



Directional-iDBSCAN

a proposal to CYGNO

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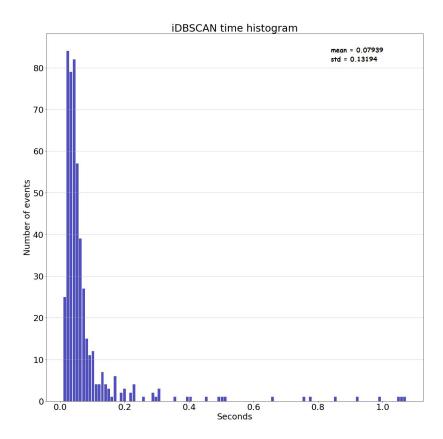
Igor Abritta and Rafael A Nobrega

Last presentation

 An implementation of the iDDBSCAN with its iteration part written in cython was made aiming to reduce the duration of the algorithm.

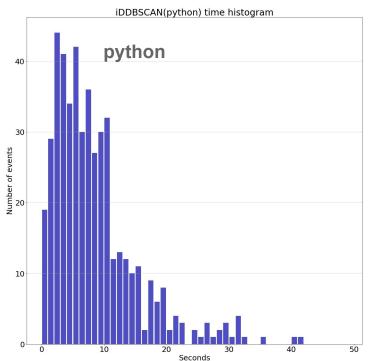
 The speed boost was not so high as other implementations found in the literature.

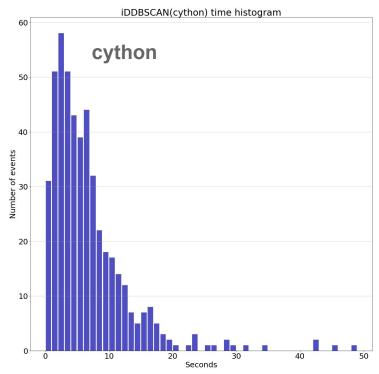
Time efficiency - iDBSCAN



- The iDBSCAN (one iteration) needed less than one second to do the clusterization in most part of the events.
- It took less than 0.15 seconds for most part of the events.
- The slowest event needed 1.073 seconds

Time efficiency - iDDBSCAN (python vs cython)





Cython.html

```
Generated by Cython 0.29.21
Yellow lines hint at Python interaction.
Click on a line that starts with a "+" to see the C code that Cython generated for it.
+001: #Libraries
003: from future import division
004: cimport cython
005: cimport numpy as np
+006: import numpy as np
007: from libcpp.vector cimport vector
+008: from sklearn, linear model import RANSACRegressor
+009: from operator import itemgetter
+010: import time
+012: np.import_array()
014: @cython.boundscheck(False)
015: @cython.wraparound(False)
+016: cdef np.ndarray[np.npy_float64, ndim=1] polyval(np.ndarray[np.npy_float64, ndim=1] fit, np.ndarray[np.npy_int64, ndim=1] x):
         cdef np.npy int i, j
         cdef np.npy float64 soma
         cdef np.ndarray[np.npy_float64] y_poly
019:
020:
         length = x.shape[0]
+021:
         y_poly = np.zeros(length, dtype = np.float64)
         for i in range(length):
+024:
             soma = 0
+025:
             for j in range(fit.shape[0]):
+026:
                soma = soma*x[i] + fit[j]
+027:
             y_poly[i] = soma
+029:
         return y_poly
032: #Defining functions
033: #Ransac function
034: @cython.boundscheck(False)
035: @cython.wraparound(False)
+036: cdef np.ndarray[np.npy_float64, ndim=1] ransac_polyfit(np.ndarray[np.npy_int64, ndim=1] x,
                                                          np.ndarray[np.npy_int64, ndim=1] y,
038:
                                                          np.npy_intp order,
039:
                                                          np.npy_float32 t,
040:
                                                          np.npv float32 n=0.8.
041:
                                                          np.npy intp k=100,
                                                          np.npy float32 f=0.9):
043:
044:
         cdef np.npy_intp kk, i
+045:
         cdef np.npy float64 thiserr, besterr = -1.0
         cdef np.ndarray[np.npy_int64, ndim=1] maybeinliers, x_in, y_in
         cdef np.ndarray[np.npy_bool, ndim=1] alsoinliers
         cdef np.ndarray[np.npy_float64, ndim=1] bestfit, polyderi, maybemodel, res_th, bettermodel
049:
         bestfit = np.full(order+1, -1, dtype = np.float64)
         polyderi = np.zeros(order, dtype = np.float64)
         for kk in range(k):
```

- By using "cython -a *cython_code.pyx*" an html page will be created to show how close to C the code is.
- The ideal is to have as many white lines as possible.

Cython updates

- Based on the article: Cython for Speeding-up Genetic Algorithm
 - ODI: <u>10.1109/ICEIT48248.2020.9113210</u>
- There are some tips that may speed up the algorithm:
 - Specify the types of the variables, arrays and its elements.
 - Loop through arrays using indexing.
 - Disable unnecessary features such as check array limits and negative indexes.
 - Use arrays and vectors instead of lists.
 - Create new arrays instead of access them if they are needed more than once.
 - Avoid type casts.

Results and conclusions

- The speed boost by using a cython version of the *ddbscan_inner* continued small, it was 30% faster than the python version after the updates.
- Almost 80% of the duration of the algorithm is on the directional search, mainly due to the *ransac_polyfit* function, made with a lot of numpy functions.
- Put the algorithm in cython is not always equivalent to have a high speed up, specially if the python algorithm has a lot of library calls.

Next steps

- Change the number of attempts in the ransac_polyfit in order to find the best parameter conciliating results and time efficiency.
- Modify the algorithm to just expand the neighborhoods of core_points at the directional search.
- Search faster implementations of RANSAC.

