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Overview of the full-simulation framework at Muon Collider

on behalf of the Muon Collider Detector and Physics Group

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Muon Collider detector: current baseline



Need to redesign the detector from ground up for $\mu^+\mu^-$ collisions at $\sqrt{s} = 3, 10$ or more TeV

full simulation is essential for accurate evaluation of the detector performance \rightarrow

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- Muon Collider detector follows the typical layout of general-purpose collider experiments:
 - low-material-budget tracking detector (TRK)
 - → Vertex Detector (VXD) → + Inner Tracker + Outer Tracker ●
 - electromagnetic calorimeter (ECAL)
 - hadronic calorimeter (HCAL)
 - superconducting solenoid
 - muon spectrometer 🛛 🔵 not so typical

large tungsten nozzles (MDI) → machine-detector interface → essential for absorbing beam-induced background (BIB) induced by muon decays inside the beam

Present model largely based on the CLIC design (e^+e^- at $\sqrt{s} \le 3$ TeV) works decently for $\mu+\mu$ - at $\sqrt{s} = 1.5$ TeV







Beam Induced Background

We want our simulation studies to be representative of what it will look like in the actual experiment

all BIB effects have to be included in the most realistic way possible \rightarrow





BIB simulation is done in two separate stages:

- 1. Muons in the accelerator \rightarrow FLUKA \rightarrow BIB particles at the MDI surface
- 2. BIB particles in the detector \rightarrow **GEANT4**

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physics analysis will be done on this kind of events



→ detector signals for event reconstruction





Simulation process



- 1. generation of stable input particles:
- 2. simulation of the detector response to the incoming particles
- 3. simulation of detector effects efficiency, electronics noise + thresholds, ...
- 4. reconstruction of higher-level objects photons, tracks, jets, particle identification



can be performed externally 5. higher-level analysis \leftarrow

Detector simulation and event reconstruction handled within a single <u>framework</u> → inherited from the CLIC experiment: comprehensive and modern workflow designed for e+e- colliders Large overlap with the <u>Key4HEP</u> software stack: planning full transition in the future

Most of custom packages specific to the Muon Collider maintained in the public Muon Collider Software repository **Docker image** for an easy and OS-independent local setup **Installation instructions** available for CentOS 8 +

best for SW/algorithnm development

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best for data analysis with a fixed SW stack



BIB preparation: generation + simulation

For 0.75 TeV beams at $2 \times 10^{12} \,\mu$ /bunch $\rightarrow 4 \times 10^5$ muon decays/m in a single beam crossing muon decays and secondary interactions with the lattice are simulated externally \rightarrow

Result of a beam-decay simulation \rightarrow list of stable particles reaching the detector region

- collected at the outer surface of the detector + MDI
- $2 \times 7.3M$ particles \rightarrow in a text file (generated by MAP for $\sqrt{s} = 1.5$ TeV using MARS15)
 - represents only a fraction of the full BX statistics [weight = 22.2] \rightarrow

- Particle definitions converted to LCI0::MCParticle instances \rightarrow ILCSoft data model • creating copies of each particle (randomised in φ angle) for the right normalisation
 - $2 \times 160M$ particles \rightarrow saved to an LCIO file

GEANT4 simulation done in ILCSoft using DD4hep detector interface

- LCIO::MCParticle \rightarrow LCIO::Sim*Hit
- → final output structure depends on the processing strategy:

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Full simulated event obtained via three distinct stages:

GEANT4 simulation of Signal: straightforward and fast

Overlay of BIB*: performed in each event before digitisation → sensitive to the # of BIB SimHits and merging logics

Reconstruction speed of higher-level objects strongly depends on the amount of input RecHits from BIB

- especially relevant for track reconstruction (combinatorics)
- BIB contribution has to be suppressed as early as possible

* Currently reading the same full simulated BX during the Overlay step

→ more flexible mixing of smaller batches of BIB particles will be possible with the new approach based on FLUKA

Every simulation step requires careful treatment of computing resources

DISK STORAGE DISK I/O **CPU TIME** Nazar Bartosik

Detector simulation process







Properties of the BIB contribution

BIB Particles

10⁶

0

50

BIB has several characteristic features \rightarrow crucial for its effective suppression

- 1. Predominantly very soft particles (p << 250 MeV) except for neutrons fairly uniform distribution in the detector \rightarrow no isolated signal-like deposits └→ conceptually different from pile-up contributions at the LHC
- **2.** Significant spread in time (few ns + long tails up to a few μs) $\mu^+\mu^-$ collision time spread: 30ps (defined by the muon-beam properties) \rightarrow strong handle on the BIB \rightarrow requires state-of-the-art timing detectors
- **3.** Large spread of the origin along the beam

different azimuthal angle wrt the detector surface + affecting the time of flight to the detector → relevant for position-sensitive detectors



Detector simulation software and computing

150

200

100

3

GEANT4 simulation of **BIB**

Not all of the ~10⁸ BIB particles arriving to the detector are relevant for its performance in a real experiment \rightarrow we want to exclude all BIB particles from the simulation chain as early as possible

No GEANT4 simulation of particles arriving too late 1.

hits at t > 10ns will be outside of the realistic readout time windows \rightarrow all particles with t > 25 at the MDI surface are discarded (accounting for TOF)

2. No GEANT4 simulation of low-energy neutrons

high-precision neutron model required for accurate simulation: **QGSP BERT HP** but they are slow \rightarrow arrive to the detector with a significant delay \rightarrow neutrons with $E_{kin} < 150 \text{ MeV}$ can be safely excluded + faster model: QGSP BERT

Improved GEANT4 simulation of a single BIB event from 127 days \rightarrow 1 day → ~10-100 reusable events can be generated in several days

- All these cutoffs might still introduce bias in certain edge cases (e.g. long-lived particles) → exact cutoff values must be re-evaluated whenever something changes
 - beam energy
 - MDI design, etc. \bullet

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Detector simulation software and computing

×6 less CPU

×20 less CPU



50 100 150 200 250 300 350 400 450 500 Hit time - T0 [ns]





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Digitisation logics

GEANT4 hits produced separately for Signal and BIB \rightarrow merging + detector effects added during digitisation → two distinct classes of hits: CalorimeterHit (ECAL, HCAL, Muon detector) + TrackerHit (Tracking detector)

- **1.** Calorimeter hits: cell ID + E_{dep} + timestamp large cells (0.5×0.5 - 3×3 cm) \rightarrow manageable # of cells → hits merged within a fixed readout time window (O-10ns)
- 2. TrackerHits: sensor ID + 2D position + time and more small pixels (50 \times 50 μ m) to macro-pixels (0.05 \times 10 mm) \rightarrow too many channels to treat them individually in GEANT4
 - **2.1.** Simple 3D smearing by $\sigma_U | \sigma_V | \sigma_t$ (30-60ps)

simple and fast NO charge sharing, pile-up, electronics effects, etc.

2.2. Realistic simulation of sensor + readout-chip response

complex and slow allows cluster-shape analysis for better BIB suppression \rightarrow more expensive digitisation \rightarrow potential savings in track reconstruction

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Tracking optimisation

Reconstruction of tracks suffers from large combinatorial background → need suppression of BIB hits + efficient tracking strategies/algorithms

- Selection of hits in the narrow time window tailored to the sensor position \rightarrow limited by the time resolution + beamspot time spread + non-relativistic TOF
- Selection of hit doublets aligned with the IP (double layers in the Vertex Detector) 2. \rightarrow limited by the IP position resolution \rightarrow requires multi-stage tracking strategy



Determine IP position with faster track reconstruction

- only central region
- inward search from ROI

Impacts acceptance for displaced tracks affecting the b-tagging performance \rightarrow has to be used with care, keeping the track topologies in mind

Trying to maintain each filtering stage as a standalone configurable processor

- OverlayTimingGeneric: selects SimHits within a wide time window for digitization
- DDPlanarDigiProcessor: drops out-of-time hits after time smearing during digitization
- FilterDoubleLayerHits: drops hits without a pair aligned with the IP

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With the current approach we pack a full BX into 1 file



BIB from the whole BX is treated as a single entity: 1K BIB simulations \rightarrow 1K independent events

In FLUKA we force every muon to decay and record the resulting particles reaching the MDI surface we can simulate muon decays in batches: e.g. 1K muons/batch \rightarrow 1 batch/event



SimHits from all the 10⁸ BIB particles are split into virtual events: ~20K particles/event

to simplify processing during Overlay

during Overlay randomly pick the necessary number



















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Latest developments

Several recent and ongoing developments are expanding the range of possible full-simulation studies

Adopting the ACTS tracking software for faster computational performance

- └→ targeting full 4D track reconstruction in the future
 - \rightarrow potential for early rejection of fake track candidates based on bad χ^2

Realistic digitisation of pixel sensors to exploit cluster shapes for BIB rejection

 \rightarrow BIB particles crossing sensors at shallow angles \rightarrow wider clusters

Alternative subdetector designs : Crilin ECAL, MPGD HCAL and Muon Detector

→ dedicated digitisation code is being developed

Generation of lightweight BIB samples with trimmed collections

→ reduced use of computing resources

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Muon Collider detector-simulation software is based on the solid ILCSoft framework with centrally distributed releases: <u>standalone + containers</u>

We now have full control over the BIB generation thanks to the FLUKA-based workflow providing new opportunities for detector + MDI optimisation

A lot of developments on top of the baseline CLIC version have been implemented to provide sufficient computational performance in presence of BIB

Many ongoing developments are concentrated on improving the detector performance at the level of digitisation and reconstruction algorithms

Considering a transition to <u>Key4HEP</u> framework after several performance issues are resolved

