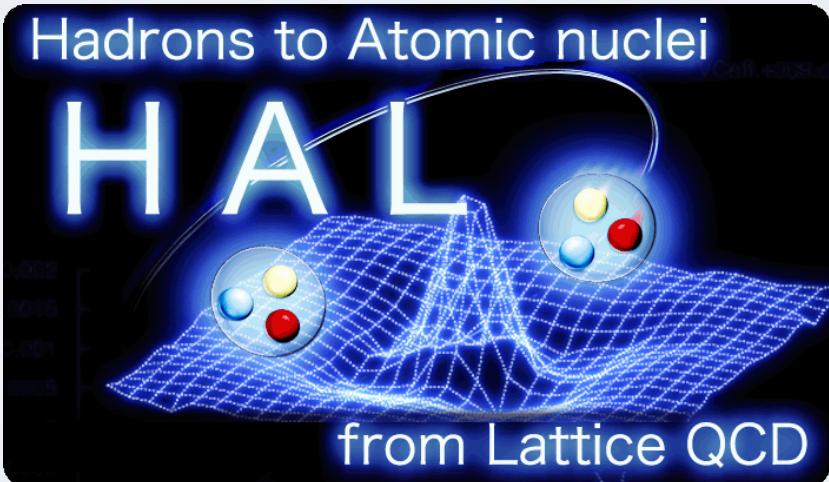


Non-locality of the nucleon-nucleon potential from Lattice QCD

K. Murano (KEK)



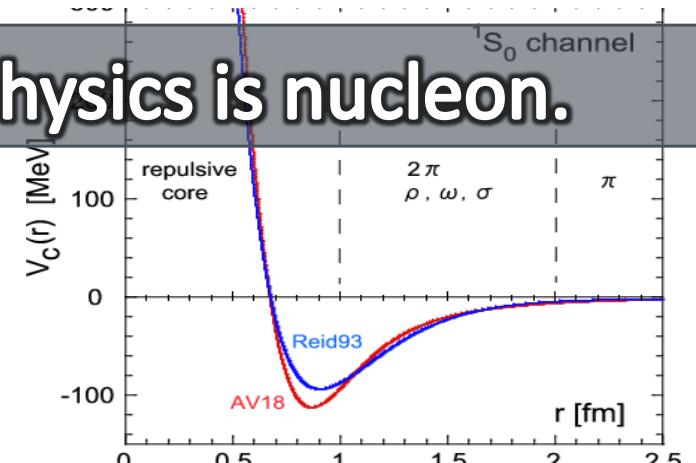
in collaboration with
S.Aoki T.Hatsuda N.Ishii H.Nemura for HAL QCD Coll.



Nuclear potential

the fundamental particle in nuclear physics is nucleon.

Nuclear potential



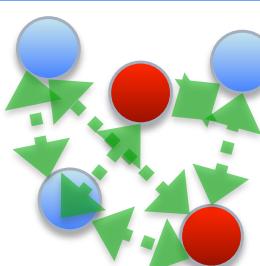
Once the nucleon-nucleon potential (NN potential) is obtained, various features of nucleus can be studied via the Schrodinger equation.

Many-body system

high density

equation of state nuclear matter

→ neutron stars



Few-body system

hyper nucleus,
exotic nucleus

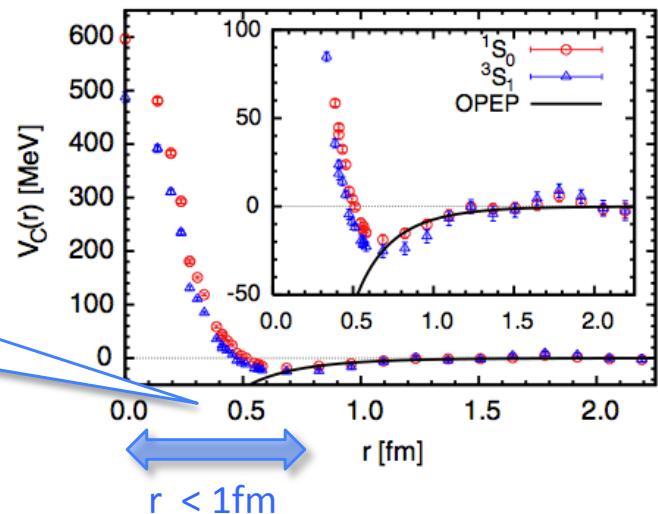
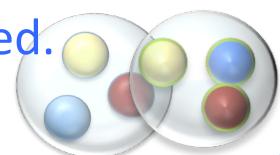
Nuclear potential from Lattice QCD

Recently, a method is proposed to extract the NN potential from Lattice QCD.

N. Ishii, S. Aoki and T. Hatsuda, Phys. Rev. Lett. **99**, 022001 (2007)

Their method reproduced the short range part of the NN potential, "repulsive core".

The region nucleons are overlapped.
Study from the QCD is needed.



This approach has following advantages:

- Scattering experimental data are not needed:
→ hyperon-nucleon, hyperon-hyperon interaction

H. Nemura, N. Ishii, S. Aoki and T. Hatsuda, Phys. Lett. B **673**, 136 (2009)

- It is also possible to investigate three nucleon force systematically. (18 June room1 15:50~ T.Doi)

NN potential from Lattice QCD: HAL's method

BS wave function

$$p \xrightarrow{\vec{x}} n \equiv \phi(\vec{x})$$

pioneering work: N. Ishizuka

Phys.Rev.D71:094504,2005.

derivation:

S.Aoki, H.Hatsuda, N.Ishii, PTP123(2010)89

Effective Schrödinger Equation:

$$(\Delta + k^2)\phi(\vec{x};k) = m_N \int d^3y U(\vec{x};\vec{y})\phi(\vec{y};k)$$

Energy independent
non-local potential

obtain the BS wave function  calculate back to the potential.

$$\phi(\vec{r};E) = \lim_{t \rightarrow \infty} \sum_{\vec{x}} \langle 0 | \hat{N}(\vec{x} + \vec{r};t) \hat{N}(\vec{x};t) \overline{NN}(t_0) | 0 \rangle$$

For the moment, U is obtained by LO of derivative expansion:

$$U(\vec{x};\vec{y}) = \left[[V_0(\vec{x}) + V_\sigma(\vec{x})(\vec{\sigma}_1 \cdot \vec{\sigma}_2)] \text{LO} + [V_T(r)S_{12} + V_{LS}(r)\vec{L} \cdot \vec{S}] \right] \delta(\vec{x} - \vec{y})$$

The purpose of this work:

Check the convergence of the derivative expansion

(Is LO enough?)

The convergence is related to E and L dependence of LO potential

ex) S=0 case : ($S_{12}=0$)

$$\begin{aligned} (\Delta + k^2) \phi^{S=0}(\vec{x}; k) &= m_N \int d^3y U(\vec{x}; \vec{y}) \phi^{S=0}(\vec{y}; k) \\ &= m_N \left[V_C(r) + V_L(r) L^2 + V_{LL}(r) L^4 + \dots \right. \\ &\quad \left. + \{V_p(r), \nabla^2\} + \{V_{pp}(r), \nabla^4\} + \dots \right] \phi^{S=0}(\vec{x}; k) \end{aligned}$$

The convergence is related to E and L dependence of LO potential

ex) S=0 case : ($S_{12}=0$)

$$\begin{aligned}
 (\Delta + k^2) \phi^{S=0}(\vec{x}; k) &= m_N \int d^3y U(\vec{x}; \vec{y}) \phi^{S=0}(\vec{y}; k) \\
 &= m_N \left[V_C(r) \left[+ V_L(r) L^2 + V_{LL}(r) L^4 + \dots \right. \right. \\
 &\quad \left. \left. + \{V_p(r), \nabla^2\} + \{V_{pp}(r), \nabla^4\} + \dots \right] \right] \phi^{S=0}(\vec{x}; k)
 \end{aligned}$$

$$(\Delta + k^2) \phi^{S=0}(\vec{x}; k) = m_N V_C(r) \phi^{S=0}(\vec{x}; k)$$

the potential obtained by LO:

$$V_C^{LO}(r; \textcolor{green}{L}, \textcolor{blue}{E}) = \frac{1}{m_N} \left(\frac{\Delta \phi^{S=0}(r; \textcolor{blue}{E}; \textcolor{green}{L})}{\phi^{S=0}(r; \textcolor{blue}{E}; \textcolor{green}{L})} + k^2 \right)$$

The convergence is related to E and L dependence of LO potential

ex) S=0 case : ($S_{12}=0$)

$$\begin{aligned}
 (\Delta + k^2) \phi^{S=0}(\vec{x}; k) &= m_N \int d^3y U(\vec{x}; \vec{y}) \phi^{S=0}(\vec{y}; k) \\
 &= m_N \left[V_C(r) \left[\text{LO} \right] + V_L(r) L^2 + V_{LL}(r) L^4 + \dots \right. \\
 &\quad \left. + \{V_p(r), \nabla^2\} + \{V_{pp}(r), \nabla^4\} + \dots \right] \phi^{S=0}(\vec{x}; k)
 \end{aligned}$$

$$(\Delta + k^2) \phi^{S=0}(\vec{x}; k) = m_N V_C(r) \phi^{S=0}(\vec{x}; k)$$

the potential obtained by LO:

$$V_C^{\text{LO}}(r; L, E) = \frac{1}{m_N} \left(\frac{\Delta \phi^{S=0}(r; E; L)}{\phi^{S=0}(r; E; L)} + k^2 \right)$$

$$= V_C(r) + \boxed{V_L(r)L^2 + V_{LL}(r)L^4 + \dots} + \{V_p(r), \nabla^2\} + \{V_{pp}(r), \nabla^4\} + \dots$$

L dependent

$$\vec{k} = -i\nabla$$

$$\vec{L} = -\vec{r} \times i\vec{\nabla}$$

$$k^2 / m_N = E,$$

$$\begin{array}{ccc}
 & \xrightarrow{k^2} & \xleftarrow{k^4} \\
 & &
 \end{array}$$

Energy dependent



Size of the higher order terms can be estimate from the examination of the E and L dependence of LO potential.



Energy dependence

Strategy

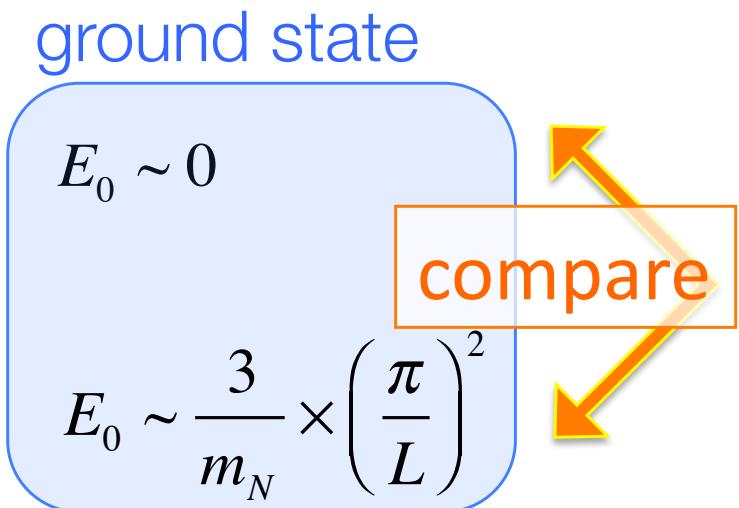
previous study of energy dependence:

2d Ising analytical study
 (S. Aoki, J. Balog P. Weisz arXiv:0805.3098)

- momentum are discretized in a finite box of size L.

PBC $\vec{p} = \left(\frac{2n_x\pi}{L}, \frac{2n_y\pi}{L}, \frac{2n_z\pi}{L} \right)$

APBC $\vec{p} = \left(\frac{(2n_x+1)\pi}{L}, \frac{(2n_y+1)\pi}{L}, \frac{(2n_z+1)\pi}{L} \right)$

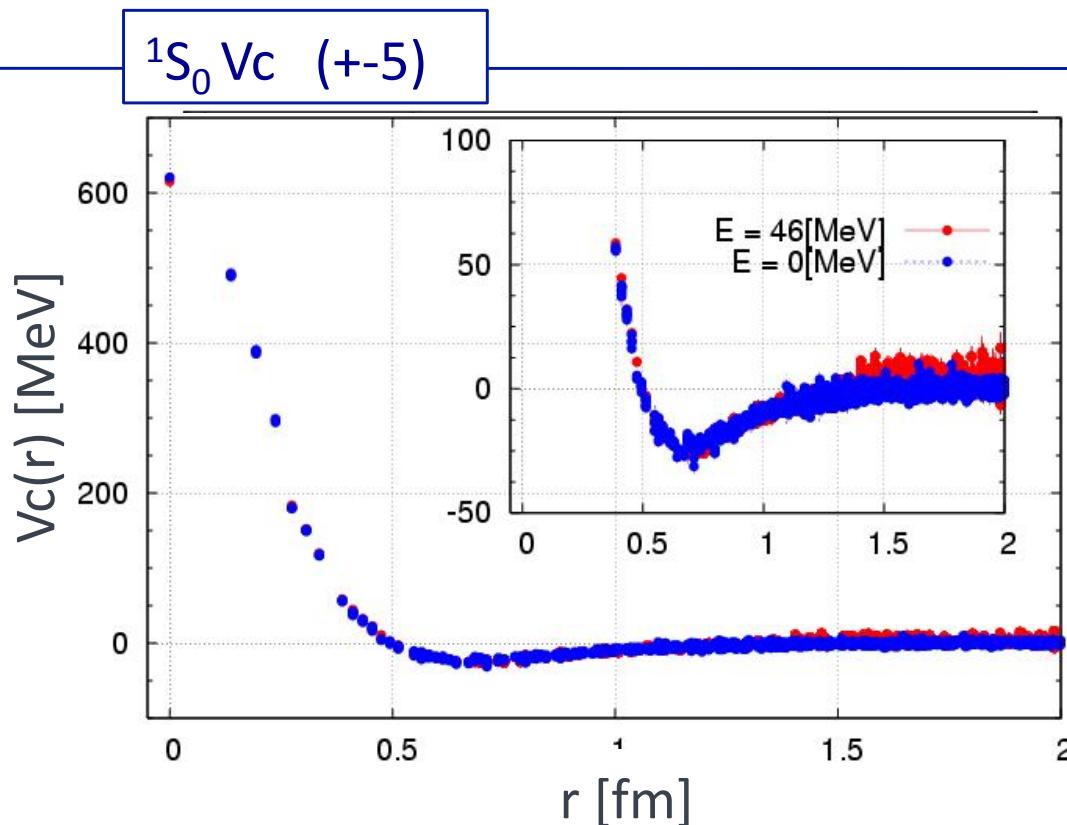


~ 45 MeV in this work.

$$\sum_{\vec{x}} \langle 0 | \hat{N}_\alpha^i(\vec{x} + \vec{r}, t) \hat{N}_\beta^j(\vec{x}, t) \overline{NN}(t_0) | 0 \rangle \\ = \phi(\vec{r}; E_0) e^{-E_0(t-t_0)} + \phi(\vec{r}; E_1) e^{-E_1(t-t_0)} + \dots \xrightarrow{t \rightarrow \infty} \phi(\vec{r}; E_0) e^{-E_0(t-t_0)}$$

ground state

comparison of potentials : 0 MeV and 45 MeV



Set up:

Lattice size: $32^3 \times 48 \sim 4.5$ [fm]

$\beta = 5.7$

$1/a=1.44$ GeV ($a \sim 0.14$ [fm])

$K_{ud} = 0.1665$

$m_\pi = 529.0(4)$ MeV $m_N = 1334$ MeV
Heat bath quenched

Plaquette gauge action

boundary condition:

PBC for 0 MeV, APBC for 45 MeV

45MeV and 0MeV are consistent
Energy dependence is weak.



Blue Gene/L
KEK 2048 PU

comparison of potentials : 0 MeV and 45 MeV

$$V_C^{LO}(r; L, E) = V_C(r) + V_L(r)L^2 + V_{LL}(r)L^4 + \dots + \{V_p(r), \nabla^2\} + \{V_{pp}(r), \nabla^4\} + \dots$$

Energy dependent part

$$\begin{aligned} (\Delta + k^2) \phi^{S=0}(\vec{x}; k) &= m_N \int d^3y U(\vec{x}; \vec{y}) \phi^{S=0}(\vec{y}; k) \\ &= m_N \left[V_C(r) + V_L(r) L^2 + V_{LL}(r) L^4 + \dots \right. \\ &\quad \left. + \{V_p(r), \nabla^2\} + \{V_{pp}(r), \nabla^4\} + \dots \right] \phi^{S=0}(\vec{x}; k) \end{aligned}$$

45MeV and 0MeV are consistent
Energy dependence is **weak**.

The size of higher derivative terms are significant weak.



L dependence

L, S, J with representation on the cubic group

symmetry under the rotation is broken => (cubic group)
L (orbital angular mom.), S (spin), J (total angular mom.)

→ The representation of cubic group

$$L, S, J \longrightarrow A_1, A_2, E, T_1, T_2$$

L, S, J

representation with spin

$l = 0$	1	2	3	4	...
A_1	T_1	$E + T_2$	$A_2 + T_1 + T_2$	$A_1 + E + T_1 + T_2$...

Source

$$\phi(\vec{r}) = \sum_{\vec{x}} \langle 0 | \hat{N}_{\alpha}^i(\vec{x} + \vec{r}, t) \hat{N}_{\beta}^j(\vec{x}, t) \overline{NN}(t_0) | 0 \rangle \quad \overline{N} = \epsilon_{abc} (\bar{Q}_a C \gamma_5 Q_b) \bar{Q}_c$$

For simplicity, we will restrict this talk to S=0 state.

wall source

$$Q = \sum_{\vec{x}} q(t, \vec{x})$$

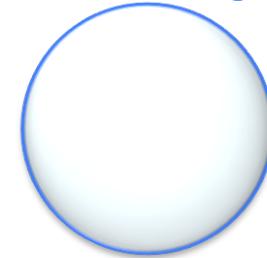
It was difficult to extract $L \neq 0$ states.

four momentum wall sources

$$Q = \sum_{\vec{x}} q(t, \vec{x}) \cos((\pm x \pm y + z)\pi / L)$$

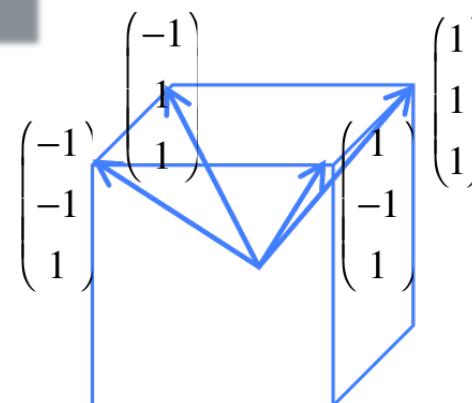
Break the rotational symmetry with source
and extract $L \neq 0$ states.

schematic figure



$$= A_1 \quad \text{dominant}$$

$$J = 0 \quad (L = 0)$$



$$= A_1 + T_2$$

dominant

$$J = 2 \quad (L = 2)$$

$L \neq 0$ BS wave functions are extracted with the projection operator.

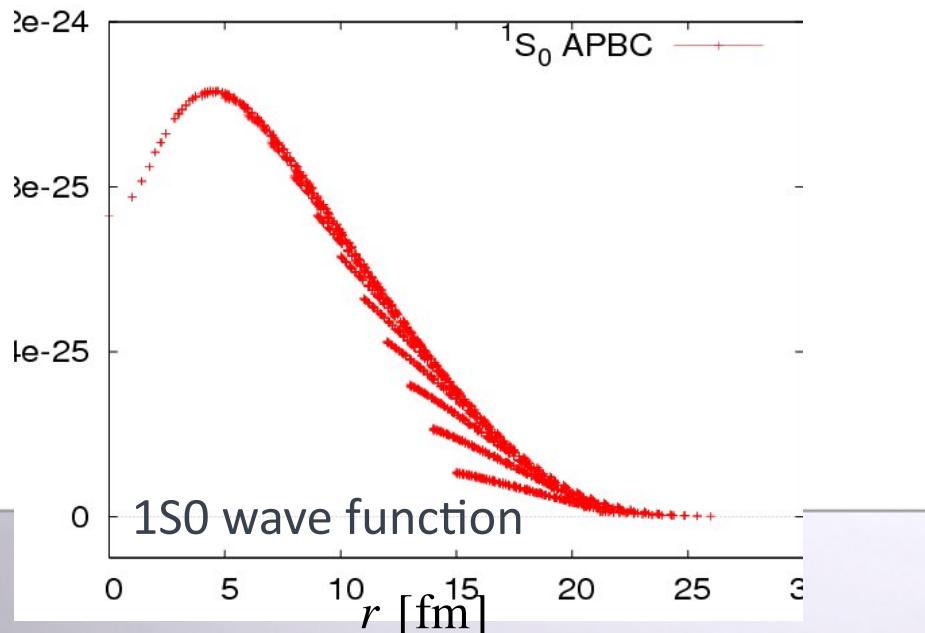
Projection operator

$$P^{(\Gamma)} \phi(\vec{r}) = \frac{d_{\Gamma}}{24} \sum_{i=1}^{24} \chi^{(\Gamma)}[R_i] \phi(R_i \vec{r})$$

($\Gamma = A_1, T_2$ in this work)

$$P^{(A_1)} \phi(\vec{r})$$

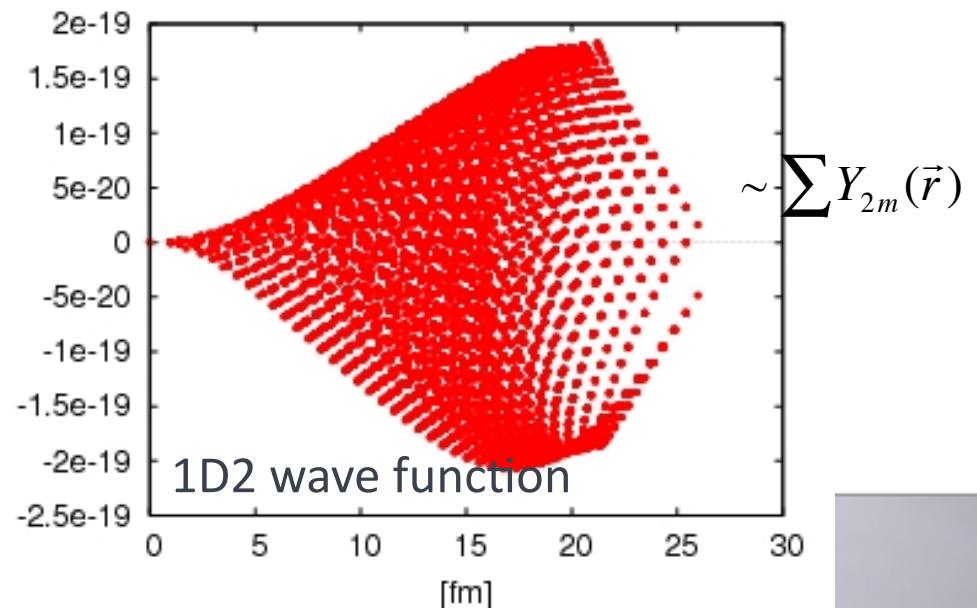
→ $^1S_0 : (S = 0) \otimes (L = 0)$



R_i elements of cubic group
 $\chi^{(\Gamma)}$ characters of representation Γ
 d_{Γ} dimension of the representation Γ

$$P^{(T_2)} \phi(\vec{r})$$

→ $^1D_2 : (S = 0) \otimes (L = 2)$



L dependence of the potential

S=0 $(\nabla^2 + k^2) \phi^{S=0}(\vec{x}; \vec{L})$

$$= m_N [V_C(r) + V_L(r)L^2 + V_{LL}(r)L^4 + \dots] \phi^{S=0}(\vec{x}; \vec{L})$$

L=0 S=0 : 1S0

$$\phi^{^1S_0}(\vec{x}; k) = \mathcal{P}^{(A_1)} \phi_{S=0}(\vec{x}; k)$$

$$\rightarrow V_C^{LO}(r) = \frac{1}{m_N} \left(\frac{\Delta \phi^{^1S_0}(r)}{\phi^{^1S_0}(r)} + k^2 \right) = V_C(r)$$

L=2 S=0 : 1D2

$$\phi^{^1D_2}(\vec{x}; k) = \mathcal{P}^{(T_2)} \phi_{S=0}(\vec{x}; k)$$

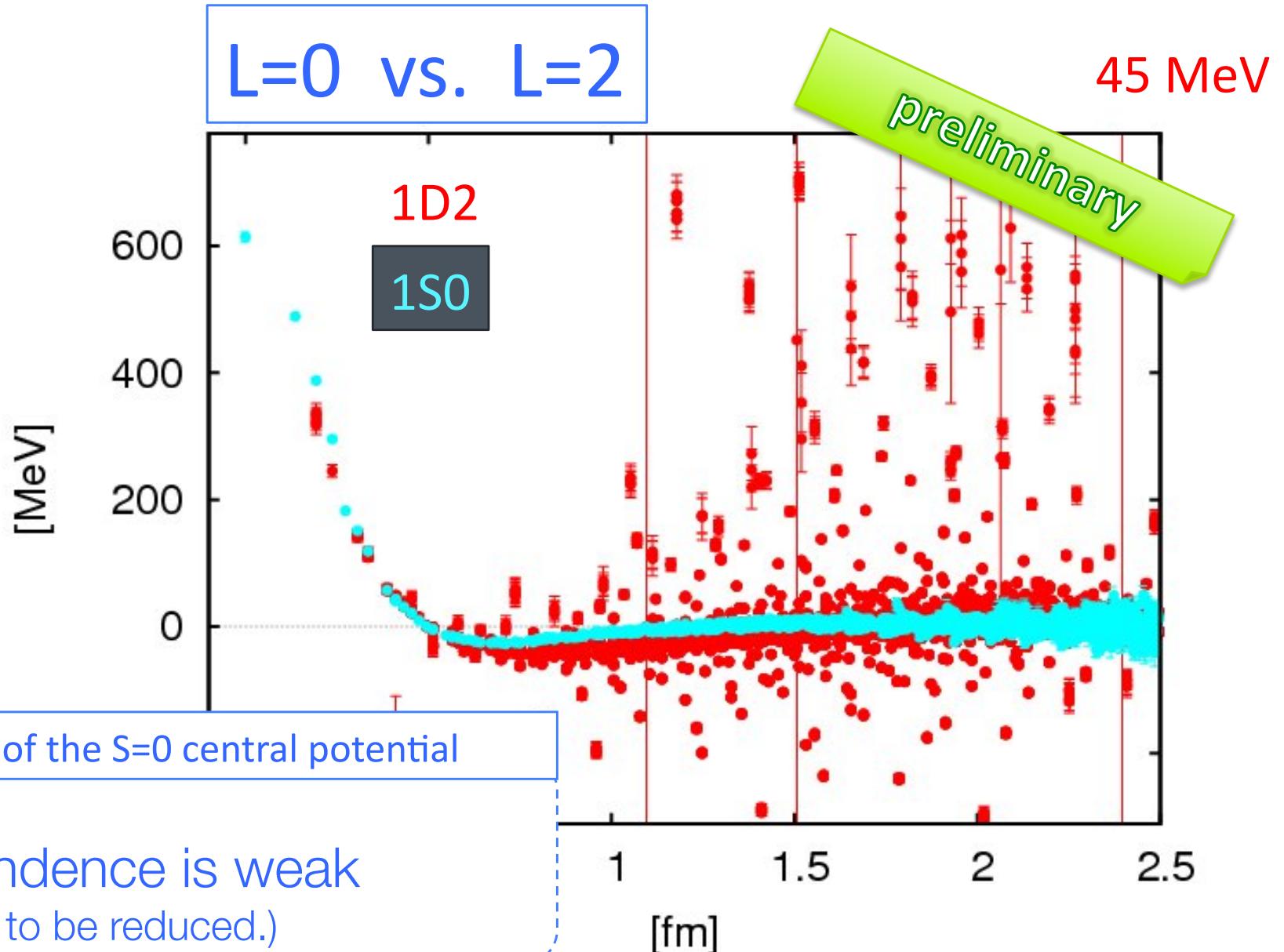
$$\rightarrow V_C^{LO}(r) = \frac{1}{m_N} \left(\frac{\Delta \phi^{^1D_2}(r)}{\phi^{^1D_2}(r)} + k^2 \right) = V_C(r) + V_L(r)2(2+1) + \dots$$

compare

the size of higher order

derivative terms

L dependence



L dependence

$$V_C^{LO}(r; \textcolor{green}{L}, \textcolor{blue}{E}) = V_C(r) + [\textcolor{green}{V_L(r)L^2 + V_{LL}(r)L^4 + \dots}] + \{V_p(r), \nabla^2\} + \{V_{pp}(r), \nabla^4\} + \dots$$

L dependent part

$$\begin{aligned} (\Delta + k^2) \phi^{S=0}(\vec{x}; k) &= m_N \int d^3y U(\vec{x}; \vec{y}) \phi^{S=0}(\vec{y}; k) \\ &= m_N \left[V_C(r) + [\textcolor{green}{V_L(r)L^2 + V_{LL}(r)L^4 + \dots}] \right. \\ &\quad \left. + \{V_p(r), \nabla^2\} + \{V_{pp}(r), \nabla^4\} + \dots \right] \phi^{S=0}(\vec{x}; k) \end{aligned}$$

L dependence is weak
(Noise has to be reduced.)



The size of higher L terms are small.

Summary and conclusion

Summary of this work:

We have examined the convergence of derivative expansion of non-local potential.

In this purpose, we have calculated 0 MeV, 45 MeV BS wave with using boundary condition and 1S0 ,1D2 BS wave with using cubic group.

$$V_C^{LO}(r; L, E) = V_C(r) + [V_L(r)L^2 + V_{LL}(r)L^4 + \dots] + \{V_p(r), \nabla^2\} + \{V_{pp}(r), \nabla^4\} + \dots$$

Conclusion:

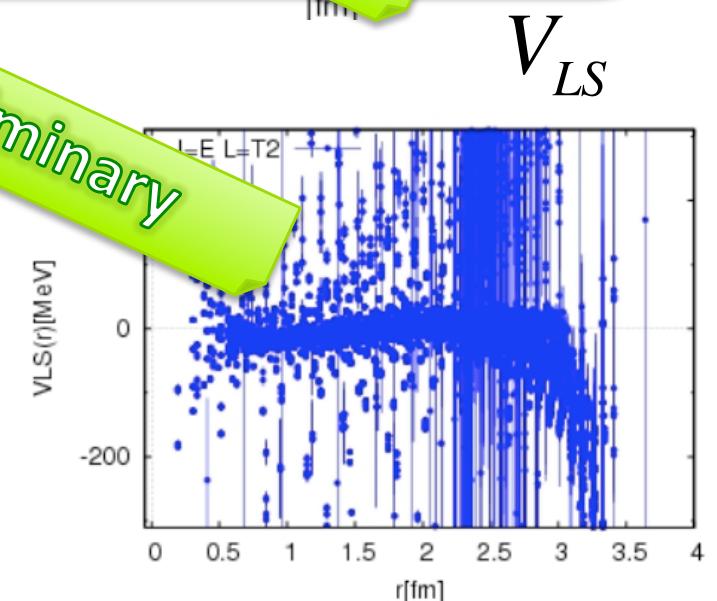
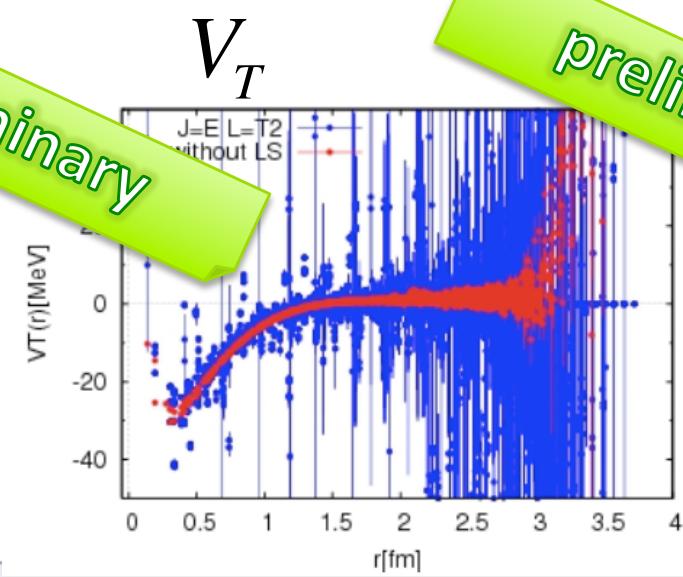
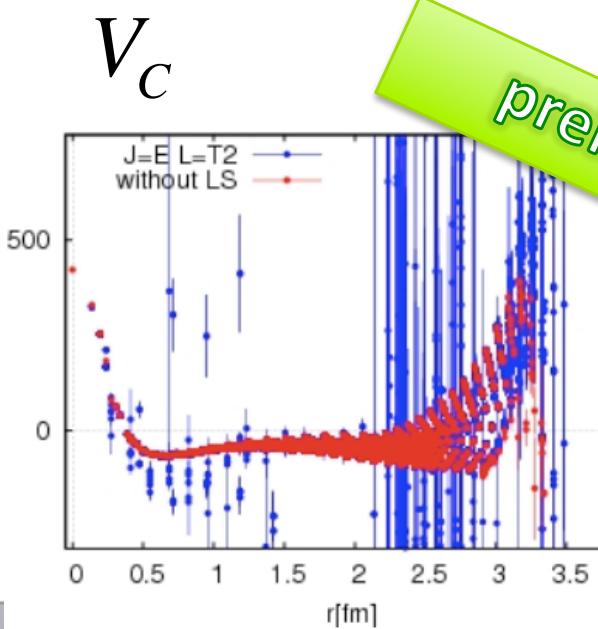
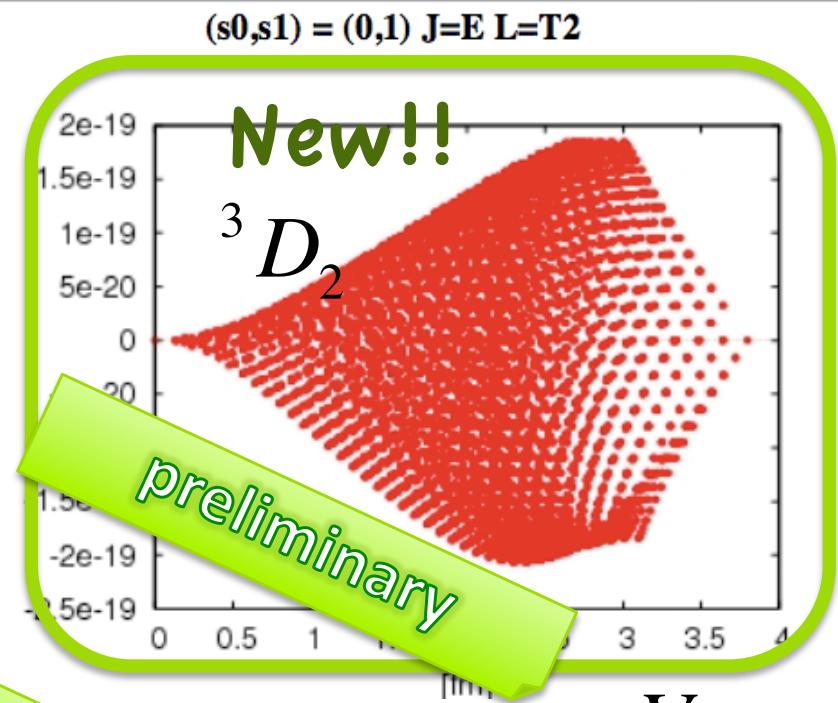
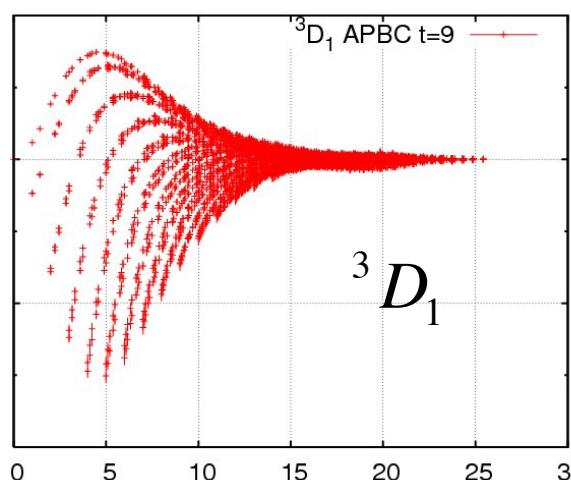
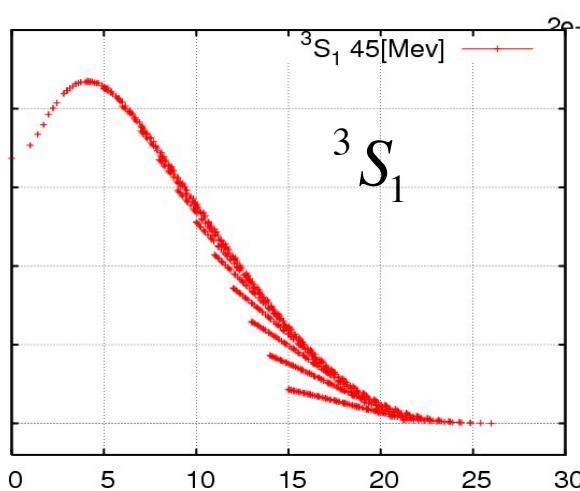
We conclude that the NN potential from the QCD obtained up to LO is valid at $E=0 \sim$ (at least) 45 MeV, and $L=0 \sim$ (at least) 2.

Future work:

Father check: full QCD, light quark mass, hyperon system...

We are applying the technique to S=1 case,
and the calculation of LS force is on going.

Very preliminary work: LS force



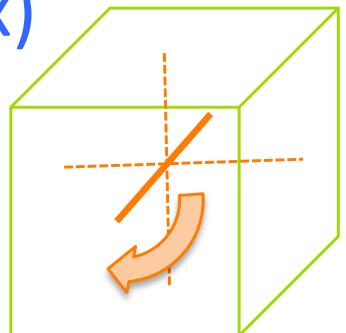


End of slides

What L is included in this system can be understood by the cubic group analysis

The representation matrix, and charactor can be obtained easily.

ex)



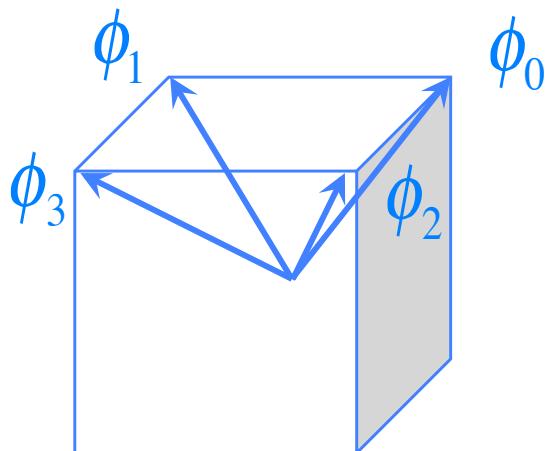
90°

$6C_4$

$$\begin{pmatrix} \phi_0 \\ \phi_1 \\ \phi_2 \\ \phi_3 \end{pmatrix} \rightarrow \begin{bmatrix} & & 1 & \\ & & 1 & \\ & & & 1 \\ 1 & & & \end{bmatrix} \begin{pmatrix} \phi_0 \\ \phi_1 \\ \phi_2 \\ \phi_3 \end{pmatrix}$$

charactor of this system

	E	$6C_4$	$3C_2$	$8C_3$	$6C_2$
χ	4	0	0	1	2



$\phi_0 \leftarrow$

$$Q = \sum_{\vec{x}} q(t, \vec{x}) \cos((+x + y + z)\pi / L)$$

$\phi_1 \leftarrow$

$$Q = \sum_{\vec{x}} q(t, \vec{x}) \cos((-x + y + z)\pi / L)$$

$\phi_2 \leftarrow$

$$Q = \sum_{\vec{x}} q(t, \vec{x}) \cos((+x - y + z)\pi / L)$$

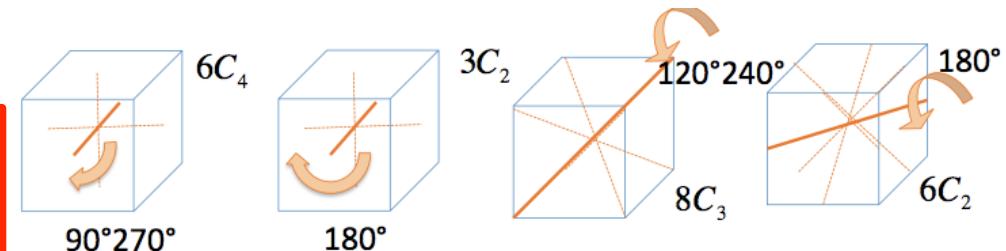
$\phi_3 \leftarrow$

$$Q = \sum_{\vec{x}} q(t, \vec{x}) \cos((-x - y + z)\pi / L)$$

What L is included in this system can be understood by the cubic group analysis

charactor of the cubic group

O	E	$6C_4$	$3C_2$	$8C_3$	$6C_2$
$\chi(A_1)$	1	1	1	1	1
$\chi(A_2)$	1	-1	1	1	-1
$\chi(E)$	2	0	2	-1	0
$\chi(T_1)$	3	1	-1	0	-1
$\chi(T_2)$	3	-1	-1	0	1



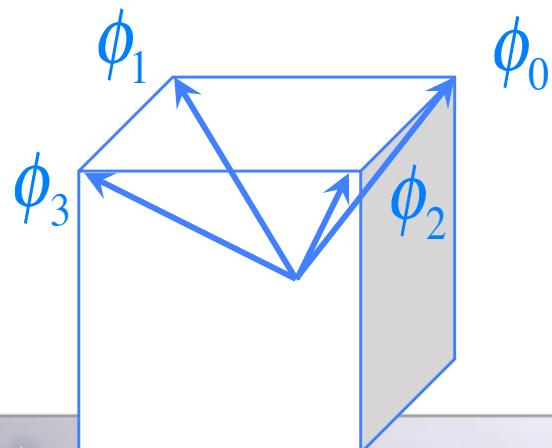
charactor of this system

	E	$6C_4$	$3C_2$	$8C_3$	$6C_2$
χ	4	0	0	1	2

irreducible decomposition:

$$c_\alpha = \sum_{i=1}^{24} \chi(\alpha)[R_i]^* \chi[R_i]$$

$$\chi(R) = c_{A1}\chi(A_1)[R] + c_{A2}\chi(A_2)[R] + \dots$$



$$L=0 \quad R_i : \text{elements of cubic group}$$

$$= A_1 + T_2 \leftarrow L=2 \text{ is dominant}$$

→ This system including $L=0$ and $L=2$ states

$$G^{(n)}_{\alpha,\beta;\alpha'\beta'}(\vec{x},\vec{y})\\=\sum_{\vec{x}_1,...,\vec{x}_6}\langle 0|T\Big[N_\alpha(\vec{x},t)N_\beta(\vec{y},t)\overline{\mathcal{N}}_{\bar{\alpha}}\overline{\mathcal{N}}_{\bar{\beta}}\Big]|0\rangle \textcolor{blue}{f^{(n)}}(\vec{x}_1,...,\vec{x}_6),$$

$$\mathcal{N}_\alpha = \sum_{x_0,x_1,x_2} \Big(q^t(x_0) C \gamma_5 \gamma_0 q(x_1)\Big) q_\alpha(x_2)$$

$$h_0(\vec{x})\equiv \cos((+x+y+z)\pi\,/\,L),$$

$$h_1(\vec{x})\equiv \cos((-x+y+z)\pi\,/\,L),$$

$$h_2(\vec{x})\equiv \cos((+x-y+z)\pi\,/\,L),$$

$$h_3(\vec{x})\equiv \cos((-x-y+z)\pi\,/\,L)$$

$$\textcolor{blue}{f}_0(\vec{x}_1,...,\vec{x}_6)\equiv h_0(\vec{x}_1)...h_0(\vec{x}_6),$$

$$\textcolor{blue}{f}_1(\vec{x}_1,...,\vec{x}_6)\equiv h_1(\vec{x}_1)...h_1(\vec{x}_6),$$

$$\textcolor{blue}{f}_2(\vec{x}_1,...,\vec{x}_6)\equiv h_2(\vec{x}_1)...h_2(\vec{x}_6),$$

$$\textcolor{blue}{f}_3(\vec{x}_1,...,\vec{x}_6)\equiv h_3(\vec{x}_1)...h_3(\vec{x}_6)$$

$$G_{\alpha,\beta;\alpha'\beta'}^{(n)}(\vec{x},\vec{y}) = \sum_{\vec{x}_1, \dots, \vec{x}_6} \langle 0 | T N_\alpha(\vec{x},t) N_\beta(\vec{y},t) \bar{q}_{\alpha_1}(\vec{x}_1) \dots \bar{q}_{\alpha_6}(\vec{x}_6) \mathbf{f}^{(n)}(\vec{x}_1, \dots, \vec{x}_6) | 0 \rangle (C\gamma_5\gamma_0)_{\alpha_1\alpha_2} (C\gamma_5\gamma_0)_{\alpha_3,\alpha_4},$$

Projection of J (total angular mom.)

$$\sum_{\vec{x}_1, \dots, \vec{x}_6} \langle 0 | T N_\alpha(\vec{x},t) N_\beta(\vec{y},t) \mathcal{P}^{(\Gamma)} \left[\bar{q}_{\alpha_1}(\vec{x}_1) \dots \bar{q}_{\alpha_6}(\vec{x}_6) \mathbf{f}^{(n)}(\vec{x}_1, \dots, \vec{x}_6) \right] | 0 \rangle (C\gamma_5\gamma_0)_{\alpha_1\alpha_2} (C\gamma_5\gamma_0)_{\alpha_3,\alpha_4},$$

$$\begin{aligned} & \sum_{\vec{x}_1, \dots, \vec{x}_6} \mathcal{P}^{(\Gamma)} \left[\bar{q}_{\alpha_1}(\vec{x}_1) \dots \bar{q}_{\alpha_6}(\vec{x}_6) \mathbf{f}^{(n)}(\vec{x}_1, \dots, \vec{x}_6) \right] | 0 \rangle \\ &= \sum_{\vec{x}_1, \dots, \vec{x}_6} \sum_{i=1}^{24} \chi^{(\Gamma)}(R_i) \left[SS \otimes S^t S^t \bar{q}_{\alpha_1}(R \vec{x}_1) \dots \bar{q}_{\alpha_6}(R \vec{x}_6) \mathbf{f}^{(n)}(\vec{x}_1, \dots, \vec{x}_6) \right] | 0 \rangle \quad \text{with } R \vec{x} \rightarrow \vec{x} \\ &= \sum_{\vec{x}_1, \dots, \vec{x}_6} \sum_{i=1}^{24} \chi^{(\Gamma)}(R_i) \left[SS \otimes S^t S^t \bar{q}_{\alpha_1}(\vec{x}_1) \dots \bar{q}_{\alpha_6}(\vec{x}_6) \mathbf{f}^{(n)}(R^{-1} \vec{x}_1, \dots, R^{-1} \vec{x}_6) \right] | 0 \rangle \end{aligned}$$

The representation of J we can obtain

(l)	\otimes	(spin=0)	J
A_1	\otimes	$A_1 = A_1$	
A_2	\otimes	$A_1 = A_2$	
E	\otimes	$A_1 = E$	
T_1	\otimes	$A_1 = T_1$	
T_2	\otimes	$A_1 = T_2$	
(l)	\otimes	(spin=1)	J
A_1	\otimes	$T_1 = T_1$	
A_2	\otimes	$T_1 = T_2$	
E	\otimes	$T_1 = T_1 \oplus T_2$	
T_1	\otimes	$T_1 = A_1 \oplus E$	$\oplus T_1 \oplus T_2$
T_2	\otimes	$T_1 = A_2 \oplus E$	$\oplus T_1 \oplus T_2$

States we can obtain with $S=1$

$S=1 \ J=A1$

$$T_1 \times T_1 = A_1$$

(spin) $\times (L) = (J)$

				L	S
				P	
				D	
A1		T1	T2	F	
		E	T1	T2	G
A2		T1	T2		
A1	E	T1	T2	G	
	E	T1	T2	H	
A1	A2	E	T1	2T2	I

Orbital Angular momentum L

3G_4 $P=+1$

				J
				0
				1
A1		T1		
		E	T2	2
A2		T1	T2	3
		E	T1	4
A1		T1	T2	5
		E	T1	6
A1	A2	E	T1	2T2

Total Angular momentum J

S=1 J=A2

$$T_1 \times T_2 = A_2 \\ (\text{spin}) \times (L) = (J)$$

$$^3D_3 + ^3G_3$$

S=1 J=E

P= + 1

$$T_1 \times T_1 = E \\ T_1 \times T_2 = E \\ (\text{spin}) \times (L) = (J)$$

$$^3D_2 + ^3G_4$$

			L	S	
			P	D	
A1	T1				
E		T2			
A2	T1	T2	F		
A1	E	T1	T2	G	
E	T1	T2	H		
A1	A2	E	T1	2T2	I

A1			J
	T1		0
A1		T1	1
E		T2	2
A1	E	T1	3
A1	A2	E	4
A1	A2	E	5
A1	A2	E	6

A1		L	S	J	
	T1	P	D	0	
A1		T1		1	
E		T2		2	
A2	E	T1	T2	3	
A1	E	T1	T2	4	
A1	E	T1	T2	5	
A1	A2	E	T1	6	
A1	A2	E	T1	2T2	I

S=1 J=T1

P= + 1

$$T_1 \times A_1 = T_1 \\ T_1 \times T_1 = T_1 \\ T_1 \times T_2 = T_1 \\ T_1 \times E = T_1$$

$$^3D_3 + ^3G_3 + ^3S_1 + ^3D_1$$

$$T_1 \times A_2 = T_2 \\ T_1 \times T_1 = T_2 \\ T_1 \times T_2 = T_2 \\ T_1 \times E = T_2$$

S=1 J=T2

P= + 1

			L	S	
			P	D	
A1	T1				
E		T2			
A2	T1	T2	F		
A1	E	T1	T2	G	
E	T1	T2	H		
A1	A2	E	T1	2T2	I

A1			J
	T1		0
A1		T2	1
E		T1	2
A2	E	T1	3
A1	A2	E	4
A1	A2	E	5
A1	A2	E	6

A1		L	S	
		P	D	
A1		T1		
E		T2		
A2	E	T1	T2	
A1	A2	E	T1	
A1	A2	E	T1	
A1	A2	E	T1	
A1	A2	E	2T2	I

A1		J	
	T1	0	
A1		1	
E		2	
A2	T1	3	
A1	A2	E	
A1	A2	2T2	I