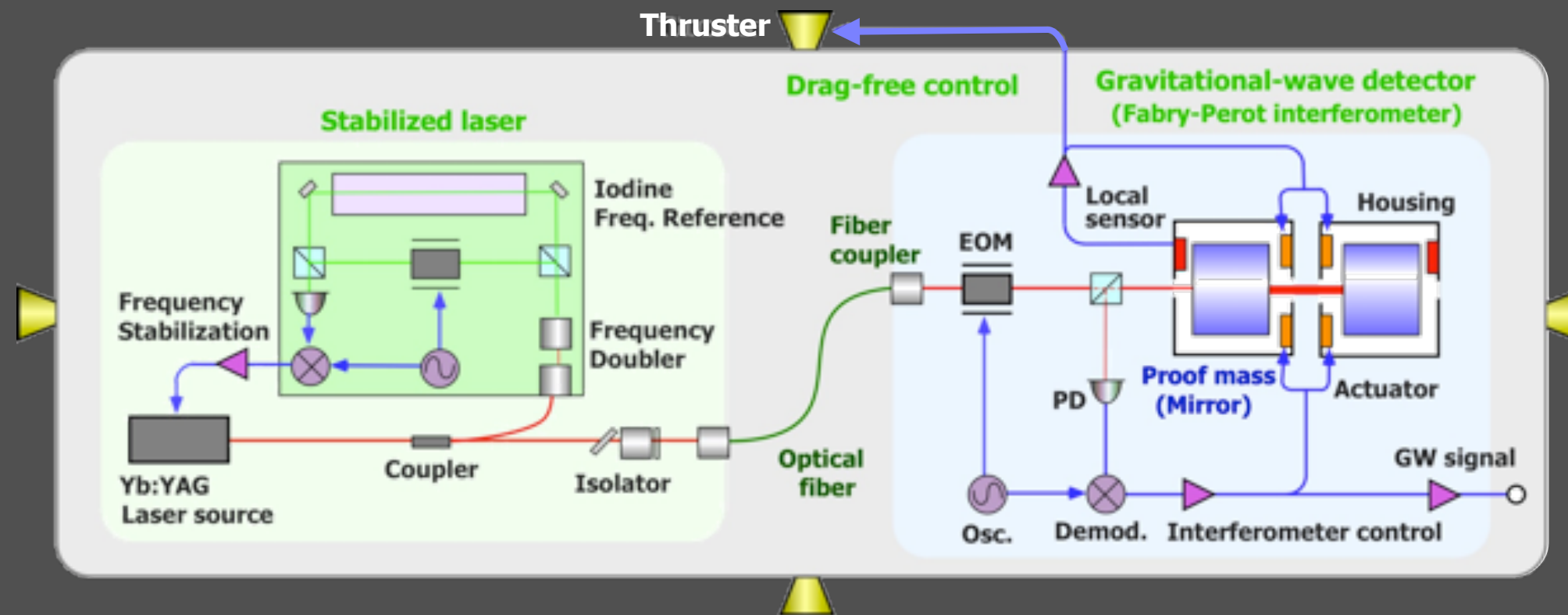
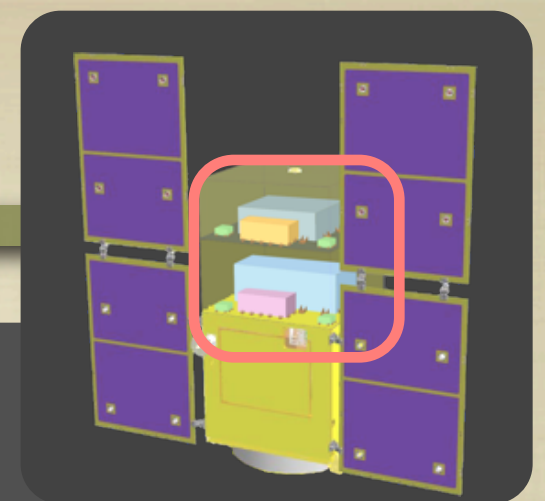
Mission weight : $\sim 150\text{kg}$

Mission space : $\sim 95 \times 95 \times 90 \text{ cm}$

Drag-free control

Local sensor signal

→ Feedback to thrusters



Laser source

Yb:YAG laser (1030nm)

Power : 25mW

Freq. stab. by Iodine abs. line

Fabry-Perot interferometer

Finesse : 100

Length : 30cm

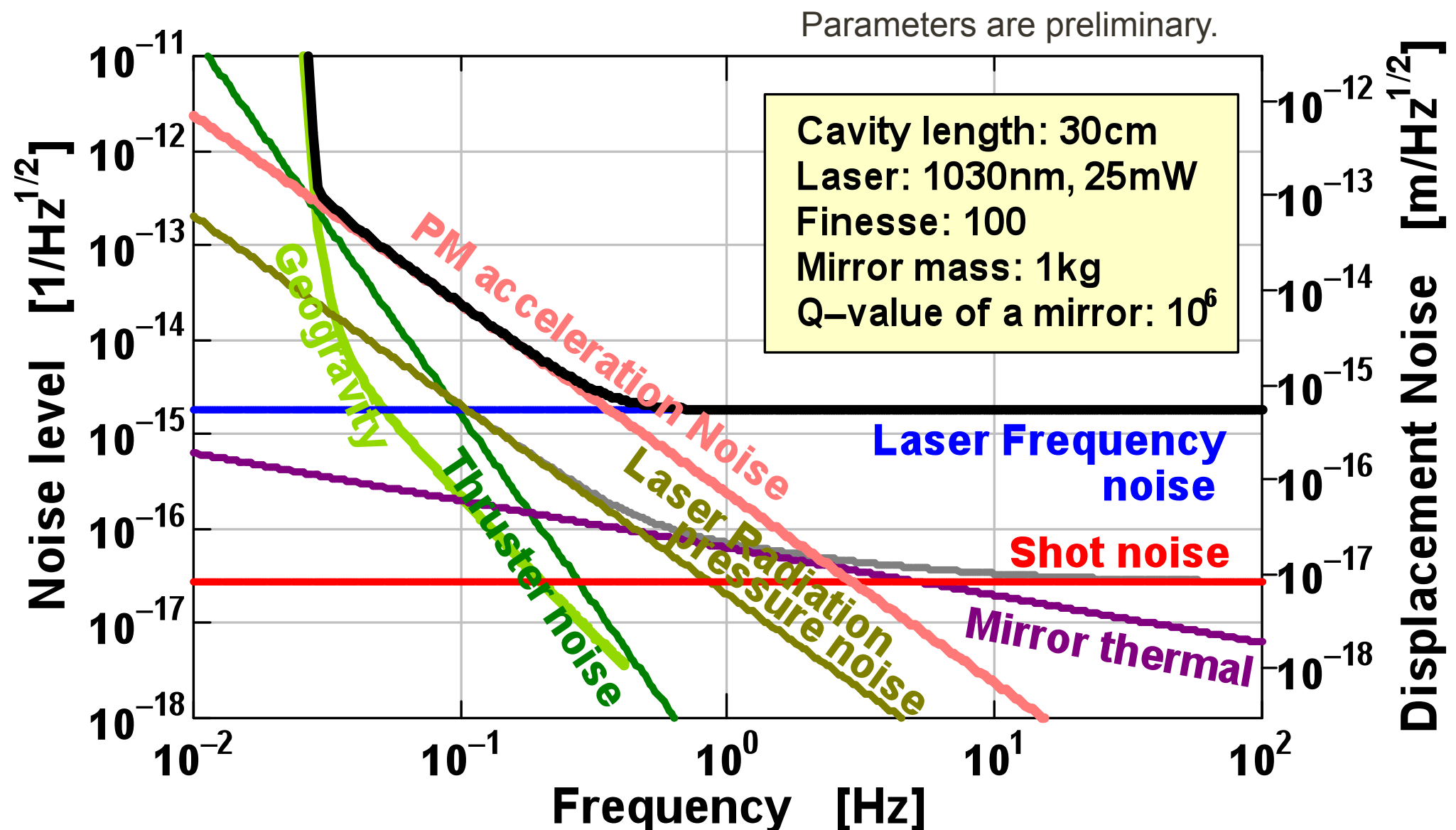
Test mass : $\sim$ a few kg

Signal extraction by PDH

Fig. by Ando

DPF sensitivity

- Noise level : $h \sim 2e-15$ strain/rtHz
- * Limited by laser frequency noise and acceleration noise



DPF Requirements

Sensor Noise

Disp. noise $6 \times 10^{-16} \text{ m/Hz}^{1/2}$ (0.1 Hz)

⇒ x 200 of DECIGO in disp. noise

Other noises

Laser freq. noise: $0.5 \text{ Hz/Hz}^{1/2}$ (1Hz)

Acceleration Noise

Force noise $1 \times 10^{-15} \text{ m/s}^2/\text{Hz}^{1/2}$ (0.1 Hz)

⇒ x 250 of DECIGO

Satellite motion

Disp. noise $1 \times 10^{-9} \text{ m/Hz}^{1/2}$ (0.1 Hz)

External force sources: Residual gas damping,
Fluctuation of magnetic field, electric field,
gravitational field, temperature, pressure, etc.

DPF Science --- 1. gravitational wave

Blackholes events in our galaxy

IMBH inspiral and merger

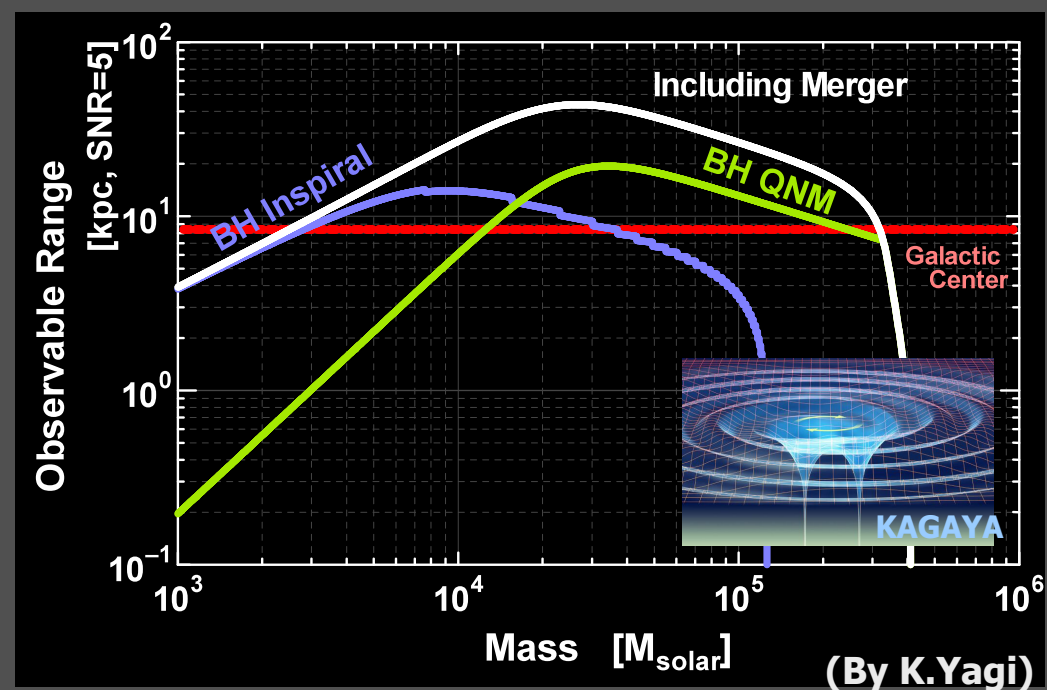
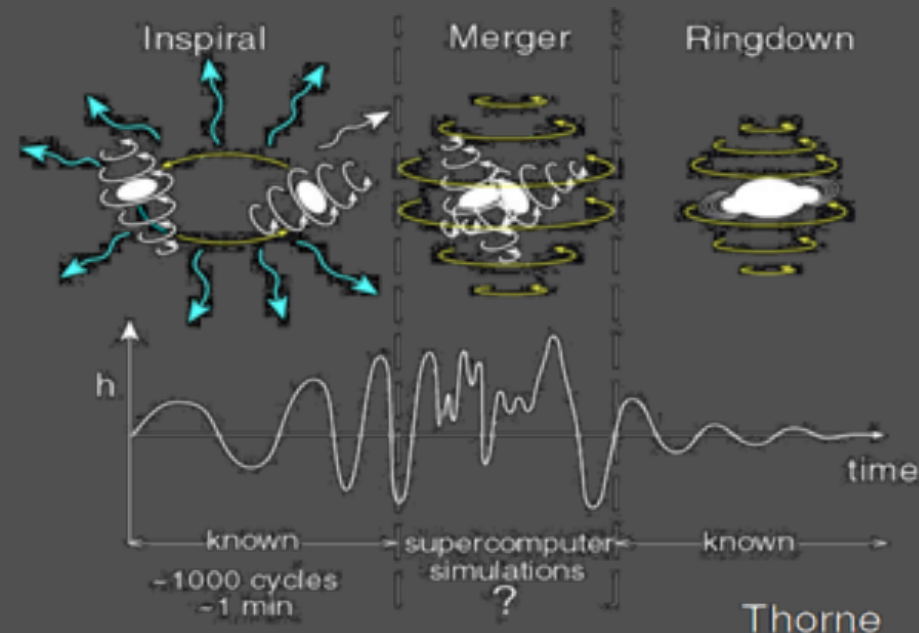
$h \sim 10^{-15}$, $f \sim 4$ Hz
Distance 10kpc, $m = 10^3 M_{\text{sun}}$
Obs. Duration (~ 1000 sec)

BH QNM

$h \sim 10^{-15}$, $f \sim 0.3$ Hz
Distance 1Mpc, $m = 10^5 M_{\text{sun}}$

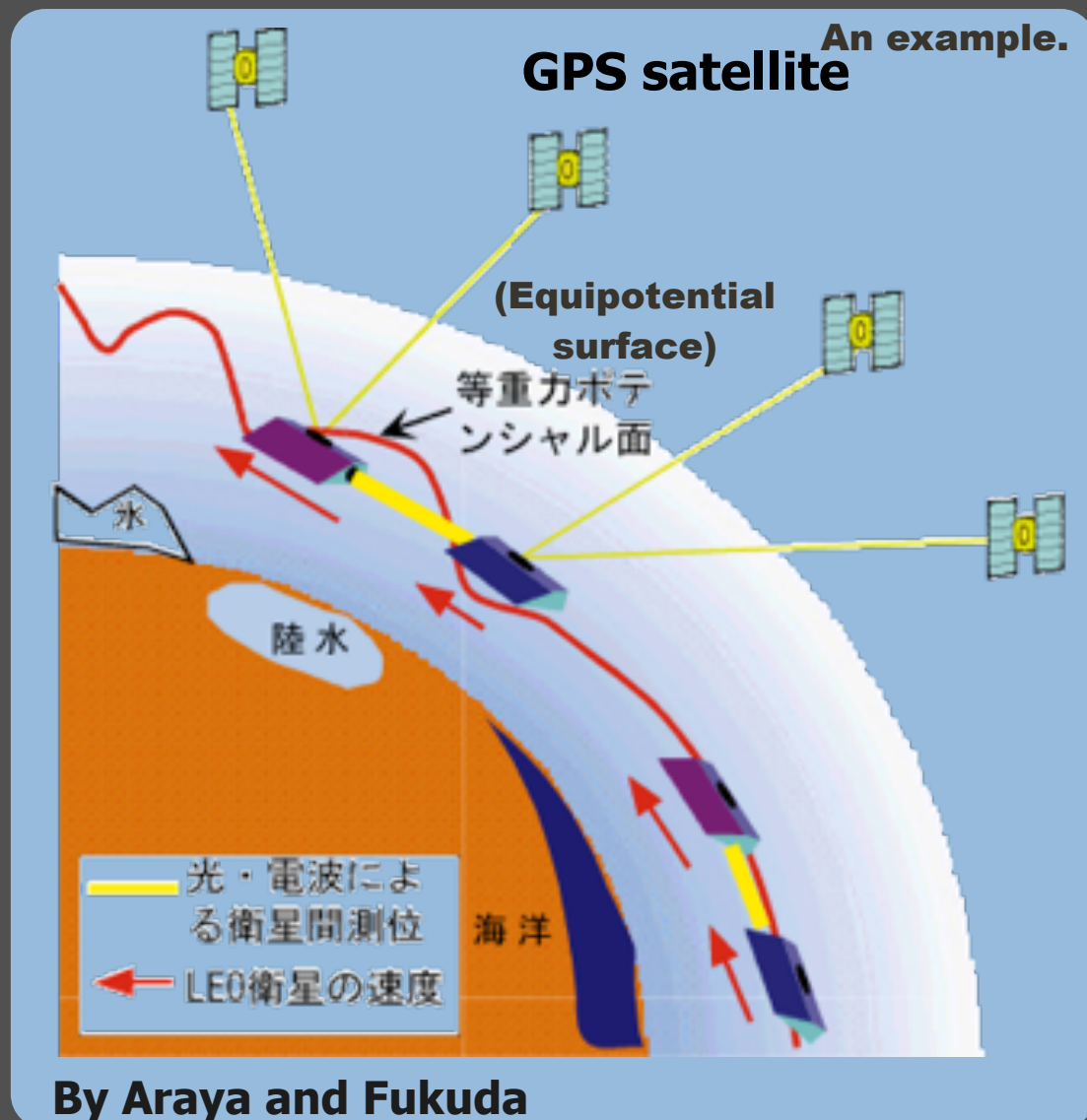
Observable range covers
our Galaxy (SNR ~ 5)

Hard to access by others
→ Original observation



DPF Science --- 2. gravity of the earth

Measure gravity field of the Earth from Satellite Orbits, and gravity-gradiometer



Determine global gravity field

→ Density distribution

Monitor of change in time

Ground water motion

Strains in crusts by

earthquakes and volcanoes

NASA's mission

GRACE FO (2016-2021?)

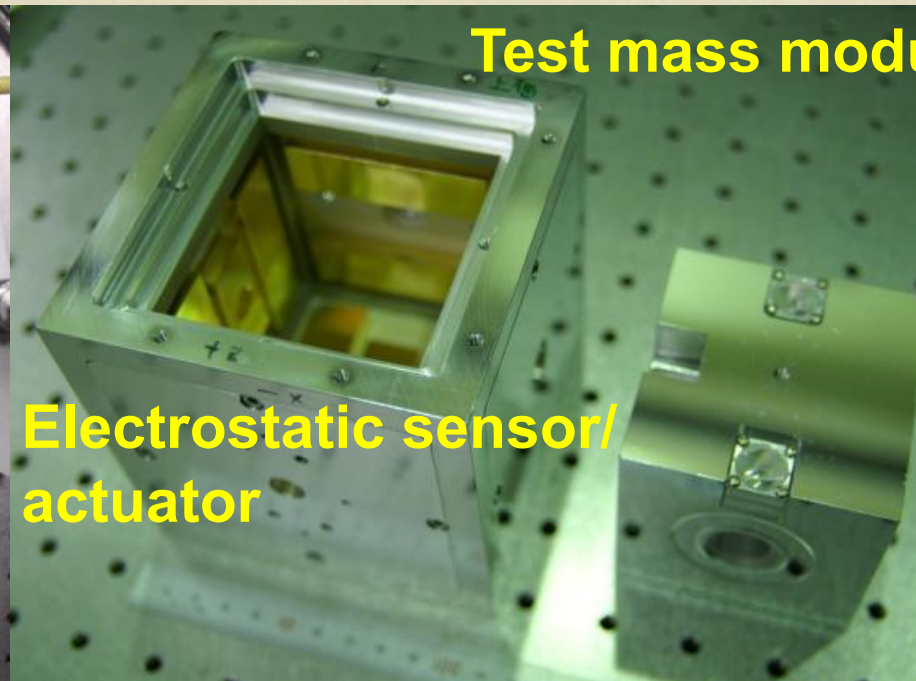
→ **DPF contribution (2017?)**

in international network

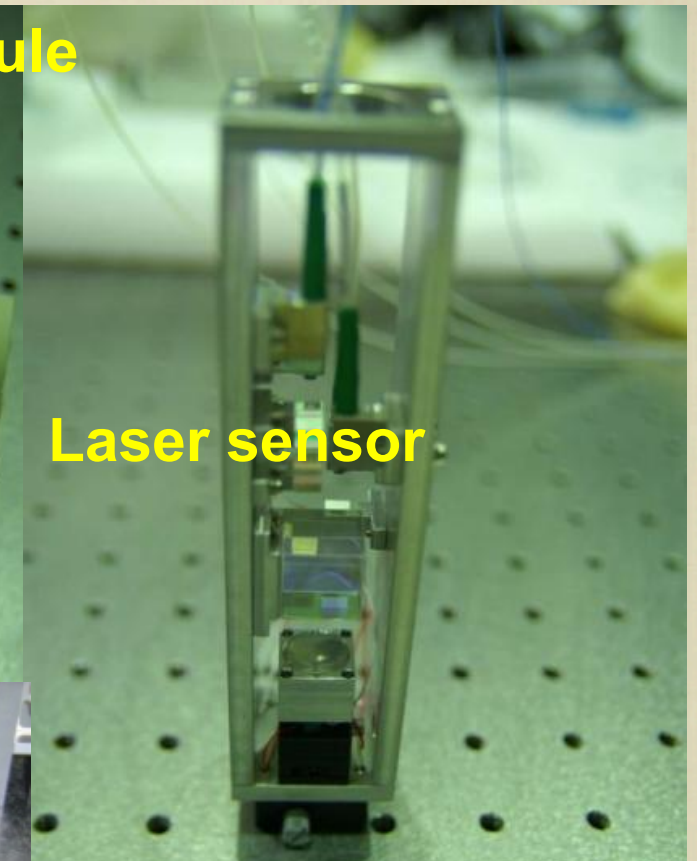
R&D for DPF subsystems



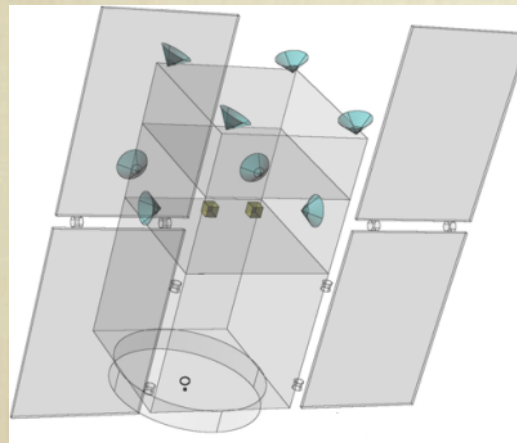
Test mass module



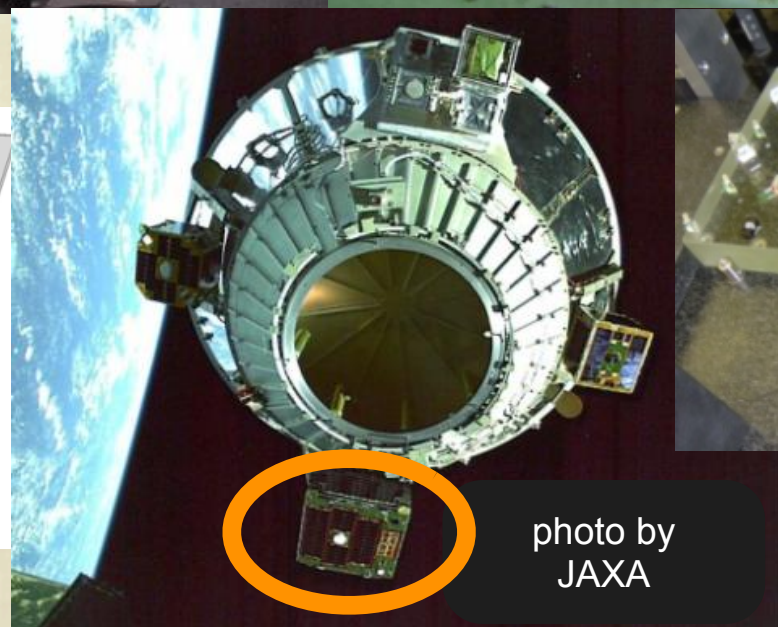
Electrostatic sensor/
actuator



Laser sensor

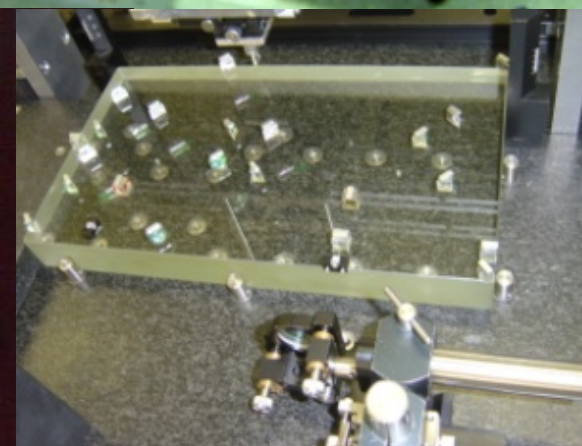


Drag-free
model



Signal processing
and control in space

photo by
JAXA



Interferometer
(monolithic
optics)



Low noise thruster

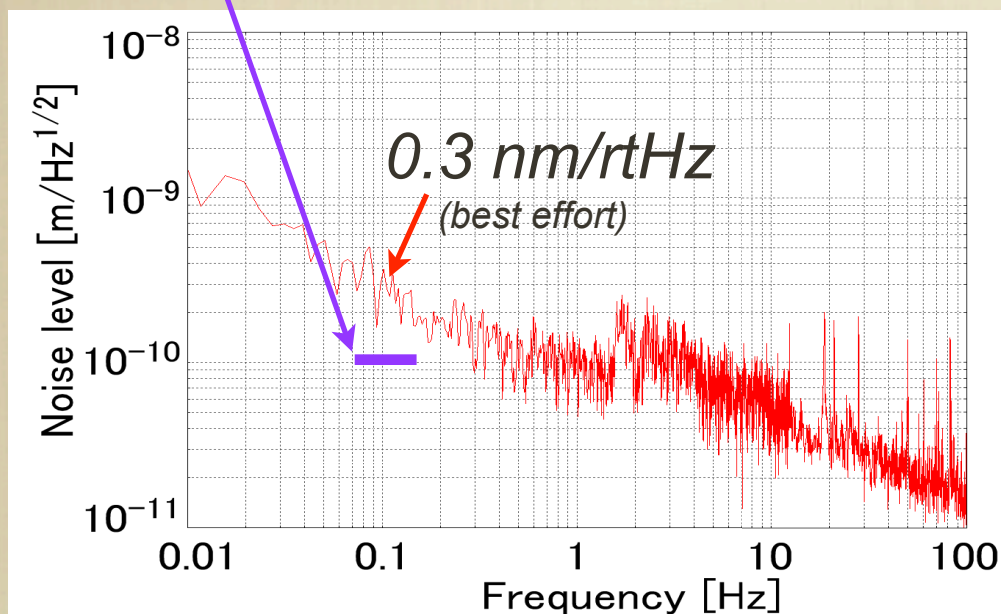
Test mass module (Inertial sensor)

Subsystem of Interferometer module

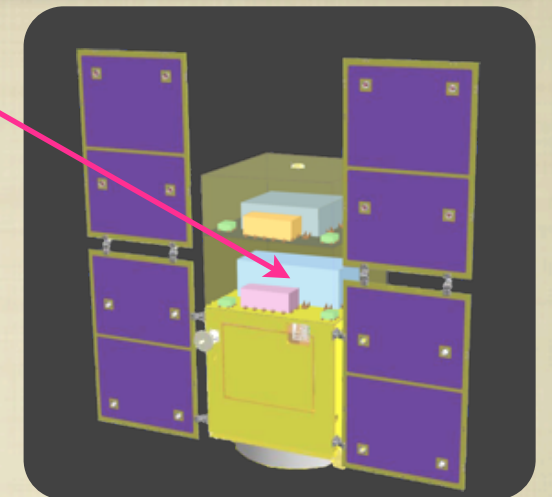
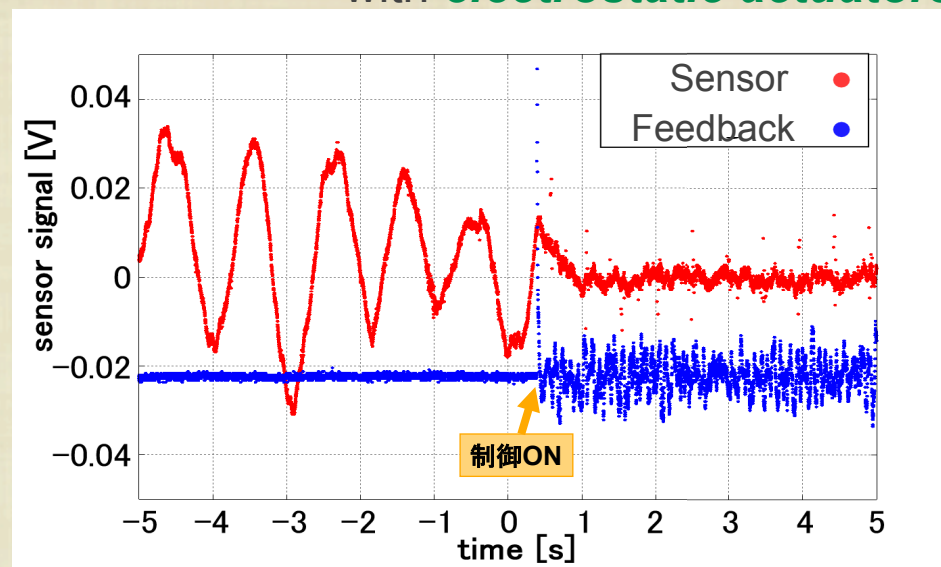
❖ Prototype experiment of individual functions

Req. of local sensor noise

(capacitive sensor)

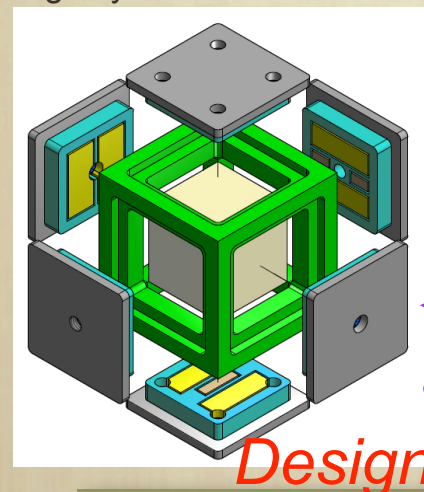


Controlling motions of a suspended test-mass with **electrostatic actuators**

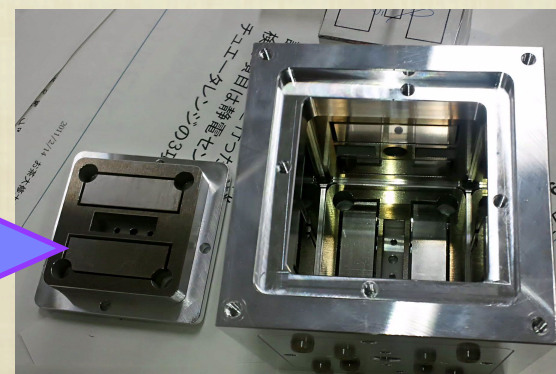
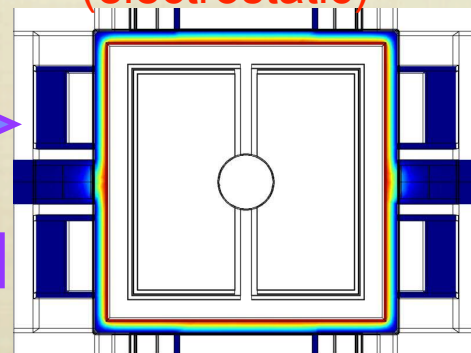


❖ Design & Analysis

Figs by R.Suzuki



FEM analysis
(electrostatic)

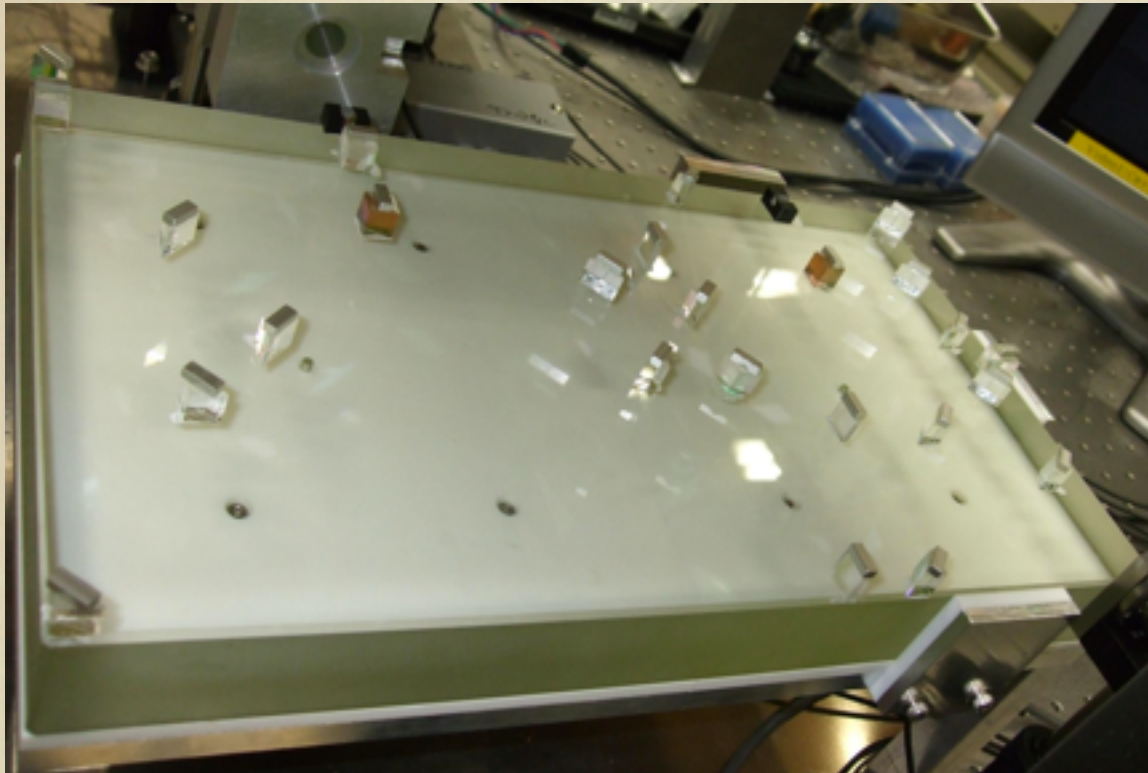


Manufacture & Functional test

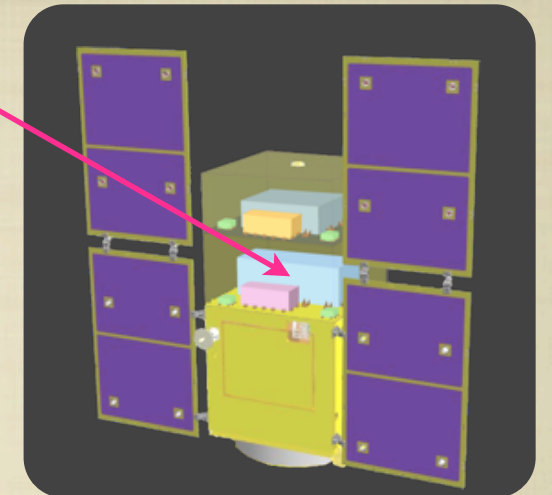
To meet the requirements of:
Noise of Capacitive sensors,
Range of Electrostatic Actuators,
and Electrostatic Stiffness

Interferometer module

❖ Monolithic optics (as input optics)



Interferometer module

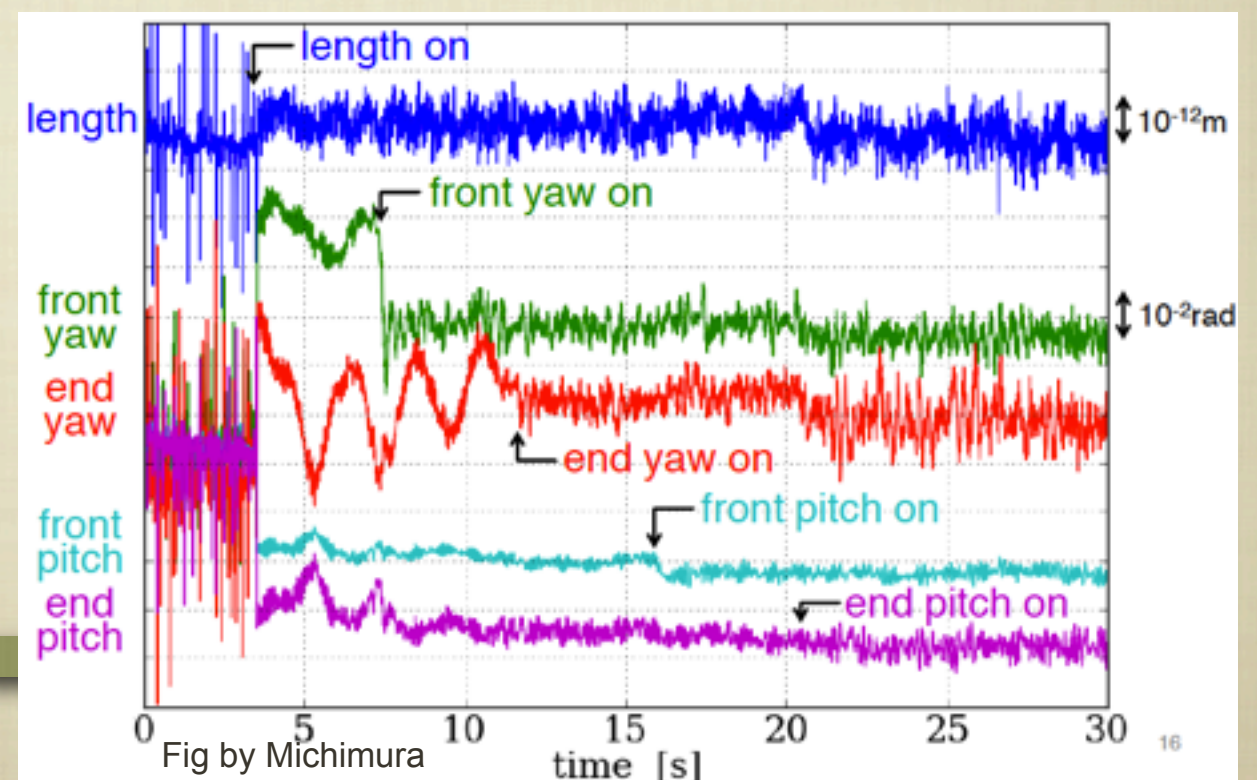


Why monolithic?

- ➡ To survive the shocks during launch.
- ➡ To prevent optical path from fluctuating in space
- ➡ etc...

Demonstration:

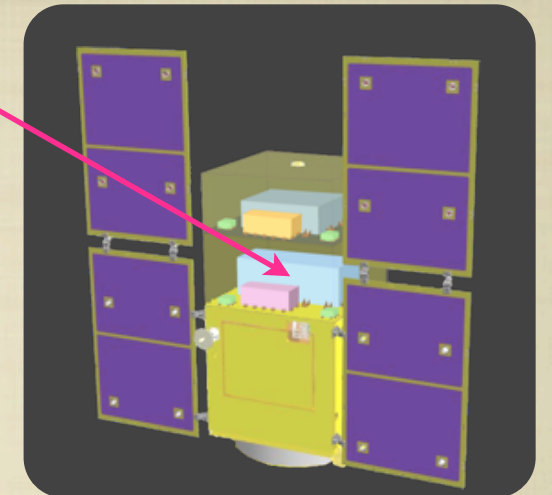
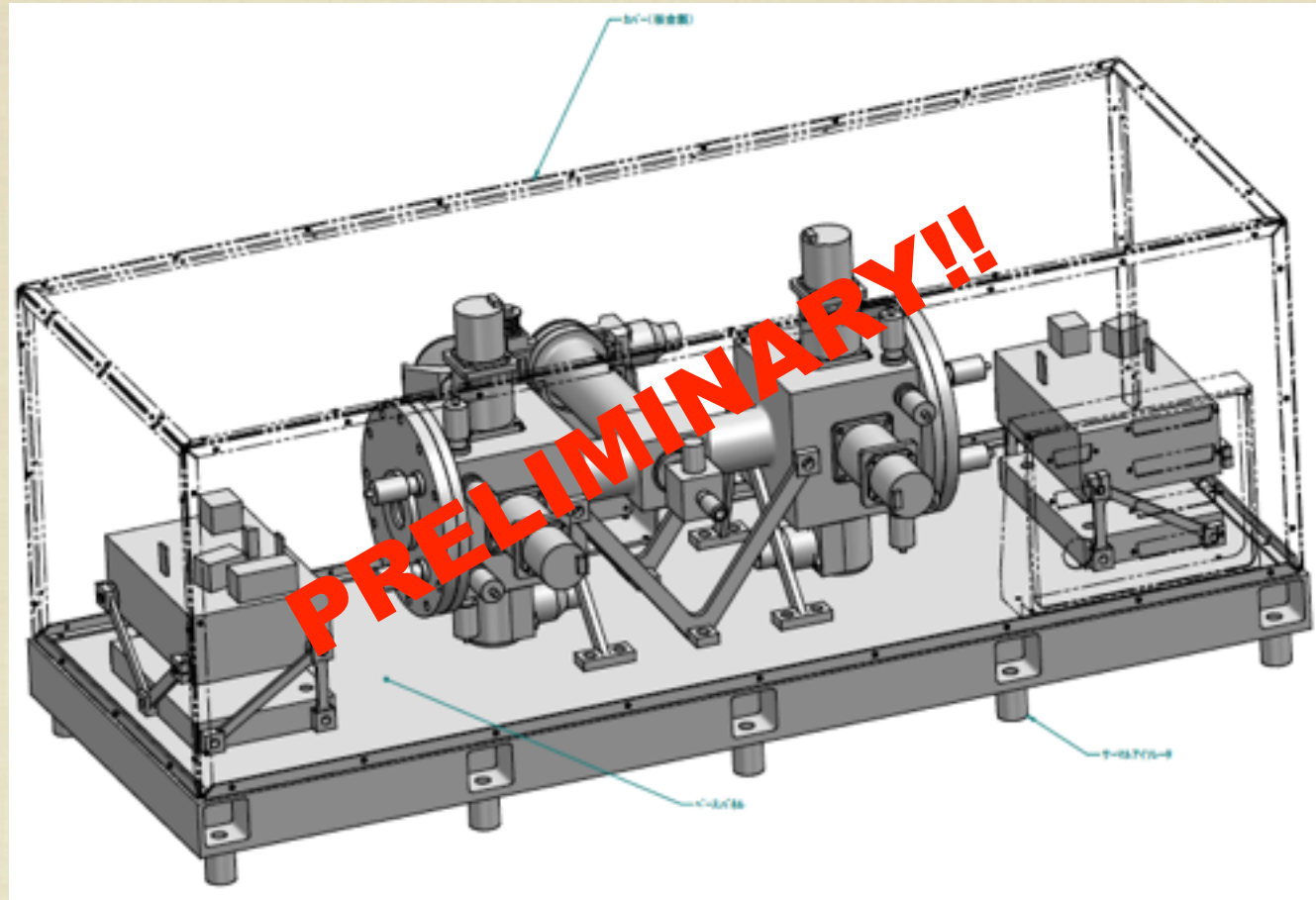
- ➡ With the optics,
a **FP cavity** can be in operation
(30cm long, same as DPF's)



Interferometer module (contd.)

❖ Structure

Interferometer module



Assemble every component to one module

➡ Components: test-mass modules, optics, electronics, optical fibers and metal wires, dynamic mechanisms, robust chassis,...

SWIM $\mu\nu$ --- Mission Successfully Completed!!

- SWIM $\mu\nu$: tiny **space GW sensor** (torsion type)
- * SWIM (one of the missions of JAXA's **S**mall **D**emonstration **S**atellite-1)
= SWIM $\mu\nu$ + **new satellite technology**
space-qualified computers, signal processing systems etc.
- * Design sensitivity: **1e-6 rad/rtHz (0.1-1Hz) in space**



TAM: Torsion Antenna Module with free-falling test mass
(Size : 80mm cube, Weight : ~500g)

Test mass

~47g Aluminum, Surface polished
Small magnets for position control

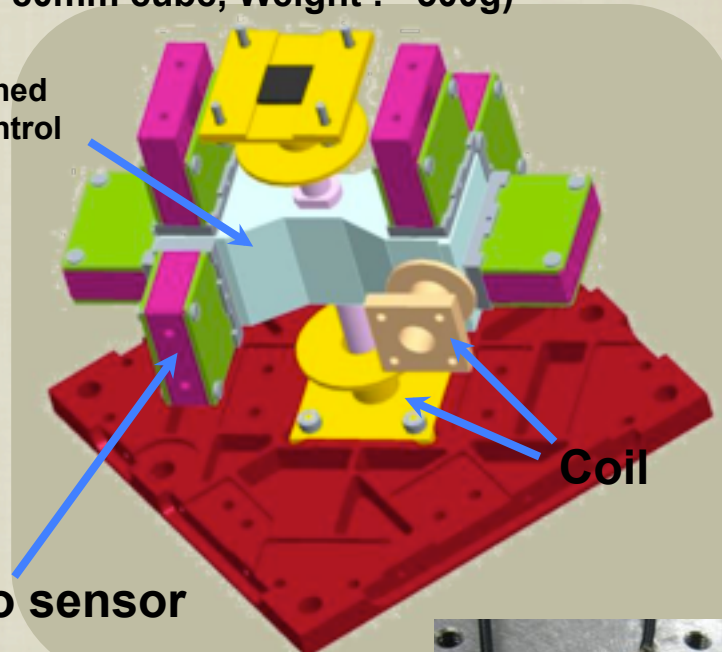
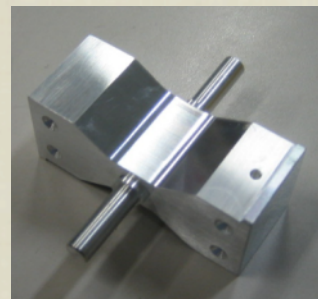
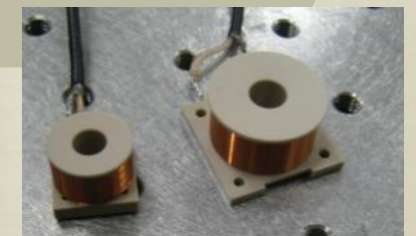
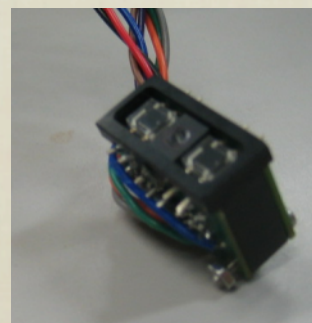


Photo sensor

Reflective-type optical
displacement sensor
Separation to mass ~1mm
Sensitivity ~ 10^{-9} m/Hz $^{1/2}$
6 PSs to monitor mass motion



SWIM $\mu\nu$ (contd)

■ Data Taking

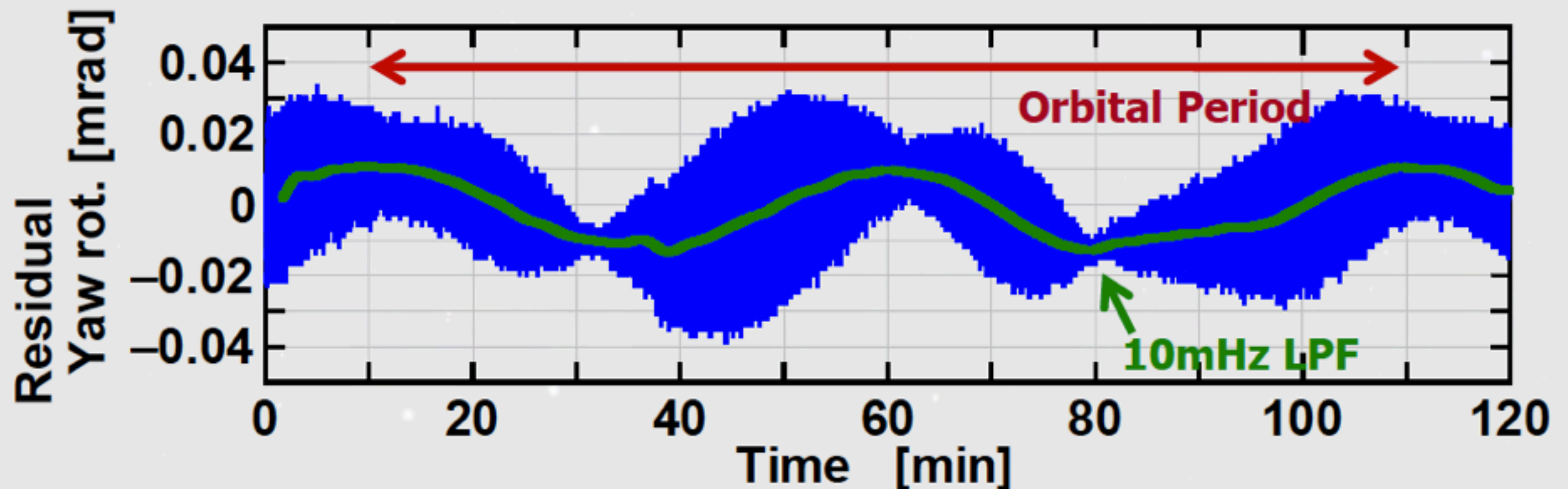
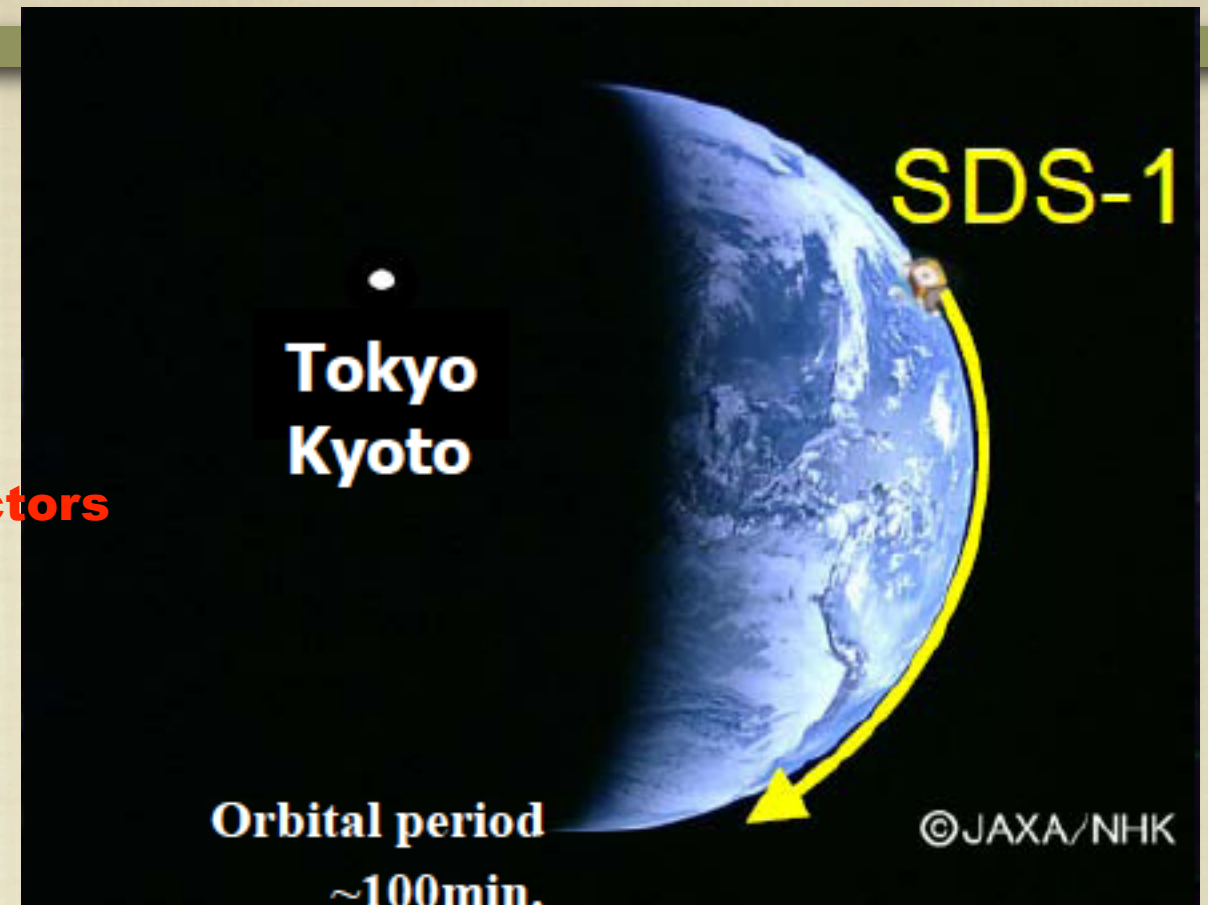
- * ~120 min (17 Jun 2010)
- * ~240 min (15 Jul 2010)

Taking data together with terrestrial detectors

Now data analysis is ongoing!!

Details:

Ando's talk tomorrow (May 25)



Funding status of DPF

DPF : One of the candidate of
JAXA's small satellite series



At least **3 satellites** in 5 years with
Standard Bus + M-V follow-on rocket

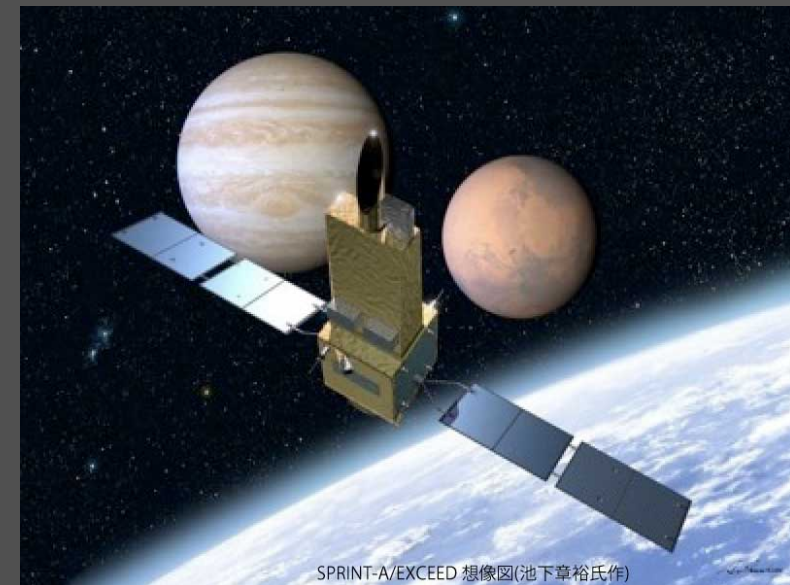
1st mission (2012): SPRINT-A/EXCEED

2nd mission (~2013/14) : ERG

DPF survived until final two

3rd mission (2016/17?) : TBD

**DPF is one of the strongest
candidates of the 3rd mission**



SPRINT-A / EXCEED
UV telescope mission



Next-generation
Solid rocket booster (M-V FO)
Fig. by JAXA

-
- 1. DECIGO**
 - 2. DECIGO Pathfinder (DPF)**
 - 3. Summary**

Summary

DECIGO : Fruitful Sciences

Very beginning of the **Universe**

Dark energy

Galaxy formation

DECIGO Pathfinder

Important **milestone** for DECIGO

Strong candidate of **JAXA's satellite series**

SWIM – Mission successfully completed!!
first precursor to space!

END