



## MCP based detectors – short introduction

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## The Detector "identity chart"

### Fundamental Questions :

Which kind of "particle" we have to detect?

Electrons/Photons/Ions

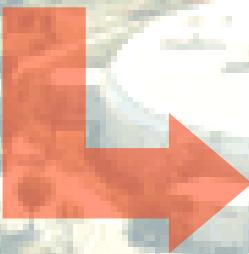


Main particle "properties" (energy, dimensions...)

Which is the required dimension of the detector?

10 – 100 cm<sup>2</sup>

Which "property" of the particle we have to know?



Position?

Yes

Time?

Yes

Number

Yes

Energy

No

Polarity

No

Resolution? Single count

Which is the maximum count rate?

$\sim 10^6$ -  $10^7$  Counts/s

Which is the "events time distribution"?

Poissonian distribution



## CHANNEL ELECTRON MULTIPLIERS

MULTIANODES  
DETECTORS

BI-DIMENSIONAL  
DETECTORS

CENTROID  
FINDING POSITION  
DETECTORS

CROSS DELAY  
ANODES  
DETECTOR

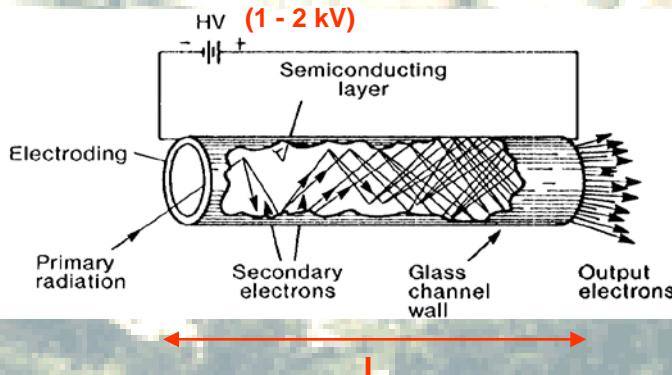
## Charge Electron Multipliers (CEM)

Single photon/electron detection  
requires charge amplification



### Channel Electron Multipliers (CEM)

devices that produce at their exit a cloud of some million electrons  
for each entering electron, thus producing a measurable charge



length to diameter ratio ( $L/D$ ) that ranges  
generally from 40 to 100

## CHANNEL ELECTRON MULTIPLIERS

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# Charge Electron Multipliers (CEM)

Generally they present particular shapes to  
reduce “ion feedback”



ions are accelerated up the channel  
by the electric field and can strike  
the CEM walls near the input face  
(ion feedback) releasing electrons  
and causing a secondary electron  
avalanche totally indistinguishable  
from “real” events

The spirals and the curved surfaces  
avoid that these ions gain enough  
kinetic energy to produce the  
secondary emission when they  
strike the walls



## CHANNEL ELECTRON MULTIPLIERS

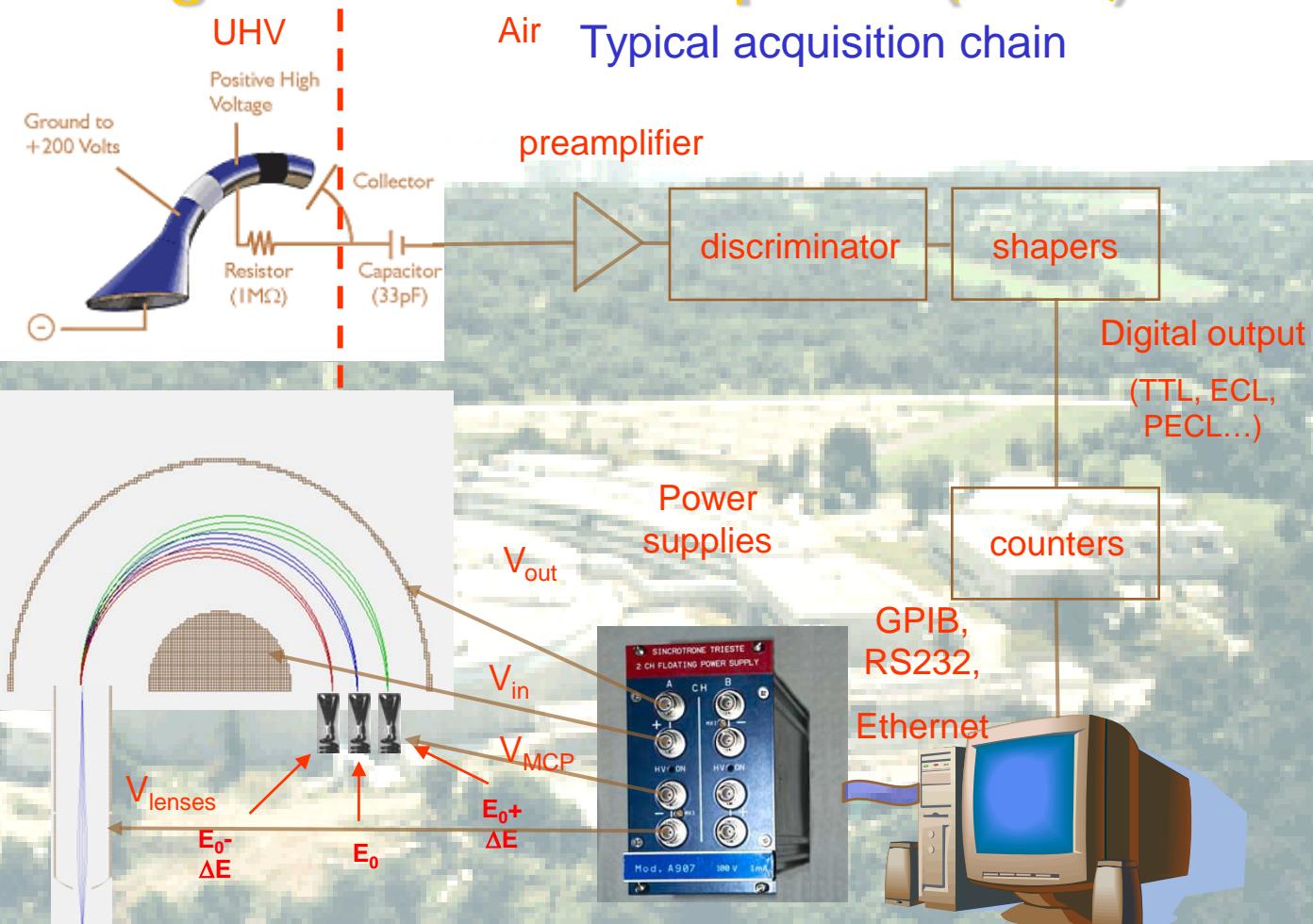
MULTIANODES  
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BI-DIMENSIONAL  
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## Charge Electron Multipliers (CEM)



CEM dimensions limit the maximum number of channels



## CHANNEL ELECTRON MULTIPLIERS

MULTIANODES DETECTORS

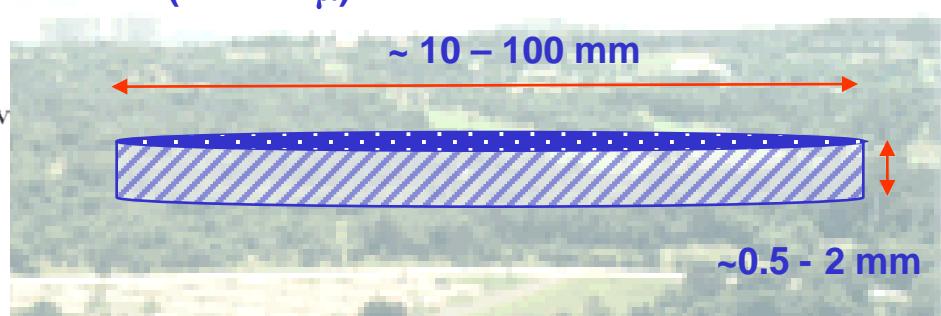
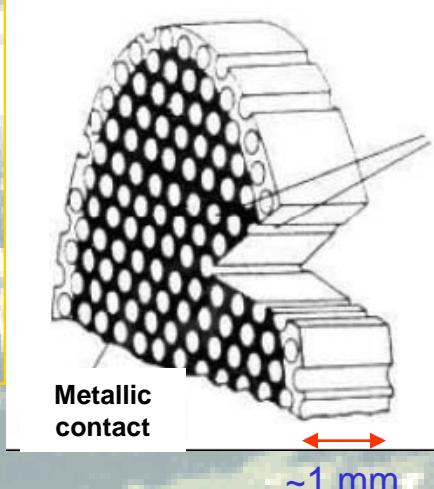
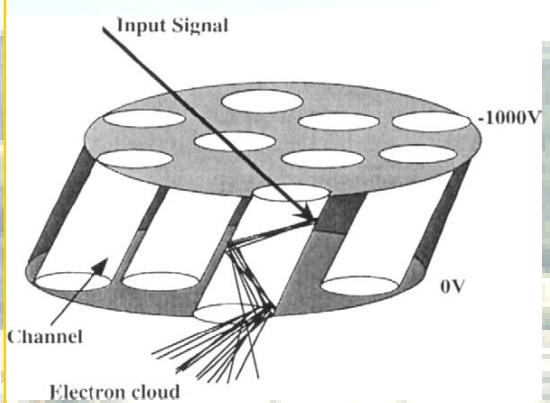
BI-DIMENSIONAL DETECTORS

CENTROID FINDING POSITION DETECTORS

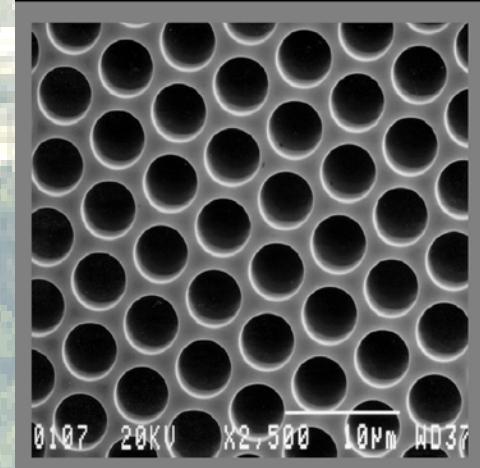
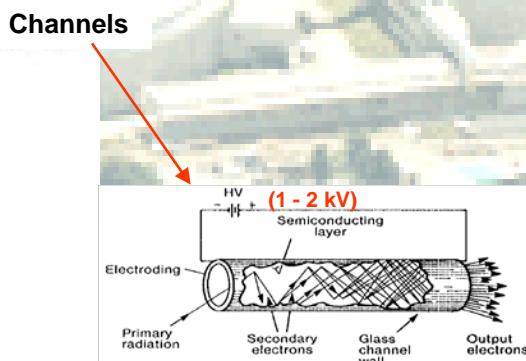
CROSS DELAY ANODES DETECTOR

## We need different kind of charge multipliers: Microchannel Plates (MCP)

Essentially MCPs are thin (~ 1 mm), silicon-lead oxide glass wafers composed of a large number ( $> 10^5 \text{ cm}^{-2}$ ) of small (~2 – 15  $\mu$ ) CEM tubes called microchannels



The MCPs are available in round or rectangular shapes with surface areas as high as  $100 \text{ cm}^2$  and channel length to diameter ratios in the range from 40 to 150





## Microchannel Plates and multianode detectors

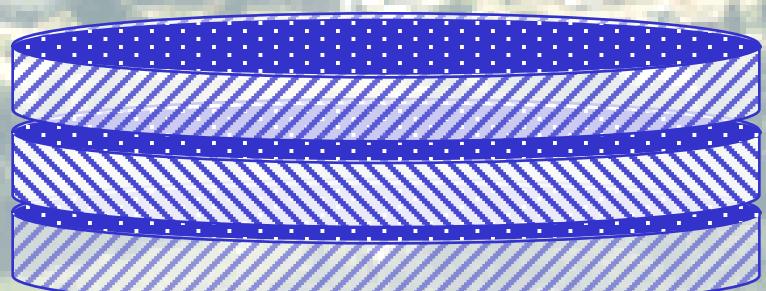
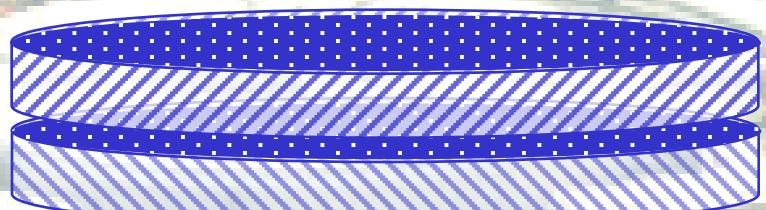
Typical gain of a single MCP disk:  $10^3$  –  $10^4$

Still not enough!

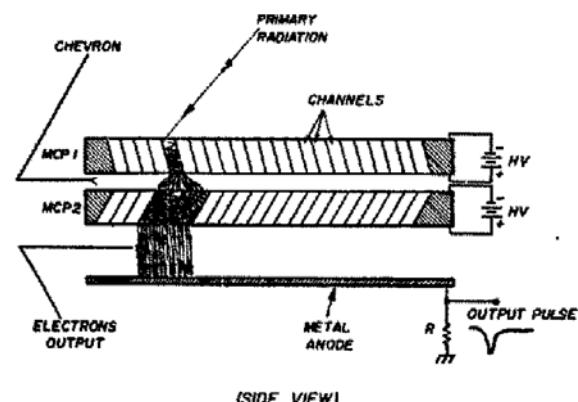


We require more amplification stages

2 MCP: Chevron assembly



3 MCP: Z-Stack assembly



The “zig-zag” of tilted channels reminds the curves of CEM and the goal is the same: to reduce ion feedback



CHANNEL  
ELECTRON  
MULTIPLIERS

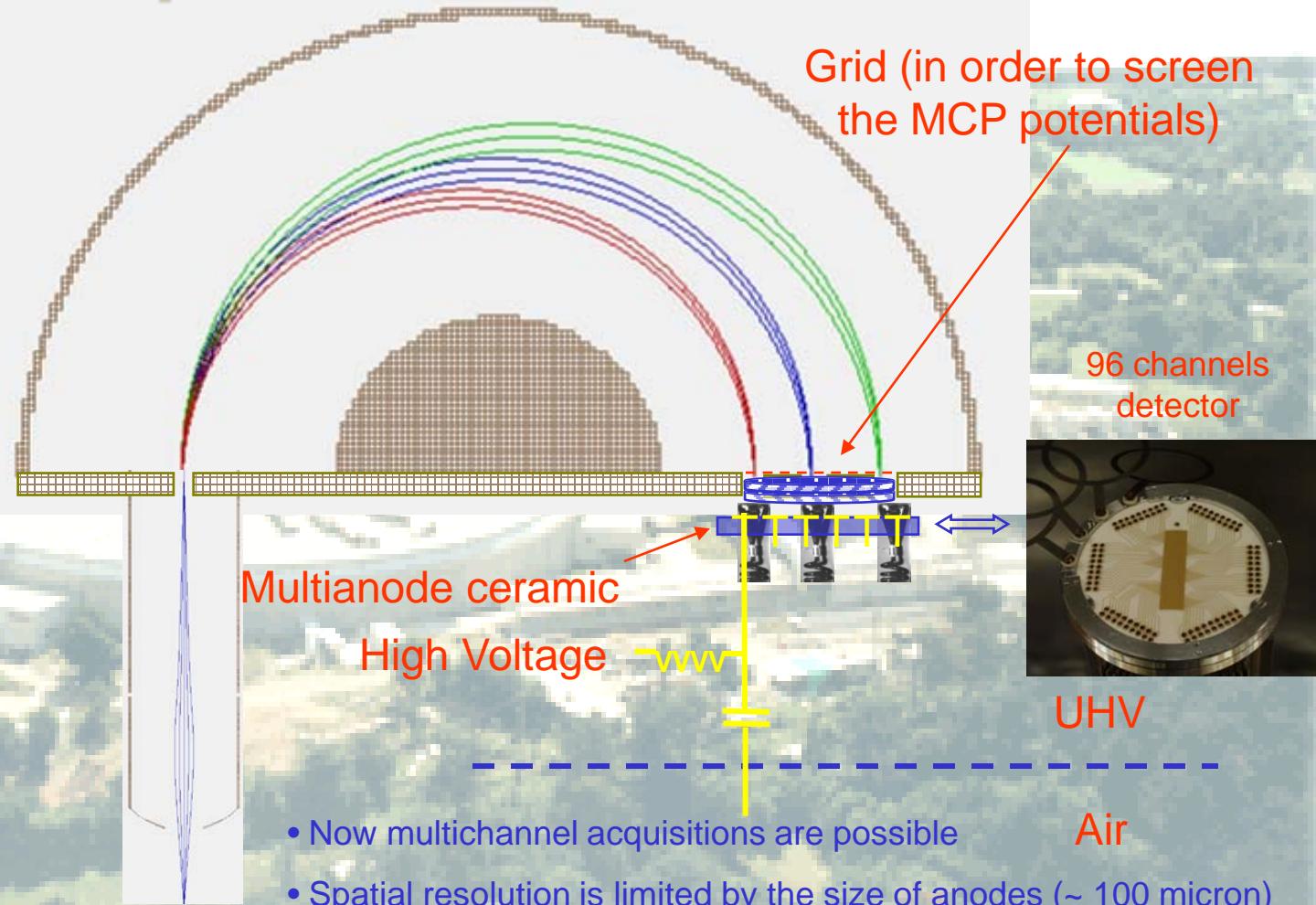
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## Microchannel Plates and multianode detectors: the acquisition chain



## Microchannel Plates and multianode detectors – weak points

Many preamplifiers,  
discriminators etc.

CHANNEL  
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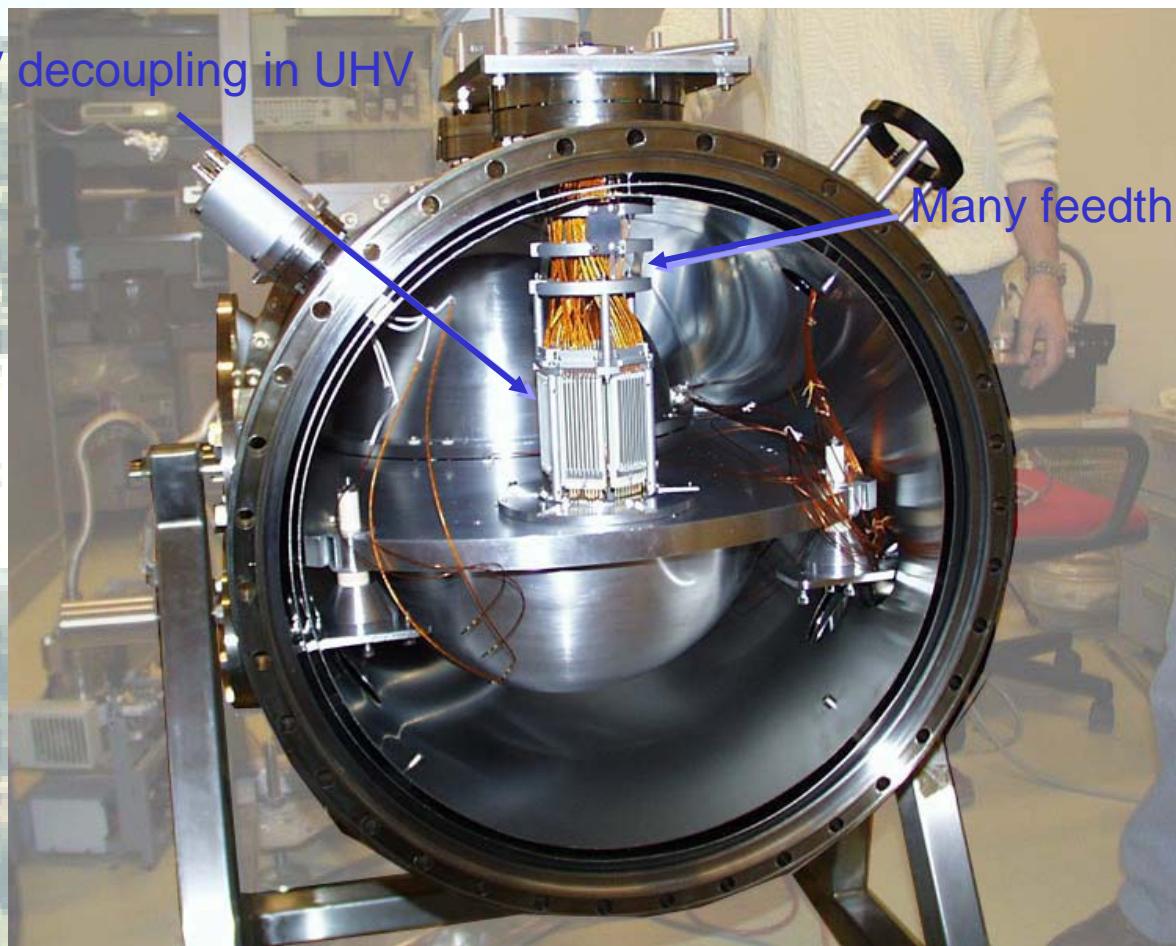
BI-DIMENSIONAL  
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HV decoupling in UHV

Many feedthroughs



Very difficult to manage more than 100 anodes



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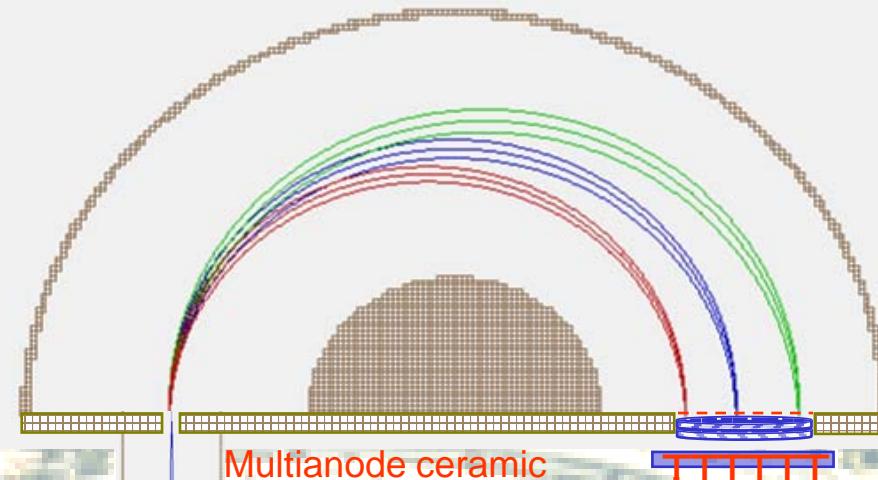
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## Microchannel Plates and multianode detectors: the VLSI solution



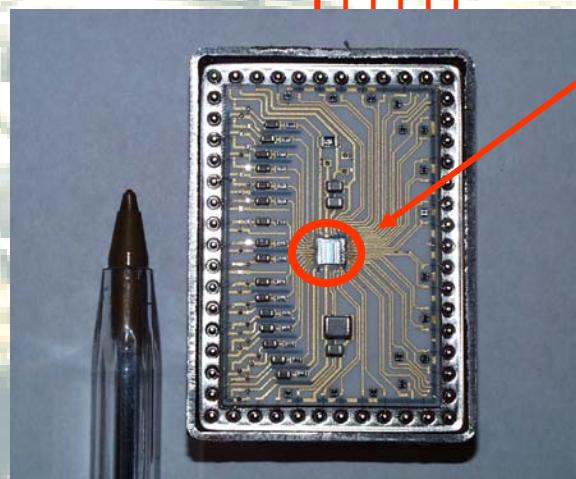
Very Large Scale of  
Integration circuit

Or

Application Specific  
Integrated Circuit  
(ASIC)

16 preamplifiers,  
discriminators,  
shapers, PECL  
drivers

UHV  
Air





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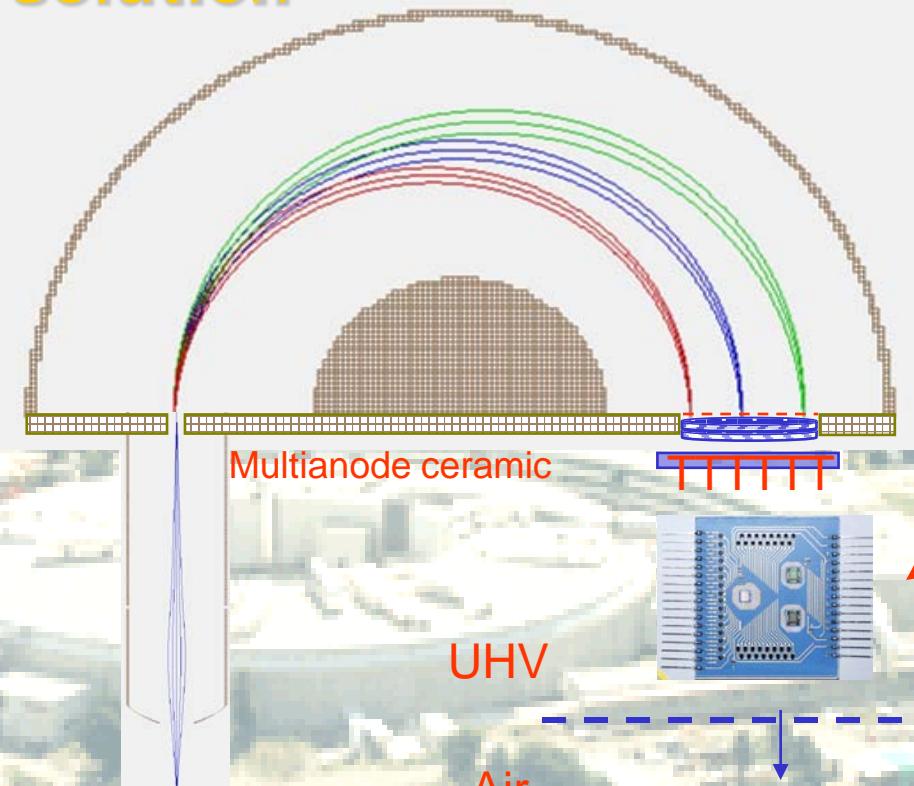
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## Microchannel Plates and multianode detectors: the **VLSI** solution



Very Large Scale of  
Integration circuit

Or

Application Specific  
Integrated Circuit  
(ASIC)

16 preamplifiers,  
discriminators,  
shapers, PECL  
drivers

&

16 counters + fast  
serial conversion

Just one feedthrough to extract all counts

Very low noise

Up to > 800 channels (well resolved snapshot peaks)

Fully parallel system → very high count rate



## Microchannel Plates and multianode detectors: the VLSI solution (blind sides)

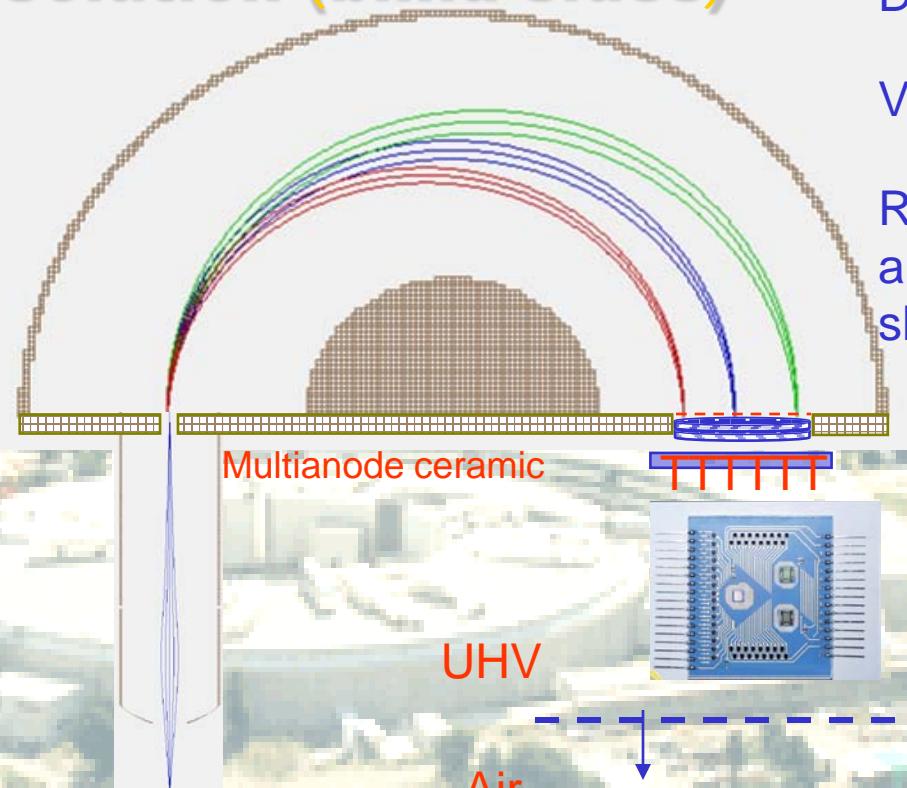
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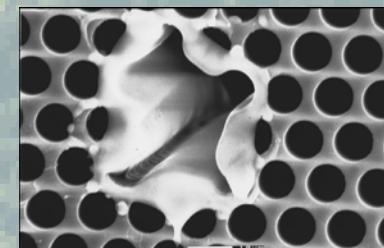
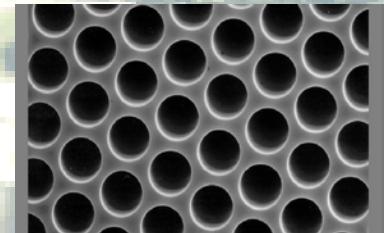
CROSS DELAY  
ANODES  
DETECTOR



Dramatically fragile

Very expensive

Requires digital and  
analogue VLSI developing  
skill

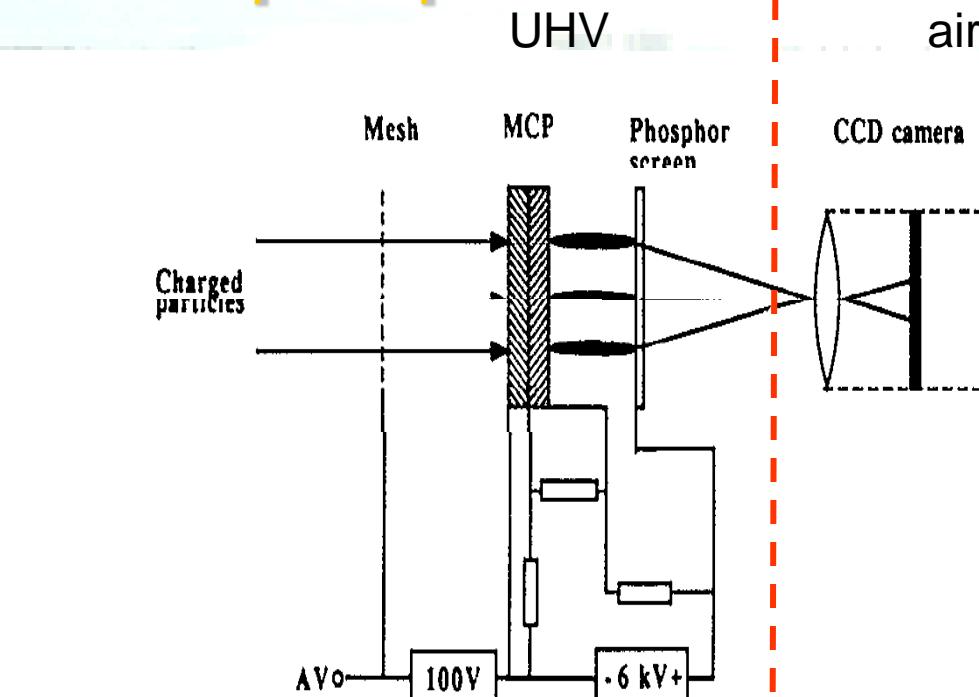


**And it is not a bi-dimensional detector!**



## Bi dimensional detectors - first simple solution:

MCP + phosphor + CCD



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Simple

Not very expensive but...

No feedthroughs

Not linear

It doesn't work in "counting mode"

Noisy (thermal noise, read noise...)

Useless if time resolution is required

Frame grabber  
board





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## Bi dimensional detectors – other possible solutions:

Brute force:

We can try the VLSI approach developing a matrix of pixels, each pixel followed by the mixed analogue - digital ASIC etc.

“Pixel detectors”

Too expensive! In terms of

Money

Time

Resources

Very brittle

Cunning trick:

We can derive individual event positions either with continuous readout anodes, or discrete element anodes with **interpolation** to provide a continuous position readout



Centroid finding detectors



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## Bi dimensional detectors – centroid finding detectors

Electrons clouds from MCP present a symmetrical Gaussian charge distribution



If we are able to find the centroid of this charge in principle the spatial resolution is limited by the pore dimensions of the (top) MCP!



Charge Division Centroiding  
approach:

The MCP output charge is divided among several output terminals in a way that the relative amplitudes depend upon the event position



Delay Line      Centroiding  
approach

Event position centroids are found by determination of the difference in arrival times of the event signal at the two (or four) ends of one (or two) high speed transmission line(s)

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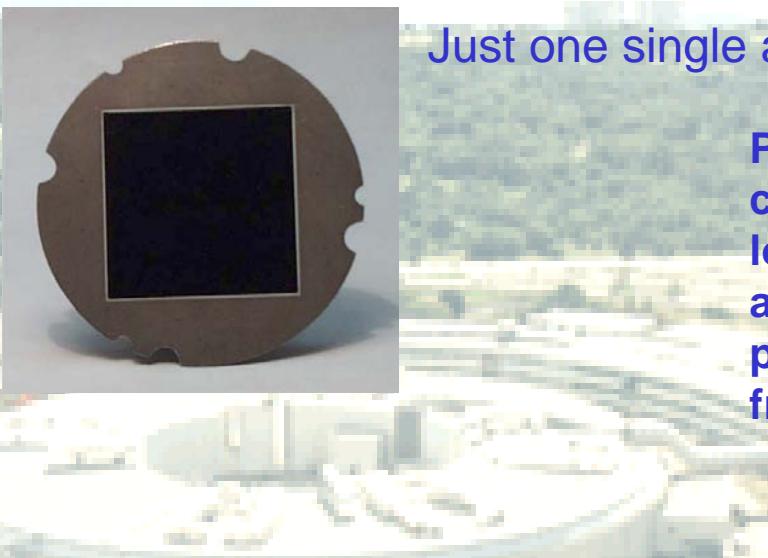
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## Bi dimensional detectors – centroid finding detectors

The most popular charge division centroid finding detector:  
the **resistive anode detector**

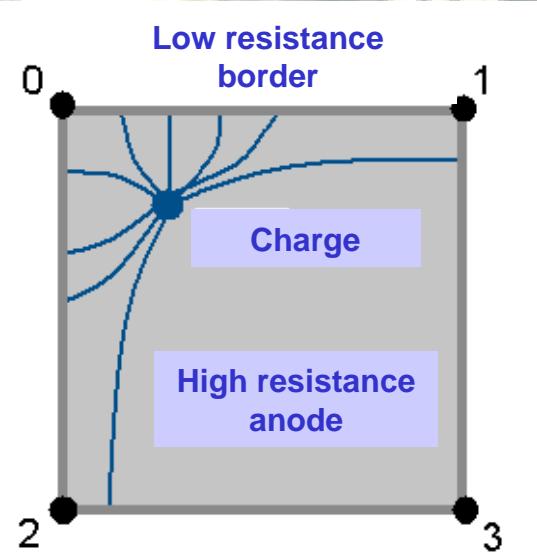


Just one single anode and 4 contacts!

Propagation of charge to the contacts from the event location gives pulse amplitudes that are proportional to the distance from the contact.

$$x = \frac{(Q_A + Q_B) - (Q_C + Q_D)}{Q_A + Q_B + Q_C + Q_D}$$

$$y = \frac{(Q_A + Q_D) - (Q_B + Q_C)}{Q_A + Q_B + Q_C + Q_D}$$



# Bi dimensional detectors – centroid finding detectors

The most popular charge division centroid finding detector:  
the **resistive anode detector** – acquisition chain

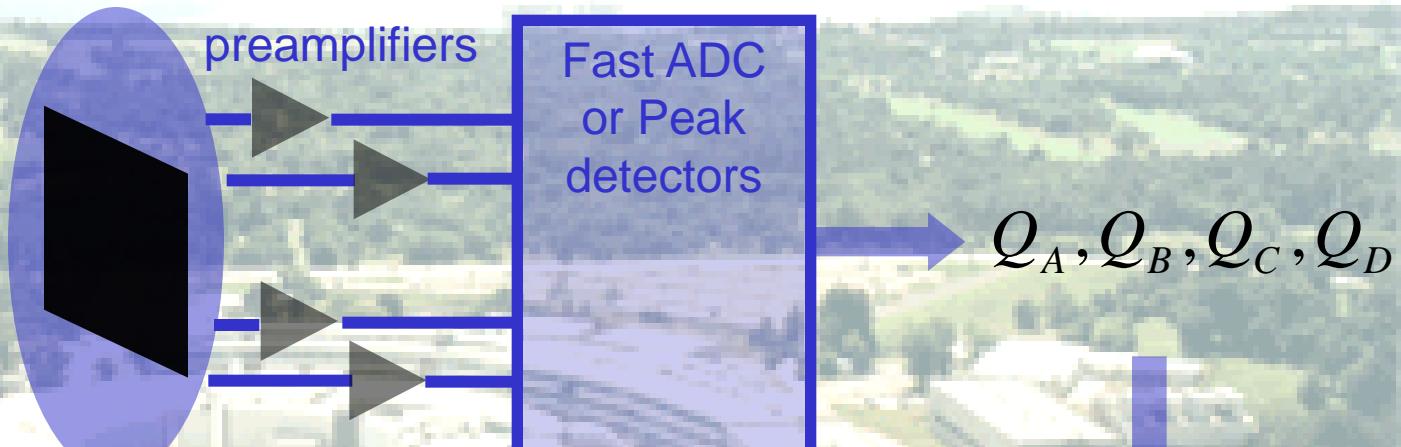
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$$y = \frac{(Q_A + Q_B) - (Q_C + Q_D)}{Q_A + Q_B + Q_C + Q_D}$$

$$x = \frac{(Q_A + Q_C) - (Q_B + Q_D)}{Q_A + Q_B + Q_C + Q_D}$$

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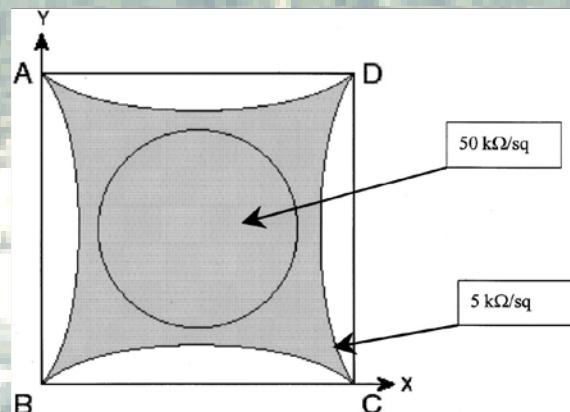
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## Bi dimensional detectors – centroid finding detectors

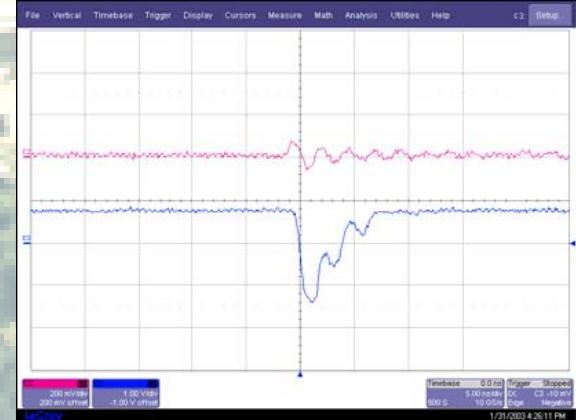
The most popular charge division centroid finding detector:  
the **resistive anode detector** – weak points

Particular shapes and specific ratio between anode and borders resistance are necessary in order to reduce distortions



Not great performances in terms of spatial resolution and count rate

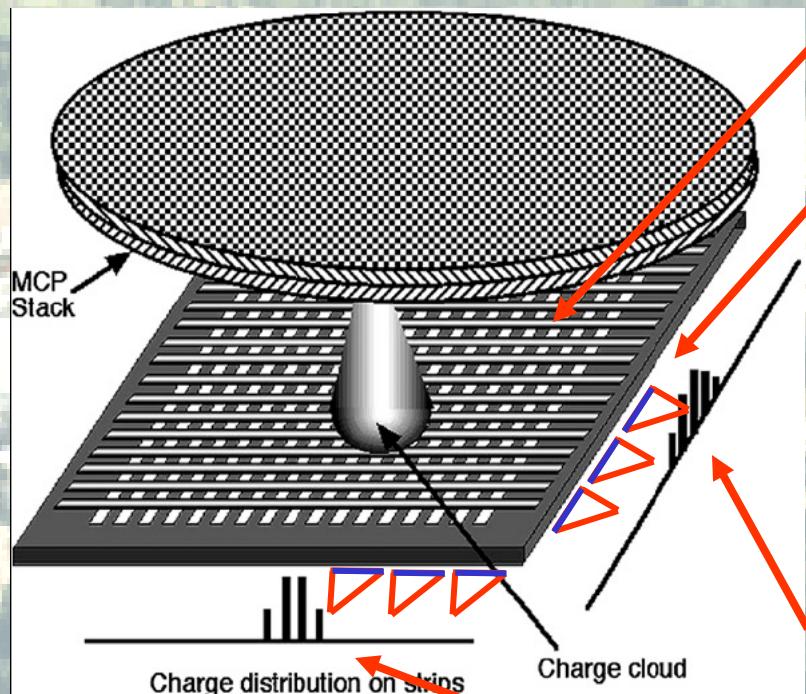
Reflections at the borders are always present when the impedance is not matched



## Bi dimensional detectors – centroid finding detectors

A second charge division centroid finding detector: the cross anodes detector

Several crossed anodes are the detector



each anode is connected to a “preamplifier + ADC” block that acquires the pulses

measuring the charge repartition among the anodes it is possible to know the centroid with very high resolution (~ micron).

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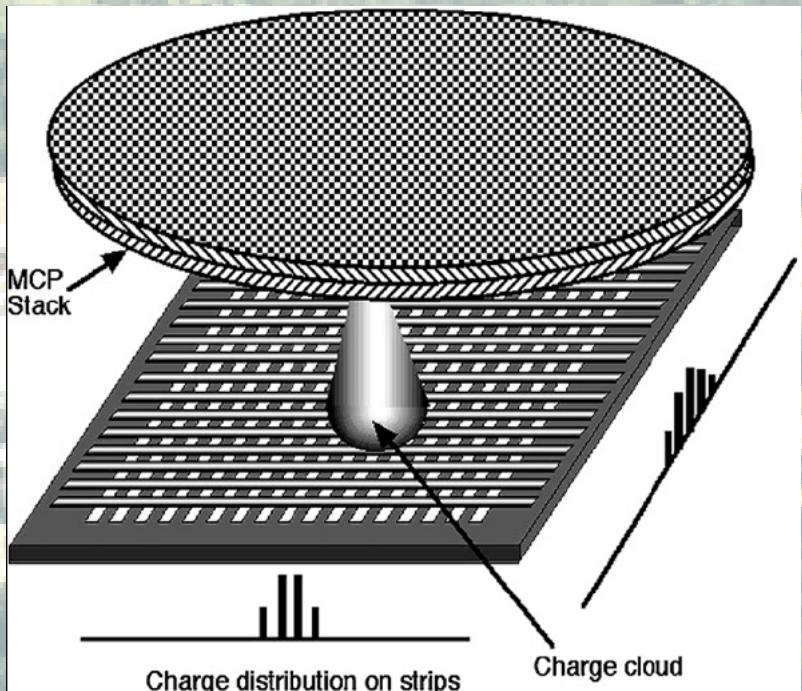
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## Bi dimensional detectors – centroid finding detectors

A second charge division centroid finding detector: the  
**cross anodes detector**



- Many preamplifiers ADC etc.



ASIC is required

- Count rate limited by the system complexity

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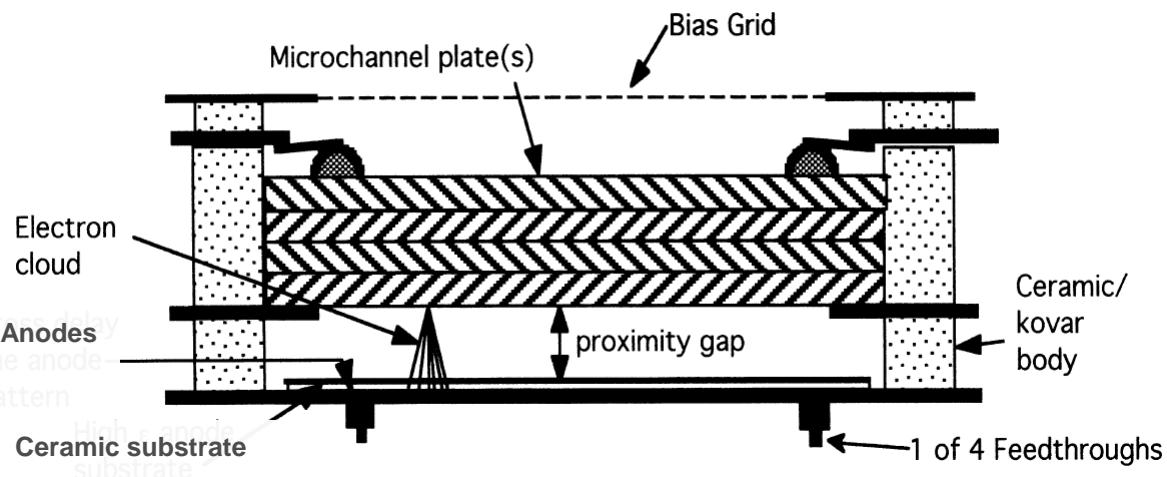
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## Bi dimensional detectors – centroid finding detectors

- Charge division centroid finding detector many other different shapes (Wedge & strip, Backgammon, Spiral anode...) but the principle is always the same: the position is extrapolated from the pulse electron charge distribution
- The “MCP + centroid finding detector” assembly is different from the “MCP + multianode detector”: now we want that the electron cloud spread over more anodes in order to calculate the centroid





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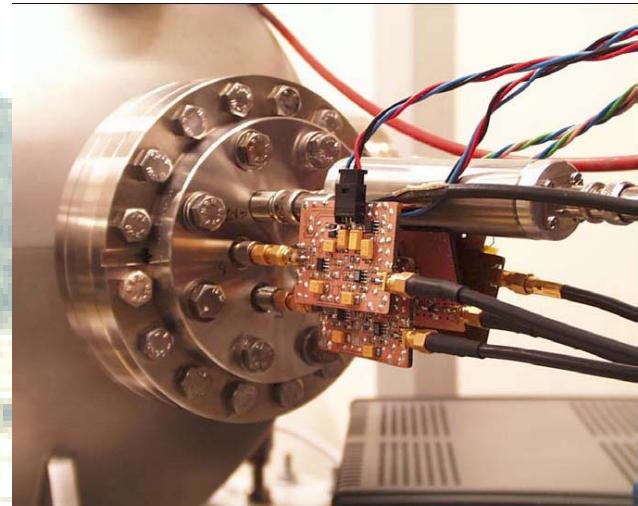
CROSS DELAY  
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## Bi dimensional detectors – centroid finding detectors



But...

ATTENTION !



We pay the extreme simplification of the architecture in terms of count rate!

1 MCounts/s (for example) is the GLOBAL count rate;

This is an other way to say that the dead time of the detector is 1 microsecond.

But REAL counts are NOT uniformly distributed in time: a “MCount/s” detector starts to show non linearity already at 200 KCounts/s



## Bi dimensional detectors – centroid finding detectors

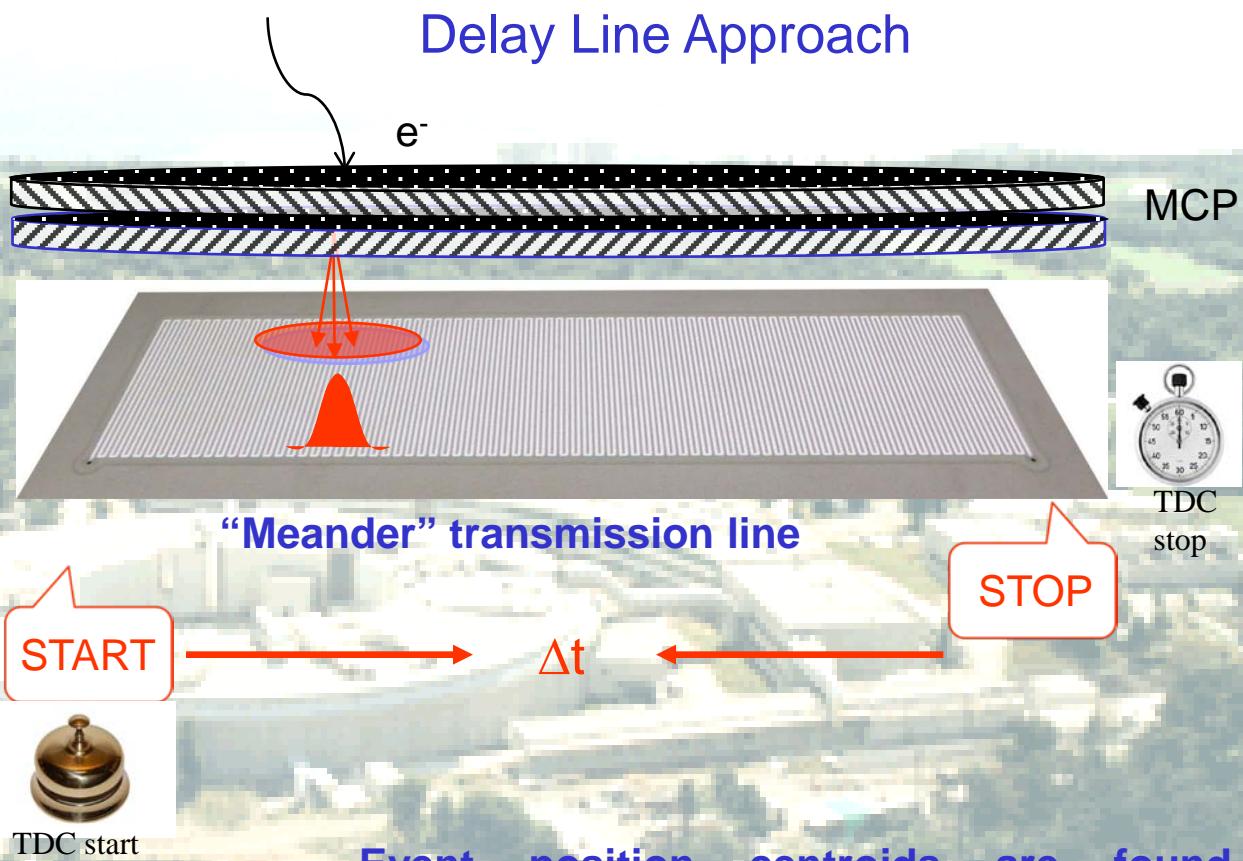
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Event position centroids are found by determination of the difference in arrival times of the event signal at the two (or four) ends of one (or two) high speed transmission line(s)



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## Bi dimensional detectors – centroid finding detectors

Delay Line Approach: the detector and the acquisition chain (now it is a bit more complicate...)

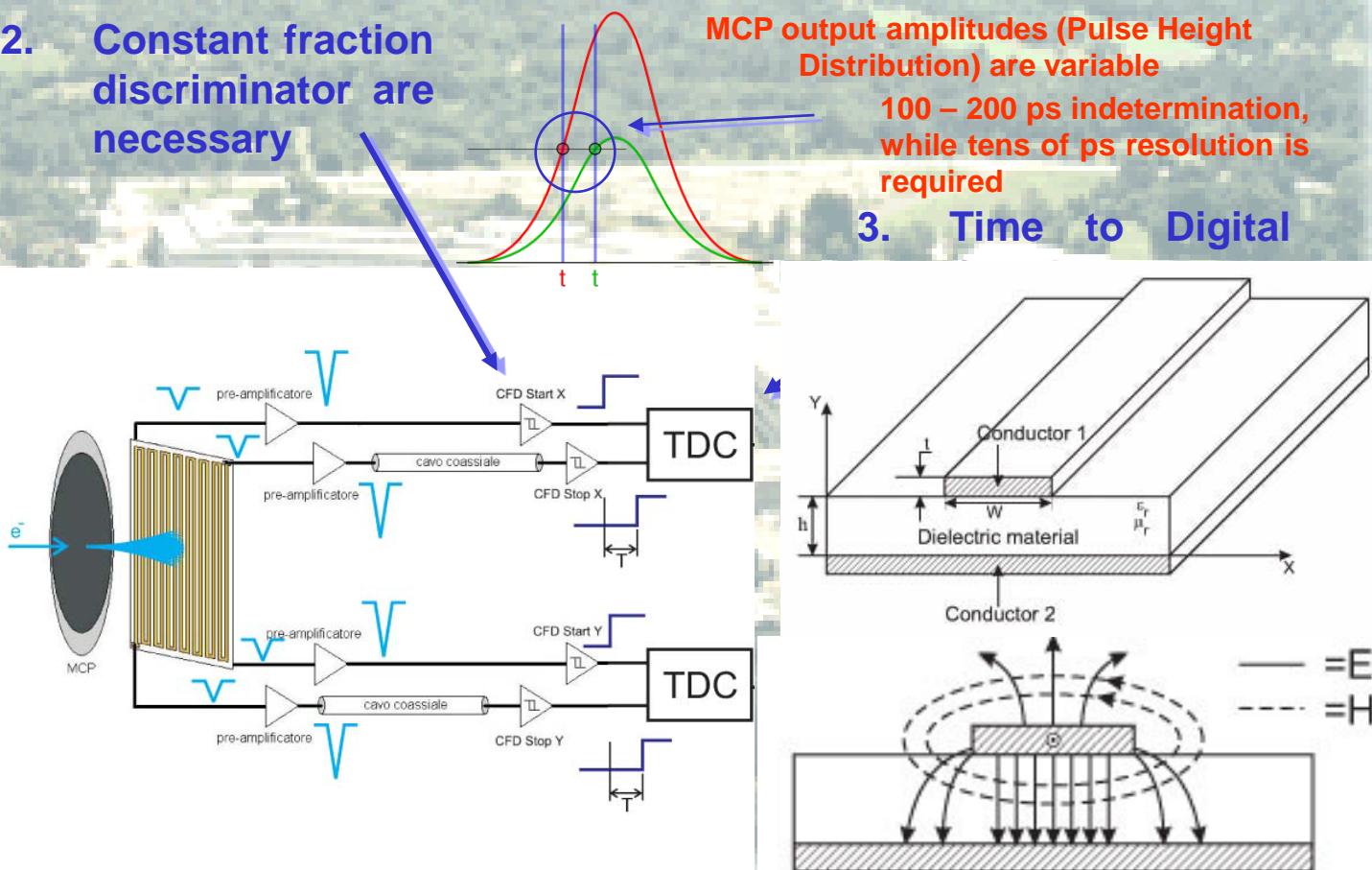
1. Anodes impedance matching is fundamental

2. Constant fraction  
discriminator are  
necessary

MCP output amplitudes (Pulse Height Distribution) are variable

100 – 200 ps indetermination,  
while tens of ps resolution is  
required

3. Time to Digital





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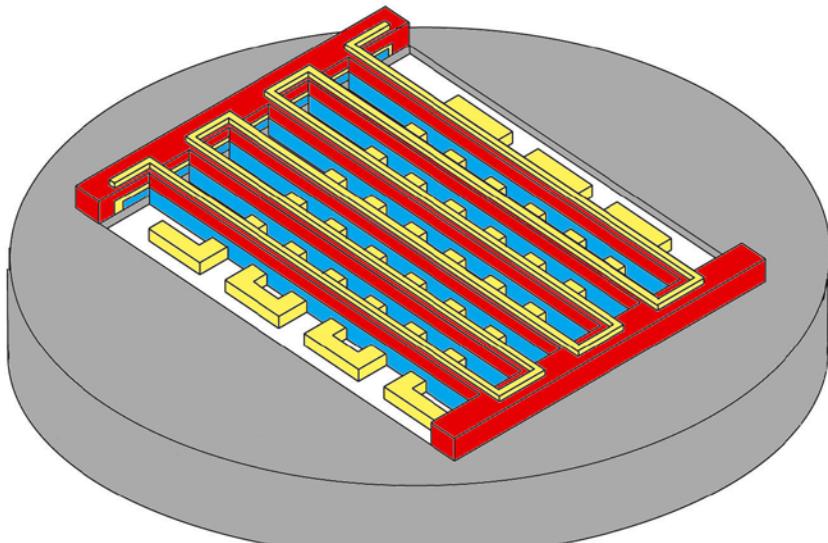
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## Bi dimensional detectors – centroid finding detectors

Delay Line Approach: the acquisition chain  
(now it is a bit more complicate...)

50 Ohm impedance  
matching is fundamental,  
but in case of cross delay  
line is very difficult to  
achieve





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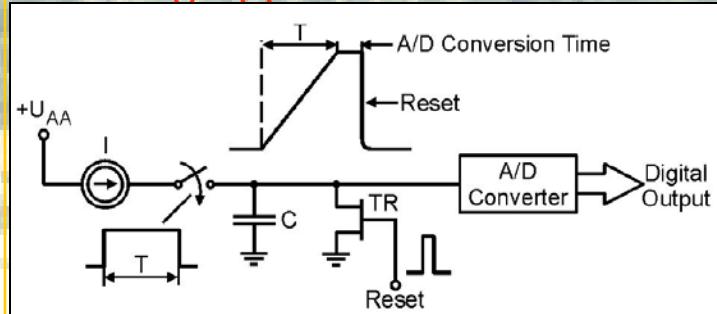
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## Bi dimensional detectors – centroid finding detectors

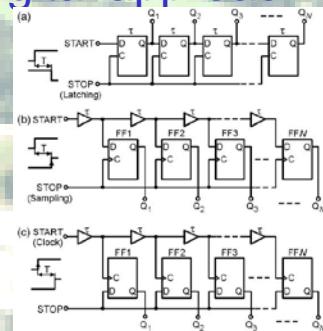
Delay Line Approach: The Time to Digit Converter (TDC)

Analog approach



Great time resolution (few ps) but  
Slow (~1MCount/S)  
Time resolution depend on the  
total time window

Digital approach



Digital TDC works exploiting the known delay propagations times on dedicated digital VLSI

Worse time resolution (20 – 30 ps) but  
Very fast (up to 100 MCount/s)  
Time resolution worsens slowly with the total time window



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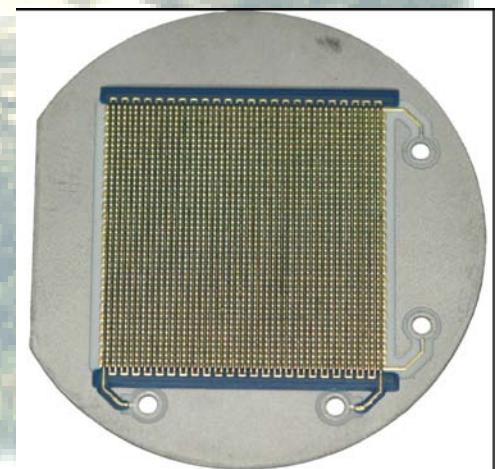
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## Bi dimensional detectors – centroid finding detectors

### Delay Line Approach: Strength and weakness

- The “time resolution” is immediate: the time information is intrinsically present, because it is required for the spatial encoding
- Counting time is limited only by the delay line propagation time
- No image distortions
- Difficult to develop the anode (impedance matching etc.)
- Acquisition electronic is complicate



## Time resolved acquisition – first example: TOF (Time Of Flight)

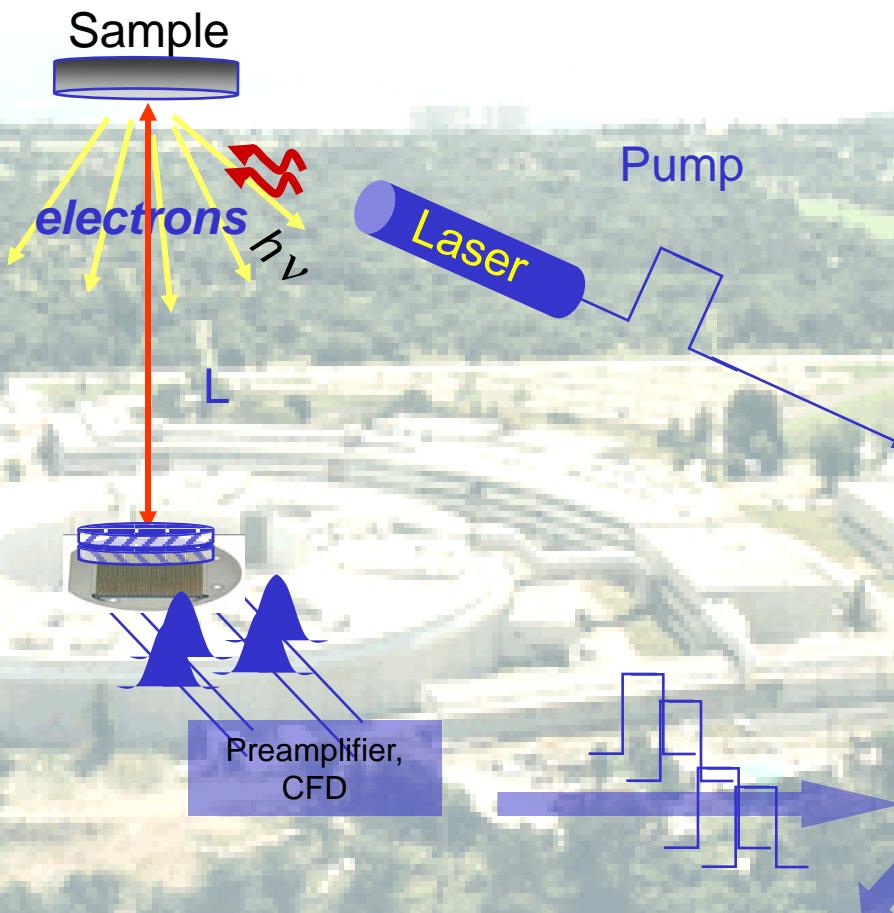
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From the known propagation time of the delay line T and length distance L (sample – detector) we associate the energy to the position



## Time resolved acquisition: second example

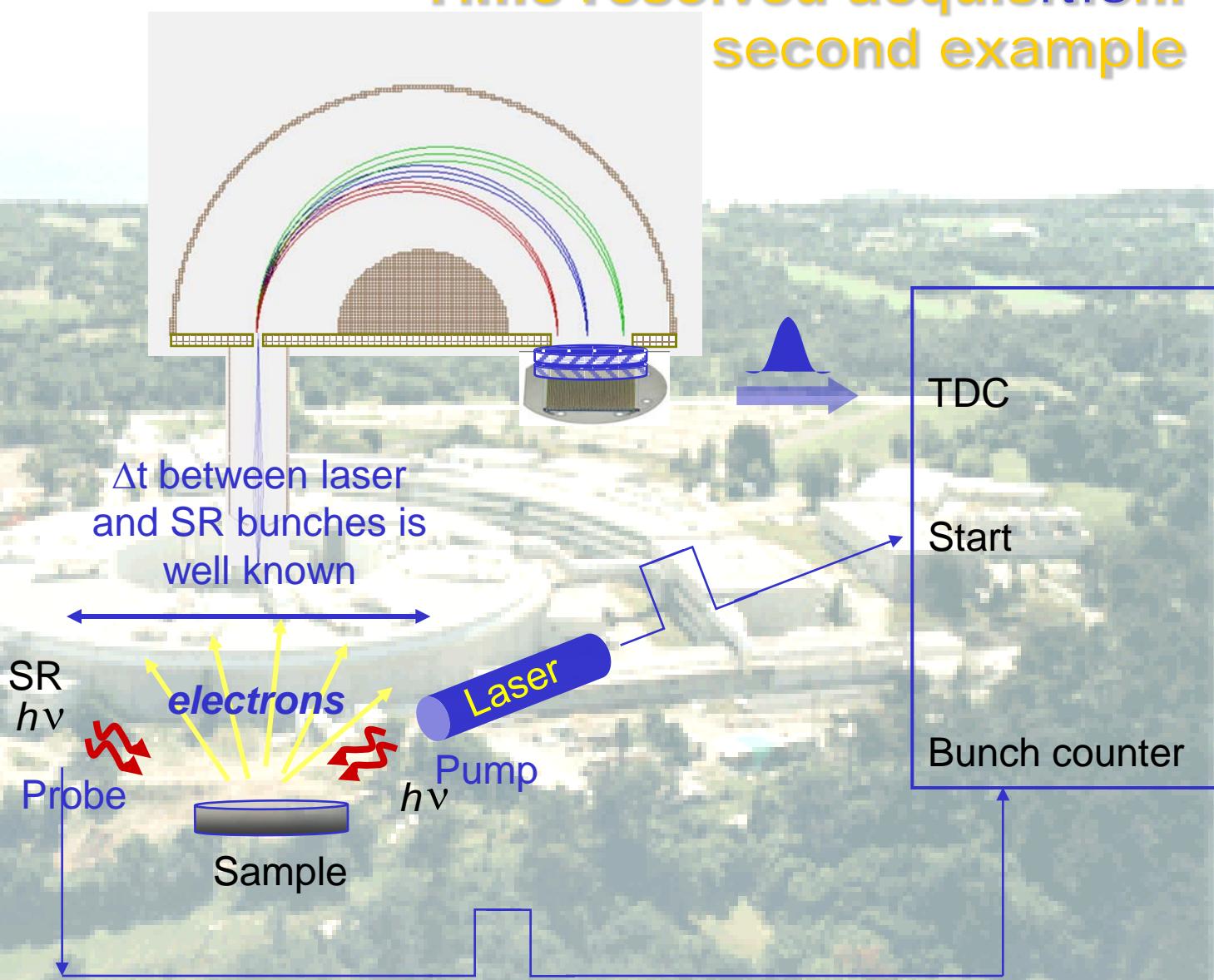
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ANODES  
DETECTOR

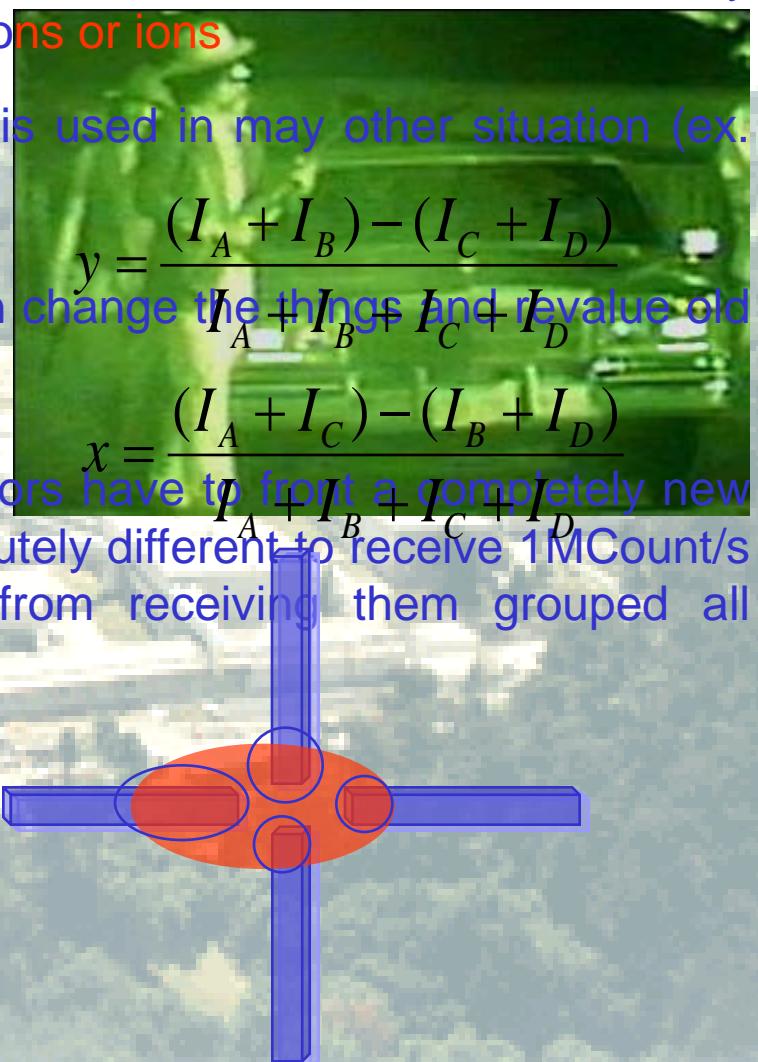
## Final remarks

The described detectors are employed not only with electron analyzers, but also in many other different instruments and they can be used to detect also photons or ions

The centroid finding technique is used in many other situations (ex. Beam Position Monitors (BPM))

New electronic components can change the things and revalue old approaches

The Free Electron Laser detectors have to front a completely new situation: for a detector is absolutely different to receive 1MCount/s uniformly distributed in time from receiving them grouped all together



**That's all...**

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**CHANNEL  
ELECTRON  
MULTIPLIERS**

**MULTIANODES  
DETECTORS**

**BI-DIMENSIONAL  
DETECTORS**

**CENTROID  
FINDING  
POSITION  
DETECTORS**

**CROSS DELAY  
ANODES  
DETECTOR**



# Bi dimensional detectors:

## Anodo resistivo

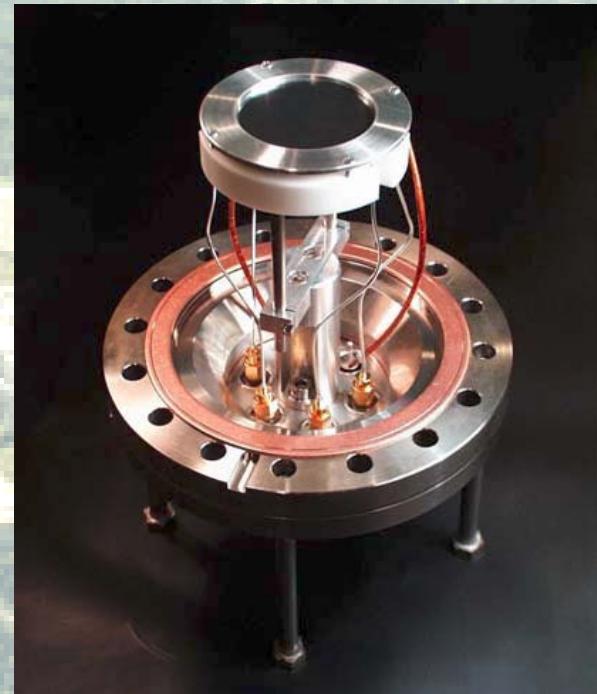
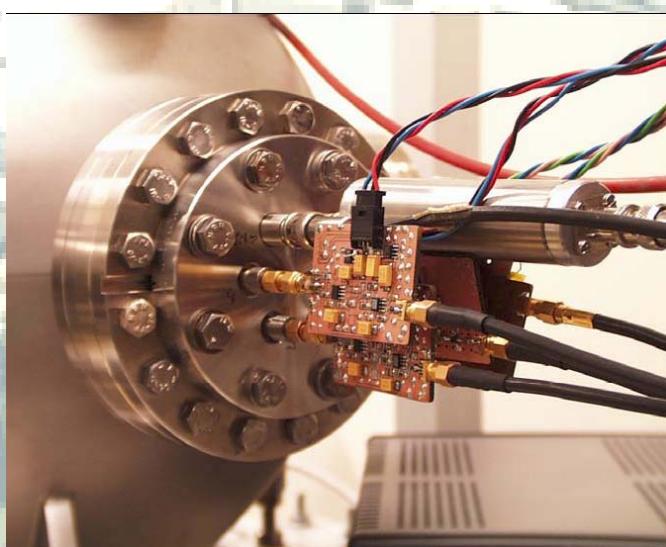
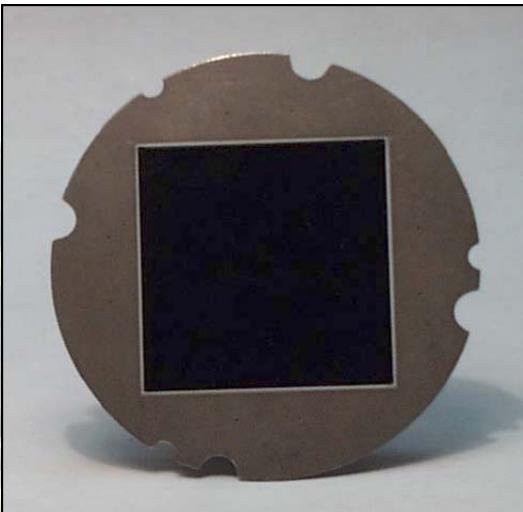
CHANNEL  
ELECTRON  
MULTIPLIERS

**MULTIANODES  
DETECTORS**

BI-DIMENSIONAL  
DETECTORS

CENTROID  
FINDING POSITION  
DETECTORS

CROSS DELAY  
ANODES  
DETECTOR



## Bi dimensional detectors:

### Delay line

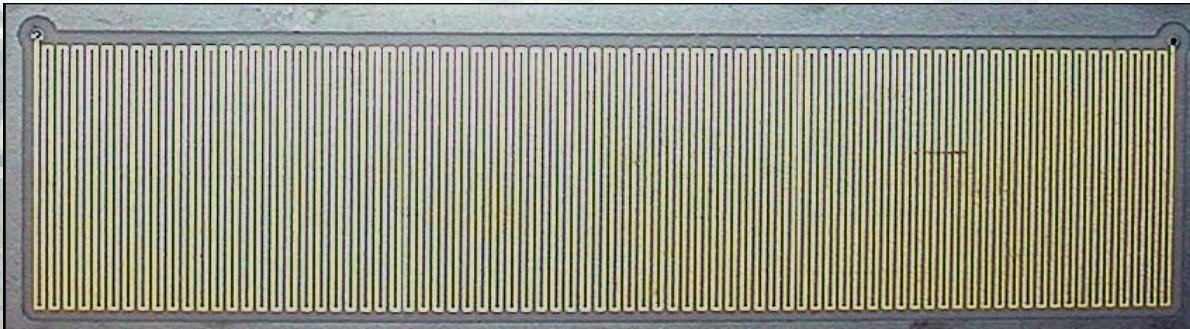
CHANNEL  
ELECTRON  
MULTIPLIERS

MULTIANODES  
DETECTORS

BI-DIMENSIONAL  
DETECTORS

CENTROID  
FINDING POSITION  
DETECTORS

CROSS DELAY  
ANODES  
DETECTOR



# SVILUPPO DELAY LINE ANODE (II)

INTRODUZIONE

MISURE RISOLTE  
IN TEMPO

SCHEMA DI  
MISURA

(CROSS) DELAY  
LINES ANODE

CONSTANT  
FRACTION  
DISCRIMINATOR

TEST SISTEMA  
COMPLETO

CONCLUSIONI &  
SVILUPPI FUTURI

Ricerca della struttura migliore:

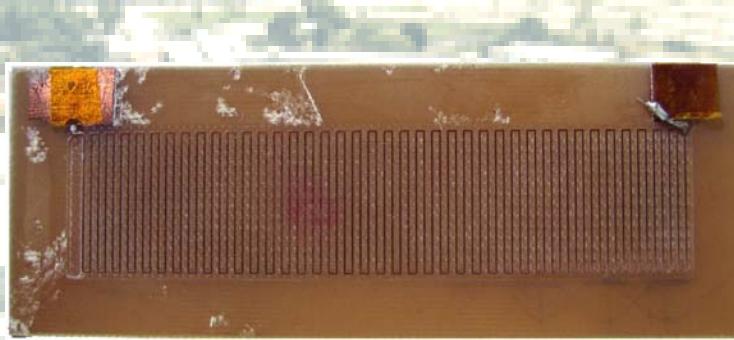


Interasse: 2.3 mm

Lunghezza meandro: 87 cm

Ritardo teorico: 5.1 ns

Ritardo misurato: 3.97 ns

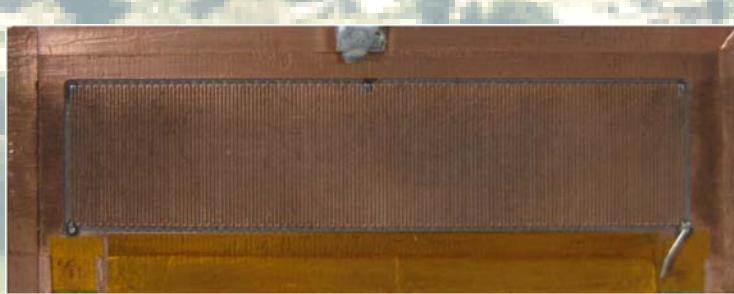


Interasse: 1.15 mm

Lunghezza meandro: 169 cm

Ritardo teorico: 9.8 ns

Ritardo misurato: 6.05 ns



Interasse: 0.575 mm

Lunghezza meandro: 334 cm

Ritardo teorico: 19.4 ns

Ritardo misurato: 7.21 ns

# SVILUPPO DELAY LINE ANODE (II)

INTRODUZIONE

MISURE RISOLTE  
IN TEMPO

SCHEMA DI  
MISURA

**(CROSS) DELAY  
LINES ANODE**

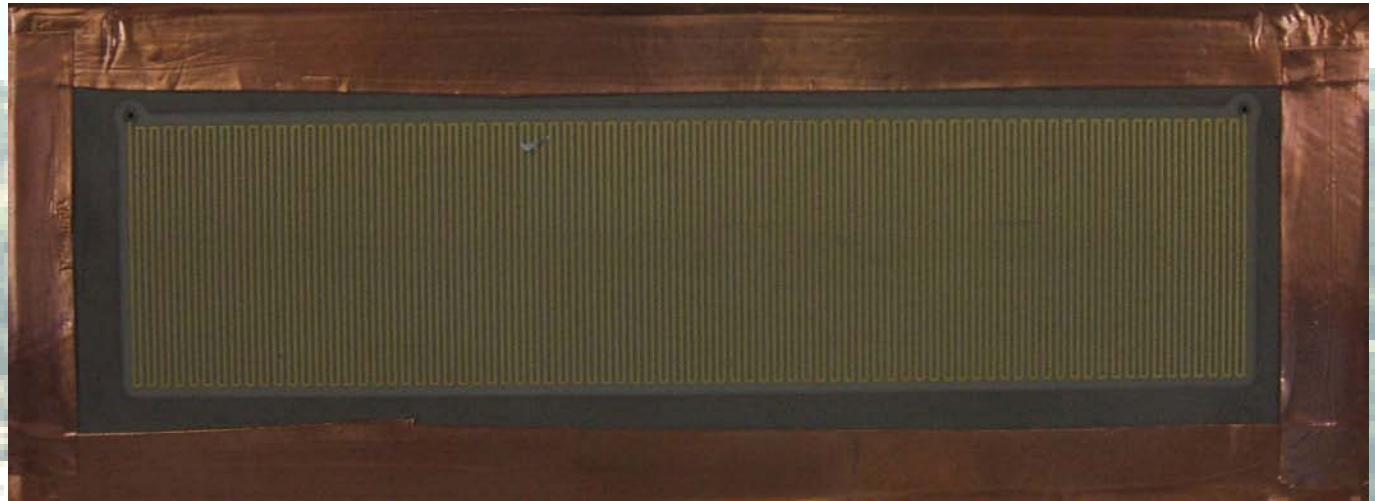
CONSTANT  
FRACTION  
DISCRIMINATOR

TEST SISTEMA  
COMPLETO

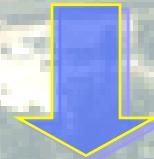
CONCLUSIONI &  
SVILUPPI FUTURI

Ricerca materiali:

Substrato in titanato di bario ( $\epsilon_r = 80$ )



Impedenza caratteristica della serpentina  $25 \Omega$



Adattata l'impedenza con trasformatori a larga banda

# TIPI DI FUNZIONAMENTO DEL CFD

INTRODUZIONE

MISURE RISOLTE IN TEMPO

SCHEMA DI MISURA

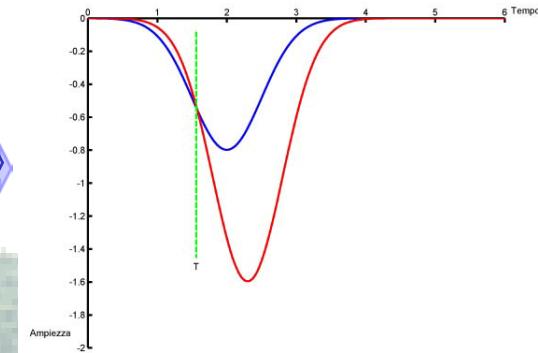
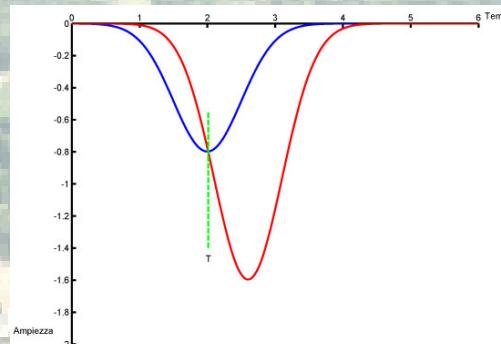
(CROSS) DELAY LINES ANODE

**CONSTANT FRACTION DISCRIMINATOR**

TEST SISTEMA COMPLETO

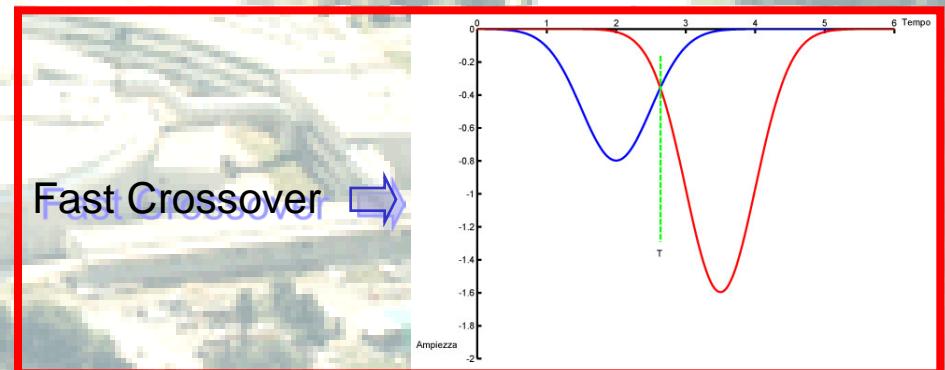
CONCLUSIONI & SVILUPPI FUTURI

ARC (Amplitude Rise-time Compensated) 



 TCF Timing (True-Constant Fraction timing)

Fast Crossover 



Jitter 

$$\sigma_T = \frac{\sigma_N}{\left( \frac{dV_1(t)}{dt} - \frac{dV_2(t)}{dt} \right) \Big|_{t=T_{ef}}}$$

# EFFETTI INTRODOTTI DAL COMPARATORE

INTRODUZIONE

MISURE RISOLTE  
IN TEMPO

SCHEMA DI  
MISURA

(CROSS) DELAY  
LINES ANODE

**CONSTANT  
FRACTION  
DISCRIMINATOR**

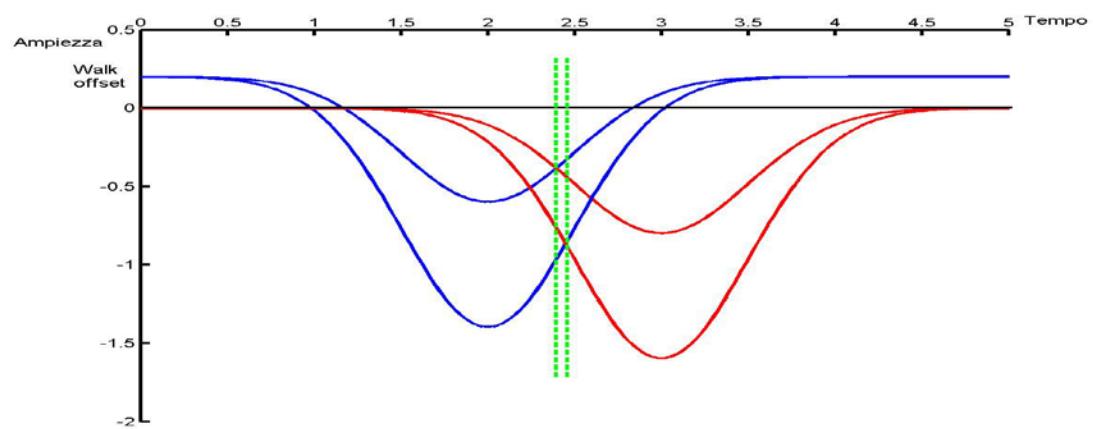
TEST SISTEMA  
COMPLETO

CONCLUSIONI &  
SVILUPPI FUTURI

Comparatore introduce componente variabile di ritardo

$$\tau_{delay} = \sqrt{\frac{2V_0 \pi_0}{SR}} + \tau_D$$

Per minimizzare la componente variabile del ritardo introdotto dal comparatore è conveniente massimizzare SR facendo lavorare il CFD in configurazione *fast crossover* ed utilizzare un cirucito di compensazione del walk



# SCHEMA DEL CFD REALIZZATO

INTRODUZIONE

MISURE RISOLTE  
IN TEMPO

SCHEMA DI  
MISURA

(CROSS) DELAY  
LINES ANODE

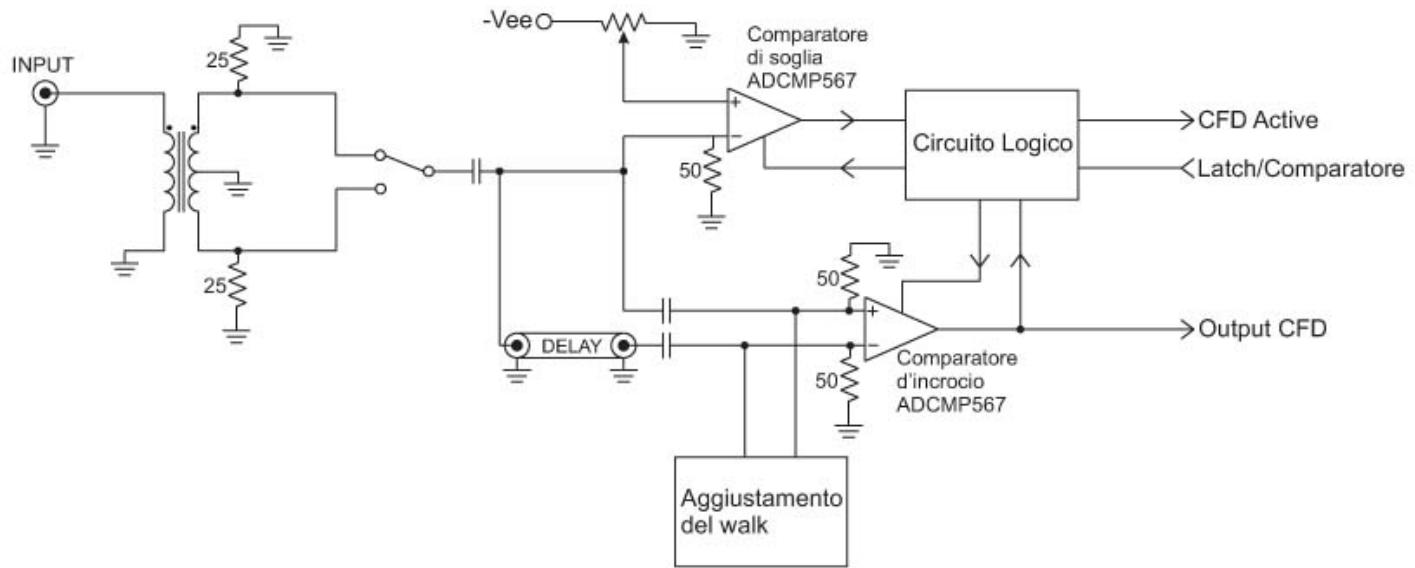
**CONSTANT  
FRACTION  
DISCRIMINATOR**

TEST SISTEMA  
COMPLETO

CONCLUSIONI &  
SVILUPPI FUTURI

## SPECIFICHE:

- **Jitter inferiore ai 20 ps;**
- **Walk error inferiore ai 40 ps;**
- **Ingresso in grado di gestire impulsi positivi e negativi;**
- **Uscite LVTTL o LVPECL;**
- **Ingresso e uscita adattati  $50 \Omega$ ;**



# TEST DEL CFD

INTRODUZIONE

MISURE RISOLTE  
IN TEMPO

SCHEMA DI  
MISURA

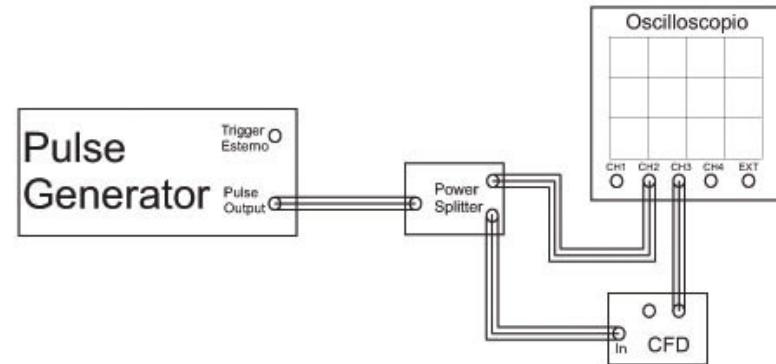
(CROSS) DELAY  
LINES ANODE

**CONSTANT  
FRACTION  
DISCRIMINATOR**

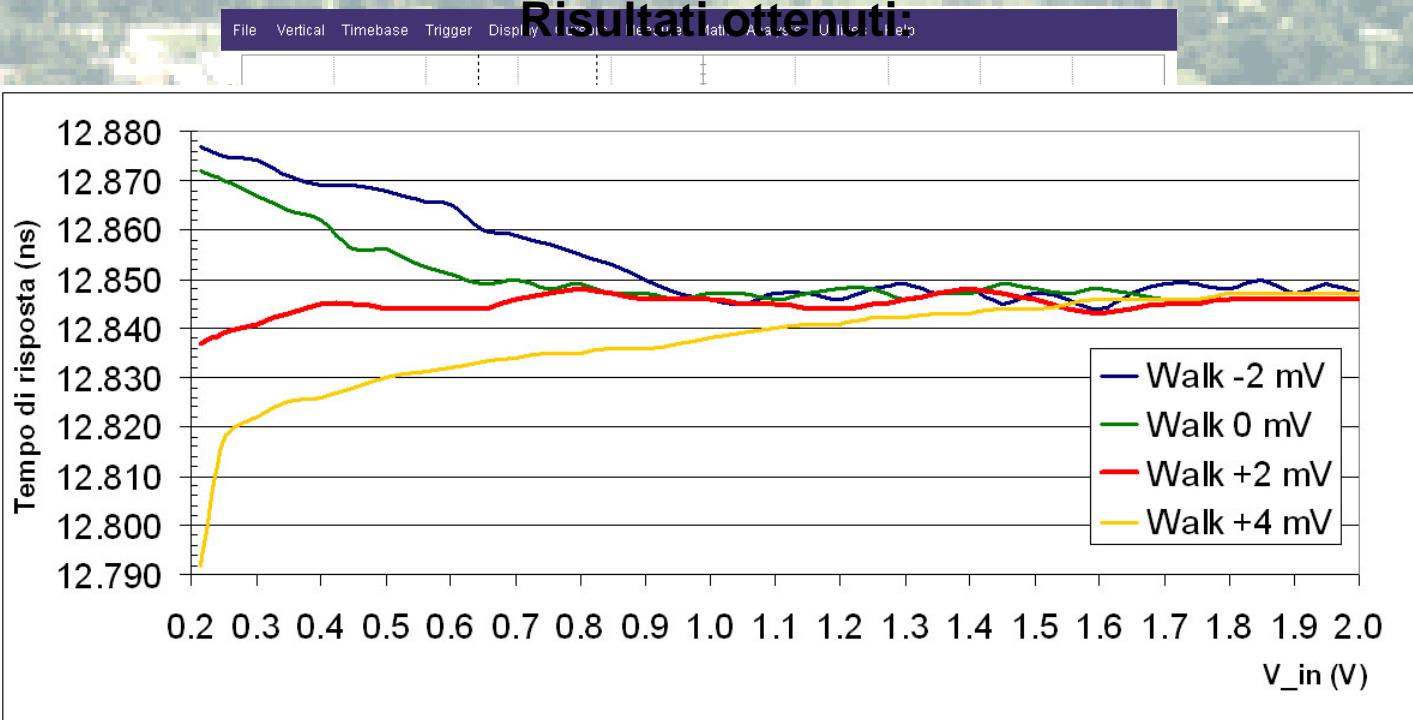
TEST SISTEMA  
COMPLETO

CONCLUSIONI &  
SVILUPPI FUTURI

**Schema utilizzato  
per il test del CFD**



Risultati ottenuti:



# TEST DEL SISTEMA COMPLETO

INTRODUZIONE

MISURE RISOLTE  
IN TEMPO

SCHEMA DI  
MISURA

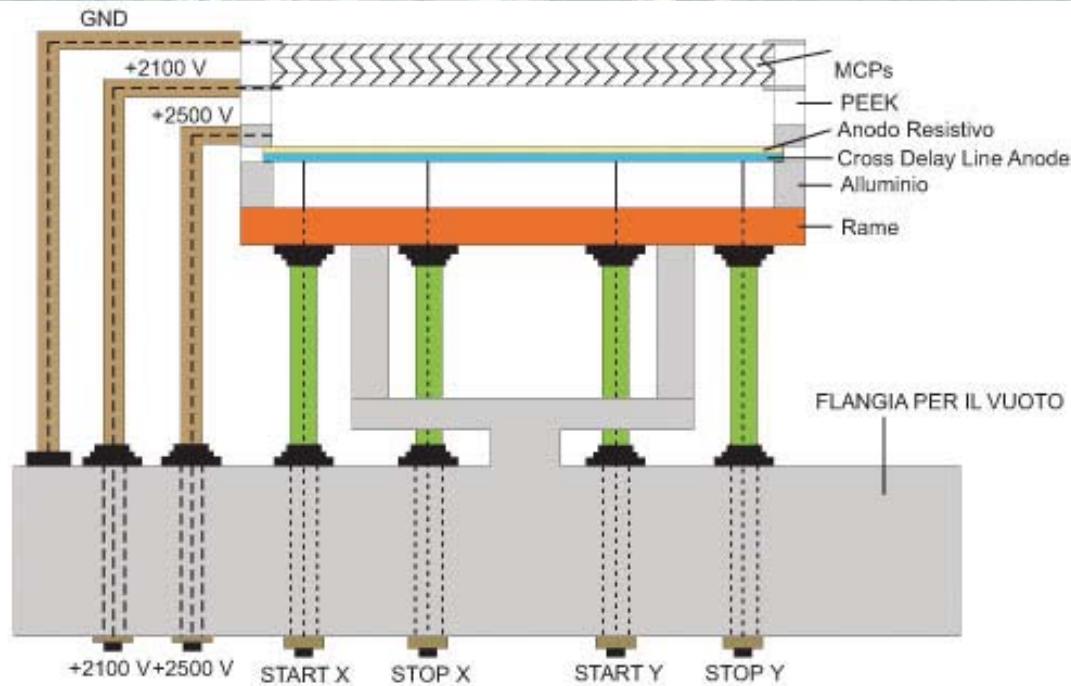
(CROSS) DELAY  
LINES ANODE

CONSTANT  
FRACTION  
DISCRIMINATOR

**TEST SISTEMA  
COMPLETO**

CONCLUSIONI &  
SVILUPPI FUTURI

## Montaggio della parte in vuoto



# TEST DEL SISTEMA COMPLETO

INTRODUZIONE

MISURE RISOLTE  
IN TEMPO

SCHEMA DI  
MISURA

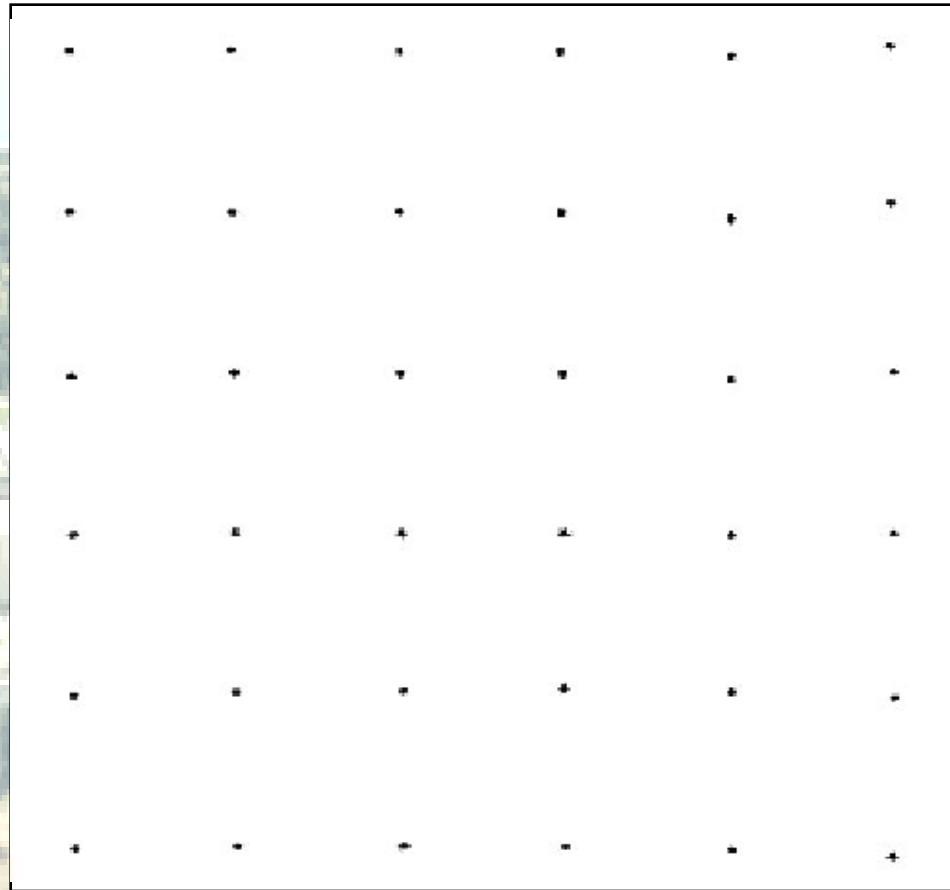
(CROSS) DELAY  
LINES ANODE

CONSTANT  
FRACTION  
DISCRIMINATOR

**TEST SISTEMA  
COMPLETO**

CONCLUSIONI &  
SVILUPPI FUTURI

## Misura risoluzione spaziale



**Migliore di 100  $\mu\text{m}$**