

# Dynamic aperture studies with MADX

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#### Hamiltonian

Hamiltonian of the system:

$$
H = -(1 + hx) \left[ \sqrt{1 + \frac{2\delta}{\beta_0} + \delta^2 - (P_x - K_x)^2 - (P_y - K_y)^2} + K_s \right] + \frac{\delta}{\beta_0} + 1
$$

with :  $K_{x,y,s} = \frac{q A_{x,y,s}}{R_0}$  $\frac{A_{x,y,s}}{p_0}$ ,  $P_{X,Y} = \frac{p_{x,y}}{p_0}$  $\frac{\partial x . y}{\partial \rho_0}$  ,  $\rho_0$  the total momentum The Taylor expansion of the Hamiltonian of an ideal straight magnet is:

$$
H = \frac{P_x^2 + P_y^2}{2} + K_1 \frac{x^2 - y^2}{2}
$$
 Linear terms  
+  $K_2 \frac{x^3 - 3xy^2}{6}$  Sextupoles  
+  $\left(P_x^2 + P_y^2\right)^2 / 8$  Kinematic term  
+  $K_3 \frac{x^4 - 6x^2y^2 + y^4}{24}$  Octupoles  
+ Chromatic terms +  $\mathcal{O}(5)$ 

Action-Angle variables:

The position and momentum of the particle can be written under the form:

$$
x = \sqrt{2\beta_x J_x} \sin(2\pi\mu_x + \phi_x)
$$
  
\n
$$
P_x = \sqrt{\frac{2J_x}{\beta_x}} (\cos(2\pi\mu_x + \phi_x) - \alpha_x \sin(2\pi\mu_x + \phi_x))
$$
  
\n
$$
\mu_x = \int_0^s \frac{dt}{\beta_x(t)}
$$

At first order, the tune shift due to a perturbation ∆H of the Hamiltonian is given by:

$$
\Delta v_x = \frac{1}{2\pi} \oint \left\langle \frac{\partial \Delta H}{\partial J_x} \right\rangle_{\phi} ds, \Delta v_y = \frac{1}{2\pi} \oint \left\langle \frac{\partial \Delta H}{\partial J_y} \right\rangle_{\phi} ds
$$

#### Kinematic term

The perturbation of the Hamiltonian by this effect is:

$$
\Delta H = \frac{\left(P_x^2 + P_y^2\right)^2}{8}
$$

The first-order contribution of the kinematic terms to the tune is then:

$$
C_{xx} = \frac{\partial v_x}{\partial J_x} = \frac{3}{16\pi} \oint \gamma_x^2 \mathbf{ds} \qquad C_{xy} = \frac{\partial v_x}{\partial J_y} = \frac{1}{8\pi} \oint \gamma_x \gamma_y \mathbf{ds}
$$

$$
C_{yy} = \frac{\partial v_y}{\partial J_y} = \frac{3}{16\pi} \oint \gamma_y^2 \mathbf{ds}
$$

The main contribution is where the gamma function is the largest: at the IP.

The strongest sextupoles are in the interaction region to cancel the local chromaticity and the betatron function are high too. These sextupoles are then the main contribution to the non linearities. To kill the second order terms the phase advance between them is *π*. The kick in position due to this kind of structure is then:

$$
x_1 = -x_0 - P_{x,0}L - \frac{(K_2L)^2}{12}(x_0^3 + x_0y_0^2)L^2 + \mathcal{O}(5)
$$

The second order is effectively killed.

**BUT:** Third order terms are not canceled for thick sextupoles.

The effect is quadratic and not proportional to the strength of the sextupole.

## Crab sextupoles



The crab sextupole strength is given by  $^{\rm l}$  :

$$
K_2L = \frac{1}{\theta} \frac{1}{\beta^*_y \beta_y} \sqrt{\frac{\beta^*_x}{\beta_x}}
$$

1 "SUPPRESSION OF BEAM-BEAM RESONANCES IN CRAB WAIST COLLISIONS", P. Raimondi et al., EPAC08, Genoa

## Crab sextupoles



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$$

A factor 2 is missing. To take into account in the future.

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### Fringe field in the quadrupoles

The perturbated Hamiltonian is:

$$
\Delta H = -\frac{K_1'}{12}(x p_x(x^2 - 3y^2) - y p_y(y^2 - 3x^2)) - \frac{K_1''}{48}(x^4 - y^4) + \mathcal{O}(5)
$$

The derivative of the tune with the amplitude is then:

$$
C_{xx} = \frac{1}{8\pi} \sum_{QP} K_1(\alpha_{x,O}\beta_{x,O} - \alpha_{x,i}\beta_{x,i})
$$
  
\n
$$
C_{xy} = \frac{1}{8\pi} \sum_{QP} K_1(\alpha_{x,O}\beta_{y,O} - \alpha_{x,i}\beta_{y,i} - \alpha_{y,O}\beta_{x,O} + \alpha_{y,i}\beta_{x,i})
$$
  
\n
$$
C_{yy} = \frac{-1}{8\pi} \sum_{QP} K_1(\alpha_{y,O}\beta_{y,O} - \alpha_{y,i}\beta_{y,i})
$$

The main contribution is where the beta function is the largest with  $K_\mathrm{l}$ : at the quadrupole QD0 near the IP.

## **Octupoles**

The perturbation of the Hamiltonian is:

$$
\Delta H = K_3 \frac{x^4 - 6x^2y^2 + y^4}{24}
$$

After calculation, we have:

$$
C_{xx} = \frac{1}{16\pi} \oint K_3 \beta_x^2 ds \qquad C_{xy} = \frac{-1}{8\pi} \oint K_3 \beta_x \beta_y ds
$$
  

$$
C_{yy} = \frac{1}{16\pi} \oint K_3 \beta_y^2 ds
$$

Remark: The kick in x due to a thin octupole is proportional to  $x^3-3xy^2$  whereas the kick due to the fringe field is  $x^3+3xy^2$ .

⇒ It is not possible to compensate the fringe field with octupoles.

## MAD8 or MADX?

The aim was to cross check the results from the simulations of Piminov and Levichev.

- The first idea was to use the very powerful package PTC to make the study of the dynamic aperture. The big advantages are:
	- **Possibility to track at a very high order.**
	- $\blacksquare$  The values of the derivatives of the tune with amplitude and momentum can be calculated at the order we wish.
	- $\blacksquare$  The fringe field can be simulated in the quadrupoles.

**BUT:** The fringe field in the quadrupoles is taken into account neither by MADX alone nor by MAD8. ⇒ The source code of Mad8 was modified. The tracking is then with Lie4 method.

## Summary of the contributions HER







Average agreement Acceleraticum with analytical formulae (kinematic and fringe field term).

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Very good agreement MADX-PTC with analytical formulae.

## Summary of the contributions LER







Average agreement Acceleraticum with analytical formulae (kinematic and fringe field term).

## Summary of the contributions LER







Very good agreement MADX-PTC with analytical formulae.

## Comparison MADX-PTC/MAD8



Good agreement between both codes.

## Comparison MADX-PTC/Acceleraticum



Good agreement between both codes.

## Comparison MADX-PTC/Acceleraticum



Good agreement between both codes.

## Dynamic aperture



With crab sextupole HER





The dynamic aperture is a bit different between MADX-PTC and Acceleraticum.

The reason why we have this difference is a different treatment of the kinematic term but a new patch in Acceleraticum should reduce the difference (the kinematic term will be taken into account in the quadrupoles too).

A way to enlarge the dynamic aperture is to change the strength of the octupoles (one near the IP and the other near the crab sextupole).

The optimization was made "by hand". A tracking was made for different parameter sets for the octupole strengthes. I have then chosen the parameter set which minimizes the non linearities.

#### Tracking with octupoles



Very weak octupoles (-5 m $^{-3}$  and -180 m $^{-3}$ )

### Tracking with octupoles



Very weak octupoles (-5 m $^{-3}$  and -240 m $^{-3}$ )

## Dynamic aperture with octupolar correction







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## Dynamic aperture with octupolar correction



 $50$ 

 $-30$  $-20$  $-10$  $\triangle$ 10 20  $30$ 

number of  $\sigma_s$ 

50

 $\Omega$  $-30$  $-20$  $-10$  $\circ$ 10 20  $30$ 

number of  $\sigma_s$ 

## Correction with decapoles

The dynamic aperture shrinks a lot with the momentum. Optimizing the dynamic aperture on momentum with octupoles might shorten it off momentum. An idea is to add decapoles in dispersive regions. That enables to add an octupolar term proportional to the dispersion and *δ* at the decapole location. For the moment, there is no significant gain. Further studies (location and strength of the decapoles, ...) are needed.

## Conclusion

- Some simulations with MADX-PTC taking into account the fringe field were performed.
- A preliminary cross-checking of Piminov and Levichev's results was made by taking into account the fringe field effect in the quadrupoles.
- **The order of magnitude for the dynamic aperture** found with MADX-PTC is quite coherent with their results despite a few differences (kinematic term contribution).
- $\blacksquare$  It is possible to enlarge significantly the on momentum dynamic aperture by adding weak octupoles in the structure.
- **More studies must be pursued to evaluate if** decapoles would be useful for the off momentum dynamic aperture.