

IP and PIP Shortening the seismic attenuation chain

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LF noise is given by

- Microseism motion
- Newtonian noise
- Upconversion of residual motion into the detection band
- Control noise

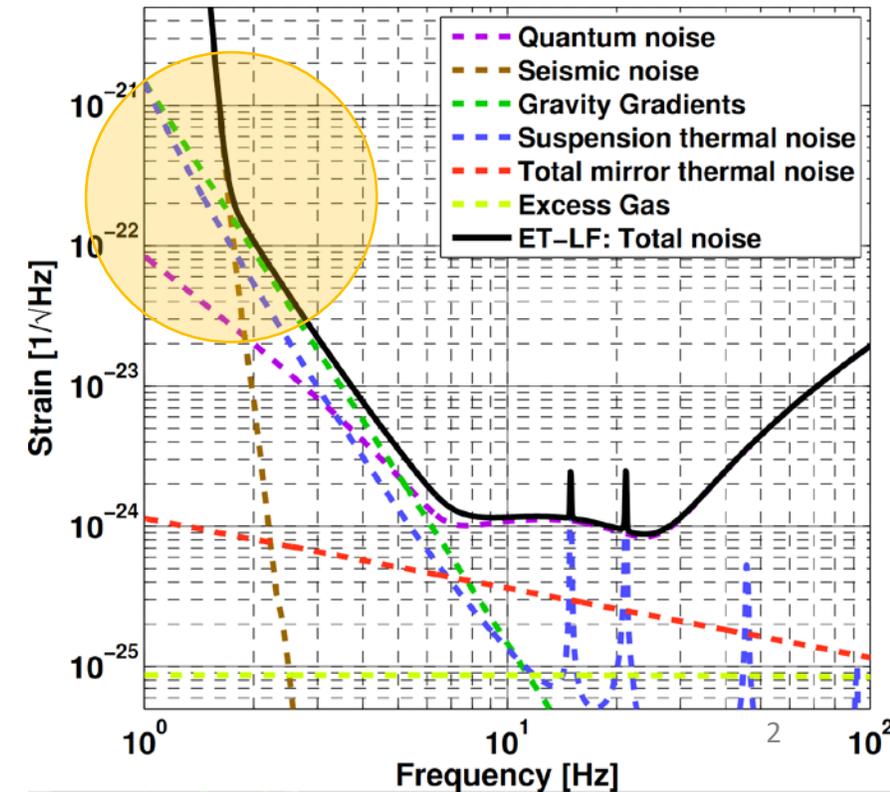
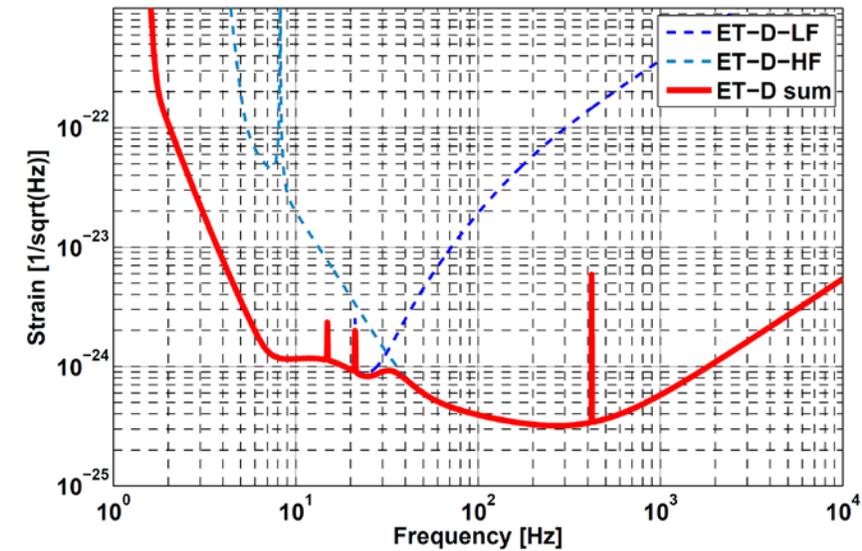
Design curve based on 17 m tall suspensions

Reduction to less than 10 m:

- Significantly lower cavern excavation cost
- Suspension management similar to Virgo

Newtonian noise crossing:

$2 \cdot 10^{-22} \text{ Hz}^{-1/2}$ at 1.8 Hz (AdV: 3.2 Hz)



Sardinia vertical

$3 \cdot 10^{-8} \text{ ms}^{-2} \text{ Hz}^{-1/2}$ at 2 Hz

$7.5 \cdot 10^{-10} \text{ m Hz}^{-1/2}$ at 2 Hz

Suspension point 30 mHz IP

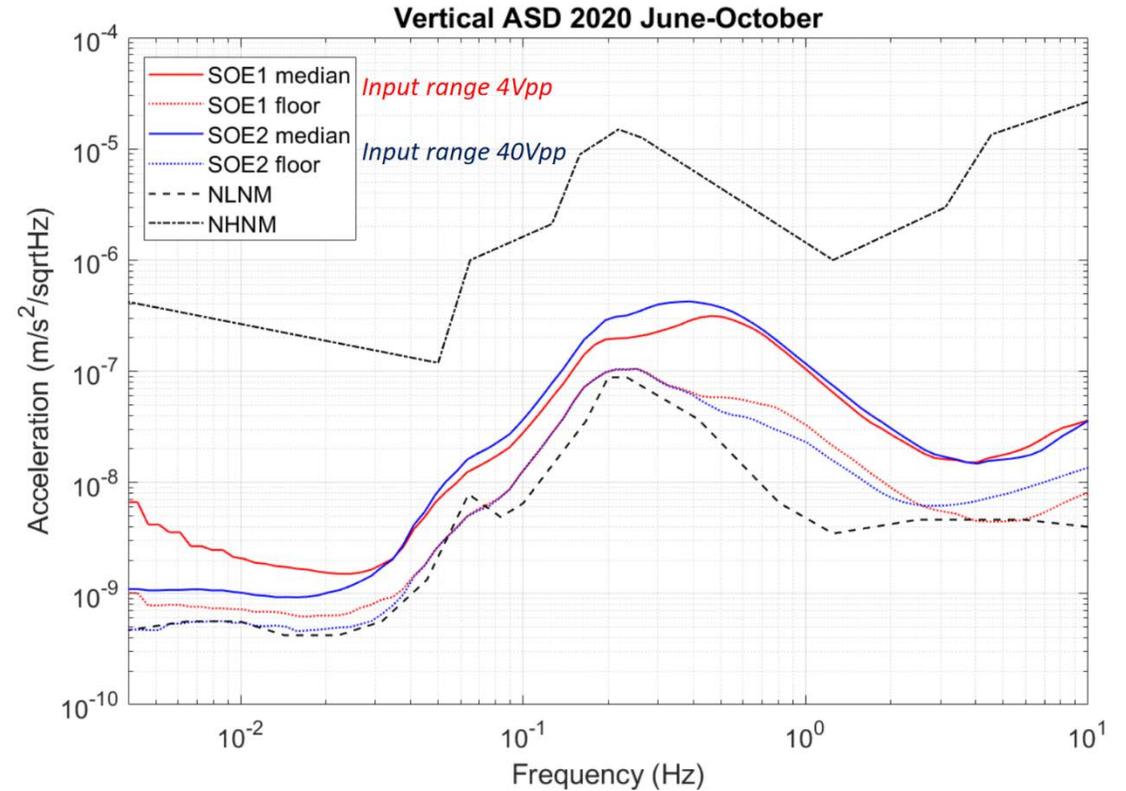
$10^{-13} \text{ m Hz}^{-1/2}$ at 2 Hz

Mirror

$2 \cdot 10^{-22} \text{ Hz}^{-1/2}$ at 2 Hz

$10^{-18} \text{ m Hz}^{-1/2}$ at 2 Hz

Required attenuation: $A=10^{-5}$ including marionetta and mirror



Cascina

$3 \cdot 10^{-9} \text{ m Hz}^{-1/2}$ at 6 Hz

Suspension point

$7.5 \cdot 10^{-14} \text{ m Hz}^{-1/2}$ at 6 Hz

Mirror

$10^{-22} \text{ Hz}^{-1/2}$ at 6 Hz (ET Scenario 1)

$1.5 \cdot 10^{-19} \text{ m Hz}^{-1/2}$ at 6 Hz

$9 \cdot 10^{-19} \text{ m Hz}^{-1/2}$ at 6 Hz for PR or SR (70/450 finesse ratio)

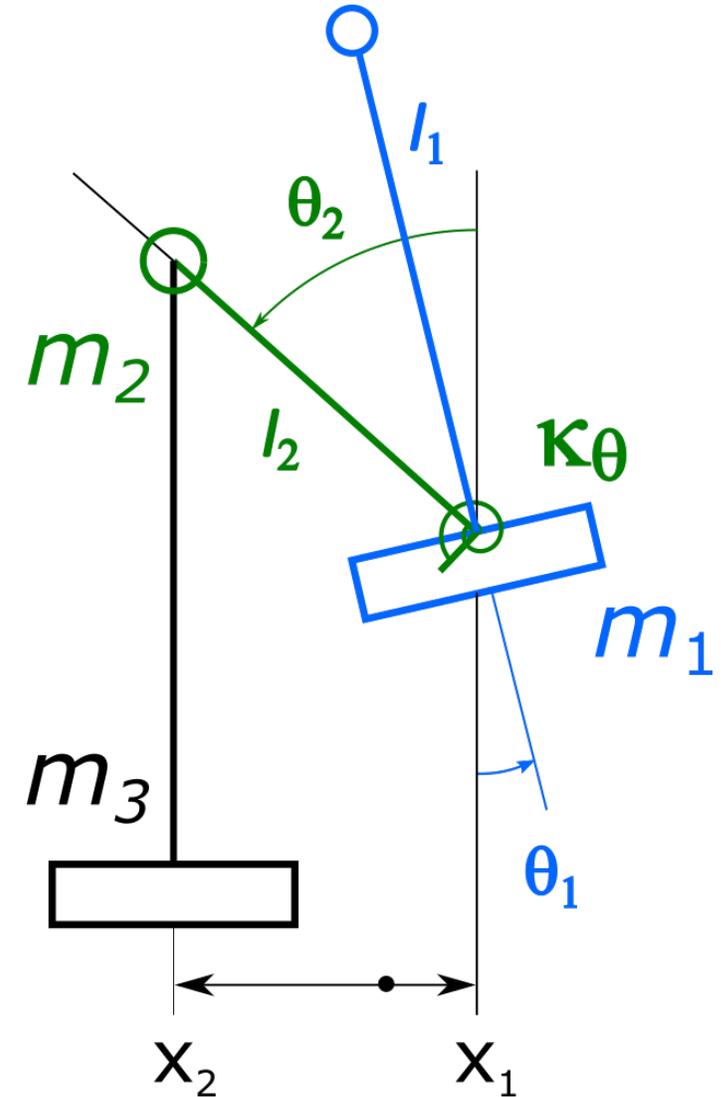
Attenuation: $A=10^{-5}$ including marionetta and mirror

Pendulum – Inverted pendulum

How to soften a suspension stage

- Spare length
 - For κ_θ sufficiently stiff, the system is stable
- l_1 : 1.544, # Pendulum length\
 - l_2 : 0.520, # IP length\
 - T_1 : 2551.0, # Pendulum tension\
 - T_2 : 1766.0, # IP compression\
 - m_1 : 80.0, # Pendulum mass\
 - m_2 : 80.0, # Filter mass\
 - m_3 : 100.0, # Load\
 - I_{1s} : 20.0, # Pendulum moment of inertia \
 - I_{2s} : 0.8, # IP moment of inertia\
 - k : 1700.0, # flex joint elastic constant\

Normal mode frequencies
0.68 Hz 0.74 Hz



Horizontal attenuation of a single PIP

$$A = \left(\frac{f_0^2}{f^2 - f_0^2} \right)^2$$

For $f_0 = 0.75$ Hz

A_2 : attenuation at 2 / 6 Hz

$$2.7 \cdot 10^{-2} / 2.5 \cdot 10^{-4}$$

Two PIP

A_2 : attenuation at 2 / 6 Hz

$$7.2 \cdot 10^{-4} / 6.3 \cdot 10^{-8}$$

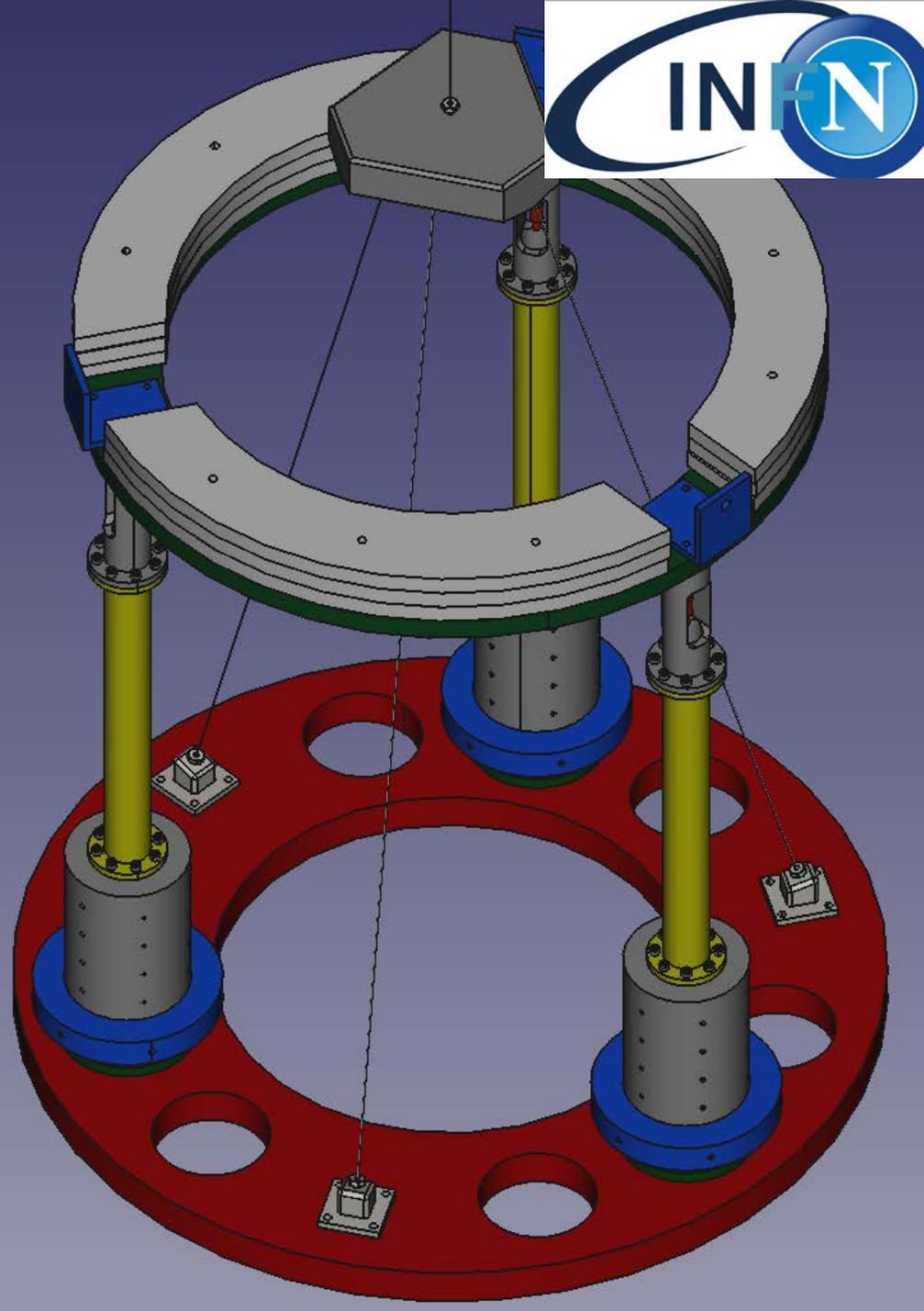
Three PIP

A_2 : attenuation at 2 / 6 Hz

$$1.9 \cdot 10^{-5} / 1.6 \cdot 10^{-11}$$

Basic structure

Explicit coupling of
pendulum and roll
DOF



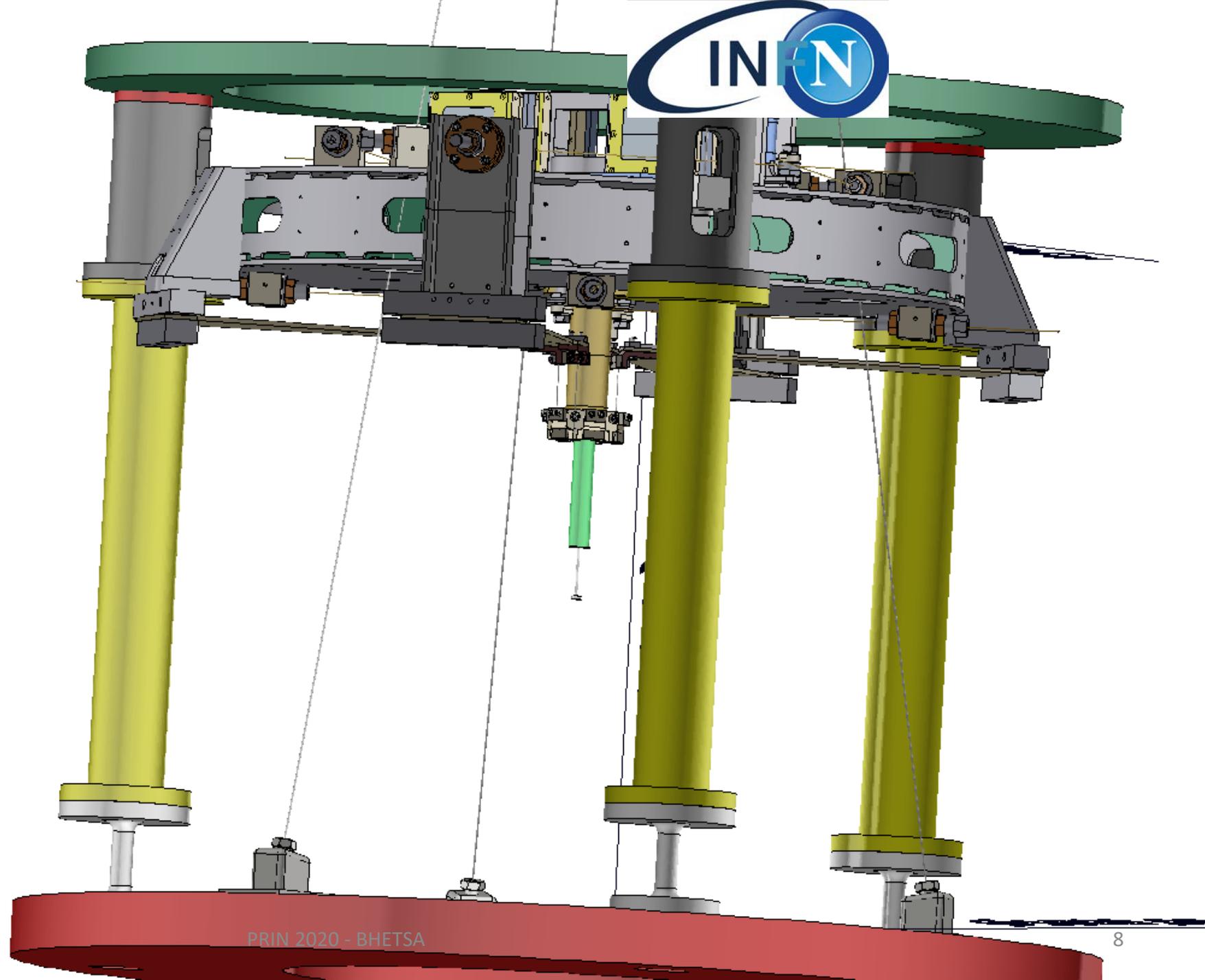
Standard filter addition for vertical attenuation

Filter suspended to IP
legs

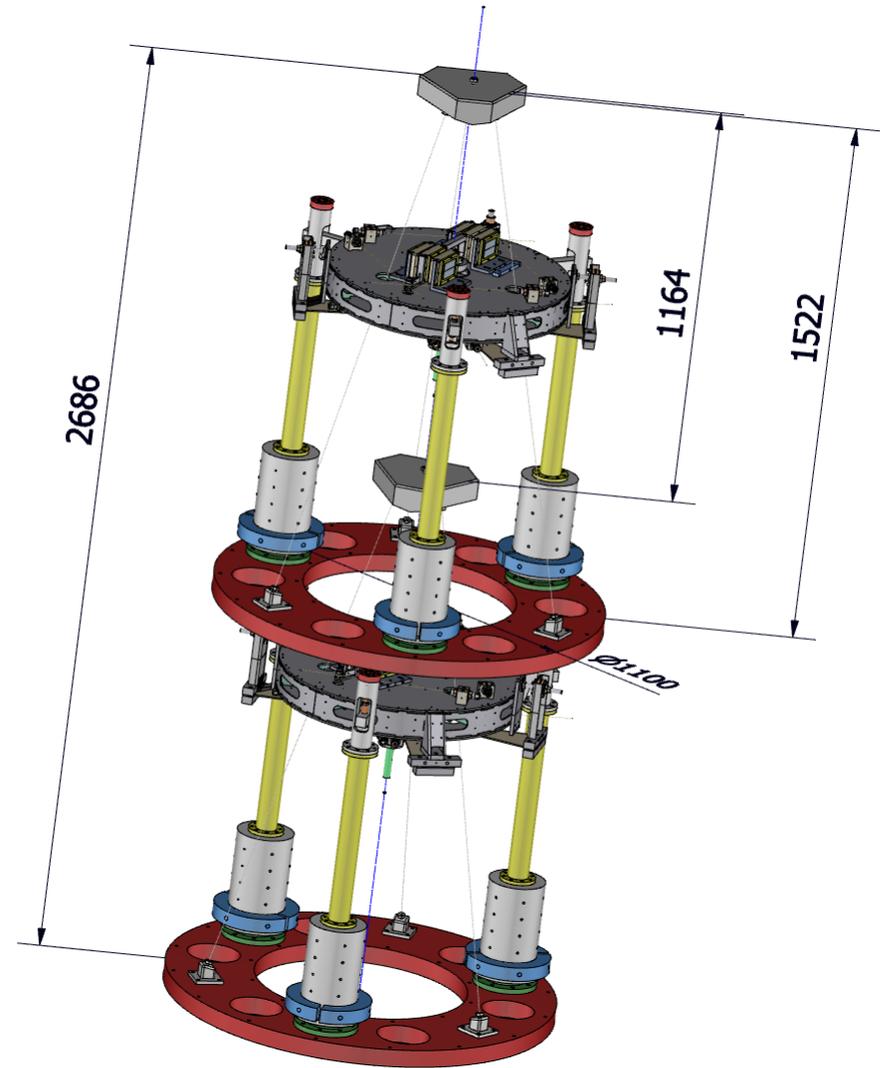
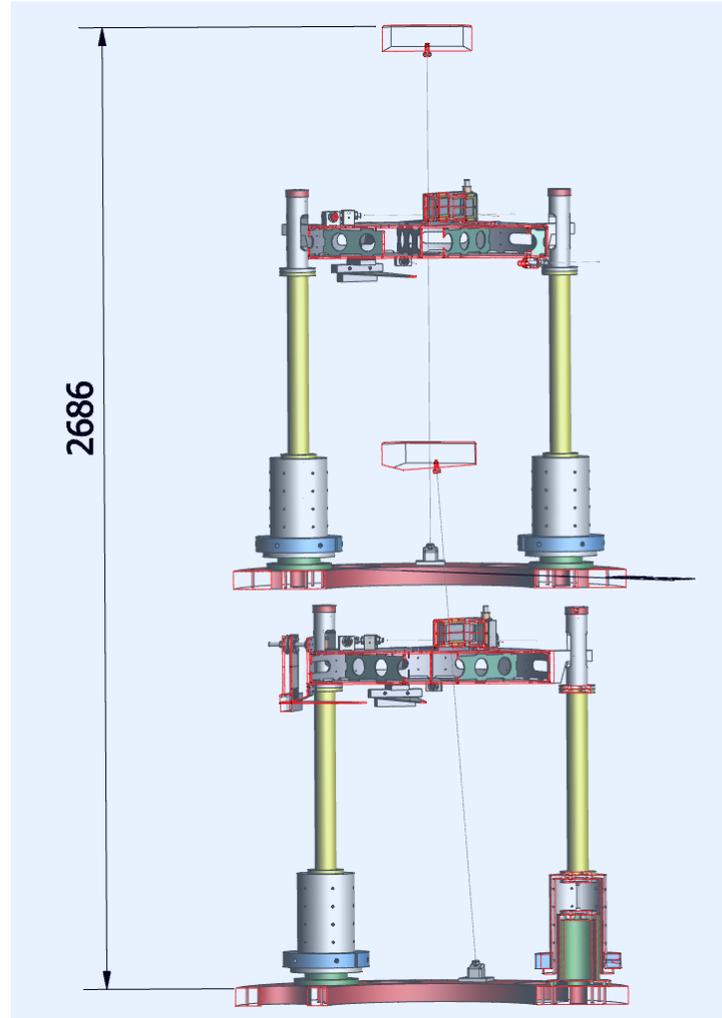
IP counterweights not
represented

Includes one stage of
vertical attenuation

Hook to next stage
above first pendulum
mass



- Entangled PIP
- Four filters in 2.70 m



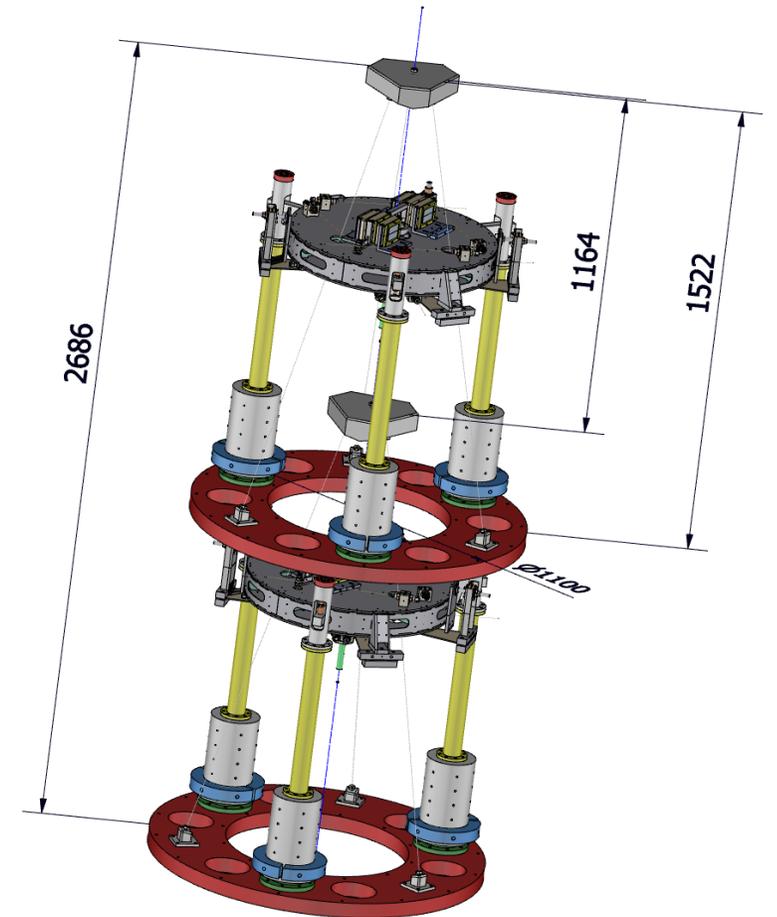
Overall length

- **A PIP chain can be built**

- Hook of the second PIP above the first filter
- Current PIP length 1.55 m
- Two PIP can live in $2.70 + 0.30 = 3.0$ m accounting for a dedicated vertical attenuation stage
- Three PIP can live in 4 m
- Proximity of different stages allows feedback control of normal modes, where sensor noise is not dominant (em or optical sensors like HoQI)

Suspensions for SRC mirrors

- Requirement on seismic isolation met with 1 IP and 2 PIP.
- Height of suspension point wrt mirror
 - Mirror: 0.7 m, marionetta: 1.0 m, 2 PIP hooks: 2.2
- Seismic isolation for stable recycling cavity mirrors could fit in 4 m from mirror center to suspension point



- **Package overview**

- MATLAB version developed by Paolo Ruggi
- To be hosted on Gitlab
- Now private repo, at some point public
- Available for developers (via git)
- Available for end users (via PIP, only on gitlab Package Registry, then move to Python Package Index)

- **Structure**

- Creation of configuration via GUI
- Configuration saved to JSON format
- Network solving to include feedback loops
- Calculation of transmission matrices
- Calculation of Transfer Function

- **Python scripts to iterate on parameters for optimization (see poster # 72)**

Suspensions for Virgo mirrors

- **PIP designed to fit into the Virgo towers**
- **VIRGO_nEXT calls for a low thermal noise payload -> additional low dissipation filter above marionetta**
- **Seismic isolation should be shortened**

- **2 – 3 PIP easily fit in the Virgo towers. R&D for VIRGO_nEXT proposed**

- **Progress in vertical attenuation to be included**

- **Main Features**

- Python (should be easy and multi-platform)
- Make it available for public usage (later on in the BHETSA life)

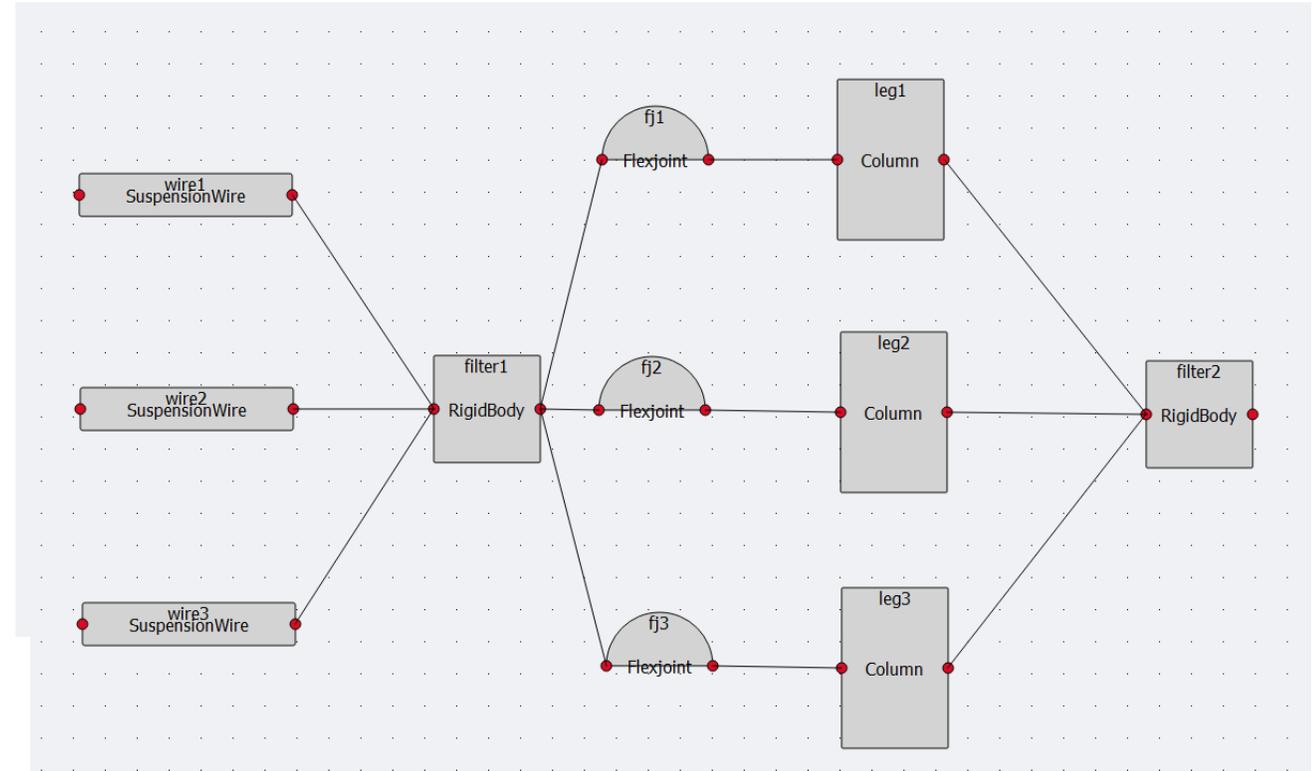
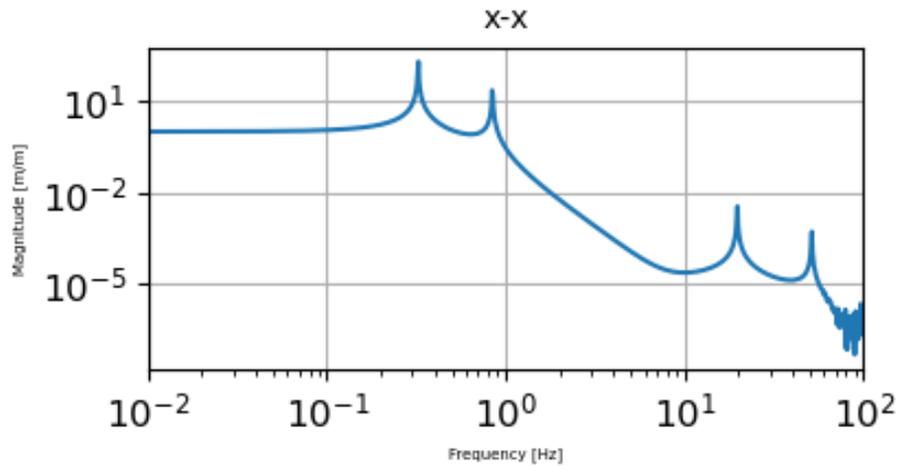
- **Development point of view**

- Implemented automatic documentation via Sphinx
- Implemented Pipelines for Continuous Integrationx
- Unittest for testing pieces of code
- Move to public platforms (Readthedocs and Python Package Index)
- Test against different versions of Python3
- Implement for usage with multi platform (Windows, MacOS2)
- Integrating new features (e.g. NetSolver class)

Test case: schematic PIP

• PIP

- Resonances @0.2 Hz (pend) and 0.8 (IP)
- attenuation $1/f^4$



L. Massaro Master thesis

- **General structure**

- Pipelines done
- Switch to public repo/documentation/package index when ready

- **Package development**

- Test with multi platform
- Finalize GUI
- Implement basic configurations as test cases
- Integrate network solver (already in Gitlab, merge done, test integration)

- **PIP Prototype construction**
 - Principle verification vs simulations
 - Engineering verifications
 - Assembly
- **Design optimization**
- **Proposal for a short seismic attenuation chain for ET**
- **Proposal for a shorter seismic attenuation chain for Virgo mirrors**
- **Proposal for a compact suspension for SRC mirrors**

Collaboration welcome!

- **#72 OctoPyus: a package to simulate seismic isolation systems for the third-generation Gravitational Wave detectors M. Razzano**
- **#100 The statics of the maraging blades in SuperAttenuators: simulation and tests P. Chessa**
- **#79 The Gravitational Wave Sky Simulator: a new package for fast simulations of gravitational wave sources L. Papalini**
- **#81 Machine learning for glitches classification in Advanced Virgo O3 M. Vacatello**
- **#82 Gravitational Wave Data Manager – A Python package for managing multichannel gravitational wave data M.A. Palaia**

Virgo seismic levels

- **Seism parametrization**

- $x(f) = 10^{-7} m Hz^{-1/2} \left(\frac{1 Hz}{f} \right)^2$, at 6 Hz $3 \cdot 10^{-9} m Hz^{-1/2}$

- **One 30 mHz IP attenuates**

- $2.5 \cdot 10^{-5} \tilde{x} = 7.5 \cdot 10^{-14} m Hz^{-1/2}$

- **ET scenario 1 at 6 Hz as ultimate Virgo_nEXT**

- $h = 10^{-22} Hz^{-1/2}$

- $\tilde{x} = 1.5 \cdot 10^{-19} m Hz^{-1/2}$ for a single test mass

- $\tilde{x} = 9 \cdot 10^{-19} m Hz^{-1/2}$ for PR or SR (70/450 finesse ratio)

- **Total attenuation 10^{-5} including pendulum (10^{-2}) -> 10^{-4} required**