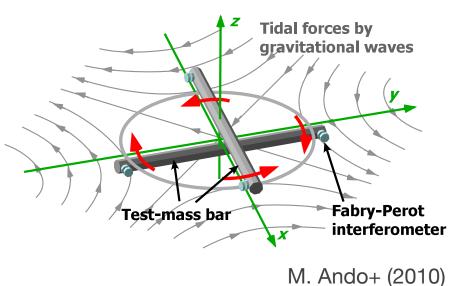
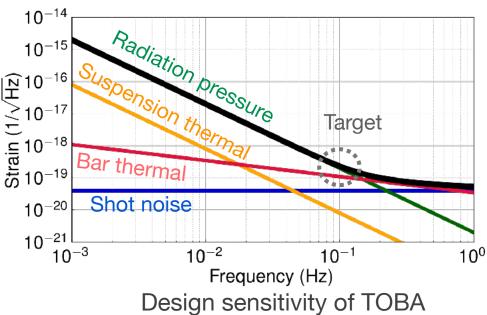


### **Torsion Bar Antenna (TOBA)**

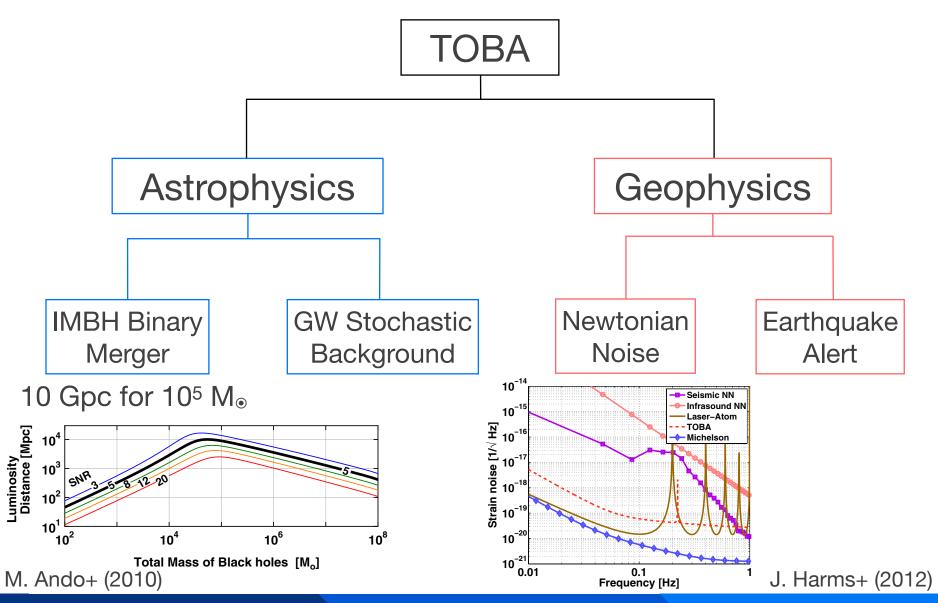
#### TOBA: TOrsion-Bar Antenna

- Gravitational wave detector using two torsion pendulums
- Resonant frequency of torsion pendulum ~ mHz
  - → Sensitive to low frequency (~ 0.1Hz)
- Target sensitivity h ~ 10<sup>-19</sup> / √Hz @ 0.1 Hz with 10 m bars





### Science of TOBA



#### **Development Plan**

Phase-I (2009)

Phase-II (2015)

Phase-III (Now)

Final (Target)

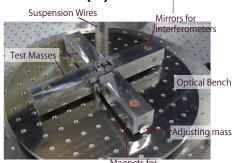
#### **Principle Test**

10<sup>-8</sup>/√Hz @ 0.1 Hz (Established)

- Room Temp.
- 25cm TM(s)



K. Ishidoshiro Ph.D Thesis



A. Shoda Ph.D Thesis

#### **Cryogenic Test**

**10**-15/**√Hz** @ 0.1 Hz (Design)

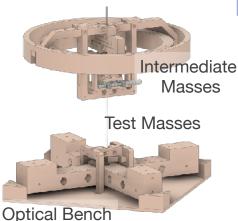
- Cryo. Temp. (4K)
- 35cm TMs

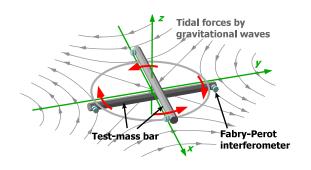
Goal 10<sup>-19</sup>/√Hz @ 0.1 Hz

- Cryo. Temp. (4K)

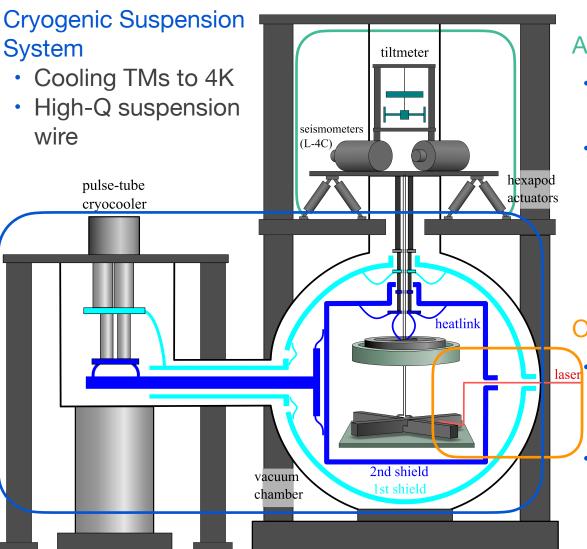
(Target)

- **10m** TMs





### Setup of Phase-III TOBA



#### **Active Vibration Isolation System**

- Reduction of vibration at the suspension point
- Reduction of vibration induced cryocooler

#### **Optical System**

- Rotation measurement by high-sensitive wave front sensor
- Beam jitter control in order to follow the incident beam to the optical bench

### **Cryogenic Suspension System**

#### Cryogenic Cooler

Cool down TMs to 4 K

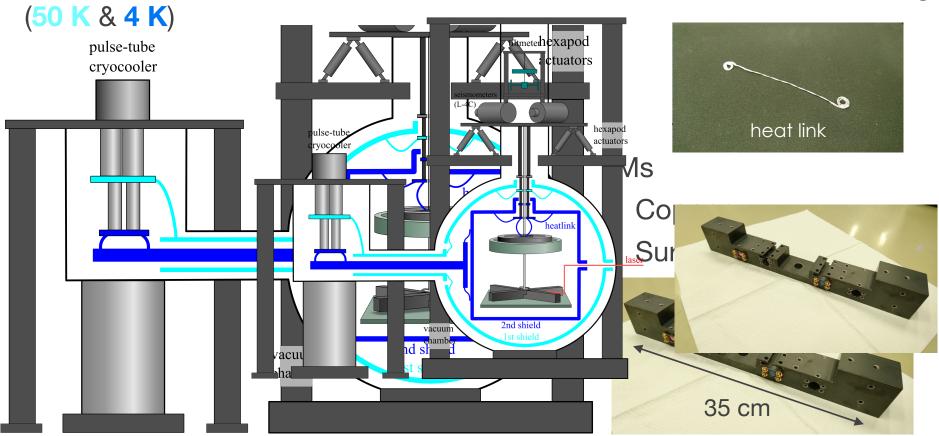
Two radiation shields

Suspension wire

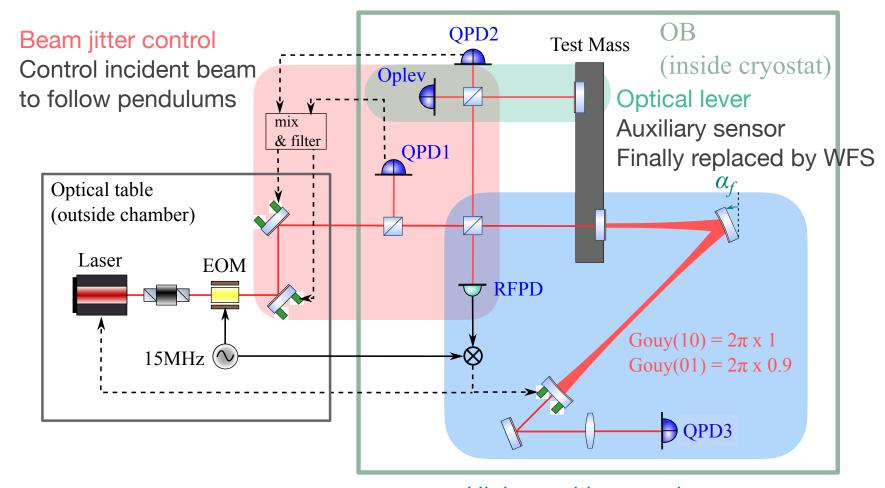
- Si wire
- High Q value (>108)

#### **Heat Links**

- High-purity aluminum
  - Conductive cooling



### **Optical System**



High sensitive angular sensor Measure HG10 mode induced by rotational motion

### **Active Vibration Isolation System**

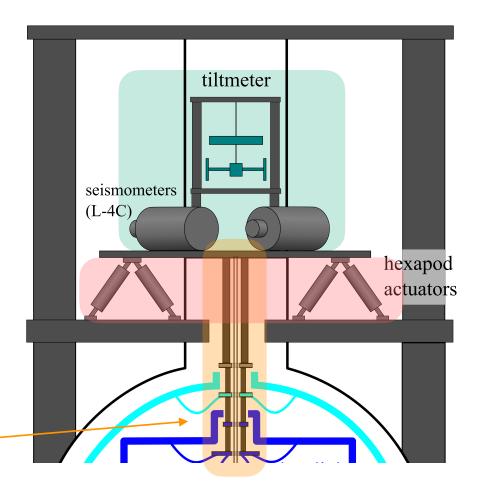
- Reduction of seismic vibration
  - Coupling from horizontal vibration
    - ► 10<sup>-7</sup> m/√Hz @ 0.1 Hz
  - Nonlinear coupling
    - ► 10<sup>-10</sup> m/√Hz @ 1 Hz

Measure motion at the suspension point by seismometer & tilt meter

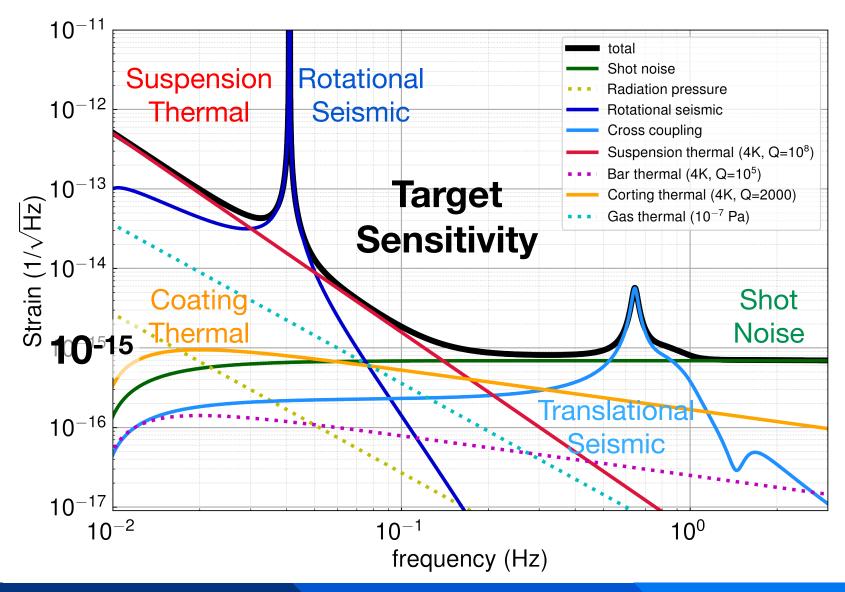


Feedback the signal to actuators to cancel out the motion

 Reduction of vibration induced by cooler



#### **Design Sensitivity**



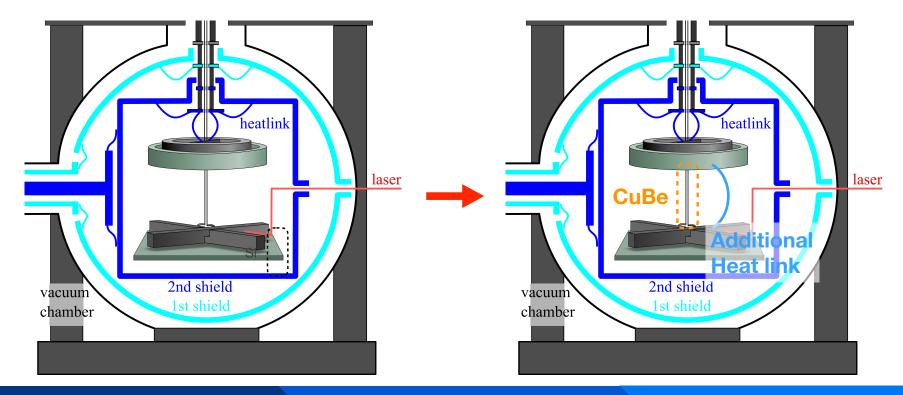
#### **Development Items**

- Cryogenic Suspension System
  - Cooling System
  - → High-Q suspension wire → Ching Pin's Poster (Sardinia, C4)
- Optical System
  - New angular sensor with higher sensitivity → Yuka's Poster
    (Corsica, C6)
- Active Vibration Isolation
  - Reduction of translational seismic noise
  - Reduction of vibration induced by cooler

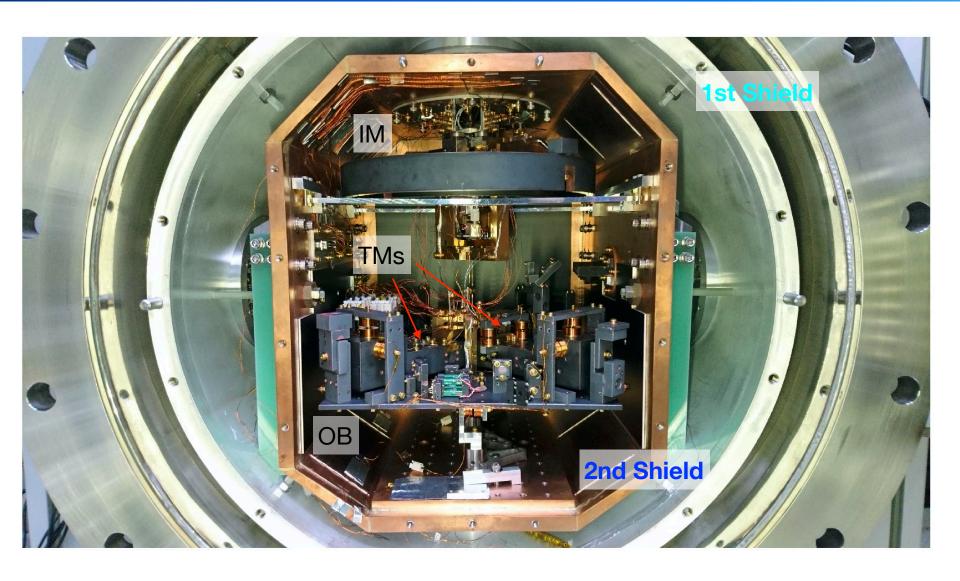
#### **Current Suspension System**

Test for cryogenic, simplified configuration

- Silicon fiber → CuBe wire
- Heatlinks between IM and TMs
- Readout: only optical levers

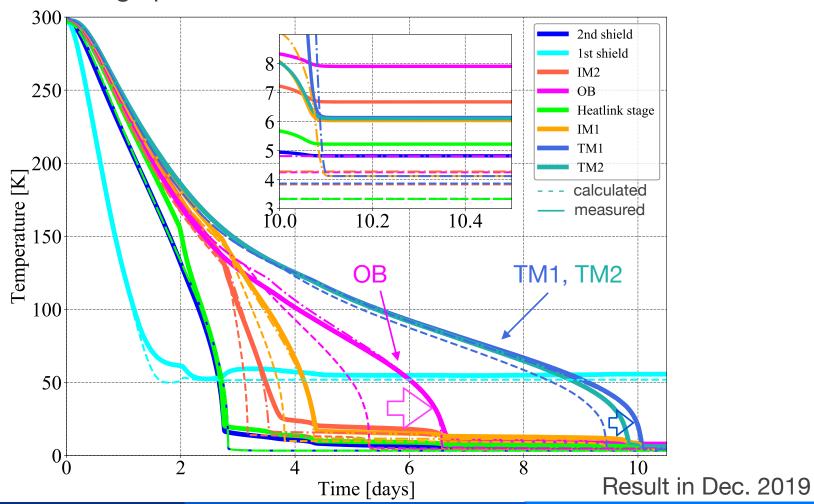


# **Current Setup**



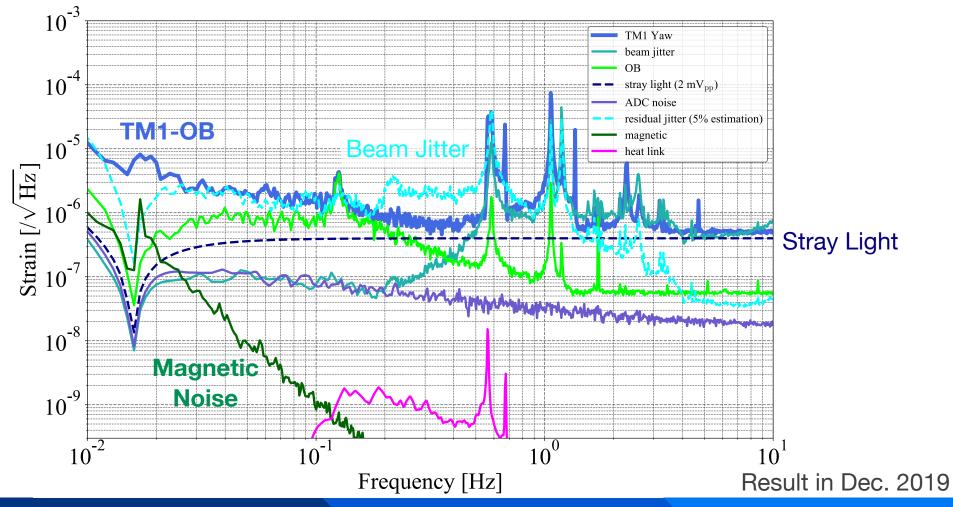
# **Cooling Result**

- Cool down to 6.1 K
- Slower cooling speed → Bad heat contact?

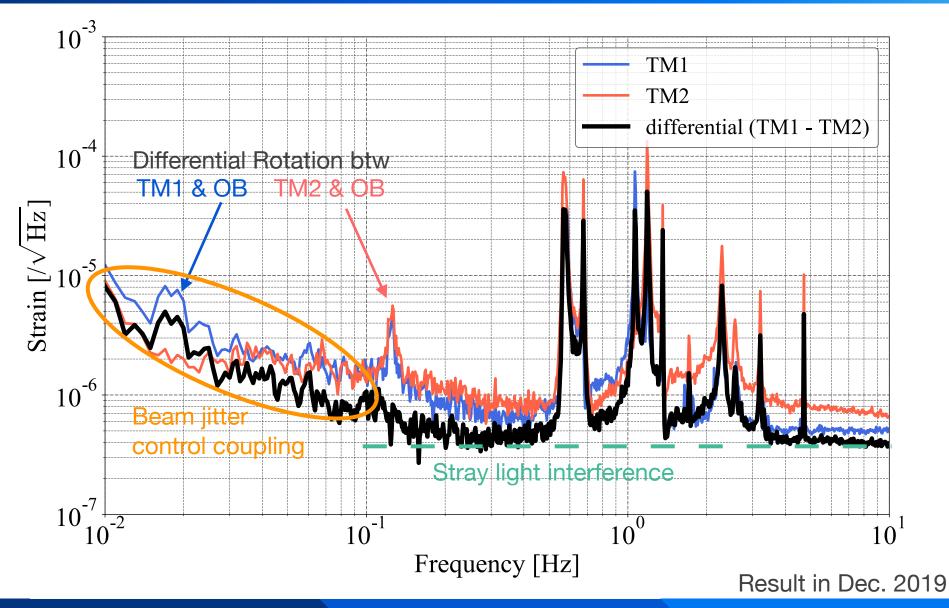


### **Sensitivity of one TM**

- Limited by beam jitter, interference of stray light
- Unexpected noise: magnetic noise due to eddy current flowing TM

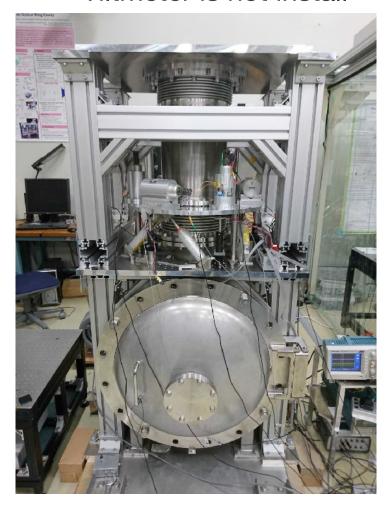


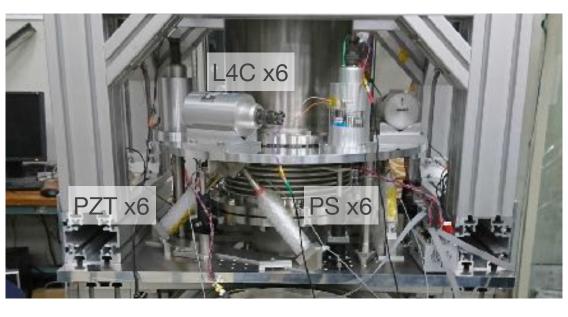
### Sensitivity of differential motion



#### **Active Vibration Isolation System**

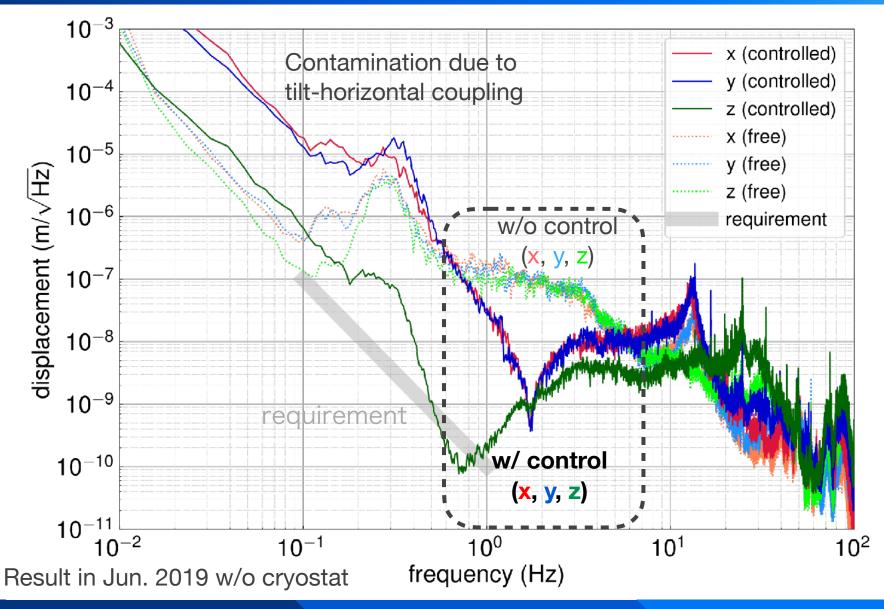
- Tested w/o the suspension and the cryostat
- Tiltmeter is not install





- Sensor: L4C (inertial) x6, PS (local) x6
- Actuator: PZT (range: ~60µm) x6

#### **Performance of AVIS**



#### **Current achievements**

- Cryogenic Suspension System
  - Cooling System
    - Succeeded in cooling doen to 6.1 K
    - Cooling speed is slower than expected
- Active Vibration Isolation
  - Reduction of translational seismic noise
    - Succeeded in controlling 3 DoF simultaneously
    - Need to decouple tilt from horizontal motion
  - Reduction of vibration induced by cooler
    - Test with cryostat

#### **Update Plans**

#### Next update:

Improvement of optical system, magnetic noise reduction

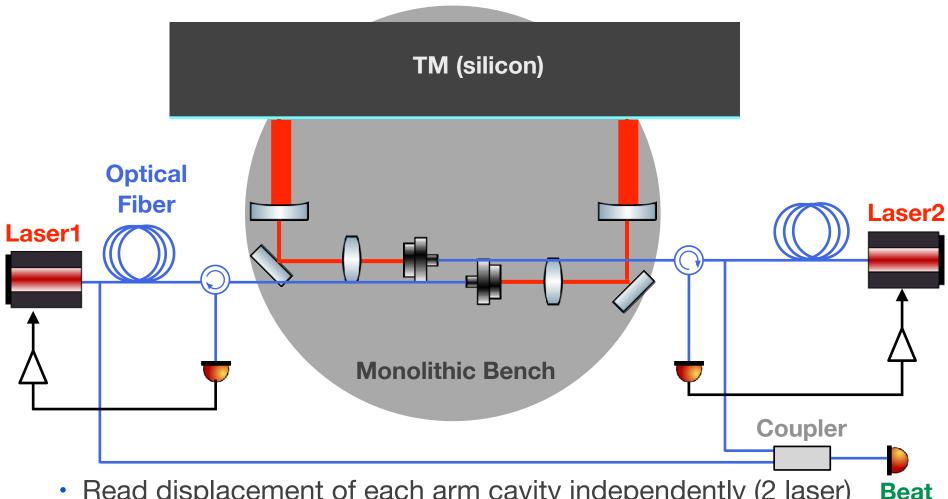
#### Mitigation of Magnetic noise

- Reduction of eddy current → silicon TM
  - Improvement of optical system & magnetic noise reduction

#### Improvement of optical system

- Introduce light to OB via optical fibers
- Make OB as a monolithic interferometer

### **Basic Optical Design**



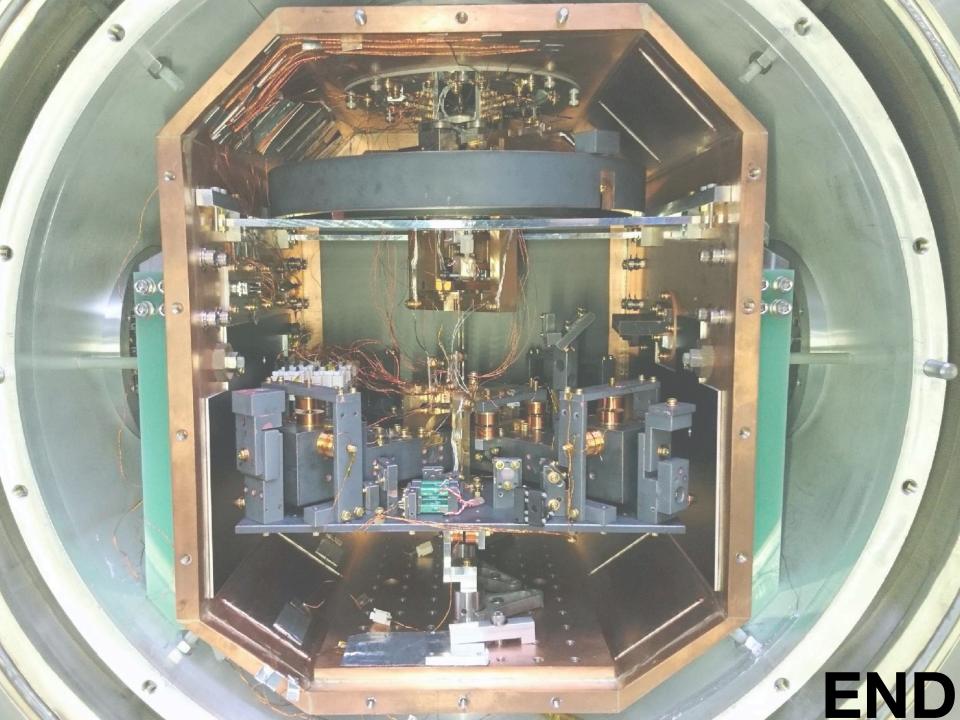
Read displacement of each arm cavity independently (2 laser)

- Feedback to each laser's frequency
- Measure beat frequency to read differential motion

**Signal** 

#### **Summary**

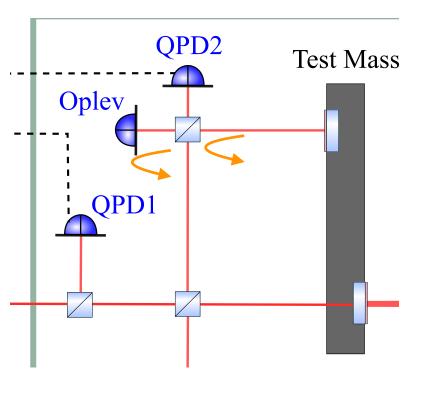
- Current achievement
- Oryogenic → basically demonstrated
  - Need some improvements (cooling speed, achieved temp.)
- Active isolation vibration → 3 DoF controlled
  - Decouple tilt motion from horizontal translation
- Update Plan
- Silicon TM
- Monolithic optical system
- On-going issues
- Development of high-Q silicon fiber
- Demonstration of coupled WFS



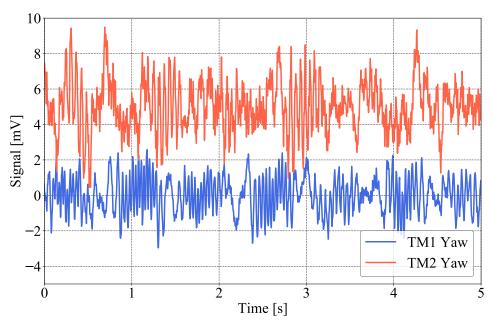
### **Stray Light Problem**

#### Front reflection at

- Cube BS
- QPD surface
  - Stray light

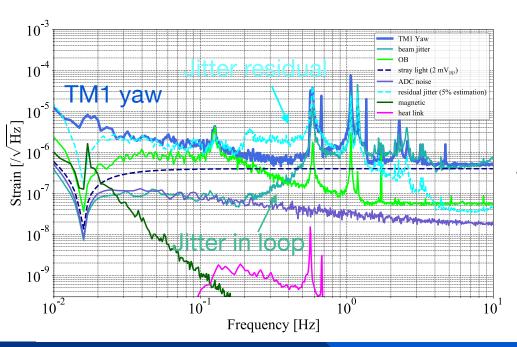


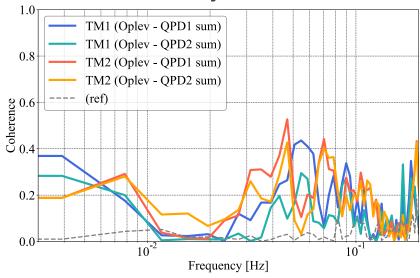
# Interference with stray light contaminates oplev signal



- Some coherence btw TM oplev yaw & Jitter QPD sum
  - Beam jitter control signal shakes beam additionally
  - Contaminates oplev signal

Coherence btw TM oplev yaw & QPD sums





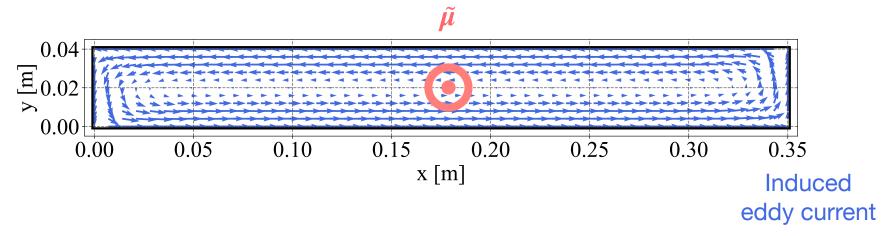
5% residual assumption

can be explained the noise budget well

### **Magnetic Noise Due to Eddy Current**

- Ambient magnetic fluctuation induces eddy current
  - TM has magnetic dipole moment \( \tilde{\mu} \)

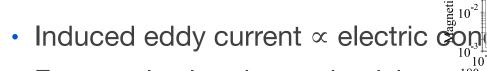
Induced magnetic dipole moment



This  $\tilde{\mu}$  induces torque noise  $\tilde{\mu} \times B$  with DC magnetic field B

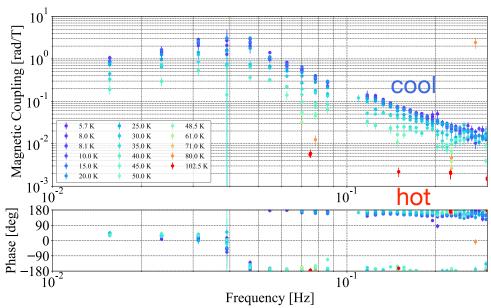
## Magnetic Noise Due to Eddy Current

45.0 K

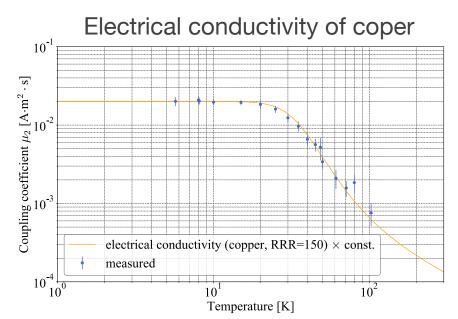


· For metals electric conductivity gets larger when cooled down

► Coupling gets larger at lower temperature



Transfer function from magnetic fluctuation to TM yaw



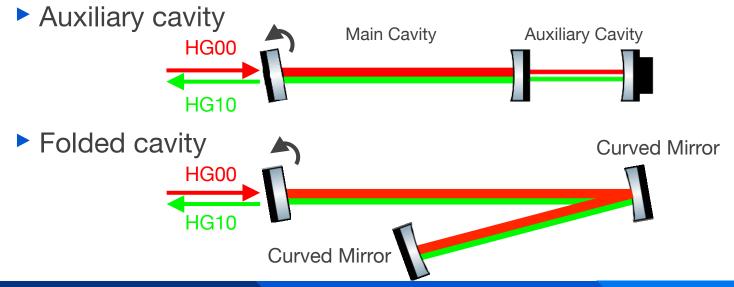
Frequency [Hz]

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### **High Sensitive Angular Sensor**

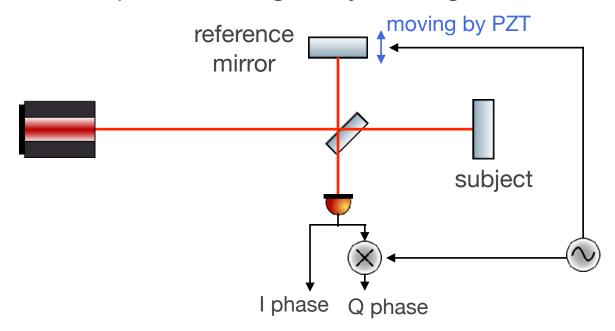
Cavity-enhanced wave front sensor (new idea)

- Compensate Gouy phase difference between HG00 and HG10
  - HG10 mode resonates as well as HG00
  - Induced HG10 is enhanced
  - ► Higher sensitivity than normal WFS 5×10<sup>-16</sup> rad/√Hz @ 0.1 Hz
- How to compensate



#### **Local Quadrature Interferometer**

- Quadrature Interferometer for a local sensor of AVIS
- Michelson interferometer with a dithered reference mirror
  - Resolution: same as Michelson interferometer
  - Range: ∞ (ideally)
- No polarization optics
- Generate quadrature signal by moving reference mirror



# **Picture**



#### **Performance**

