

# Global Reconstruction Framework

**Strategy**

**Requirements**

**Kalman Filter**

**Reconstruction**

**Reconstruction Action**

**Conclusions**

# Strategy (i)

(adopted from FIRST)

• Backward approach:

1. Start from TW hits with atomic charge  $Z$ , assuming
  - a.  $A = Z \times 2$  (except for  $Z = 1$  thus  $A = 1$ )
  - b.  $E_c = E_{\text{beam}}/A$  (could be given by CAL)
2. Extrapolate to MSD, combine with a local track
3. Extrapolate to IT, search for closest cluster
4. Extrapolate to VTX, search for the closest track for a vertex matched with BM
5. Feed the Kalman filter and process
6. If good store candidate, else repeat 1a changing hypothesis

# Strategy (ii)

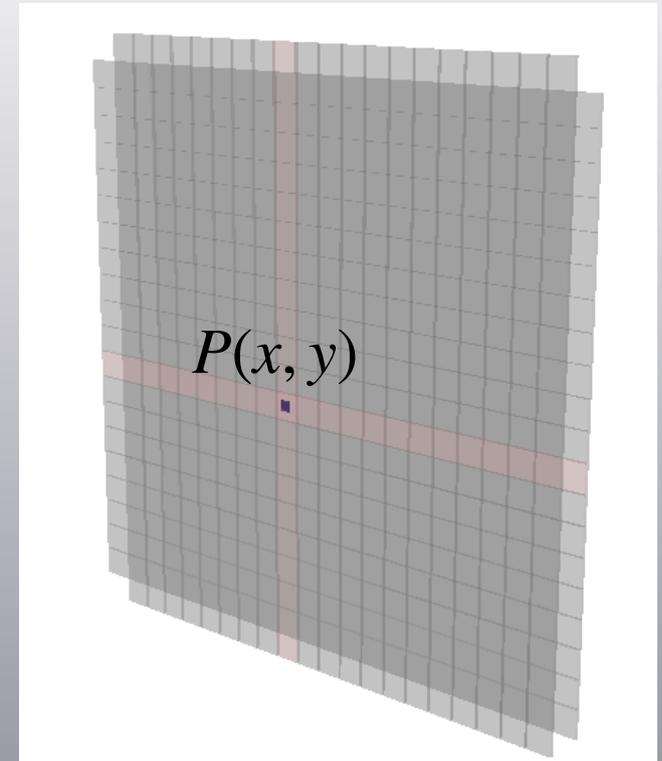
1. Start from TW hits with atomic charge  $Z$

$$P(x, y) = f(L_{bar}, v_{propa}, T_{left/right})^*$$

$$Z \propto \sqrt{\Delta E} \times \beta$$

$$\beta = \frac{L}{cToF} \text{ with } L = f(\vec{B}, A, Z)$$

➔ assumption L as straight line



(\*Done in TATWactNtuPoint class)

# Strategy (ii)

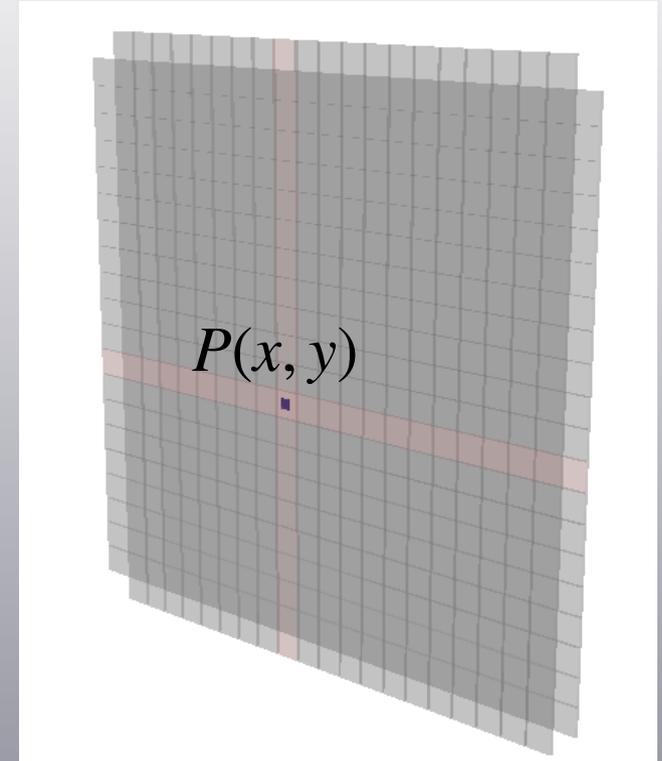
1. Start from TW hits with atomic charge  $Z$

$$P(x, y) = f(L_{bar}, v_{propa}, T_{left/right})^*$$

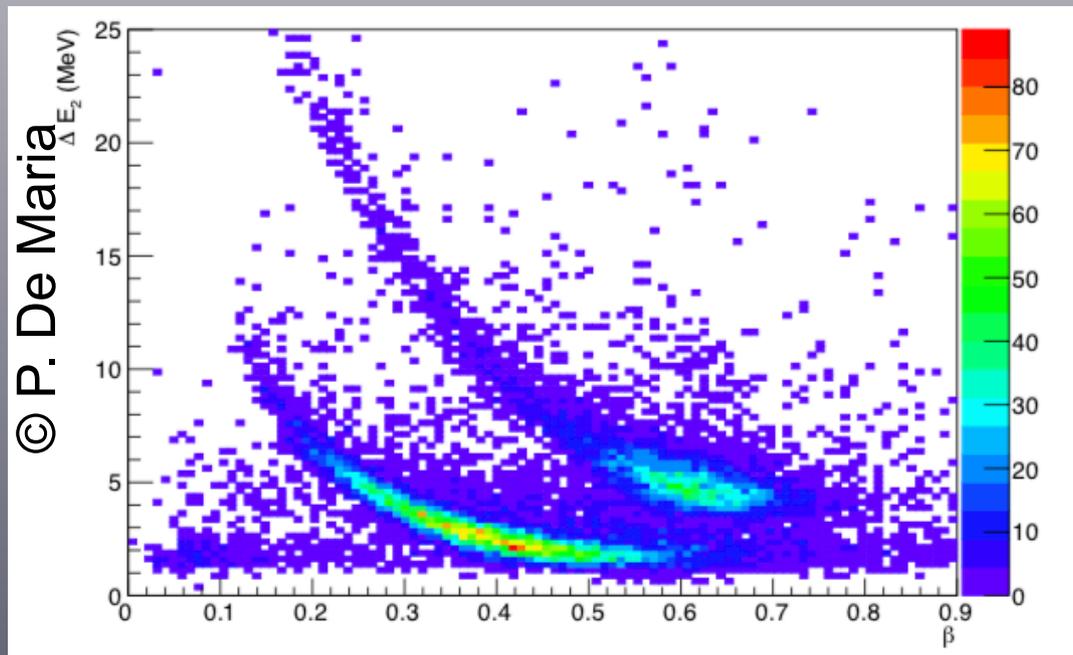
$$Z \propto \sqrt{\Delta E} \times \beta$$

$$\beta = \frac{L}{cToF} \text{ with } L = f(\vec{B}, A, Z)$$

➔ assumption L as straight line



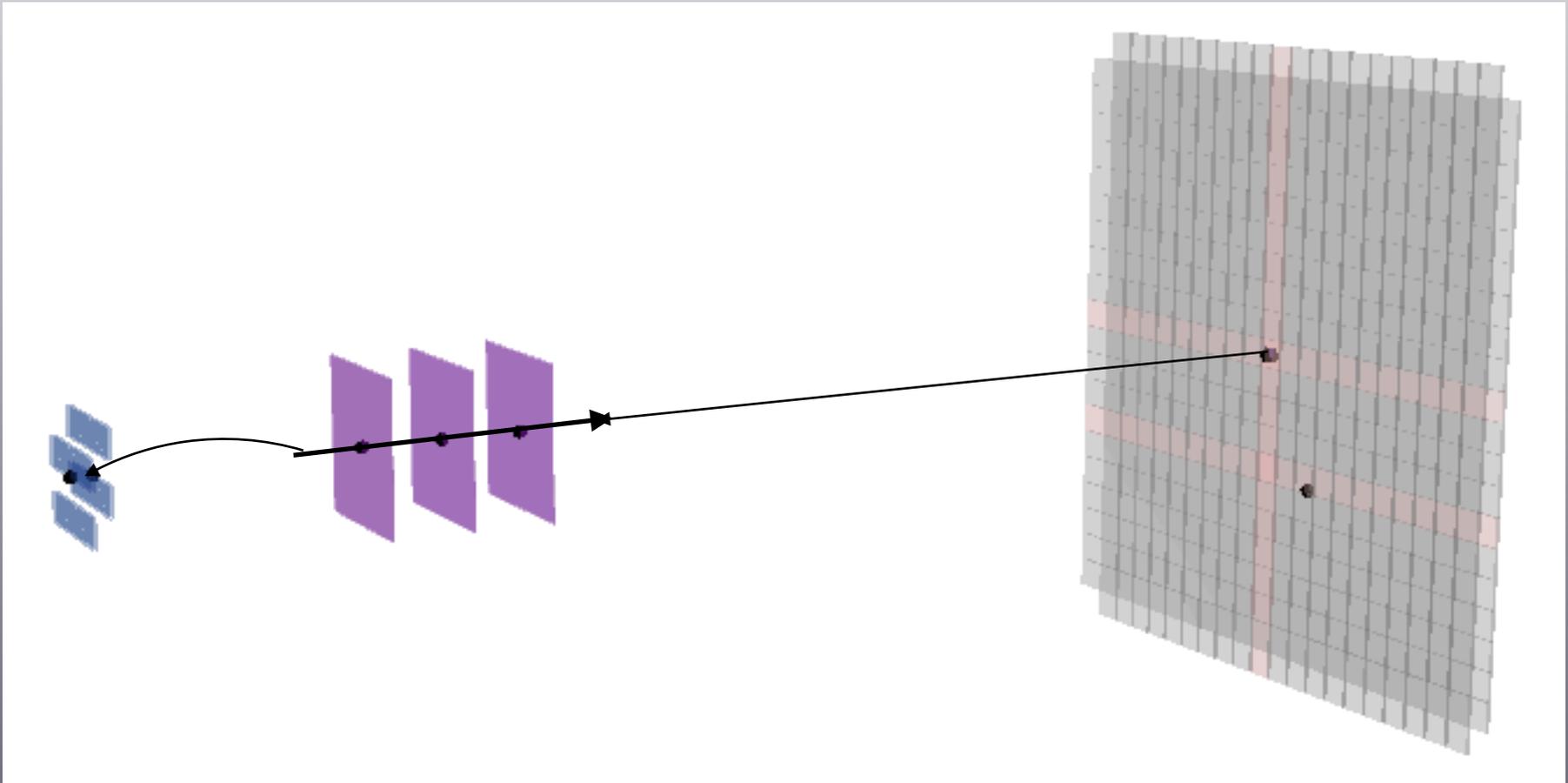
➔ Each line fits with a charge state



(\*Done in TATWactNtuPoint class)

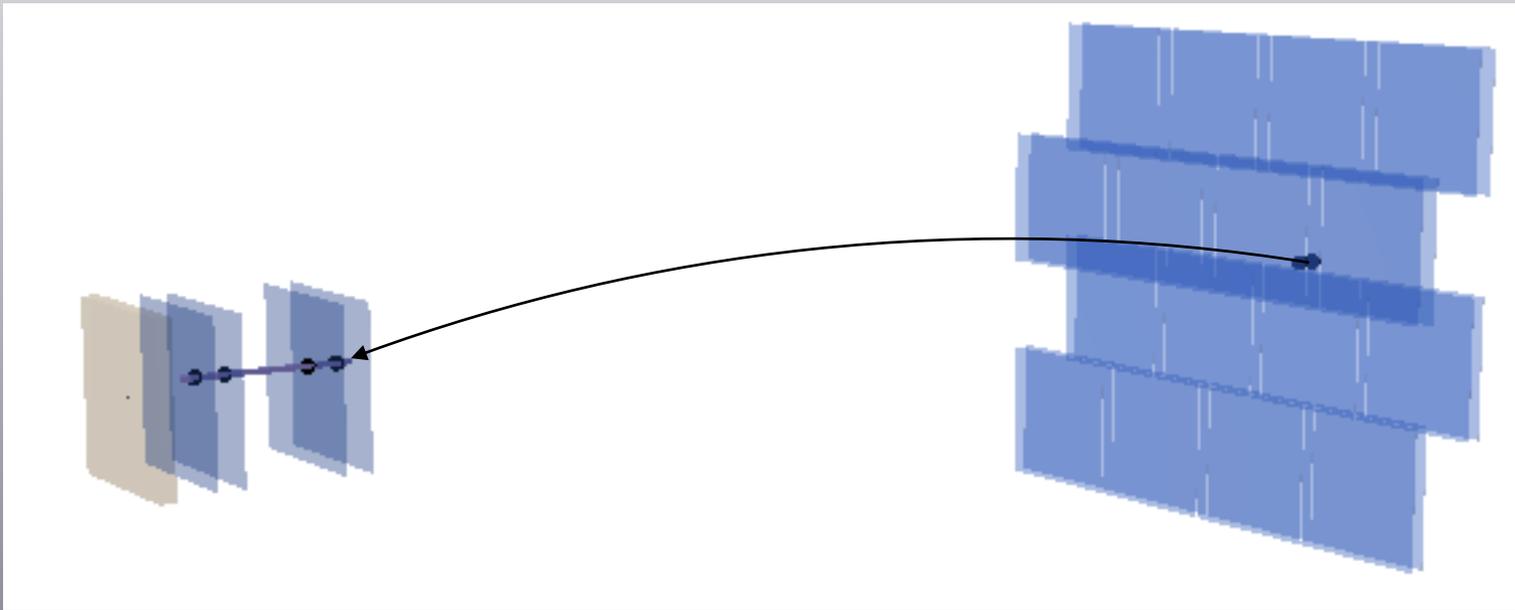
# Strategy (iii)

2. Extrapolate to MSD, combine with a local track (no field)
3. Extrapolate to IT, search for closest cluster (propagation in field)



# Strategy (iv)

4. Extrapolate to VTX, search for the closest track for a vertex matched with BM (Propagation in Field)



5. Feed the Kalman filter and process
6. If good store candidate, else repeat 1a changing hypothesis

# Requirements

BM:

- Tracking: ✓

VTX:

- Vertexing: ✓

IT:

- Clustering: ✓

MSD:

- 1D Clustering: ✓
- 2D Clustering/Tracking: ✗

TW:

- Point reconstruction: ✓
- Atomic charge reconstruction: ✗

CAL:

- Kinetic energy reconstruction: ✗

Digitizer:

- ST+BM+VTX+IT: ✓
- MSD+TW+CAL: need more work

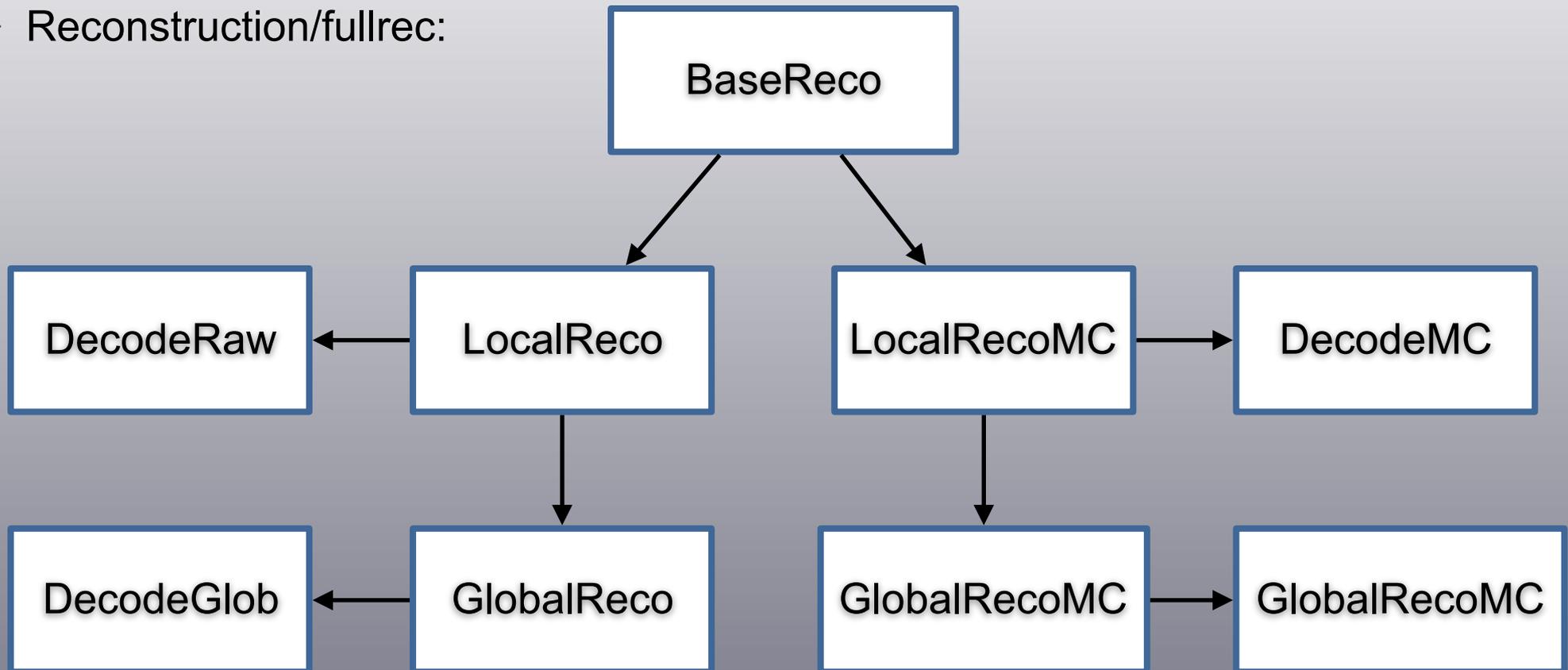
Rem: MC track index propagated from hits to tracks  
when cluster/track exits

# Kalman Filter

- GenFit: heavy package, need a simplified approach for better control
- ➔ Development of a new global reconstruction TOE (Tracking Of Ejectile):
  - new Kalman filter (UKF): under development
  - new propagator (RK5-6): done
  - test with “scholar” data: ongoing

# Global reconstruction (new framework)

• Reconstruction/fullrec:



- Global reconstruction inherits from local reconstruction
- Dedicated actions for global reconstruction

# Global reconstruction (i)

→ BaseReco: change name of base class

```
//  
void BaseReco::AddRecRequiredItem()  
{ ...  
  
    if (GlobalPar::GetPar()->IncludeKalman())  
        gTAGroot->AddRequiredItem("glbActTrack");  
}  
...  
  
//  
void BaseReco::CreateRecActionGlb()  
{  
    if(fFlagTrack) {  
        fpNtuGlbTrack = new TAGdataDsc("glbTrack", new TAGntuGlbTrack());  
        fActGlbTrack = new TAGactNtuGlbTrack("glbActTrack", fpNtuVtx, fpNtuClusIt, fpNtuClusMsd,  
                                             fpNtuRecTw, fpNtuGlbTrack, fpParGeoDi,  
                                             fpParGeoVtx, fpParGeoIt, fpParGeoMsd, fpParGeoTw);  
  
        if (fFlagHisto)  
            fActGlbTrack->CreateHistogram();  
    }  
}
```

- Add dedicated classes for global reconstruction
  - ➔ TAGntuGlbTrack: global track container
  - ➔ TAGactNtuGlbTrack: global tracking action

# Global reconstruction (ii)

→ GlobalReco:

```
class GlobalReco : public LocalReco
{
public:
    ///! default constructor
    GlobalReco(TString expName, TString fileNameIn = "", TString fileNameout = "");

    virtual ~GlobalReco();

    ClassDef(GlobalReco, 0);
};
```

```
class GlobalRecoMC : public LocalRecoMC
{
public:
    ///! default constructor
    GlobalRecoMC(TString expName, TString fileNameIn = "", TString fileNameout = "");

    virtual ~GlobalRecoMC();

    ClassDef(GlobalRecoMC, 0);
};
```

- Virtual interface for executables, should NOT be modified
- WARNING: for local reconstruction, *IncludeKalman* must be off in FootGlobal.par

# Global reconstruction (iii)

• Executable: DecodeGlob(MC)

```
int main (int argc, char *argv[]) {  
  
    TString in("");  
    TString exp("");  
  
    Int_t pos = in.Last('.');  
    TString out = in(0, pos);  
    out.Append("_Out.root");  
  
    Bool_t ntu = false;  
    Bool_t his = false;  
    Bool_t hit = false;  
    Bool_t trk = false;  
    Int_t nTotEv = 1e7;  
  
    for (int i = 0; i < argc; i++){  
        if(strcmp(argv[i],"-out") == 0) { out =TString(argv[++i]); } // Raw file name for output  
        if(strcmp(argv[i],"-in") == 0) { in = TString(argv[++i]); } // Root file in input  
        if(strcmp(argv[i],"-exp") == 0) { exp = TString(argv[++i]); } // extention for config/geomap files  
        if(strcmp(argv[i],"-nev") == 0) { nTotEv = atoi(argv[++i]); } // Number of events to be analyzed  
        if(strcmp(argv[i],"-ntu") == 0) { ntu = true; } // enable tree filling  
        if(strcmp(argv[i],"-his") == 0) { his = true; } // enable histograming  
        if(strcmp(argv[i],"-hit") == 0) { hit = true; } // enable hits saving  
        if(strcmp(argv[i],"-trk") == 0) { trk = true; } // enable tracking action  
        if(strcmp(argv[i],"-help") == 0) {  
            cout<<" Decoder help:"<<endl;  
            cout<<" Ex: Decoder [opts] "<<endl;  
            cout<<" possible opts are:"<<endl;  
            cout<<" -in path/file : [def=""] raw input file"<<endl;  
            cout<<" -out path/file : [def=*_Out.root] Root output file"<<endl;  
            cout<<" -nev value : [def=10^7] Numbers of events to process"<<endl;  
            cout<<" -exp name : [def=""] experient name for config/geomap extention"<<endl;  
            cout<<" -trk : enable tracking actions"<<endl;  
            cout<<" -hit : enable saving hits in tree (activated ntu option)"<<endl;  
            cout<<" -ntu : enable tree filling"<<endl;  
            cout<<" -his : enable crtl histograming"<<endl;  
            return 1;  
        }  
    }  
}
```

# Global reconstruction (iii)

## Executable: DecodeGlob

```
TApplication::CreateApplication();

GlobalPar::Instance();
GlobalPar::GetPar()->Print();
GlobalReco* glbRec = new GlobalReco(exp, in, out);

// global setting
if (ntu)
    glbRec->EnableTree();
if (his)
    glbRec->EnableHisto();
if (hit) {
    glbRec->EnableTree();
    glbRec->EnableSaveHits();
}
if (trk) {
    glbRec->EnableTracking();
}
TStopwatch watch;
watch.Start();

glbRec->BeforeEventLoop();
glbRec->LoopEvent(nTotEv);
glbRec->AfterEventLoop();

watch.Print();
}
```

# MC Global reconstruction (iii)

• Executable: DecodeGlobMC

```
TApplication::CreateApplication();

GlobalPar::Instance();
GlobalPar::GetPar()->Print();
GlobalRecoMC* glbRec = new GlobalRecoMC(exp, in, out); // <- only change

// global setting
if (ntu)
    glbRec->EnableTree();
if (his)
    glbRec->EnableHisto();
if (hit) {
    glbRec->EnableTree();
    glbRec->EnableSaveHits();
}
if (trk) {
    glbRec->EnableTracking();
}
TStopwatch watch;
watch.Start();

glbRec->BeforeEventLoop();
glbRec->LoopEvent(nTotEv);
glbRec->AfterEventLoop();

watch.Print();
}
```



# Global Reconstruction Action (ii)

→ TAGpoint:

```
class TAGpoint : public TAGobject {
private:
    TVector3    fPosition;        // position in FOOT framework
    TVector3    fPosError;       // position error in FOOT framework
    Double32_t  fTime;           // Time information
    Double32_t  fChargeZ;        // Charge Z
    Double32_t  fChargeProbaZ;   // Probability of charge Z
public:
    TAGpoint();
    TAGpoint(TVector3 pos, TVector3 posErr, Double_t time, Double_t chargeZ, Double_t probaZ);
    ~TAGpoint() {};

    // All the Get methods
    TVector3    GetPosition()      const { return fPosition;    }
    TVector3    GetPosError()     const { return fPosError;    }
    Double32_t  GetTime()         const { return fTime;        }
    Int_t       GetChargeZ()      const { return fChargeZ;     }
    Double32_t  GetChargeProbaZ() const { return fChargeZ;     }

    void        SetTime(Double_t time) { fTime = time;        }
    void        SetPosition(TVector3 pos) { fPosition = pos;    }
    void        SetPosError(TVector3 pos) { fPosError = pos;    }
    void        SetChargeZ(Int_t z) { fChargeZ = z;          }
    void        SetChargeProbaZ(Double_t z) { fChargeProbaZ = z; }

    void        Clear(Option_t* opt);

    ClassDef(TAGpoint,1)
};
```

# Global Reconstruction Action (iii)

## Vertex tracks:

```
class TAVTbaseTrack : public TAGobject {  
  
protected:  
    TVector3*      fOrigin;           //->  origin x0,y0,z0  
    TVector3*      fSlope;           //->  the slope (dx/dz, dy/dz, 1)  
    Float_t        fLength;  
  
    Bool_t         fPileup;          // true if track is part of pileup events  
    UInt_t         fType;            // 0 for straight, 1 inclined, 2 for bent  
    Int_t          fTrackNumber;     // number of the track  
    TClonesArray*  fListOfClusters;  // list of cluster associated to the track  
  
    Float_t        fChiSquare;       // chisquare/ndf of track fit in 2D  
    Float_t        fChiSquareU;     // chisquare/ndf of track fit, U dim  
    Float_t        fChiSquareV;     // chisquare/ndf of track fit, V dim  
    Float_t        fVertexZ;        // vertex z-position  
    Int_t          fValidity;        // if = 1 track attached to vertex  
  
    TArrayF*       fChargeProba;     //!< charge probability array  
    Int_t          fChargeWithMaxProba; //!< charge with maximum probability  
    Float_t        fChargeMaxProba;  //!< charge maximum probability  
    TArrayF*       fChargeProbaNorm; //!< charge probability array for normalized charge  
    Int_t          fChargeWithMaxProbaNorm; //!< charge with maximum probability for normalized charge  
    Float_t        fChargeMaxProbaNorm; //!< charge maximum probability for normalized charge  
  
    ...  
}
```

- Possibility to have information about atomic charge Z (TAVTparCal)
- Need a calibration run

# Global Reconstruction Action (iv)

• Time of Flight point:

```
class TATWpoint : public TAGobject {  
private:  
    TVector3    m_position;    // position in detector framework  
    int        m_column;      // column number  
    int        m_row;        // row number  
  
    TATWntuHit* m_columnHit;   // hit col  
    TATWntuHit* m_rowHit;     // hit row  
  
    Double32_t m_de1;         // energy loss in the scintillator bars layer 1  
    Double32_t m_de2;         // energy loss in the scintillator bars layer 2  
    Double32_t m_time;        // for the moment I take the column time  
  
    int        m_chargeZ;     // raw guess of charge Z  
    Double32_t m_chargeZProba; // raw guess of charge Z probability  
    ...  
};
```

- We NEED a atomic charge identification in TW within a magnetic field: (Marco)

# Global Reconstruction Action (v)

## → TAGactNtuGlbTrack: action (i)

```
class TAGactNtuGlbTrack : public TAGaction {
public:

    explicit TAGactNtuGlbTrack(const char* name          = 0, TAGdataDsc* p_vtxtrack = 0,
                               TAGdataDsc* p_itrclus    = 0, TAGdataDsc* p_msdcclus  = 0,
                               TAGdataDsc* p_twpoint    = 0, TAGdataDsc* p_glbtrack  = 0,
                               TAGparaDsc* p_geodi      = 0, TAGparaDsc* p_geoVtx   = 0,
                               TAGparaDsc* p_geoItr     = 0, TAGparaDsc* p_geoMsd   = 0,
                               TAGparaDsc* p_geoTof     = 0);

    virtual ~TAGactNtuGlbTrack();

    //! Action
    Bool_t   Action();
    //! Base creation of histogram
    void     CreateHistogram();
    //! Set up branches
    void     SetupBranches();
    //! Open File
    void     Open(TString name);
    //! Close File
    void     Close();
};
```

- Possibility to read back TTree (fgStdAloneFlag option)
- ➔ If needed, another global action could be implemented (with a switch in GlobalPar)



# Global Reconstruction Action (vii)

→ TAGntuGlbTrack: container

```
class TAGntuGlbTrack : public TAGdata {
private:
    TClonesArray*    fListOfTracks;    // tracks

private:
    static TString fgkBranchName;    // Branch name in TTree

public:
    TAGntuGlbTrack();
    virtual ~TAGntuGlbTrack();

    TAGtrack*       GetTrack(Int_t i);
    const TAGtrack* GetTrack(Int_t i) const;
    Int_t           GetTracksN()      const;

    TClonesArray*   GetListOfTracks() { return fListOfTracks; }

    TAGtrack*       NewTrack();
    TAGtrack*       NewTrack(Double_t mass, Double_t mom, Double_t charge, Double_t tof,
                             Double_t energy, Int_t id, Int_t trkID);
    TAGtrack*       NewTrack(TAGtrack& track);
    . . .
public:
    static const Char_t* GetBranchName() { return fgkBranchName.Data(); }

    ClassDef(TAGntuGlbTrack,2)
};
```

- Class adopted from FIRST

# Global Reconstruction Action (viii)

## → TAGtrack:

```
class TAGtrack : public TAGobject {  
  
public:  
  
    TAGtrack();  
    TAGtrack(Double_t mass, Double_t mom, Double_t charge, Double_t tof, Double_t energy, Int_t id,  
Int_t trkID);  
  
private:  
    Double32_t      fMass;  
    Double32_t      fMom;  
    Double32_t      fCharge;  
    Double32_t      fTof;  
    Double32_t      fEnergy;  
    Int_t           fId;  
    Int_t           fTrkID;  
  
    //Particle directions and positions computed on Target  
    TVector3        fTgtDir;  
    TVector3        fTgtPos;  
  
    //Particle directions and positions computed on ToF Wall  
    TVector3        fTofPos;  
    TVector3        fTofDir;  
  
    TClonesArray*   fListOfPoints;        // Attached points  
  
    ClassDef(TAGtrack,1)  
};
```

- Class adopted from FIRST

# Strategy (ia)

(adopted from FIRST)

• Foreward approach:

1. Start from VTX track and a point detected in TW with atomic charge  $Z$ , assuming
  - a.  $A = Z \times 2$  (except for  $Z = 1$  thus  $A = 1$ )
  - b.  $E_c = E_{\text{beam}}/A$
2. Extrapolate to IT, search for closest cluster, if not go back to 1, changing VTX track
3. Extrapolate to MSD, combine with a local track
4. Extrapolate to TW, search for the closest point
5. Process the Kalman filter
6. Using next hit in TW with atomic charge  $Z'$ , go to 1

# Conclusions

- New framework for Global reconstruction relying on local reconstruction
  - Strategy relies on FIRST experiment with given requirements  
Urgent: need Z identification in TW (Marco) and tracks in MSD (Gianluigi ?)
  - New Kalman filter
- ➡ Start to study a “real” global reconstruction efficiency