

# Component separation for the Simons Observatory Large Aperture Telescope

Benjamin Beringue

- on behalf of the Simons Observatory foreground working group -

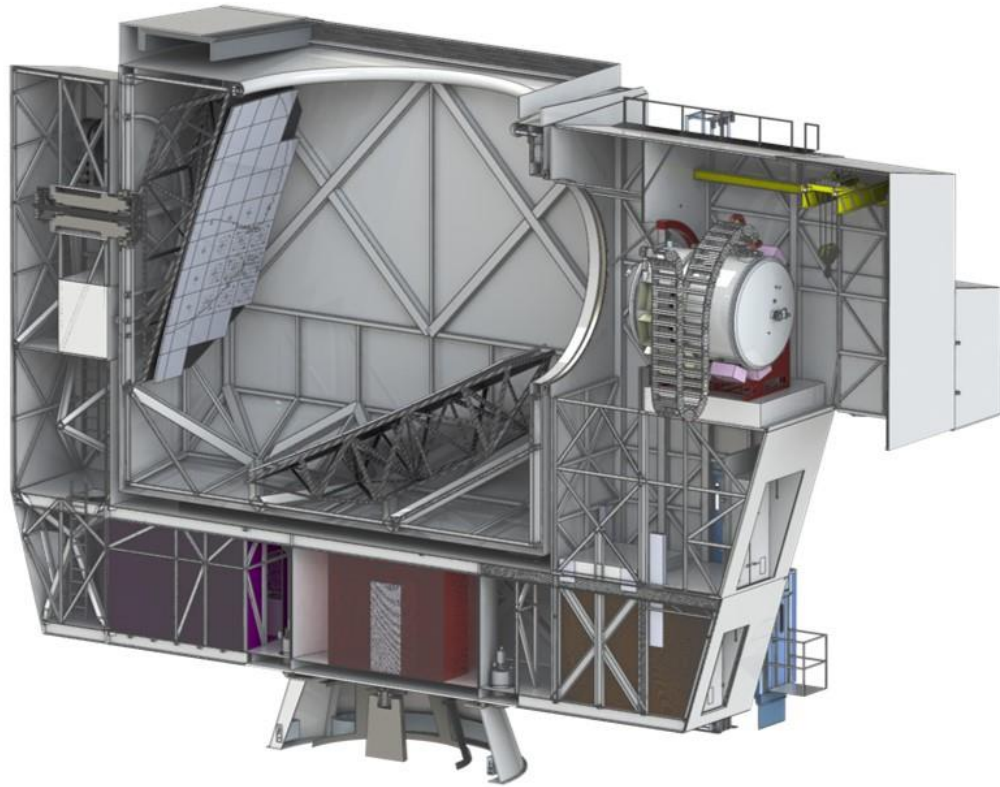
## Outline:

- ⚙️ Component separation for the Simons Observatory Large Aperture Telescope
- ⚙️ Semi-parametric component separation with `sps4lat`
- ⚙️ First tests on realistic map-based simulations
- ⚙️ Remaining challenges

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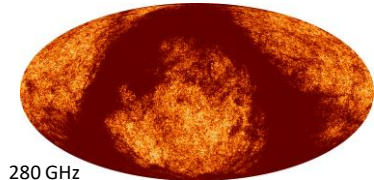
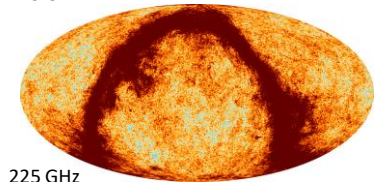
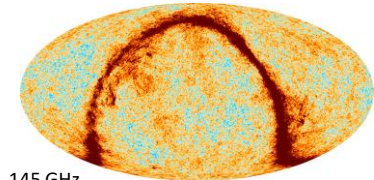
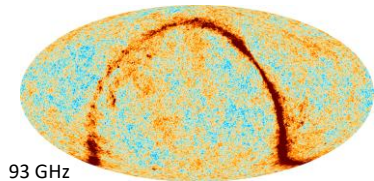
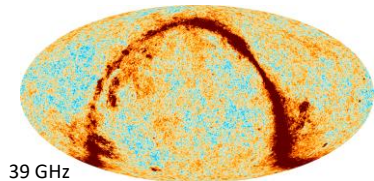
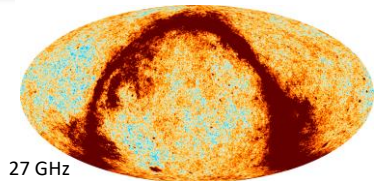
# Simons Observatory (SO)



- ⚙ Currently under construction/deployment
- ⚙ 40+ institutions, 300+ members
- ⚙ 3 Small Aperture Telescopes targeting *B-modes*
- ⚙ 1 Large Aperture Telescope (LAT) :
  - 6m cross-dragone telescope
  - > 30,000 TES detectors
  - 6 frequency channels (27, 39, 93, 145, 225, 280 GHz)
  - Variety of science cases:  $N_{\text{eff}}$ ,  $\Sigma m_\nu$ ,  $\sigma_8$ ,  $H_0$ ,  $f_{\text{NL}}$ , ...



# Component separation

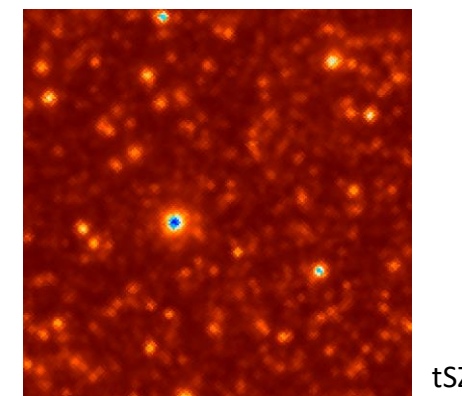
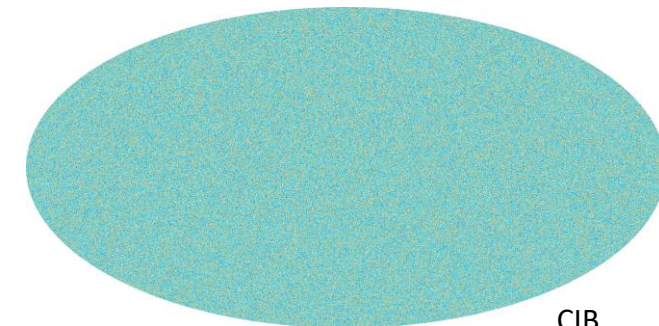
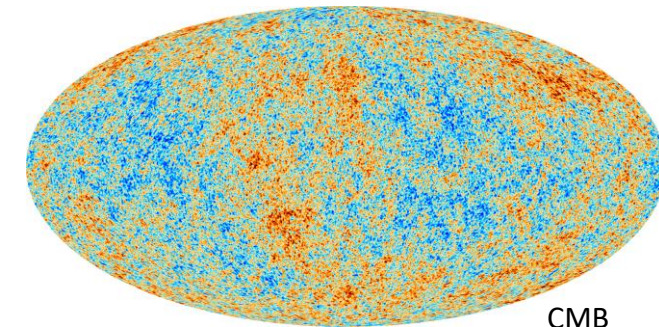


Component separation amounts to isolate the signals with different astrophysical origins.

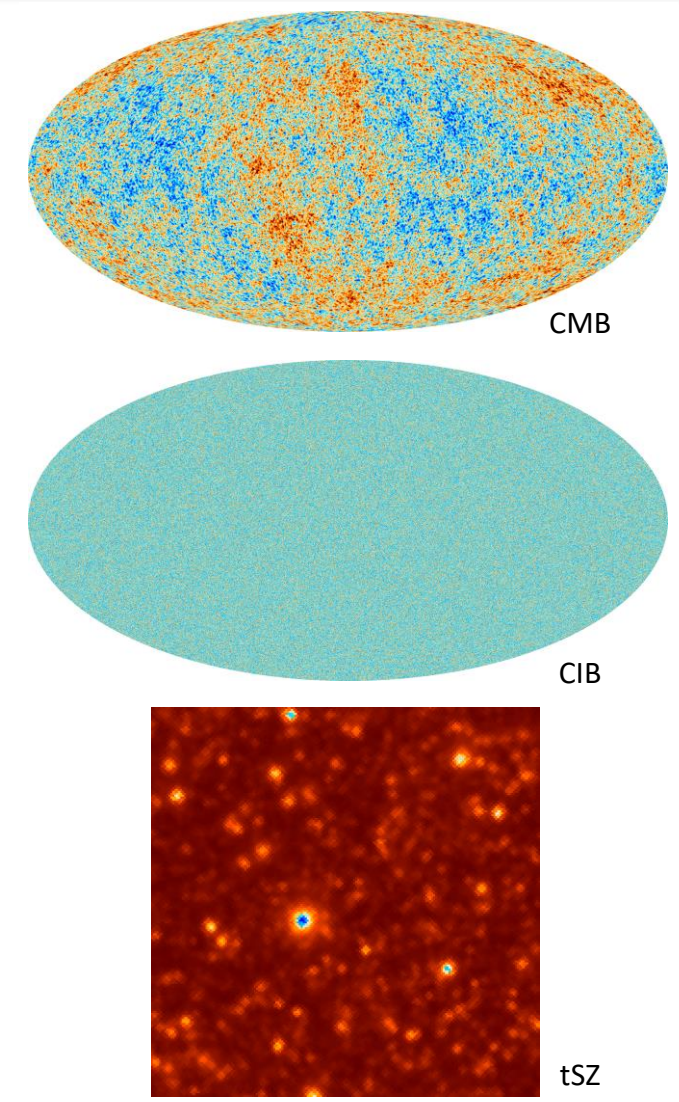
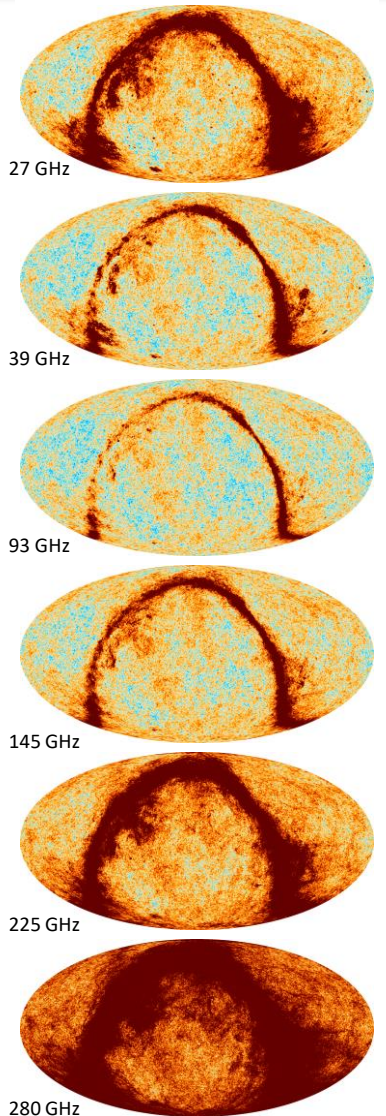
Required step in most science cases:

- ⚙️  $\Lambda$ CDM and extensions (consistency checks)
- ⚙️ Non-gaussianities
- ⚙️ Compton-y map
- ⚙️ ...

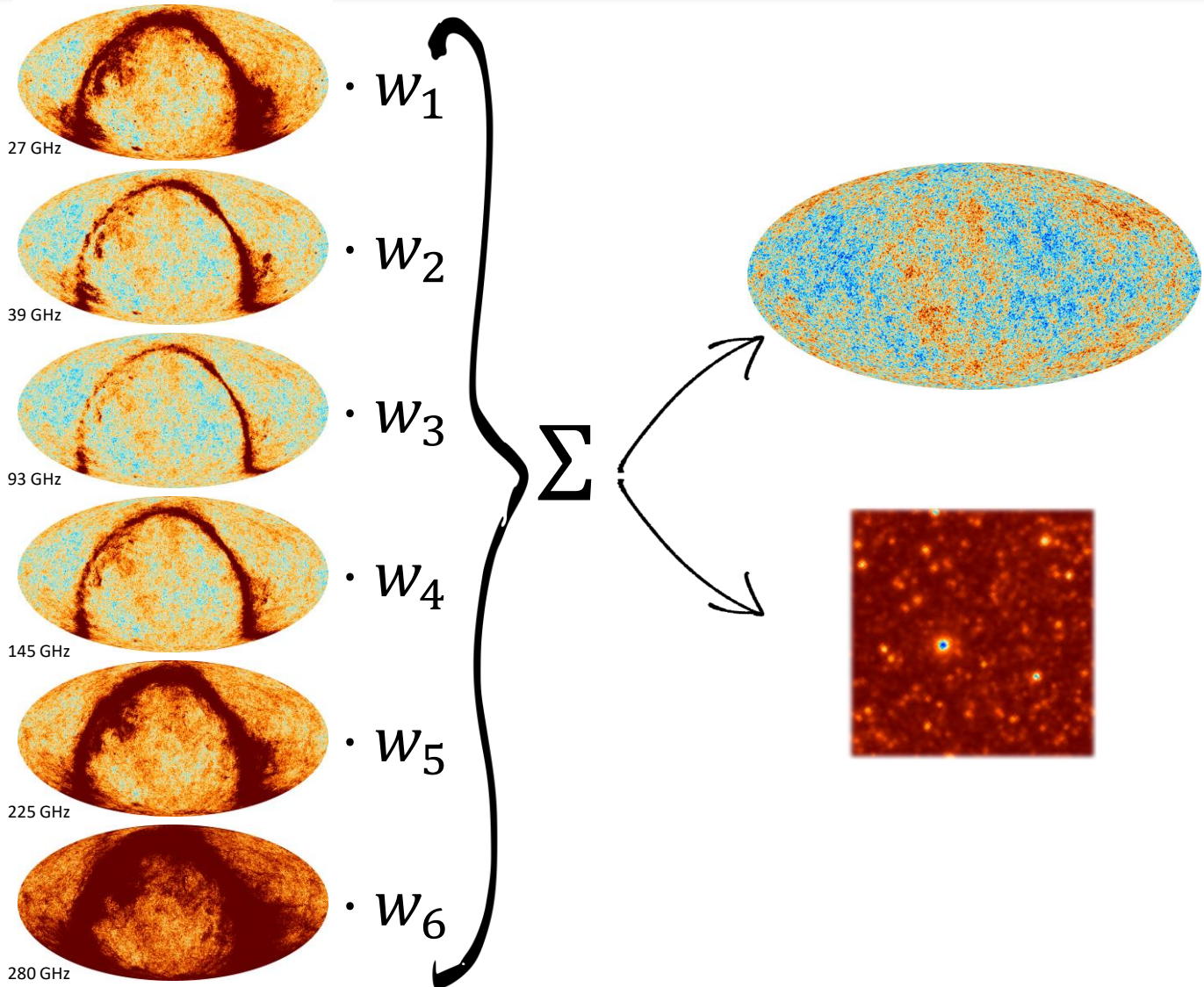
Different methods are implemented with Simons Observatory.



# Component separation



# Component separation: ILC



## Internal Linear Combination (ILC)

Define a set of weights that

1. Preserves the signal of interest
2. Minimizes the variance of the resulting map
3. Nulls contribution from specific components

Pros:

- ⚙ Limited assumptions on the signal (blind)
- ⚙ Easy to implement

Cons:

- ⚙ Doesn't use any prior knowledge/model on the signal
- ⚙ Potentially large bias/residual contamination depending on the localization of the statistics

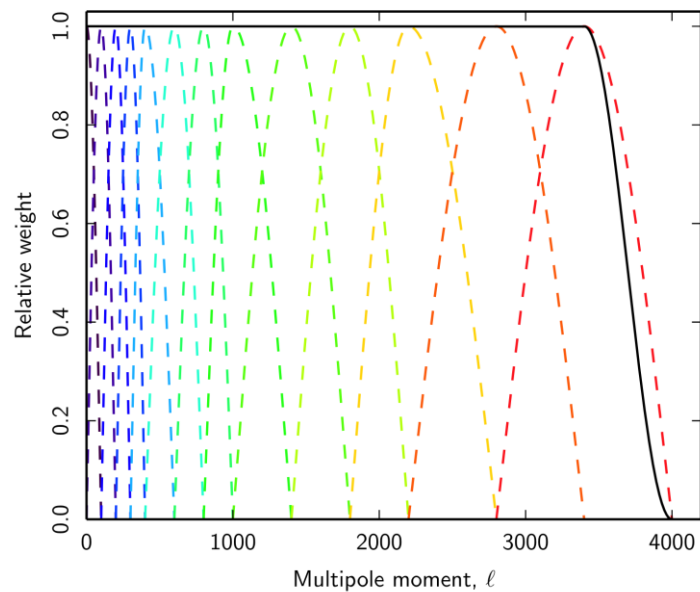
[see eg. Delabrouille et al. 09, Remazeilles et al. 11, 20]

# Component separation: Needlet ILC

What are needlets ?

- ⊗ Alternative basis for projecting signals on the sphere
- ⊗ Localized in both real and harmonic domain

See Will Coulton's poster for an application on ACT + Planck maps !!



- ⊗ Use harmonic filter to produce maps at a different needlet scales
- ⊗ Compute needlet coefficients from these filtered maps
- ⊗ Determine ILC weights for each of these coefficients

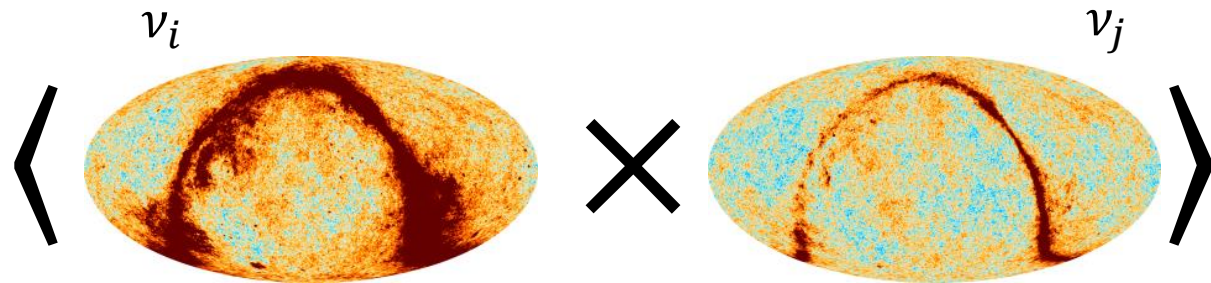
From [Planck iv 2018]





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```

Sum:
- FactorizedCrossSpectrum:
  - FreeSED (SED):
    nu: FREQS
    sed: null
  - FreeCls (Cl):
    cls: null
    ell: ELLS
- FactorizedCrossSpectrum:
  - FreeSED (SED):
    nu: FREQS
    sed: null
  - FreeCls (Cl):
    cls: null
    ell: ELLS
    alpha_knee: a_knee
    beam: FWHM
    ell: ELLS
    ell_knee: l_knee
    nred: null
    nu: FREQS
    nwhite: null
  
```

fgspectra model

$$\hat{R}_\ell = \begin{pmatrix} \hat{C}_\ell(\nu_1, \nu_1) & \dots & \hat{C}_\ell(\nu_1, \nu_N) \\ \vdots & \ddots & \vdots \\ \hat{C}_\ell(\nu_N, \nu_1) & \dots & \hat{C}_\ell(\nu_N, \nu_N) \end{pmatrix}$$

$$R(\theta) = A^{CMB} C_\ell^{CMB} A^{CMB,T} + A^{fgs} P_\ell^{fgs} A^{fgs,T} + N_\ell$$

Measure of mismatch:  
Computation of **KL divergence** and optimization

$$KL(\hat{R}, R(\theta)) = \frac{1}{2} (\text{Tr}(\hat{R}R(\theta)^{-1}) - \log \det(\hat{R}R(\theta)^{-1}) - n)$$

$$R(\theta) = A^{CMB} C_{\ell}^{CMB} A^{CMB,T} + A^{fgs} P_{\ell}^{fgs} A^{fgs,T} + N_{\ell}$$

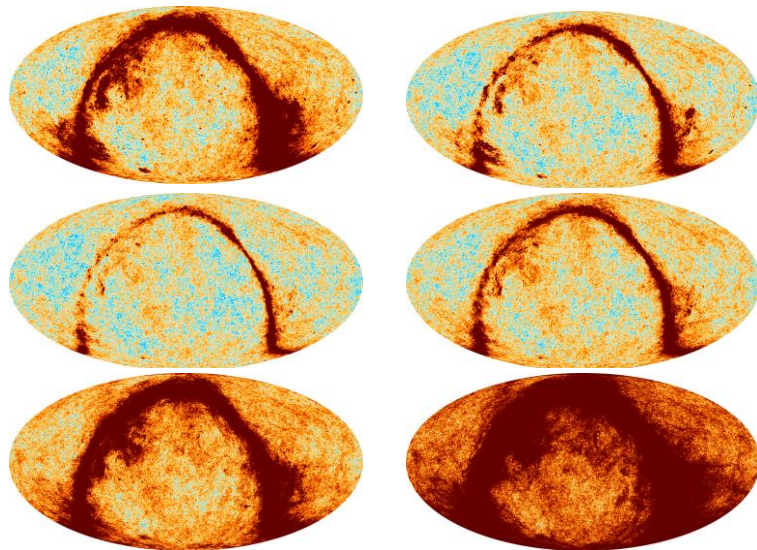
Allows for a flexible parametrization:

- ⊗  $C_{\ell}^{CMB}$  free bandpowers or pre-computed template with free-amplitude,
- ⊗  $P_{\ell}^{fgs}$  multidimensional space, physically motivated templates or free bandpowers,
- ⊗  $A$  fixed, free or modelled mixing matrices,
- ⊗  $N_{\ell}$  noise model.

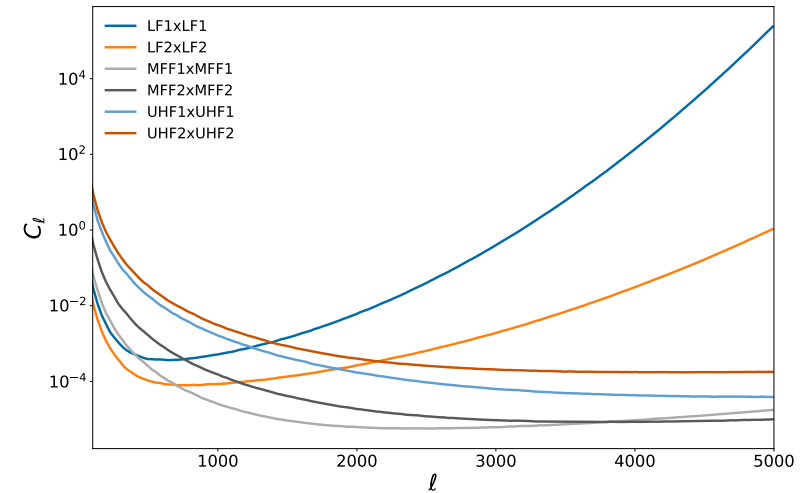
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First tests run on map-based simulations.



- Galactic foregrounds are modelled using **pysm3** [Thorne et al. 17]
- Extragalactic foregrounds are extrapolated from **Websky** [Stein et al. 20]



- Sensitivities from SO overview paper [Ade et al. 19]
- Realistic hitmap and survey strategy
- Top-hat bandpasses



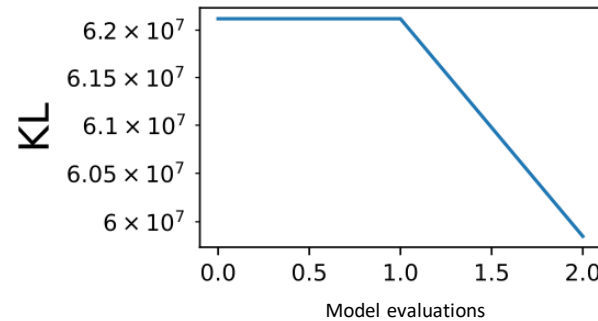
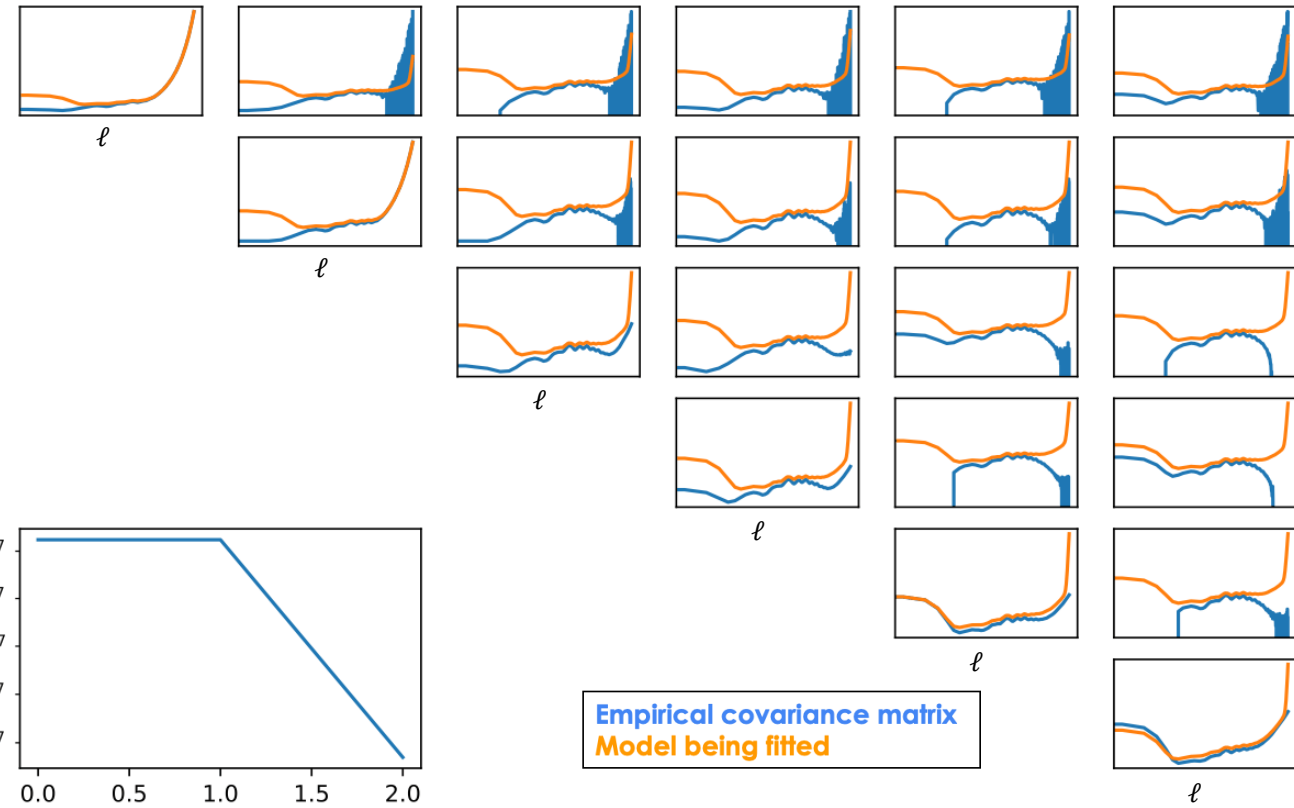
# First tests

- ⚙️ Fixing the CMB sed and fitting the bandpowers.
- ⚙️ Varying the dimensionality of “foreground” component
- ⚙️ Noise model includes both atmospheric and instrumental noise:

$$N_{\ell} = N_{red} * \left( \frac{\ell}{\ell_{knee}} \right)^{\alpha_{knee}} + N_{white}$$

Free parameters

Fixed



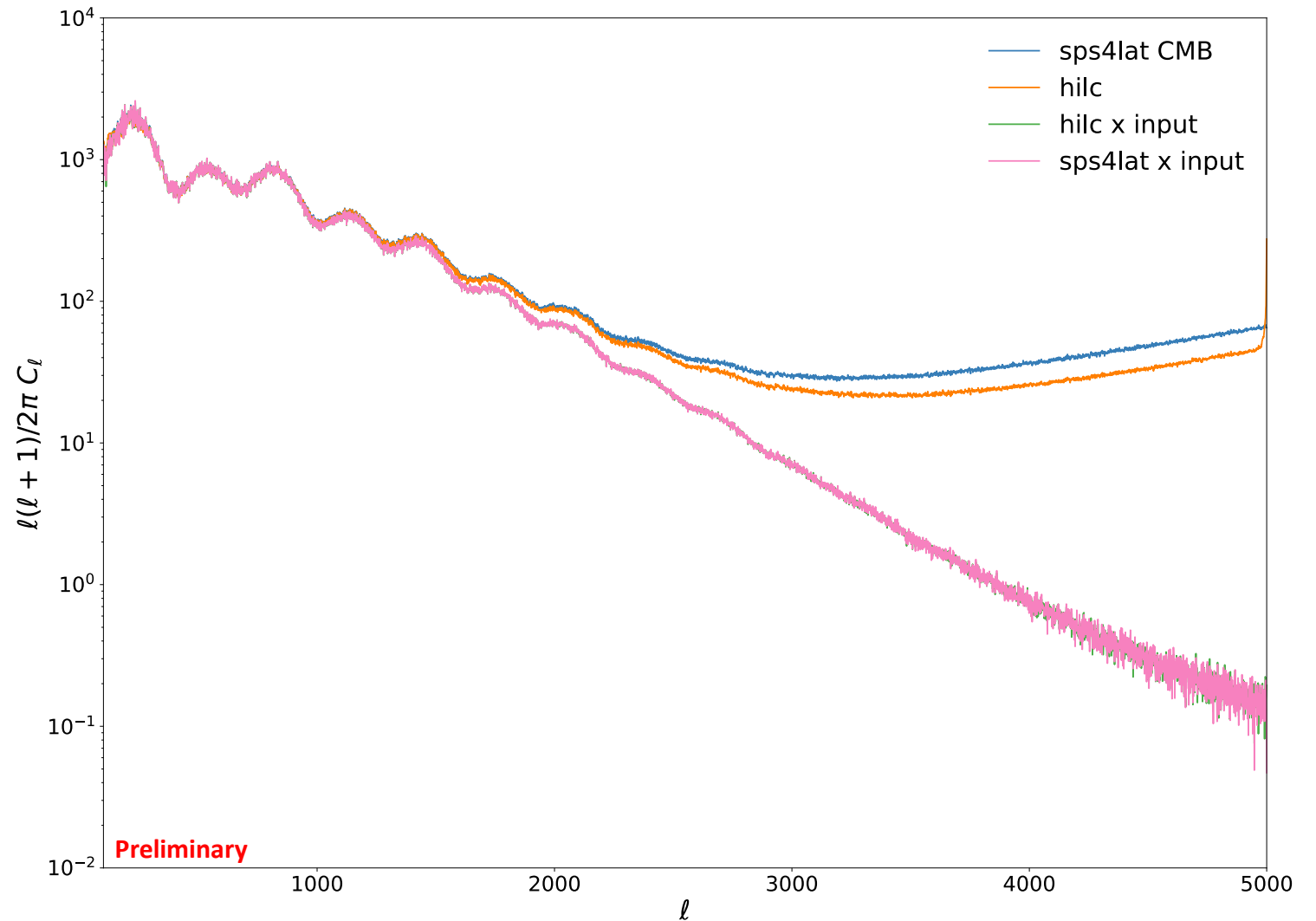
Empirical covariance matrix  
Model being fitted

# First tests

$$\mathbf{R}(\theta) = \mathbf{a}^{\text{CMB}} \cdot \mathbf{a}^{\text{CMB},\text{T}} C_{\ell}^{\text{CMB}} + \mathbf{N}_{\ell}$$

$$\mathbf{a} = (1, \dots, 1)^{\text{T}} \quad \text{Fixed}$$

$$C_{\ell}^{\text{CMB}} \quad \text{Free bandpowers}$$



# First tests

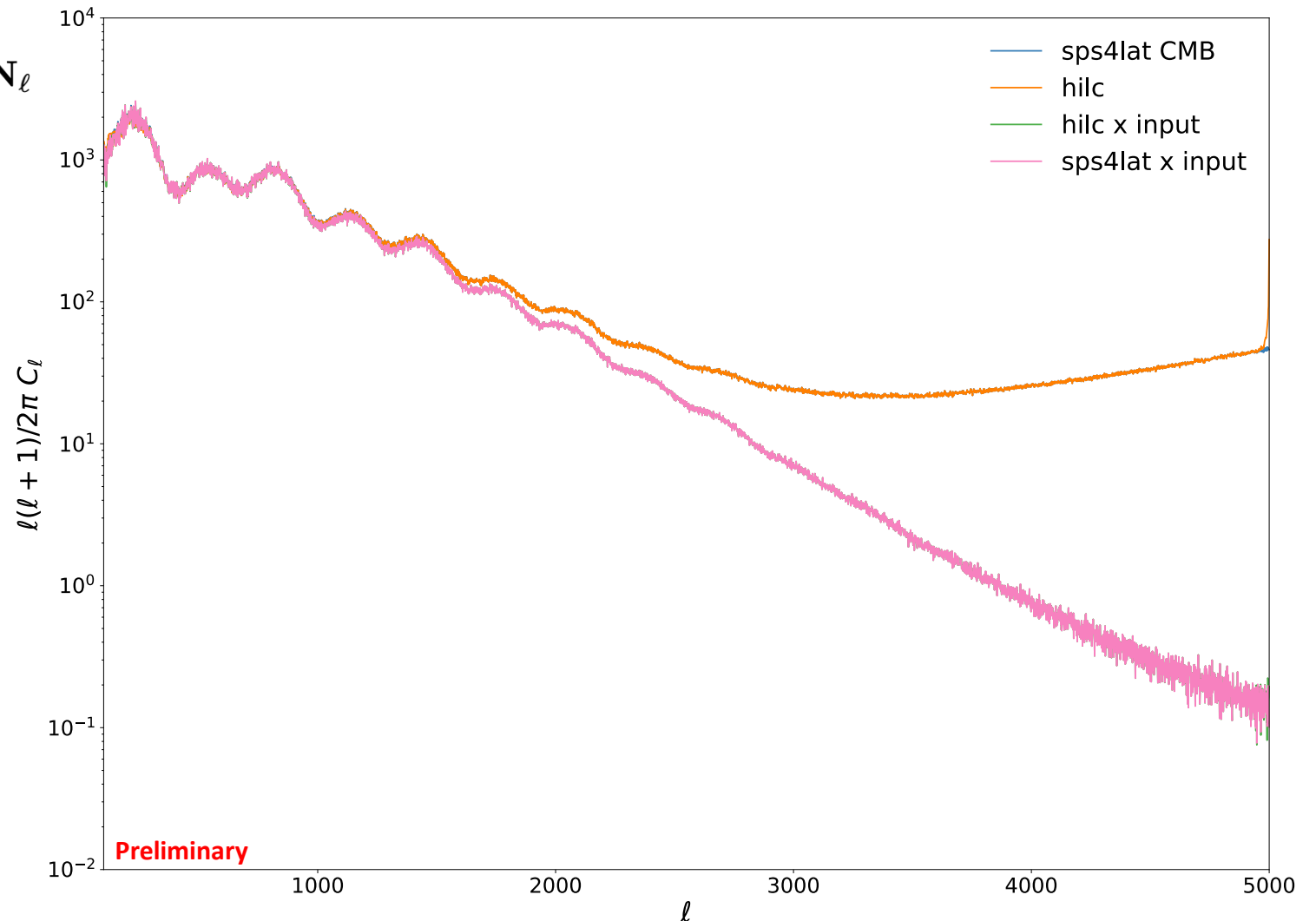
$$\mathbf{R}(\theta) = \mathbf{a}^{\text{CMB}} \cdot \mathbf{a}^{\text{CMB},T} C_{\ell}^{\text{CMB}} + \mathbf{b}^{\text{fg}} \cdot \mathbf{b}^{\text{fg},T} C_{\ell}^{\text{fg}} + \mathbf{N}_{\ell}$$

$$\mathbf{a} = (1, \dots, 1)^T \quad \text{Fixed}$$

$$\mathbf{b} = (b_1, \dots, b_N)^T \quad \text{Free sed}$$

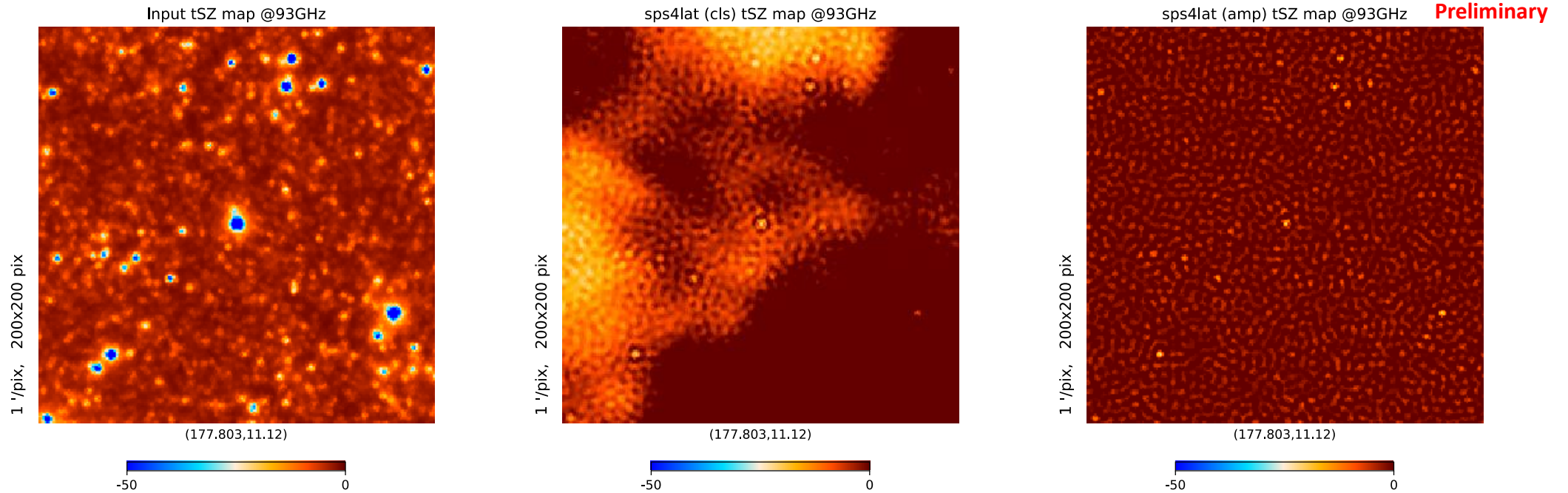
$C_{\ell}^{\text{CMB}}$  Free bandpowers

$C_{\ell}^{\text{fg}}$  Free bandpowers





# First tests



$$\mathbf{R}(\theta) = \mathbf{a}^{\text{CMB}} \cdot \mathbf{a}^{\text{CMB},T} C_l^{\text{CMB}} + \mathbf{b}^{\text{tSZ}} \cdot \mathbf{b}^{\text{tSZ},T} C_l^{\text{tSZ}} + \mathbf{c}^{\text{fg}} \cdot \mathbf{c}^{\text{fg},T} C_l^{\text{fg}} + \mathbf{N}_l$$

↑ Fixed      ↑ Free      ↑ Fixed      ↑ Free bandpowers or free amplitude      ↑ Free      ↑ Free

## Next steps:

- ⚙ Increasing the complexity of the model requires investigating both the starting prescription and the optimization methods,
- ⚙ Identifying science cases where semi-parametric component separation is beneficial,
- ⚙ Including polarization,
- ⚙ Exploring the feasibility of applying `sps4lat` in the needlet domain.

# Thank you for your attention !

-- Feel free to ask any question now, at a coffee break or via email ! --



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