July Production Goals

- Evaluate major DG options
 - Forward PID and backwards Emc
 - Generate signal, generic bkg. to $B \rightarrow K^{(*)}vv$, $B \rightarrow \tau v$
- Include all known detector backgrounds
 - Rad Bhabha tertiaries from machine elements
 - neutrons, photons
 - Rad Bhabha primaries
 - Pair electrons
- 10X statistics of February production
- Required ~X20 efficiency improvement

FastSim Improvements

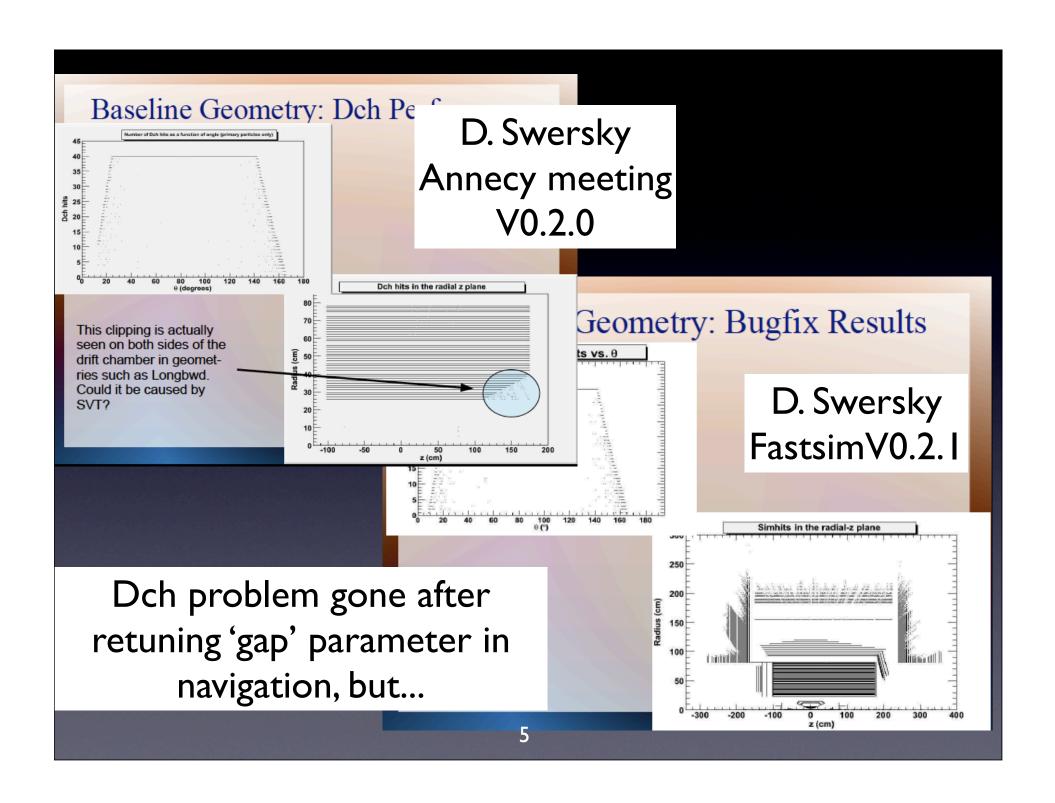
- Neutron interactions modeled in Bruno/G4
- Pair electrons filter (Svt dE/dx)
- Faster, more accurate EMC time response
- Detector-based PID selectors
 - instead of (Babar) tables
- Hadronic and Semileptonic Signal cocktails
 - preserve ~80% of relevant modes, ~10% of Xsection
- Code improvements
 - background frame reading, hit merging, ...

Net Result

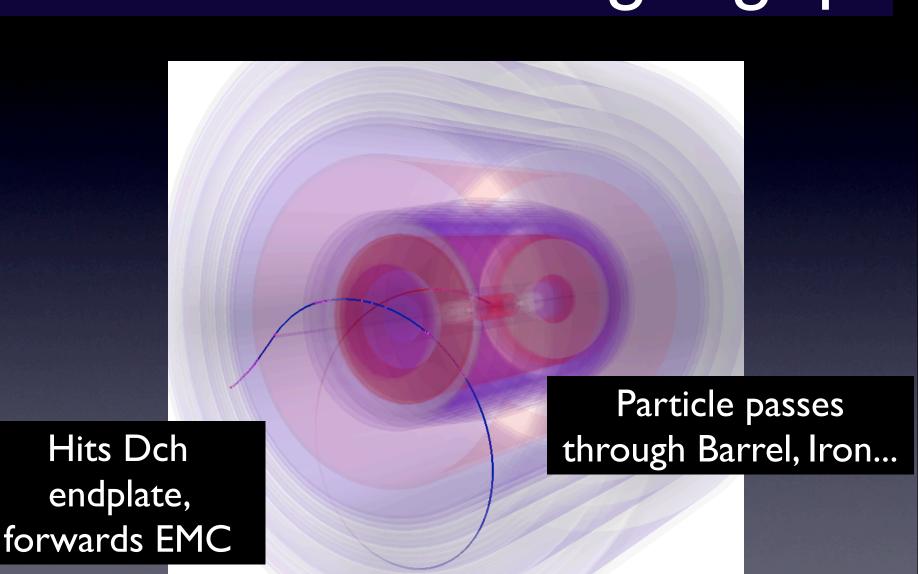
- Effective event processing rate of ~20 Hz
- > 20X per-event rate of February production

Fastsim Problems in July

- Pair electron hits merged on pion tracks
 - confused dE/dx calculations, no selector efficiency
 - Fixed (in September) by removing merged hits from dE/dx calculation
- Pair filtering has low efficiency (more later)
- → Only include neutron backgrounds (nopair)
- Navigation problems
 - known problem, but had larger impact than expected



Problems with large 'gap'

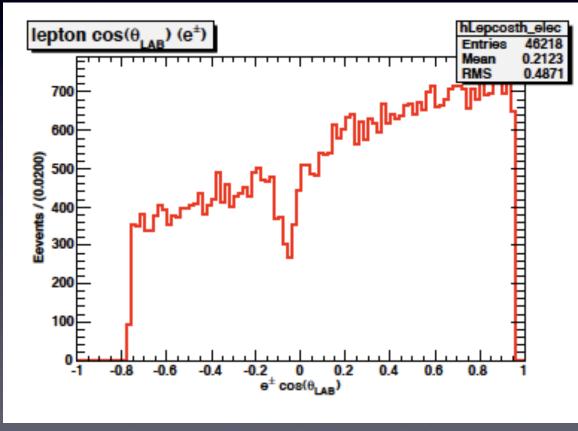


Fastsim Particle Navigation

- Old model: particle simulation navigation loops over detector elements in a fixed order
 - order set by configuration
- Works when particles have a well defined path
 - outwards through cylindrical shells (SuperB)
- Fails when particles come from 'unexpected' directions, or when elements have no fixed order WRT particle direction
 - Dch endplate vs barrel

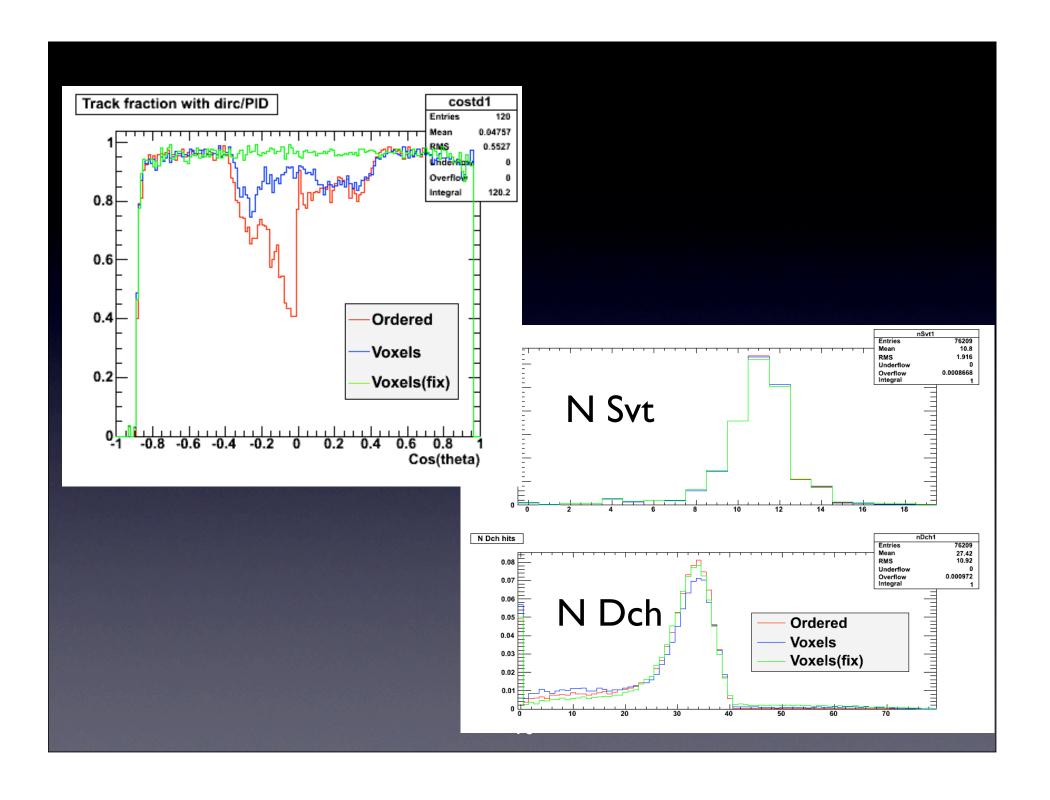
July Data Navigation Problems

- Inefficiency in PID selection vs Cos(theta)
- Not believed to directly affect DG issues



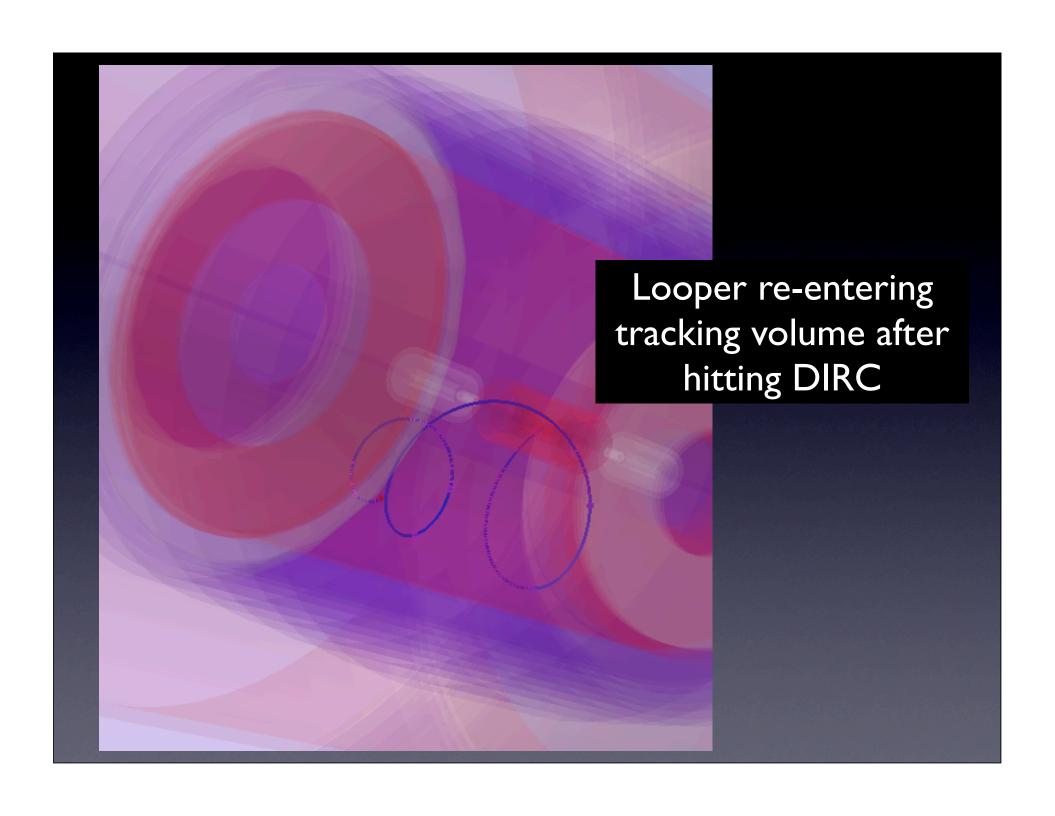
Voxel-based Navigation

- Detector volumes are divided into voxels
 - cylindrical geometry
- Voxels reference enclosed detector elements
 - No assumptions about element order inside a voxel
- Released in late August
 - ~2K lines of code, long debugging period



September Problems

- After Navigation fix, low Pt tracking inefficiency
 - energy loss changes trajectory, track fit fails
 - solution: ignore hits after significant energy loss
- Pair filtering exposed old BaBar bug
 - PID maps keyed to candidate pointers, not UID
 - 'Solution': limit electron selectors to >100MeV
- Pilot error updating release for production
 - build and validation are made by hand
- Fully functional executable not produced till 23 Sept.
 - ~1% of jobs fail due to code problems



Why weren't problems found and fixed earlier?

 Insufficient manpower to develop and validate code and procedures required to meet production goals

Conclusions

- Technical goals of July production were met
 - Efficiency improvements
 - Background mixing
 - Navigation rewrite
- Not all fixes were available at production start
- Lesson for SuperB: more manpower is needed to meet experiment software goals