



# UPDATE ON THE ANALYSIS OF GSI2 $^{16}\text{O}$ (200 MeV) ON $\text{C}_2\text{H}_4$

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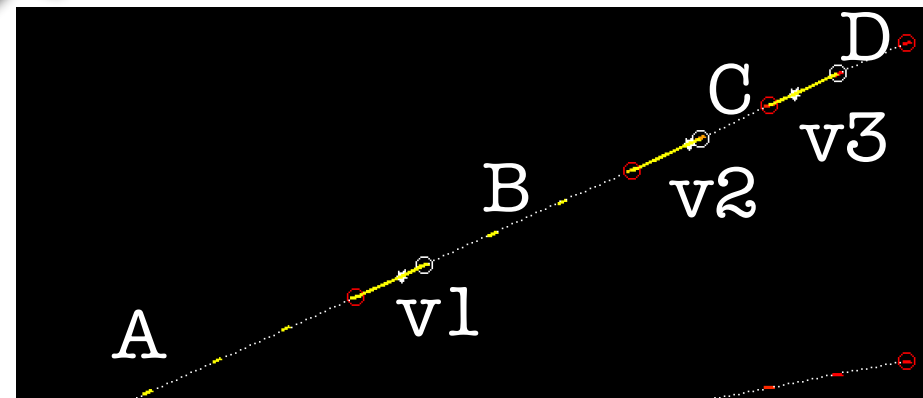
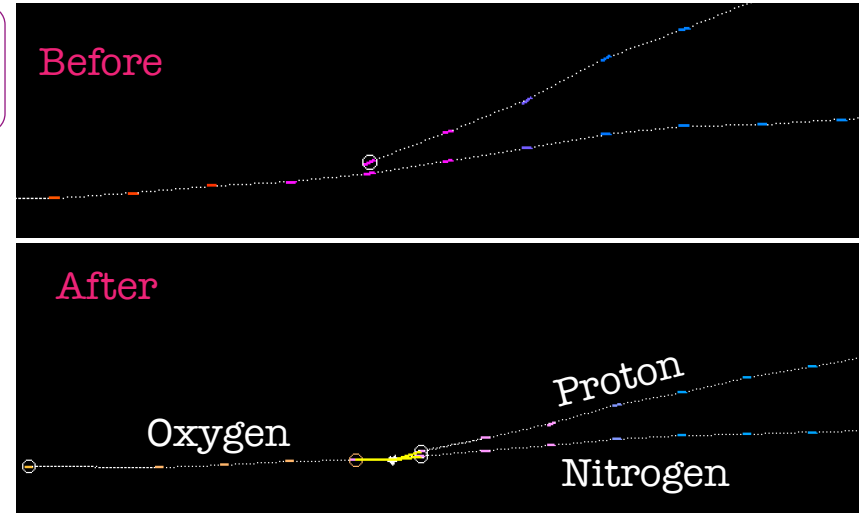
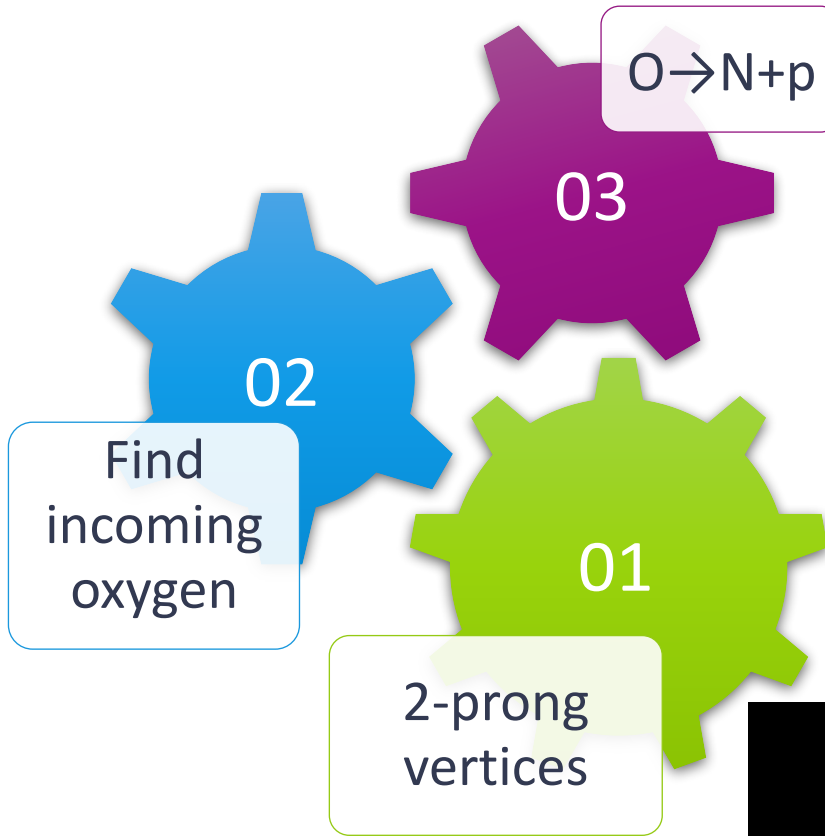
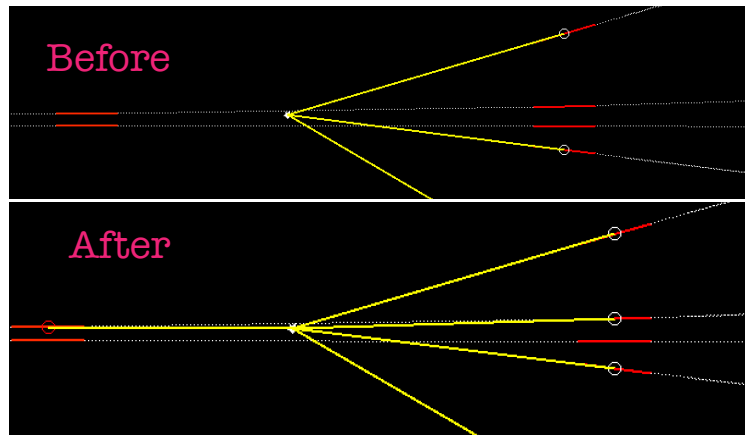
Physics Meeting, ZOOM, 03/02/2021

# Scanning Progress

		2019		2020
		Oxygen 200 MeV/n	Oxygen 400 MeV/n	Carbon 700MeV/n
TARGET	BEAM			
Carbon		GSI1	GSI3	GSI5
Polyethylene		GSI2	GSI4	GSI6

- 2019 (GSI1, GSI2, GSI3, GSI4):
  - scanning: completed
  - alignment:
    - GSI1: completed
    - GSI2: completed
    - GSI3: S1 completed
    - GSI4: S1 completed
  - tracking:
    - GSI2: S1+S2 completed
- 2020 (GSI5, GSI6):
  - scanning: about 240/328

# Vertices Reconstruction (summary)



# Vertices Selection: new results



	Monte Carlo		
	Before	Now	
Entries	11350	9918	
n $\geq$ 3	4660	5848	
n=2	6690	4070	
vtx good n $\geq$ 3	3912	4926	26%
vtx good n=2	1472	644	-56%
tot good	5384	5570	

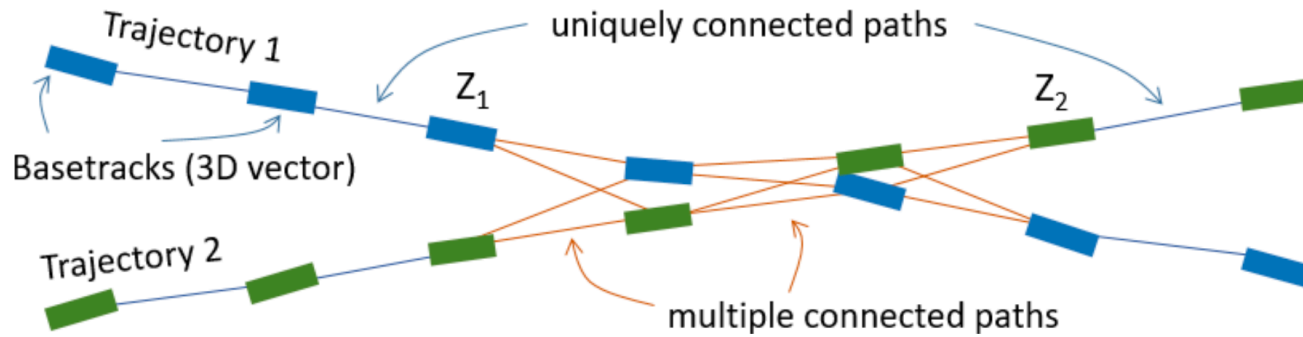
Data		
Before	Now	
12412	11338	
3748	4928	31%
8664	6410	-26%

- MC: A vertex is considered good if it has at least 2 tracks belonging the same MC event
- MC: We are about to reach the number of expected vertices (~6300)

- Improvements in tracking reconstruction could help in finding the missing vertices: a wrong segment attached to the beginning or end of the track could prevent the vertices reconstruction

# New tracking estimator

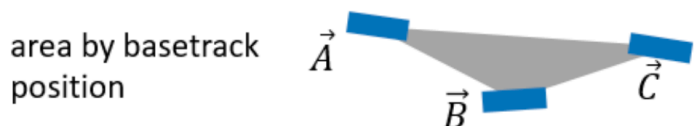
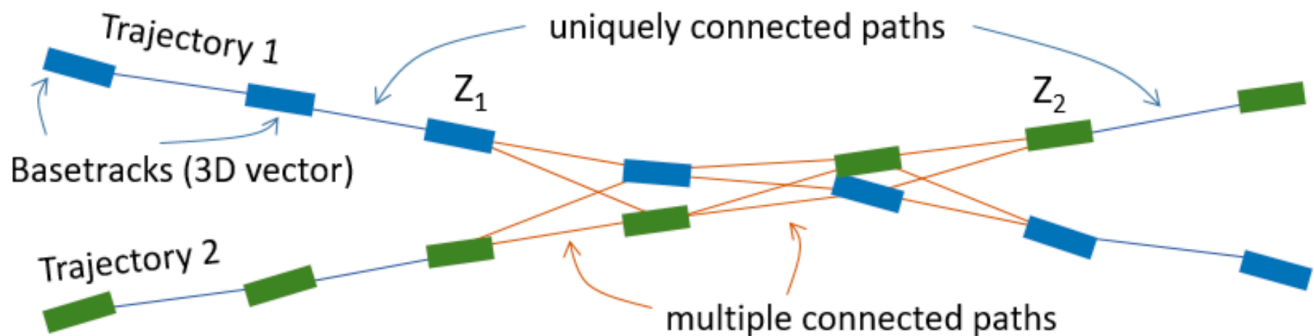
- New tracking algorithm to reconstruct tracks in the environment with high track density and narrow angular spread



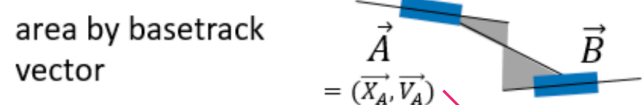
- When it faces multiple path candidates, the algorithm keeps all possible paths (TO DO)
- For each path, it evaluates a test variable based on average of area made by segments involved in the possible paths

# New tracking estimator

- New tracking algorithm to reconstruct tracks in the environment with high track density and narrow angular spread



$$a^{pos} = \frac{1}{2} \cdot |\overline{AB} \times \overline{AC}|$$



$$a^{angle} = \frac{1}{2} \cdot \frac{|\overline{AB}|}{2} \cdot \left| (\vec{V}_A + \vec{V}_B) \times \frac{\overline{AB}}{2} \right|$$

Each segment is described by a 3D coordinates vector  $X = (x,y,z)$  and a 3D vector  $V = (\tan \theta_x, \tan \theta_y, 1)$

$$a^{average} = \frac{\left( \sum_i^{n-2} a^{pos} + \sum_i^{n-1} a^{angle} \right)}{n - 0.5}$$

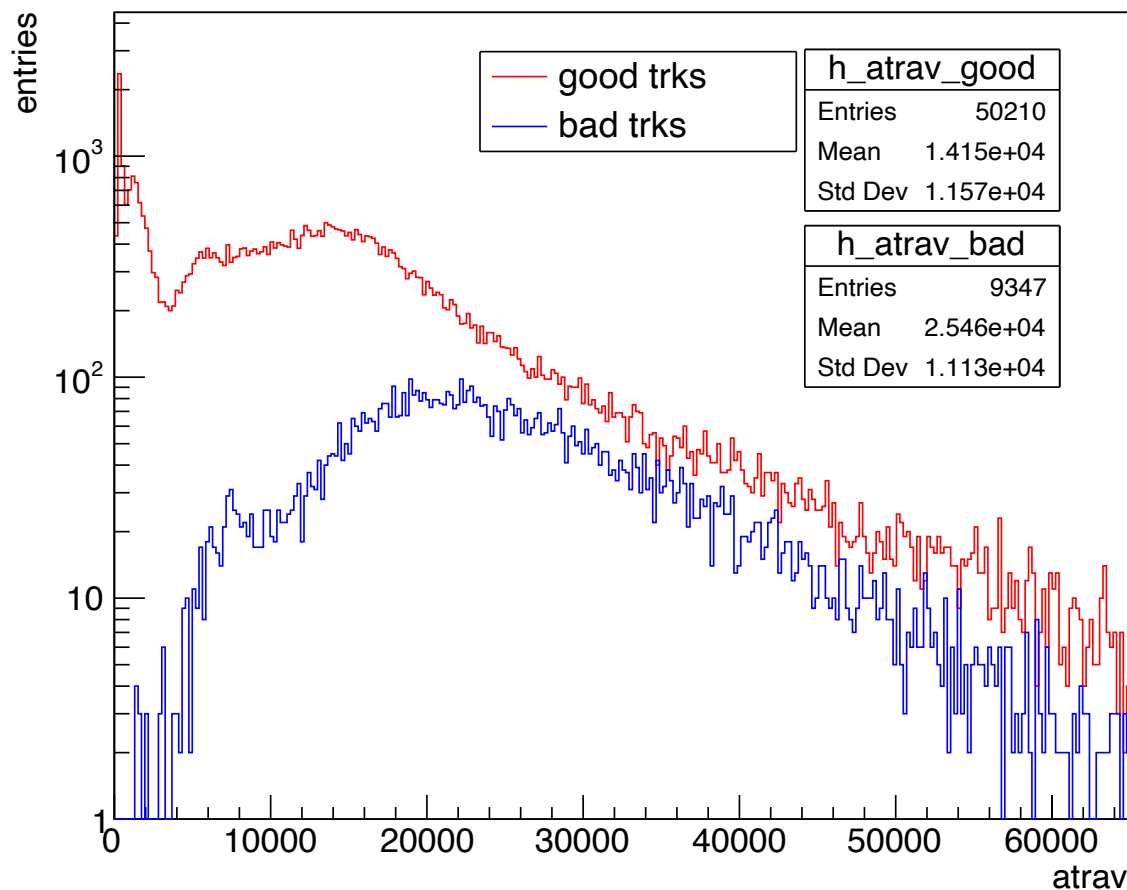
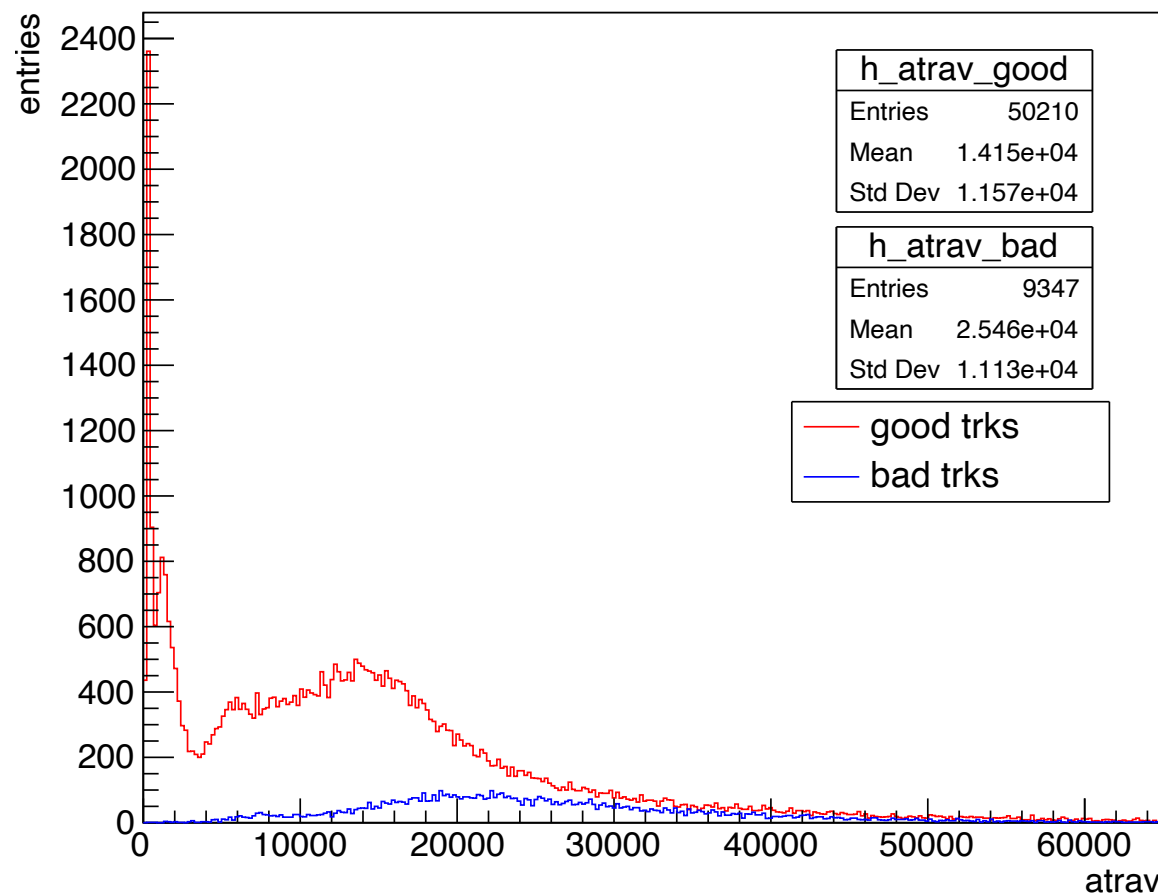
$n$  is the number of segments involved in the path

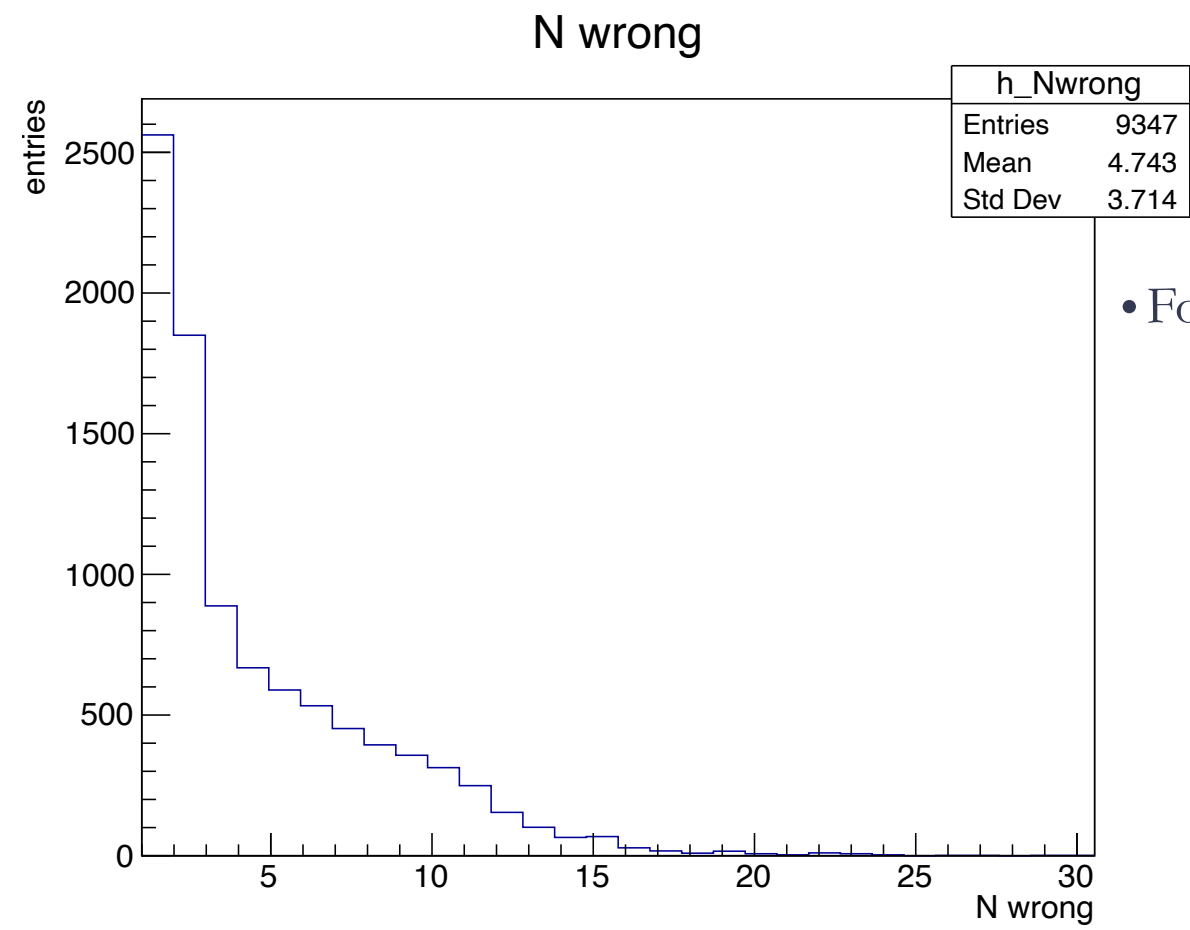
empirical value to put a higher weight on longer paths

- $a^{average}$  gives the averaged area made by segments positions and angles
- The path with the smallest  $a^{average}$  is chosen to be the best one

# New tracking estimator

- A first check has been done on tracks already reconstructed by standard algorithm (based on  $\chi^2$ ).
- A track is defined “bad” if it has at least one segment different from other ones.

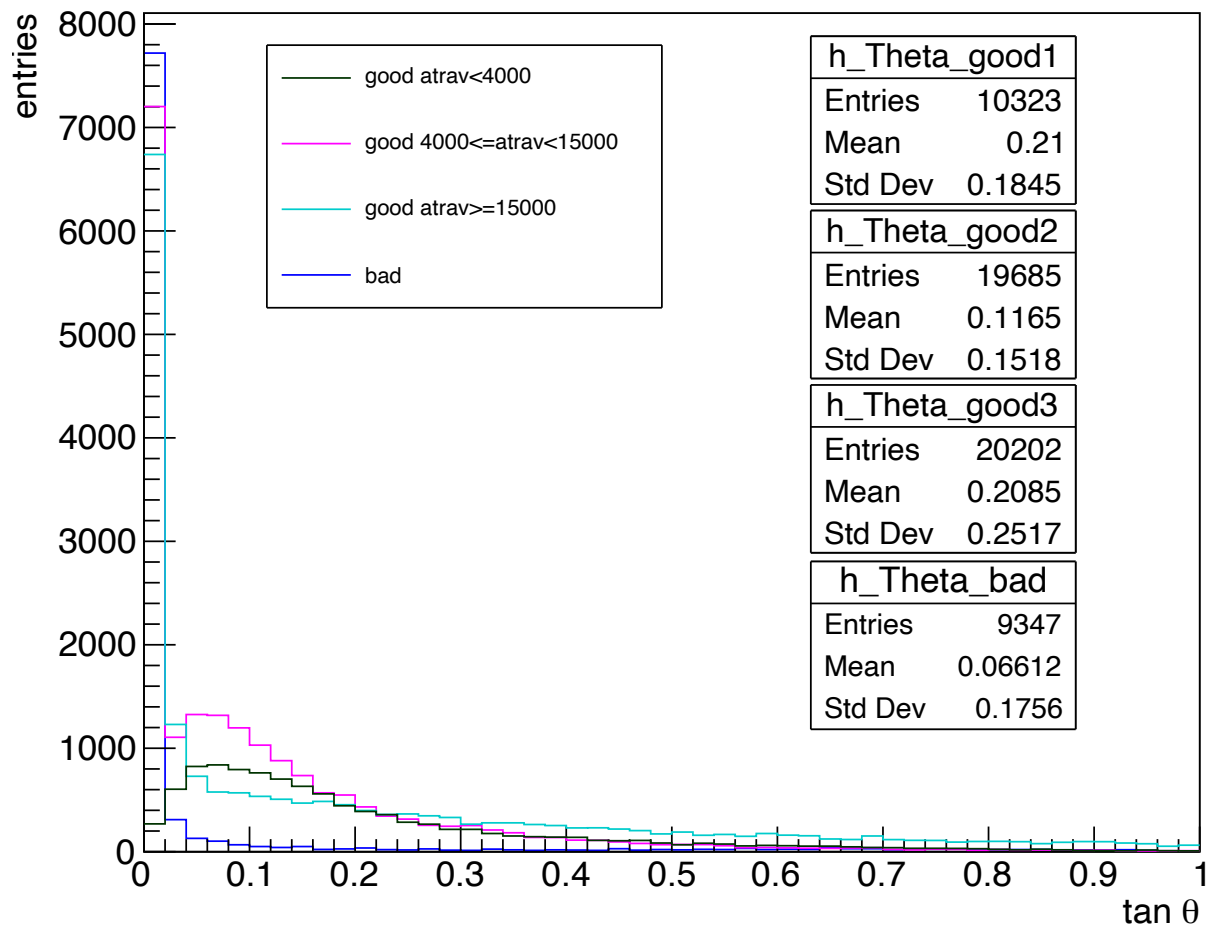




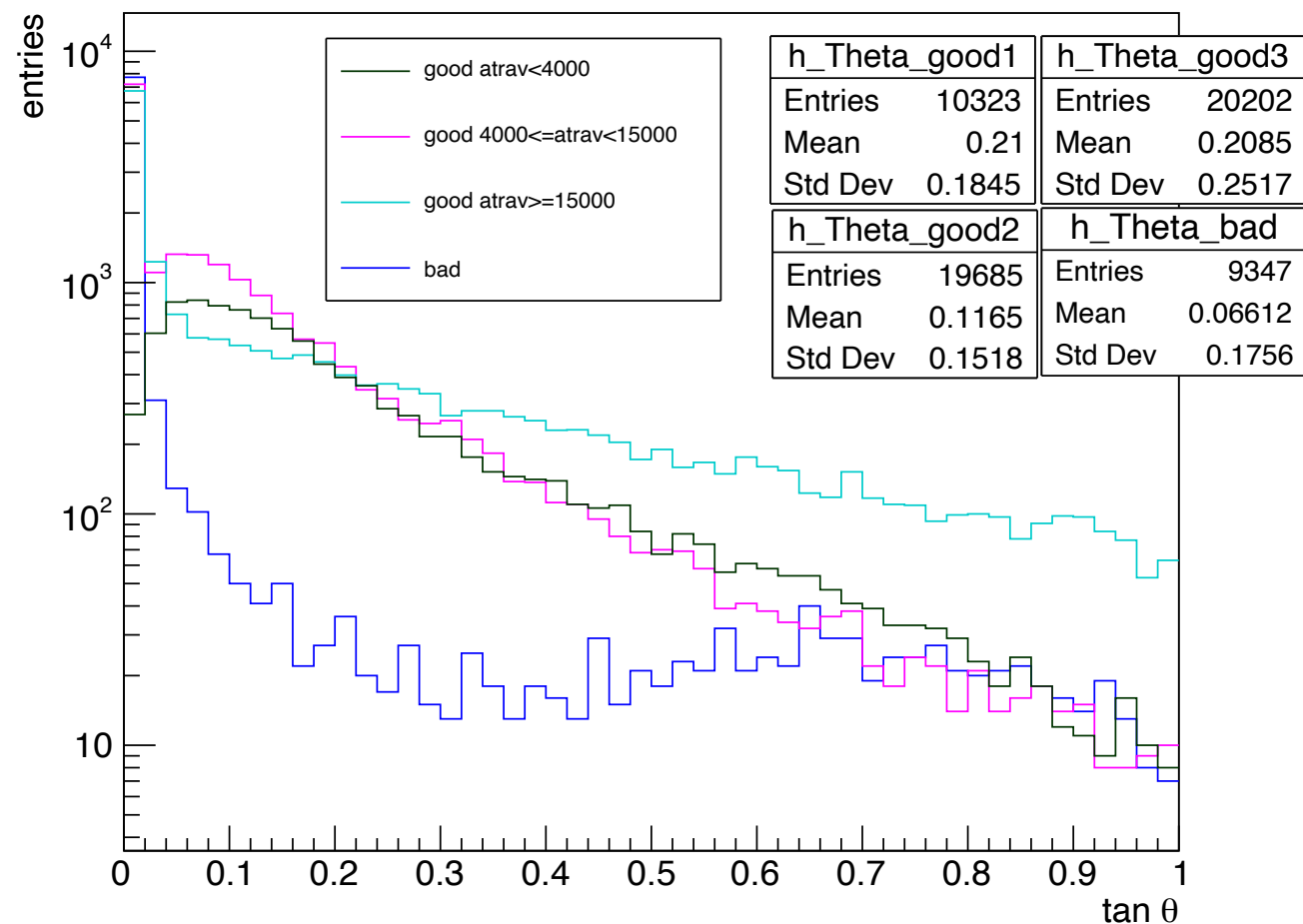
- For “bad” tracks often the first and/or last segment is wrong:
  - last wrong: 2242 cases → problem for tracks entering the vertex
  - first wrong: 5494 cases → problem for tracks exiting the vertex

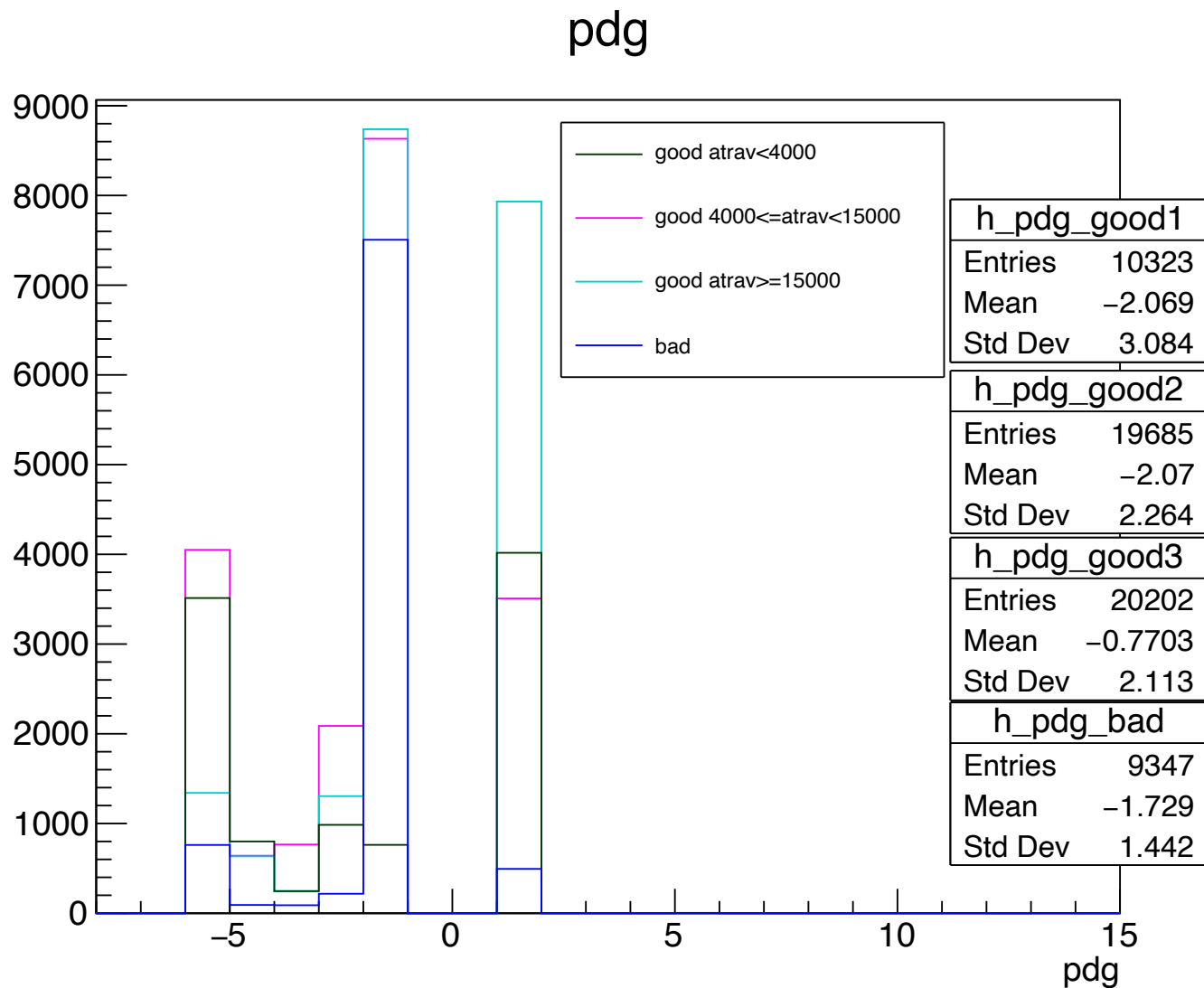


$\tan \theta$



$\tan \theta$





- -6 = 4He
- -5 = 3He
- -4 = 3H = Trizio
- -3 = 2H = deuterio
- -2 = heavy ion
- 1 = protone
- 3 = elettrone
- 4 = positrone
- 7 = fotone
- 8 = neutrone
- 13 = pione+
- 14 = pione-

# Conclusions

- In Monte Carlo reconstruction we miss about 700 vertices
- Improvements in tracking reconstruction could help in finding the missing vertices: a wrong segment attached to the beginning or end of the track could prevent the vertices reconstruction
- An algorithm based on a new estimator is under development to reconstruct tracks in an environment with high track density and narrow angular spread



**HANK**



**OU!**