

Pixel chamber: a silicon heavy-flavour imager with monolithic active pixel sensors for measurements of charm and beauty with unprecedented precision

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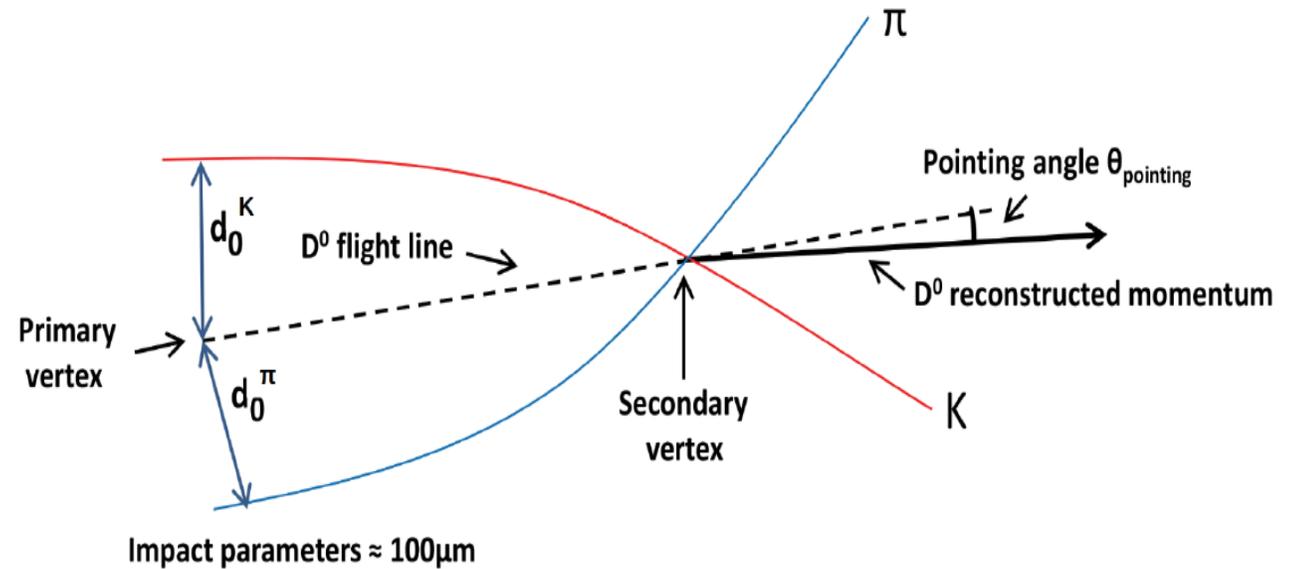
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Charm and beauty

Charm and beauty quarks are very important for SM studies and for the research of new physics

- Long lifetime → can travel distances from $O(10-100 \mu m)$ up to mm before decay



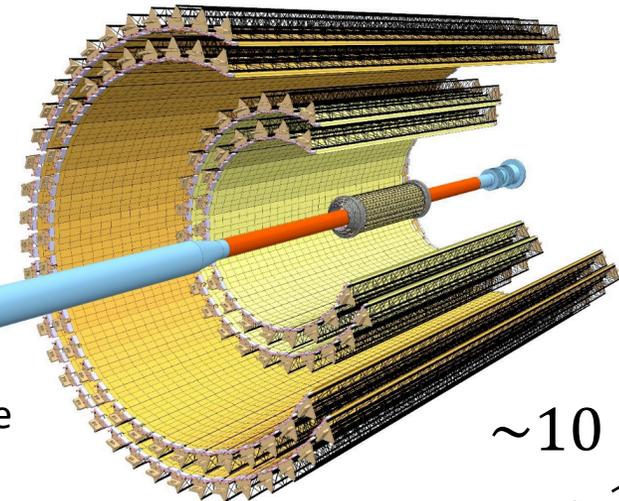
Ideal detectors

- great spatial resolution to separate primary from secondary vertices



ALICE

In modern vertex detectors silicon sensors (pixels or strips) are placed close to the interaction point (few centimetres away)

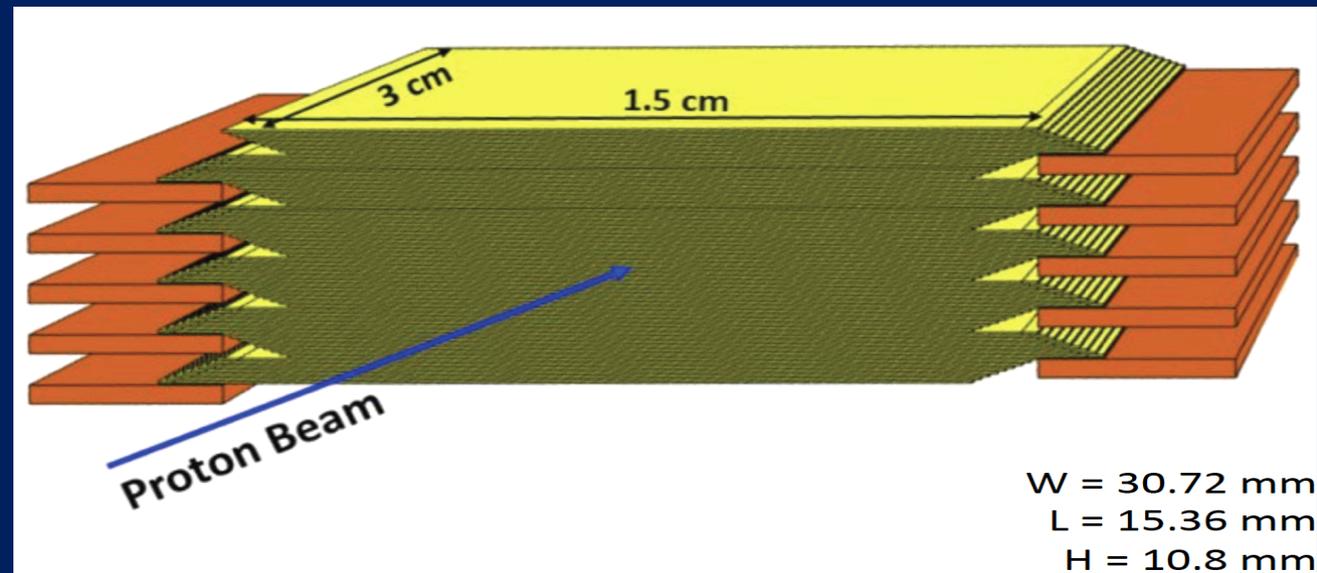
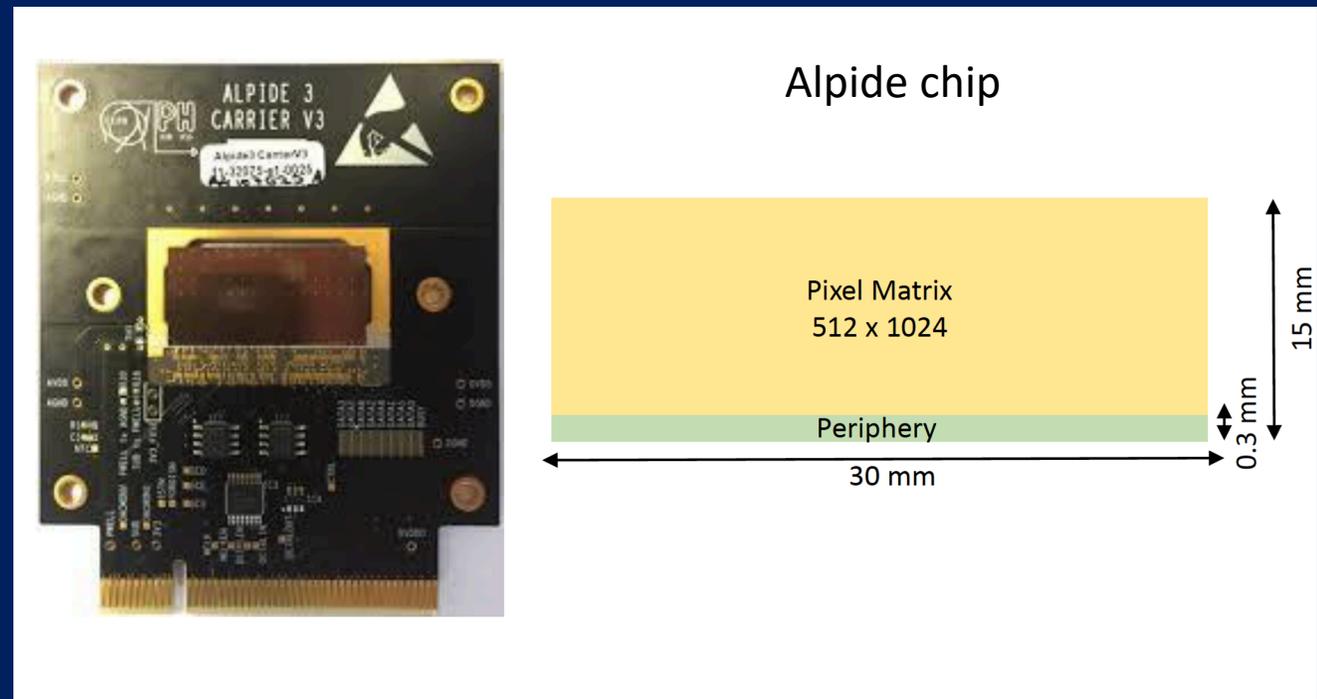


$\sim 10^6$ pixels
 $\sim 10^2$ m²

Pixel Chamber

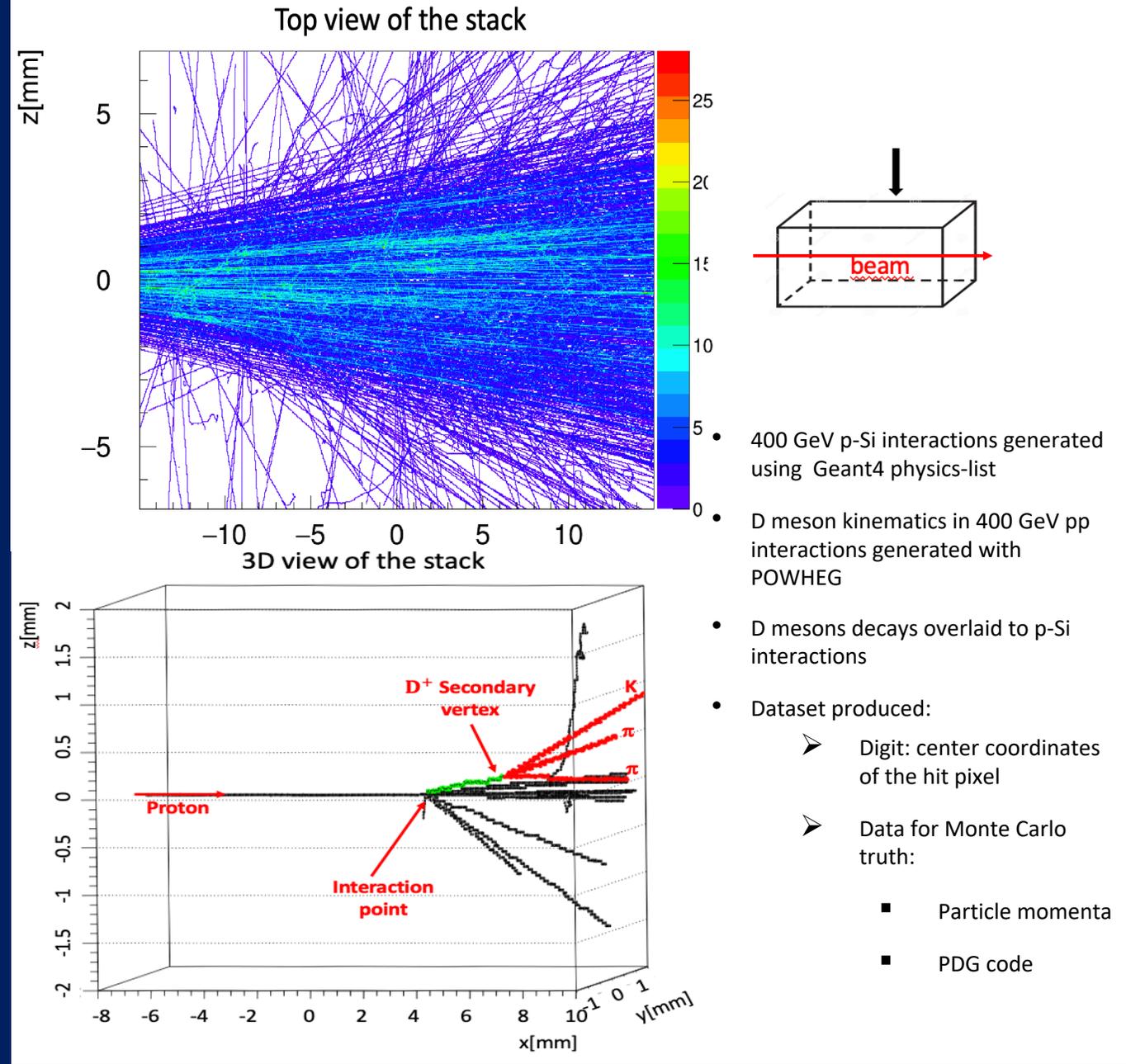
Idea:

- stack of 216 ALPIDE chips
 - matrix of 1024x512 pixels ($\sim 29 \times 27 \mu\text{m}^2$) in a surface of $\sim 30 \times 15 \text{ mm}^2$
 - thickness of 50 μm
- 3D volume of 10^8 pixels! ($\sim 30 \times 15 \times 11 \text{ mm}^3$)
- solid state bubble chamber
 - allows to perform continuous tracking with very high precision: $\sim 5 \mu\text{m}$ spatial resolution
 - possibility to observe secondary vertices inside the detector



Pixel Chamber: Geant4 Simulation

- Simulation of a prototype made of 216 ALPIDE sensors
- Each sensor is a matrix of 1024x512 pixels
- 10^4 p-Si inelastic interactions at 400 GeV/c:
- Beam simulation:
 - ✓ Gaussian y,z production coordinates with $\sigma=0.2$ mm
 - ✓ Considered some angular spread of beam direction



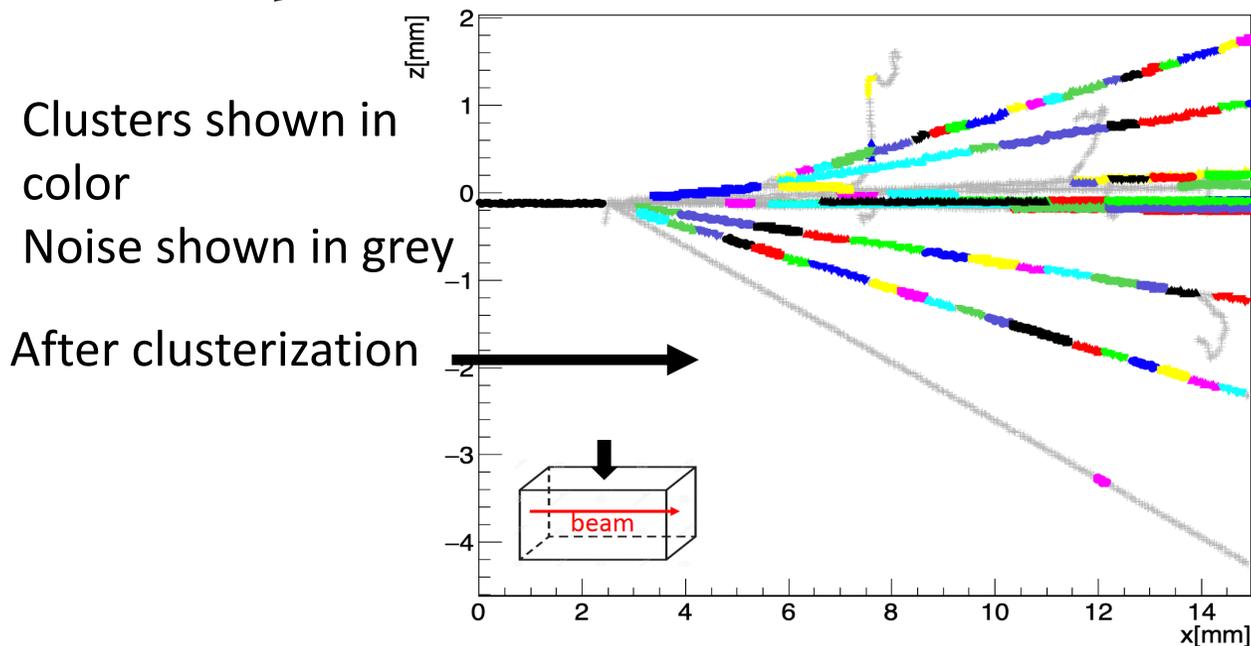
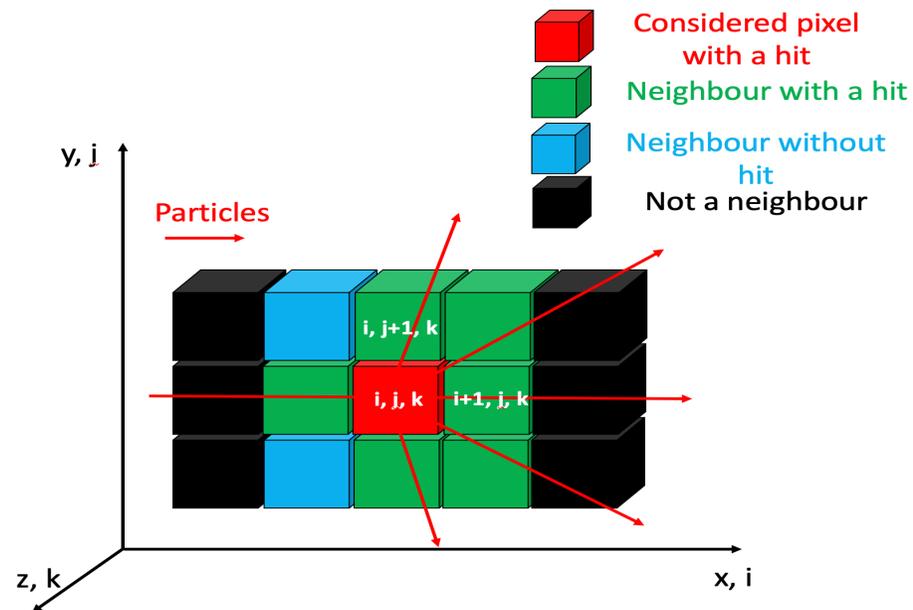
Clusterization: group hits in clusters

➤ Search of pixel neighbours

- a neighbour of a hit pixel is another hit pixel for which the discrete distance is 1

➤ Hit clusters

- Place a hit pixel into a cluster if it has 2 or 3 neighbours
- Consider a hit pixel as a noise point if:
 - Number of neighbours < 2
 - Number of neighbours > 3 required to break clusters belonging to different tracks in regions with high density of hits (example figure right)



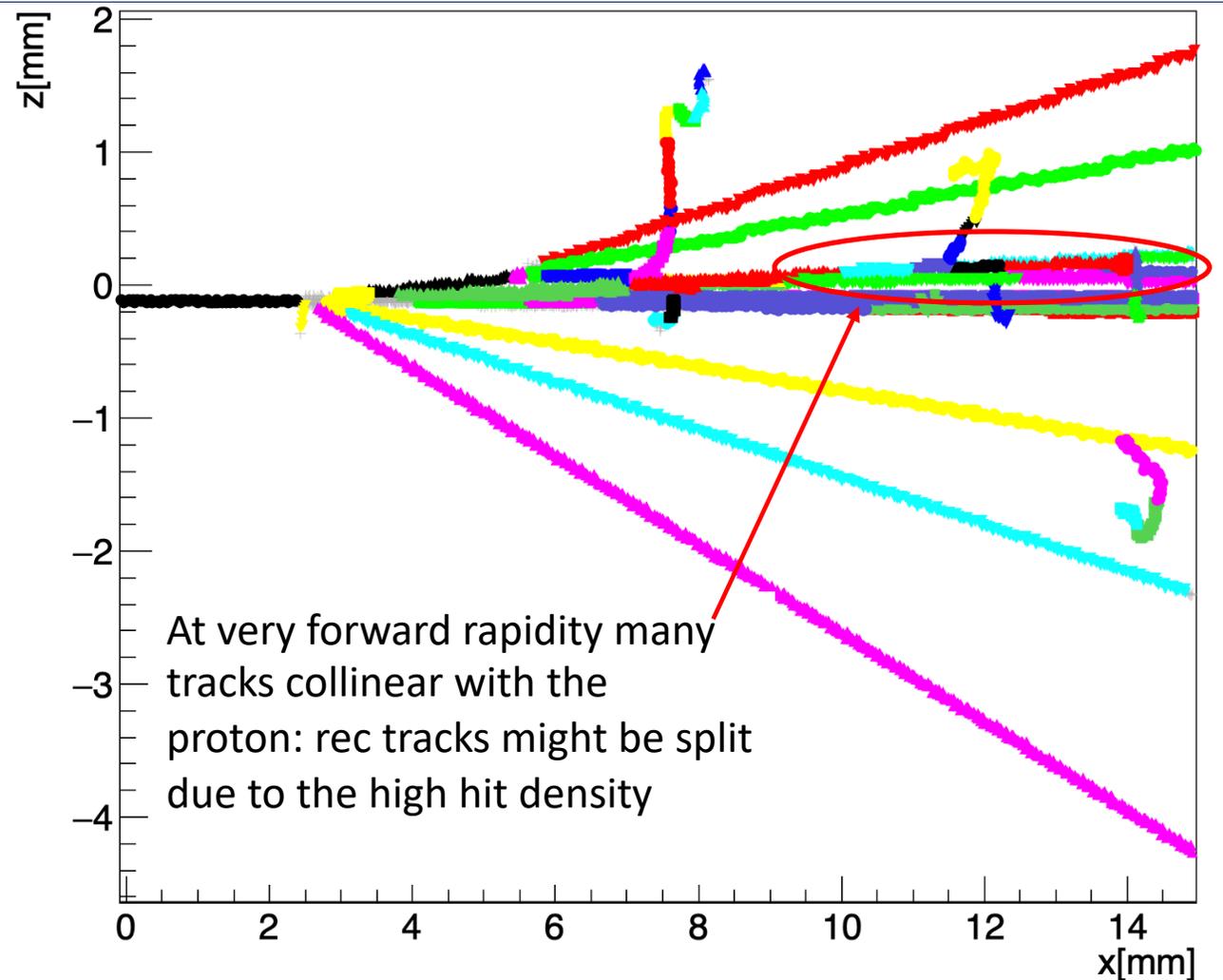
Algorithm: track finding

- Fit all reconstructed clusters with straight lines
- Merge of compatible linear clusters:
 - Compatible direction cosines
 - Cluster boundary points close to each other

Further clusterization for noise points:

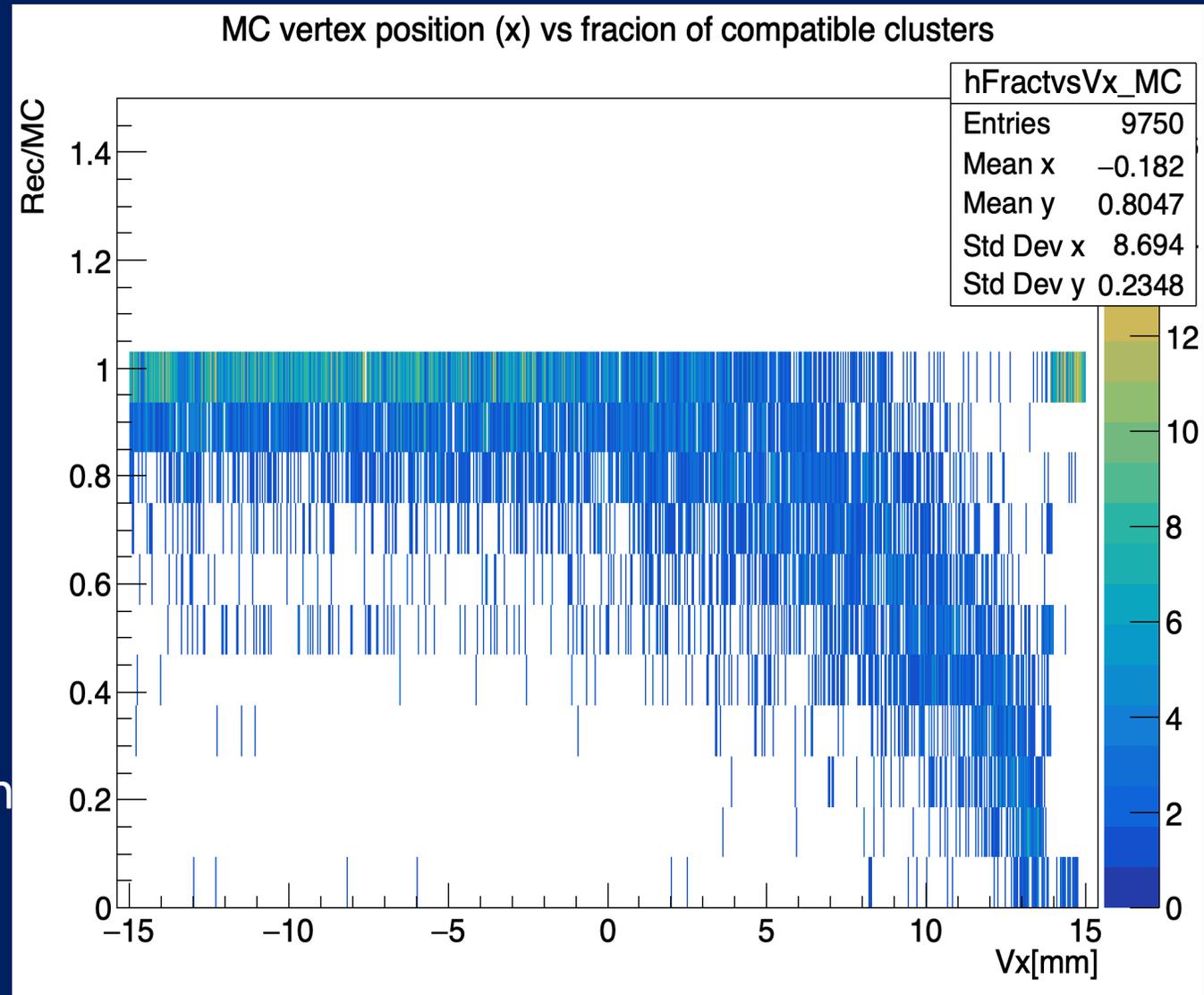
- Two more passes with less stringent neighbours condition:
 - number of neighbors < 4 and < 6

Satisfactory reconstruction of most hadronic tracks



Tracks reconstruction efficiency

- The efficiency of the track reconstruction (Reconstructed/MC tracks) gets worst at the end of the detector
- Mean value of efficiency reconstruction:
 - ~80% with no cuts on the vertex position
 - ~90% with a cut on the vertex position along $x < 5$ mm



Vertex Fit

Goal: determine x_v , y_v , z_v vertex coordinates

- Algorithm based on a *weighted* Least Square fit procedure (from LHCb[1], ALICE, NA45 and NA60)

[1]M. Kucharczyk, P. Morawski, and M. Witek, *Primary Vertex Reconstruction at LHCb*, LHCb-PUB-2014-044

1. Mandatory proton track: the track at the entrance of the sensor
2. First guess for the vertex coordinates:
 - end point of the proton track → reasonably close to the primary vertex
3. All other tracks with $\chi^2/\text{ndf} < 1.5$ from the linear fit and with more than 50 points included in the vertex fit
4. A χ_{IP}^2 is calculated for each track that expresses the distance between the fitted vertex and the calculated one (obtained from the track fit)
5. Biweighted correlation used to assign a weight (W_T) to each track under test according to their χ_{IP}^2 and some constants called Tukey's constants, in order to avoid the worsening of the vertex resolution due to tracks not well reconstructed

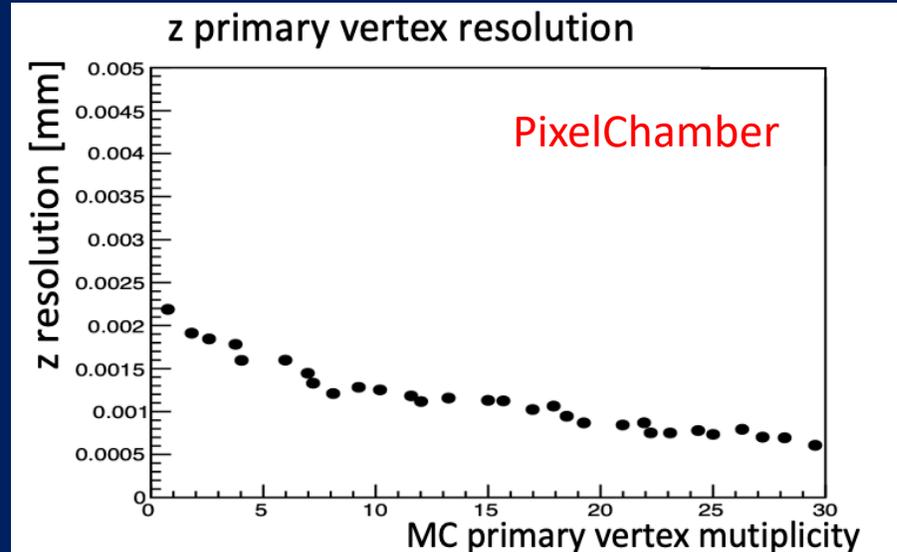
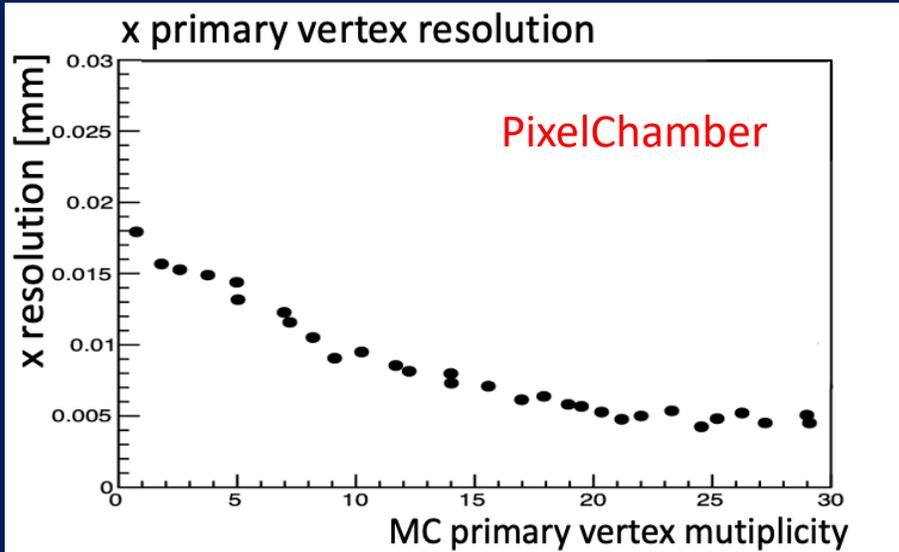
Steps of vertexing algorithm for primary vertex

5. Minimization of primary vertex χ_{PV}^2 :

$$\chi_{PV}^2 = \sum_{i=1}^{n_{tracks}} \chi_{IP_i}^2 W_{T_i}$$

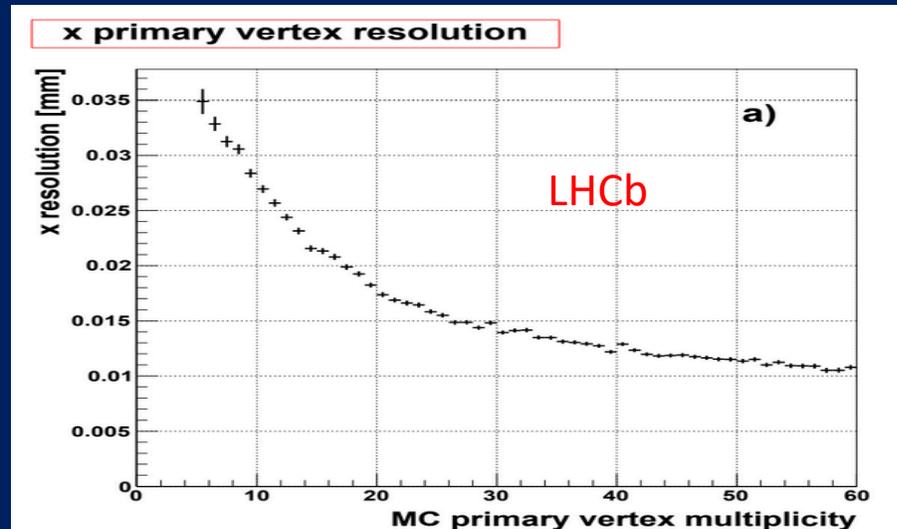
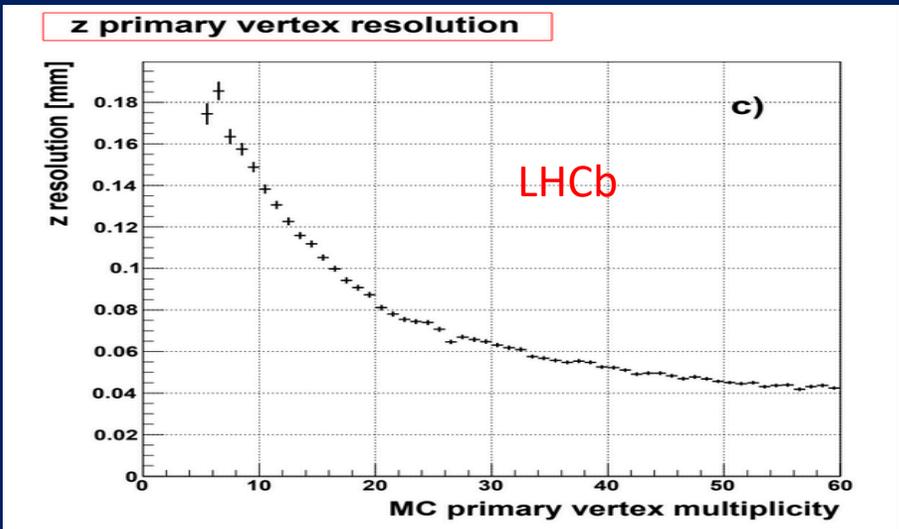
6. Iterative procedure repeated for different decreasing values of C_T
- initially set to a large value (10^6) to avoid convergence to a local minimum and decreased down iteratively \rightarrow iteration stopped upon convergence to final χ_{PV}^2
7. Updated vertex position used to recalculate χ_{IP}^2 and W_T at each iteration:
- Tracks with a zero weight at a certain iteration are not excluded \rightarrow weight recalculated at the following iteration and attached to the PV if the updated weight is different from zero

Vertex resolution vs #tracks associated to vertex



Resolution: σ of the residual
(Reconstructed vertex coordinates – MC vertex coordinates) distributions. For $N_{\text{tracks}} > 2$

- $\sigma_x = 15 \mu\text{m}$
- $\sigma_y = 2.4 \mu\text{m}$
- $\sigma_z = 1.8 \mu\text{m}$



Qualitatively the resolution with PixelChamber is a factor 10 better than LHCb

LHCb note *Primary Vertex Reconstruction at LHCb*,
LHCb-PUB-2014-044

Example of reconstructed D^0 secondary vertex

Preliminary studies on secondary vertices for $D^0 \rightarrow K \pi$:

➤ vertex searched testing two tracks at a time using the same algorithm described for primary vertex

• Monte Carlo truth for D^0 vertex:

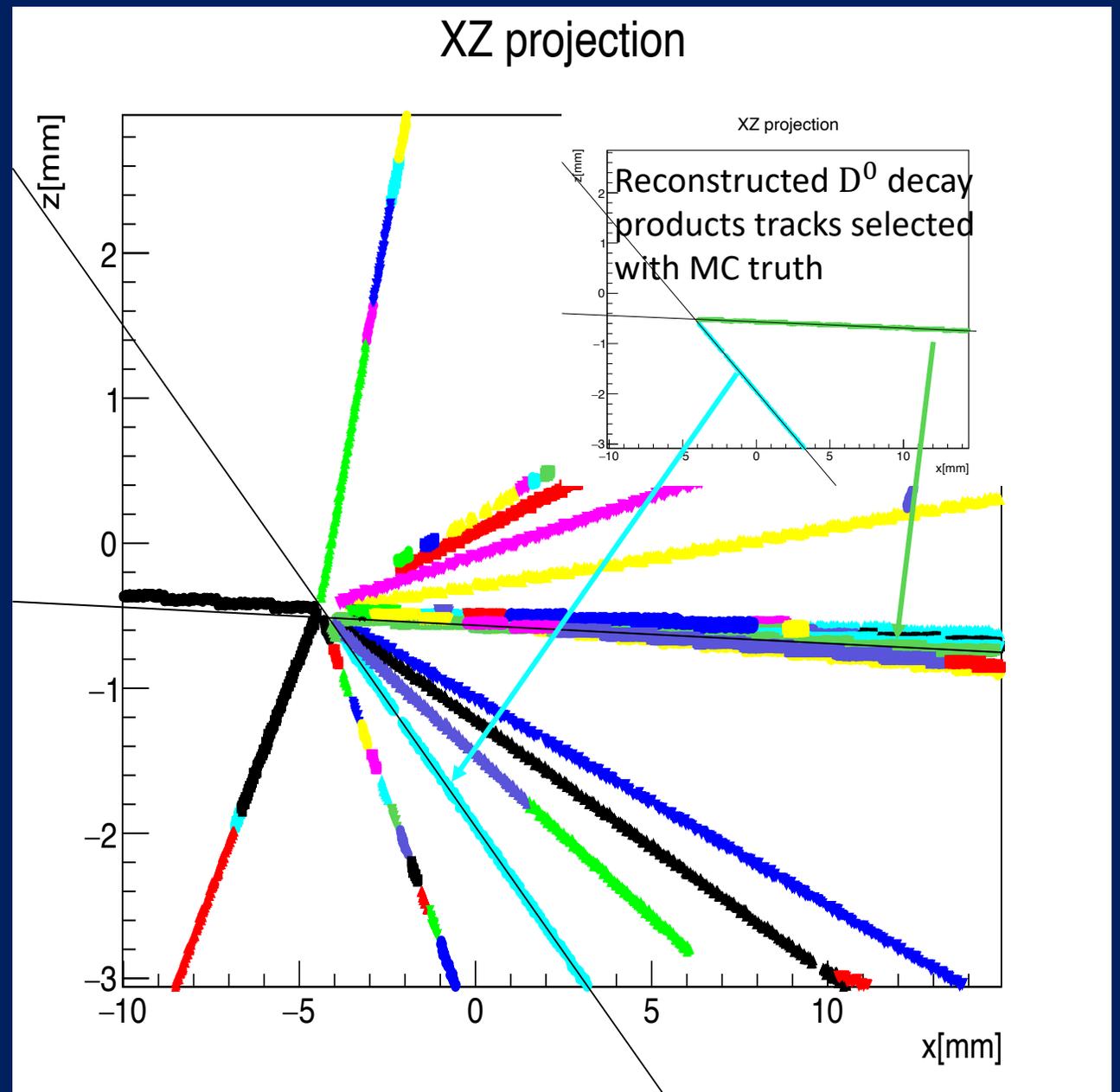
- $X_v = -4.160679$ mm
- $Y_v = 0.202199$ mm
- $Z_v = -0.514571$ mm

• Reconstructed secondary vertex:

- $X_v = -4.170620 \pm 0.002387$ mm
- $Y_v = 0.204738 \pm 0.000817$ mm
- $Z_v = -0.513834 \pm 0.000612$ mm

• Residuals:

- $\Delta X = -0.009941$ mm
- $\Delta Y = 0.002539$ mm
- $\Delta Z = 0.000737$ mm



Outlook



- ✓ Improvement of the track finding algorithm:
 - Kalman filter to take into account multiple scattering
 - Machine learning (neural network) for 3D imaging (in collaboration with M. Marchesi and R. Tonelli from Dipartimento di informatica)
- ✓ Finalize development of secondary vertex reconstruction algorithm (reconstruction of other charm and beauty states)
- Full reconstruction of charmed particles:
 - Momentum measurements of decay products with a silicon telescope
 - Detailed performance study of charm production at CERN SPS
- Construction of a detector prototype