A study of the complex action problem in a simple model for dynamical compactification in superstring theory using the factorization method

K. N. Anagnostopoulos¹ T. Azuma² J. Nishimura³

¹Department of Physics, National Technical University of Athens

²Department of Mathematics and Physics, Setsunan University

³Theory Center, KEK and SOKENDAI, Tsukuba

Lattice 2010: June 17, 2010



Outline



Introduction

- Matrix Models
- Factorization Method

2 Results

- Phase Quenched Model
- Effect of the Phase



Matrix Models Factorization Method

Motivation to ... stay awake

- Study a model with strong complex action problem
- Apply a method of wide applicability with a promise to solve the overlap problem and improve chances to extrapolate results to larger systems
- Method used in SUSY matrix models [Nishimura-K.N.A ('01)], statistical models [Azcoiti-Di Carlo-Galante-Laliena ('02)], random matrix theory [Ambjorn-K.N.A-Nishimura-Verbaarschot ('02)], finite density QCD [Fodor-Katz-Schmidt ('07)]
- Attempt to explain when and how the method could be useful



< 回 > < 回 > < 回 >

Introduction Results

Matrix Models





Introduction

- Matrix Models
- Factorization Method

- Phase Quenched Model
- Effect of the Phase



< 🗇 🕨 A study of the complex action problem in a simple model...

→ E > < E</p>

Matrix Models Factorization Method

Large–N Reduction

• Large N U(N) gauge theory on D-dim torus [Eguchi-Kawai ('82)]

$$S = -N\beta \sum_{n} \operatorname{tr} \left(U_{n,\mu} U_{n+\hat{\mu},\nu} U_{n+\hat{\nu},\mu}^{\dagger} U_{n,\nu}^{\dagger} \right)$$

$$\rightarrow S = N\beta \operatorname{tr} \left(U_{\mu} U_{\nu} U_{\mu}^{\dagger} U_{\nu}^{\dagger} \right)$$

• If $U(1)^D$ symmetry $U_\mu
ightarrow {\rm e}^{i lpha} U_\mu$ not spontaneously broken



ъ

ヘロン 人間 とくほ とくほ とう

Matrix Models Factorization Method

Large–N Reduction

• A continuum version of the large–N reduced model

[Gross-Kitazawa ('82), Gonzalez-Aroyo & Korthals-Altes ('83)]

$$S = \frac{1}{4g^2} \int d^D x \operatorname{tr} \left(\partial_\mu A_\nu - \partial_\nu A_\mu + i[A_\mu, A_\nu]\right)^2$$

$$\to S = -\frac{1}{4g^2} \operatorname{tr} \left([A_\mu, A_\nu]\right)^2$$

• If $U(1)^D$ symmetry $A_\mu \to A_\mu + \alpha_\mu$ not spontaneously broken

- Revival of interest in this model+SUSY (and its 1-dim counterparts) in the context of
 - Non-perturbative string theory
 - Gauge/Gravity duality



イロト イポト イヨト イヨト

Matrix Models Factorization Method

IKKT or IIB Matrix Model

• D = 10, N = 1, SU(N) SYM at zero volume limit as a non-perturbative formulation of type IIB superstring theory (conjecture) [Ishibashi-Kawai-Kitazawa-Tsuchiya ('96)]

$$S = -\frac{1}{g^2} \operatorname{tr} \left\{ \frac{1}{4} [A_{\mu}, A_{\nu}]^2 + \frac{1}{2} \psi_{\alpha} \left(\Gamma_{\mu} \right)_{\alpha\beta} [A_{\mu}, \psi_{\beta}] \right\}$$

 $A_{\mu}(\mu = 1, \dots, 10), \ \psi_{\alpha}(\alpha = 1, \dots, 16) \quad N \times N$ Hermitian

• ψ_{α} are Majorana–Weyl in the *adjoint*

э

イロト イポト イヨト イヨト

Matrix Models Factorization Method

Quantum Space-time

- Eigenvalues of A_µs interpreted as space–time coordinates ⇒space–time dynamically generated
- Quantum (fuzzy) space-time: A_μ not simultaneously diagonalizable on generic configurations.
- Posibility of dynamical compactification of extra dimensions



Matrix Models Factorization Method

Dynamical Compactification

• SSB of *SO*(10): Order parameter the 10 × 10 real symmetric "moment of inertia"

$$T_{\mu\nu} = \frac{1}{N} \mathrm{tr} \left(A_{\mu} A_{\nu} \right)$$

with eigenvalues

$$\lambda_1 > \lambda_2 > \ldots > \lambda_{10}$$

• e.g $SO(10) \rightarrow SO(4)$ given by

$$\langle \lambda_1 \rangle = \langle \lambda_2 \rangle = \langle \lambda_3 \rangle = \langle \lambda_4 \rangle \gg \langle \lambda_5 \rangle$$

in the large N limit

• Evidence that this is possible to realize using gaussian expansion methods

[Nishimura-Sugino ('01), Kawai-Kawamoto-Kuroki-Matsuo-Shinohara ('02)]

Matrix Models Factorization Method

Related Models Expected to Realize SO(D) SSB

- 6d IKKT model [Nishimura-Vernizzi ('00) Nishimura-K.N.A ('01)] $A_{\mu}(\mu = 1, \dots, 16), \psi_{\alpha}(\alpha = 1, \dots, 4)$ (6d Weyl, adjoint) $SO(6) \rightarrow SO(3)$ [Nishimura-Okubo-Sugino in prep]
- 4d toy model (non-SUSY)[Nishimura ('01)] $A_{\mu}(\mu = 1, \dots, 4),$

 $\psi^{f}_{\alpha}(\alpha = 1, \dots, 4; f = 1, \dots, N_{f})$ (4d Weyl, fundamental)

$$Z = \int dA d\psi d\bar{\psi} \, \mathrm{e}^{-S_B - S_F}$$

$$S_B = \frac{1}{2} N \operatorname{tr}(A_{\mu})^2 \qquad S_F = -\bar{\psi}^f_{\alpha}(\Gamma_{\mu})_{\alpha\beta} A_{\mu} \psi^f_{\beta}$$

 $N
ightarrow \infty, \, r = N_{\!f}/N \, {
m fixed} \Rightarrow SO(4)
ightarrow SO(2)$ [Nishimura-Okubo-Sugino



э

(104)]

K. N. Anagnostopoulos, T. Azuma, J. Nishimura

A study of the complex action problem in a simple model...

ヘロト ヘワト ヘビト ヘビト

Matrix Models Factorization Method

Related Models Expected to Realize SO(D) SSB

- 6d IKKT model [Nishimura-Vernizzi ('00) Nishimura-K.N.A ('01)] $A_{\mu}(\mu = 1, \dots, 16), \psi_{\alpha}(\alpha = 1, \dots, 4)$ (6d Weyl, adjoint) $SO(6) \rightarrow SO(3)$ [Nishimura-Okubo-Sugino in prep]
- 4d toy model (non-SUSY)[Nishimura ('01)] $A_{\mu}(\mu = 1, ..., 4),$ $\psi^{f}_{\alpha}(\alpha = 1, ..., 4; f = 1, ..., N_{f})$ (4d Weyl, fundamental)

$$Z = \int dA d\psi d\bar{\psi} \, \mathsf{e}^{-S_B - S_F}$$

$$S_B = \frac{1}{2} N \operatorname{tr}(A_\mu)^2 \qquad S_F = -\bar{\psi}^f_\alpha(\Gamma_\mu)_{\alpha\beta} A_\mu \psi^f_\beta$$

 $N
ightarrow \infty, \, r = N_{\!f}/N \; {\rm fixed} \Rightarrow SO(4)
ightarrow SO(2)$ [Nishimura-Okubo-Sugino ('04)]



э

A study of the complex action problem in a simple model...

ヘロン ヘアン ヘビン ヘビン

Introduction Results

Matrix Models Factorization Method

Outline



Introduction

- Matrix Models
- Factorization Method

Results

- Phase Quenched Model
- Effect of the Phase



A study of the complex action problem in a simple model...

イロト イポト イヨト イヨ

Matrix Models Factorization Method

Monte Carlo Simulations

• Complex fermionic partition function:

$$S_F = \frac{1}{2g^2} (\Gamma_{\mu})_{\alpha\beta} \operatorname{tr} \left\{ \psi_{\alpha}[A_{\mu}, \psi_{\beta}] \right\} = \Psi_i \mathcal{M}_{ij} \Psi_j \operatorname{IKKT}$$

 $\mathcal{M}_{\textit{ij}} \text{ is } 16(\textit{N}^2-1)\times 16(\textit{N}^2-1)$ ($\mathcal{O}(\textit{N}^6)$ comp effort)

 $S_F = -ar{\psi}^f_lpha(\Gamma_\mu)_{lphaeta}A_\mu\psi^f_eta = \Psi_i\mathcal{D}_{ij}\Psi_j$ 4d toy model

 \mathcal{D}_{ij} is $4N \times 4N$ ($\mathcal{O}(N^3)$ comp effort) which gives $Z_F[A] = \operatorname{Pf}\mathcal{M}[A]$ (IKKT), $Z_F[A] = (\operatorname{det}\mathcal{D}[A])^{N_f}$ (toy model) and

$$Z = \int dA \, \mathbf{e}^{-S_B[A]} \, Z_F[A]$$

where $Z_F[A]$ is in general complex \Rightarrow (strong) complex action problem



ъ

・ロト ・ 理 ト ・ ヨ ト ・

Matrix Models Factorization Method

Dynamical Compactification

d-dimensional configurations $\{A_{\mu}\}$

$$BO \in SO(10)$$
 s.t. $A'_{\mu} = O_{\mu\nu}A_{\nu}$
 $A'_{d+1} = A'_{d+2} = \dots = A'_{10} = 0$



[Nishimura-Vernizzi ('00)]

- Stationarity of phase increases for lower *d*, compensates entropy loss
- Low dimensional configurations ($d \le 6$ for IKKT $d \le 3$ for 4d toy model) have $Z_F[A] \ge 0!$



K. N. Anagnostopoulos, T. Azuma, J. Nishimura

Matrix Models Factorization Method

Dynamical Compactification

d-dimensional configurations $\{A_{\mu}\}$

$$dO \in SO(10)$$
 s.t. $A'_{\mu} = O_{\mu\nu}A_{\nu}$
 $A'_{d+1} = A'_{d+2} = \ldots = A'_{10} = 0$

$\{A_{\mu}\}$ is 9–dimensional	$\Gamma = 0 \mod \pi$	$Pf\mathcal{M}(A) \in \mathbb{R}$
$\{A_{\mu}\}$ is 8–dimensional	$\frac{\partial\Gamma}{\partial A_{\mu_1}}=0$	
$\{A_{\mu}\}$ is 7–dimensional	$rac{\partial^2 \Gamma}{\partial A_{\mu_1} \partial A_{\mu_2}} = 0$	
$\{A_{\mu}\}$ is 6–dimensional	$rac{\partial^3 \Gamma}{\partial A_{\mu_1} \partial A_{\mu_2} \partial A_{\mu_3}} = 0$	$Pf\mathcal{M}(A) \geq 0$

[Nishimura-Vernizzi ('00)]

- Stationarity of phase increases for lower *d*, compensates entropy loss
- Low dimensional configurations ($d \le 6$ for IKKT $d \le 3$ for 4d toy model) have $Z_F[A] \ge 0!$



K. N. Anagnostopoulos, T. Azuma, J. Nishimura

Matrix Models Factorization Method

Dynamical Compactification

d-dimensional configurations $\{A_{\mu}\}$

$$dO \in SO(10)$$
 s.t. $A'_{\mu} = O_{\mu\nu}A_{\nu}$
 $A'_{d+1} = A'_{d+2} = \ldots = A'_{10} = 0$

$\{A_{\mu}\}$ is 9–dimensional	$\Gamma = 0 \mod \pi$	$Pf\mathcal{M}(A) \in \mathbb{R}$
$\{A_{\mu}\}$ is 8–dimensional	$rac{\partial \Gamma}{\partial A_{\mu_1}} = 0$	
$\{A_{\mu}\}$ is 7–dimensional	$rac{\partial^2 \Gamma}{\partial A_{\mu_1} \partial A_{\mu_2}} = 0$	
$\{A_{\mu}\}$ is 6–dimensional	$rac{\partial^3 \Gamma}{\partial A_{\mu_1} \partial A_{\mu_2} \partial A_{\mu_3}} = 0$	$Pf\mathcal{M}(A) \geq 0$

[Nishimura-Vernizzi ('00)]

- Stationarity of phase increases for lower *d*, compensates entropy loss
- Low dimensional configurations (d ≤ 6 for IKKT d ≤ 3 for 4d toy model) have Z_F[A] ≥ 0!



Matrix Models Factorization Method

Reweighting...

- Fluctuations of complex phase crucial in the realization of the SSB scenario [Nishimura-K.N.A ('01)]
 ... but difficult to simulate
- Simulate phase quenched model

$$Z_0 = \int dA \, \mathrm{e}^{-S_0}$$

$$Z_F[A] = |Z_F[A]| \mathbf{e}^{i\Gamma} \qquad S_{\mathbf{0}} = S_B - \ln |Z_F[A]|$$
$$\langle \lambda_n \rangle = \frac{\langle \lambda_n \mathbf{e}^{i\Gamma} \rangle_{\mathbf{0}}}{\langle \mathbf{e}^{i\Gamma} \rangle_{\mathbf{0}}}$$



э

→ E → < E →</p>

< 🗇 🕨

Matrix Models Factorization Method

Density of States

Principal moments of inertia

$$\tilde{\lambda}_n \equiv \frac{\lambda_n}{\langle \lambda_n \rangle_0}$$

(deviation from 1: effect of phase)

density of states

$$\langle \tilde{\lambda}_n \rangle = \int_0^\infty dx \, x \, \rho_n(x) \qquad \rho_n(x) = \langle \delta(x - \tilde{\lambda}_n) \rangle$$

• Factorization:

$$\rho_n(x) = \frac{1}{\langle \mathbf{e}^{i\Gamma} \rangle_0} \rho_n^{(0)}(x) w_n(x)$$
$$\rho_n^{(0)}(x) = \langle \delta(x - \tilde{\lambda}_n) \rangle_0 \quad w_n(x) \equiv \langle \mathbf{e}^{i\Gamma} \rangle_{n,x}$$
$$\langle \cdot \rangle_{n,x} \to Z_{n,x} = \int dA \, \mathbf{e}^{-S_0} \delta(x - \tilde{\lambda}_n)$$



Matrix Models Factorization Method

Solution

Minimize the "free energy"

$$\mathcal{F}_n(x) = -\ln \rho_n(x)$$

by solving the saddle point equation

$$\frac{1}{N^2} f_n^{(0)}(x) \equiv \frac{d}{dx} \ln \rho_n^{(0)}(x) = -\frac{1}{N^2} \frac{d}{dx} \ln w_n(x) \equiv -\frac{d}{dx} \Phi_n(x)$$

- $\frac{1}{N^2} f_n^{(0)}(x)$: No complex action problem, calculate at large *N*.
- $\Phi_n(x)$: Complex action problem, obtain by FSS
- Error in determining (λ_n) does not propagate exponentially in N.



< 同 > < 三 > < 三 >

Matrix Models Factorization Method

Implementation

Simulate the system

$$Z_{n,V} = \int dA \, \mathbf{e}^{-S_0 - V(\lambda_n)} \quad \mathbf{e.g.} \quad V(z) = \frac{1}{2} \gamma (z - \xi)^2$$
$$\gamma \sim 10^3 - 10^7, \quad \xi \sim [-10 \langle \lambda_n \rangle_0, +100 \langle \lambda_n \rangle_0]$$

• Consider the distribution function:

$$\rho_{n,V}(x) = \langle \delta(x - \tilde{\lambda}_n) \rangle_{n,V} \propto \rho_n^{(0)}(x) \mathbf{e}^{-V(x \langle \lambda_n \rangle_0)}$$

Solve

$$0 = \frac{d}{dx} \ln \rho_{n,V}(x) \big|_{x=x_p} = f_n^{(0)}(x_p) - \langle \lambda_n \rangle_0 V'(x_p \langle \lambda_n \rangle_0)$$

• Use estimator $x_p = \langle \tilde{\lambda}_n \rangle_{n,V}$ and

 $w_n(x_p) = \langle \cos \Gamma \rangle_{n,V}$ $f_n^{(0)}(x_p) = \gamma \langle \lambda_n \rangle_0 \left(\langle \lambda_n \rangle_{n,V} - \xi \right)$



Introduction Results

Phase Quenched Model

Outline



- Matrix Models
- Factorization Method

Results 2

- Phase Quenched Model
- Effect of the Phase



< 🗇 🕨 A study of the complex action problem in a simple model...

(4) 王

3

Introduction Results Ef

Phase Quenched Model Effect of the Phase

No SSB: $\langle\lambda_n angle_0=1+rac{r}{2},\,r=1/4,1,2,4$ [Nishimura (01)]





Phase Quenched Model Effect of the Phase

Scaling of $f_n^{(0)}(x)$ for small x: $d \approx (n-1)$

• Expect from measure dA ($A_{\mu} \sim \sqrt{x}$): $\rho_n^{(0)}(x) \sim (\sqrt{x})^{(5-n)N^2}$

$$\frac{1}{N^2} f_n^{(0)}(x) \approx \left\{ \frac{1}{2} (5-n) + r \delta_{n,1} \right\} \frac{1}{x} + a_n$$

(for n = 1 also contribution from fermion determinant)





Phase Quenched Model Effect of the Phase

Scaling of $f_n^{(0)}(x)$ for large $x: d \approx n$

• Leading term from $\rho_N^{(0)}(x) \sim \exp\left(-\langle \frac{1}{2}N \operatorname{tr}(A_{\mu})^2 \rangle_{n,V}\right)$ = $\exp\left(-\frac{1}{2}N^2 \sum_{k=1}^n \langle \lambda_k \rangle_{n,V}\right) \sim \exp\left(-\frac{1}{2}N^2 nx \langle \lambda_n \rangle_0\right)$ plus subleading term from measure and fermionic determinant:

$$\frac{1}{N^2} f_n^{(0)}(x) \approx -\frac{1}{2} n \langle \lambda_n \rangle_0 + \left(\frac{n}{2} + r\right) \frac{1}{x}$$



Introduction Results

Effect of the Phase

Outline



- Matrix Models
- Factorization Method

Results 2 Phase Quenched Model

Effect of the Phase



→ E > < E</p>

Scaling of $\Phi_n(x)$ for small x: $d \approx (n-1)$

• Since $A_{\mu} \sim \sqrt{x}$, fluctuations of phase has width $\delta\Gamma \sim (\sqrt{x})^{5-n}$ and assuming the distribution is gaussian $(-\ln w_n(x) = \delta\Gamma^2/2)$

$$\Phi_n(x) = \frac{1}{N^2} \ln w_n(x) \simeq -c_n x^{5-n}, \qquad x \ll 1, \ n = 2, 3, 4$$



K. N. Anagnostopoulos, T. Azuma, J. Nishimura A study of the complex action problem in a simple model...

Scaling of $\Phi_n(x)$ for small x: $d \approx (n-1)$

• Since $A_{\mu} \sim \sqrt{x}$, fluctuations of phase has width $\delta\Gamma \sim (\sqrt{x})^{5-n}$ and assuming the distribution is gaussian $(-\ln w_n(x) = \delta\Gamma^2/2)$

$$\Phi_n(x) = \frac{1}{N^2} \ln w_n(x) \simeq -c_n x^{5-n}, \qquad x \ll 1, \ n = 2, 3, 4$$



K. N. Anagnostopoulos, T. Azuma, J. Nishimura A study of the complex action problem in a simple model...

Scaling of $\Phi_n(x)$ for large $x: d \approx n$

• Since $A_{\mu} \sim \sqrt{x}$, fluctuations of phase has width $\delta\Gamma \sim (1/\sqrt{x})^{4-n}$ and assuming the distribution is gaussian $(-\ln w_n(x) = \delta\Gamma^2/2)$

$$\Phi_n(x) = \frac{1}{N^2} \ln w_n(x) \simeq -d_n x^{-(4-n)}, \qquad x \gg 1, \, n = 1, 2, 3$$



Scaling of $\Phi_n(x)$ for large x: $d \approx n$

• Since $A_{\mu} \sim \sqrt{x}$, fluctuations of phase has width $\delta\Gamma \sim (1/\sqrt{x})^{4-n}$ and assuming the distribution is gaussian $(-\ln w_n(x) = \delta\Gamma^2/2)$

$$\Phi_n(x) = \frac{1}{N^2} \ln w_n(x) \simeq -d_n x^{-(4-n)}, \qquad x \gg 1, \, n = 1, 2, 3$$



K. N. Anagnostopoulos, T. Azuma, J. Nishimura A study of the complex action problem in a simple model...

Solution: Double peak structure for n = 2, 3

• Using c_n and d_n we extrapolate...



r = 1 n = 1: Large dimension dominates



Solution: Double peak structure for n = 2, 3

• Using c_n and d_n we extrapolate...





Solution: Double peak structure for n = 2, 3

• Using c_n and d_n we extrapolate...





Introduction Results Effect of the Phase Conclusions

Solution: Double peak structure for n = 2, 3

• Using c_n and d_n we extrapolate...







Solution: Double peak structure for n = 2, 3

• Using c_n and d_n we extrapolate...



r = 2 n = 1: Large dimension dominates



Solution: Double peak structure for n = 2, 3

• Using c_n and d_n we extrapolate...





Solution: Double peak structure for n = 2, 3

• Using c_n and d_n we extrapolate...





Solution: Double peak structure for n = 2, 3

• Using c_n and d_n we extrapolate...



r = 2 n = 4: Small dimension dominates



Introduction Results

Phase Quenched Model Effect of the Phase

Solution: $\langle \tilde{\lambda}_n \rangle$

	r = 1			r = 2			
n	x _s	$x_{l} \langle \tilde{\lambda}_{n} \rangle_{\text{Gauss}}$		x _s	x _l	$\langle \tilde{\lambda}_n angle_{Gauss}$	
1		2.12	1.4		1.94	1.7	
2	0.49	1.29	1.4	0.48	1.36	1.7	
3	0.67 ¹	1.13	0.7	0.53 ¹	1.16	0.5	
4	0.75		0.5	0.51		0.1	

 $\langle \tilde{\lambda}_n
angle_{
m Gauss}$ obtained by GEM [Nishimura-Okubo-Sugino ('04)]

э

¹assuming $SO(4) \rightarrow SO(2)$

K. N. Anagnostopoulos, T. Azuma, J. Nishimura

A study of the complex action problem in a simple model...

・ 同 ト ・ ヨ ト ・ ヨ ト

Phase Quenched Mode Effect of the Phase

Solution:

- $\langle \tilde{\lambda}_1 \rangle > 1 > \langle \tilde{\lambda}_4 \rangle$ shows SSB
- Determine dominant peak for n = 2, 3 [Nishimura-K.N.A ('01)]

$$\begin{aligned} \Delta_n &\stackrel{\text{def}}{=} \quad \frac{1}{N^2} \Big\{ \log \rho_n(x_l) - \log \rho_n(x_s) \Big\} \\ &= \quad \Phi_n(x_l) - \Phi_n(x_s) + \Xi_n \\ \Xi_n &\stackrel{\text{def}}{=} \quad \int_{x_s}^{x_l} dx \, \left\{ \frac{1}{N^2} f_n^{(0)}(x) \right\} \end{aligned}$$

 Δ_n depends on $\Phi_n(x)$ only at x_l , x_s Ξ_n computed by fitting $\frac{1}{N^2} f_n^{(0)}(x)$ to a continuous function in $[x_s, x_l]$

• $\Delta_n > 0 \Rightarrow x_l$ dominates; $\Delta_n < 0 \Rightarrow x_s$ dominates



э

A study of the complex action problem in a simple model...

・ 回 と ・ ヨ と ・ ヨ と

Introduction Results

Phase Quenched Model Effect of the Phase

Solution:

	r = 1			r = 2				
n	$\Phi_n(x_s)$	$\Phi_n(x_1)$	Ξ_n	Δ_n	$\Phi_n(x_s)$	$\Phi_n(x_l)$	Ξ_n	Δ_n
1		-0.23				-0.18		
2	-0.27	-0.20	0.27	0.34	-0.25	-0.25	0.25	0.25
3	-0.18	-0.22	0.07	0.03	-0.19	-0.31	0.12	0.00
4	-0.17				-0.17			

- n = 2 large x peak dominates
- n = 3 uncertain

э



Summary

4d toy matrix model:

- Dynamical compactification in matrix models: first time from direct, non perturbative calculations
- Importance of phase in SSB: No SSB if absent
- Double peak structure: Two dynamical length scales
- Consistent with gaussian expansion method

Factorization Method:

- Compute density of states (DOS) at regions where the competing phase fluctuations+entropy favour configurations using simple scaling properties of the phase and DOS of phase quenched model
- Expectation values computed by minimizing free energy, drastically reducing propagation of errors
- Applicable to a wide range of models



Summary

4d toy matrix model:

- Dynamical compactification in matrix models: first time from direct, non perturbative calculations
- Importance of phase in SSB: No SSB if absent
- Double peak structure: Two dynamical length scales
- Consistent with gaussian expansion method

Factorization Method:

- Compute density of states (DOS) at regions where the competing phase fluctuations+entropy favour configurations using simple scaling properties of the phase and DOS of phase quenched model
- Expectation values computed by minimizing free energy, drastically reducing propagation of errors
- Applicable to a wide range of models



- Study dynamical compactification in 6D IKKT model using Monte Carlo and gaussian expansion method
- Improve results in 4d model:

$$\rho(x_1, x_2, x_3, x_4) = \langle \prod_k \delta(x_k - \tilde{\lambda}_k) \rangle$$



< 回 > < 回 > < 回