















ENVIRONMENTAL NOISE MEASUREMENTS AT SOS ENATTOS

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Outline

- Status of Environmental Monitoring at Sos Enattos
- Focus on Magnetic Noise Measurements
 - Underground long-term measurement
 - Surface vs Underground
 - New measurements at Bitti (P2)
 - In Time Analysis
 - Magnetic noise projection
- Next steps

Status of EnvMon at Sos Enattos

Underground probes

- Apart from seismic probes there is still a single magnetic probe at -111 m): Metronix MFS-06 sampled at 250 Hz: SOE2
- New hermetic rack installed, hosting the electronics, including two acquisition systems;





ET Site Studies and Characterization Workshop - November 8th 2021

Status of EnvMon at Sos Enattos

Surface Probes

- The surface magnetometer (SOE0: Metronix MFS-06e sampled at 250 Hz, N-S orientation) is now active.
- Several stops during the last year.
- Data taking periods:
 - 1 2020 August 6 to November 9;
 - 2 2021 March 13 to April 30;
 - 3 2021 July 27 to September 14;
 - 4 2021 October 16 ongoing





Status of EnvMon at Sos Enattos

Weather Station

- The station is regularly collecting data since June 6 2020
- Data summary available on web

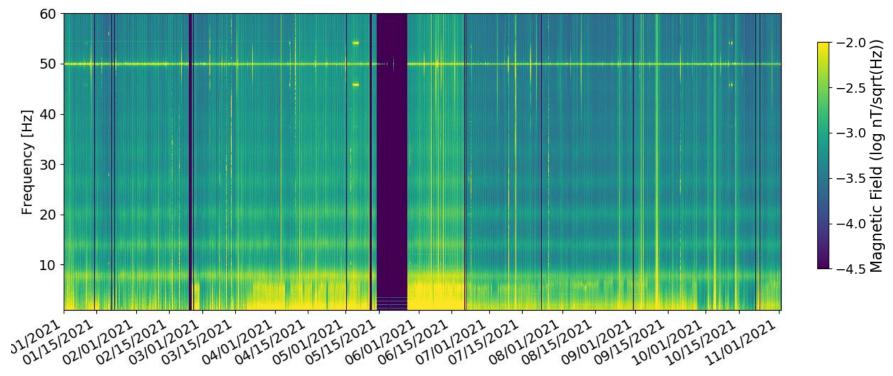


Magnetic Noise Measurements Motivation

- The noise from natural or anthropogenic electromagnetic fields can affect the sensitivity of a gravitational wave interferometer in different ways:
 - Direct coupling with magnet actuators of the mirror and suspension systems;
 - Coupling with electronic devices managing the interferometer;
- A special role, among the possible noise sources, is played by the Schumann resonances: a world-wide electromagnetic field sustained by the lightning discharges between the Earth surface and the ionosphere.
- Due to their global character, the Schumann resonances could set a strong limit in the detection capability of selected class of sources (e.g GW stochastic noise);

Magnetic Noise Measurements About One Year Long Measurement

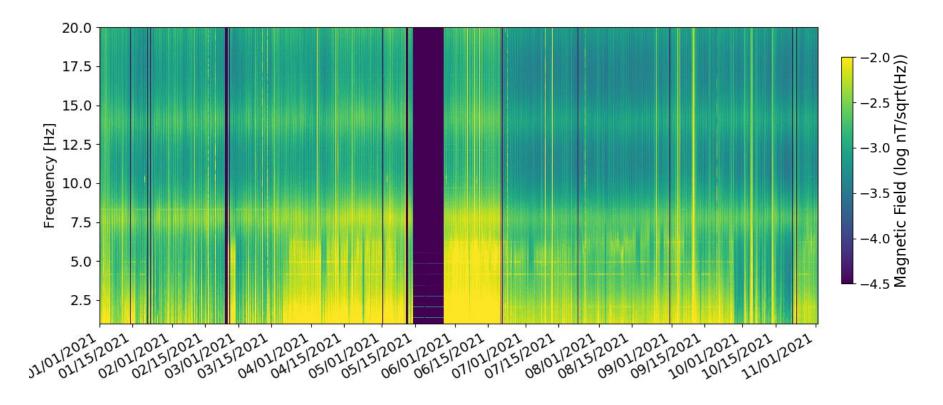
- Data from the SOE2 (-111 m) magnetometer;
- Schumann Resonances peaks (SR) from 1st to 7th (SR1
- ... SR7) clearly visible;



 $SR1 \sim 7.8 \text{ Hz}, SR2 \sim 15.6 \text{ Hz}, SR3 \sim 23.4 \text{ Hz}, \dots$

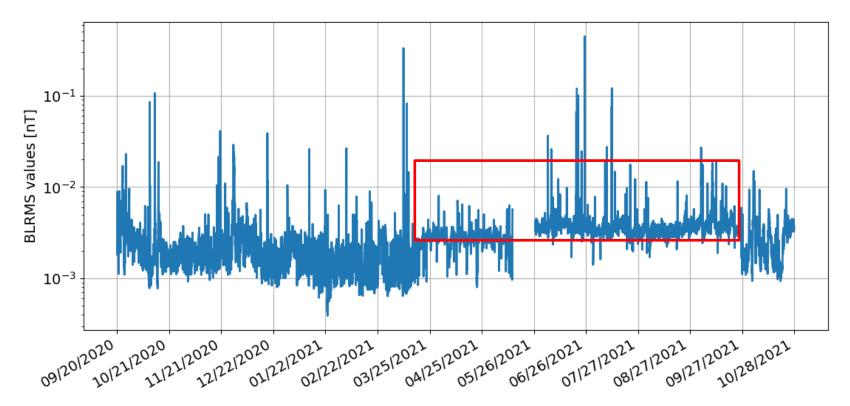
Magnetic Noise Measurements About One Year Long Measurement

- Zoom at low frequency;
- Higher low frequency noise (up to about 6 Hz) from mid march to end of September;



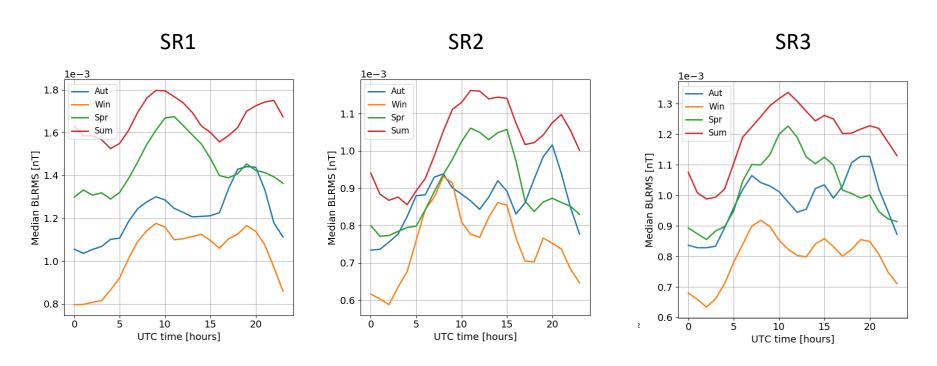
Magnetic Noise Measurements About One Year Long Measurement

- More clear looking at BLRMS (integrated from 1 to 5 Hz);
- Note the different time scale (more than one year);
- Excess noise not yet really understood investigation in progress with auxiliary sensors;



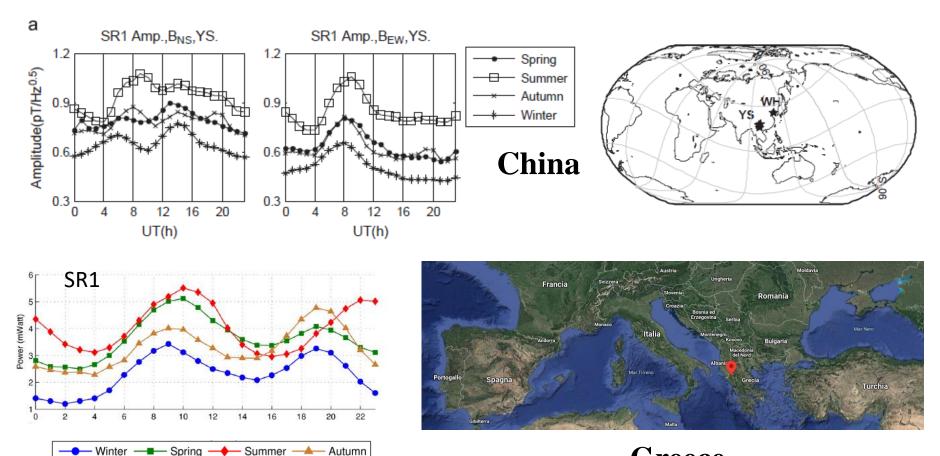
Schumann Resonance variability

- Apart the anomalous low frequency noise, the SR show their characteristic variability;
- For any season, the minimum value is reached during night (about 1-2 UTC);



Schumann Resonance variability

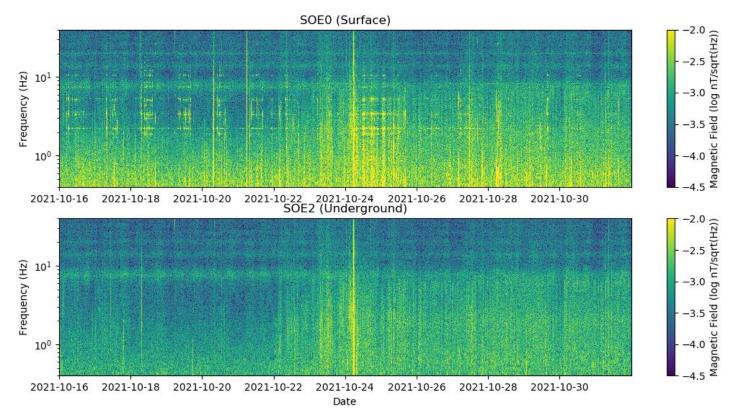
• The observed variability is compatible with other measurements performed in other observatories



Greece

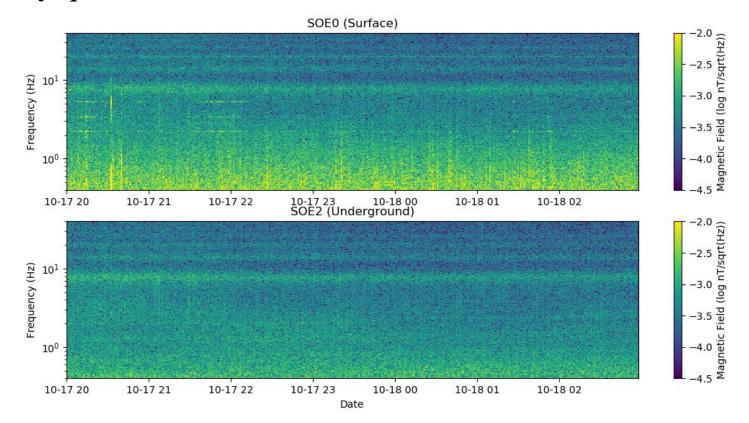
Surface vs. Underground comparison

- Comparison between SOE2 and SOE0 in the period 16-31
 October 2021
- Larger noise, in surface, below 10 Hz;



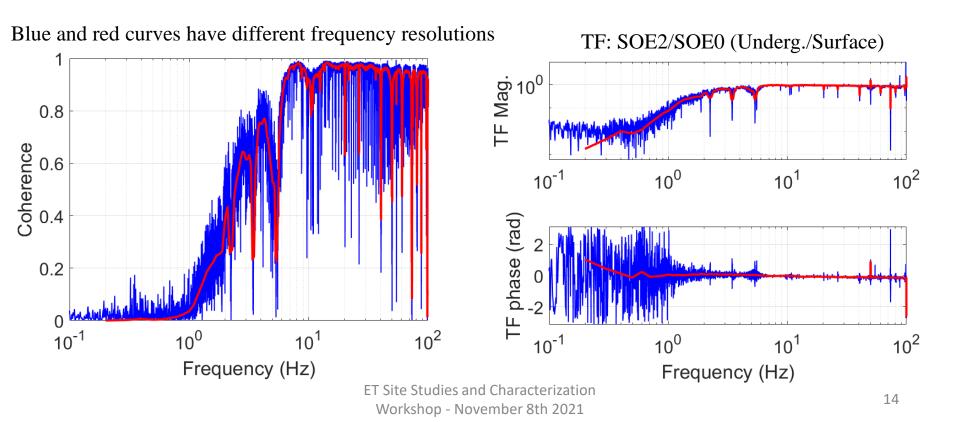
Magnetic Noise Measurements Surface vs. Underground comparison

- A comparison between underground and surface during a quiet period (7 hours from 17 October 2021);
- Very quiet data both at SOE2 and SOE0:



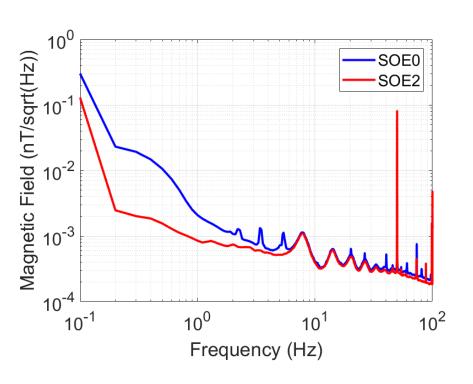
Surface vs. Underground comparison

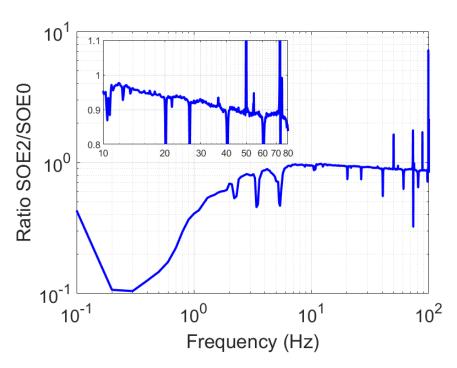
- Last data were used to perform a more detailed comparison between surface and underground;
- Good coherence from 1 Hz and almost flat and unitary TF in the SR region;



Surface vs. Underground comparison

- Spectra and their ratio computed on the full quiet period;
- The ratio show a decrease of the magnetic field, in the SR band, for underground location;





Surface vs. Underground comparison

- A simple model assuming a uniform conductivity of the soil and a slow varying field approximation for the magnetic field is enough to approximately explain the measured behavior;
- Surface to underground described by the transfer function;

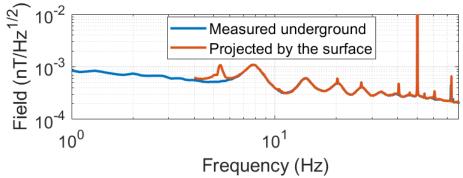
$$TF = e^{-(1+i)d\sqrt{\pi\mu_r\mu_0\sigma f}}$$

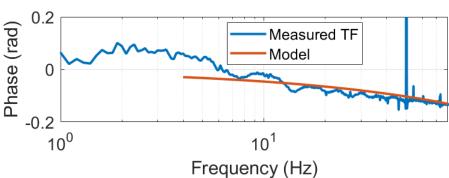
The depth was fixed to:

$$d=110 \text{ m}$$

The resulting conductivity was:

$$\sigma = 4.5 \cdot 10^{-3} \text{ S/m}$$





New Measurements at Bitti (P2)

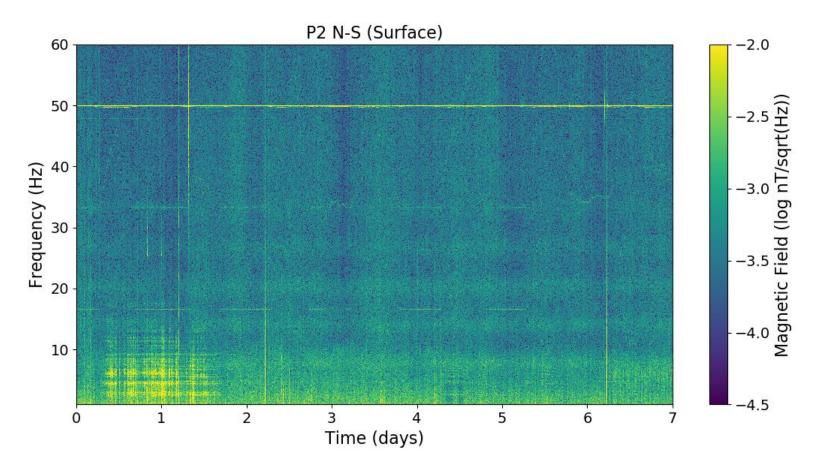
- Last September 17 a couple of magnetometers were installed in P2 (Bitti NU), N-S and E-W orientation;
- The probes are the same used for Sos Enattos, with a different data logger (Metronix ADU 08) sampling at 512 Hz;





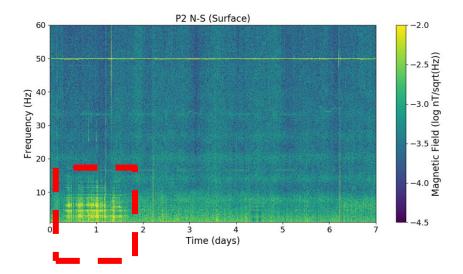
New Measurements at Bitti (P2)

• Magnetic noise is low enough, but there are strong disturbances in the band 2-10 Hz. Not always present...

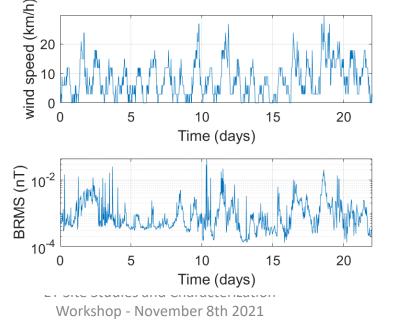


New Measurements at Bitti (P2)

• The disturbances are very likely due to wind induced vibrations of the metallic wire mesh placed all around the protected area;

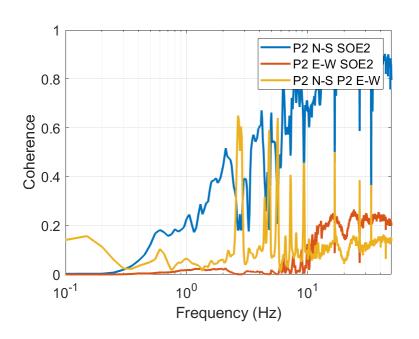


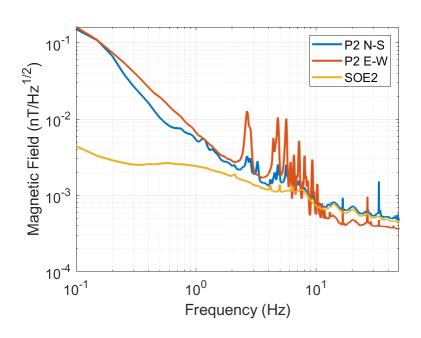
- A little correlation is visible with the far (about 12 km) weather station at Sos Enattos...
- Plan to install a weather station in P2 also;



New Measurements at Bitti (P2)

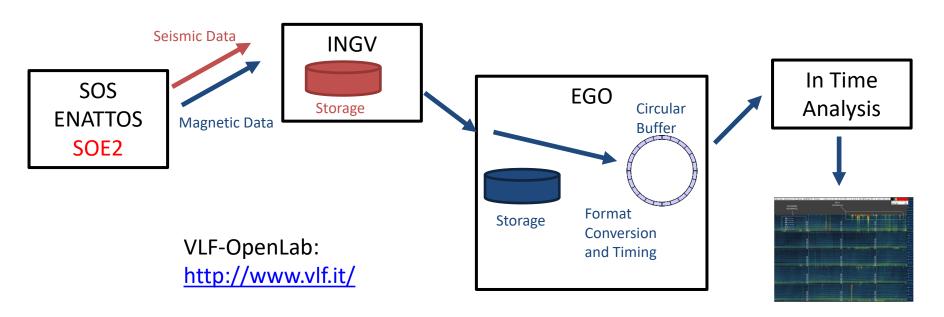
- Comparison with the underground field (SOE2);
- Larger low frequency noise;
- SR from 2 very well visible;
- Probably the orientation is not really good;





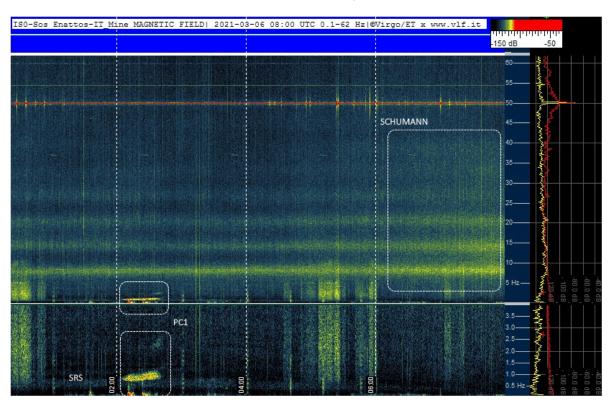
Data repository and transmission

- Data from the underground magnetometer are sent to INGV together with the seismic signals from SOE2;
- Magnetic data are then stored at EGO (mseed format);
- Finally they are sent to VLF-OpenLab for the in-time analysis (wav format);



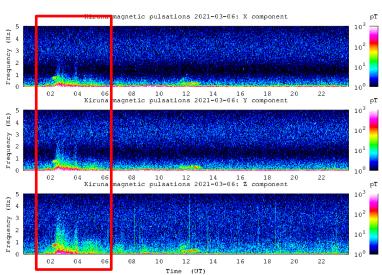
In time analysis

• A detail showing SR (up to 6th), 50 Hz disturbances, a Magnetic Pulsation (PC1) and Spectral Resonance Structures (SRS) observed on 6 March 2021;



In time analysis



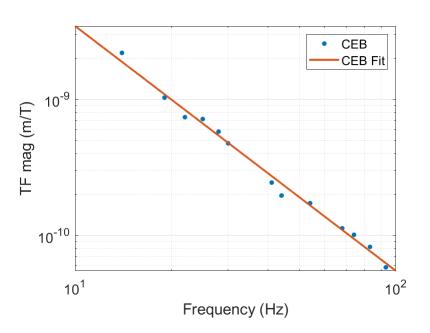


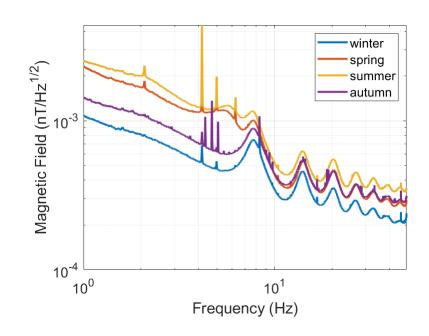
- Magnetic pulsation are produced inside the magnetosphere and their detection, on Earth, requires very quiet environment;
 - The same pulsation detected in SOE2 was detected at Atmospheric and Geophysical Observatory. (Sweden)



Magnetic Noise Projection

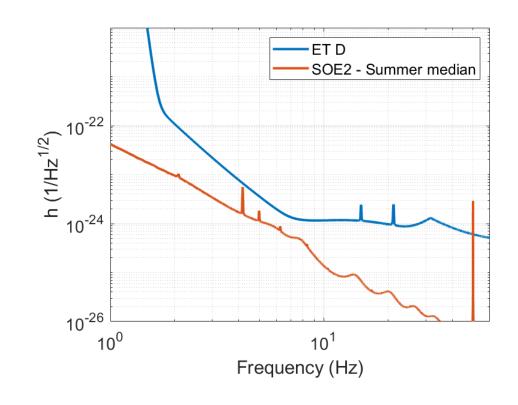
- The Magnetic field measured at SOE2 was used to estimate the effect of this noise on the ET floor;
- The coupling function was estimated by the result of the magnetic noise injections performed in Virgo during O3 (VIR-0291A-20). Warning: no direct measurement under 10 Hz;





Magnetic Noise Projection

- With this assumption the magnetic noise (measured at SOE2) does not limit the ET sensitivity, but...
 - This is, of course, only a conservative projection in a very quiet environment;
 - Coupling below 10 Hz was just extrapolated by the fit;
 - We expect a significant background noise increase in the final ET environment;
 - More inputs are needed to estimate the magnetic coupling, both at low as at high frequencies;



Next Steps

Beginning of next year

- Installation of the microphones: initially in surface, inside the control room for test, and then at level -2 for correlation with seismometer;
- Installation of a third magnetometer in SOE3;

Middle 2022

• Displacement of the magnetic probes from P2 to P3;

