



# Z identification (ZID) with TW detector

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# What we have done

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- **Goal:** introduce an algorithm in SHOE to identify the fragment charge  $Z$ , on an event-by-event basis, exploiting the energy released in the TW as a function of the ToF information (TW-SC).

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- The idea is to parametrize Bethe-Bloch (BB) curves as a function of ToF (  $\beta$  depends on the tracking ( $L$ ) while the  $Z$  info has to be provided before tracking ) and assign to each TW hit (ToF,Eloss) the  $Z$  corresponding to the closest BB curve

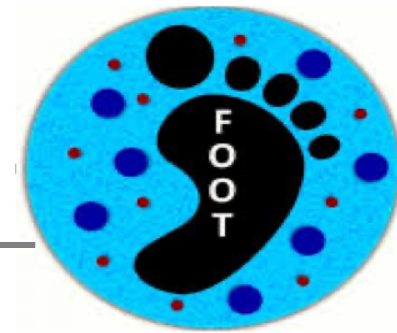
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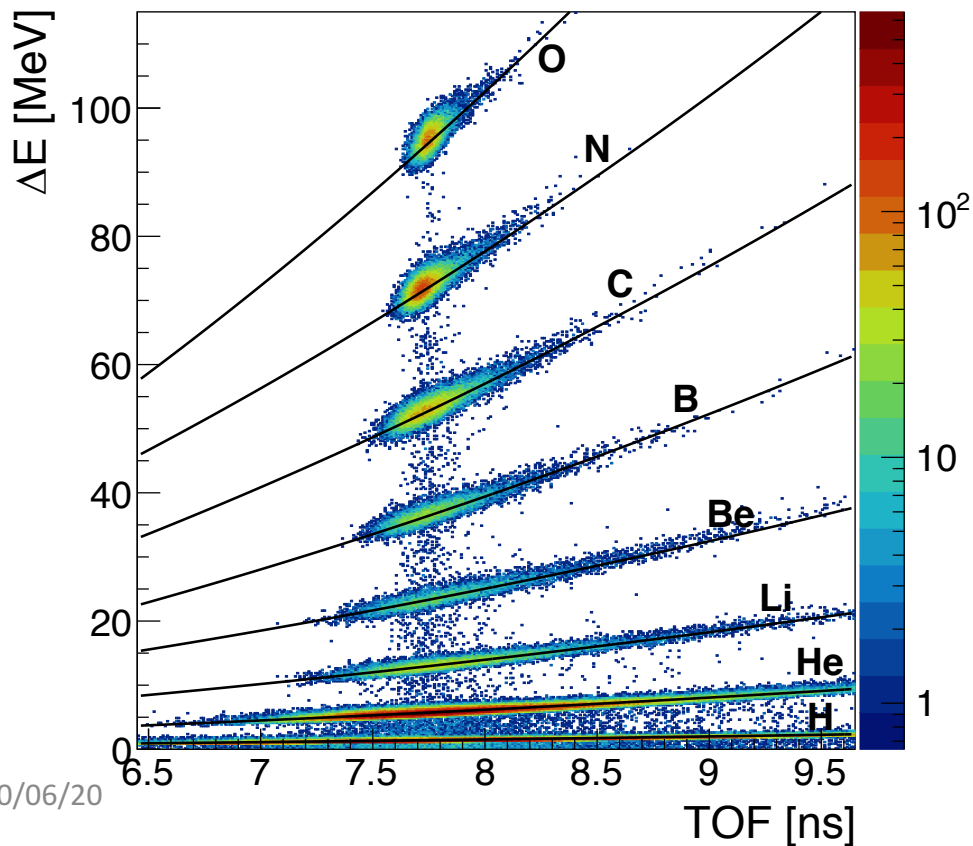
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- This has been tuned for various MC productions ( $^{12}\text{C}$  and  $^{16}\text{O}$  with full and GSI geometries) and applied on GSI DATA ( $^{16}\text{O}$  400 MeV/n) after having introduced in SHOE the calibration performed by the TW - Pisa group

# Bethe-Bloch parametrization

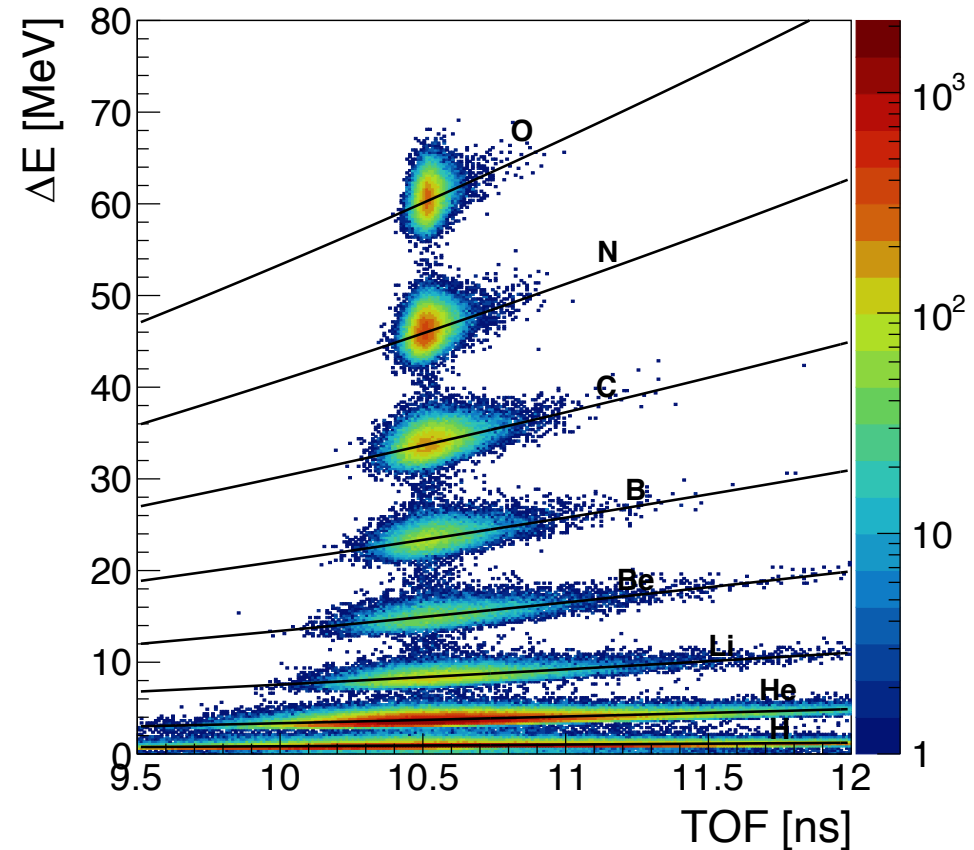


Bethe-Bloch parametrization from **Monte Carlo truth**, asking for primary fragmentation and Z\_MC.

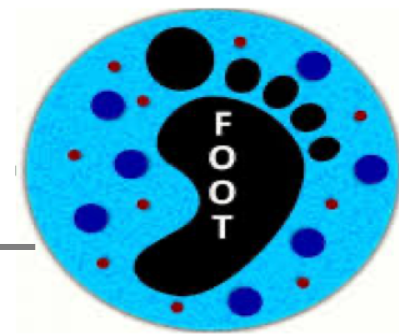
$^{16}\text{O} - 200 \text{ MeV/n}$  MC true – full geo



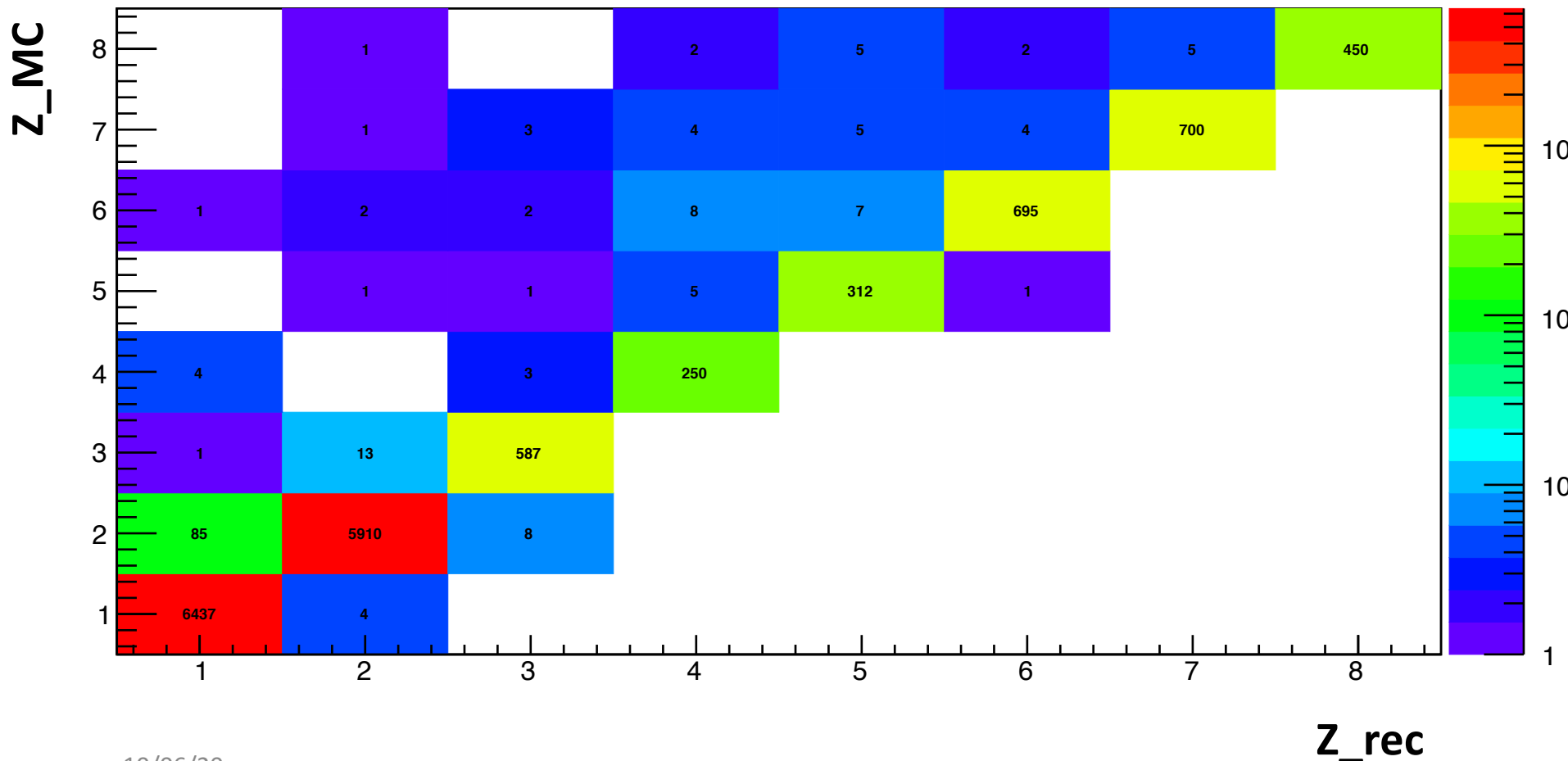
$^{16}\text{O} - 400 \text{ MeV/n}$  MC true - GSI



# Algorithm performances: MC true



$^{16}\text{O}$  – 200 MeV/u MC rec – full geo

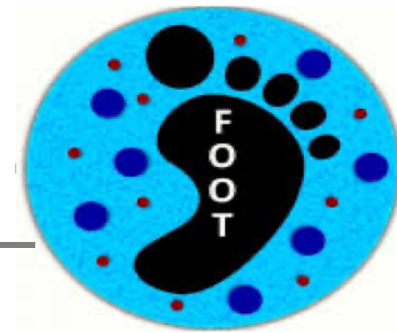


Good ZID algorithm performances (wrong Z charge assignment < **1.2%**)

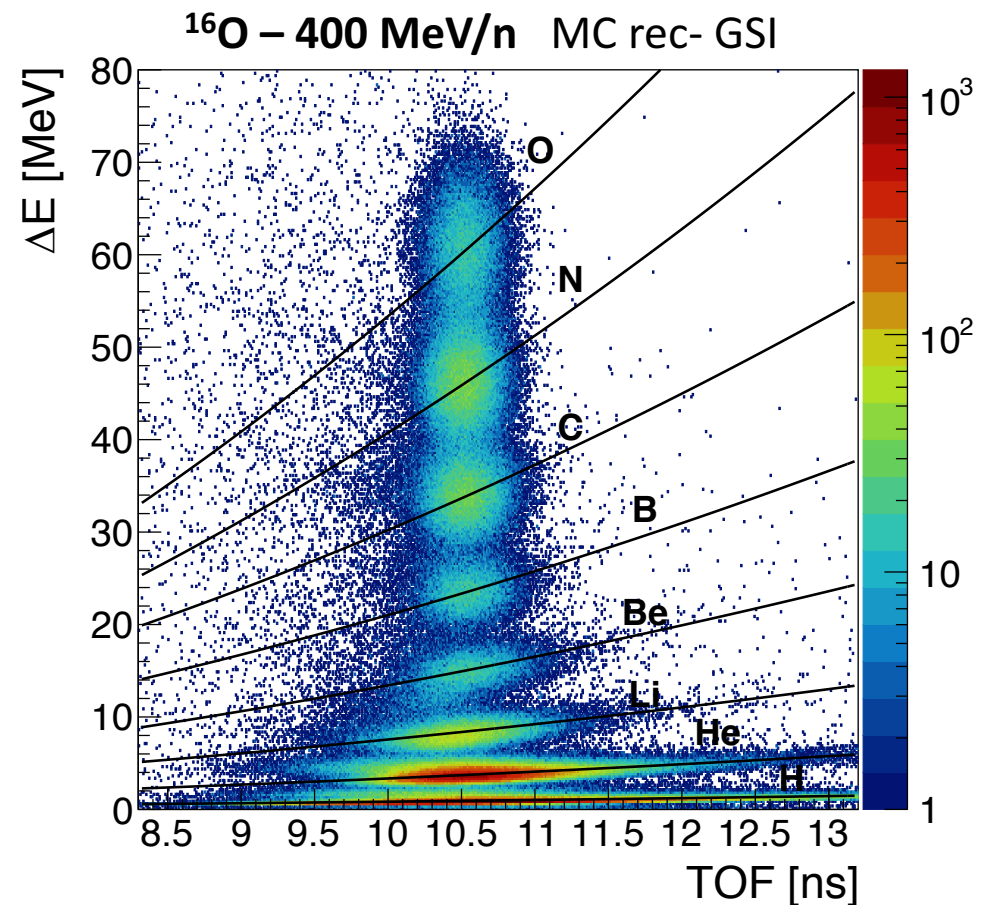
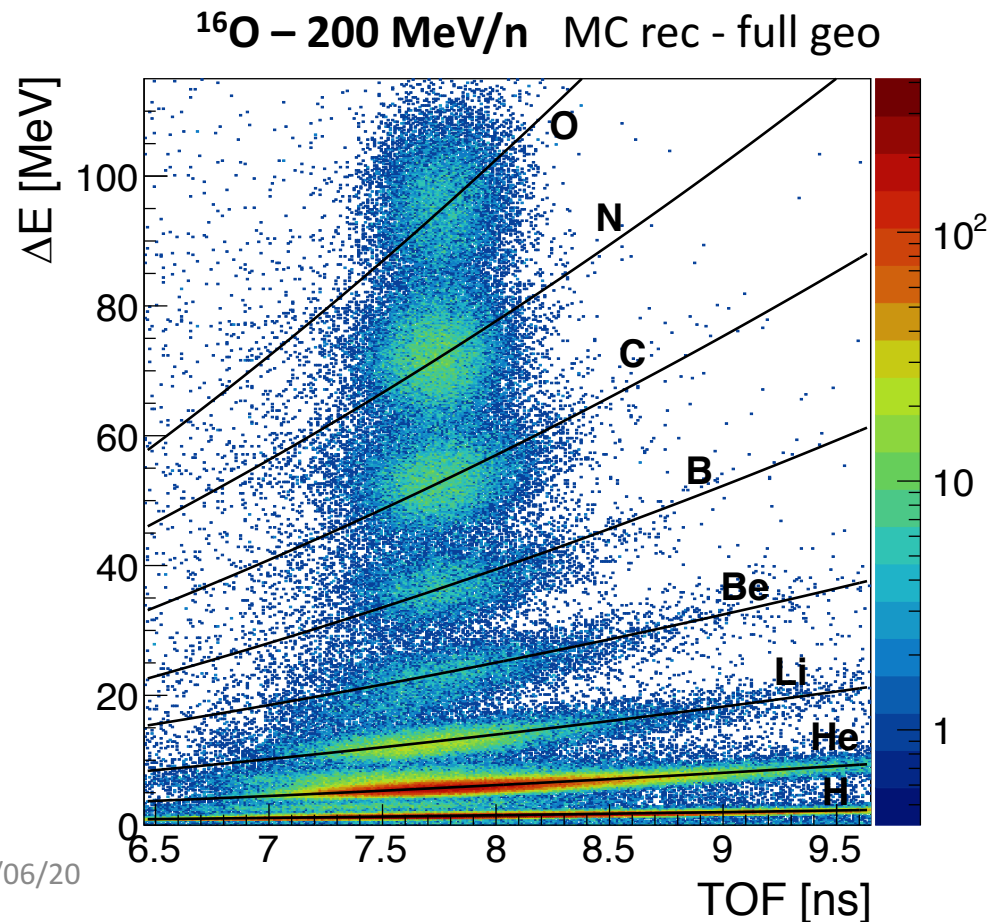
→ MC true with request of only primary fragments in order to tune the algorithm



# ZID for reconstructed MC

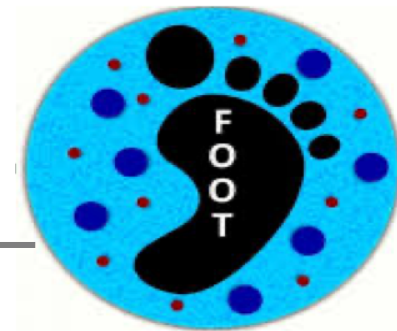


The BB curves are superimposed on the **reconstructed MC**. Pile-up and Eloss and ToF resolution from calibration data (thanks to Pisa group) have been implemented in SHOE

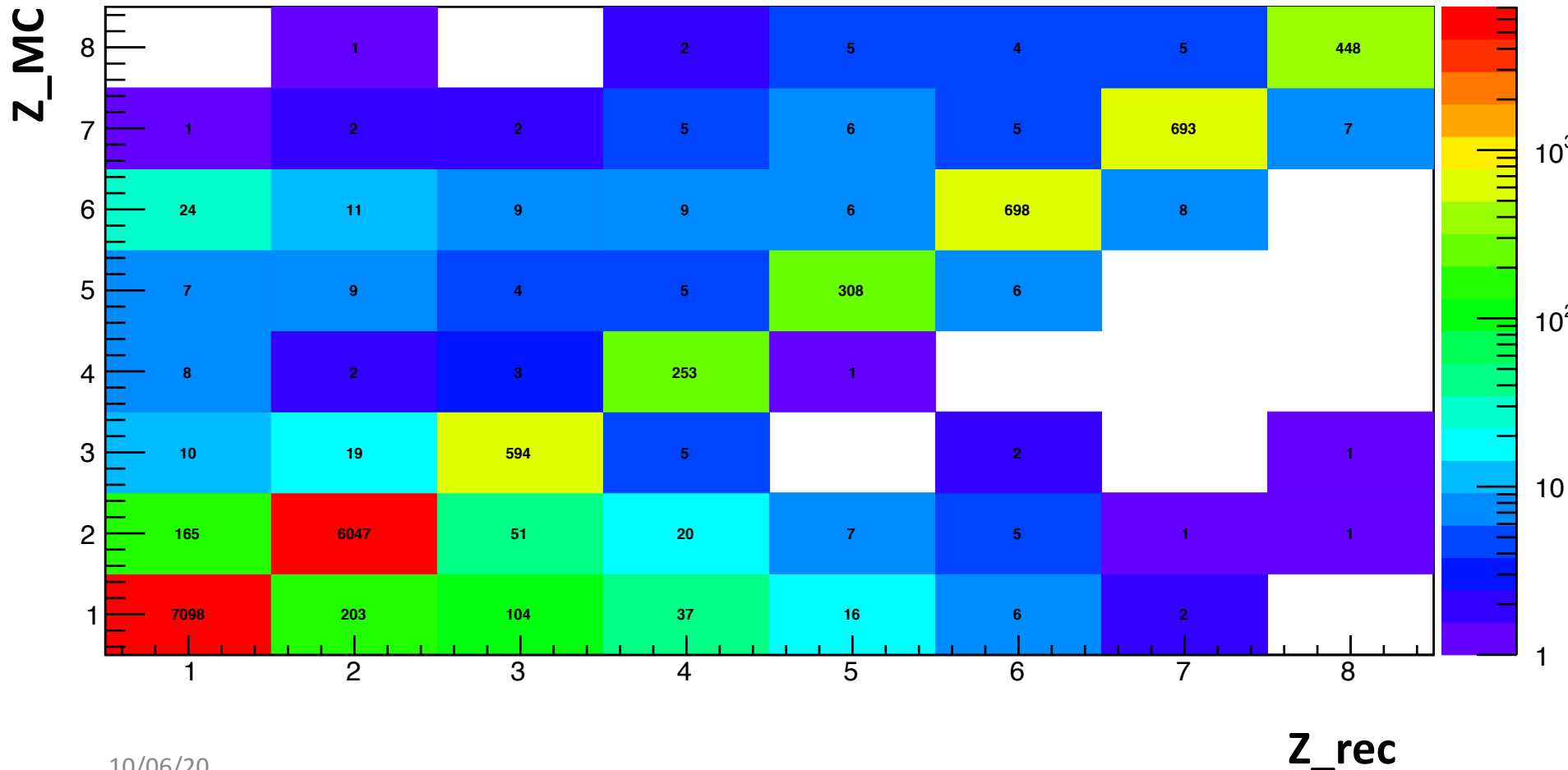




# Algorithm performances: MC rec



$^{16}\text{O}$  – 200 MeV/u MC rec – full geo



Good Zid performances.  
(wrong Z charge assignment < **4.8%**)

[Here reconstr. MC with no Pile-Up: impossible to assign a true MC Z charge in the case of Pile-Up]

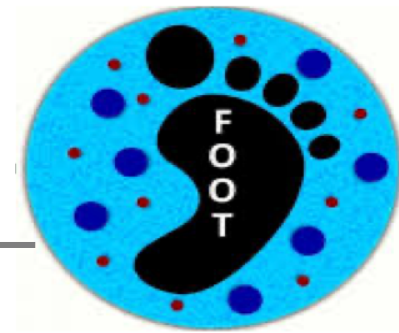
# Moving ZID from MC to GSI DATA

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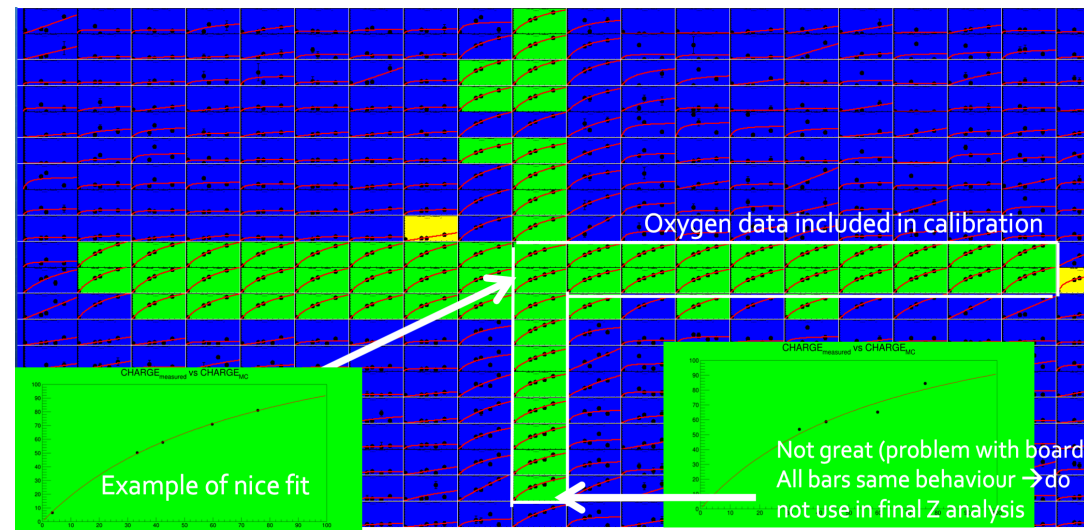
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1. Energy loss and TOF calibration performed by the Pisa group has been implemented in SHOE: such calibration takes care of TW detector light response inhomogeneities along each bar providing a very precise «Position per Position» calibration.



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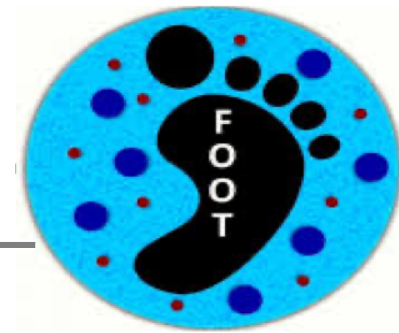
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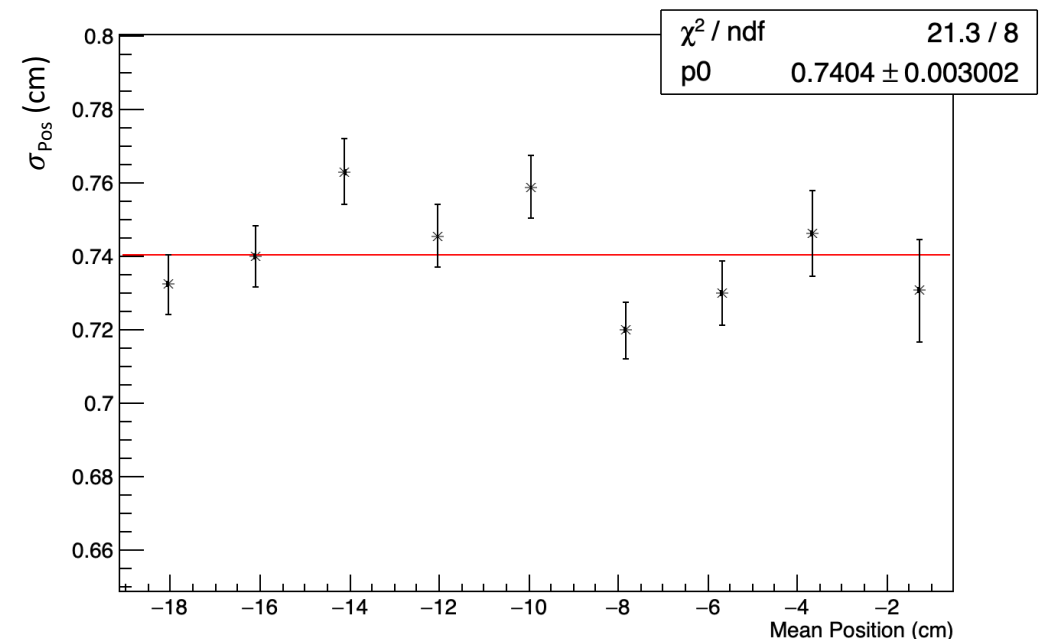
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2. Extended the calibration to the not-calibrated position filling empty positions with the average of the calibrated positions of the same bar/layer.

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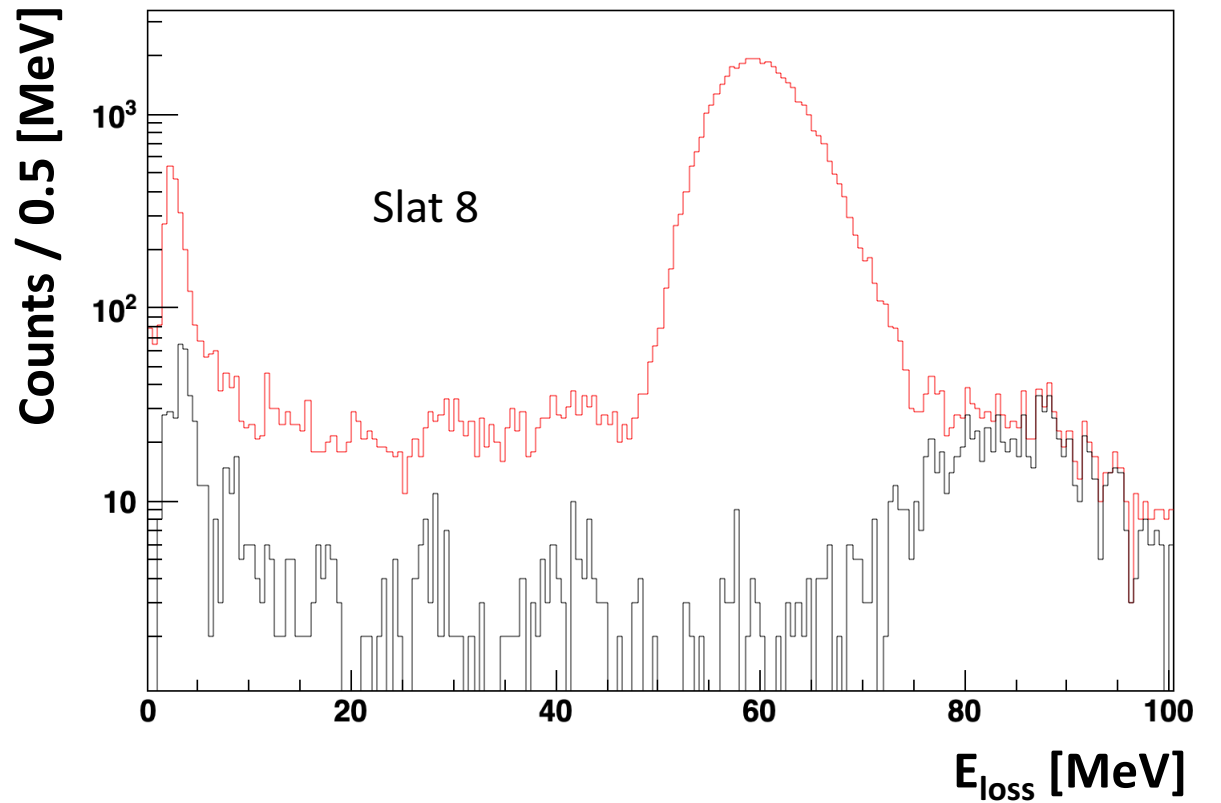
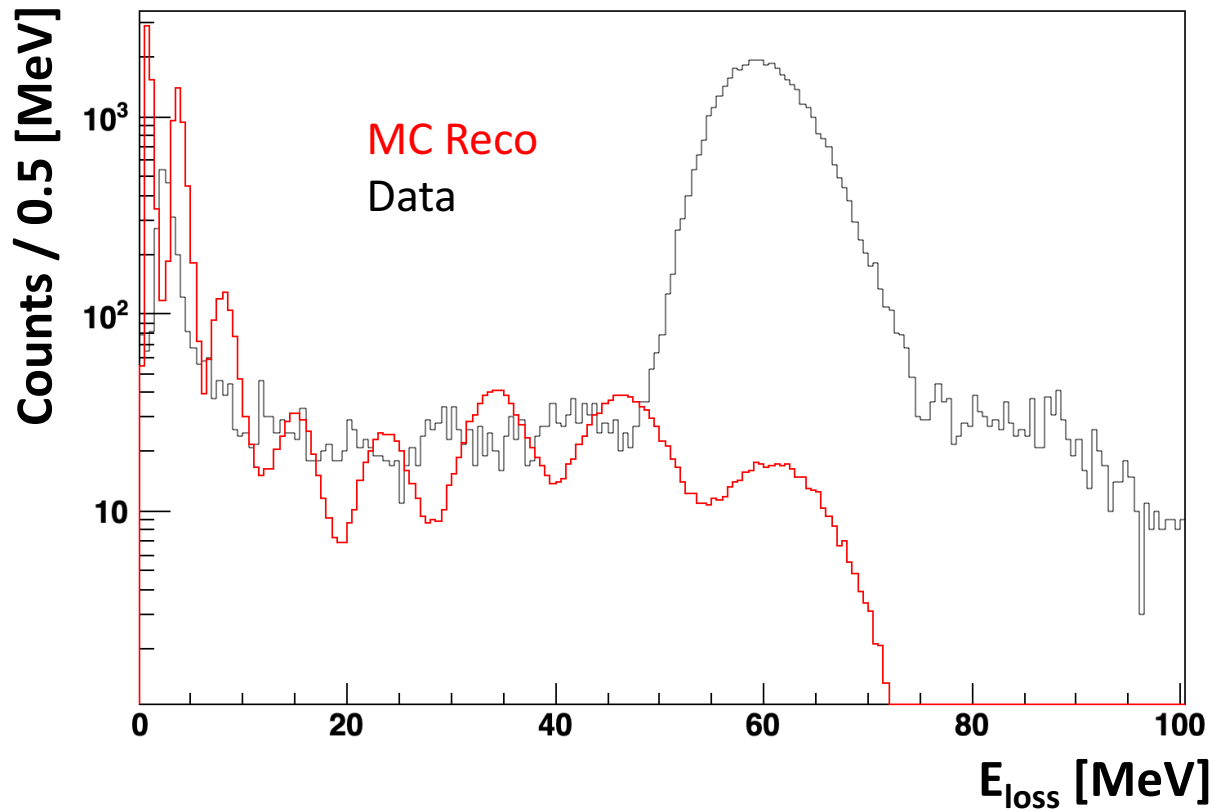
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3. Ghosts have been managed on an event-by-event basis exploiting the reconstructed position along the bar from time differences at the bar edges (with  $\sigma_{POS} < 8$  mm, less than bars cross of 2 cm )



# Moving ZID from MC to GSI DATA



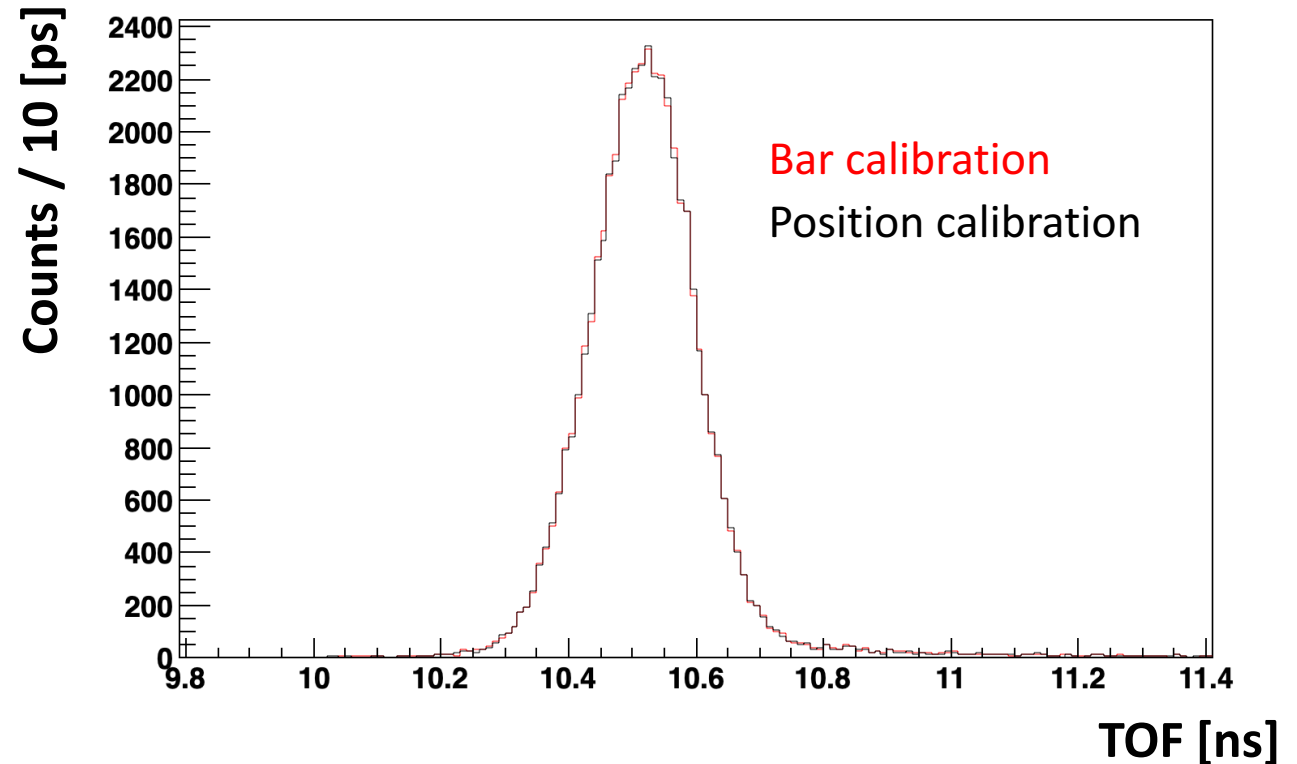
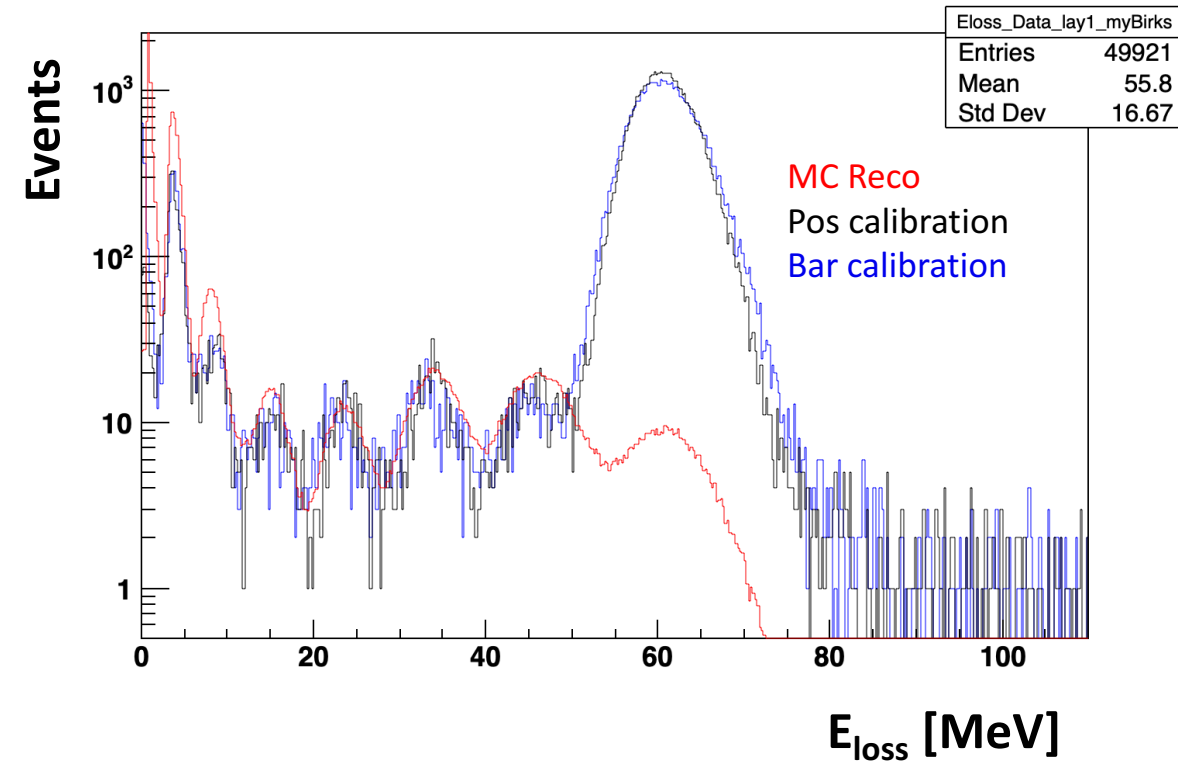
4. After calibration a further small tuning of the peaks to the MC energy has been necessary



# Moving ZID from MC to GSI DATA

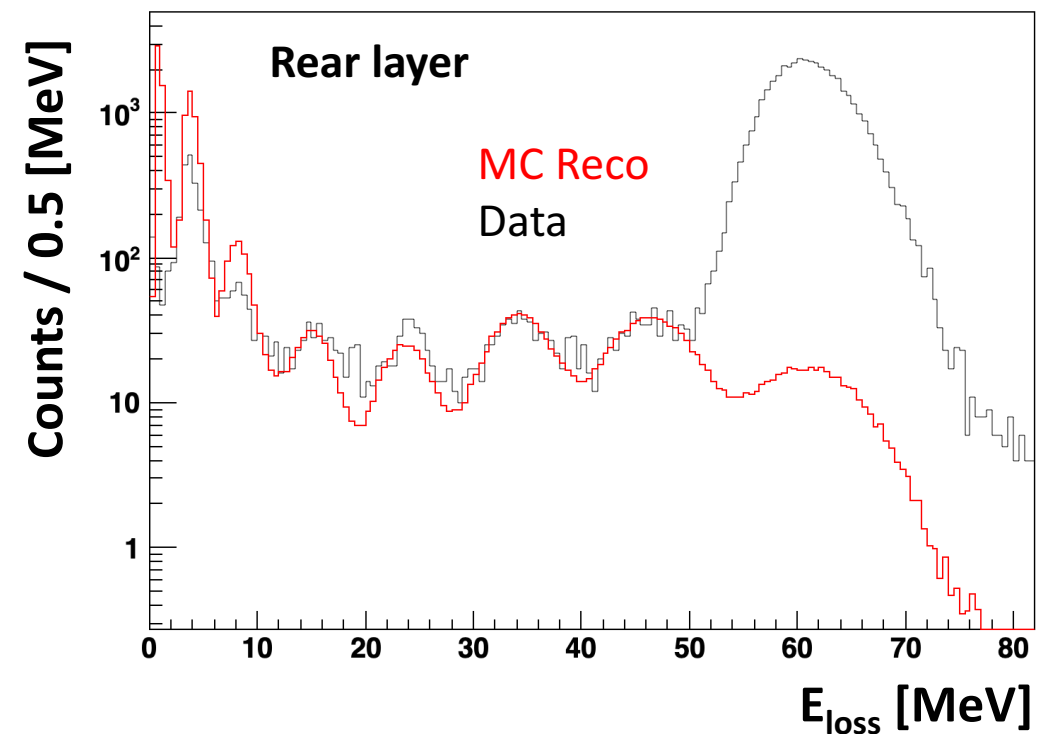
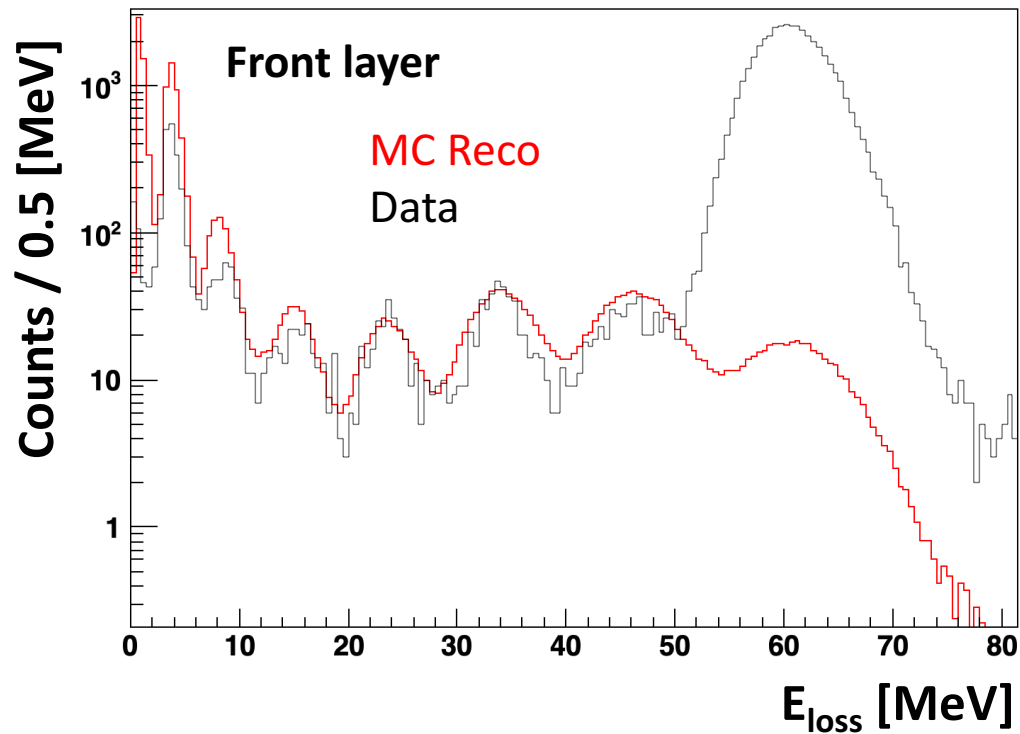
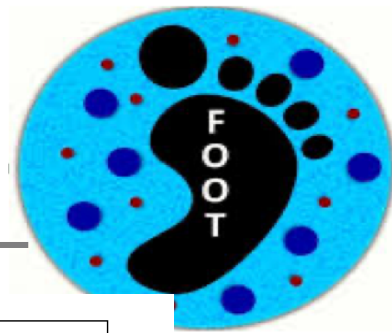


5. Crosschecked different Eloss and TOF calibration strategies successfully (GSI fragmentation data standalone)



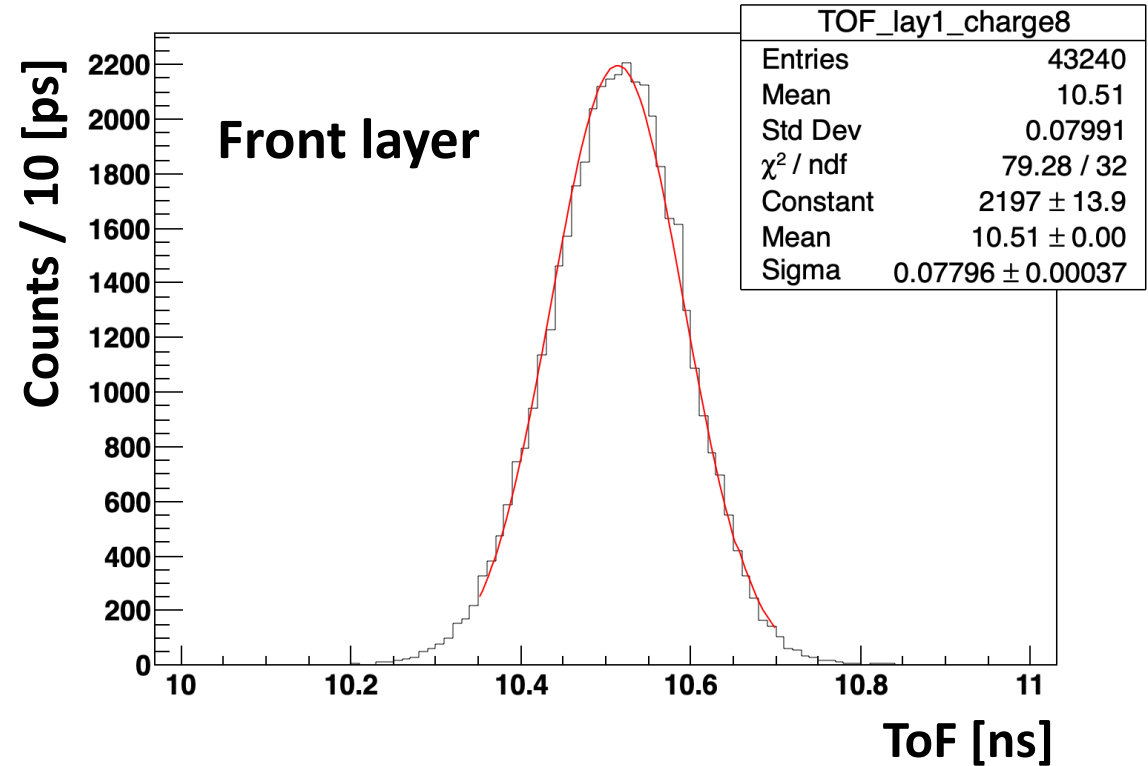
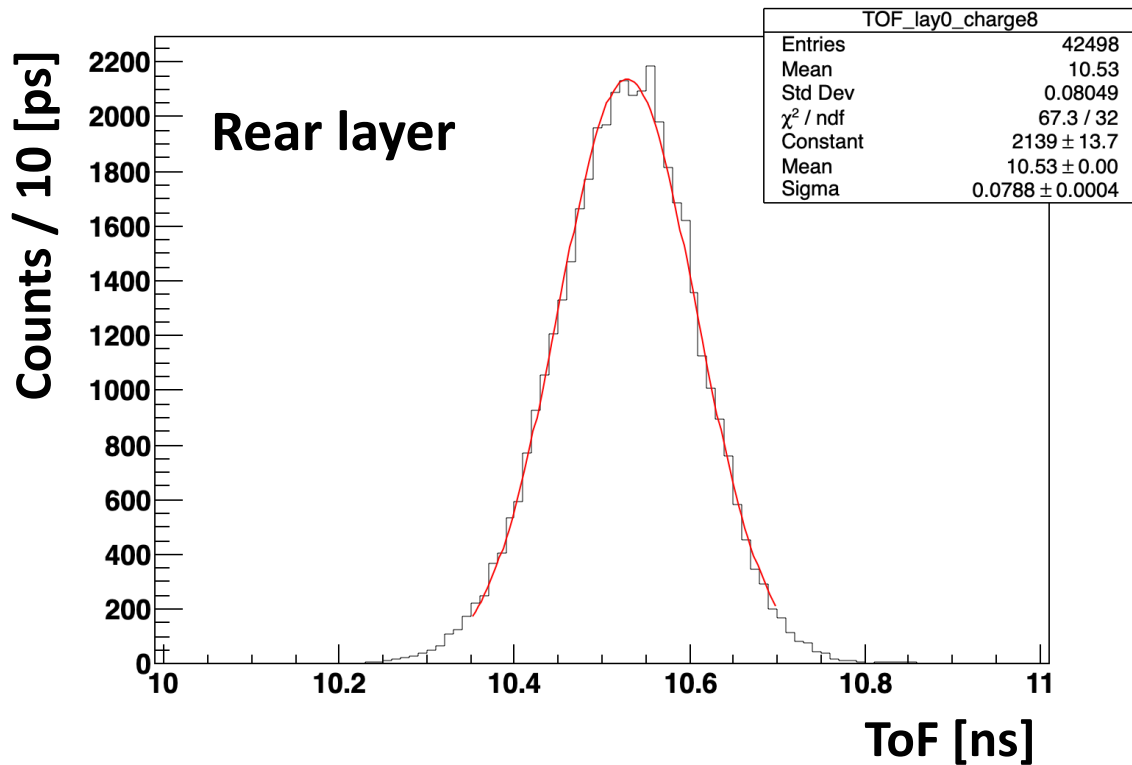
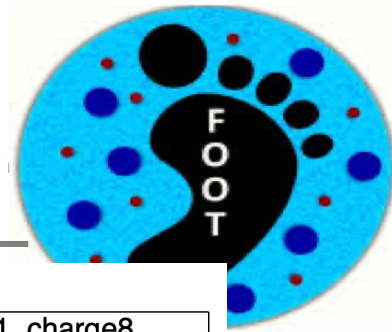


# Energy loss distributions



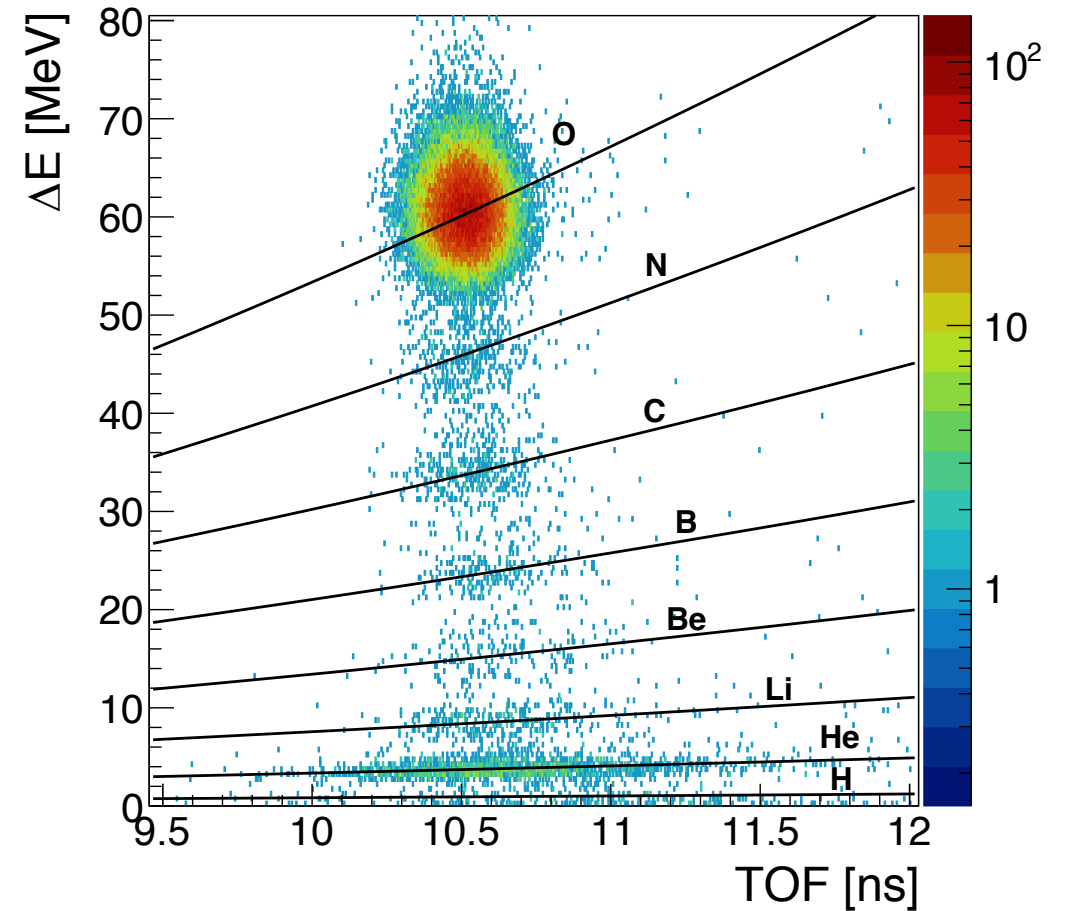
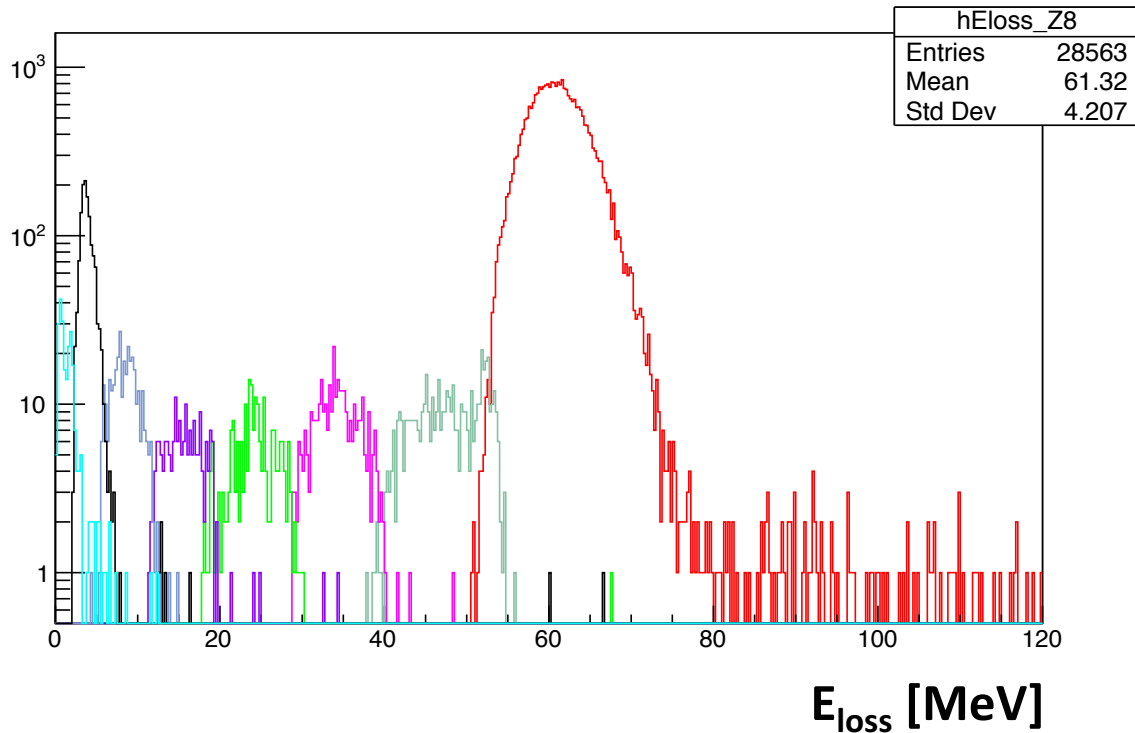
- Nice comparison Data - MC reconstructed
- Normalization to C peaks: FLUKA is able to reproduce very nicely the yield ratios for  $Z=4-7$  (Concerning Oxygen: MC implements a fragmentation trigger)
- Recovered mis-calibrated bars in layer rear

# TOF in fragmentation runs



- Cross checked a TOF calibration «position per position» with a calibration per bar shifting:  
 $\text{TOF}_{\text{raw}} = (t_A + t_B) / 2 - t_{\text{SC}}$  from GSI data to the value expected from MC simulation.
- $\sigma_{\text{TOF}} \approx 78 \text{ ps}$  [see also Giacomo's talk tomorrow]

# ZID for GSI data



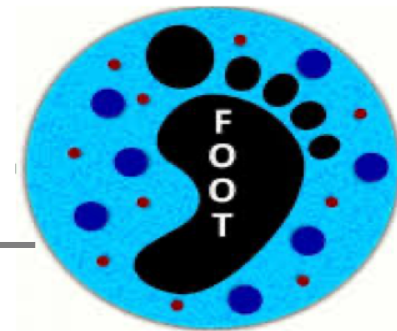
Applying the ZID algorithm implemented in SHOE is possible to distinguish the different Eloss distribution due to each fragment in GSI data.

# Conclusions

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- **Charge Z identification algorithm available now in SHOE for MC and GSI data**
- Implementation in SHOE of TW energy loss and TOF calibration for GSI data
- **Next steps:**
  - Prior: move TOF and Eloss calibration from dedicated branch in SHOE to newgeom and master branch
  - Implement in SHOE an improved TW clustering needed for global reconstruction
  - Estimate TOF and Eloss resolution for different fragments selecting the  $E_{kin}$  of the fragment
  - Measurement of elemental cross section for  $Z > 1$  (integrated and maybe in some  $E_{kin}$  and angle bin for He and Oxygen) as natural continuation of fragment Z identification to be finalized with a publication of GSI data

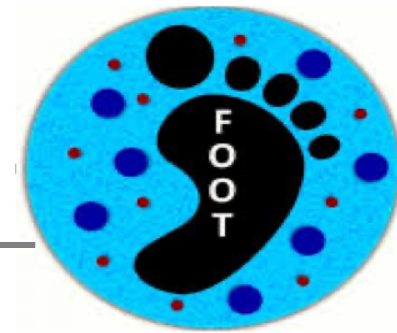


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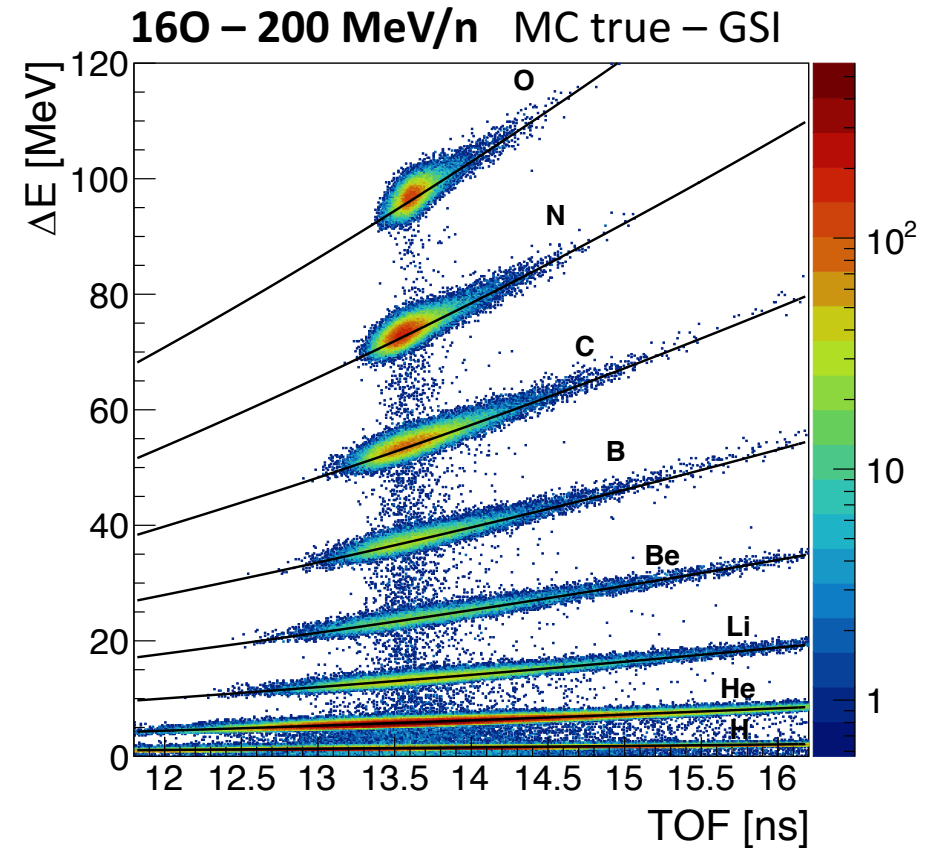
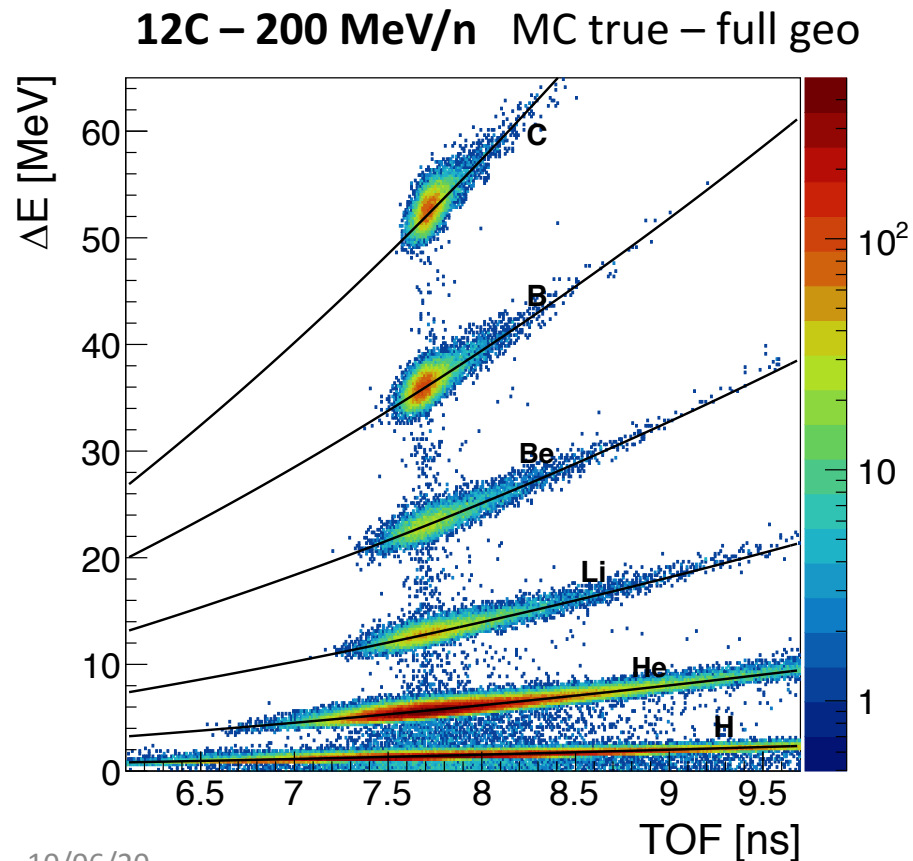
*Spare slides*



# Bethe-Bloch parametrization



- Bethe-Bloch parametrization from **Monte Carlo truth**, asking for primary fragmentation and Z\_MC



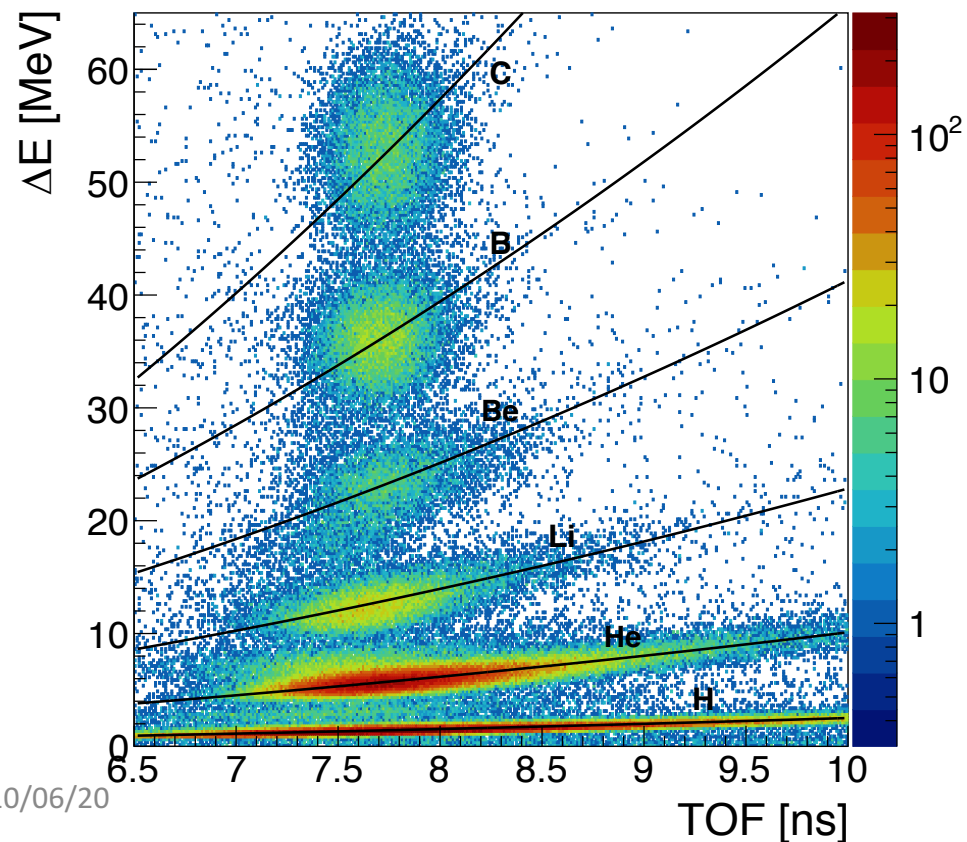


# Bethe-Bloch parametrization

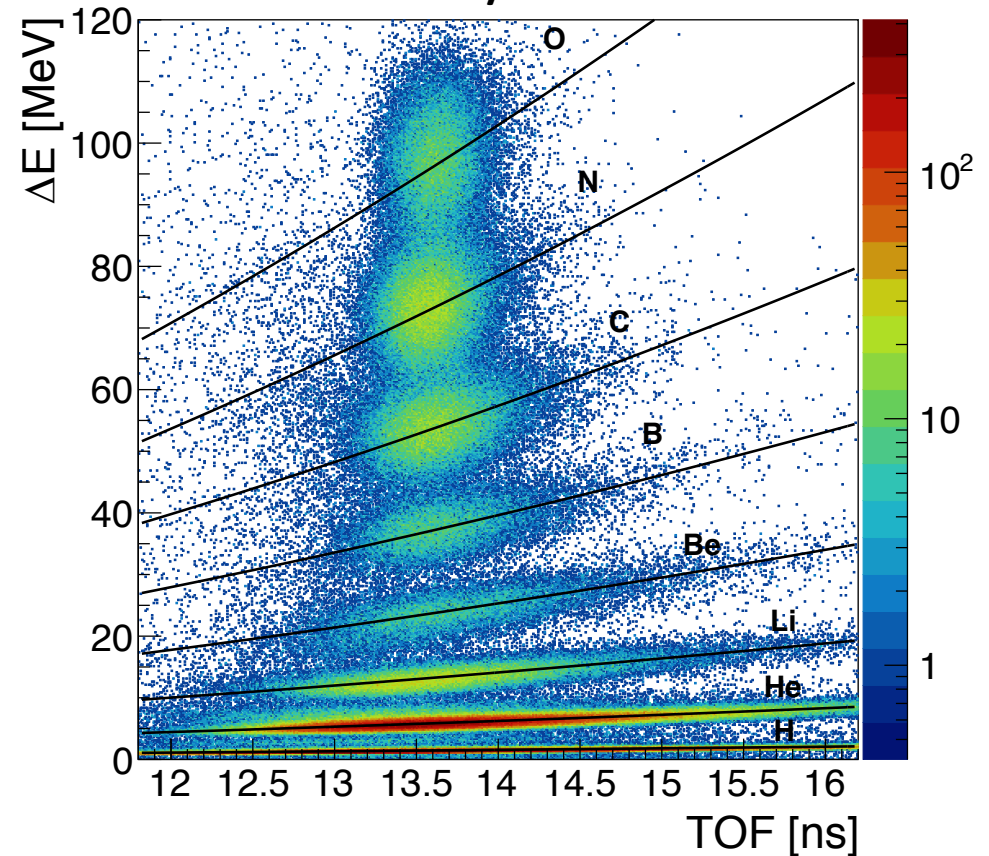


The BB curves are superimposed on the **reconstructed MC**. Pile-up and Eloss and ToF resolution from calibration data have been implemented in SHOE

12C – 200 MeV/n MC rec - full geo

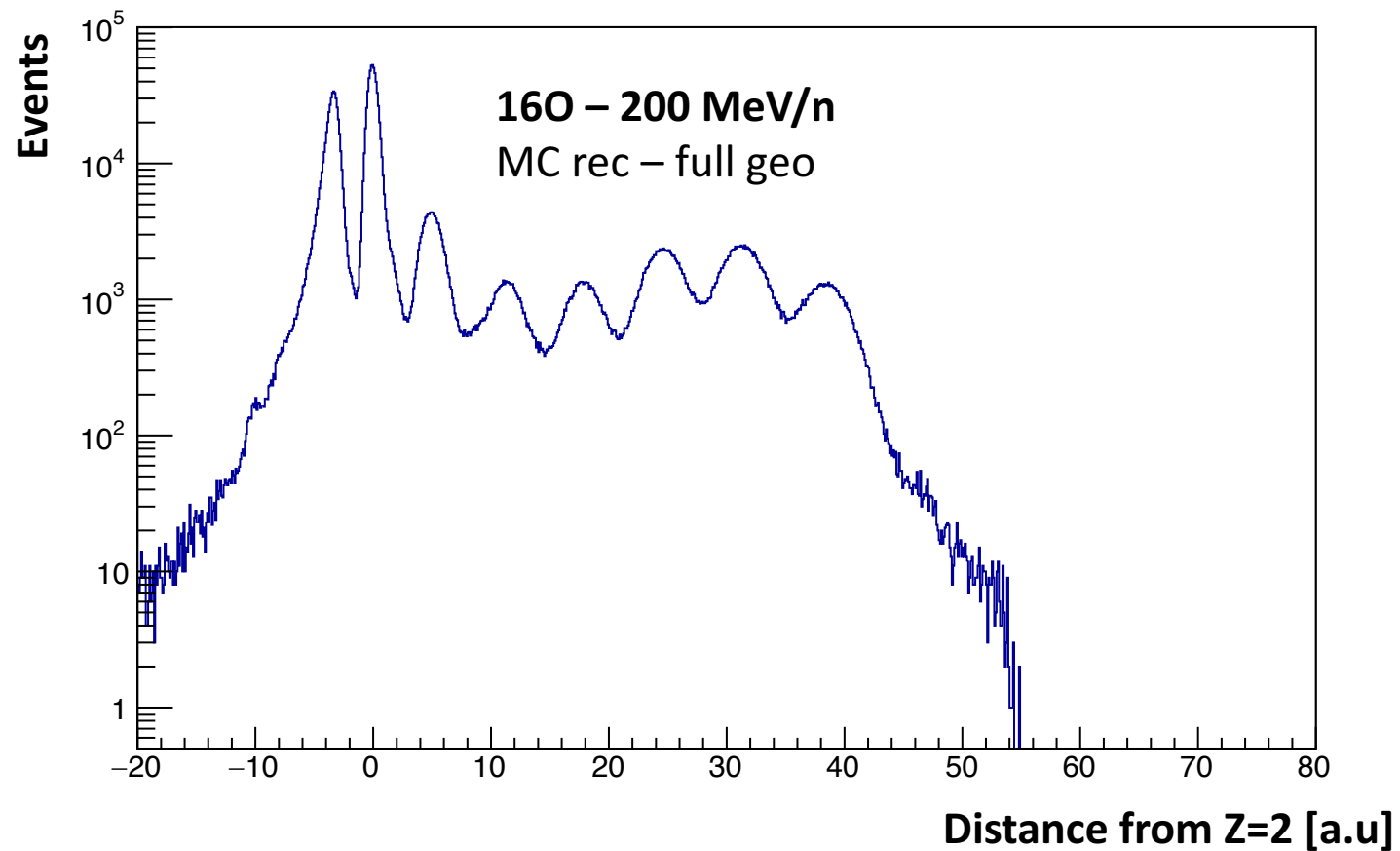
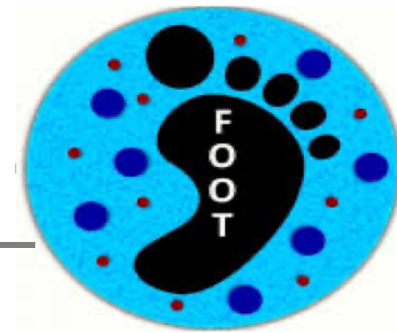


16O – 200 MeV/n MC rec- GSI





# Minimum distance method



# Moving ZID from MC to GSI DATA

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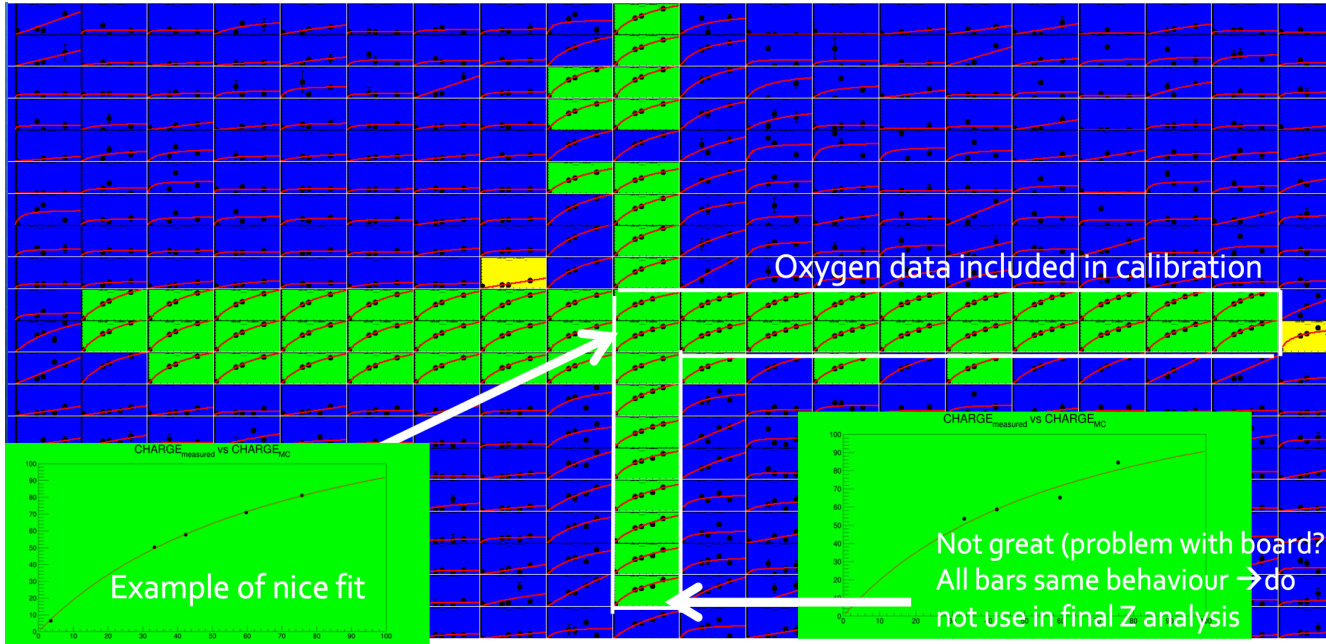
In order to apply ZID to GSI data in SHOE some preliminary steps have been done:

- Energy loss and TOF calibration performed by the Pisa group has been implemented in SHOE: such calibration takes care of TW detector light response inhomogeneities along each bar providing a very precise «Position per Position» calibration.
- Extended the calibration to the not-calibrated position filling empty positions with the average of the calibrated positions of the same bar/layer
- Ghosts have been managed on an event-by-event basis exploiting the reconstructed position along the bar from time differences at the bar edges (with resolution  $< 8$  mm, less than bars cross)
- After calibration a further small tuning of the peaks to the MC energy has been necessary
- TOF calibration performed per bar and per position have been crosschecked and imported in SHOE
- Crosschecked different Eloss and TOF calibration strategies successfully (available in SHOE)

# Talking about data: Energy Calibration



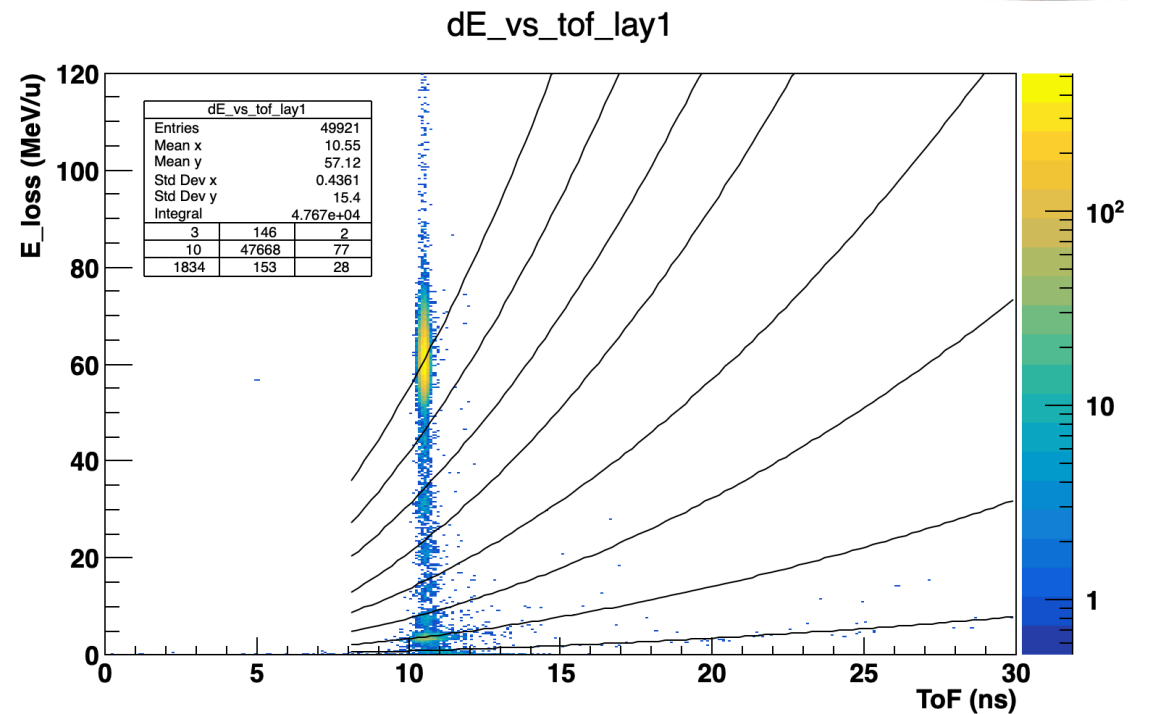
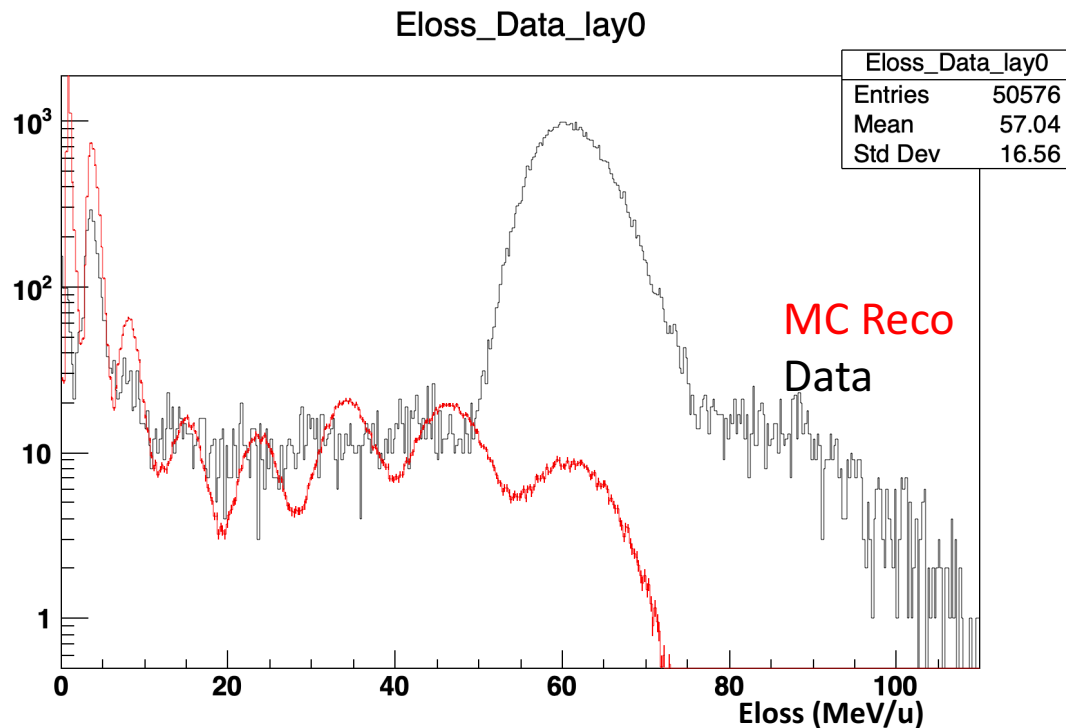
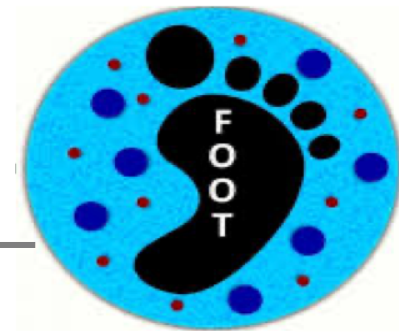
Thanks to the Pisa group we have a very precise «Position per Position» front and rear energy calibration for the TW.



In order to implement Pisa calibration in SHOE and to apply it to GSI fragmentation data, we have extended the calibration to the not-calibrated position:

- Empty position are filled with the average of the calibrated positions of the same bar, whenever we have it.
- If one bar is totally empty its parameters are taken from the average of all the good positions in the same layer.

# Data comparison with MC: run 2239-2240-2241



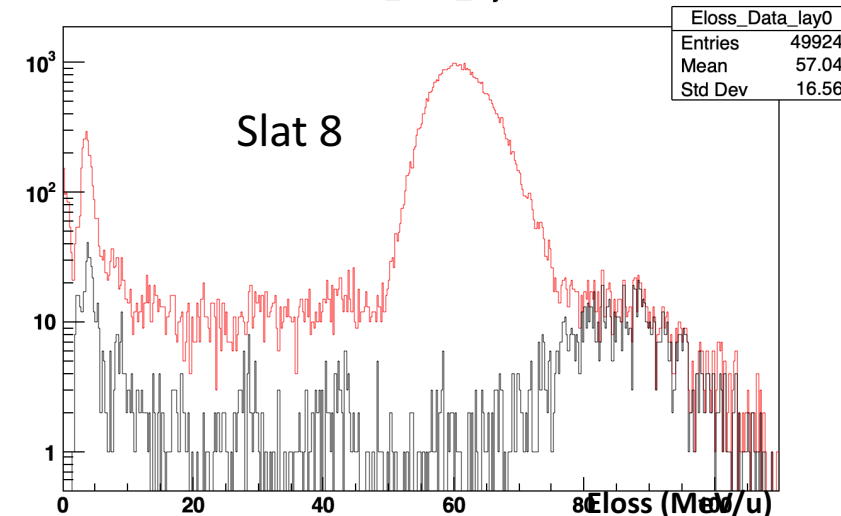
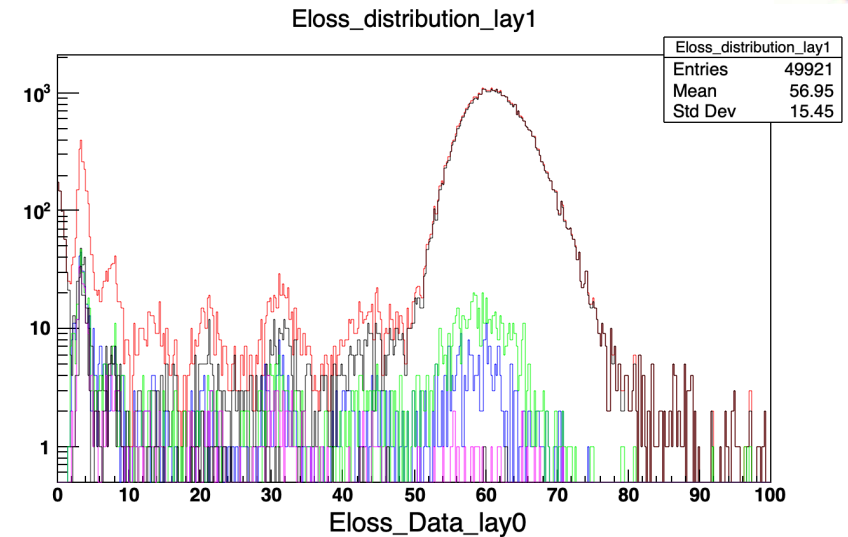
- Comparing MC Reconstructed with Calibrated Data is still evident a small shift for some peaks (Z=5, Z=6, Z=7) ) → this worsen charge identification (ZID) performances
- We've now implemented in SHOE in TW digitizer for MC reconstructed the resolution from calibration data (for both Eloss and TOF) Roberto Zarrella provided us (thanks!)

# Energy loss per bar



Observed energy loss distribution per bar (not easy for very low statistics for not central bars) :

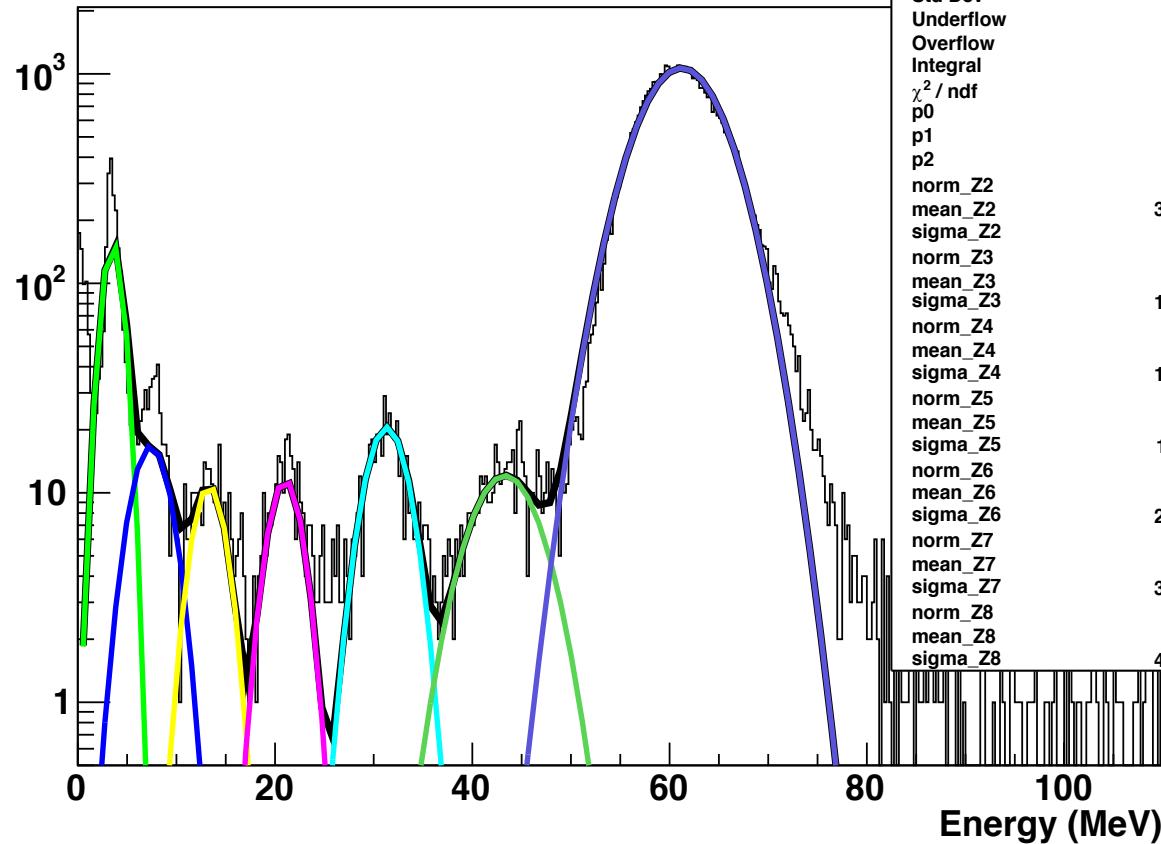
- For layer 1 (Front layer, orizzontal bars) very good equalization thanks to the calibration procedure for all peaks and all 20 bars
- For layer 0 (Rear layer, vertical bars) again good equalization with the exception of the bars 8 and 10 that were impossible to calibrate in calibration runs
  - Even if poor in statistics we have tried to recover these data also and equalize the peaks to MC



# Energy Loss tuning



Eloss\_Data\_lay1

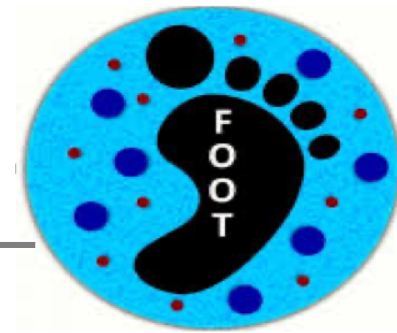


Eloss\_Data\_lay1

Entries	49921
Mean	56.99
Std Dev	15.5
Underflow	2015
Overflow	179
Integral	4.773e+04
$\chi^2 / \text{ndf}$	2308 / 371
p0	0 ± 2.0
p1	0 ± 2.0
p2	0 ± 2.0
norm_Z2	155.3 ± 4.7
mean_Z2	3.529 ± 0.033
sigma_Z2	1 ± 0.0
norm_Z3	16.72 ± 1.52
mean_Z3	7.4 ± 0.0
sigma_Z3	1.887 ± 0.023
norm_Z4	10.77 ± 1.00
mean_Z4	13.3 ± 0.1
sigma_Z4	1.615 ± 0.142
norm_Z5	11.47 ± 1.01
mean_Z5	21.02 ± 0.18
sigma_Z5	1.632 ± 0.081
norm_Z6	20.56 ± 0.68
mean_Z6	31.33 ± 0.13
sigma_Z6	2.026 ± 0.066
norm_Z7	12.08 ± 0.85
mean_Z7	43.3 ± 0.2
sigma_Z7	3.376 ± 0.097
norm_Z8	1067 ± 6.1
mean_Z8	61.2 ± 0.0
sigma_Z8	4.003 ± 0.015

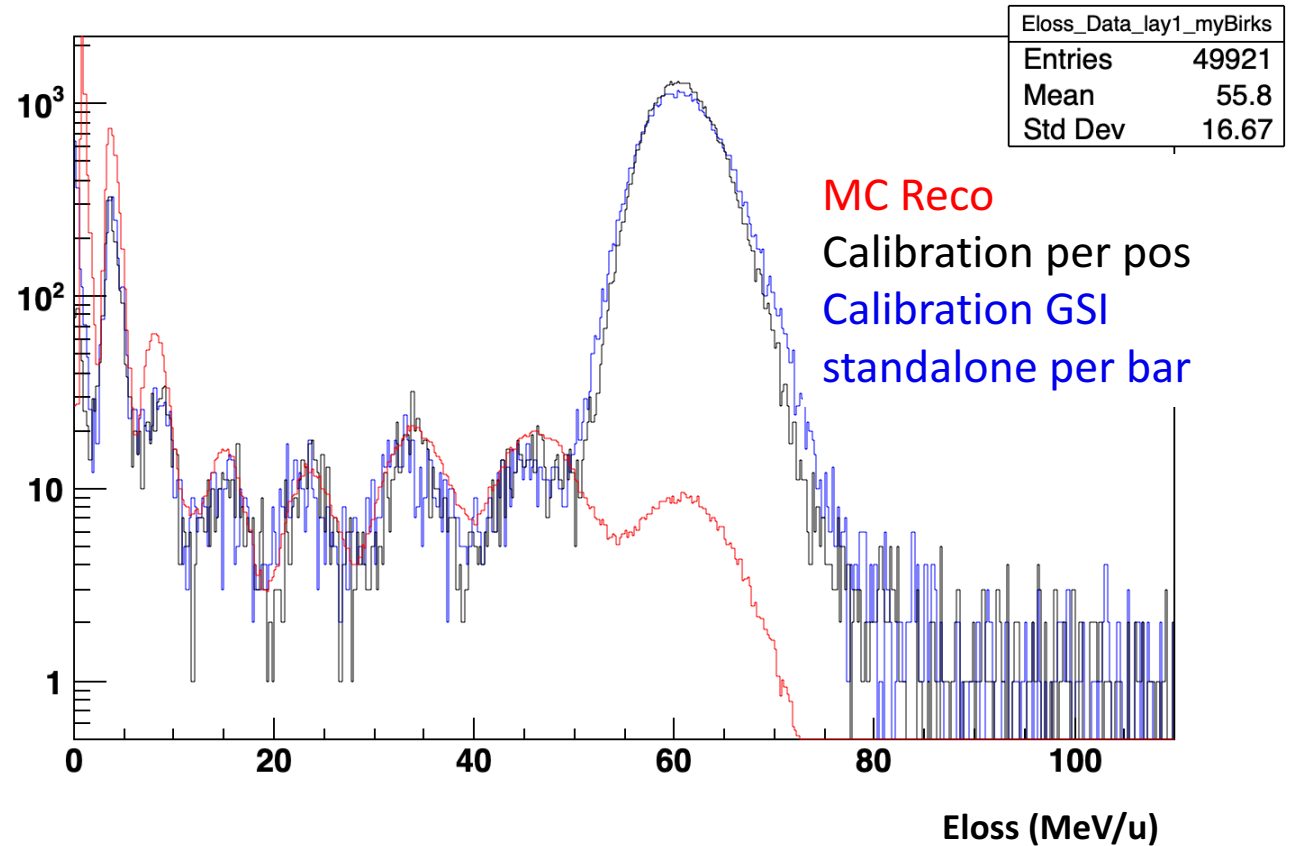
Fitting all the peaks with a convolution of gaussians we re-tune the calibrated energy mean values to the MC energy peaks(with effects only on Z=4,5,6)

# GSI standalone bar calibration

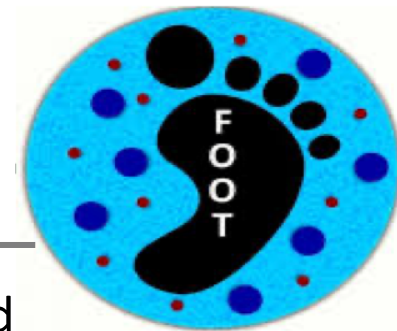


Alternative calibration for cross-check, performed with the only standalone fragmentation data @ GSI (run 2239,2240,2241)

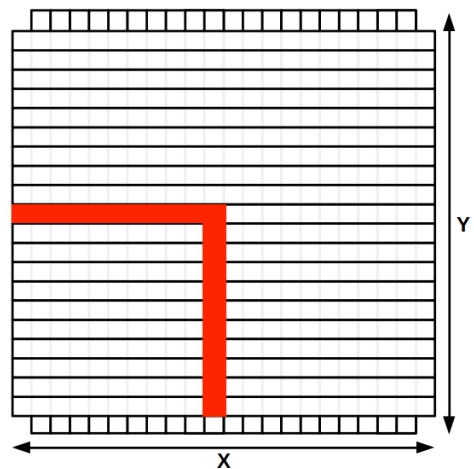
Not bad...As expected the resolution is always worse than the calibration performed by position, but not that much







# Check on time delay given by cables



In GSI calibration run 2242 (no target) only few bars have been irradiated by 160 beam at 400 MeV/n.

Few events in slats<9 are given by fragmentation.

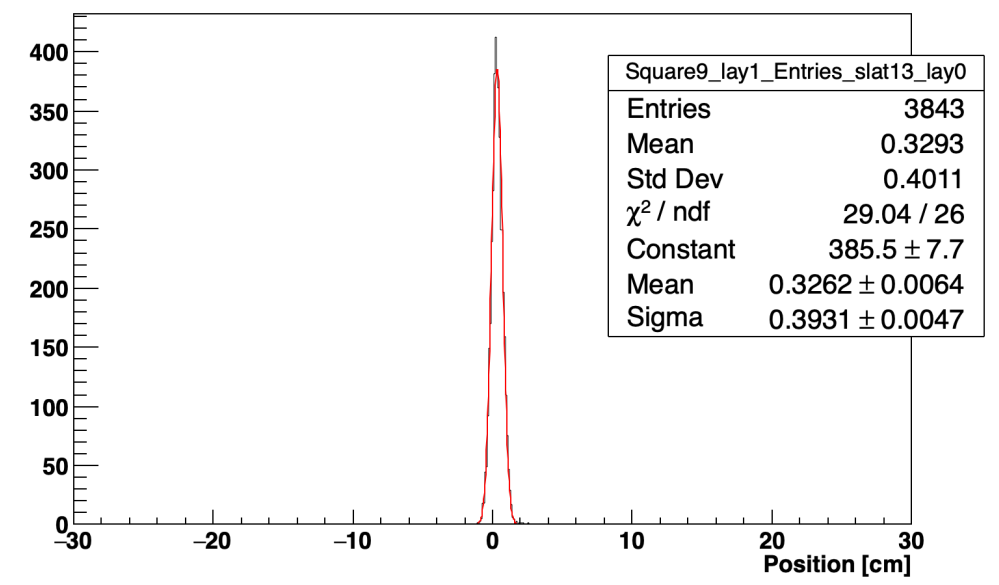
With this data it's possible to check for time difference given by cables during data acquisition.

It is possible to notice that the mean value given by this gaussian fit is comparable with 0 in  $1\sigma$ .

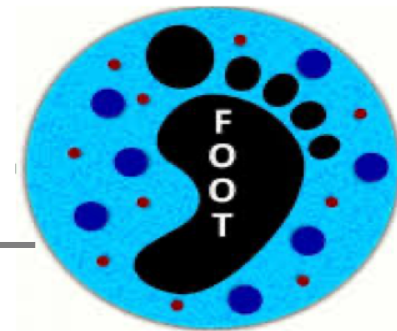
**No  $\Delta$ time cable effect. No differences in time have been considered.**



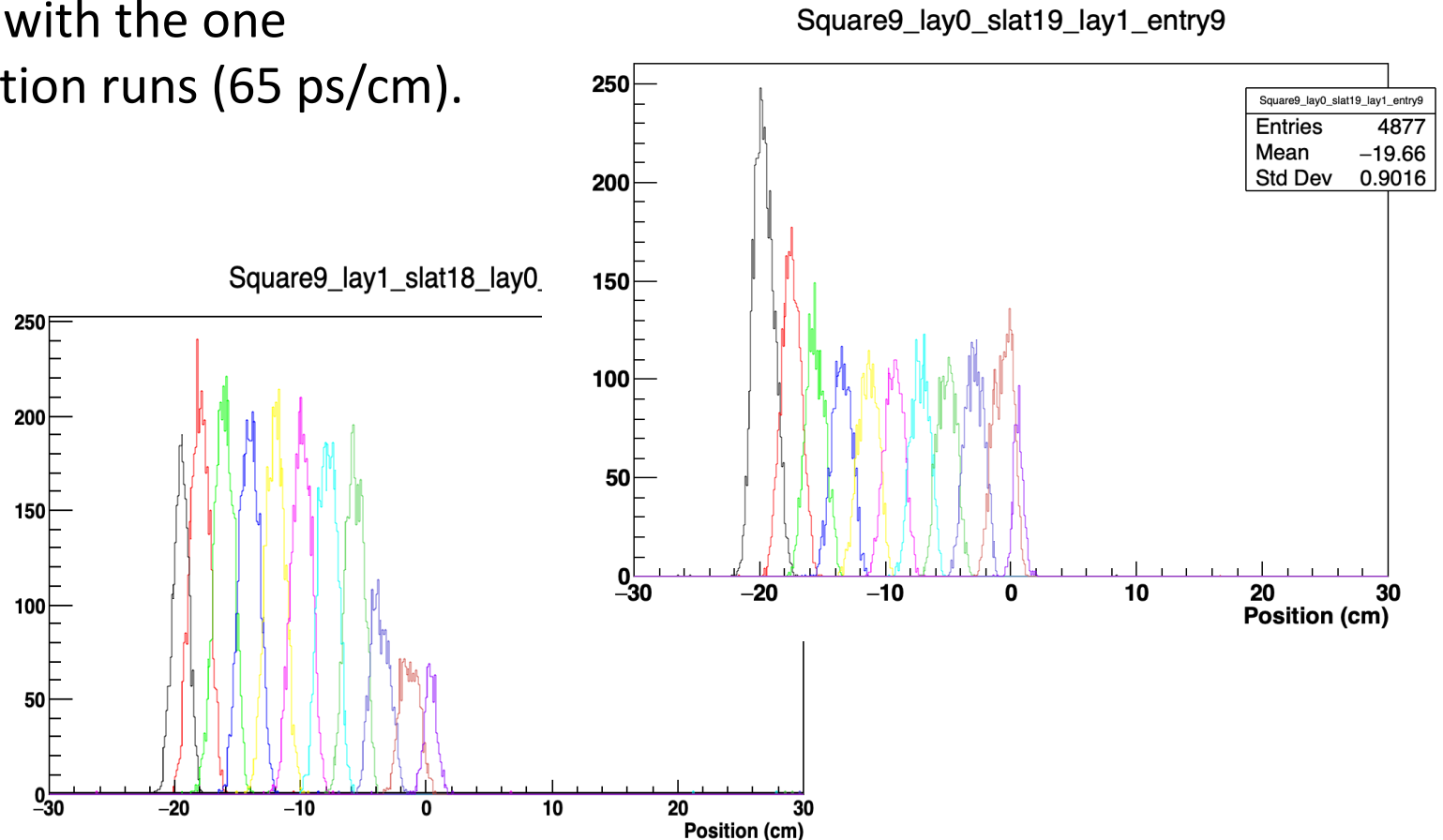
Square9\_lay1\_Entries\_slats13\_lay0



# Check on propagation velocity in TW



- From GSI run 2242 we have cross checked the value of propagation velocity in TW  $v_p$  with the one provided by Pisa group in calibration runs (65 ps/cm).
- To have a reliable value  $v_p$  is fundamental to clusterize TW front/rear information in multiple fragments events
- By selecting each intersection between bars separately we can correlate difference in time  $t_A - t_B$  for each bar to the cross position along the bar



# Check on propagation velocity in TW

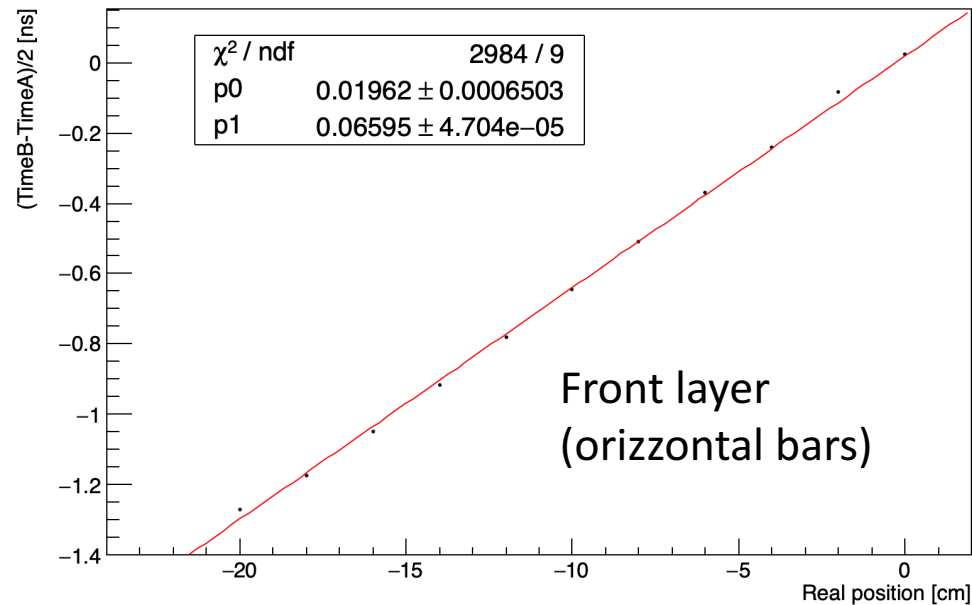


$$(TimeB - TimeA)/2 = p0 + p1 * X$$

$$\frac{1}{V_p} = 66 \text{ ps/cm}$$

Now implemented in SHOE (before it was wrong: 140 ps/cm).  
From datasheet (refraction index=1.58  $\rightarrow$   $1/v \sim 53$  ps/cm).  
For future data acquisition it could be important measure it for each bar (also with a source)

Fit entries lay1 slat 9



Fit entries lay0 slat 9

