

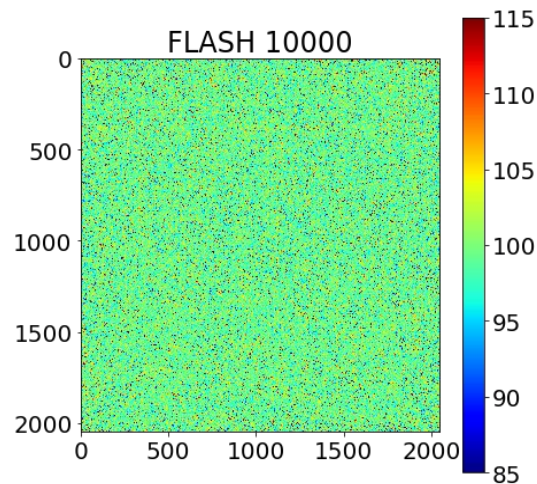
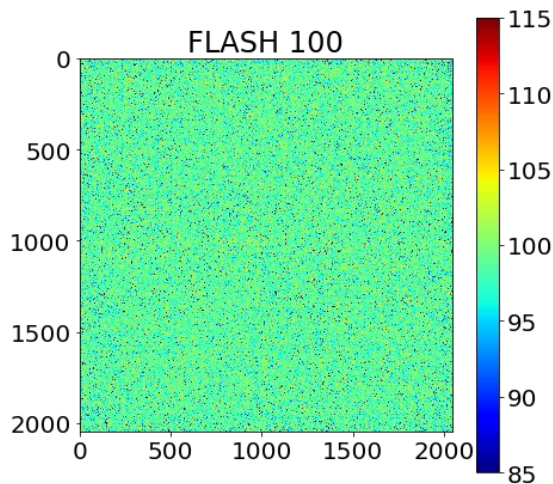
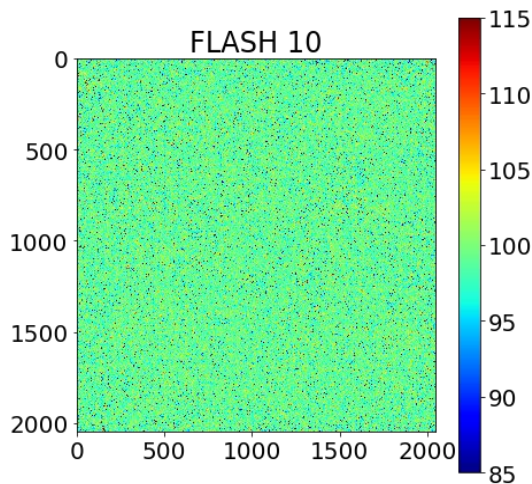
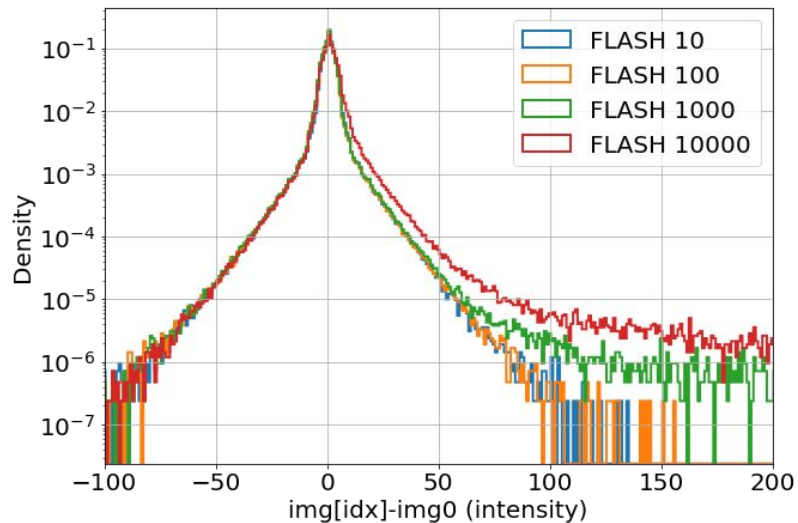


Noise \times Exposure Time

Flash vs. Fusion

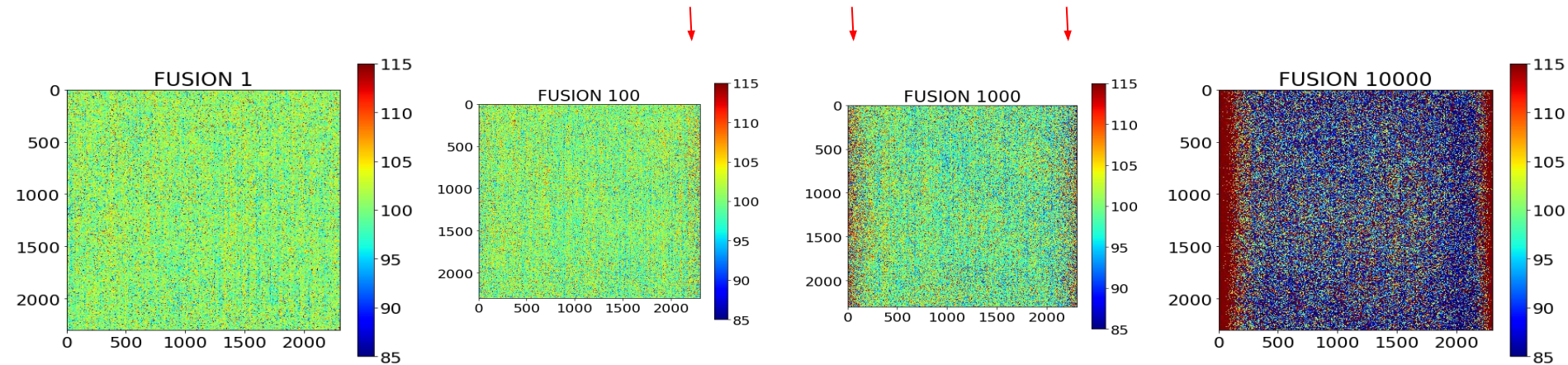
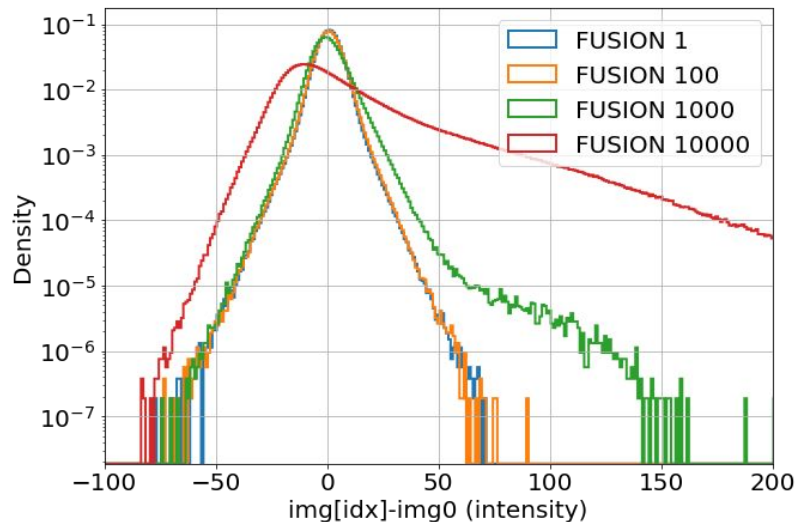
Flash

- Up to 100 ms the noise is practically the same
- The hot pixels are spread ~uniformly throughout the sensor



Fusion

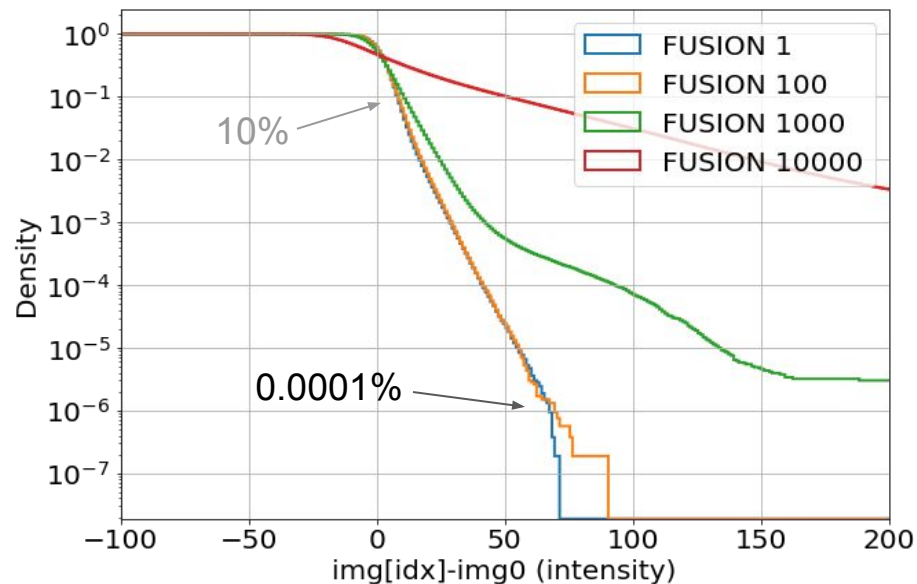
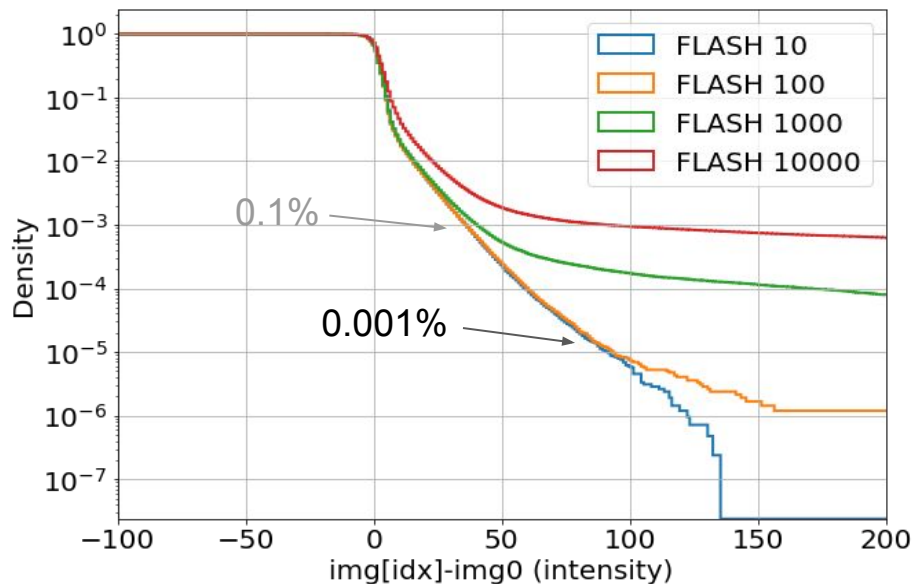
- Up to 100 ms the noise is practically the same
- The hot pixels are more concentrated on the borders of the sensor
- Strong effect for 1000 ms and drastic change for 10000 ms
- The mean value of the pixels on the center seems to decrease



iCDF to see the probabilities

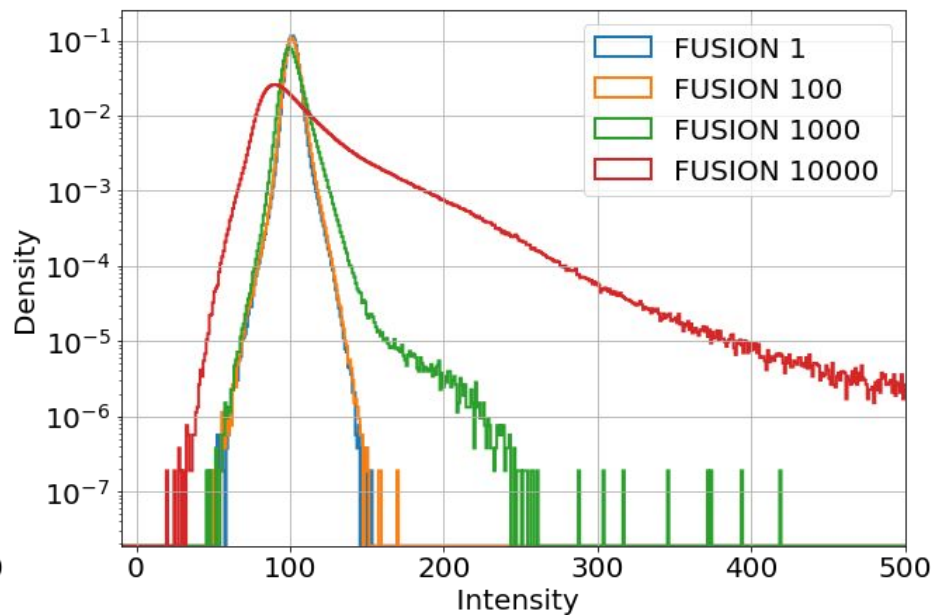
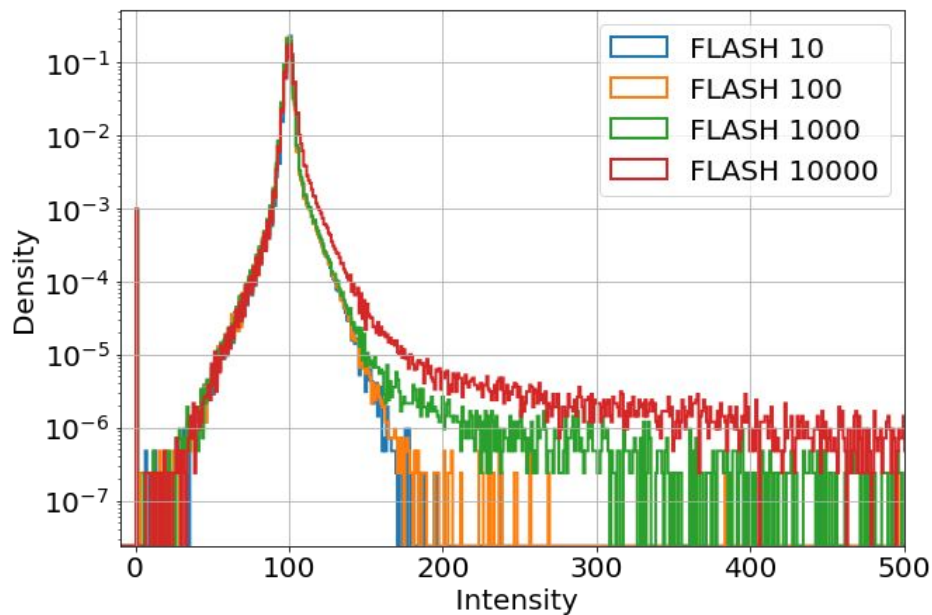
From 1 to 100 ms Fusion presents less noise variation, changing or about 0.0001% pixels

For longer exposure times (>100 ms) Fusion noise starts to increase rapidly



Absolute values (intensity)

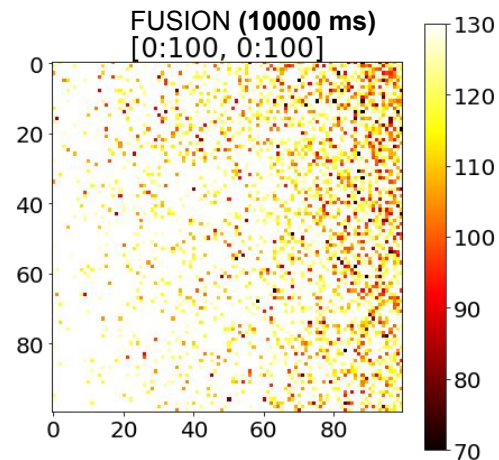
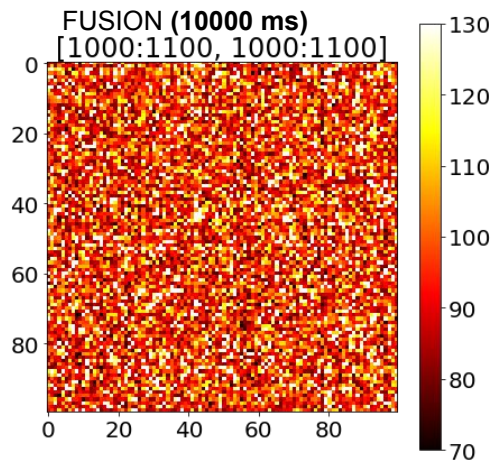
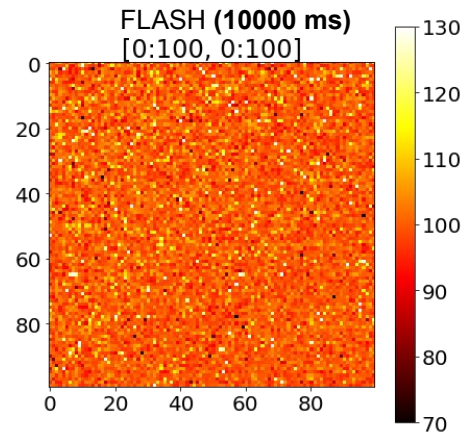
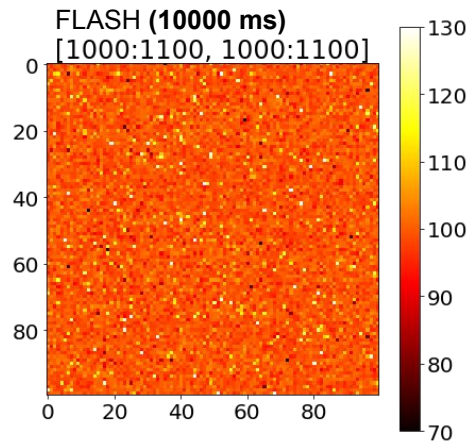
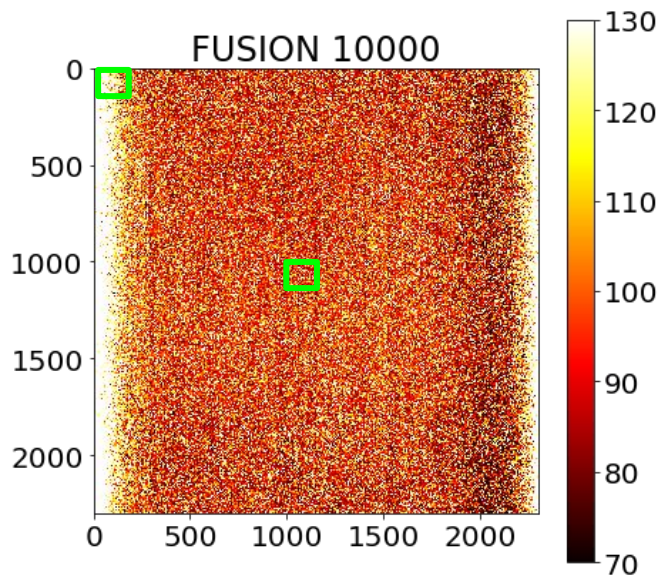
Just to see the absolute values....nothing new...



Center vs. Border

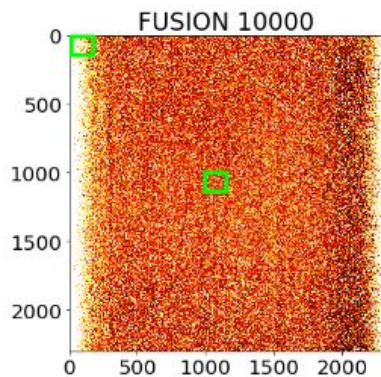
On 10000 ms data

- The concentration on the border is much stronger for the Fusion sensor

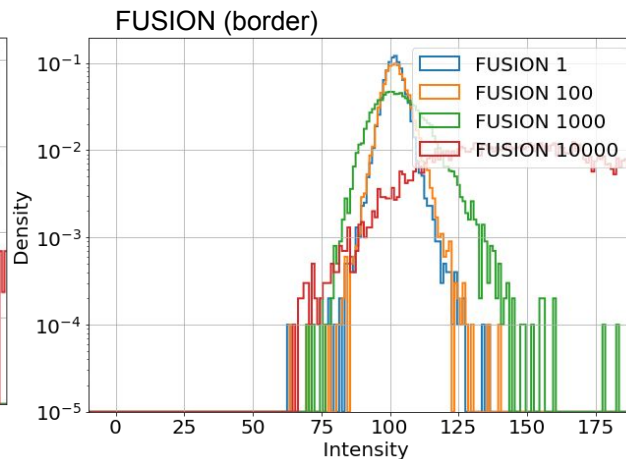
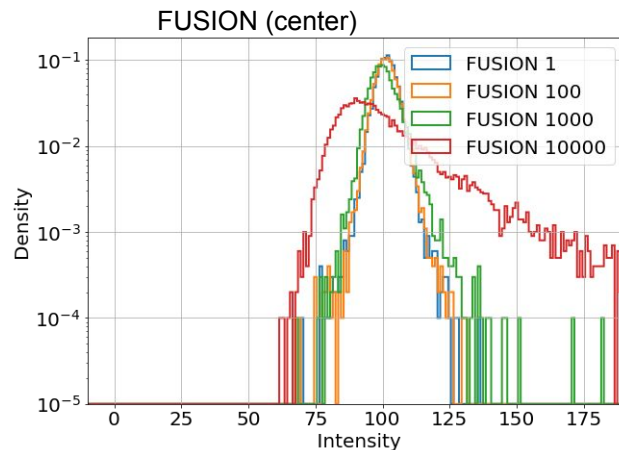
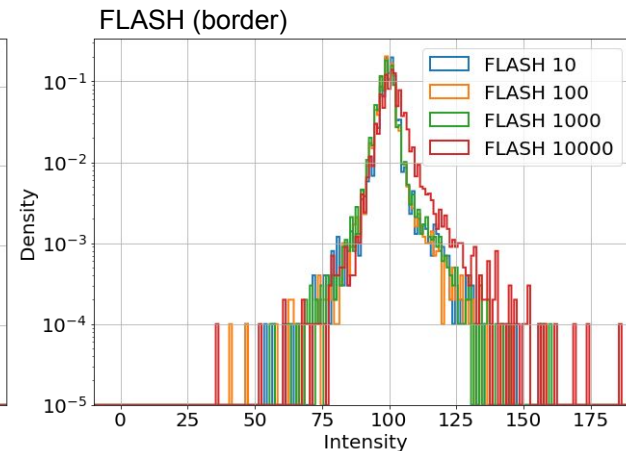
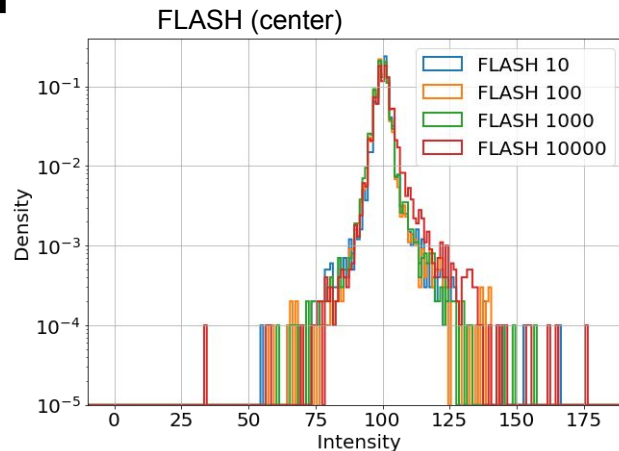


Center vs. Border

- The concentration on the border is much stronger for the Fusion sensor
- But there are hot pixels on the center as well

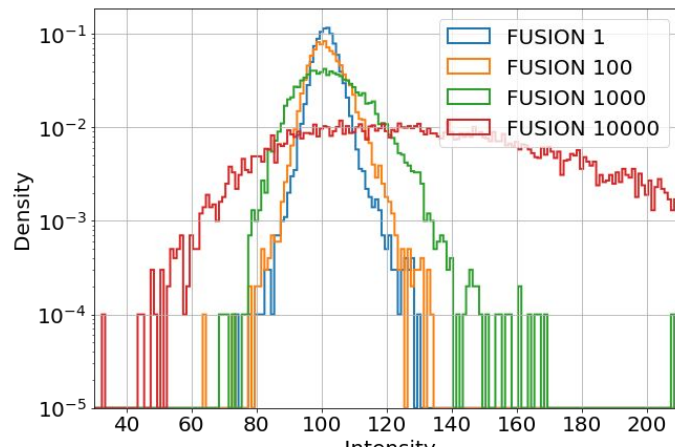
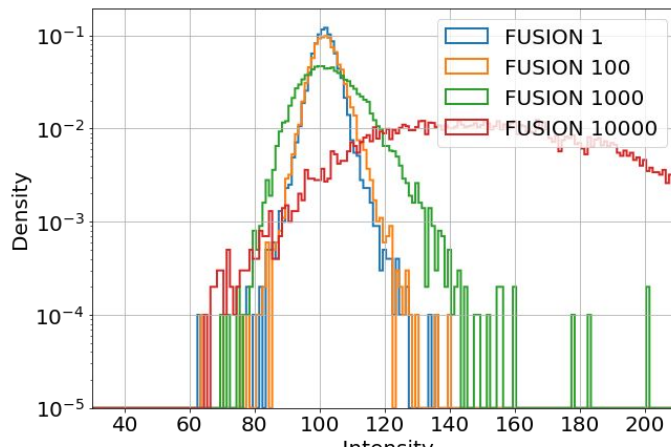
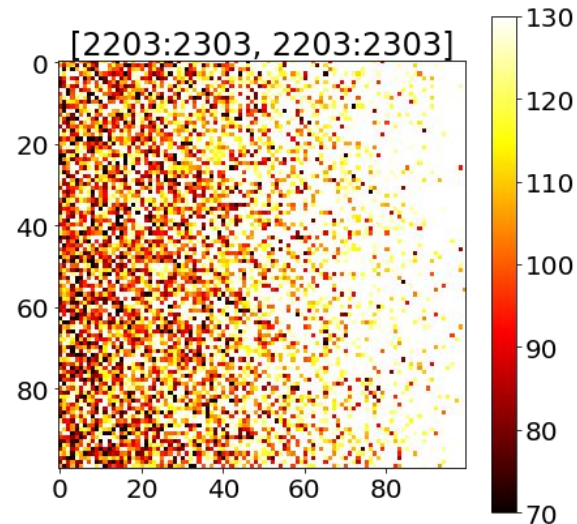
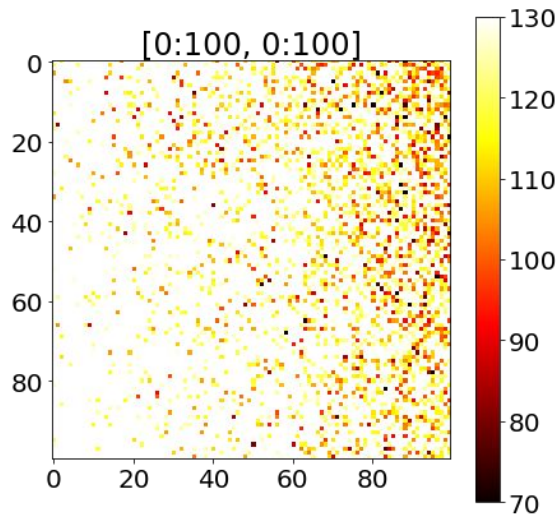
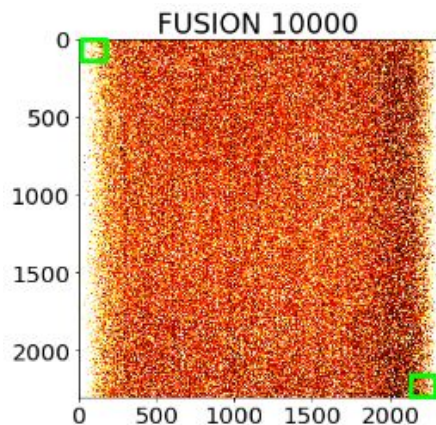


Note that the right side is different from the left side

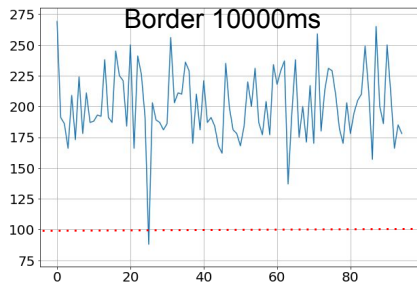
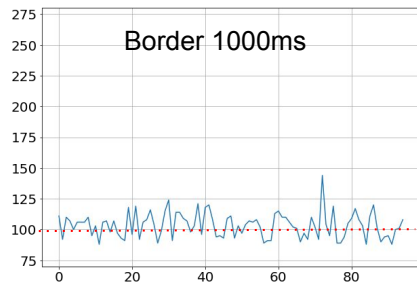
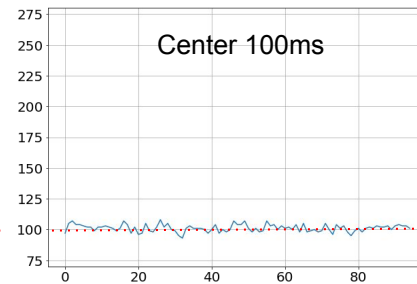
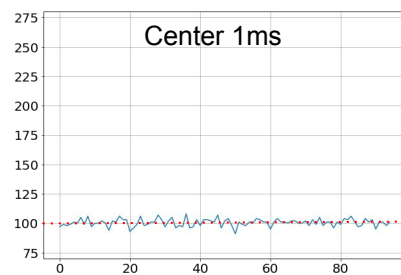
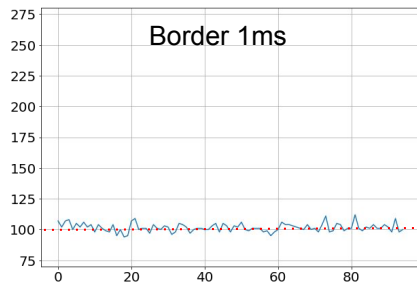
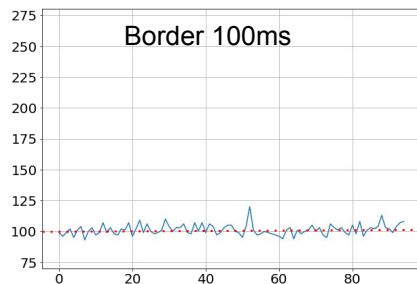


Fusion Borders

- Fusion is asymmetric...



Fusion Border x Center *(checking by eye)*



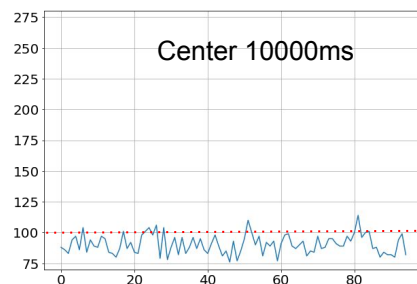
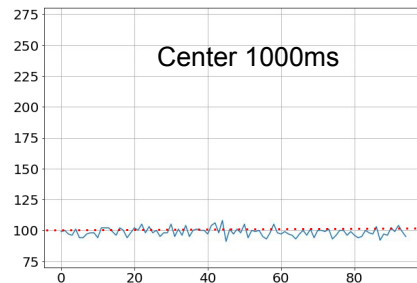
- Examples of:

- A typical border pixel

- Mean value increasing
 - Noise increasing

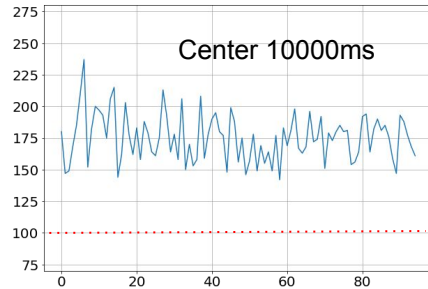
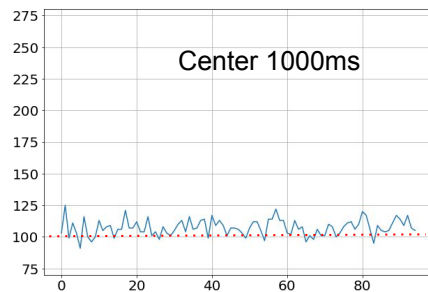
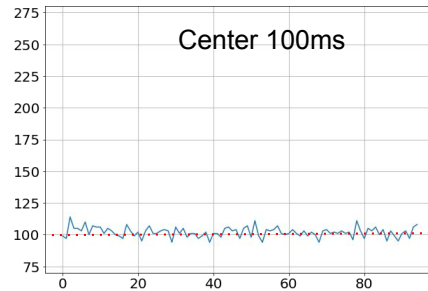
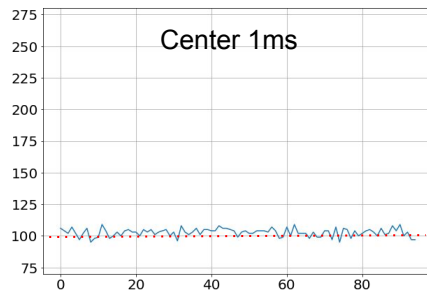
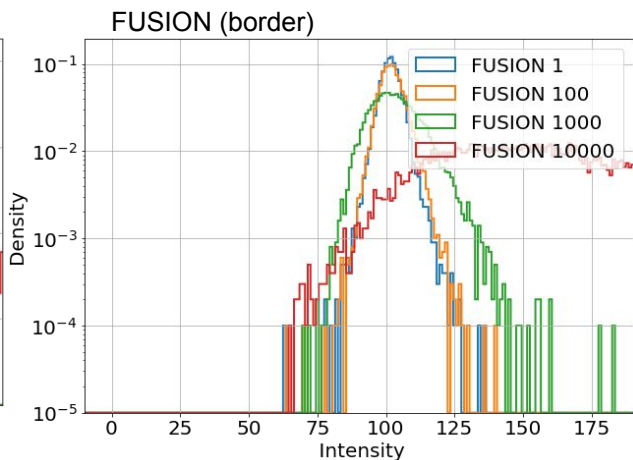
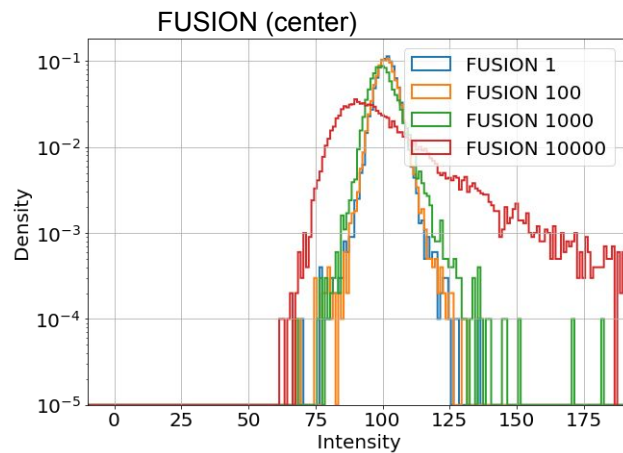
- A typical center pixel

- Mean value decreasing
 - Noise increasing (less)



Fusion Border x Center *(checking by eye)*

- But center pixels can also go higher...
 - Mean value increasing
 - Noise increasing (more)



Dark current Flash vs. Fusion

C13440-20CU

ORCA-Flash 4.0 V3 Digital CMOS camera

Dark current	0.06 electrons/pixel/s (Air Cooled to -10° C) (typ.)
	0.06 electrons/pixel/s (Water Cooled to -10° C) (typ.)
	0.006 electrons/pixel/s (Water Cooled to -30° C) (typ.)

ORCA-Fusion

Digital CMOS Camera

C14440-20UP/C14440-20UP01

Dark current ※ ¹	cooling temperature:-5 °C	0.5 electrons/pixel/s
	cooling temperature:-15 °C	0.2 electrons/pixel/s

- Under investigation but...
 - Dark current is dependent of exposure time
 - For short exposure time it can be ignored (other noise sources dominate)
 - For long exposure times, dark current can dominate
 - **Fusion has a dark current level much higher than the Flash**

Preliminary conclusions

- Analysis is ongoing but...
 - Fusion seems to have lower noise up to 100 ms of exposure time
 - Fusion sensor is much more sensitive to long exposure times (>100 ms)
 - Mean shifting and RMS noise increasing
 - With drastic change for 10 seconds

