

Investigation of two-particle contributions to nucleon matrix elements

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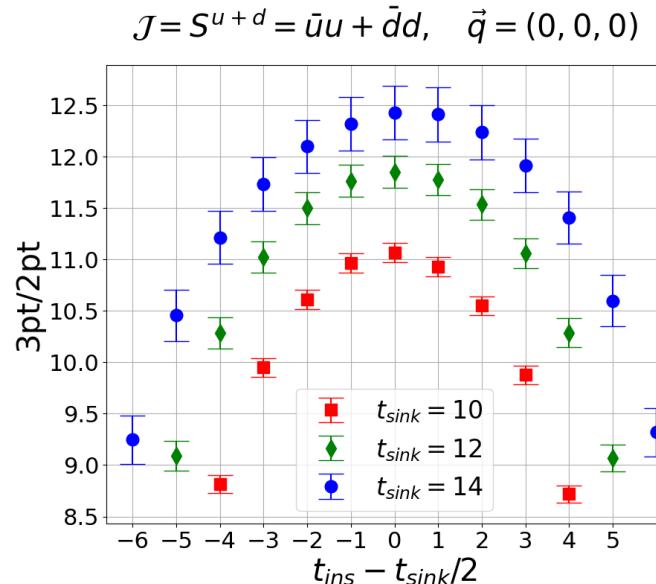


Background

- Nucleon structure: nucleon matrix elements

$$\frac{\langle 0 | O_N(t_{\text{sink}}) J(t_{\text{ins}}) \bar{O}_N(0) | 0 \rangle}{\langle 0 | O_N(t_{\text{sink}}) \bar{O}_N(0) | 0 \rangle} \xrightarrow{\text{all } t \text{ well-separated}} \langle N | J | N \rangle$$

- Time-dependence indicates contamination from excited states
- Lowest excited state is a Nucleon–Pion state

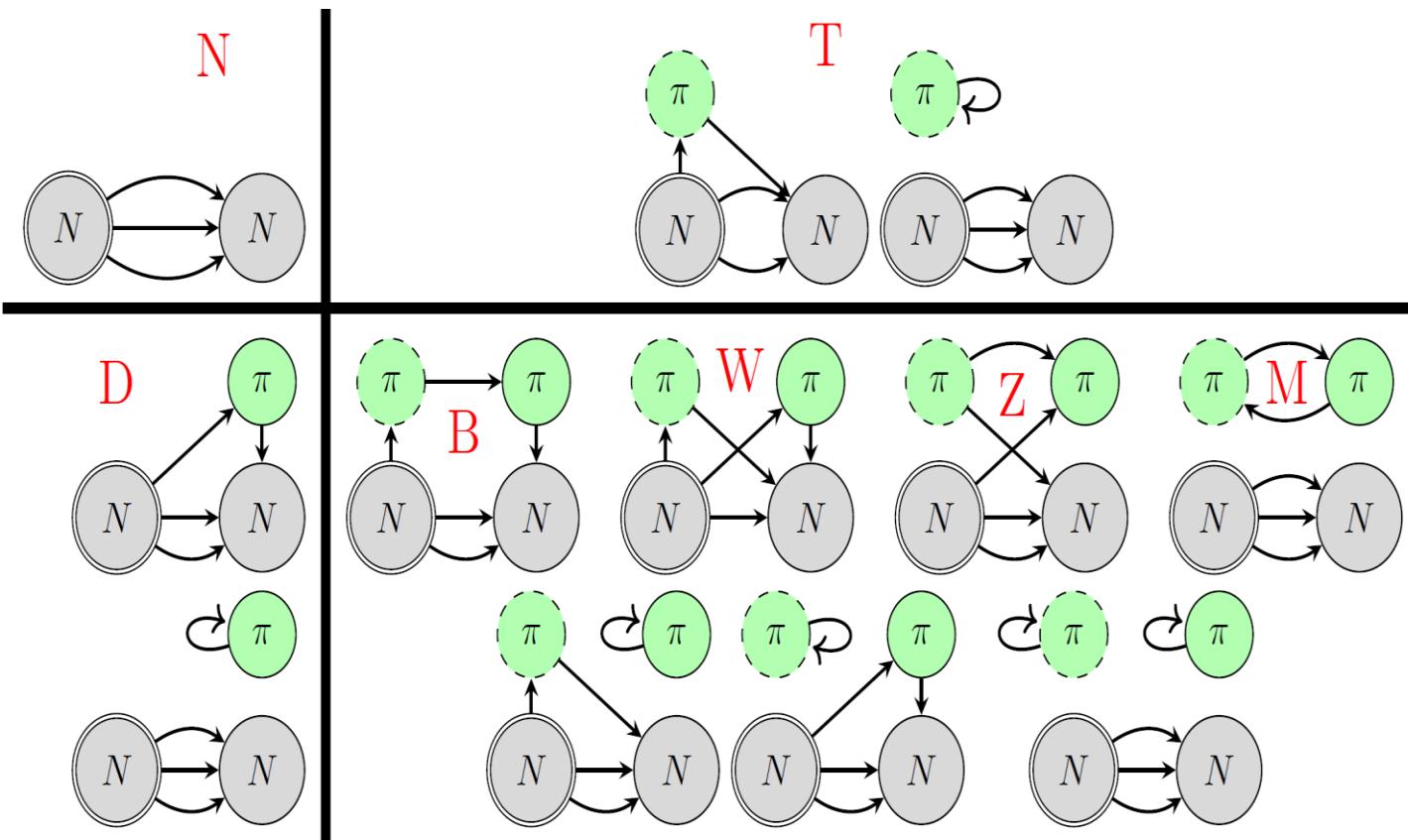


Simulation details

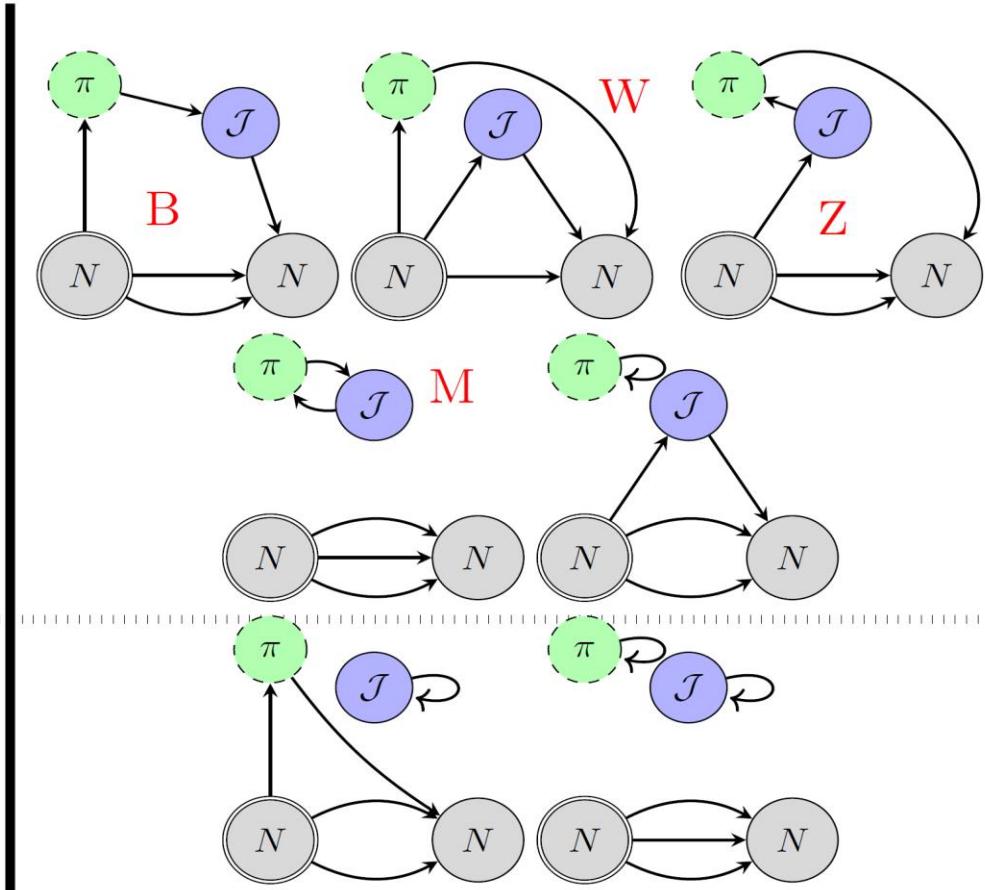
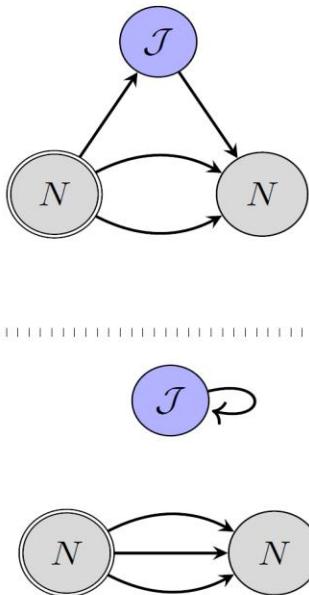
Ensembles	Flavors	$N_L^3 \times N_T$	m_π (MeV)	L (fm)	$m_\pi L$	N_{cfg}
cA211.53.24	2+1+1	$24^3 \times 48$	346	2.27	3.99	2400
cA2.09.48	2	$48^3 \times 96$	131	4.50	2.98	300

- Twisted-mass lattice
- Interpolating operators used:
 $O_p; \quad O_{N\pi}^{1/2} = \sqrt{2/3} O_{n\pi^+} - \sqrt{1/3} O_{p\pi^0}$
- Generalized eigenvalue problem (GEVP)
 - Do GEVP on 2pt functions
 - Use the results to improve 3pt functions
- Based on: <https://github.com/cylqcd/PLEGMA>
<https://github.com/lattice/quda/>

Diagrams: 2pt functions



Diagrams: 3pt functions



Generalized eigenvalue problem (GEVP)

- GEVP starts with 2pt functions:

$$C_{ij}(t) = \langle 0 | O_i(t) O_j^\dagger(0) | 0 \rangle$$

- GEVP returns eigenvalues and eigenvectors:

$$C_{ij}(t) v_j^n = \lambda^n(t, t_0) C_{ij}(t_0) v_j^n$$

$$\lambda^n(t, t_0) = e^{-E_n(t-t_0)}, \quad v_j^n O_j^\dagger(0) |0\rangle = |n\rangle$$

- We determine the optimal interpolating field:

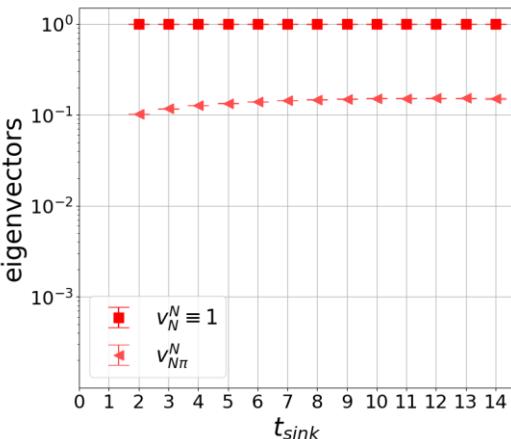
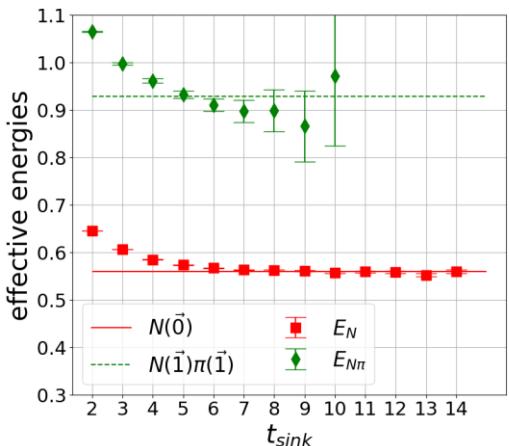
$$O'_N |0\rangle = (O_N + v_{N\pi}^N O_{N\pi}) |0\rangle \propto |N\rangle$$

- We can use it to improve matrix elements:

$$\frac{\langle 0 | O_N J \bar{O}_N | 0 \rangle}{\langle 0 | O_N \bar{O}_N | 0 \rangle} \xrightarrow{\text{GEVP improving}} \frac{\langle 0 | O'_N J \bar{O}'_N | 0 \rangle}{\langle 0 | O'_N \bar{O}'_N | 0 \rangle}$$

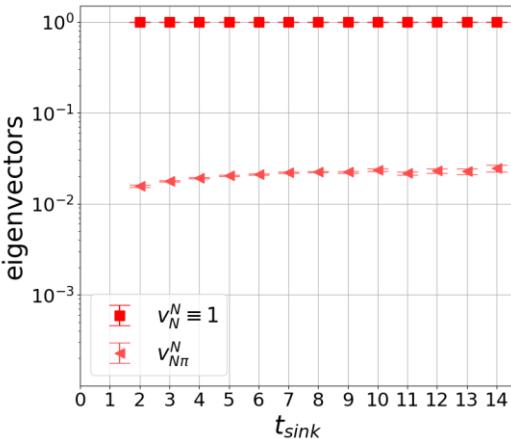
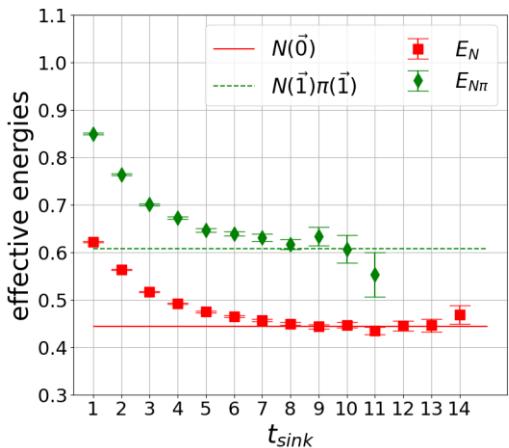
GEVP for 2pt functions:

$$\vec{p}_{tot} = (0, 0, 0); \mathbf{N}(\vec{0}), \mathbf{N}(\vec{1})\pi(-\vec{1})$$



$$m_\pi = 346 \text{ MeV}$$

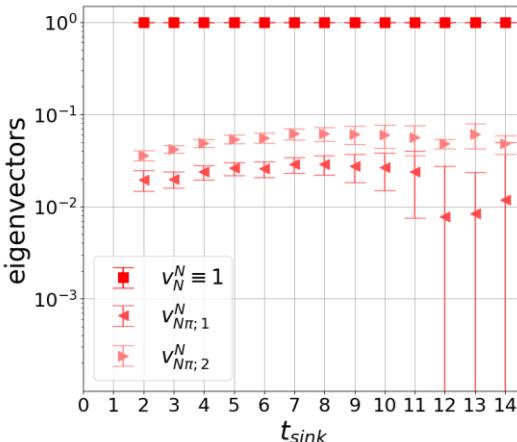
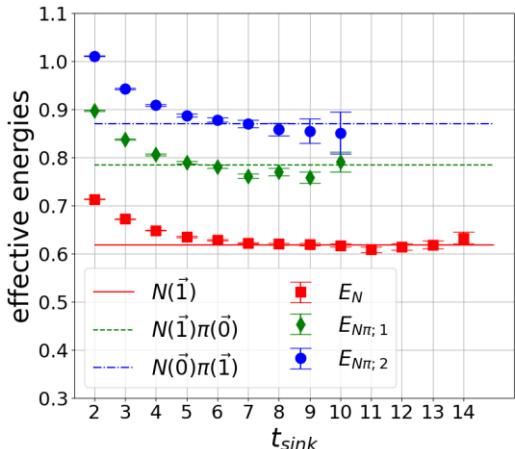
$$O'_N = O_N + v_{N\pi}^N O_{N\pi}$$



$$m_\pi = 131 \text{ MeV}$$

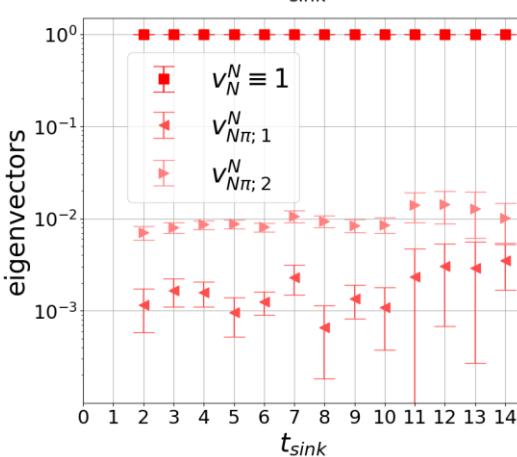
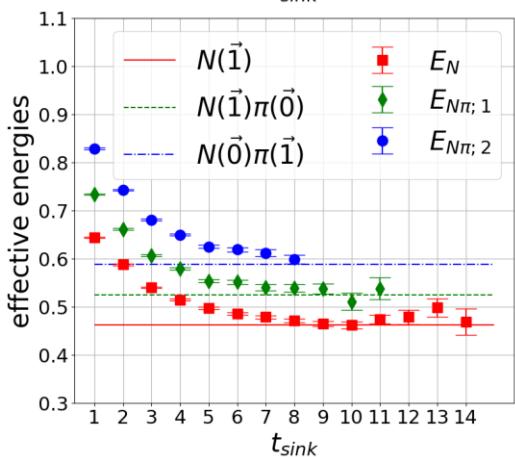
GEVP for 2pt functions:

$$\vec{p}_{tot} = (0, 0, 1); N(\vec{1}), N(\vec{1})\pi(\vec{0}), N(\vec{0})\pi(\vec{1})$$



$$m_\pi = 346 \text{ MeV}$$

$$O'_N = O_N + v_{N\pi;1}^N O_{N\pi;1} \\ + v_{N\pi;2}^N O_{N\pi;2}$$



$$m_\pi = 131 \text{ MeV}$$

GEVP improvement on 3pt functions

$$O_N |0\rangle = |N\rangle + x |N\pi\rangle$$

$$O_{N\pi} |0\rangle = |N\pi\rangle + y |N\rangle$$

Up to normalization constants and time-dependent terms

$$O'_N |0\rangle \equiv O_N - x O_{N\pi} |0\rangle = (1 - xy) |N\rangle$$

$$\frac{\langle 0|O_N J \bar{O}_N |0\rangle}{\langle 0|O_N \bar{O}_N |0\rangle} \xrightarrow{\text{GEVP improving}} \frac{\langle 0|O'_N J \bar{O}'_N |0\rangle}{\langle 0|O'_N \bar{O}'_N |0\rangle}$$

$$\langle 0|O'_N J \bar{O}'_N |0\rangle = \langle 0|(O_N - x O_{N\pi}) J (\bar{O}_N - x \bar{O}_{N\pi}) |0\rangle$$

$$= \langle 0|O_N J \bar{O}_N |0\rangle - \mathbf{x} \langle 0|O_N J \bar{O}_{N\pi} |0\rangle - x \langle 0|O_{N\pi} J \bar{O}_N |0\rangle + x^2 \langle 0|O_{N\pi} J \bar{O}_{N\pi} |0\rangle$$

$$\langle 0|O_N J \bar{O}_{N\pi} |0\rangle = [\langle N | + x \langle N\pi |] J [y |N\rangle + |N\pi\rangle]$$

$$= \mathbf{y} \langle N|J|N\rangle + \mathbf{1} \langle N|J|N\pi\rangle + \mathbf{xy} \langle N\pi|J|N\rangle + \mathbf{x} \langle N\pi|J|N\pi\rangle$$

GEVP improvement on 3pt functions

	$\langle N J N \rangle$	$\langle N J N\pi \rangle$	$\langle N\pi J N \rangle$	$\langle N\pi J N\pi \rangle$
$\langle 0 O_N J \bar{O}_N 0 \rangle$	1	x	x	x^2
$-\mathbf{x} \langle 0 \mathbf{O}_N \mathbf{J} \bar{O}_{N\pi} 0 \rangle$	$-\mathbf{x} * \mathbf{y}$	$-\mathbf{x} * \mathbf{1}$	$-\mathbf{x} * \mathbf{x}\mathbf{y}$	$-\mathbf{x} * \mathbf{x}$
$-x \langle 0 O_{N\pi} J \bar{O}_N 0 \rangle$	$-xy$	$-x^2y$	$-x$	$-x^2$
$x^2 \langle 0 O_{N\pi} J \bar{O}_{N\pi} 0 \rangle$	x^2y^2	x^2y	x^2y	x^2
$\langle 0 O'_N J \bar{O}'_N 0 \rangle$	$(1 - xy)^2$	0	0	0

$$\begin{aligned} \langle 0|O'_N J \bar{O}'_N |0 \rangle &= \langle 0|(O_N - x O_{N\pi}) J (\bar{O}_N - x \bar{O}_{N\pi}) |0 \rangle \\ &= \langle 0|O_N J \bar{O}_N |0 \rangle - \mathbf{x} \langle 0|\mathbf{O}_N \mathbf{J} \bar{O}_{N\pi} |0 \rangle - x \langle 0|O_{N\pi} J \bar{O}_N |0 \rangle + x^2 \langle 0|O_{N\pi} J \bar{O}_{N\pi} |0 \rangle \end{aligned}$$

$$\begin{aligned} \langle 0|O_N J \bar{O}_{N\pi} |0 \rangle &= [\langle N| + x \langle N\pi|] J [y|N\rangle + |N\pi\rangle] \\ &= \mathbf{y} \langle N|J|N \rangle + \mathbf{1} \langle N|J|N\pi \rangle + \mathbf{x}\mathbf{y} \langle N\pi|J|N \rangle + \mathbf{x} \langle N\pi|J|N\pi \rangle \end{aligned}$$

GEVP improvement on 3pt functions

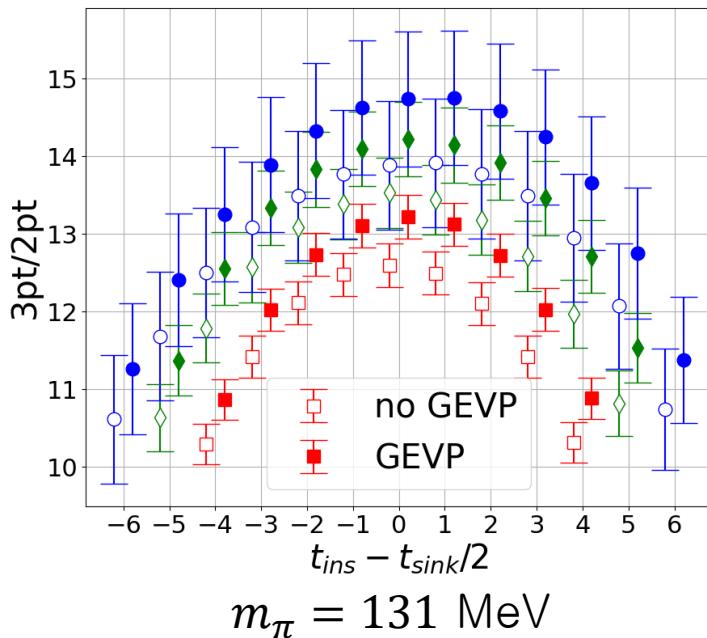
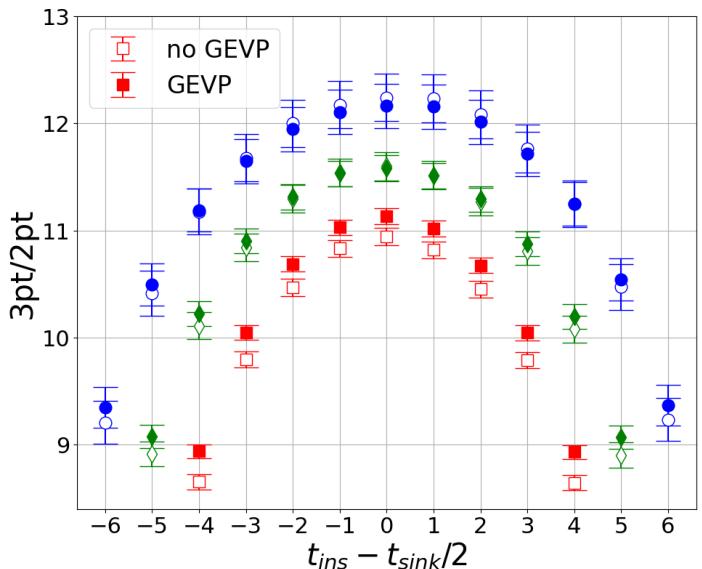
- We have: $\langle 0|O_N J \bar{O}_N |0\rangle \quad \langle 0|O_N J \bar{O}_{N\pi} |0\rangle \xrightarrow{\text{by symmetry}} \langle 0|O_{N\pi} J \bar{O}_N |0\rangle$
- So we can include three rows

	$\langle N J N\rangle$	$\langle N J N\pi\rangle$	$\langle N\pi J N\rangle$	$\langle N\pi J N\pi\rangle$
$\langle 0 O_N J \bar{O}_N 0\rangle$	1	x	x	x^2
$-x \langle 0 O_N J \bar{O}_{N\pi} 0\rangle$	$-xy$	$-x$	$-x^2y$	$-x^2$
$-x \langle 0 O_{N\pi} J \bar{O}_N 0\rangle$	$-xy$	$-x^2y$	$-x$	$-x^2$
$x^2 \langle 0 O_{N\pi} J \bar{O}_{N\pi} 0\rangle$	x^2y^2	x^2y	x^2y	x^2
$\langle 0 O'_N J \bar{O}'_N 0\rangle$	$1 - 2xy$	$-x^2y$	$-x^2y$	$-x^2$

- Conclusions can be made without the inclusion of the 4th row.
- Contamination from $\langle N|J|N\pi\rangle$ and $\langle N\pi|J|N\rangle$ will be mostly removed
- Contamination from $\langle N\pi|J|N\pi\rangle$ will be flipped
- In both cases, we should see changes. => If NO changes are seen, contamination does NOT come from the $N\pi$ state under consideration

GEVP improvement on 3pt functions:

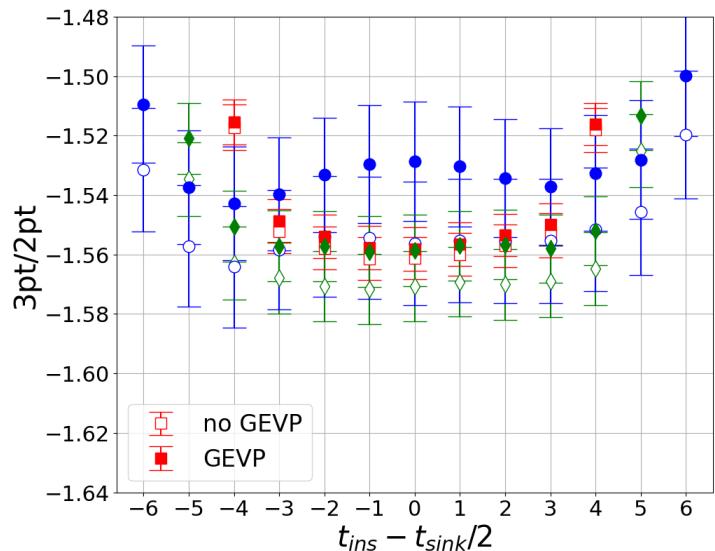
$$J = S^{u+d} = \bar{u}u + \bar{d}d; \quad \vec{q} = (0, 0, 0)$$



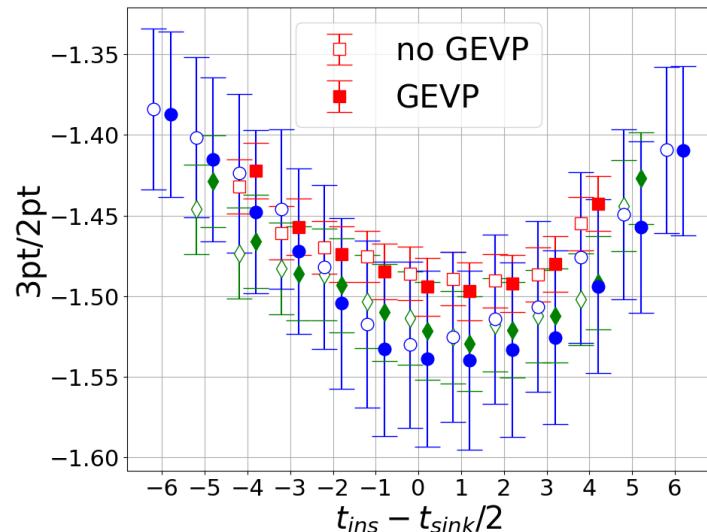
- Different color & shape denote different t_{sink}
- No significant improvement

GEVP improvement on 3pt functions:

$$J = A_3^{u-d} = \bar{u}\gamma_5\gamma_3 u - \bar{d}\gamma_5\gamma_3 d; \vec{q} = (0, 0, 0)$$



$$m_\pi = 346 \text{ MeV}$$

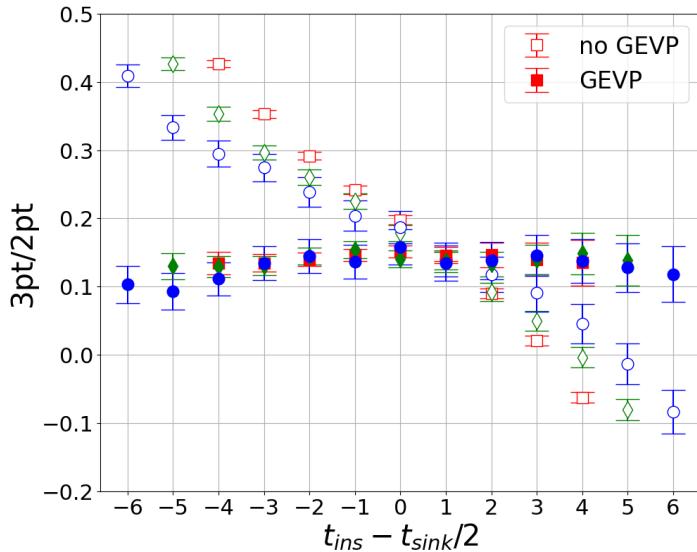


$$m_\pi = 131 \text{ MeV}$$

- No significant improvement

GEVP improvement on 3pt functions:

$$J = A_4^{u-d} = \bar{u}\gamma_5\gamma_4 u - \bar{d}\gamma_5\gamma_4 d; \vec{q} = (0, 0, 1)$$

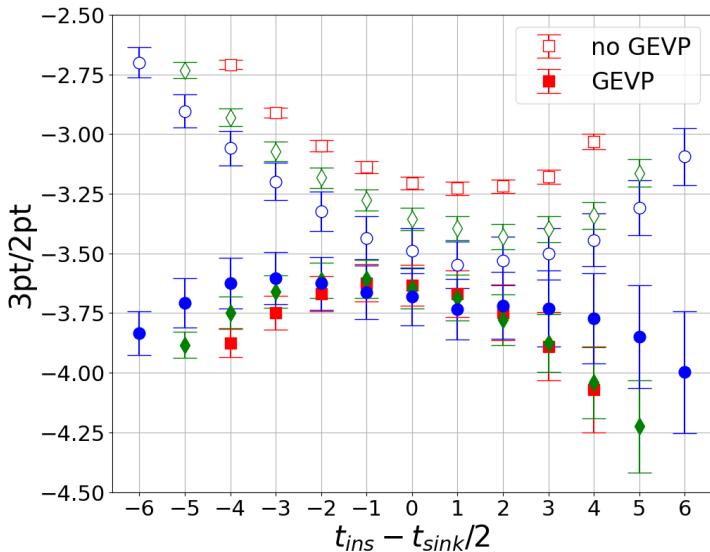


$$m_\pi = 346 \text{ MeV}$$

- Significant improvement compared with the two previous cases
- Physical point results are in producing

GEVP improvement on 3pt functions:

$$J = P^{u-d} = \bar{u}\gamma_5 u - \bar{d}\gamma_5 d; \quad \vec{q} = (0, 0, 1)$$

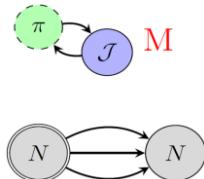


$$m_\pi = 346 \text{ MeV}$$

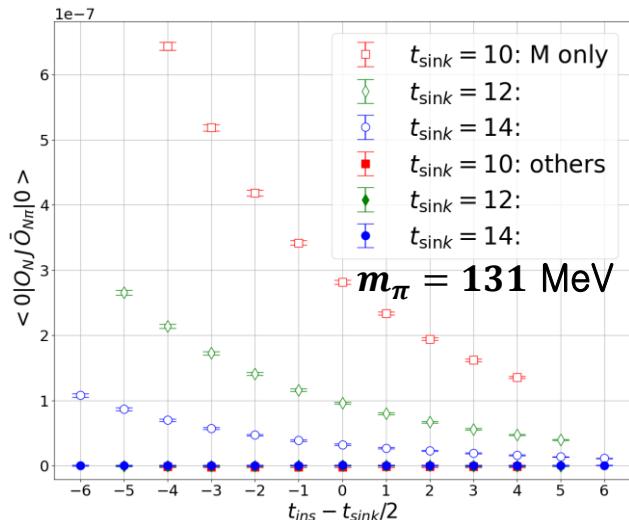
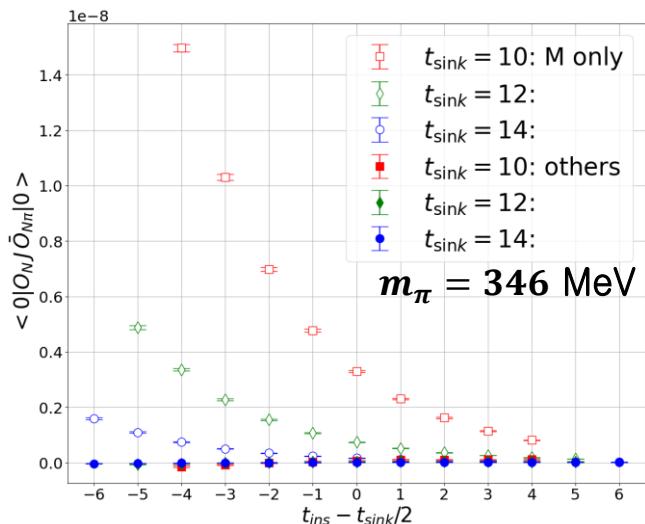
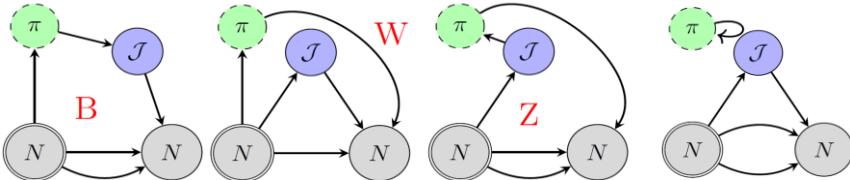
- Significant improvement
- Physical point results are in producing

GEVP on 3pt: dominant contribution

M:



others:



- M is the dominant diagram in both ensembles
- Agree with Regensburg group

Summary

- Studied two ensembles:
 - $N_L^3 = 24^3$ and $m_\pi = 346$ MeV
 - $N_L^3 = 48^3$ and $m_\pi = 131$ MeV
- Performed a GEVP analysis for the 2pt functions
- Projected 3pt functions using the optimized eigenvectors

Outlook

- Complete physical point ensemble
- Include more states in the GEVP
 - Other momenta (\vec{p}_{tot} and \vec{q})
 - Other two-particle states?

THANKS



Με τη συγχρηματοδότηση
της Ευρωπαϊκής Ένωσης



Κυπριακή Δημοκρατία



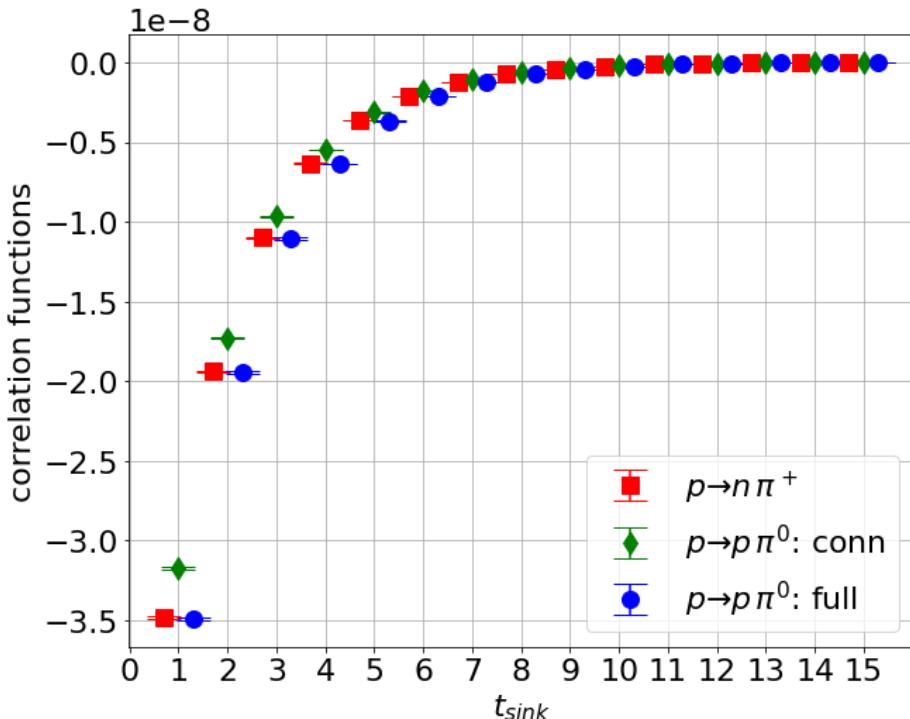
ΙΔΡΥΜΑ
ΕΡΕΥΝΑΣ ΚΑΙ
ΚΑΙΝΟΤΟΜΙΑΣ

EXCELLENCE/0421/0043

Isospin symmetry

$$\langle 0 | O_p \begin{bmatrix} \bar{O}_{n\pi^+} = \sqrt{\frac{2}{3}} O_{\frac{1}{2}} + \sqrt{\frac{1}{3}} O_{\frac{3}{2}} \\ \bar{O}_{p\pi^0} = -\sqrt{\frac{1}{3}} O_{\frac{1}{2}} + \sqrt{\frac{2}{3}} O_{\frac{3}{2}} \end{bmatrix} | 0 \rangle$$

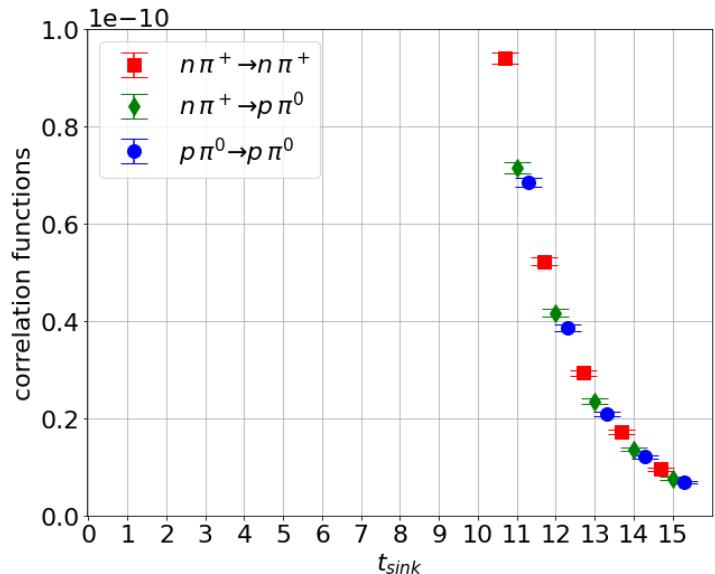
$$\langle 0 | O_p \bar{O}_{n\pi^+} | 0 \rangle = \langle 0 | O_p \bar{O}_{p\pi^0} | 0 \rangle \times (-\sqrt{2})$$



Isospin symmetry

$$\langle 0 | O_{n\pi^+} \bar{O}_{n\pi^+} | 0 \rangle \xrightarrow{t \rightarrow \infty} \begin{bmatrix} \langle 0 | O_{n\pi^+} \bar{O}_{p\pi^0} | 0 \rangle \times (-\sqrt{2}) \\ \langle 0 | O_{p\pi^0} \bar{O}_{p\pi^0} | 0 \rangle \times 2 \end{bmatrix}$$

No loops



With loops

