

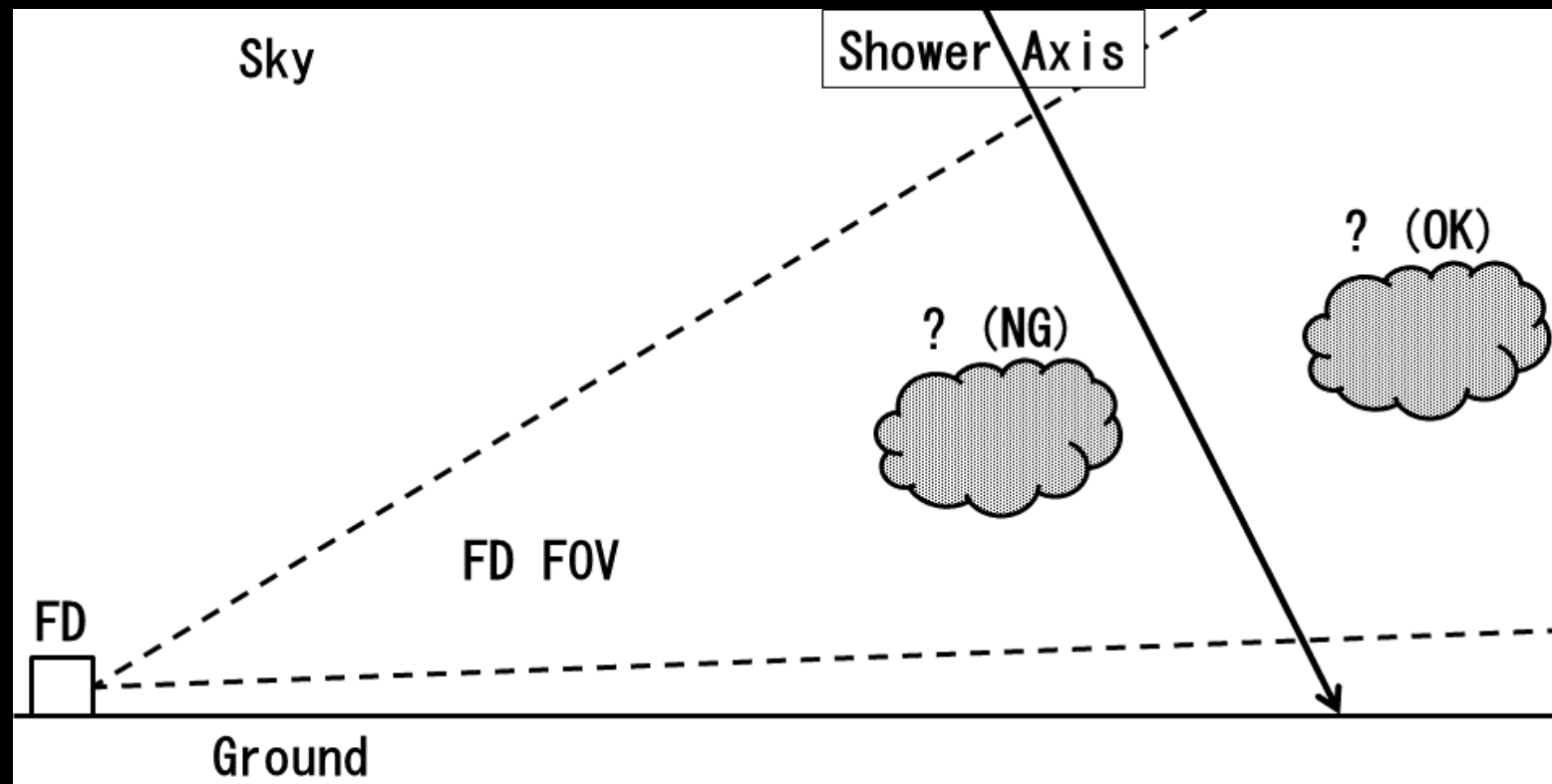
Passive measurement of distance to cloud

220715

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FD and cloud

The atmospheric Fluorescence telescopic Detector (FD) observes very far incident UHECR airshower to cover large area because of low statistics. The observation does not take place in overcast night. However, the cloud status changes quickly and sometimes there are some isolated clouds.



Method to measure distance to cloud

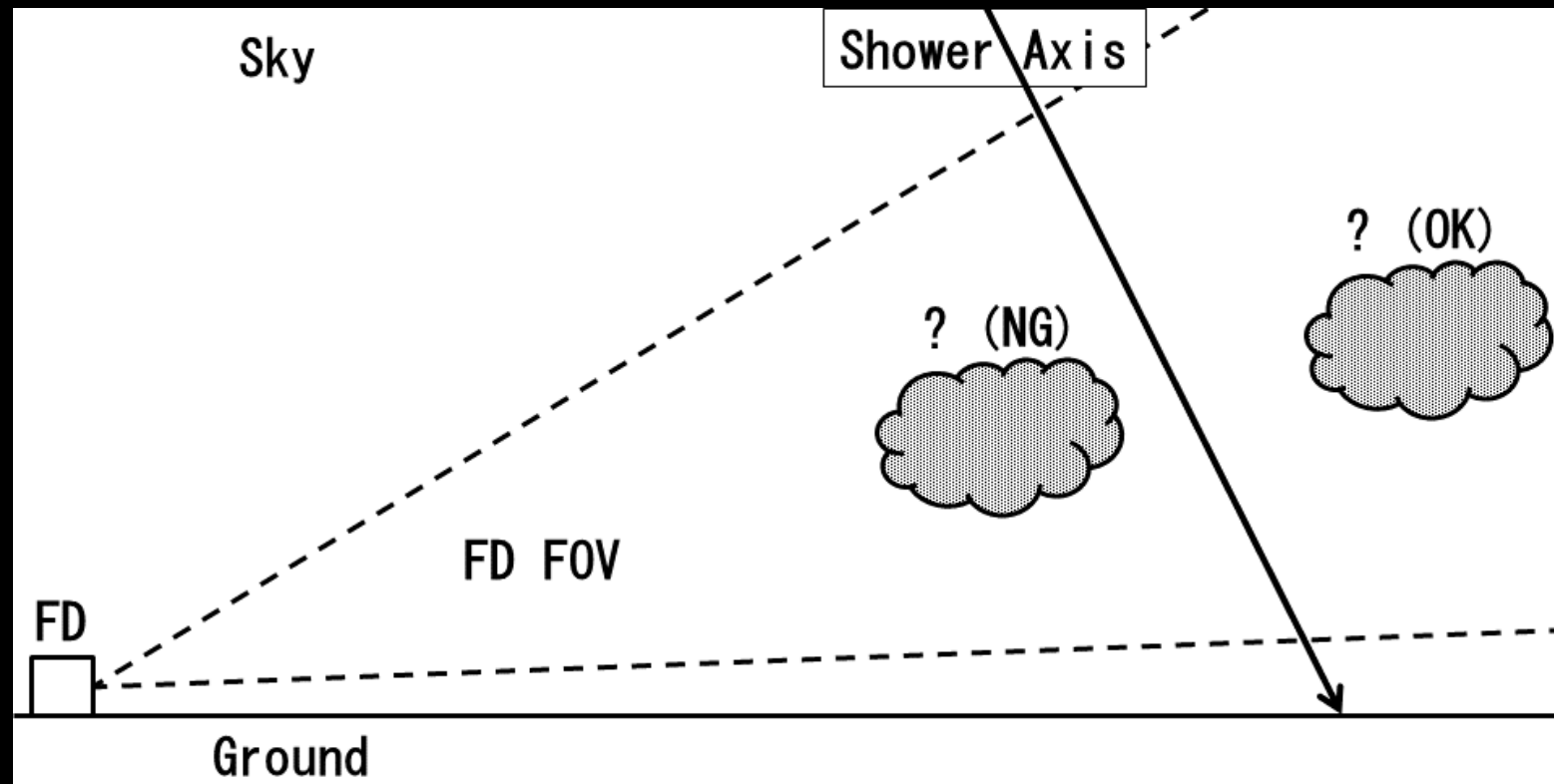
Radar is too expensive and large power consumption.

The lidar field of view is very narrow.

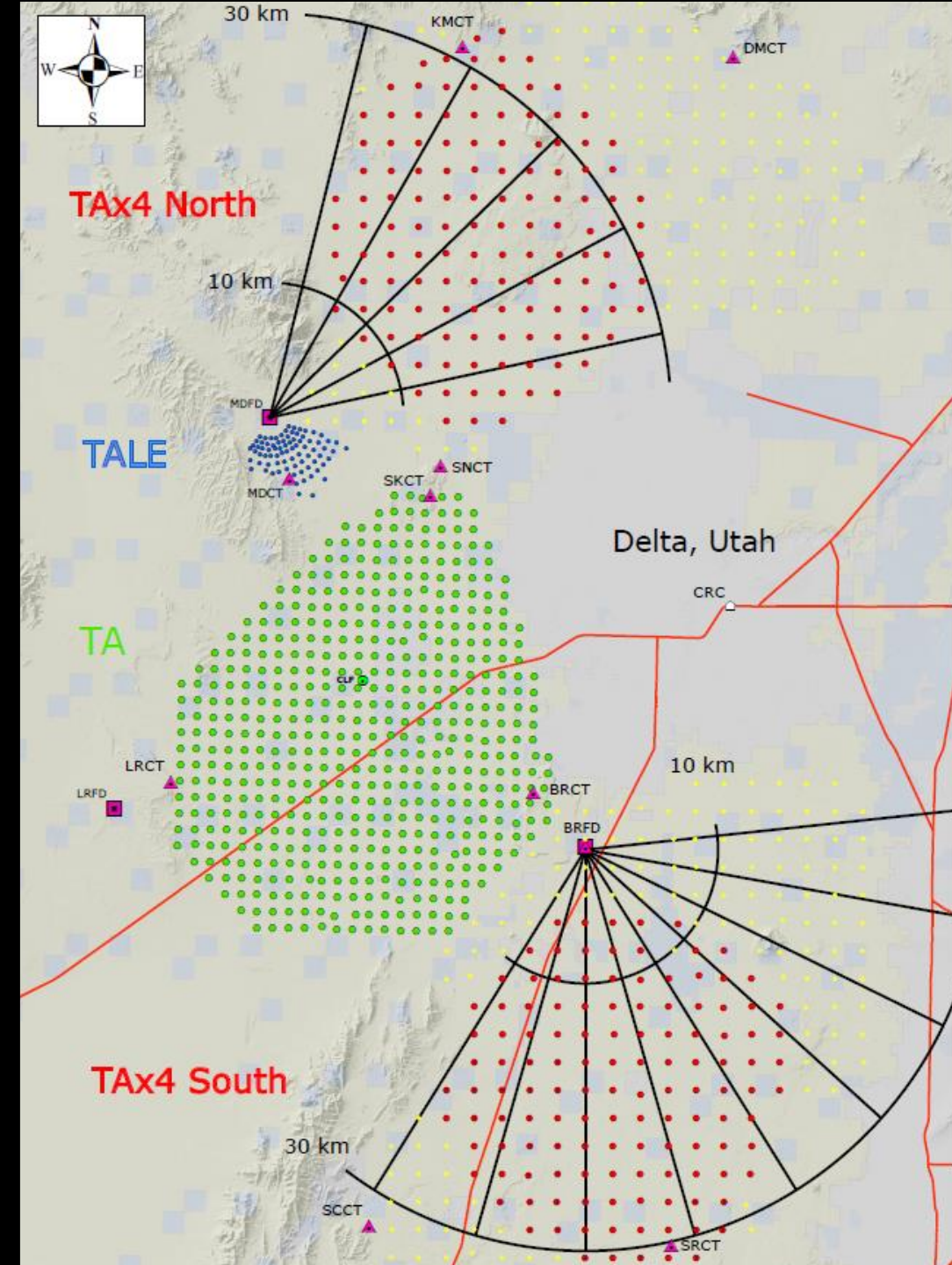
It cannot cover area whose cloud status changes quickly.

As passive method, Telescope Array Cloud Ranging Test(TACRT) has started to test the method for evaluating the correction of exposure.

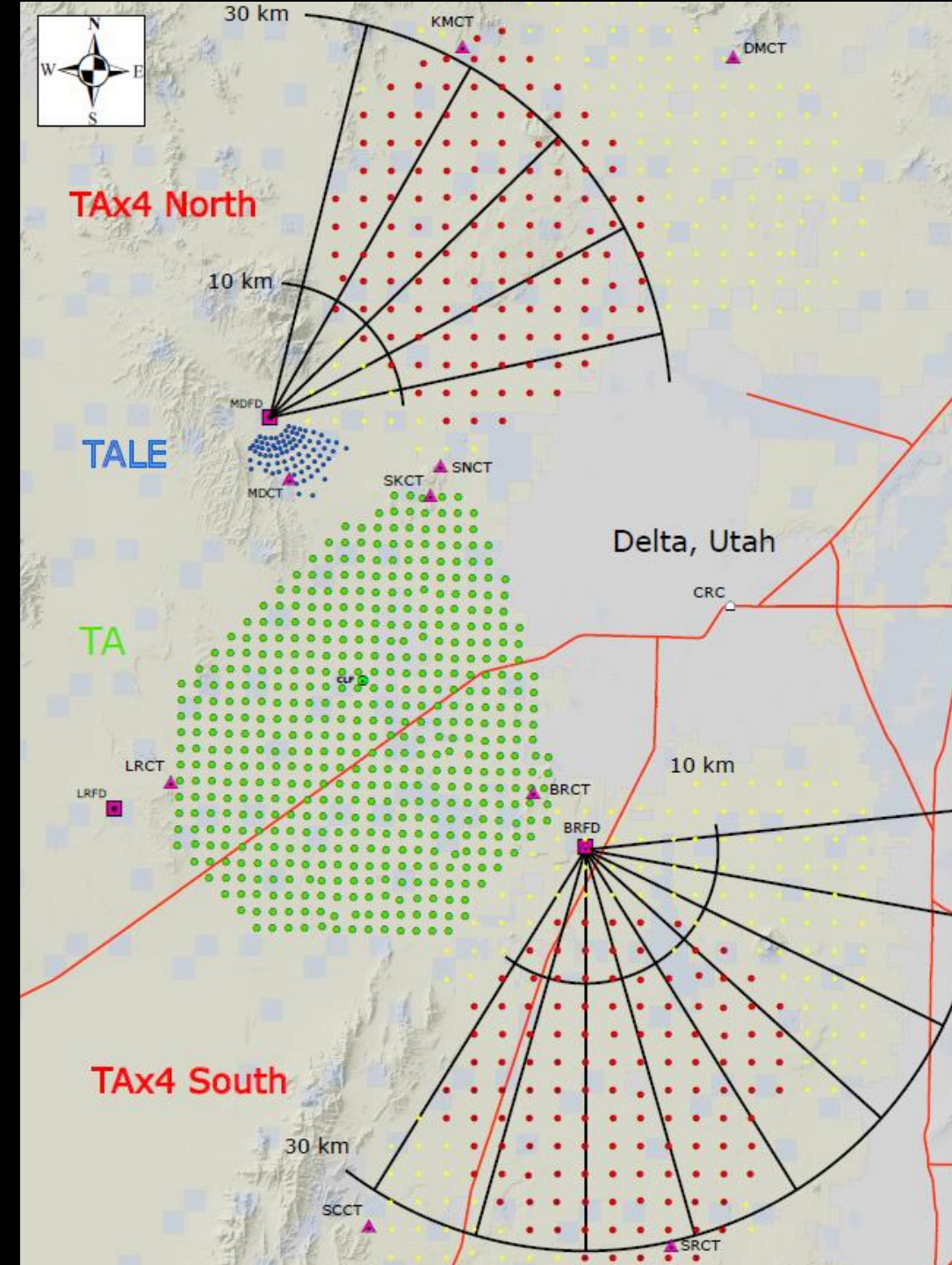
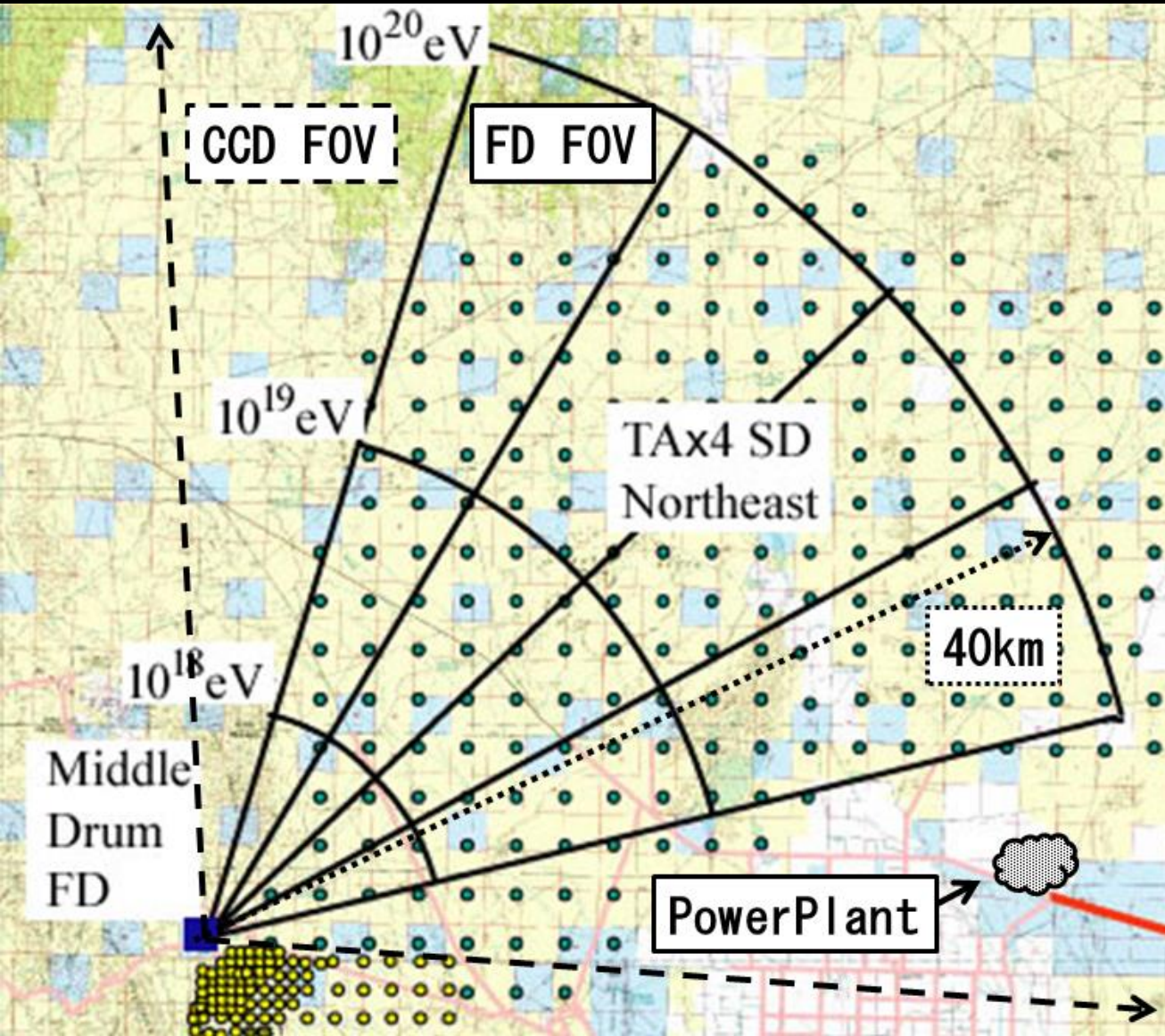
Stand alone stereo cloud cameras was installed near one of FD site.



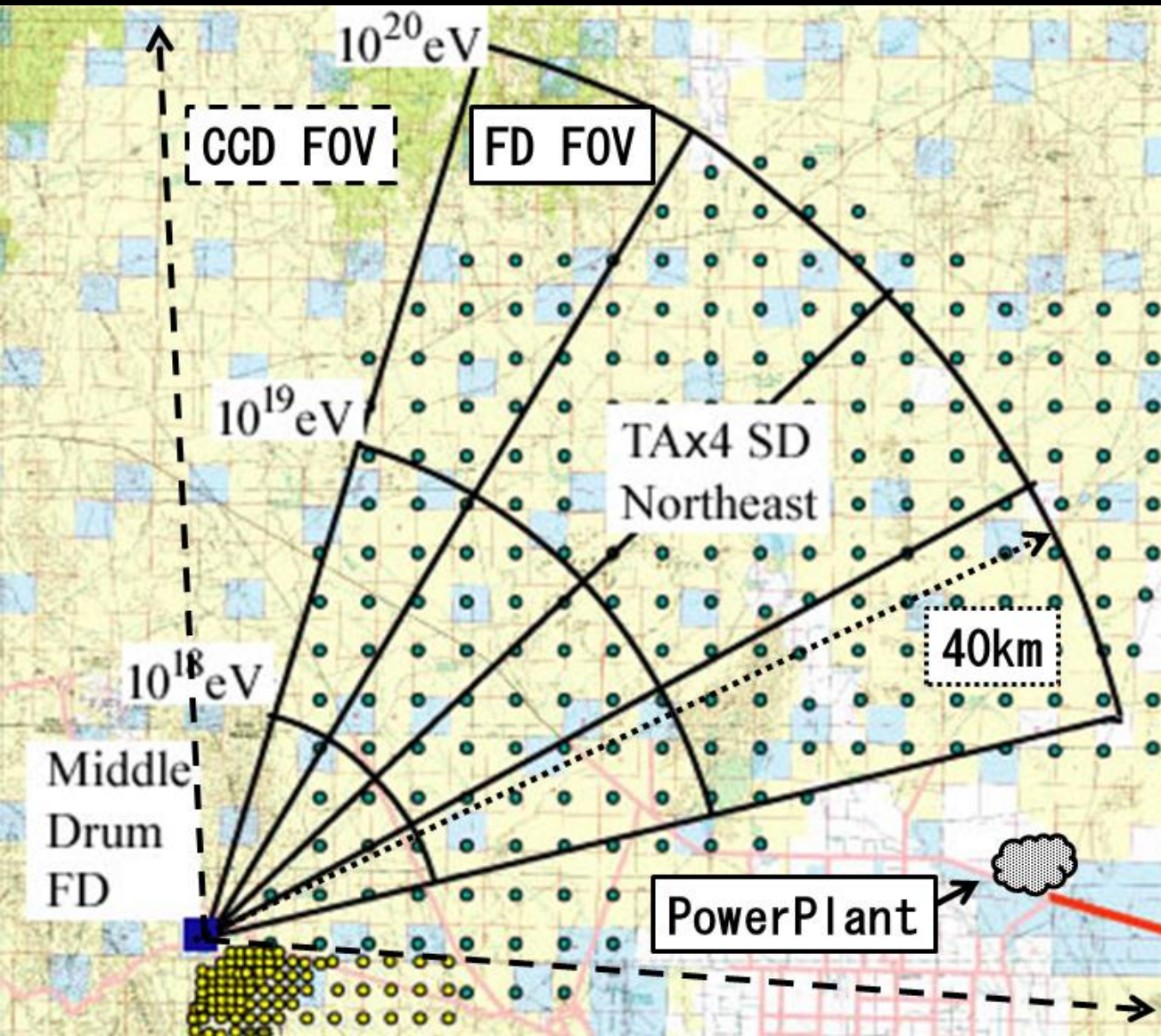
Telescope Array
(39.3° N, 112.9° W, altitude 1382 m)
extended TAx4 experiment from 2019.



Telescope Array (39.3° N, 112.9° W, altitude 1382 m) extended TAx4 experiment from 2019.



Telescope Array
(39.3° N, 112.9° W, altitude 1382 m)
extended TAx4 experiment from 2019.



Cloud at FD site is darker than sky.

Cloud (edge) distance can be evaluated by the visibility of the background star.

The field of view of camera is about 95° horizontally.

The camera has monochrome 8 bit 1024x768 pixels.

The horizontal resolution is roughly 0.1° per pixel.

Middle Drum
Observatory

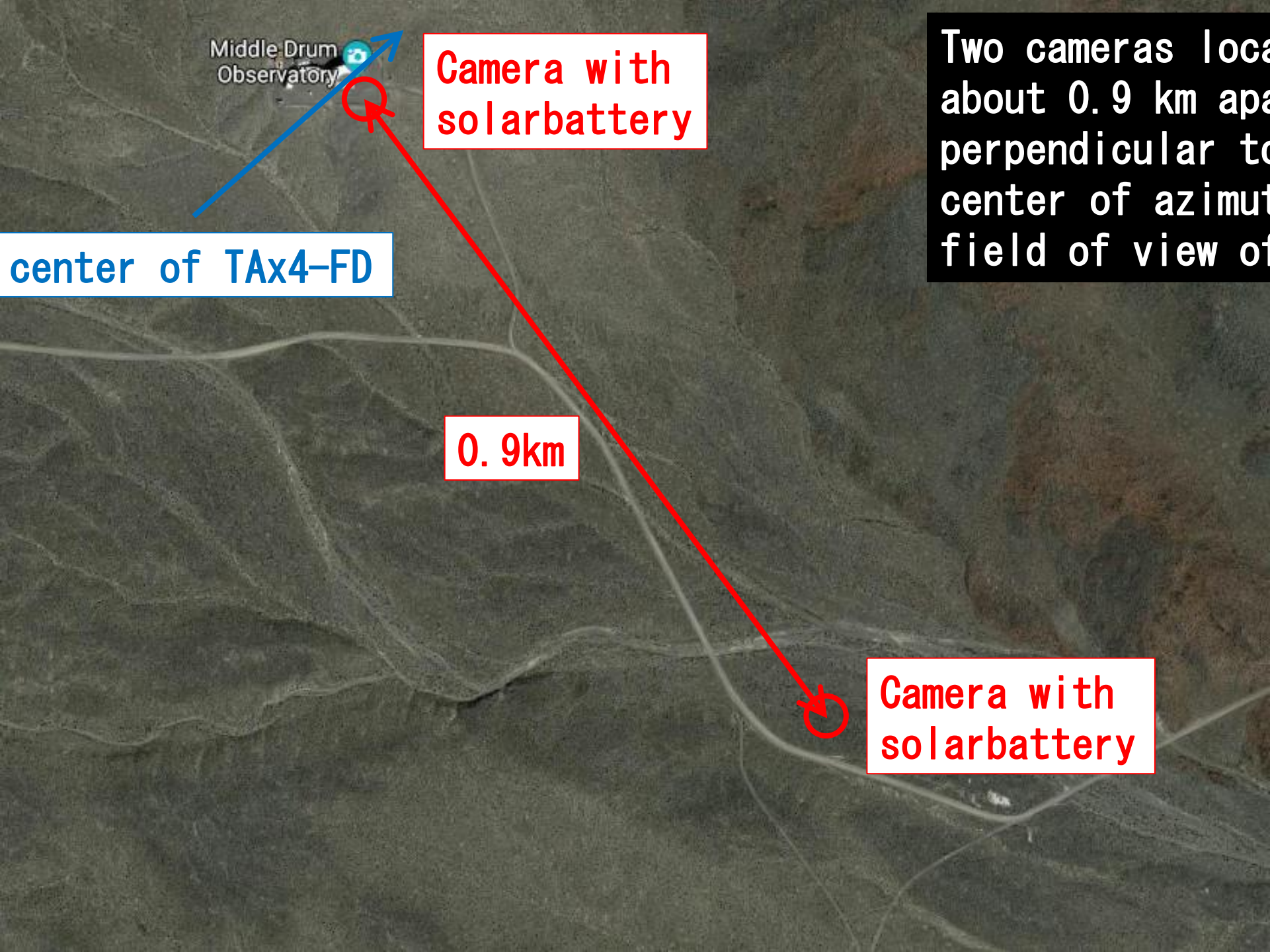
Camera with
solarbattery

Azimuth center of TAx4-FD

0.9km

Camera with
solarbattery

Two cameras located
about 0.9 km apart
perpendicular to the the
center of azimuth of
field of view of TAx4FD.





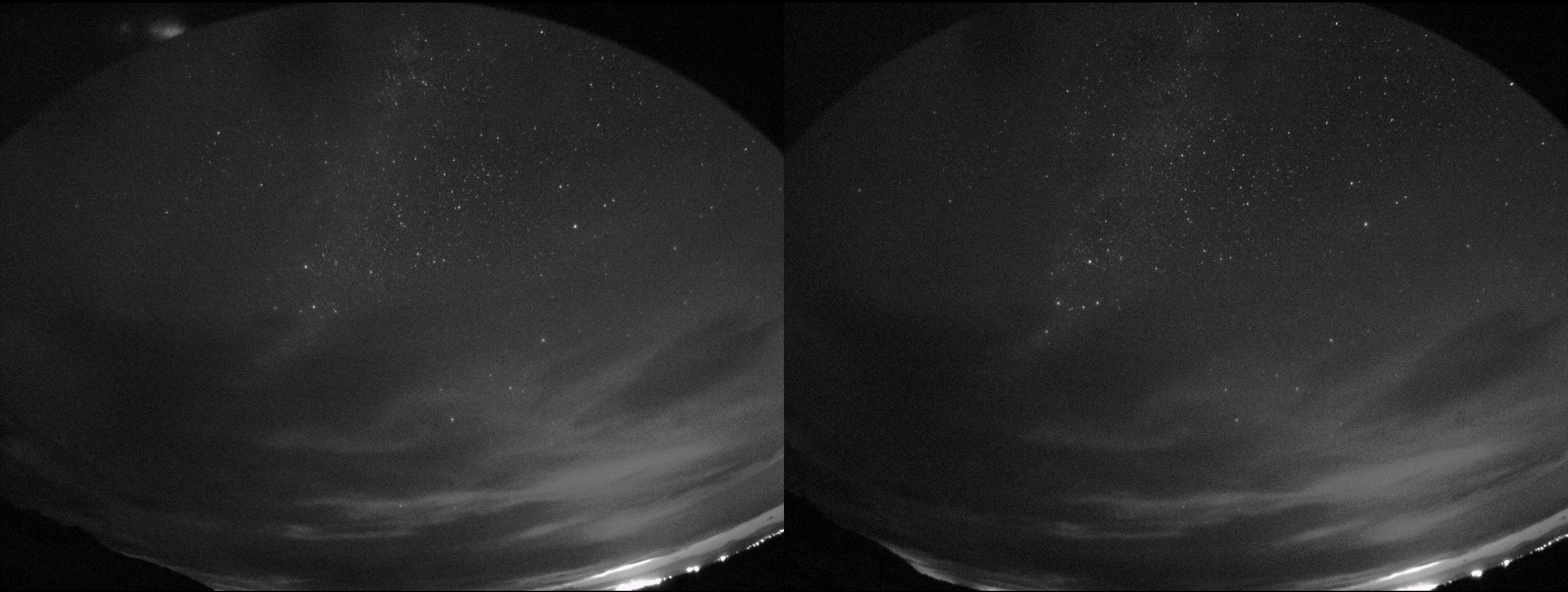
th
ery

Two cameras located
about 0.9 km apart
perpendicular to the the
center of azimuth of
field of view of TAx4FD.

This configuration
correspond to about 12
pixels shift on image for
40 km distance, which is
enough to test the method.



Test image just after stereo installation at moonrise



Simultaneous stereo image is acquired every 1 min.

Movie for pptx

Stereo image

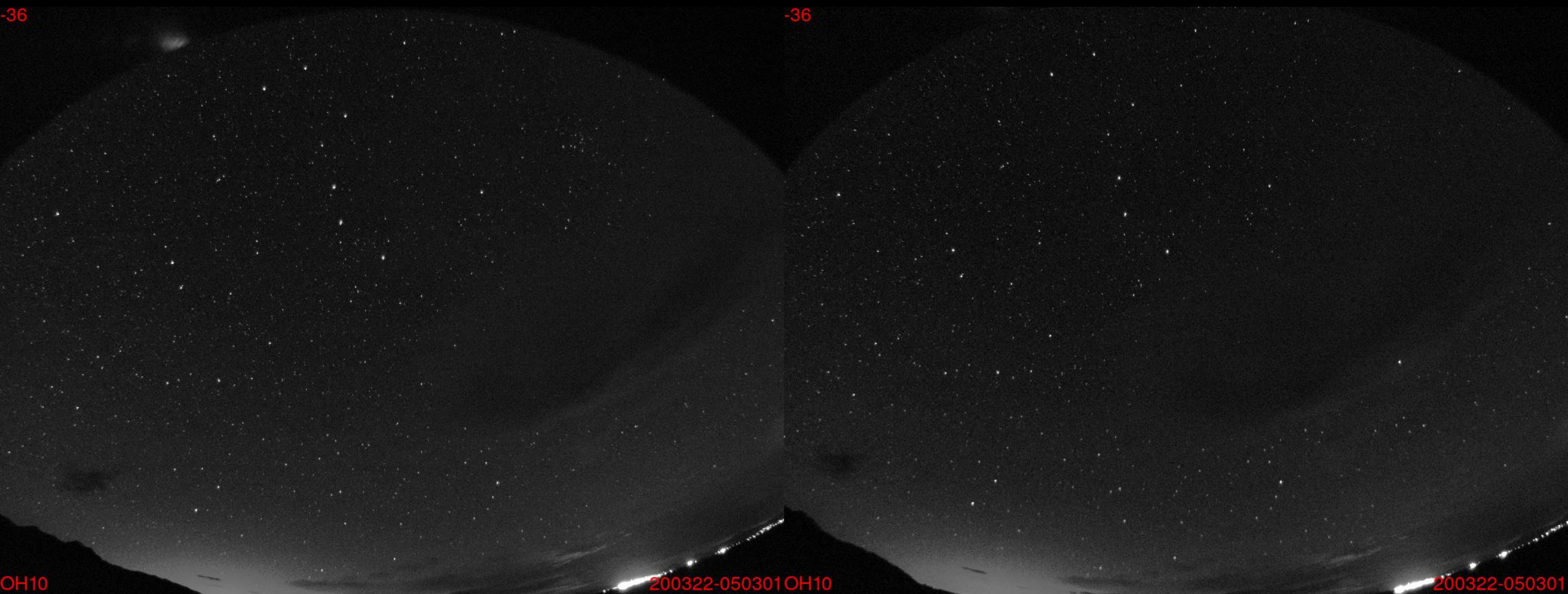
-36

-36

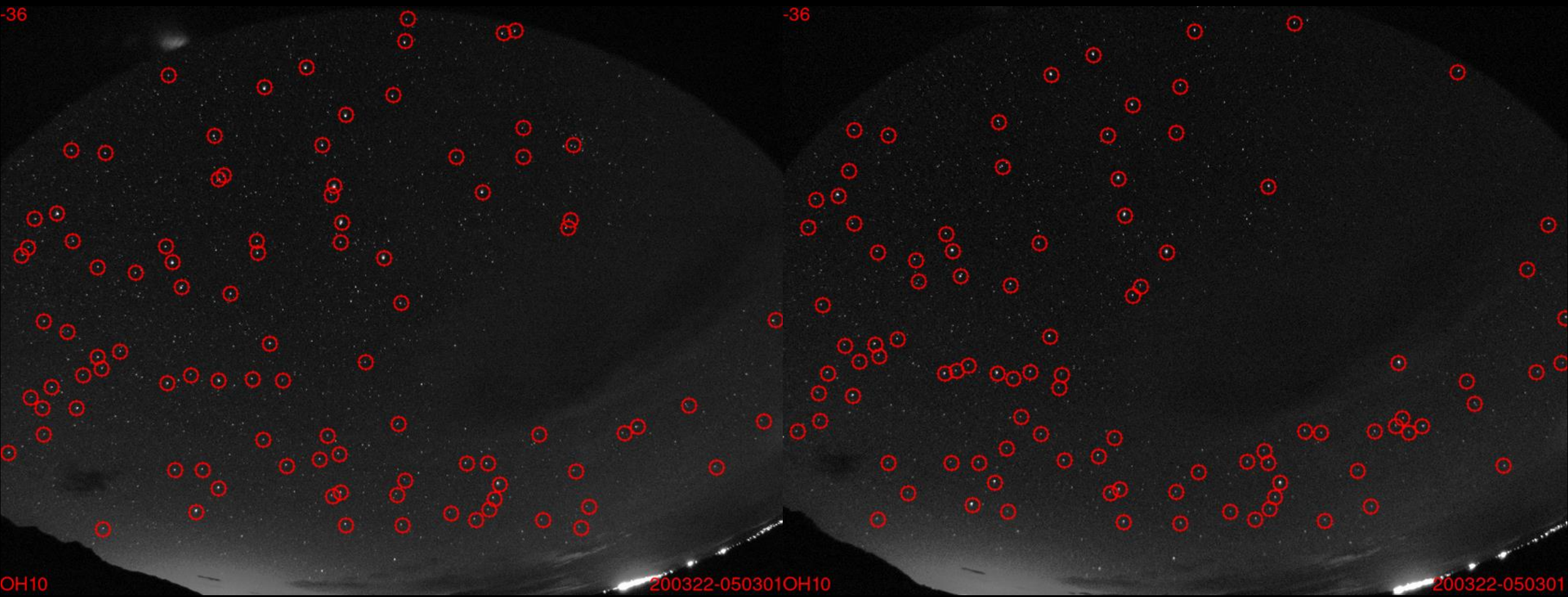
OH10

200322-050301 OH10

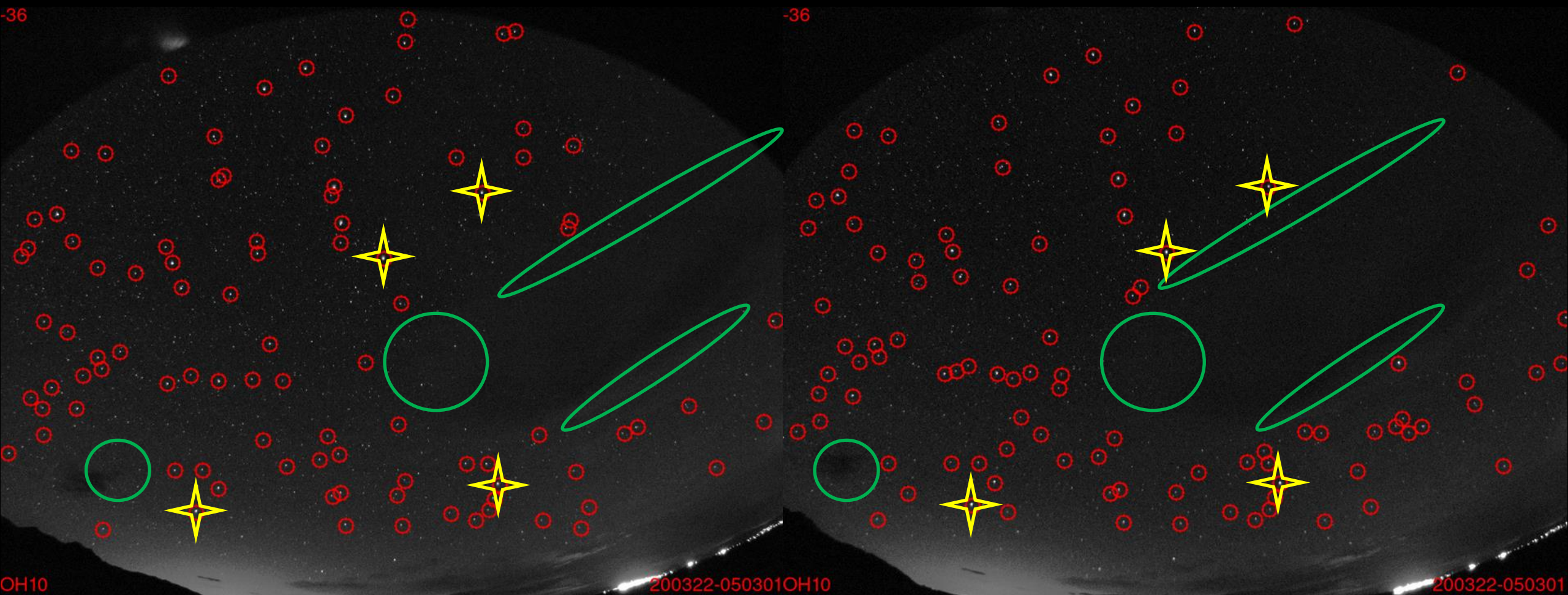
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Stereo image with coarse star detection



Stereo image with coarse star detection



Components of TACRT

Solar battery stand

Camera enclosure

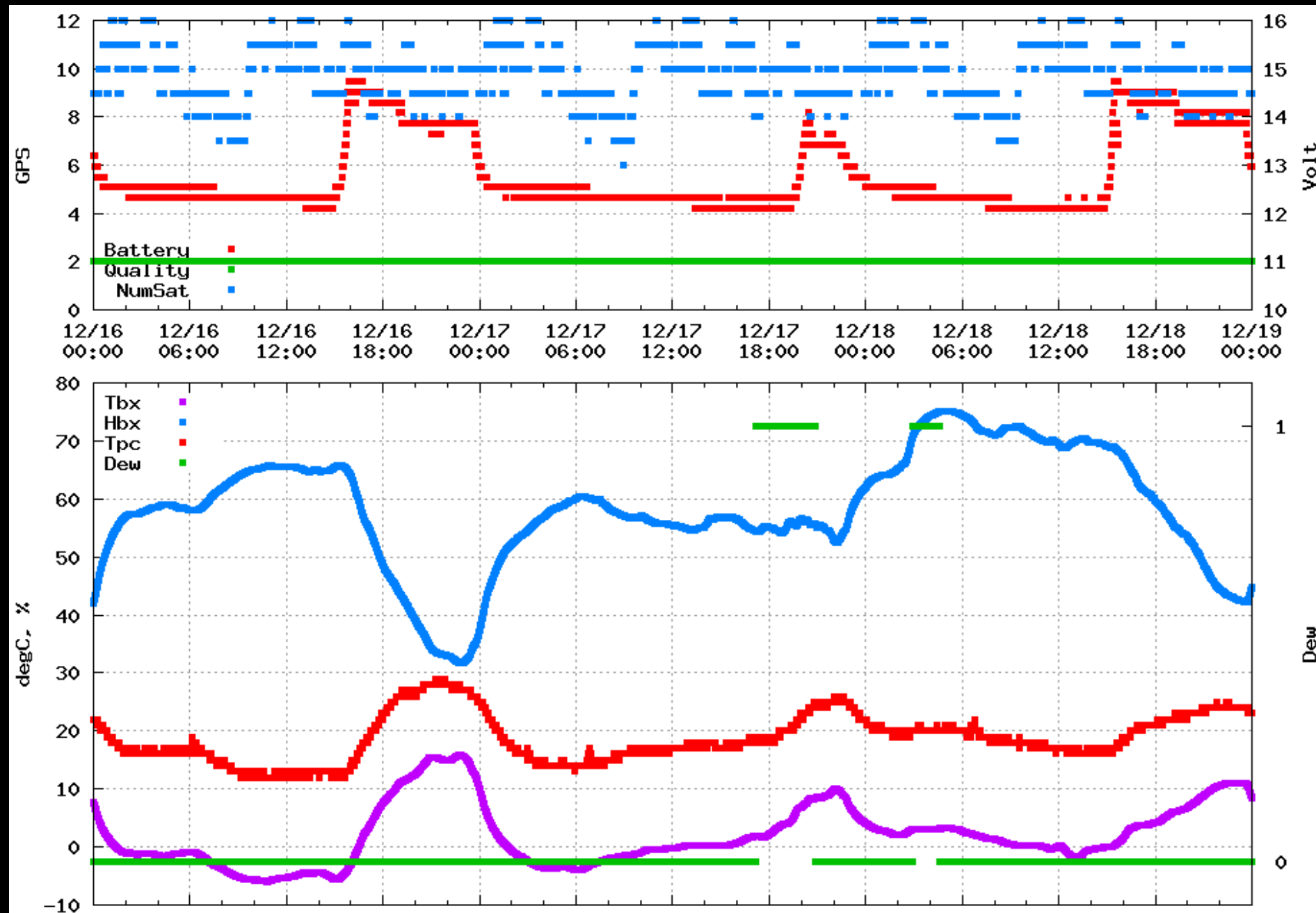
Relay for Iris
and Film Heater

WLAN module

GPS

Thermohydrometer

Dew sensor

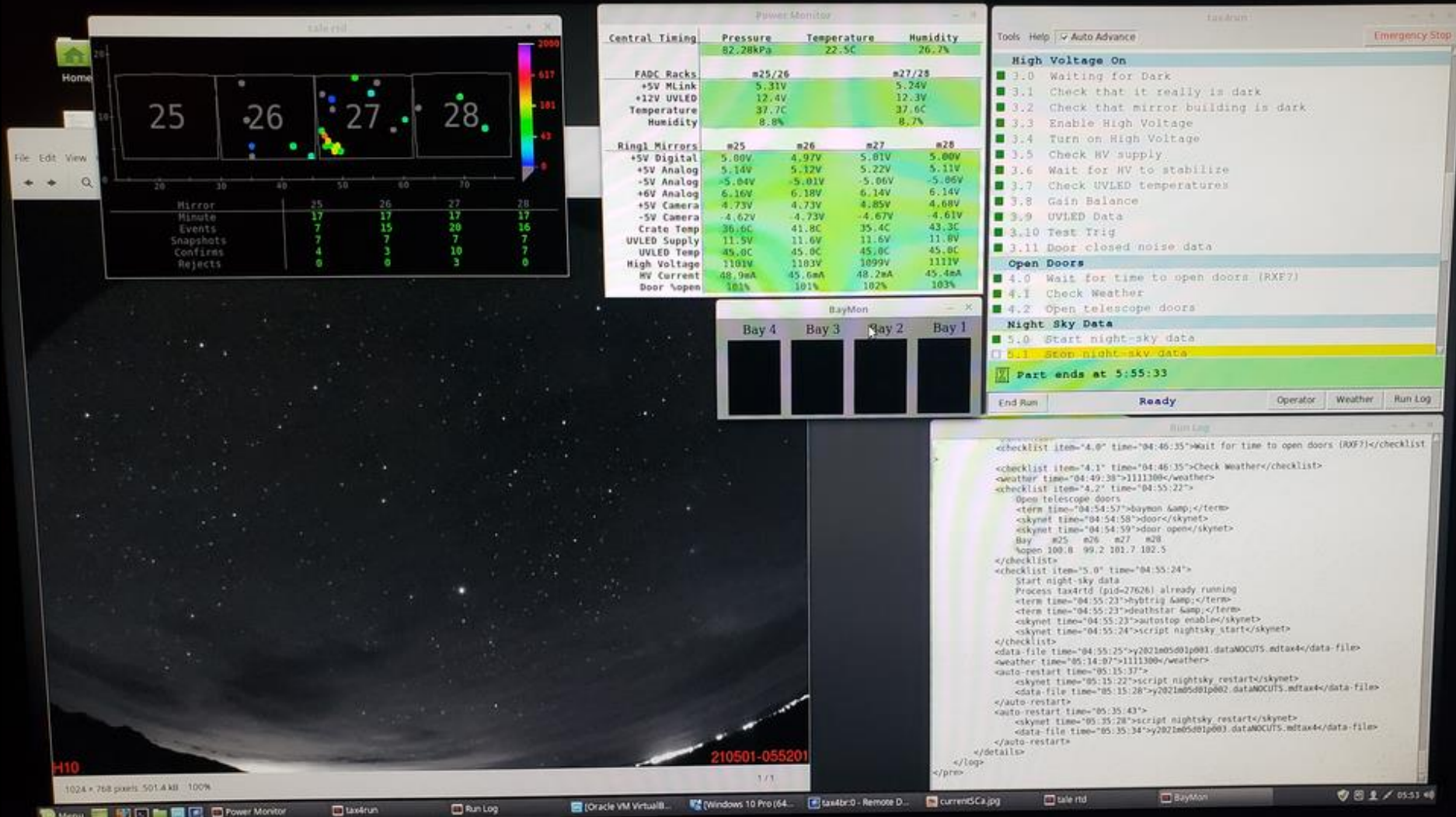


By-product for FD operation

The compressed sky image is transferred to WWW every 10 minute to check sky from anywhere online before FD observation.

In night time, sky image is transferred to TAx4FD PC every 1 minute to support FD observation.

As by-product, TACRT works to support quasi remote FD operation under pandemic.



Summary

TACRT is test of the method to measure cloud distance for evaluating the correction of FD exposure.

However, it also works to support quasi remote operation under pandemic.

The analysis of stereo image is on going.

Two CRT system observe cloud distance uniquely.

Therefore, uncertainty of cloud distance cannot be evaluated by this system.

If there is the third CRT, different pair of CRT supplies cross calibration.

The materials for the third CRT is already stored near observation site.

The third CRT will be installed in the future depending on various circumstances.

End