

Design and calculations of the 4π -Continuous-Mode Target current leads

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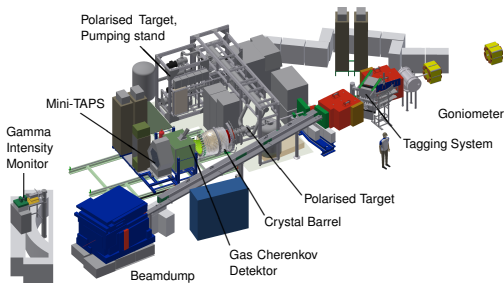


1 Motivation

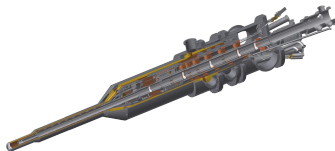
2 Design of the current leads

3 CFD-simulation

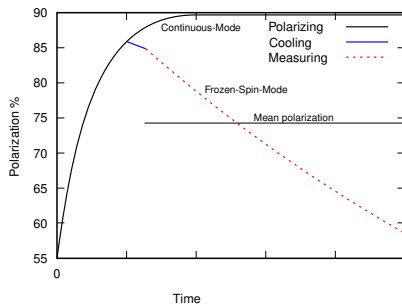
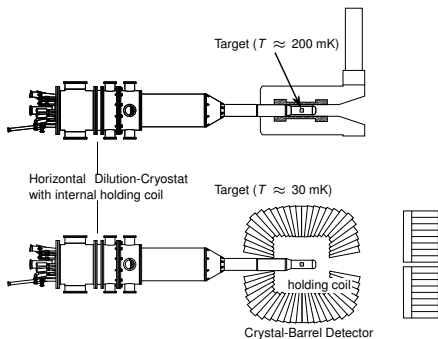
4 Summary and Outlook



Dilution refrigerator



- ▶ Observation of excitation spectra of baryons with double-polarisation observables
- ▶ Cryogenic temperatures, high magnetic field, microwaves are needed for Dynamic Nucleon Polarisation (DNP)
- ▶ Polarized Target Bonn: Frozen-Spin-Technique

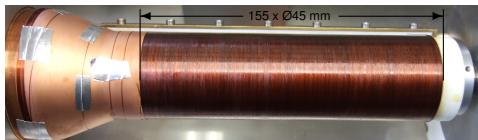


- ▶ **Frozen-Spin-Target:** External magnet (2.5 T), internal holding coil (0.6 T)
- ▶ **Advantage:** Large angular acceptance, 4π -Detector
- ▶ **Disadvantage:** Continuous loss of polarization during data taking, interruption of the experiment, complex handling, low particle flow (4 nA)

4π -Continuous-Mode Target

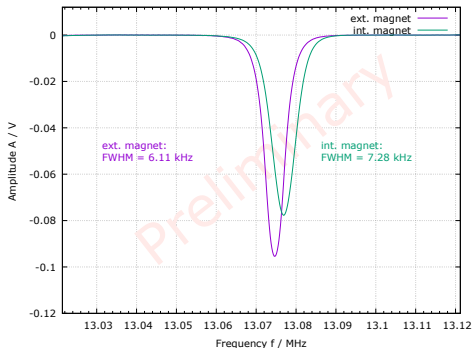
Combines the advantages of high polarisation and the large angular acceptance

Key element: Internal magnet with the same magnetic properties as the external magnet



- ▶ As thin as possible
→ Overall thickness ≤ 2 mm
→ Passively cooled
- ▶ Internal magnet with $B_0 = 2.5$ T @ 90 A @ 1 K
- ▶ $\frac{\Delta B}{B_0} \ll 10^{-4}$ @ 1/40 V_{overall}
- ▶ Building process by wet wiring (with epoxy)
- ▶ Precondition: Homogeneous (orthocyclic) wire pattern!

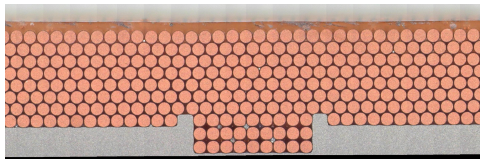
Tests in ^4He Kryostat: 6LiD at 1 K



- ▶ A proton and a deuteron target could be dynamically polarized with an internal magnet

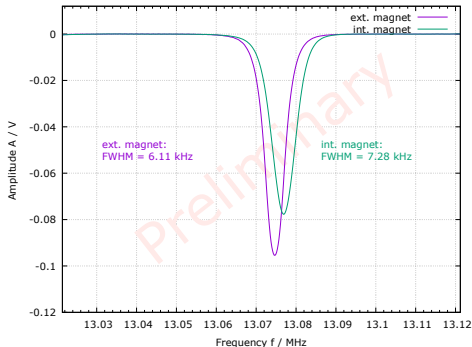
For operating an internal magnet

Two (electrical) **stable and low heat generating current leads** are necessary



- ▶ As thin as possible
 - Overall thickness ≤ 2 mm
 - Passively cooled
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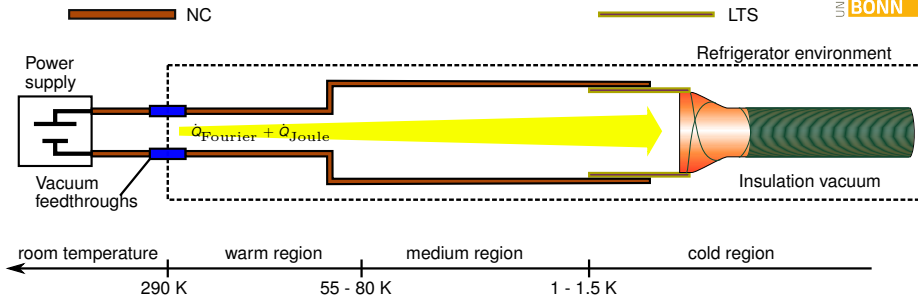


- ▶ A proton and a deuteron target could be dynamically polarized with an internal magnet

For operating an internal magnet

Two (electrical) **stable and low heat generating current leads** are necessary

Stable and low heat generating current leads: Hybrid type



Problems with normal conducting (NC) current leads:

- ▶ Large heat load on the cold region due to Fourier's law
- ▶ Additional heat load due to Joule heating when energising the magnet
- ▶ Cooling of magnet and current leads only by conduction
- ▶ Large heat load can lead to a quench of the low temperature superconductor (LTS) / magnet
- ▶ There exist a minimum heat flow with $\dot{Q}_{\text{Fourier}} = 0$

$$\dot{Q}_{\text{Fourier}} = -kA \frac{dT}{dl}$$

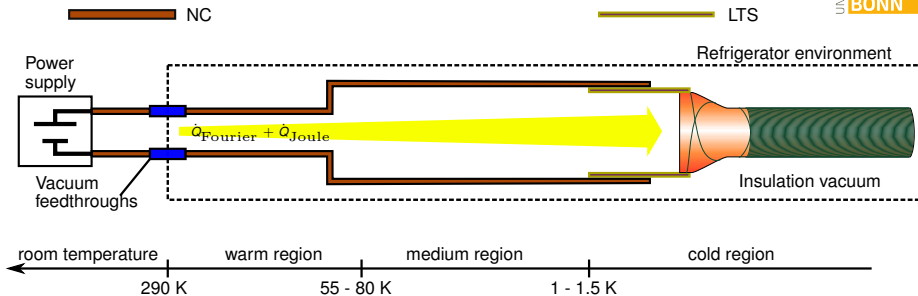
$$\dot{Q}_{\text{Joule}} = \frac{\rho^2}{A} \sigma l$$

A: Cross section area
 I: Current
 k: Thermal conductivity
 σ : Electrical conductivity
 l: Length of the current lead
 T_h : Temperature at the hot end
 T_c : Temperature at the cold end

$$\dot{Q}_{c,\min} = I \left[2 \int_{T_c}^{T_h} k(T) \sigma(T) dT \right]^{\frac{1}{2}}$$

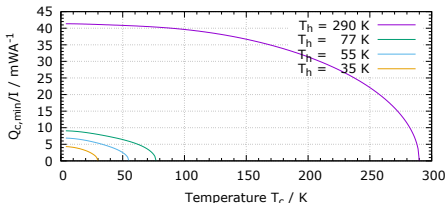
R. McFee, "Optimum Input Leads for Cryogenic Apparatus, Rev. Sci. Instrum. Vol. 30, American Institute of Physics, 1959

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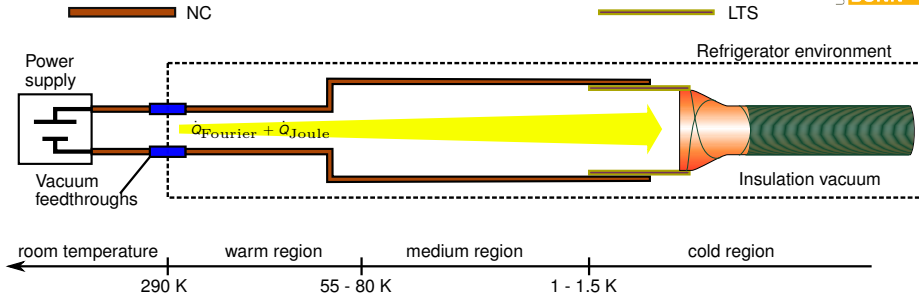
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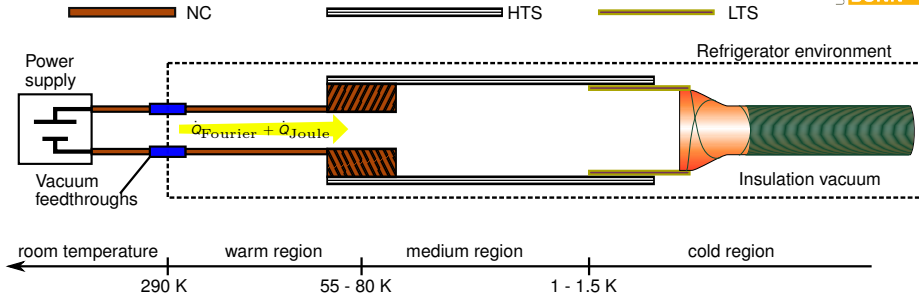
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Solution for the cold region:

- ▶ Thermal decoupling between warm and cold region/LTS
- ▶ Can be archived by using a high temperature superconductor (HTS, here: BSCCO)
- ▶ But nonetheless: Heat load must be minimised up to the NC-HTS junction for not quenching the HTS

Stable and low heat generating current leads: Hybrid type



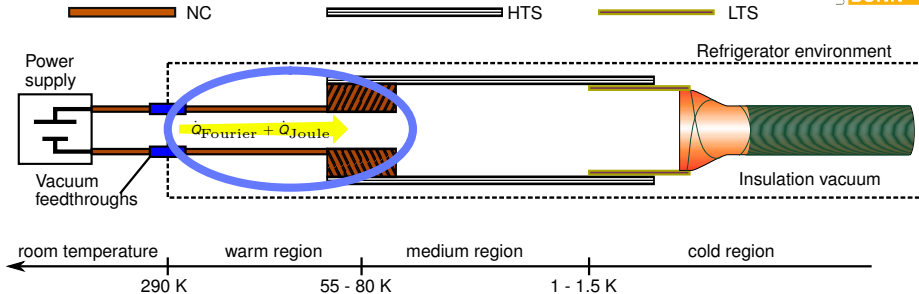
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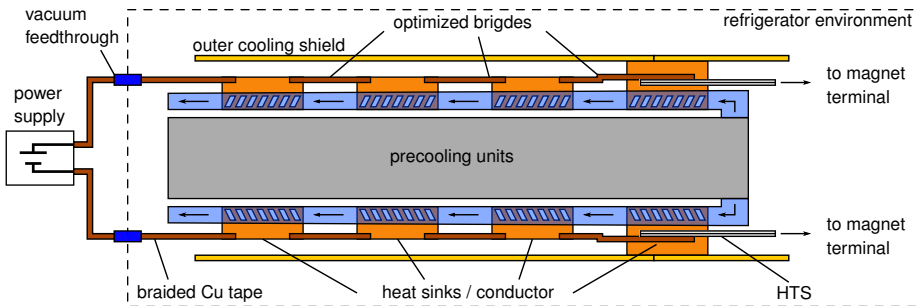
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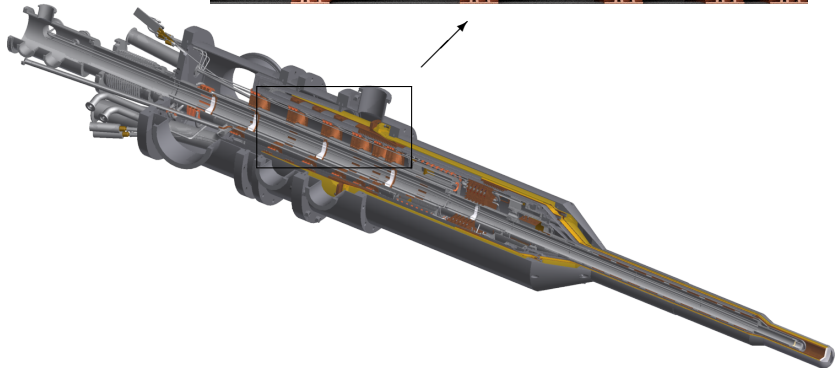
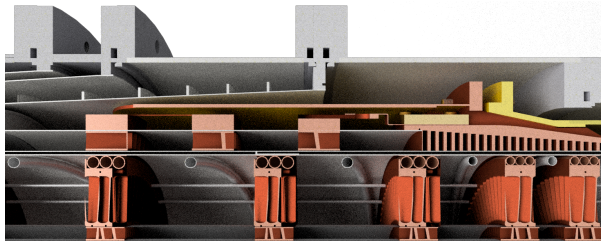
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Block scheme for minimum heat load on NC-HTS junction

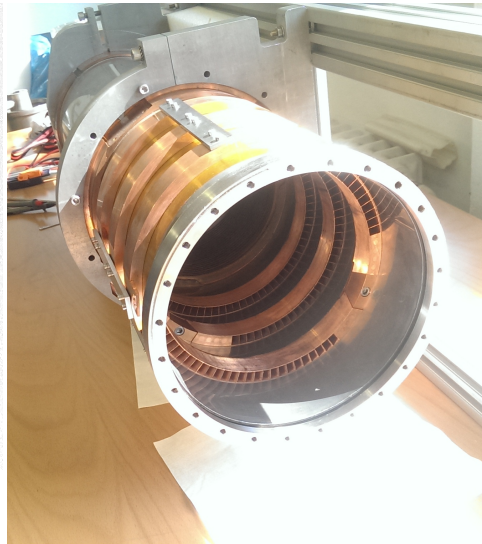
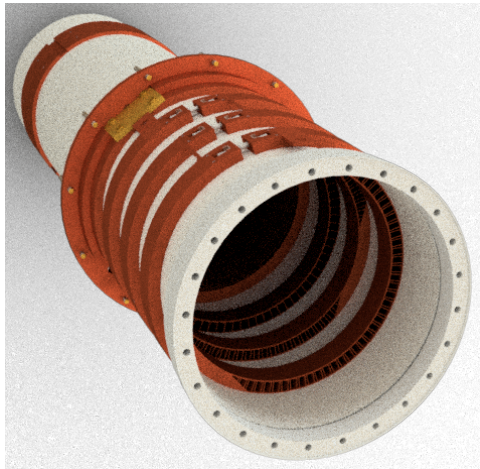


- ▶ Braided flexible copper tape ($A = 25 \text{ mm}^2$, $L = 1.4 \text{ m}$)
- ▶ 3 (turbine) heat sinks / copper-(half) rings for each terminal ($A = 260 \text{ mm}^2$)
- ▶ Ring-conductorss are connected by bridges ($A = 1.5 \text{ mm}^2$, $L = 4 \text{ cm}$)
- ▶ Bridges are designed for minimising thermal conduction from one sink to the next when energised
- ▶ Thermal decoupling between the heat sinks (McFee)

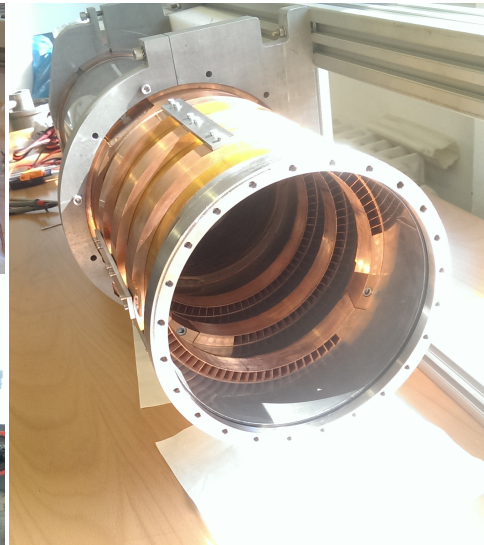
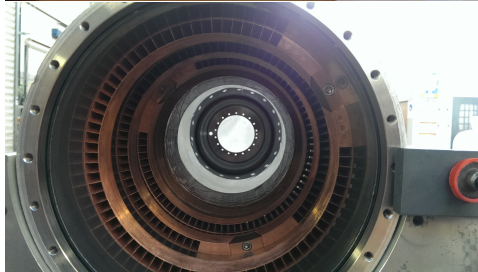
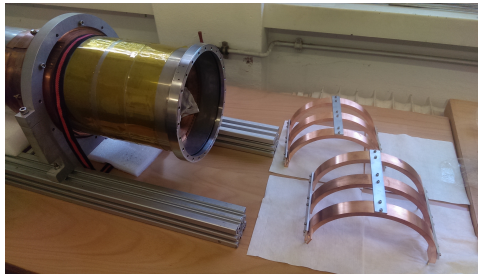
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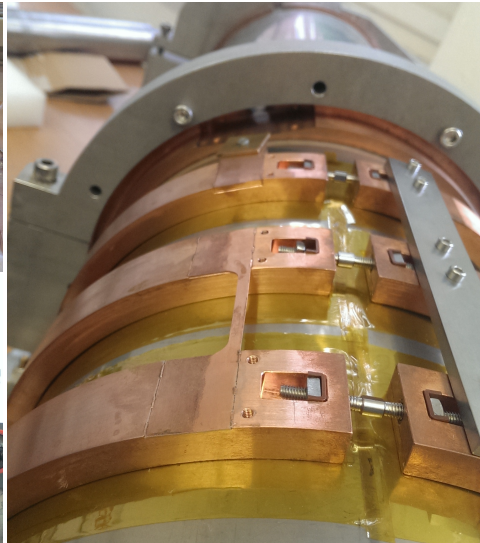
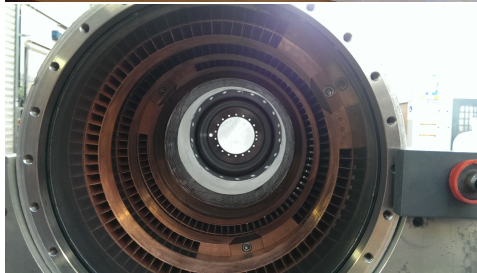
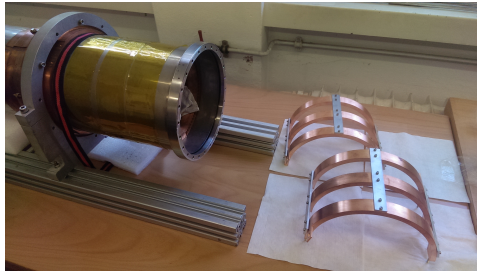
Current leads concept- Impressions



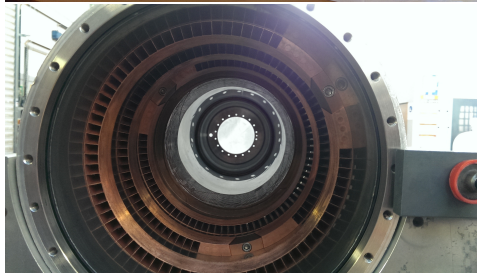
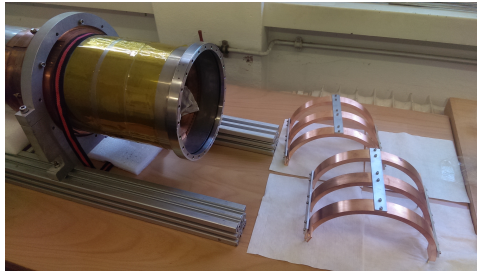
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Current leads concept- Impressions



Idea

- ▶ Compare and optimize different bridge geometries
- ▶ Detailed information about the temperatures over the full length of a current lead and the heat sinks
- ▶ OpenFoam was successfully used for calculating the precooling stages of the refrigerator

But:

- ▶ There does not exist any solver for calculate electric currents (has to be added)
- ▶ An explicit heat source has to be added to the heat diffusion solver
- ▶ Temperature dependency of σ and k has to be implemented since stock tools are not sufficient

Governing equations: Solid part

Stat. heat diffusion equation: $\nabla(k\nabla T) + \dot{q} = 0$

Joule's first law: $\dot{q} = \int_V \frac{1}{\sigma} \mathbf{J}^2 dV$

Ohm's law: $\mathbf{J} = -\sigma \nabla \Phi$

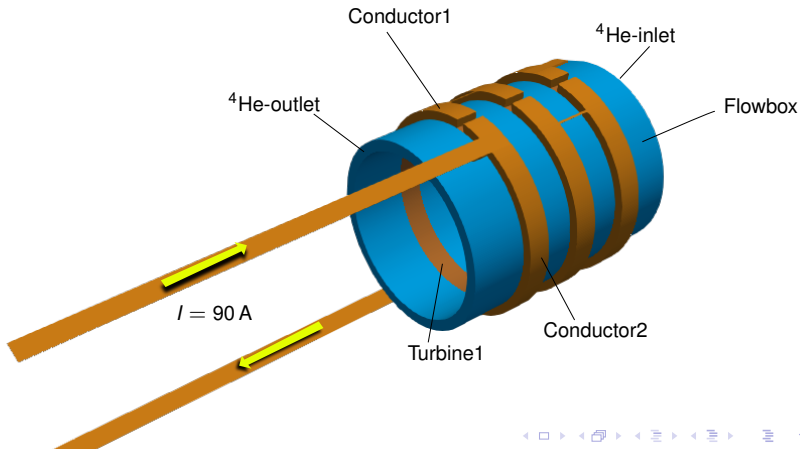
resp. $0 = \nabla(-\sigma \nabla \Phi)$

k	Thermal conductivity
σ	Electric conductivity
\dot{q}	Heat power density
\mathbf{J}	Current density
Φ	Electric potential field
V	Volume

Governing equations: Fluid part → Talk Stefan Runkel

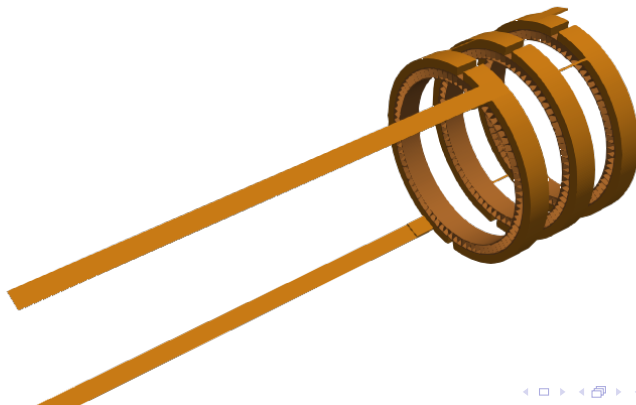
Boundary conditions

- ▶ Inlet: Gas-Temperature 40 K
- ▶ Flow: 13 mmol s^{-1}
- ▶ Outlet-Pressure 50 mbar
- ▶ Current: 90 A



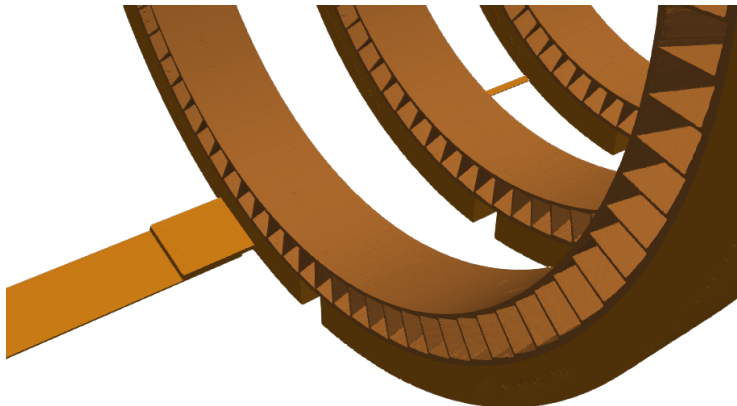
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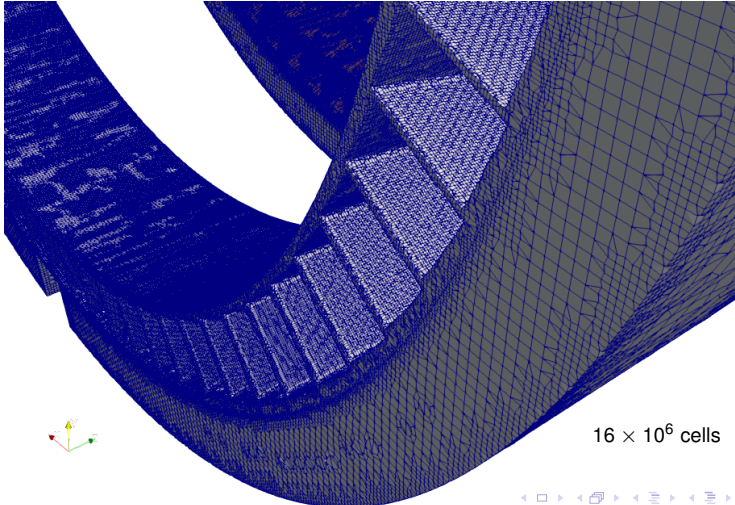
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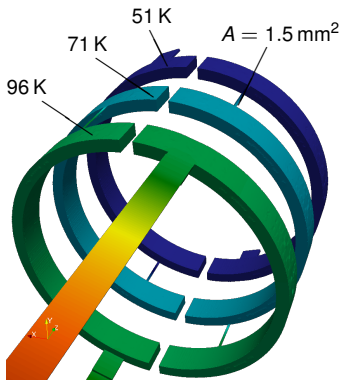


Results - Temperature distribution

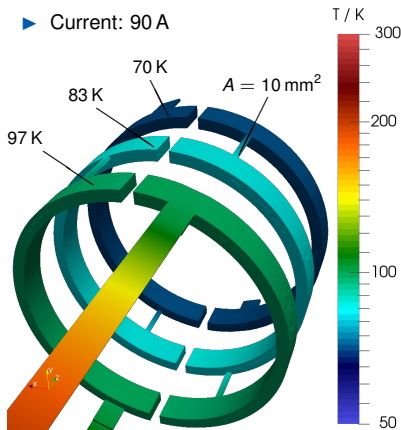
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- ▶ Joule heating: $2 \times 4.15 \text{ W}$
(consistent with McFee)



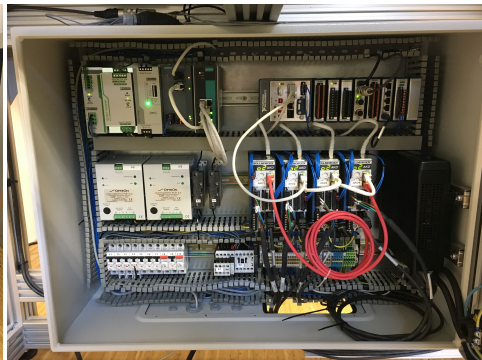
- ▶ Joule heating: $2 \times 3 \text{ W}$

Result: Lower end temperatures by thermal decoupling of each sink with optimised bridges

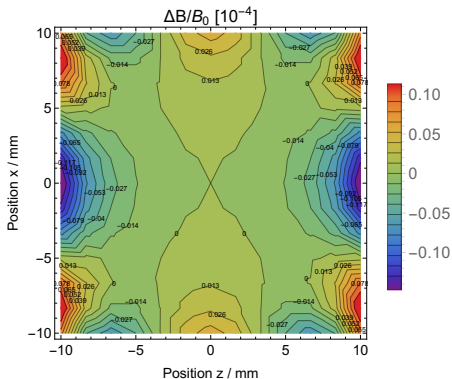
- ▶ Motivation for development: 4π -Continuous-Mode-Target with the "Inverse Notched Coil" as a key part
- ▶ Two stable and low heat generating current leads are necessary for operating a high current magnet within a refrigerator
- ▶ CFD-simulation as an optimizing tool for the normal conducting part of the leads
- ▶ Result of CFD-simulation: Lower end temperatures by thermal decoupling of each sink with optimised bridges

- ▶ Mounting and take measurements to validate the calculations
- ▶ If validated, Openfoam can be used to simulate gas-cooled current leads for certain geometries

- ▶ FPGA-based controller for high precision (absolute positioning $10\ \mu\text{m}$)
- ▶ Possible magnet length $1\ \text{m} \times \text{Ø}20\ \text{cm}$ (Scaling internal magnets/ tracking magnet)
- ▶ Option for building transversal (shrunk coils) / saddle coils



Construction of an improved version (prototype 3)



d_{eff}	0.265	mm
length	176.225	mm
radius	23.3	mm
Correcton width	9	d_{eff}
Correction position	105 to 116	d_{eff}
Current	70	A
Center field B_0	2.574	T
Homogeneity $ \Delta B/B_0 $	1.5×10^{-5}	

$$JL = \frac{1}{\sqrt{2}} \int_{T_c}^{T_h} \frac{k(T) dT'}{\left[\int_{T'}^{T_h} k(T) \rho(T) dT \right]^{1/2}}$$

