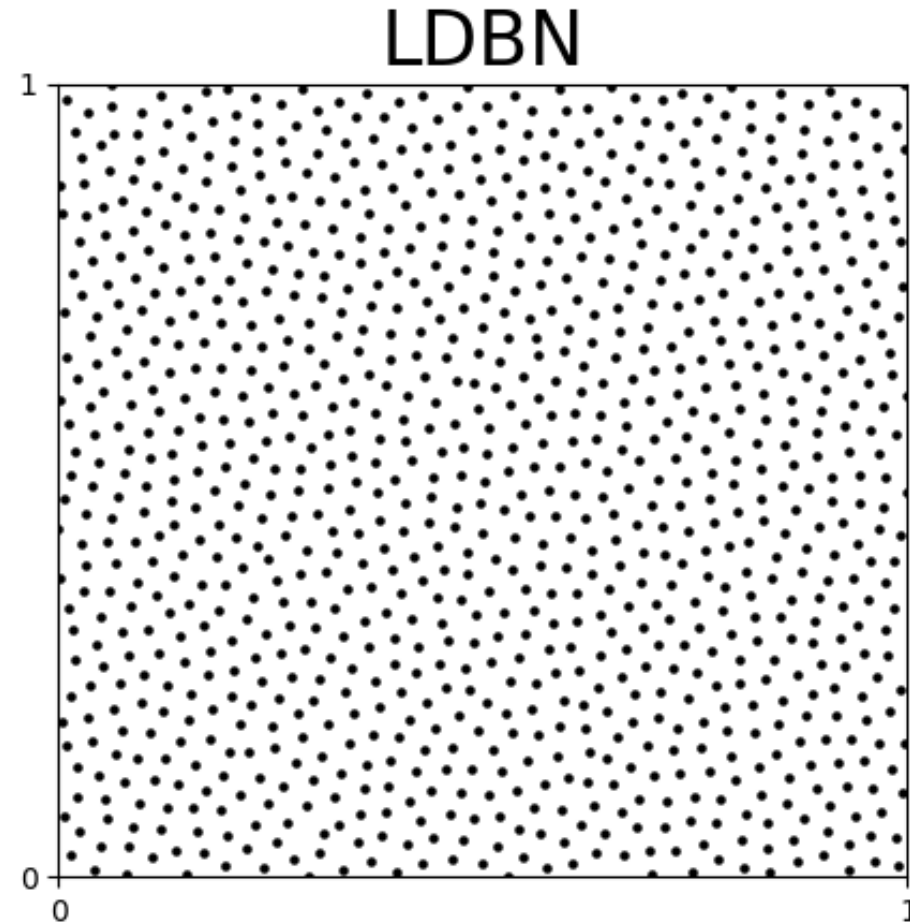
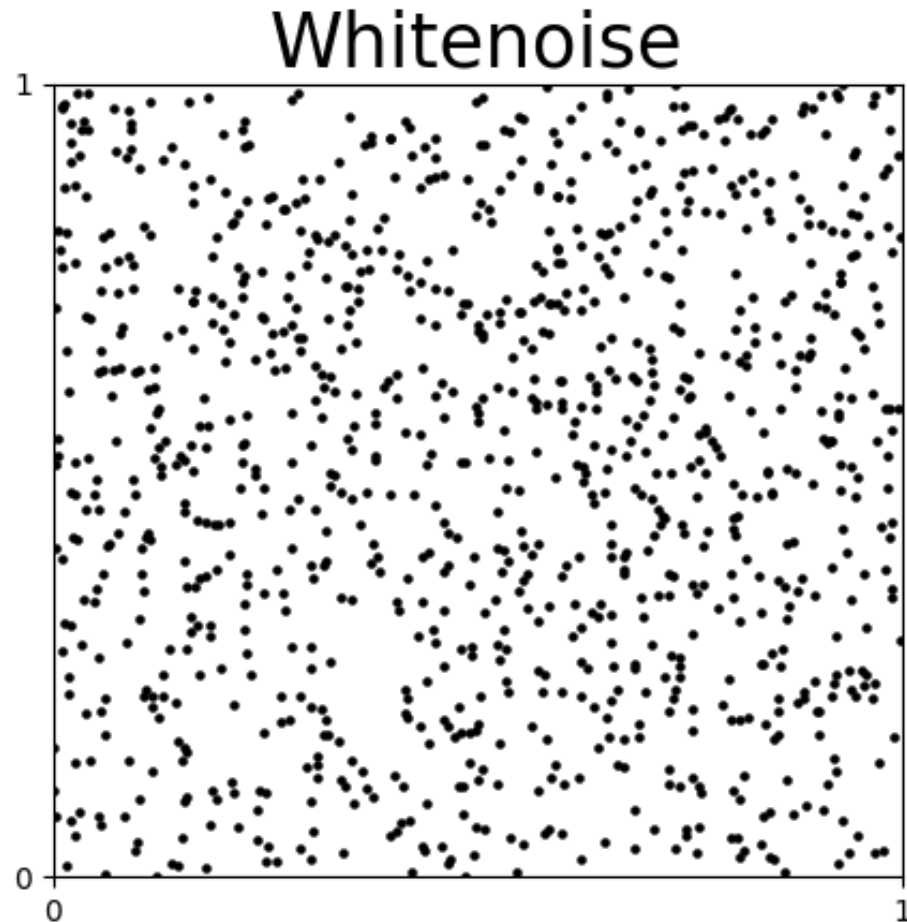


Investigating Quasi Monte Carlo in Geant4 / Gate simulations

Théo Kaprelian¹,
 Bastien Doignies²,
 Nicolas Bonneel²,
 David Coeurjolly²,
 Victor Ostromoukhov²,
 David Sarrut¹

¹CREATIS; CNRS (UMR 5220); INSERM (U1294); INSA Lyon; Université de Lyon, France,
²LIRIS; CNRS (UMR 5205); INSA Lyon; UCBL; Université de Lyon, France

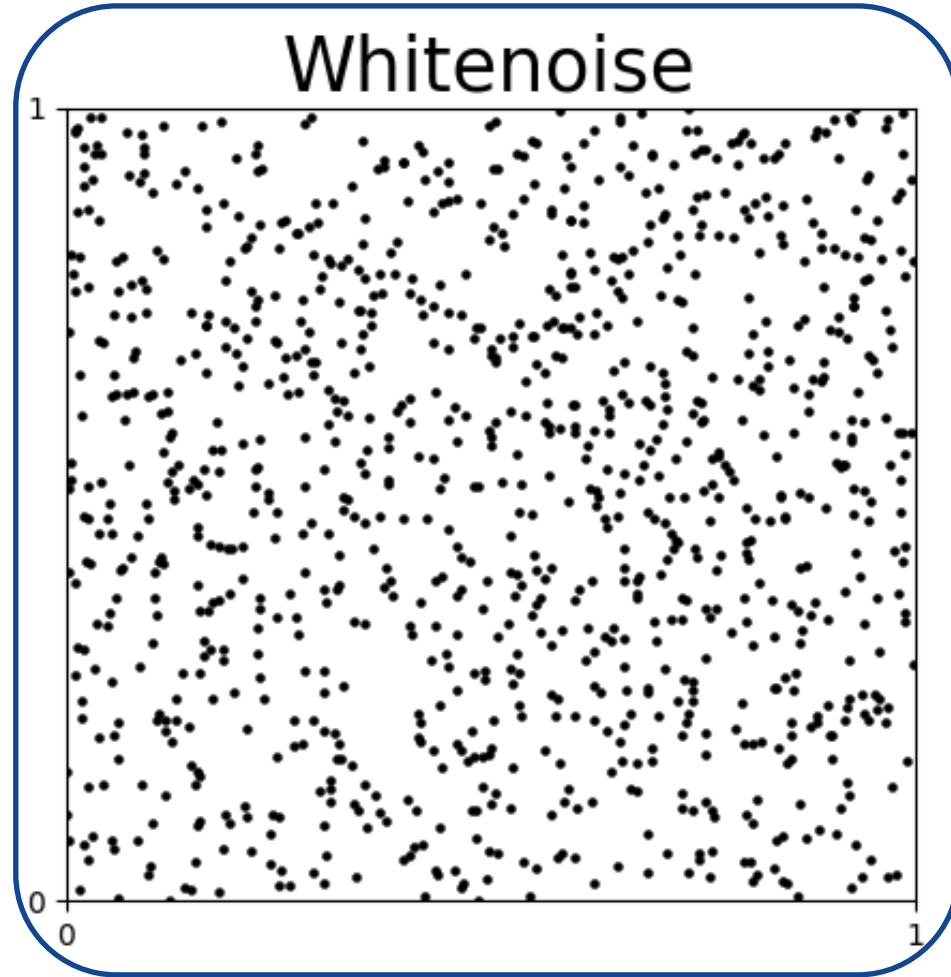
Points Matter



$N = 1024$ points

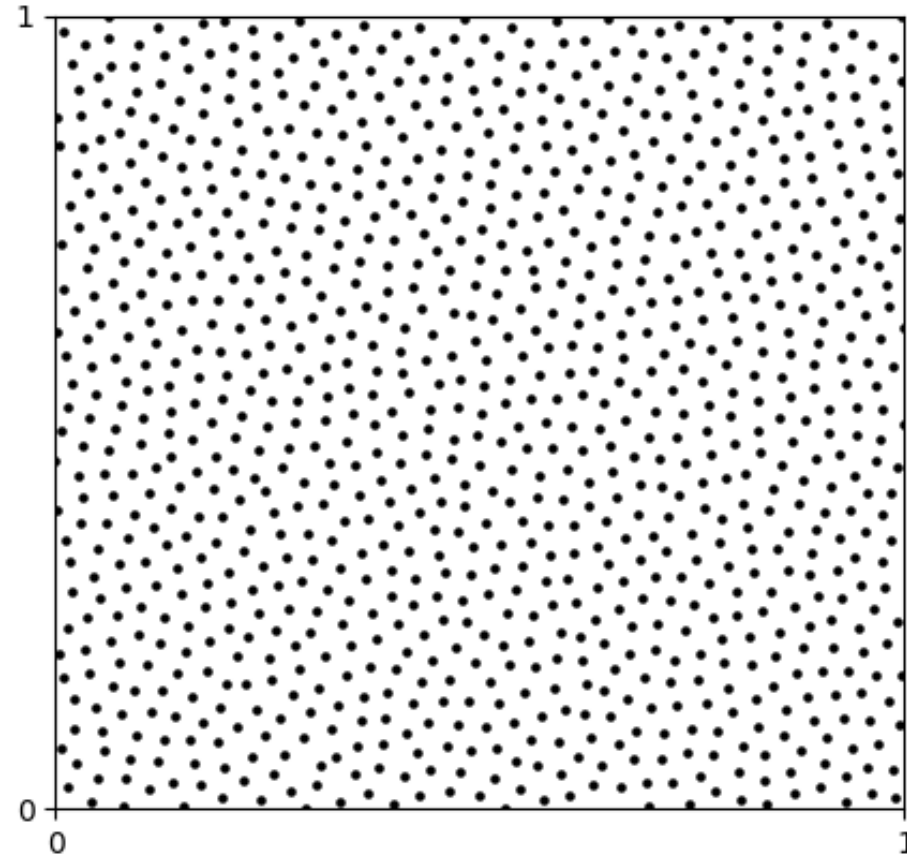
Points Matter

Whitenoise



Pseudo-
Random

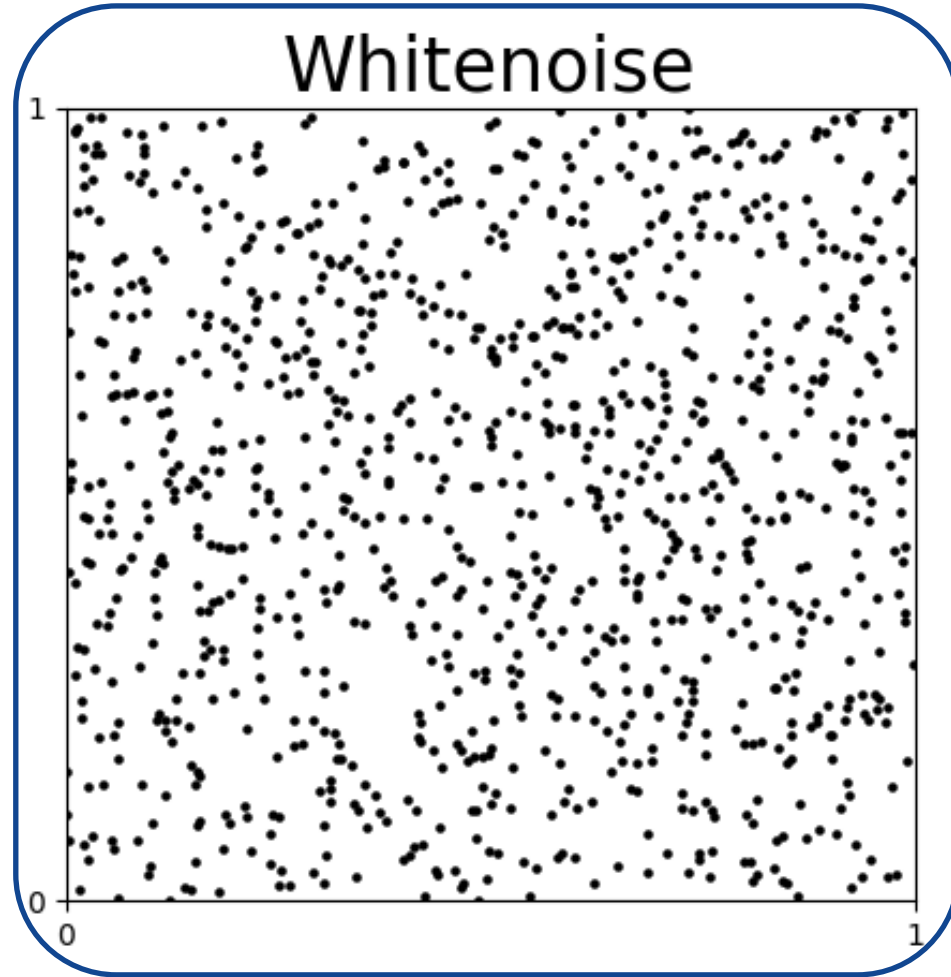
LDBN



N = 1024 points

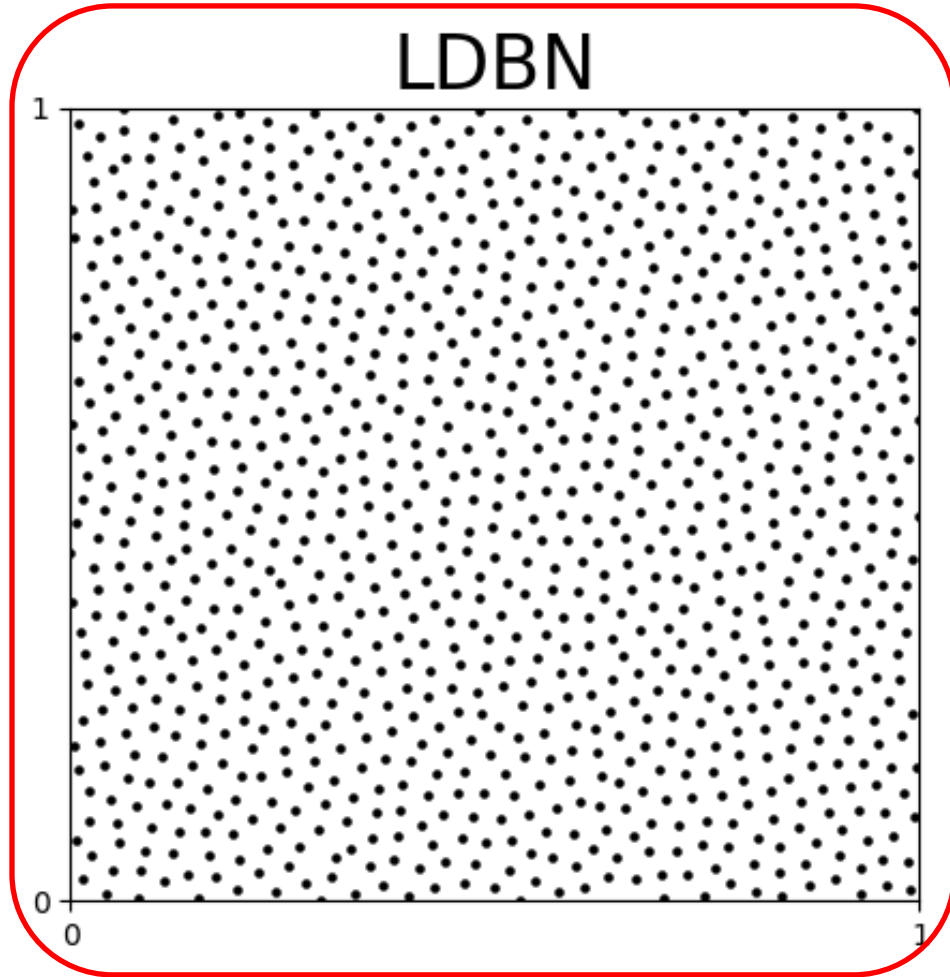
Points Matter

Whitenoise



Pseudo-Random

LDBN



Quasi-Random

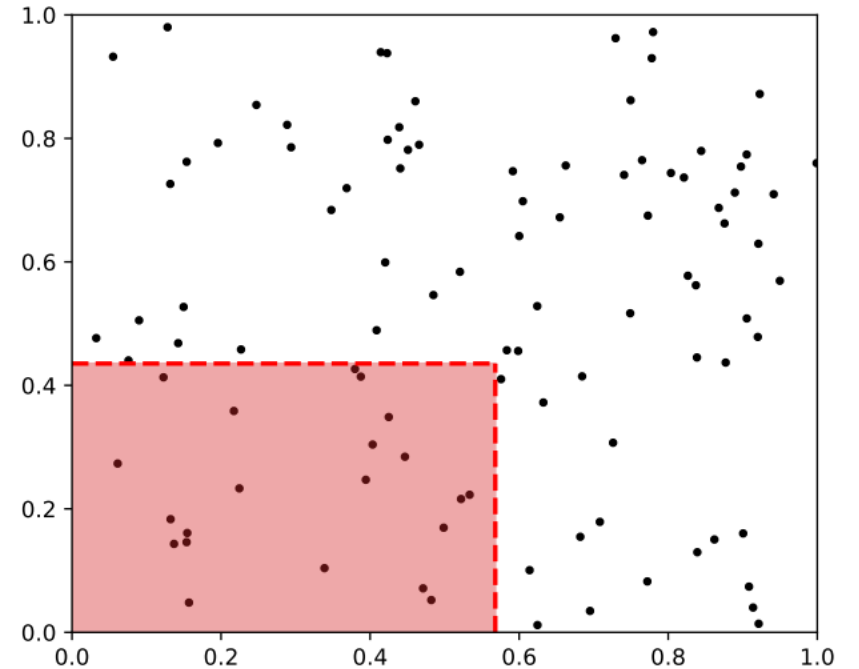
N = 1024 points

Low Discrepancy

Koksma-Hlawka inequality :

$$\left| \frac{1}{N} \sum_{i=1}^N f(x_i) - \int_{Id} f(u) du \right| \leq V(f) D_N^*(x_1, \dots, x_N)$$

where D_N^* : “discrepancy”

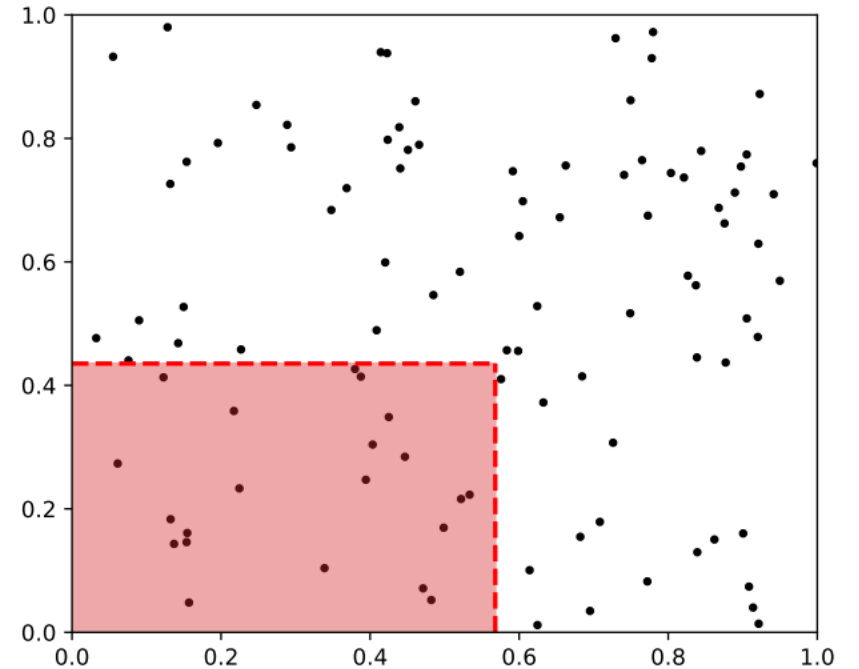


Low Discrepancy

Koksma-Hlawka inequality :

$$\left| \frac{1}{N} \sum_{i=1}^N f(x_i) - \int_{Id} f(u) du \right| \leq V(f) D_N^* (x_1, \dots, x_N)$$

where D_N^* : “discrepancy”



« Whitenoise » (or *Random*) :

$$E[D_N^* (x_1, \dots, x_N)] \leq \frac{C_1}{\sqrt{N}}$$

« Low discrepancy » (or *Quasi Random*) if :

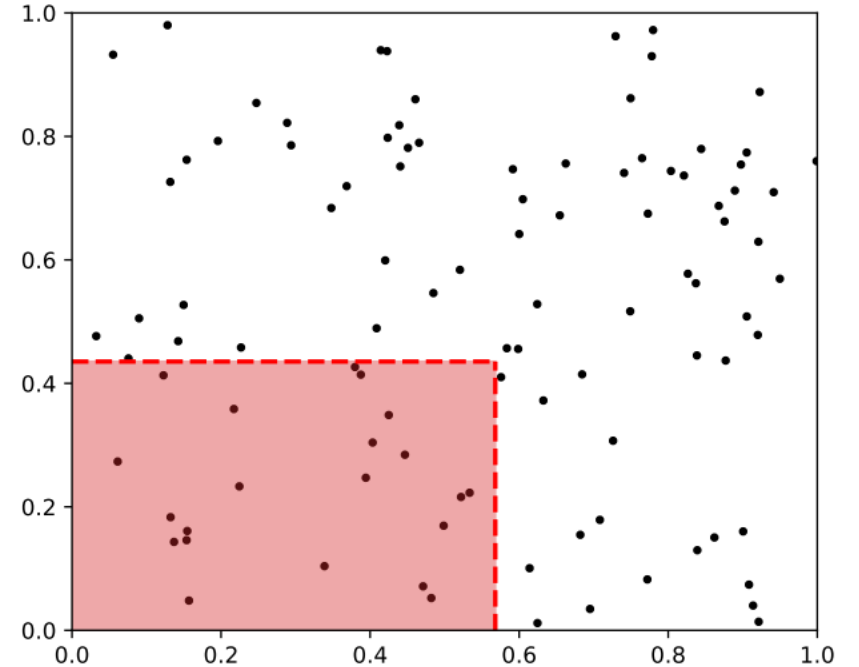
$$D_N^* (x_1, \dots, x_N) \leq \frac{C_2 (\ln N)^d}{N}$$

Low Discrepancy

Koksma-Hlawka inequality :

$$\left| \frac{1}{N} \sum_{i=1}^N f(x_i) - \int_{Id} f(u) du \right| \leq V(f) D_N^* (x_1, \dots, x_N)$$

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« Whitenoise » (or *Random*) :

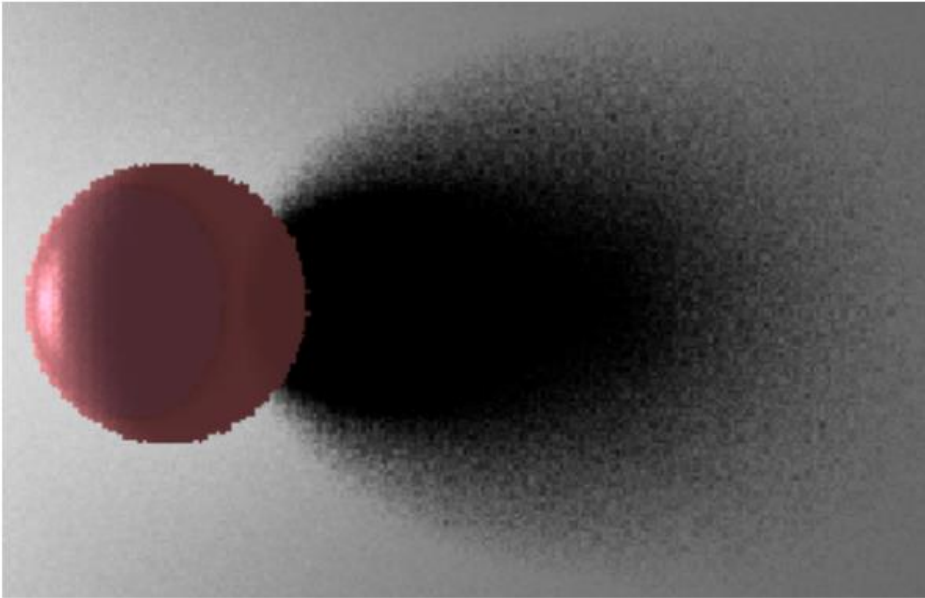
$$E[D_N^* (x_1, \dots, x_N)] \leq \frac{C_1}{\sqrt{N}}$$

« Low discrepancy » (or *Quasi Random*) if :

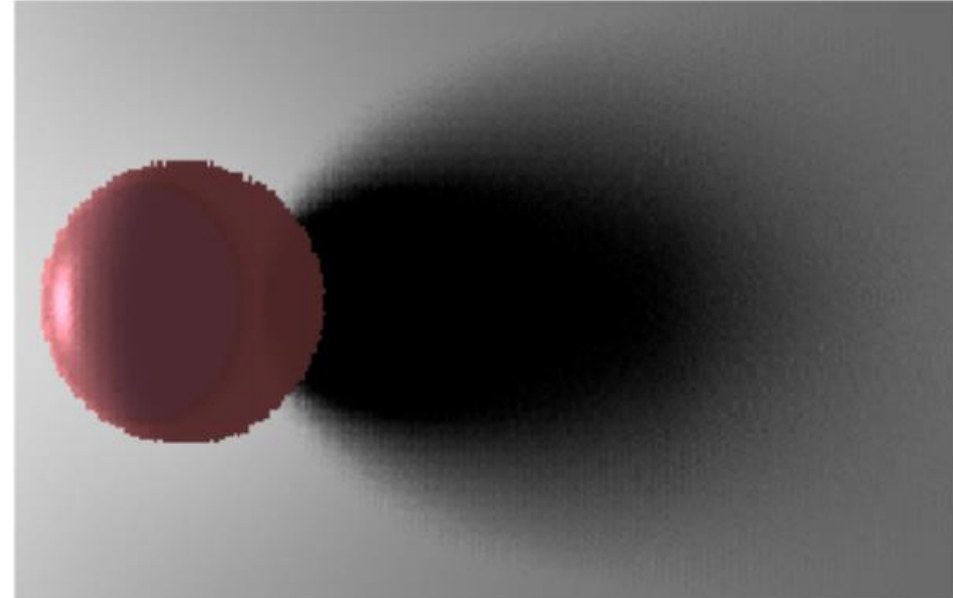
$$D_N^* (x_1, \dots, x_N) \leq \frac{C_2 (\ln N)^d}{N}$$

QMC in Rendering (Computer Graphics)

Whitenoise (MC)



Sobol (QMC)

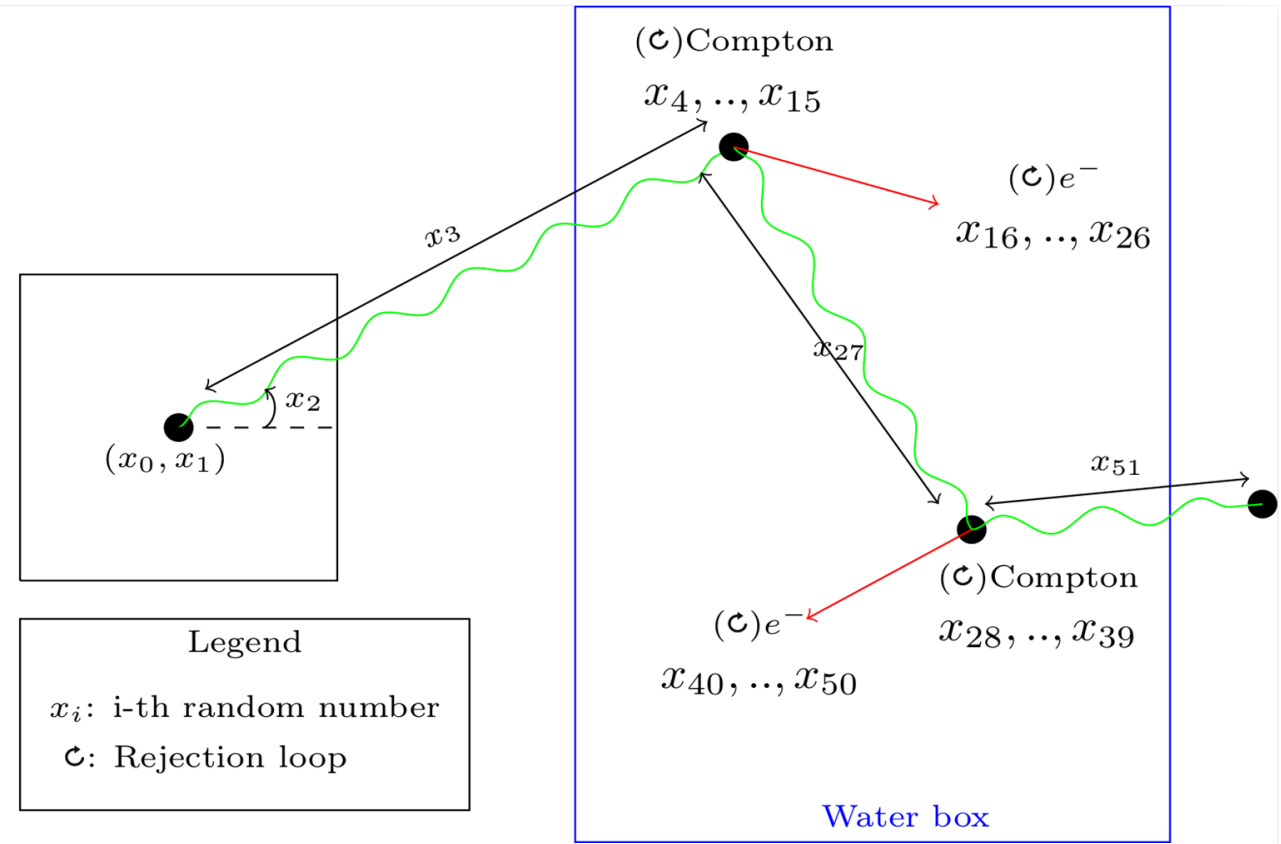


36 rays per pixel

QMC in Geant4

k^{th} point of Sobol' sequence in dimension $d : (x_0^k, x_1^k, \dots, x_{d-1}^k)$

Each dimension $i < d \rightarrow$ one *physical* dimension of the simulation



QMC in Geant4

k^{th} point of Sobol' sequence in dimension $d : (x_0^k, x_1^k, \dots, x_{d-1}^k)$

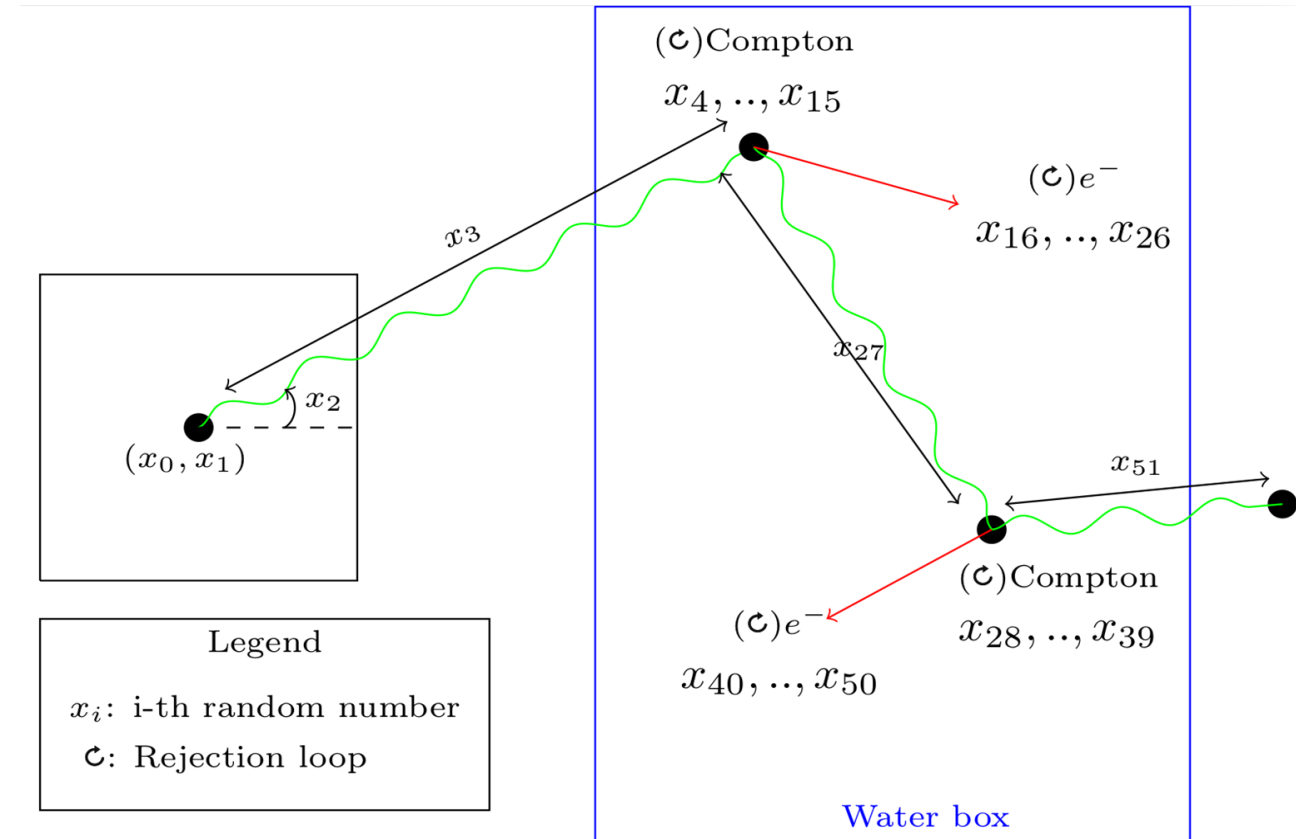
Each dimension $i < d \rightarrow$ one *physical* dimension of the simulation

HepRandomEngine

...

double flat(std::source_location)

...



“Calling context” = dimension

Experience 1

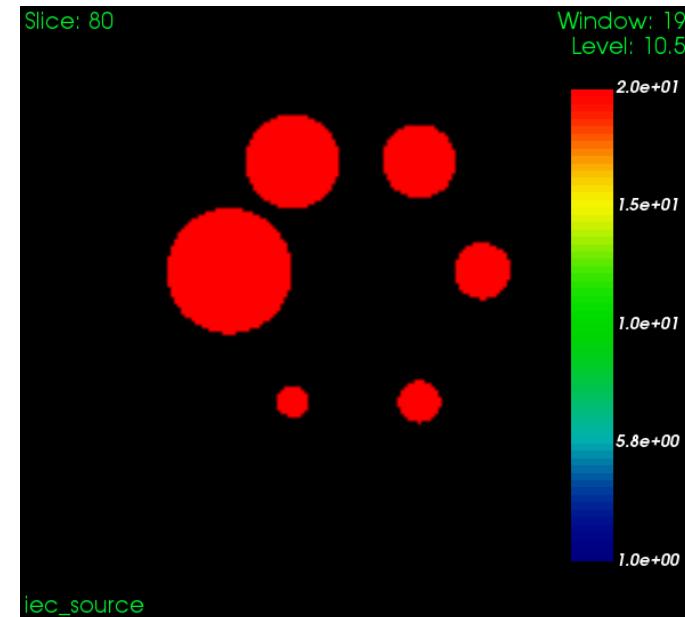
Toy SPECT experiment.

Source :

- 6 spheres
- gamma particles
- 140 keV
- source-to-background ratio : 20:1

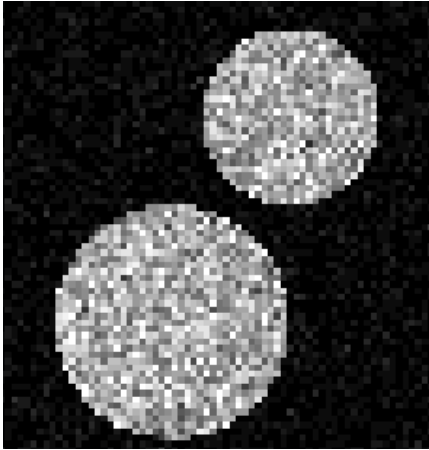
Medium : **vacuum**

Sampling : **5 QMC dimensions** (initial position / direction)

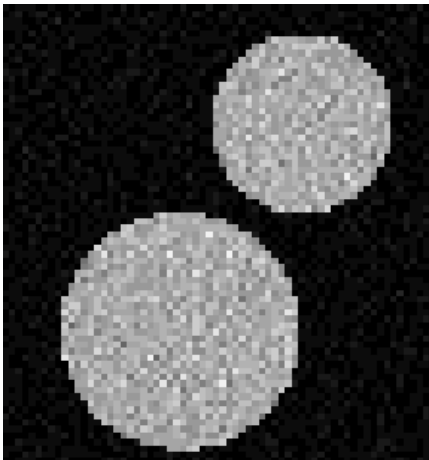


Experience 1

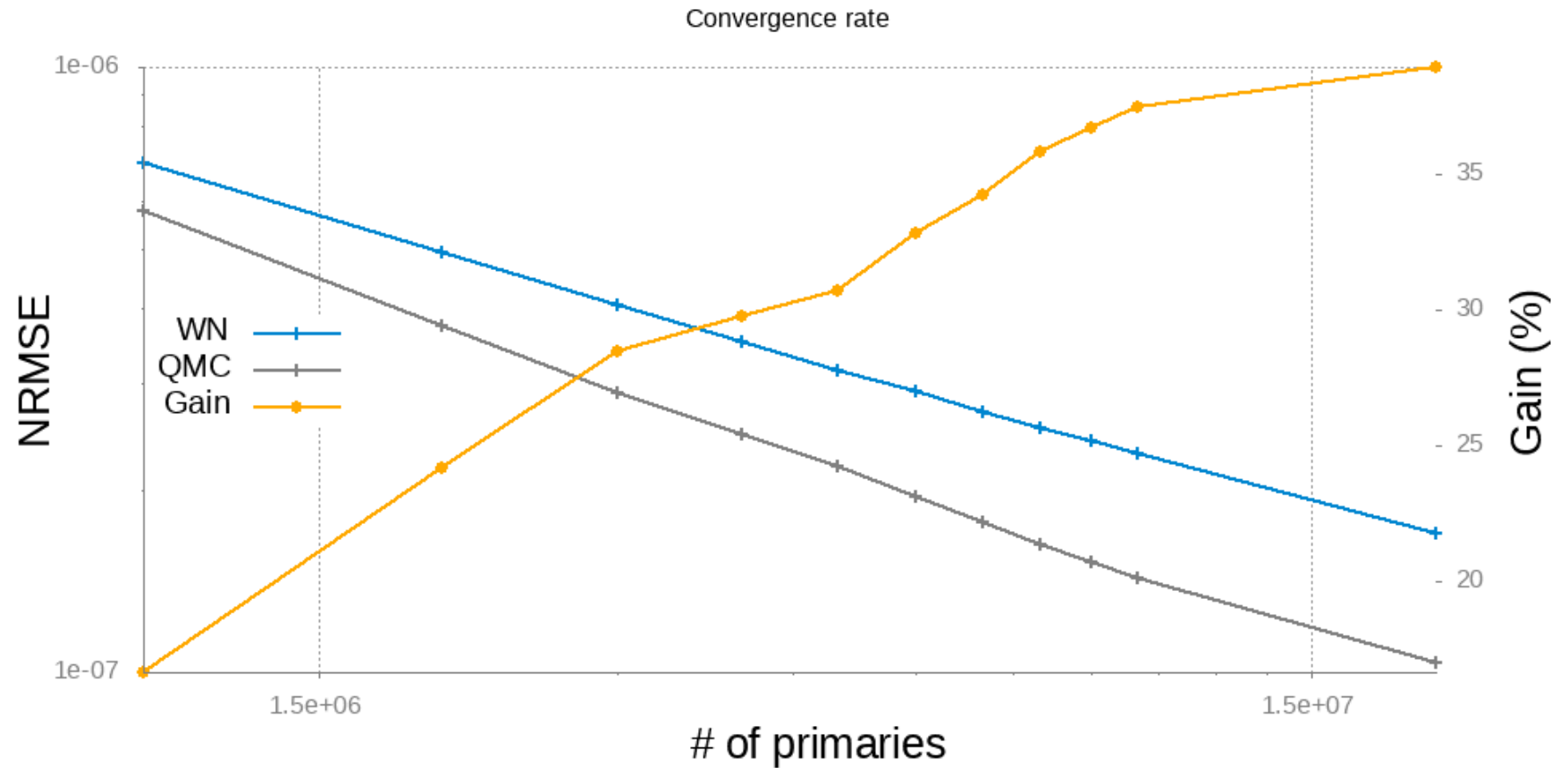
MC



QMC



$N = 2 \cdot 10^6$



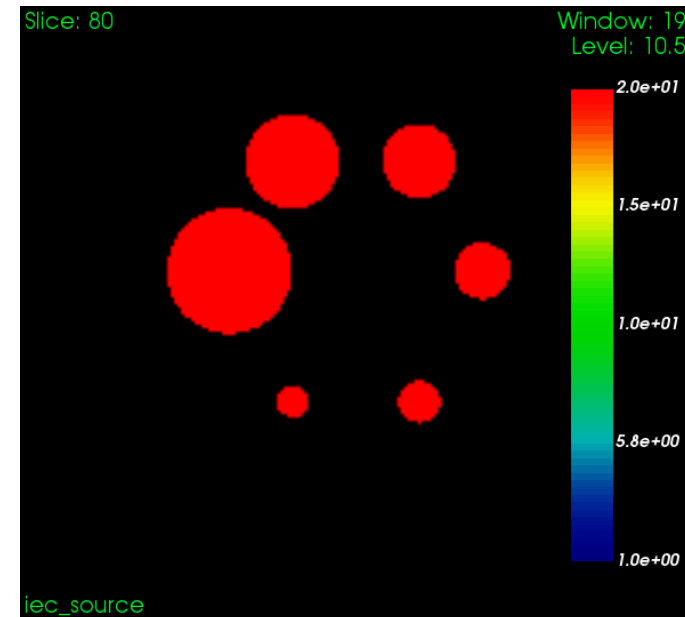
Experience 2

Source :

- 6 spheres
- gamma particles
- 140 keV
- source-to-background ratio : 20:1

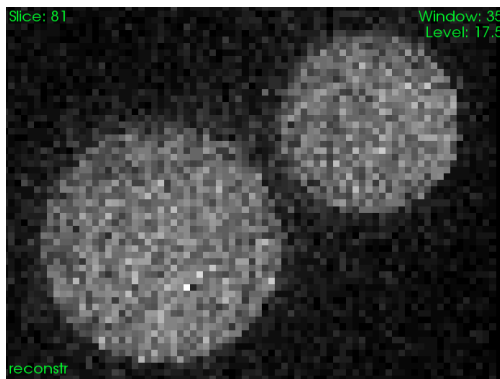
Medium : **Water** but Limited Physics List (only Compton)

Sampling : **23 QMC dimensions** (primary dimension
+ 1 Compton max)

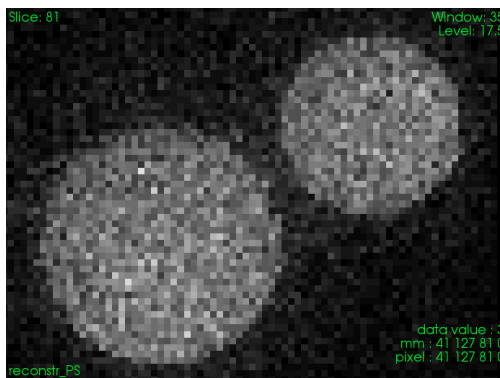


Experience 2

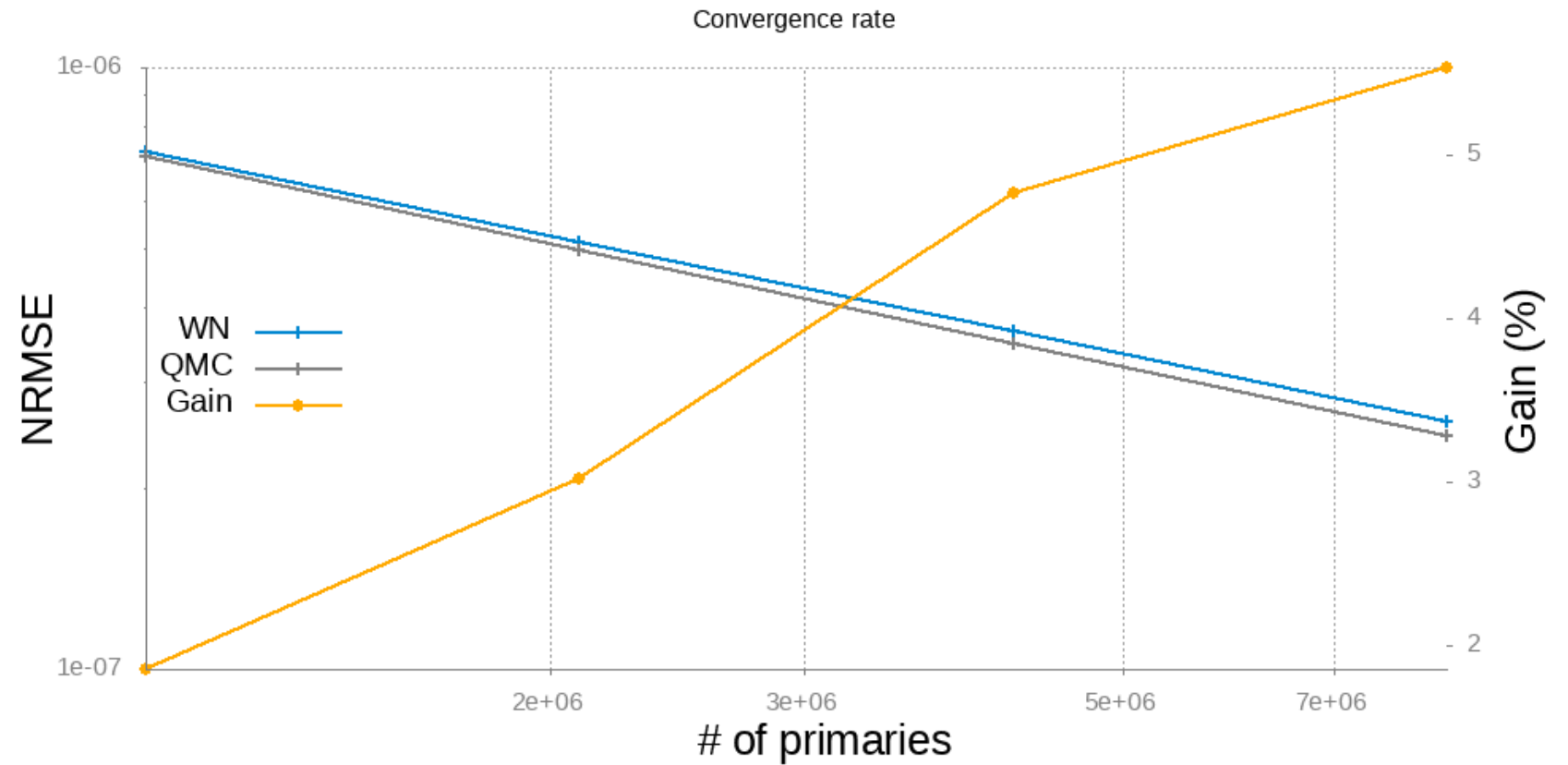
MC



QMC



$N \approx 4 \cdot 10^6$



Conclusion

Potential Advantages

- + QMC as G4RandomEngine
- + Variance Reduction Technique
- + Generalisable

Conclusion

Potential Advantages

- + QMC as G4RandomEngine
- + Variance Reduction Technique
- + Generalisable

Limitations

- Dependance to dimensions
- Prototype implementation (still slower)

Thanks

