# PM2022 - 15th Pisa Meeting on Advanced Detectors

## **Expected reconstruction performance with the** new ATLAS Inner Tracker at the High-Luminosity LHC

The High Luminosity-Large Hadron Collider is expected to start in 2029 and to provide an integrated luminosity of 4000 fb<sup>-1</sup> in ten year, about a factor 20 more than what was collected so far. This high statistics will allow to perform precise measurements in the Higgs sector and improve searches of new physics at the TeV scale. The luminosity needed is L  $\sim$ 7.5 10<sup>34</sup> cm<sup>-2</sup> s<sup>-1</sup>, corresponding to  $\sim$ 200 additional proton-proton pile-up interactions, which can significantly degrade the reconstruction performances. To face such harsh environment some sub-detectors of the ATLAS experiment will be upgraded or completely substituted. The current Inner Detector will be replaced with a new all-silicon Inner Tracker (ITk) designed to face the challenging environment associated with the high number of collisions per bunch crossing. In this poster an overview of the ITk performance to reconstruct and identify high-level objects will be shown. A particular focus will be given to the pile-up jets tagging and the impact of the spatial density of the number of collisions per bunch crossing

### New Inner Tracker (ITk) at HL-LHC



CERN-LHCC-2017-005, ITk Strip TDR CERN-LHCC-2017-021, ITkPixel TDR

Sensor Technology

*Motivation*: To face the harsh environment at HL-LHC, the current inner detector will be replaced with a new fullsilicon Inner Tracker (ITk).

#### **Finer segmentation**

- More and smaller channels
- All silicon inner tracker with strips and pixel
- Extension up to  $|\eta| < 4$

Increase radiation hardness: new sensors & front-end

**HL-LHC** *Pile-up* conditions

- Larger average number of pile-up interaction per bunch crossing
- Larger **pile-up density =**

fraction of events where a vertex is reconstructed within 0.1 mm of the true hard-scatter position in the longitudinal direction

 $\rightarrow$  Impact on reconstruction and identification of high level objects



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## Vertexing

- Vertices reconstructed through an Adaptive Multi-Vertex Finder algorithm
- Primary vertex identified as the reconstructed vertex with the largest  $\sum p^2_{\tau}$  of associated tracks



di ley	1.4 ATLAS Simulation Preliminary
פווכו	Single e, pT = 100 GeV 1.2 √s = 14 TeV, ⟨μ⟩ = 200



Photon conversion reconstruction efficiency above 80% up to the first

Several HL-LHC configurations Parameter 8b+4e 200 MHz No CCs Baseline Flat z<sub>RMS</sub> at start of leveling [mm] 54 37 to mitigate risks and reduce costs 47  $z_{\rm RMS}$  at end of leveling [mm] 41 39 42 44 29  $\rightarrow$  Impact on the luminous region, Peak instantaneous luminosity [ $\times 10^{34}$  cm<sup>-1</sup>s<sup>-2</sup> 5.5 7.5 7.5 7.5 7.5 Peak pileup density at start of leveling [mm<sup>-1</sup>] 1.58 1.48 2.13 1.62 1.56 the pileup conditions and luminosity Peak pileup density at end of leveling  $[mm^{-1}]$ 1.93 2.73 1.95 2.02 1.88 Effective pileup density over fill [mm<sup>-1</sup>] 1.08 1.58 1.20 1.20 1.17 Yearly integrated luminosity [fb<sup>-1</sup>/160 days] 326 340 243 304 293

#### **Pile-up Jet tagging:**

- Up to 20% efficiency deterioration in the forward region at typical working points.
  - Expected improvement using time information from the new High Granularity Time Detector





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