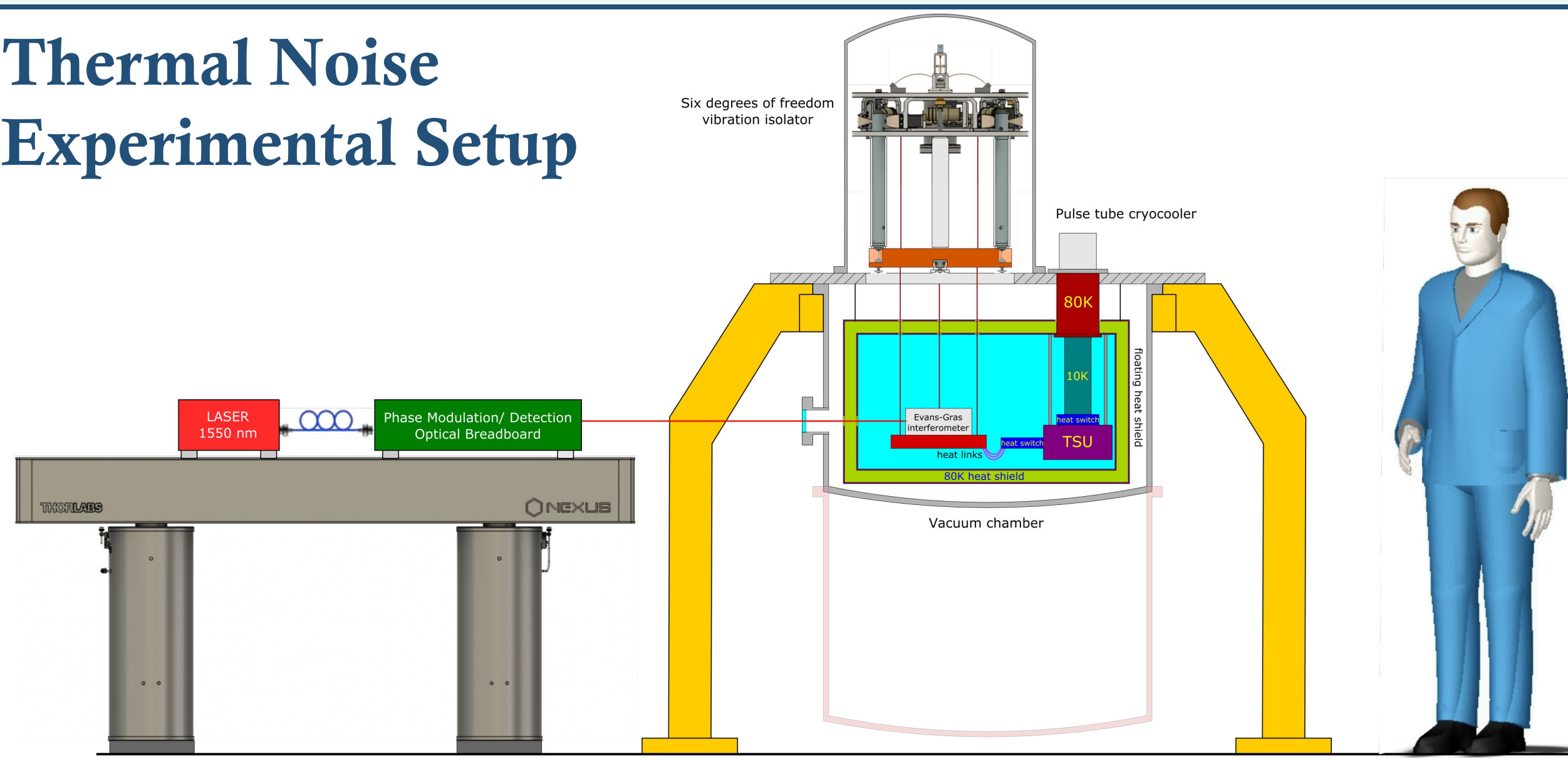


## Motivation & goals

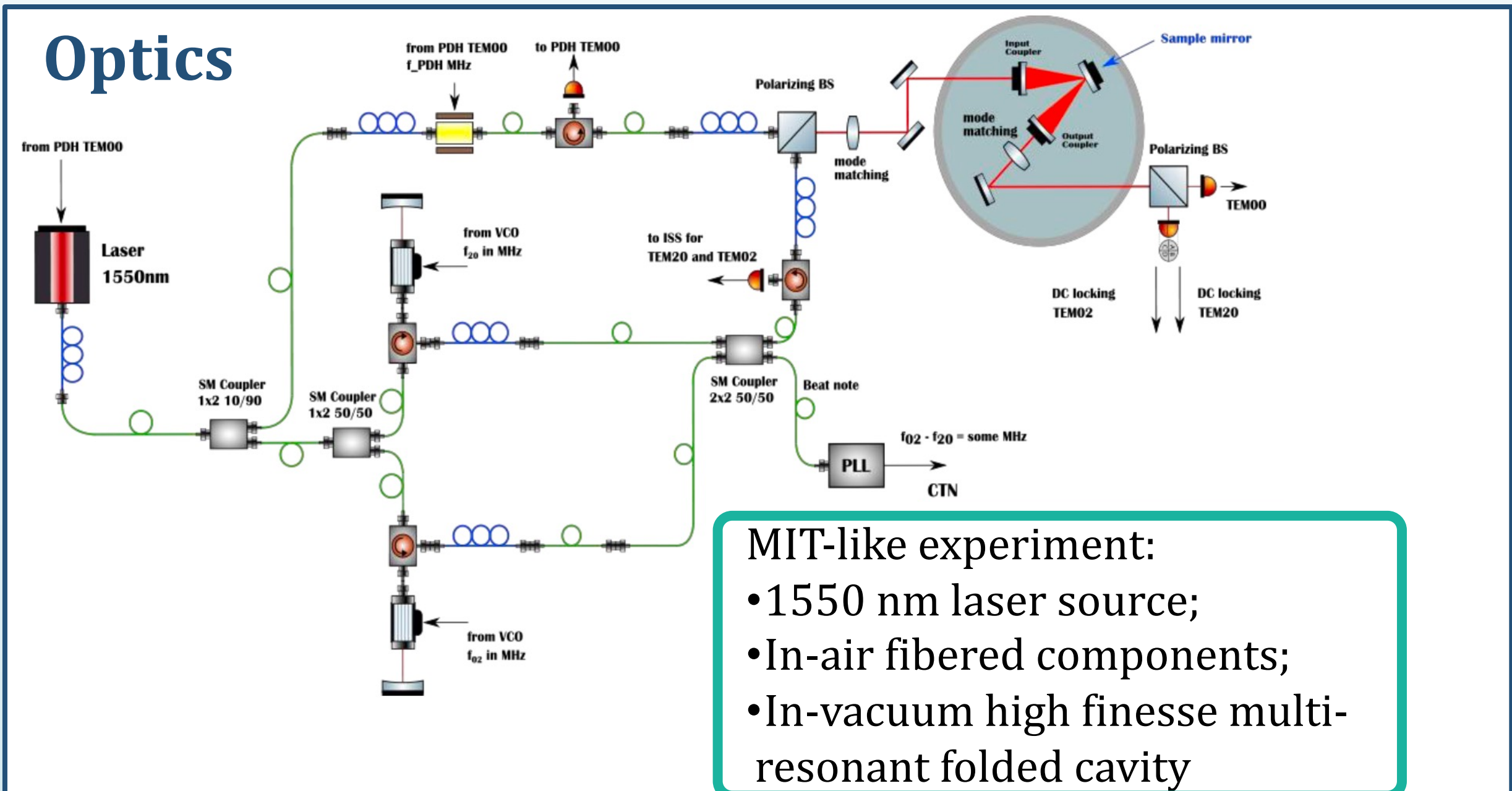
- Major improvements in GW instrumentation science are expected from the Thermal Noise (TN) reduction in the mid-frequency range of the detectors, achievable also by cooling down the mirrors to cryogenic temperature. In order to select the coating material that are intended to be used in the 3<sup>rd</sup> generation of detectors, the TN of new coatings should be directly measured using an interferometric method in a cryogenic environment.
- Reduction of local control noise in cryogenic 3<sup>rd</sup> gen. detectors requires new sensors and actuators compatible with low temperature environment. A low noise fast turn around cryogenic test bench would be essential.
- Liquid free low noise cryogenics is more and more required in many fields of fundamental physics. R&D on new low noise technology is of wide interest.

➔ A cryogenic optical bench with  $\sim 10^{-13} \text{ m}/\sqrt{\text{Hz}}$  residual motion above 30 Hz.

## Thermal Noise Experimental Setup



## Optics

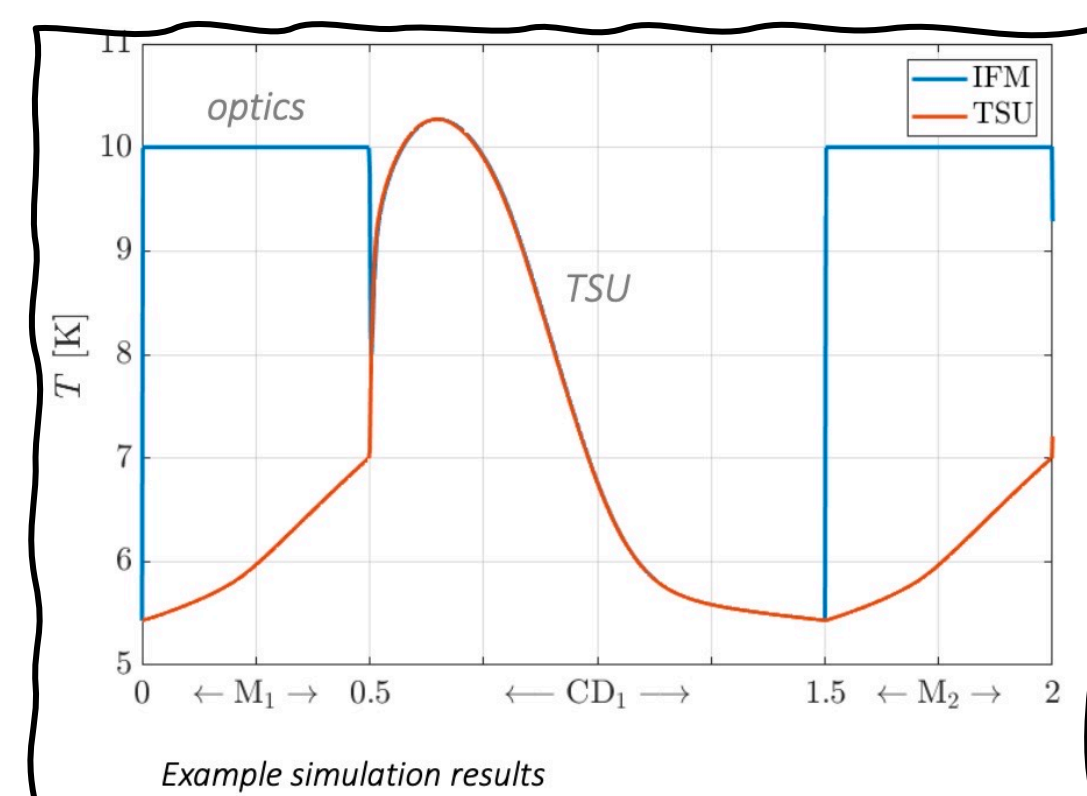


MIT-like experiment:

- 1550 nm laser source;
- In-air fibered components;
- In-vacuum high finesse multi-resonant folded cavity

## Cryogenics

- Dual stage cryocooler (CC) to cool the heat-shields (80 K and 4 K) and to charge a Thermal Storage Unit (TSU).
- Ultra-pure Aluminum low stiffness wires heat links.
- CC off during the measurement to avoid vibrations, TSU used as a heat sink.



➔ 0.5 hour quiet condition to make measurement.

## Mechanics

- Vibrations and thermal isolation: the optical bench is suspended by means of three titanium wires.
- Vertical & Tilt vibration isolation: each wire is connected to a pair of blade springs in Geometric Anti Spring (GAS) configuration located on the top platform. All three rigid body modes below 0.3 Hz.
- Horizontal isolation: Three inverted pendulum (IP) legs support the top platform. Translational modes at ~0.1 Hz and the yaw mode at 0.5 Hz.

## Sensors and Actuators

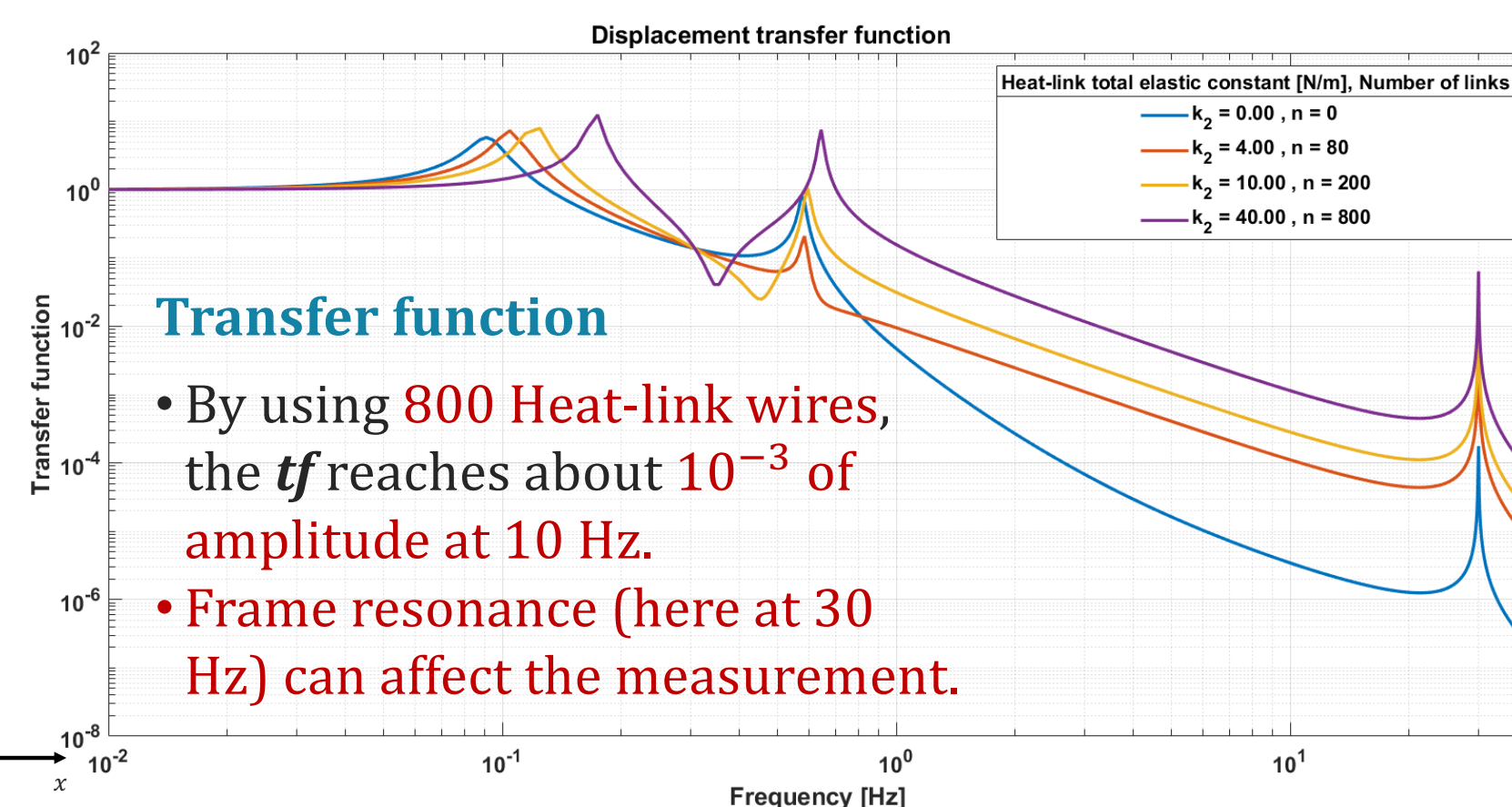
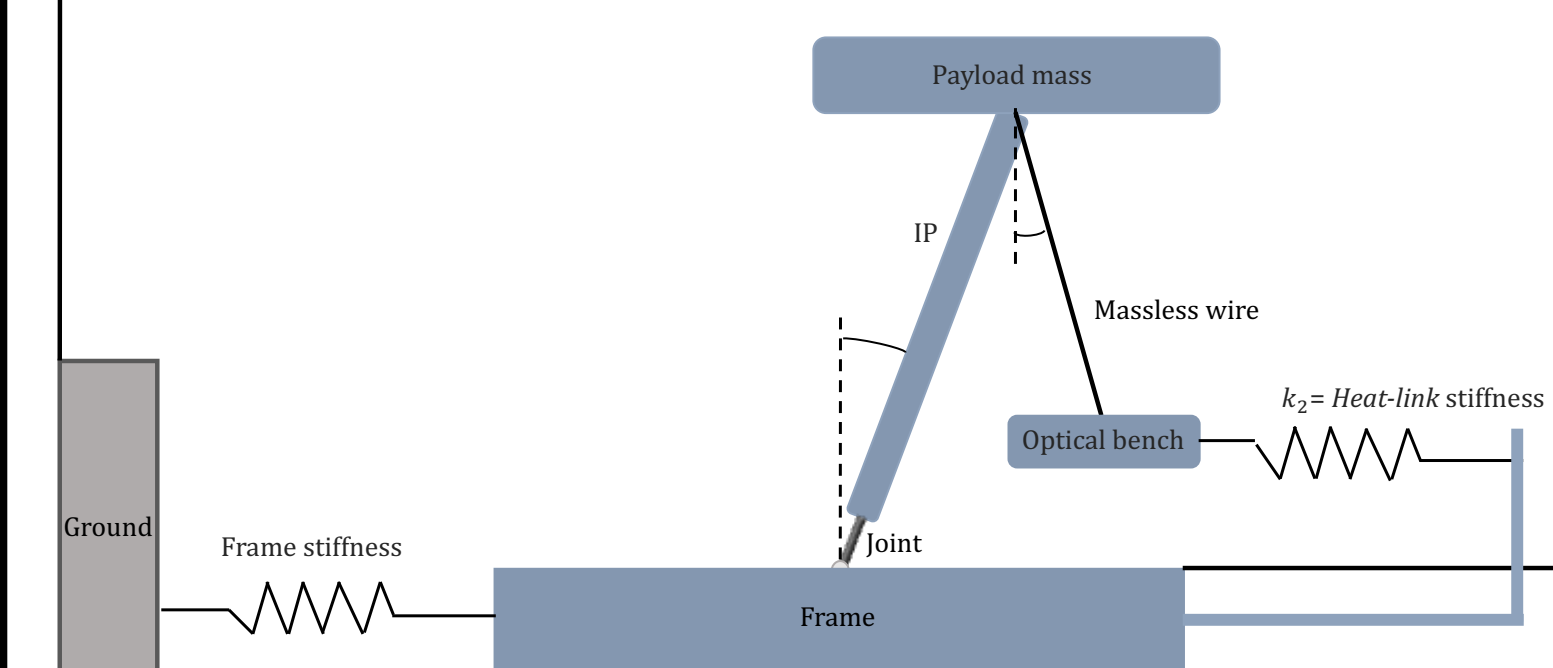
- Three horizontal and three vertical LVDT displacement sensors at the top platform level.
- Tri-axial seismometer "Trillium 120" at the center of the top platform inside a vacuum pod.
- Three Maxwell-pair actuators collocated to the horizontal LVDTs.
- Three voice-coil actuators collocated to the vertical LVDTs.

## Control strategy

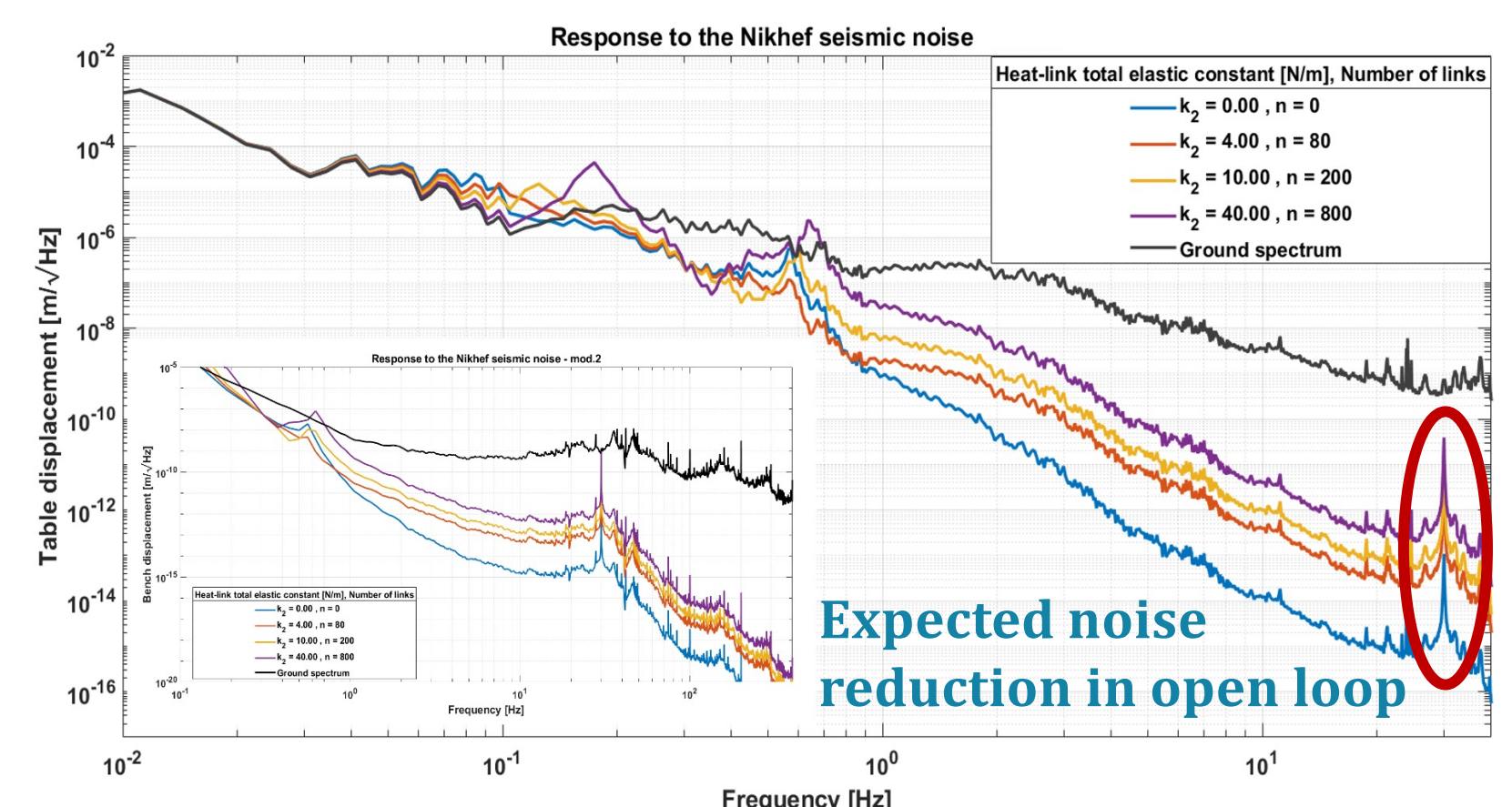
- NO sensors and actuators inside the cryostat.
- Horizontal DoFs controlled by a super-sensor LVDT+Seismometer.
- Yaw DoF controlled only by LVDTs.
- Vertical, Pitch and Roll controlled by sensor corrected LVDTs.

## Vibration Attenuation modelling

Lagrangian Model of the system horizontal DoF.



- Transfer function
- By using 800 Heat-link wires, the  $tf$  reaches about  $10^{-3}$  of amplitude at 10 Hz.
  - Frame resonance (here at 30 Hz) can affect the measurement.

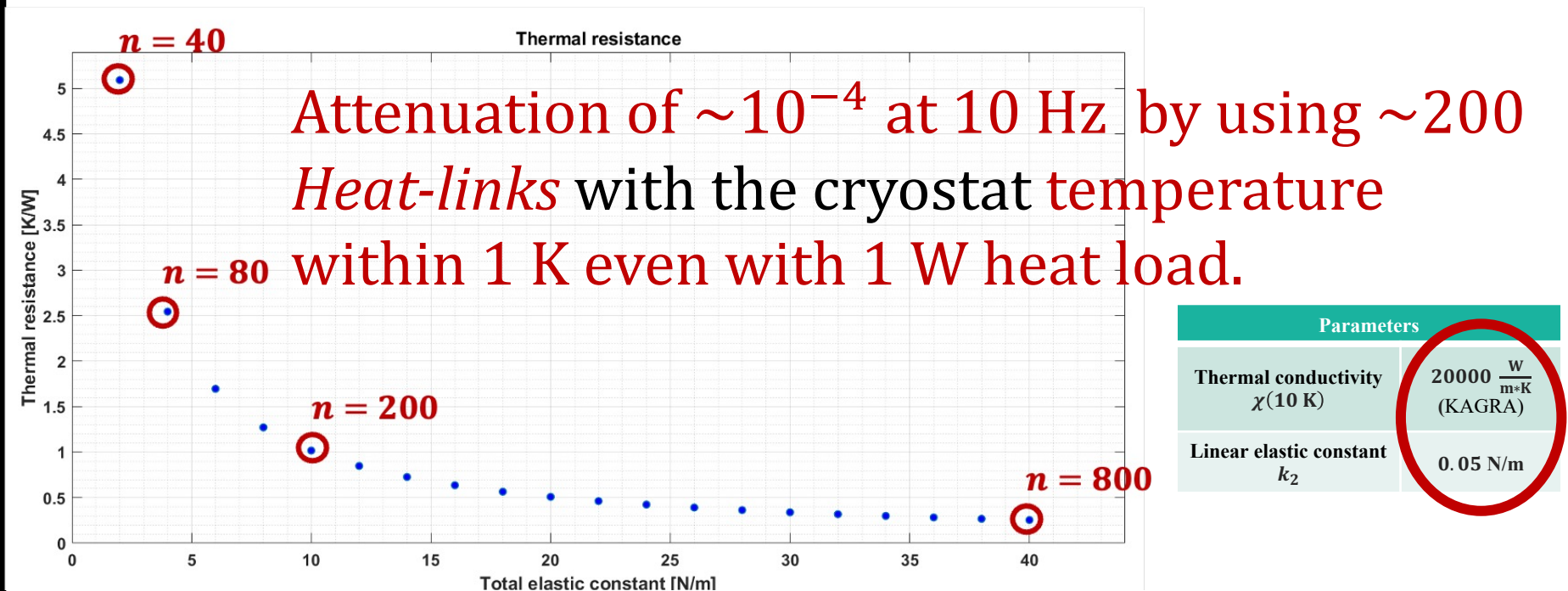
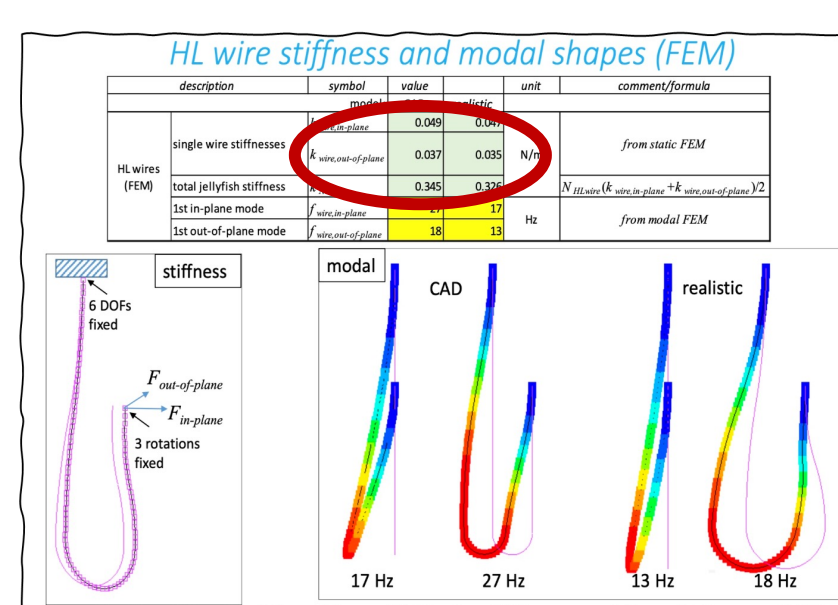


Expected noise reduction in open loop

## Heat-links Stiffness and Thermal Resistance

Two competing requirements

- Thermal resistance should be minimized.
- Stiff heat-links can spoil the measurement.



Attenuation of  $\sim 10^{-4}$  at 10 Hz by using  $\sim 200$  Heat-links with the cryostat temperature

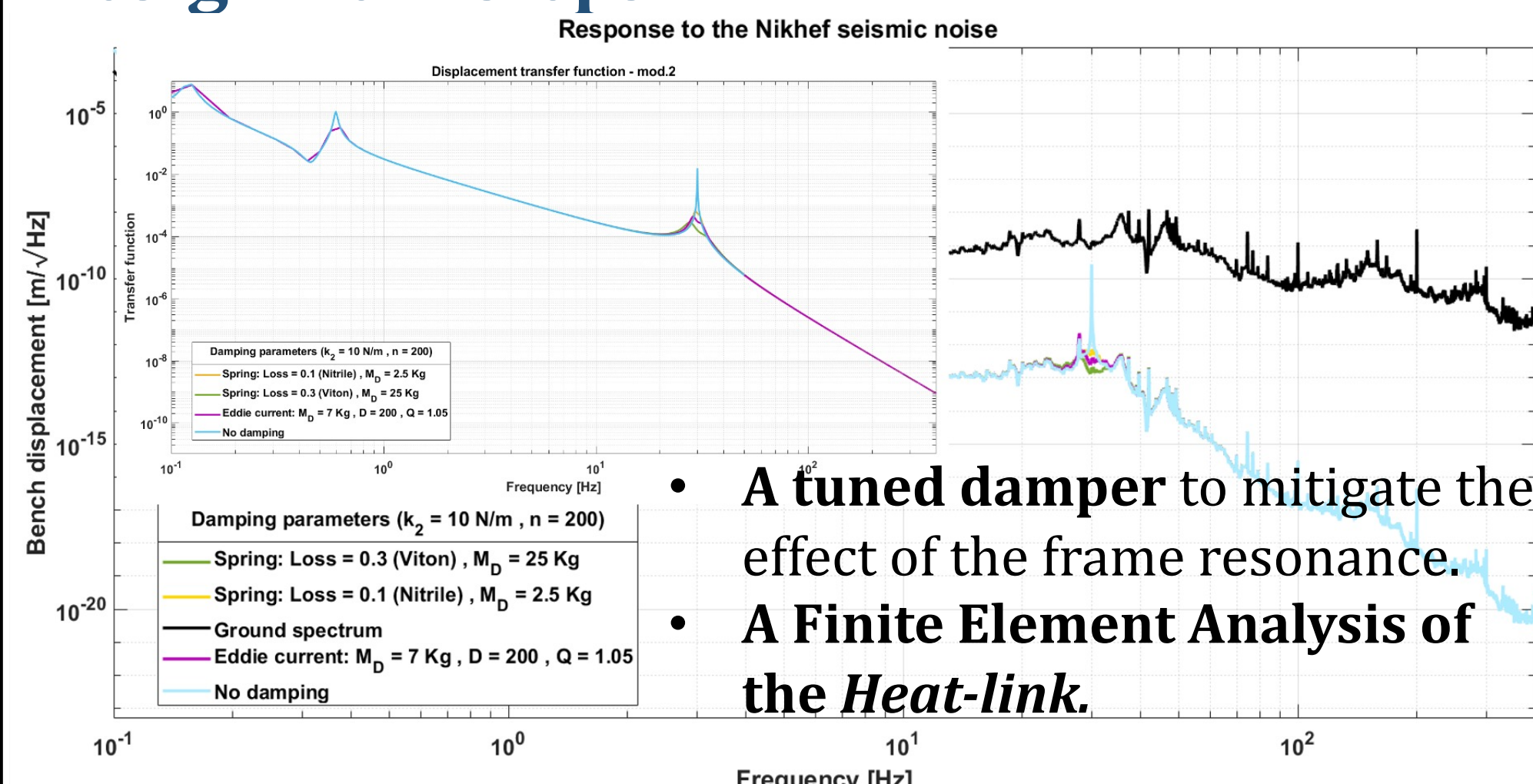
$n = 80$  within 1 K even with 1 W heat load.

Parameters

Thermal conductivity  $\chi(10 \text{ K})$  20000  $\frac{\text{W}}{\text{m} \cdot \text{K}}$  (KAGRA)

Linear elastic constant  $k_2$  0.05 N/m

## Design next steps



- A tuned damper to mitigate the effect of the frame resonance.
- A Finite Element Analysis of the Heat-link.

## Conclusion

Using 200 heat-links seems the best compromise up to now:

- Vibration attenuation @ 10 Hz:  $\sim 3000$
- $R_T = \frac{l}{\chi sn} \approx 1 \frac{\text{K}}{\text{W}}$  @ 10 K
- $\Delta T_{\text{bench-battery}} \sim 1 \text{ K}$  even by applying 1 W of power.

## Acknowledgements

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