

# ATLAS ITk Lecce Update

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# Local support FDR (Final Design Review)

Ieri ed oggi ci sono le presentazioni del Local Support FDR per Outer Barrel e Outer Endcap: <https://indico.cern.ch/event/1075990/>

Presentazione interessante di Review per i local support dell'Outer Encap:

- Endcap Half Ring Design and Interfaces - Peter Sutcliffe (University of Liverpool (GB))
- OE Bare Local Supports Qualification: Material and Electrical (G&S) Francisca Munoz Sanchez (University of Manchester (GB))

**NB: Mi hanno chiesto i nomi sul documento di Local Support FDR per l'Outer Barrel ed io ho comunicato il mio, quello di Alessandro (handling frame) e quello di Rita (transport box). Ovviamente sul Loaded Local Support FDR ci sarà il nome di tutto ITK Lecce (Prossima slide).**

# Local support FDR from Cecilia

- End-cap local supports are fabricated in two independent lines, one in Italy and one in UK.
  - The Italian line will produce 50% of Layer 2 and all Layer 4 Half rings.
  - The UK line will produce 50% of Layer 2 and all Layer 3 Half rings. This is mainly based on machining facilities.
- In the latest ITk schedule, production of Layer 2 HR will happen from November 2022 to September 2023. Layer 4 (IT) and Layer 3 (UK) HR will be produced from September 2023 to December 2024.

Number Bare Half Ring depends on the number of Loaded local supports needed:

Sub-system	Needed for detector	Production (includes yield)	Pre-production	Total to produce
Endcap A	56	58	4	62
Endcap C	56	58	4	62

*Required loaded local supports*

Sub-system	Needed	Production (includes yield)	Pre-production	Total to produce
Endcap A	62	68	4	72
Endcap C	62	68	4	72

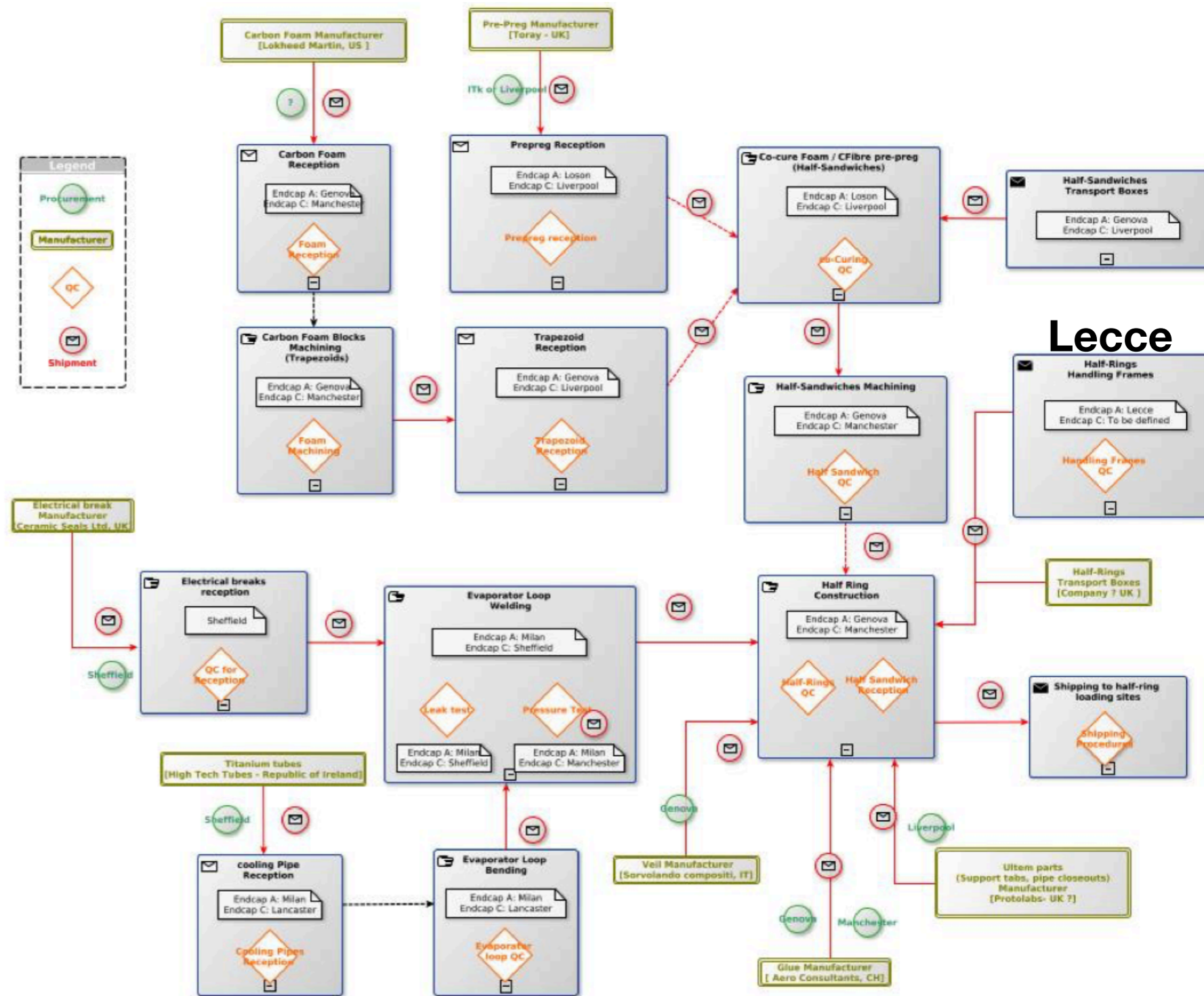
*Required bare local supports*

Production flow diagram illustrates sequential steps of LS fabrication procedure.

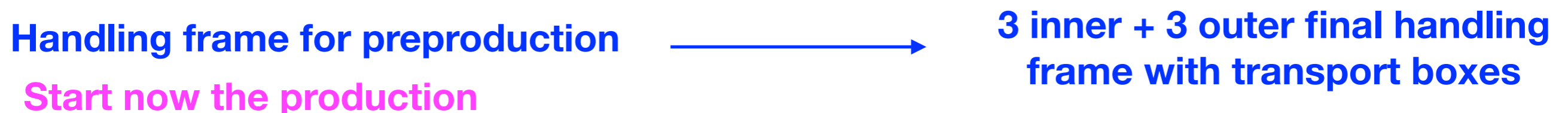
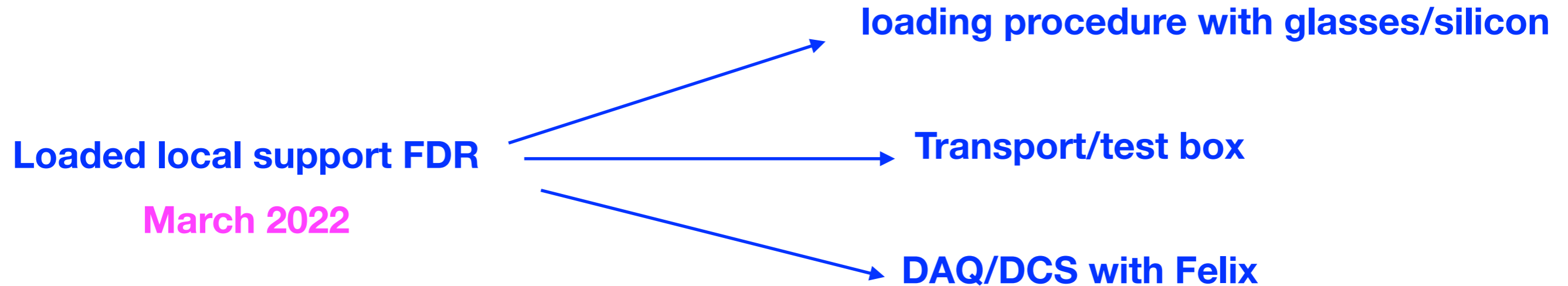
- Shipments and QC procedures are explicitly indicated.
- The exact place where the manufacturing or testing is performed is also indicated.

Identical production flow.

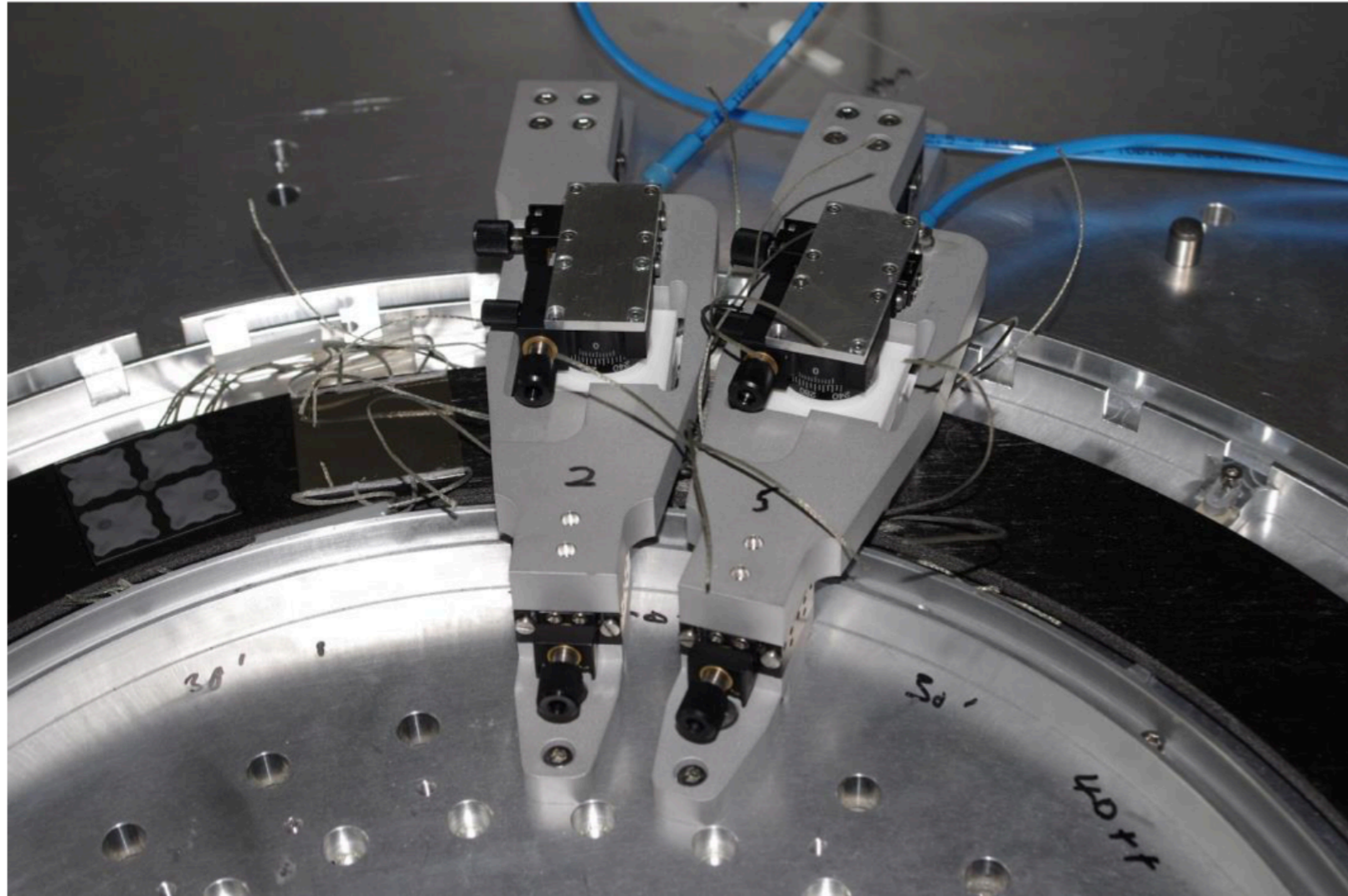
Only relevant difference is co-curing of the HS:  
 Italy → External company (Loson),  
 UK → University lab (Liverpool).



# Impegni di Lecce a corto termine



# Four loading sites: RAL



**Gantry X,Y,Z**

**No Theta Stage**

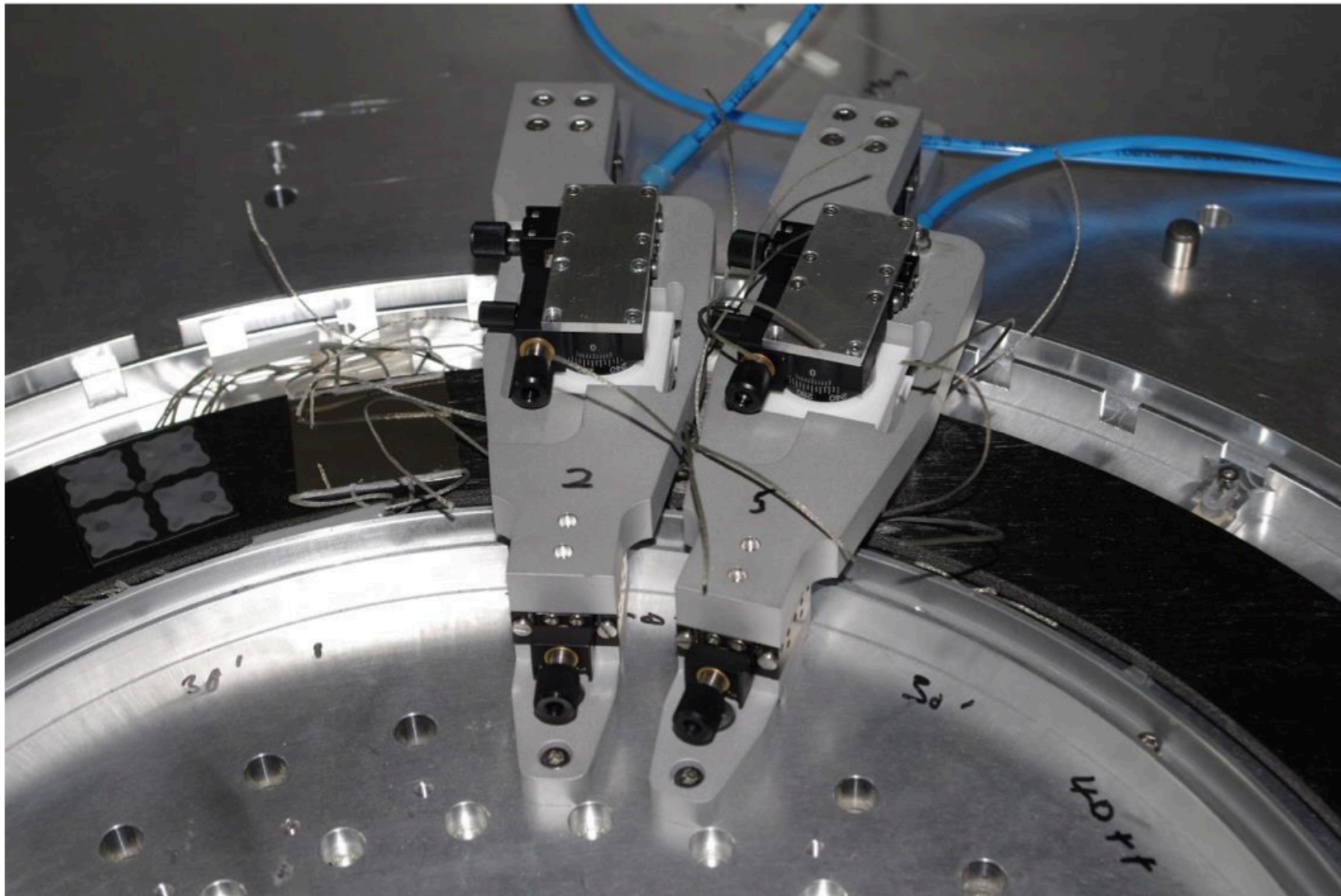
**Manual bridges with manual micrometric xyz-theta adjustments**

**Needed custom made baseplate**

**No need to wait for glue curing between two modules.**

**Build a working UK Half-Ring 0  
Now building UK Half-Ring 1**

# Four loading sites: Oxford



**Gantry X,Y,Z,Theta**

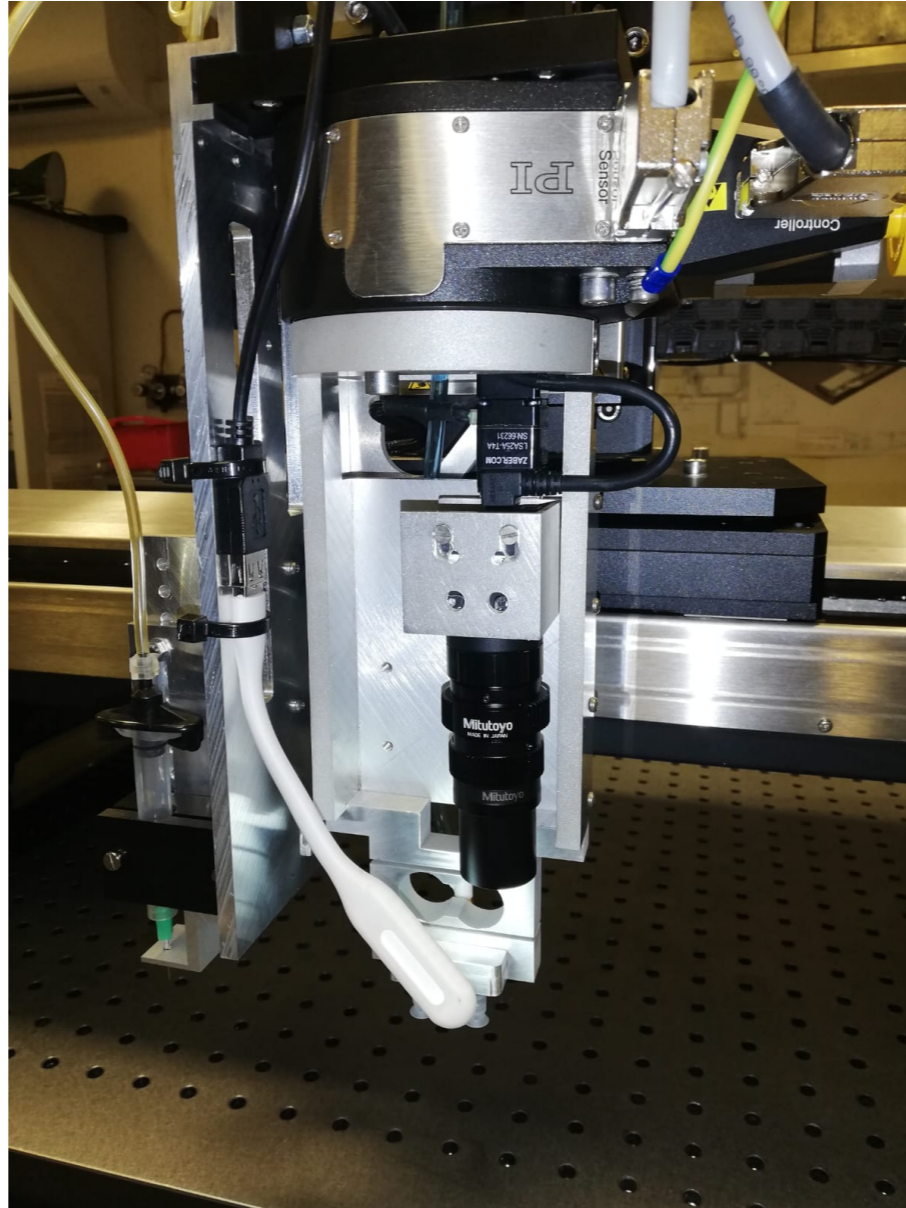
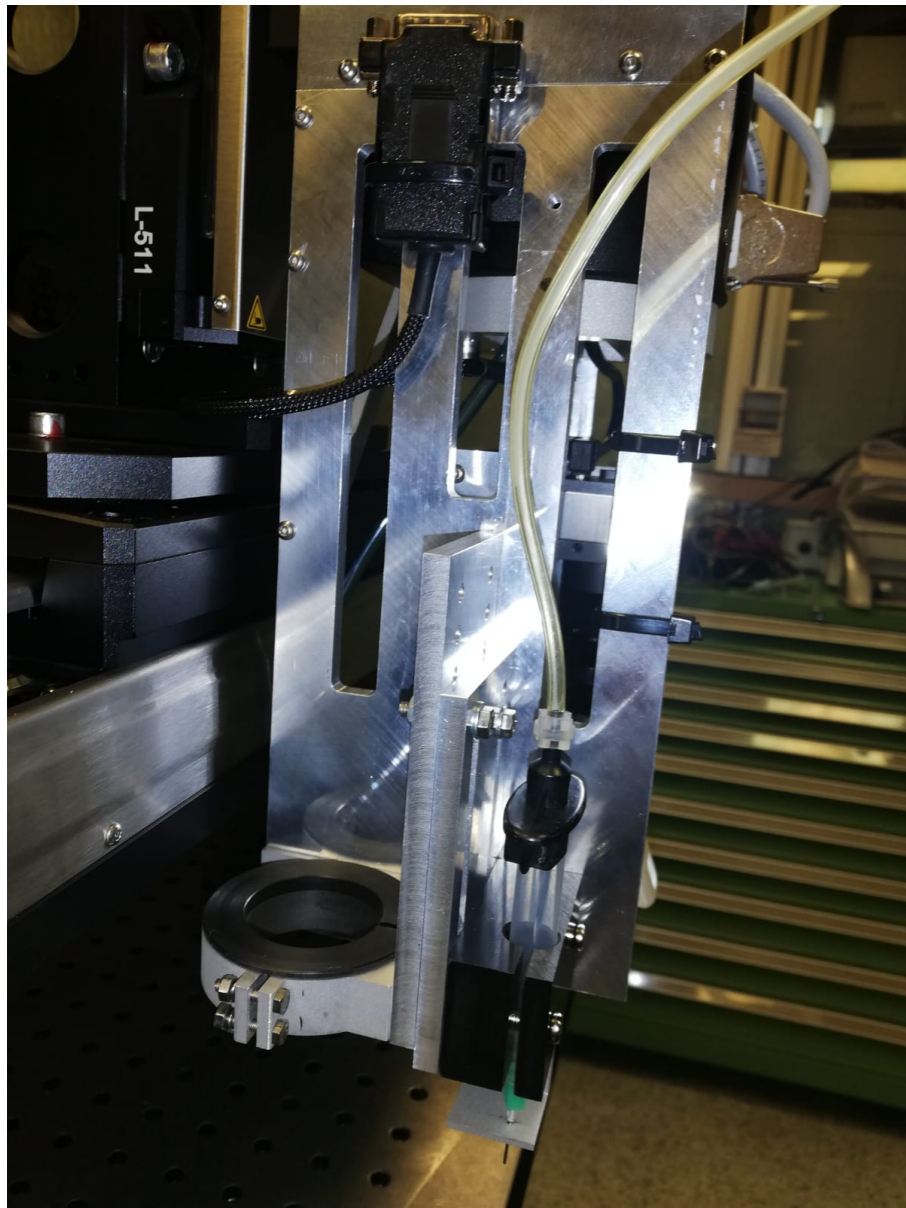
**Automatic Bridges**

**Needed custom made baseplate**

**No need to wait for glue curing between two modules.**

**Just started**

# Four loading sites: Genova



**Gantry X,Y,Z,Theta**

**Pick&Place head with microscope independent z-movements (supervised module after pick)**

**No need custom made baseplate**

**Need to wait for glue curing between two modules.**

**Just started**



# Four loading sites: Lecce vs Genova

## GE

**Gantry X,Y,Z,Theta**

**Pick&Place head with microscope  
independent z-movements  
(supervised module after pick)**

**No need custom made baseplate**

**Need to wait for glue curing  
between two modules.**

**Just started**

## LE

**Gantry X,Y,Z,Theta**

**Pick&Place head**

**Microscope on z stage (no  
supervised module after pick)**

**No need custom made baseplate**

**Need to wait for glue curing  
between two modules.**

**Hardware and software (Labview +  
Original) capable to due a large  
scale loading exercise.**

# Glue thickness and chip coverage

**The most crucial step it is the final glue thickness and chip coverage.**

**It is related to:**

- Deposited glue quantity (assuming good spread when loading)**
- Module planarity**
- Half-ring local support local planarity**
- Relative orientation in space of module chip surface and half ring during loading**

**Strategy to deal with**

- RAL : pillars and silicon spheres (already tried)**
- OXFORD : silicon sphere (already tried) and**
- GENOVA : Strain Gauge on Pick&Place head (to be proven)**
- LECCE : Geometrical plane adjustment of (parking tool ?) and pick and place head to be parallel to the half-ring (our next goal)**