

Pixel chamber: a silicon heavy-flavour imager with monolithic active pixel sensors for measurements of charm and beauty with unprecedented precision

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Mini symposium HEP

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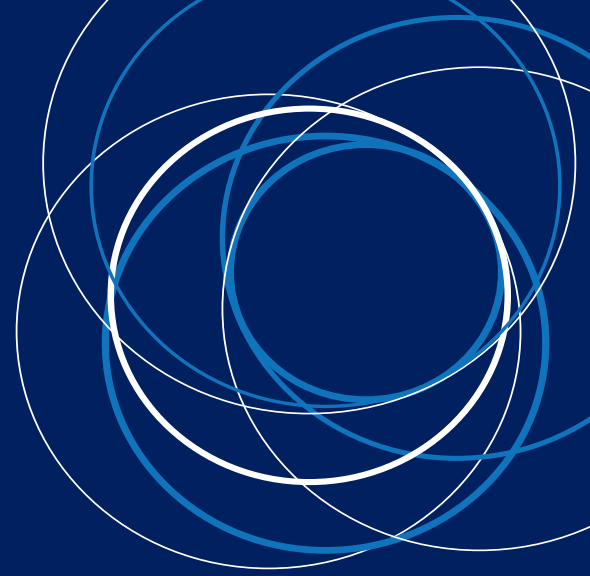


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Summary

- Introduction
- Geant4 simulation
- Track and vertex finding and fitting
- Future developments



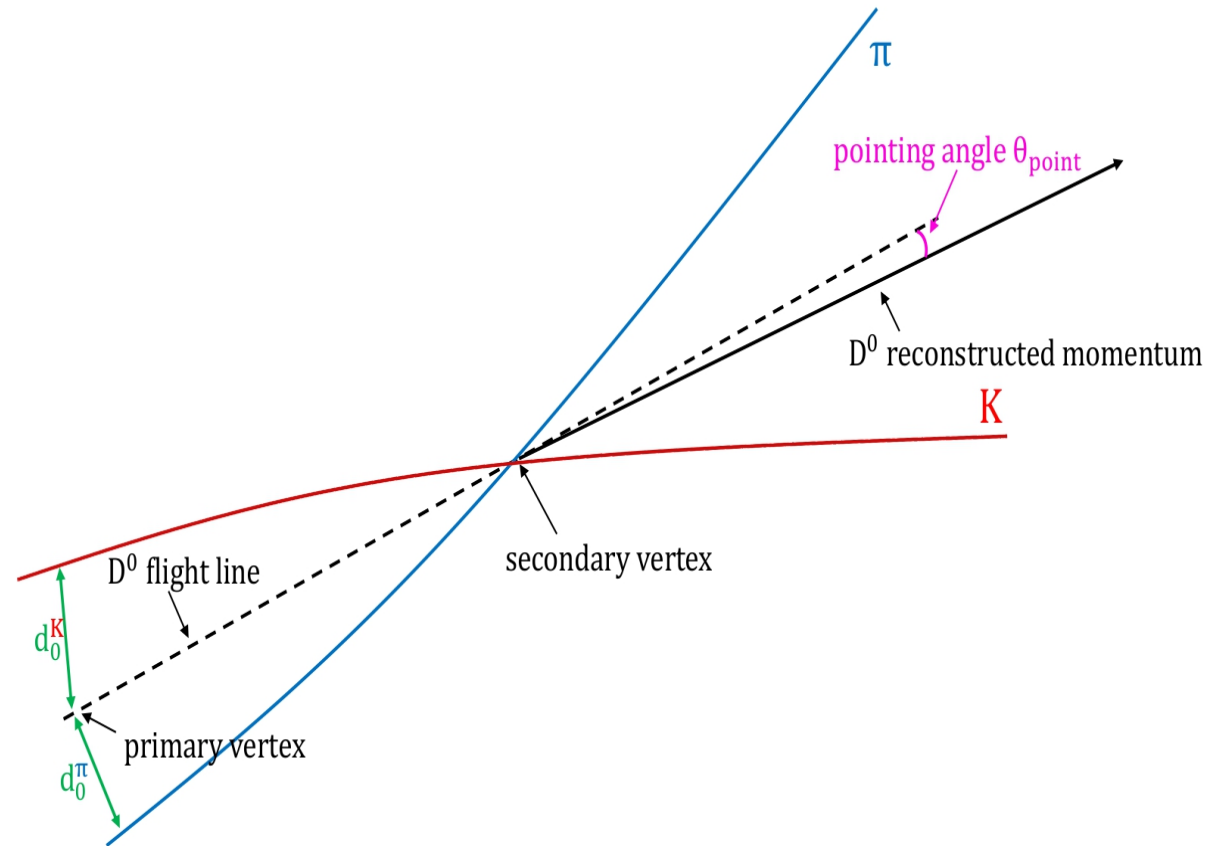
Charm and beauty

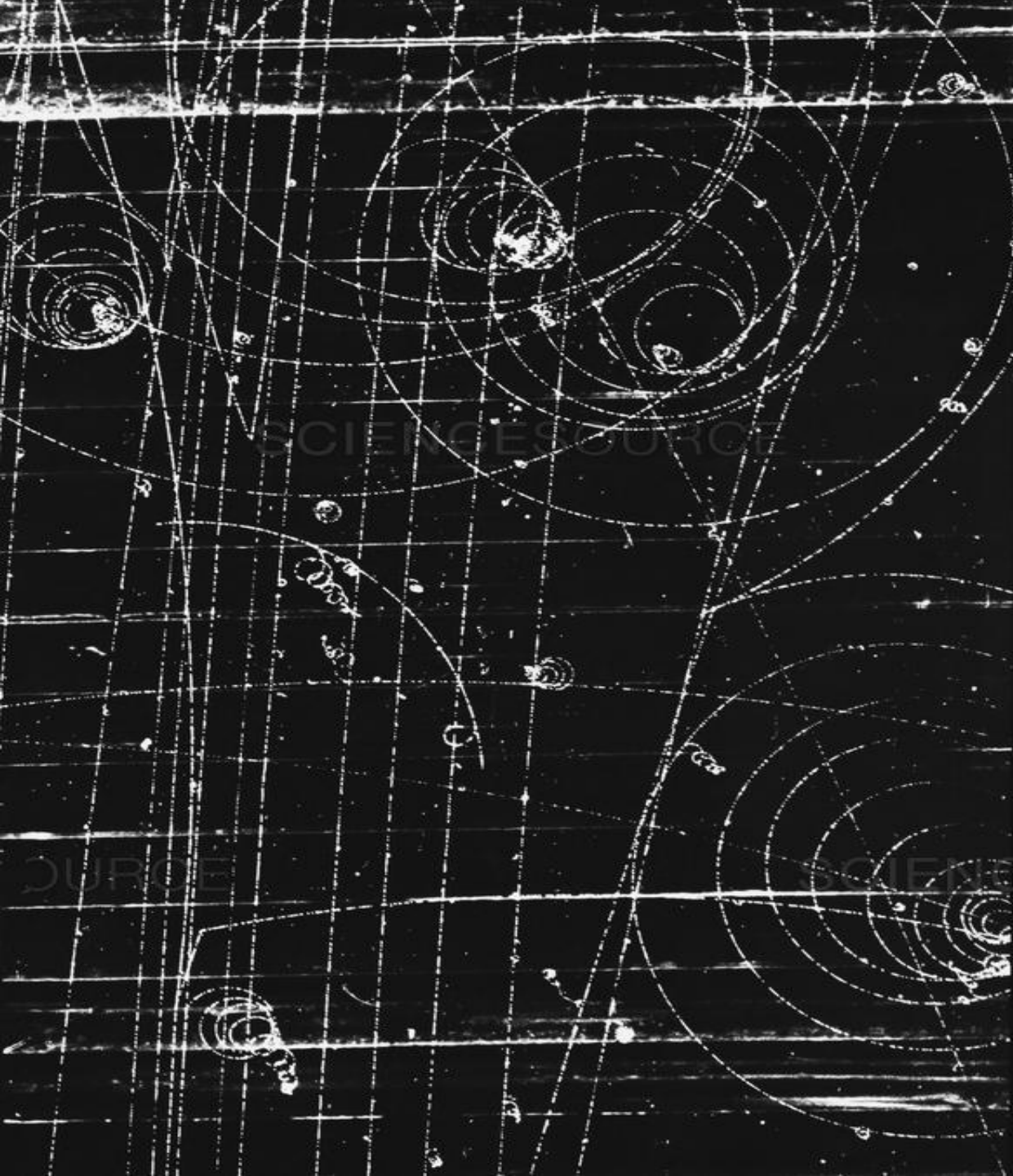
- Long lifetime→can travel distances from $O(10-100 \mu m)$ up to mm before decay

Ideal Detectors

- As close as possible to production point
- Precision tracking: great spatial resolution to separate primary from secondary vertices

$$D^0 \rightarrow K^- + \pi^+$$
$$c\tau(D^0) = 122.9 \mu m$$



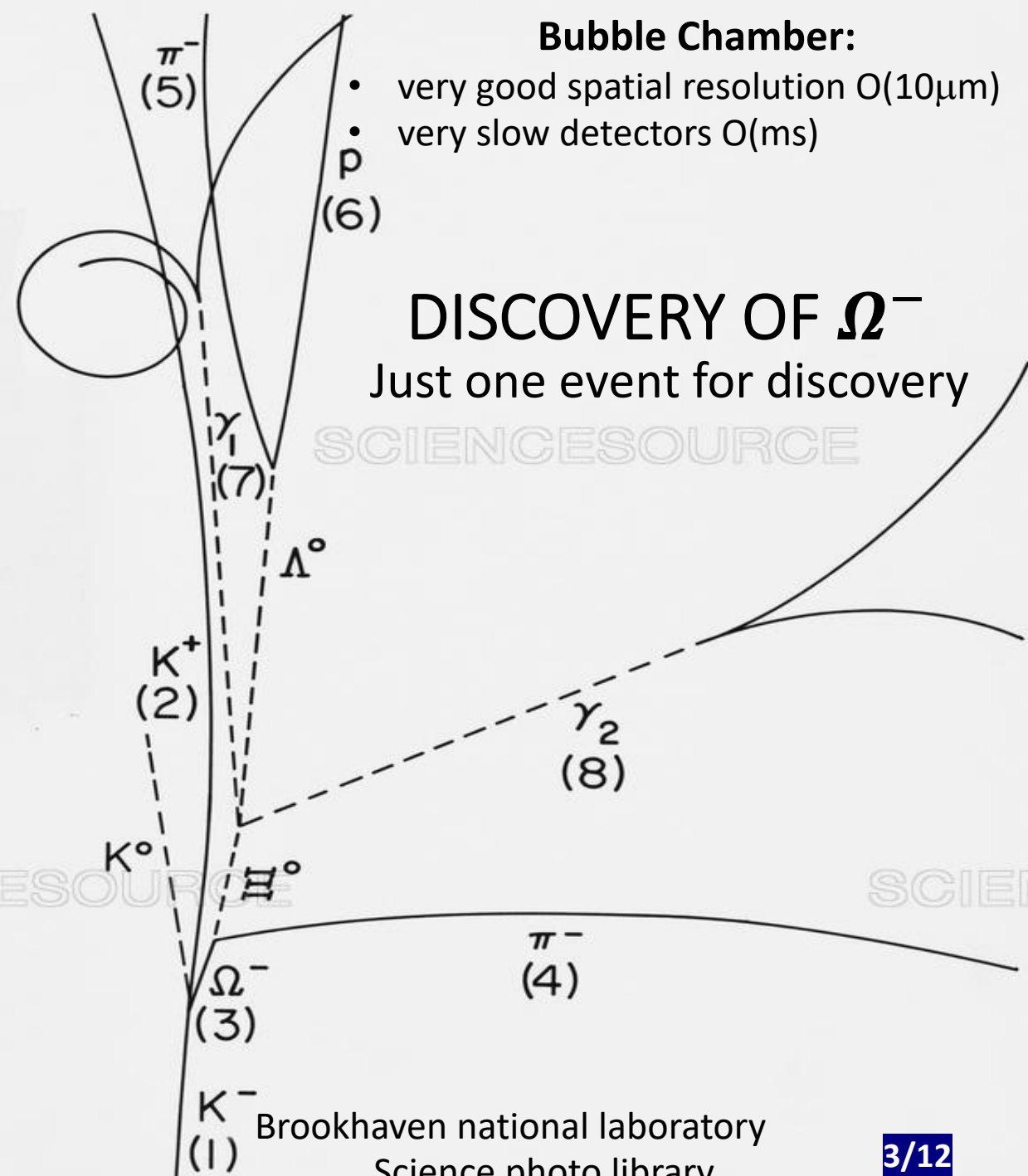


Bubble Chamber:

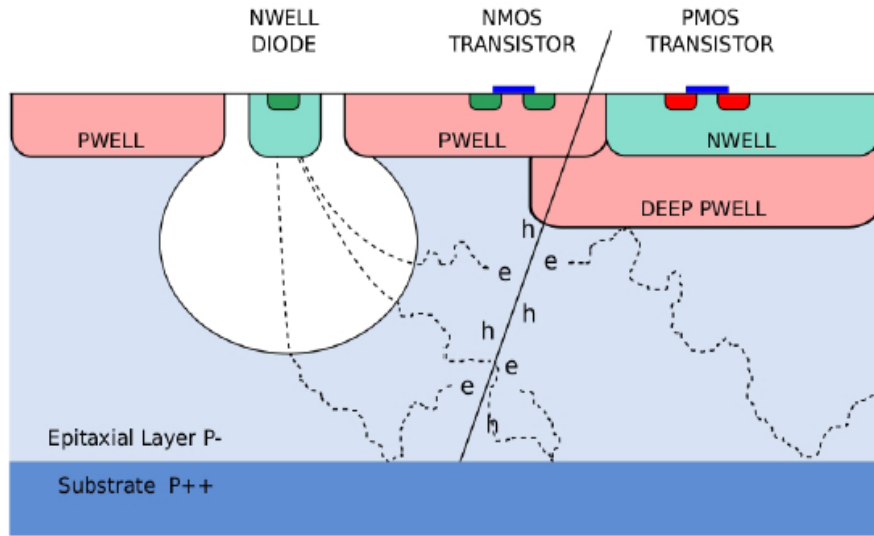
- very good spatial resolution $O(10\mu\text{m})$
- very slow detectors $O(\text{ms})$

DISCOVERY OF Ω^-

Just one event for discovery



Very high resolution silicon pixel detectors: Monolithic sensors



Silicon pixel detectors:

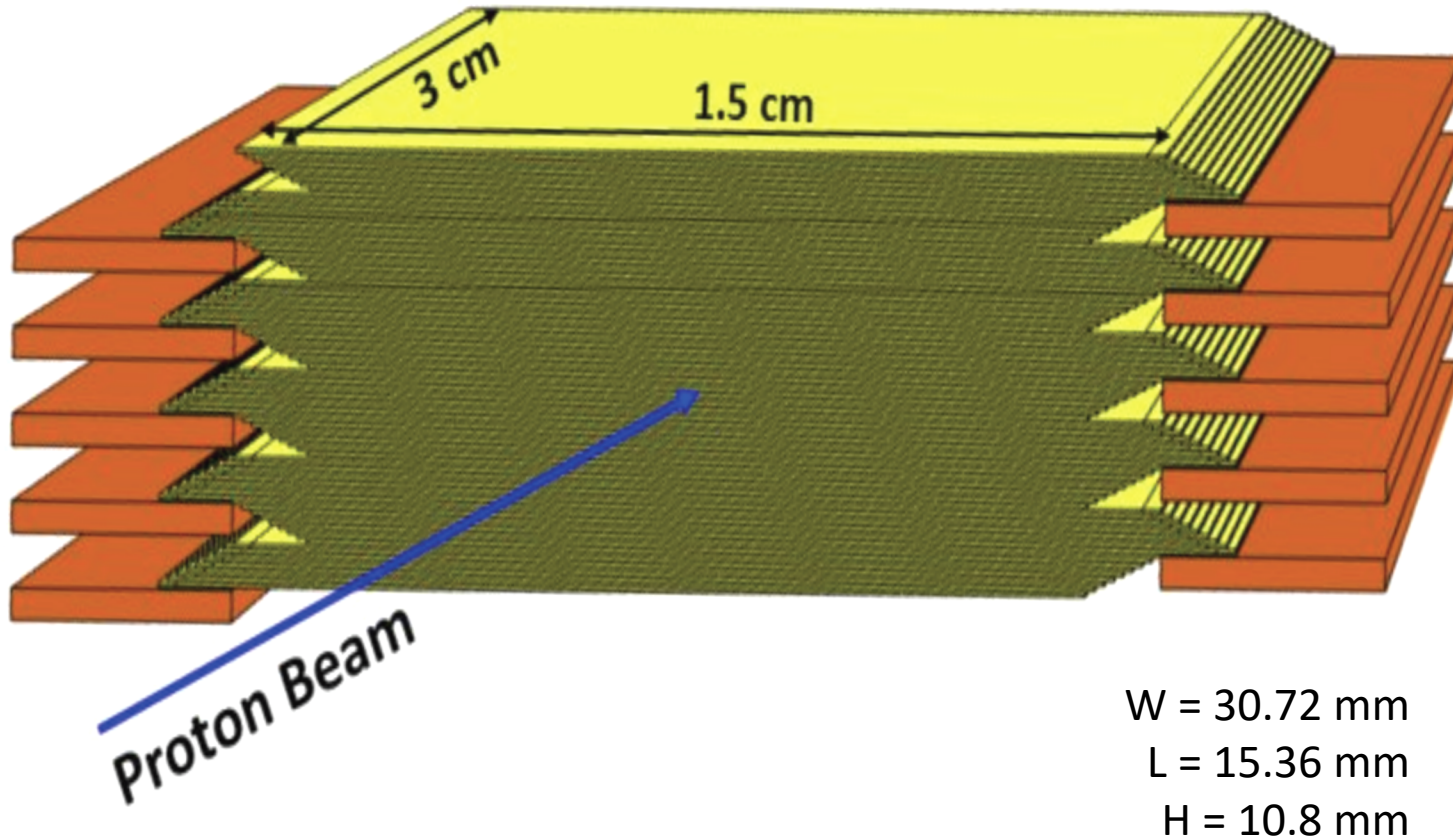
- Reverse biased used to detect a charge particle
- In monolithic pixels the readout electronic is implemented inside the pixel itself

The ALPIDE monolithic sensor (ALICE experiment):

- Most granular and high resolution sensor ever done for high energy physics experiments
- Pixel area $30 \times 30 \mu\text{m}^2$
- Matrix of 1024×512 pixels ($3 \times 1.5 \text{ cm}^2$)
- Material budget: $50 \mu\text{m}$ silicon



Interaction inside the chamber



Project funded by RAS (110 keuro):

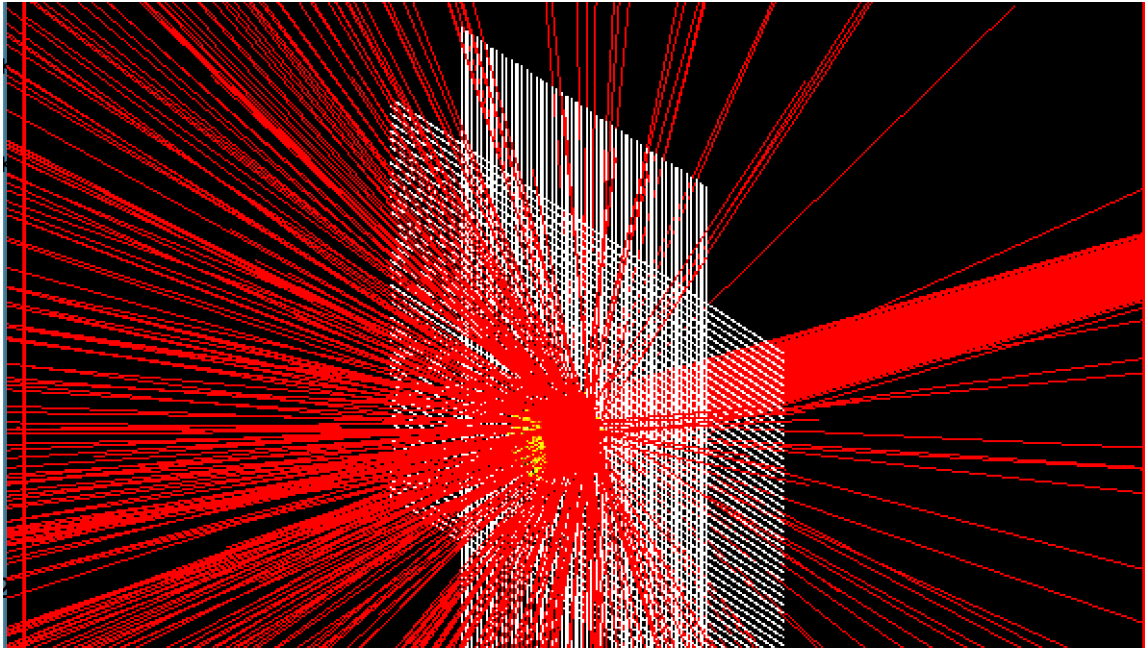
G. Usai, P. Bhattacharya, S. Siddhanta, D. Marras, E. Casula,
M. Arba, M. Tuveri, A. Masoni, A. Mulliri

Pixel Chamber

Idea:

- stack of several ALPIDE chips
- 3D volume of pixels
- solid state bubble chamber
 - active target
 - performs continuous tracking with very high precision $\sim 5\mu\text{m}$ spatial resolution

Step1: simulation

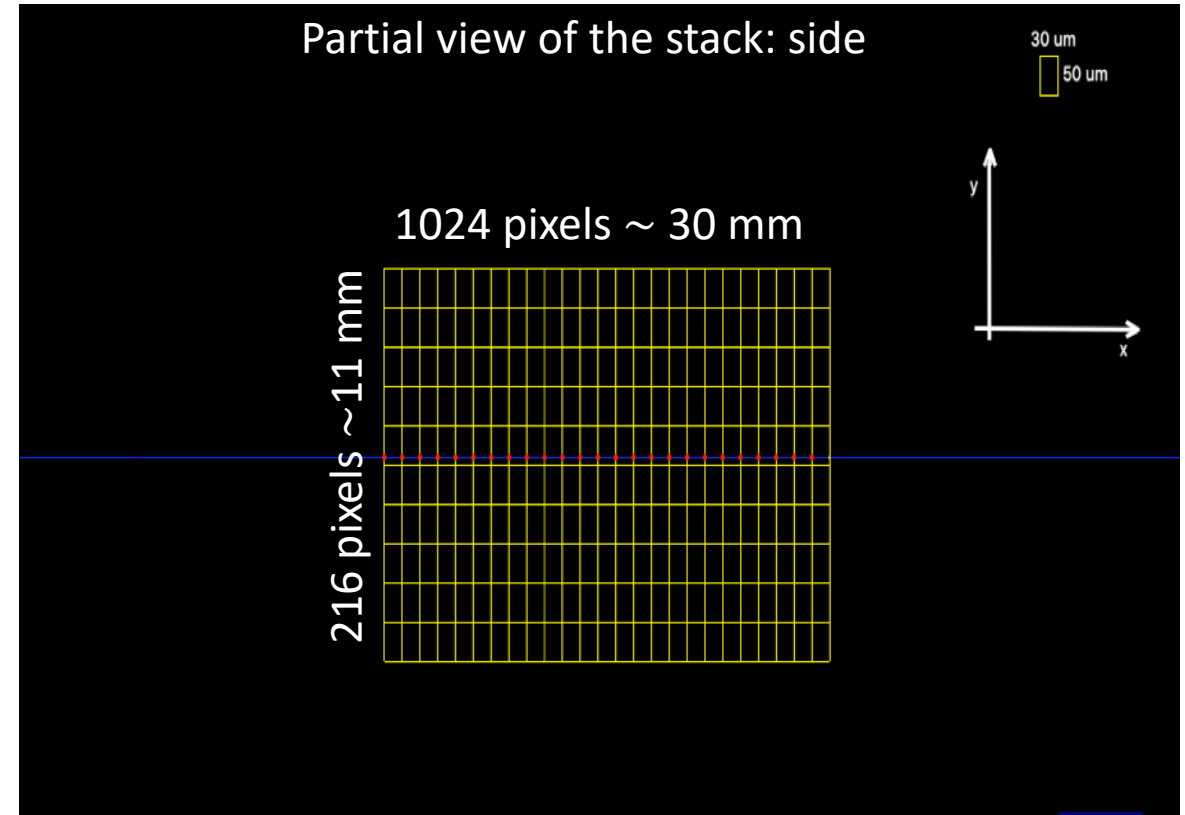
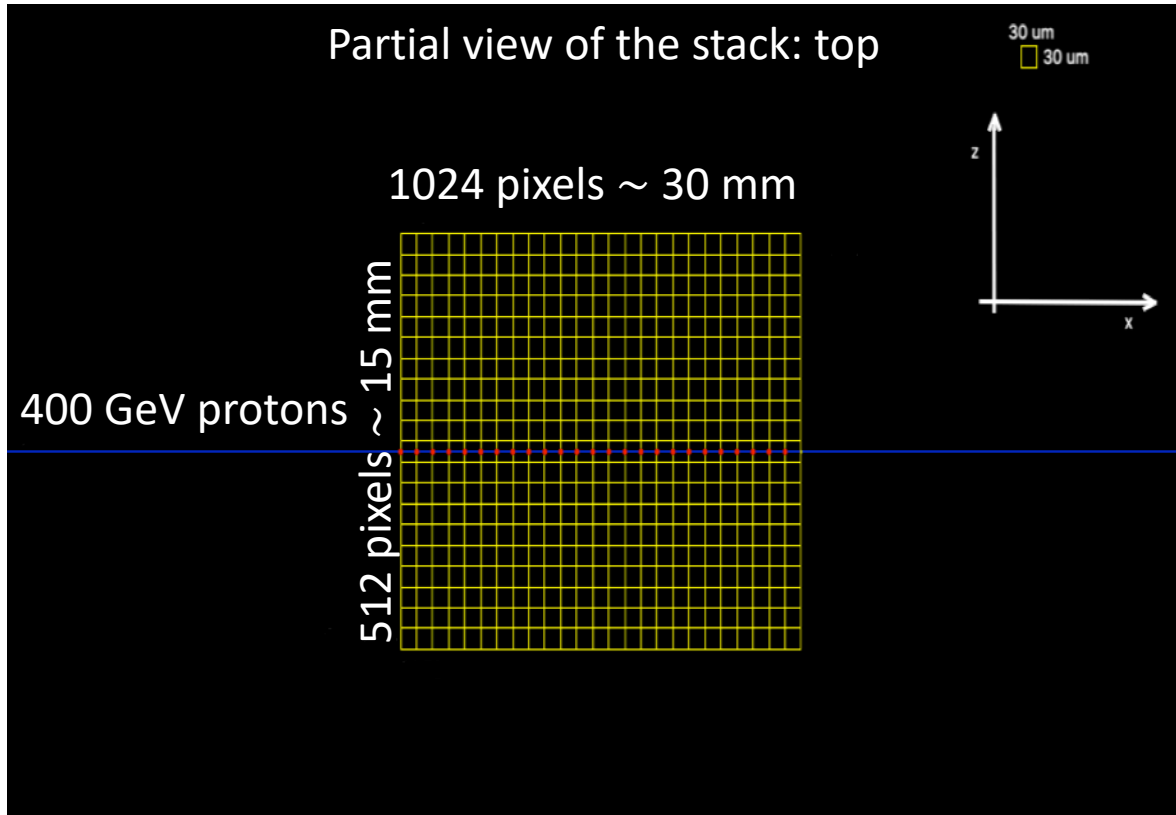


GEANT4
A SIMULATION TOOLKIT

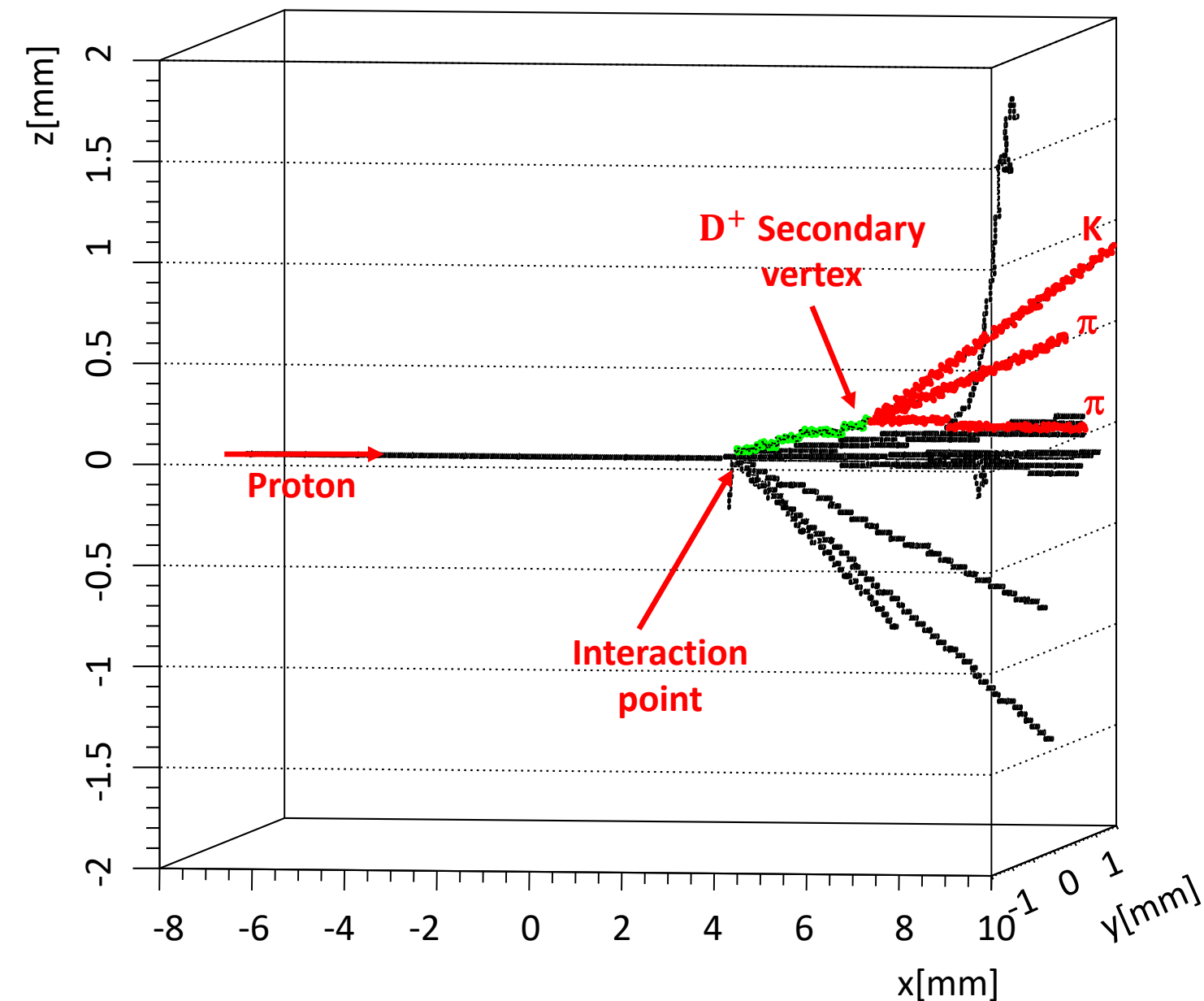
Pixel chamber in Geant4

- Simulation of a prototype made of 216 ALPIDE sensors
- Each sensor is a matrix of 1024x512 pixels
- Each pixel is $\sim 30 \times 30 \times 50 \mu\text{m}^3$

→ 3D Matrix of $\sim 10^8$ Pixels!



3D view of the stack



Pixel chamber: Geant4 simulation

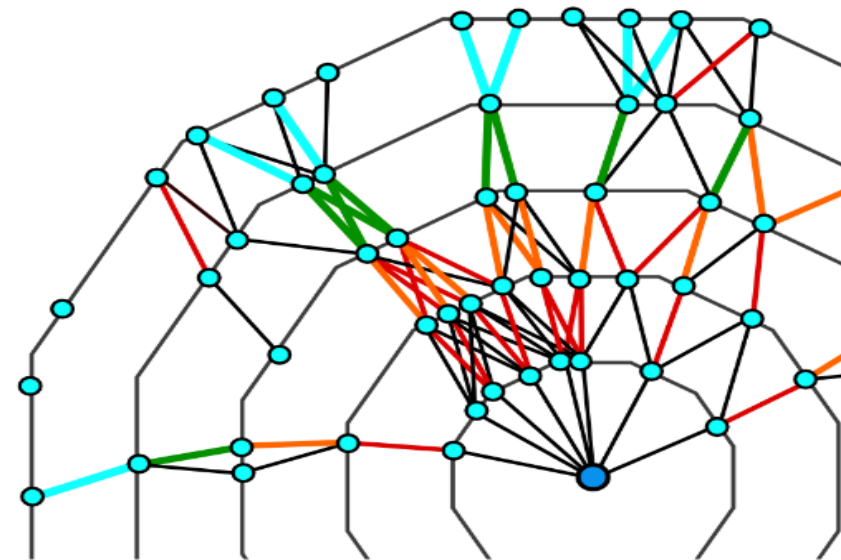
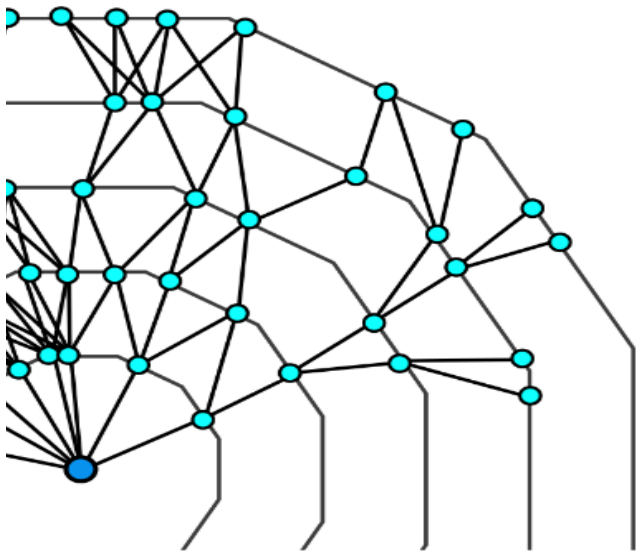
- 400 GeV p-Si interactions
- 3D visualization of p-Si inelastic collision with a D^+ meson

Dataset produced:

- Digit: center coordinates of the hit pixel
- Data for Monte Carlo truth:
 - Particle momenta
 - PDG code

Step 2: track and vertices finding and fitting

Track finding: group hits into clusters

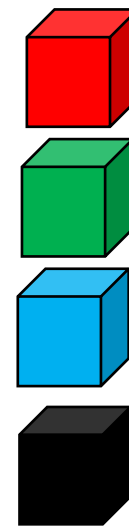
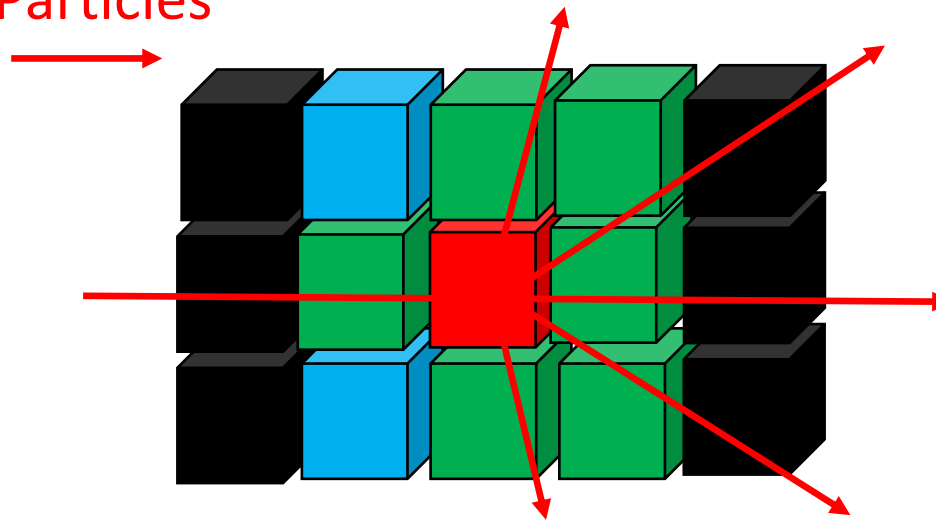


Algorithm

First step:

- Look for pixels' neighbors
- Check which neighbors have a hit
- Consider a point as noise if:
 - Number of neighbors < 2
 - Number of neighbors > 3 required to break clusters belonging to different tracks in regions with high density of hits (example figure right)

Particles



Considered pixel
with a hit

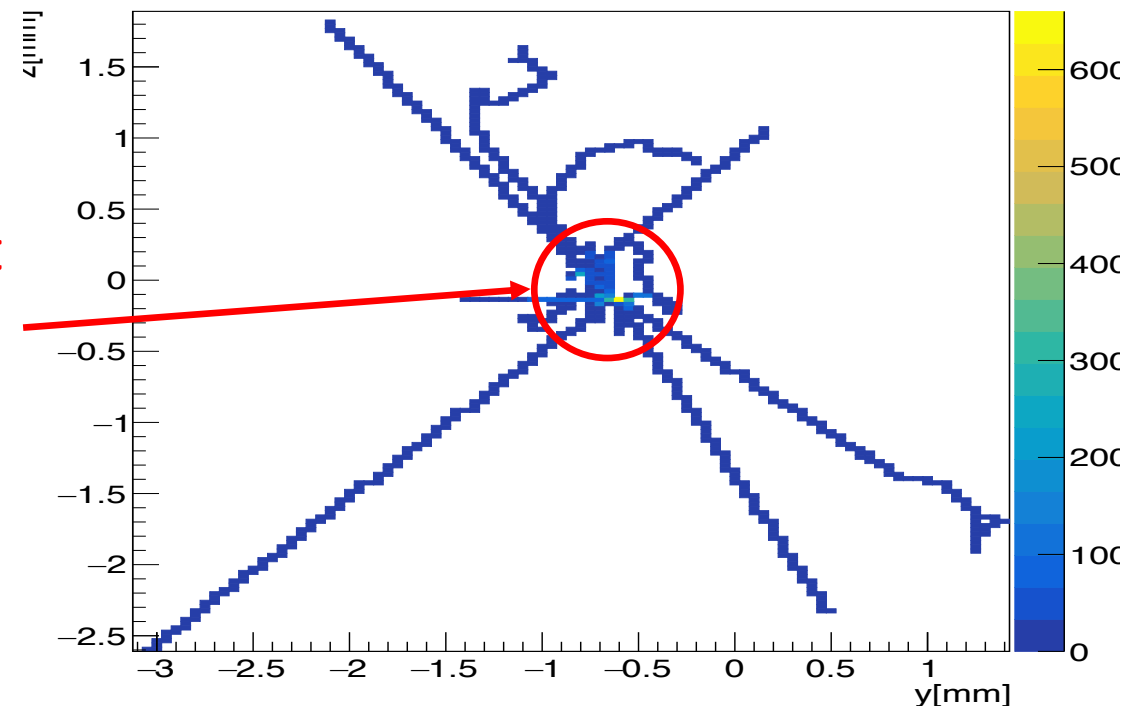
Neighbour with a hit

Neighbour without
hit

Not a neighbour

YZ

Interaction vertex point
with large number of
hit neighbors

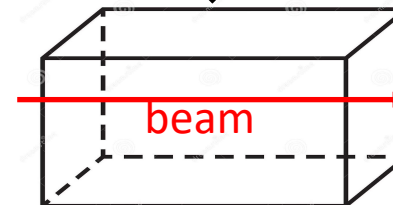
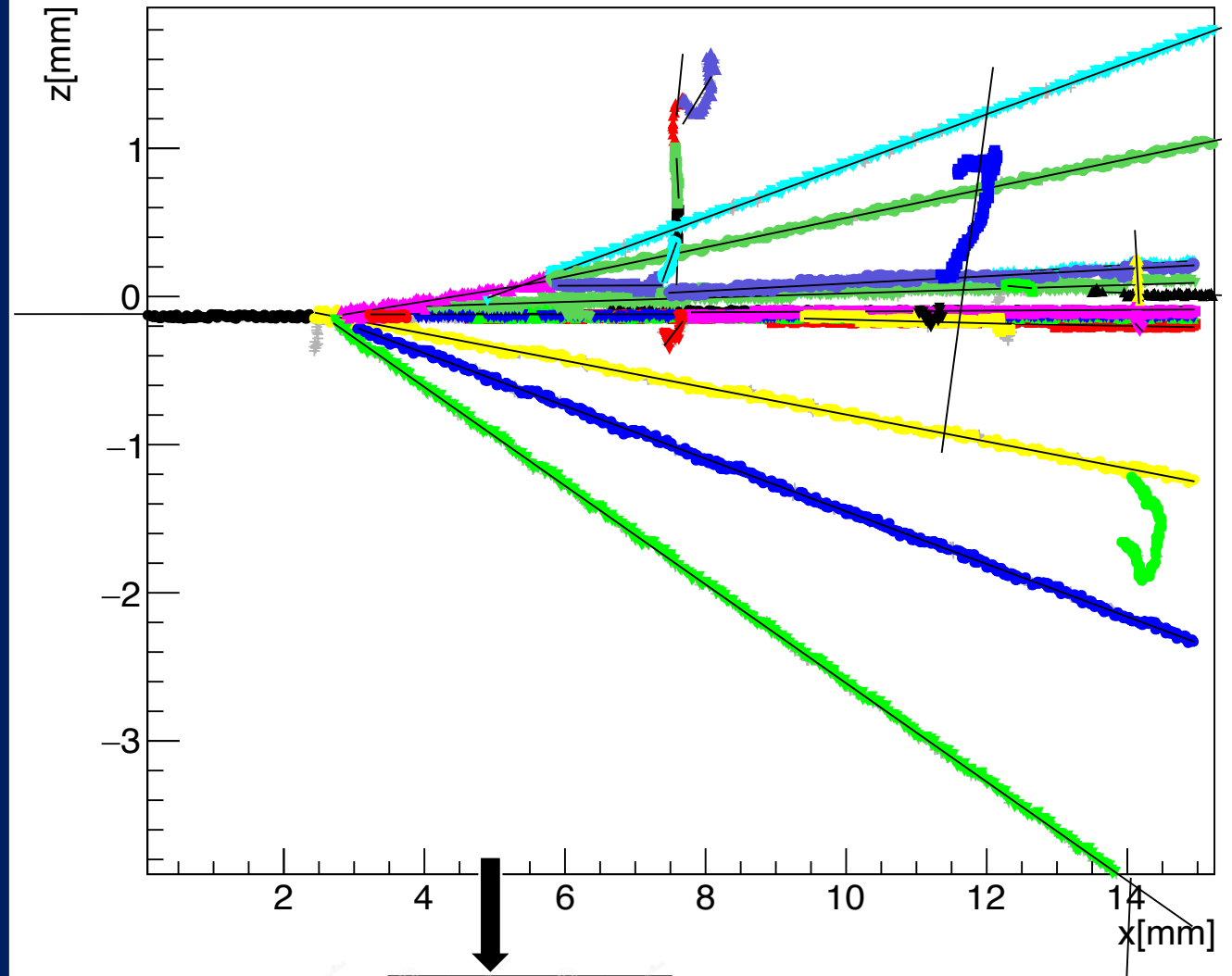


Algorithm

Further steps:

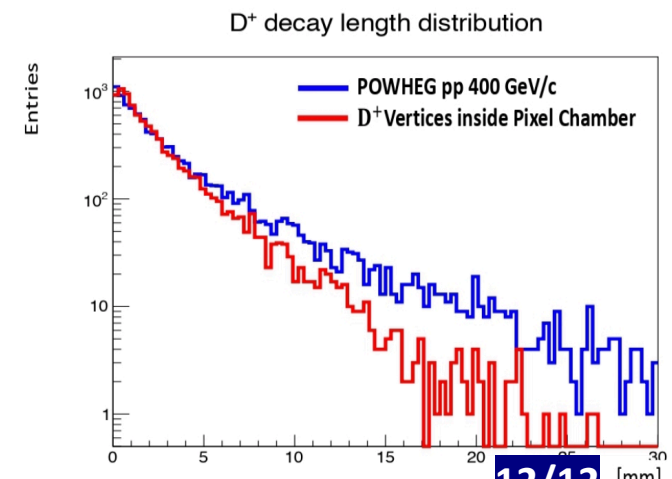
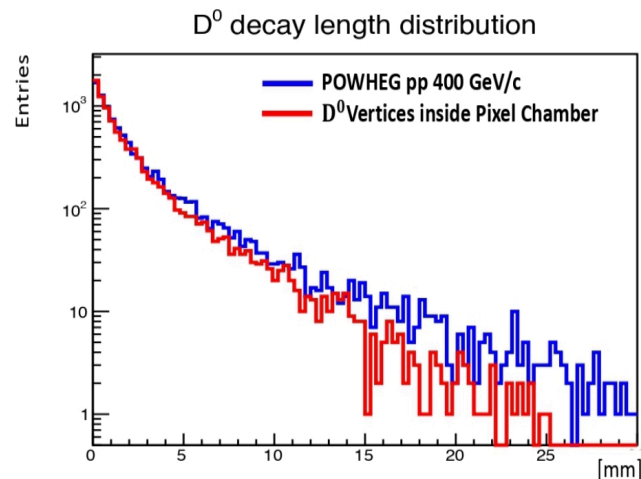
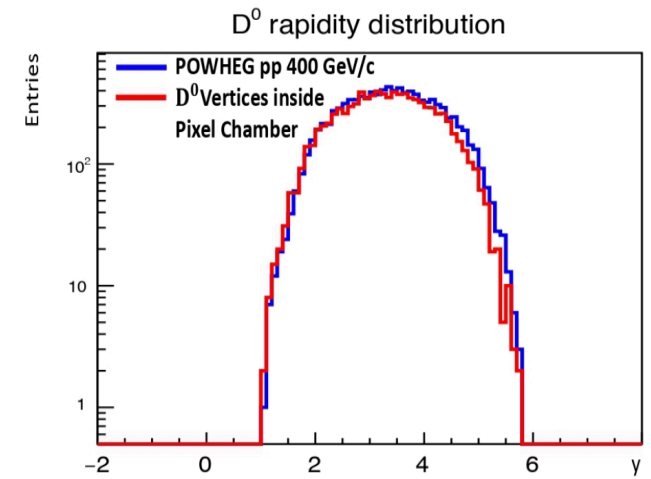
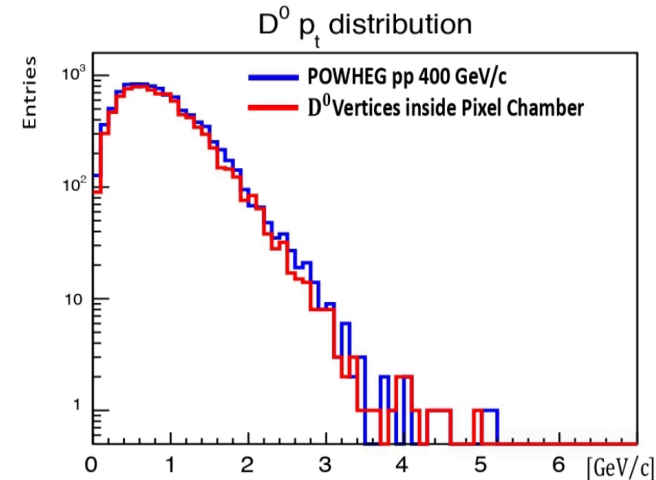
- Fit all reconstructed tracks with straight lines
- Look for compatible straight lines
- Merge compatible linear clusters
- Look if noise points are compatibles with some linear cluster
- New clusterization for residual noise points
- New fit to find vertices (under study):
 - New fit lines have to cross the same point

Reconstructed tracks:
Satisfactory reconstruction of most of the tracks



Summary and outlook

- ✓ Optimize track finder algorithm:
 - Secondary vertices reconstruction
 - Introduce machine learning
 - ✓ Reconstruction of charmed particles:
 - Secondary vertex selection
 - Momentum measurements of decay products with additional silicon telescope
 - Performance study of reconstruction of other charm and beauty states
 - Example of physics measurements: detailed performance study of very high precision charm production at CERN SPS
 - ✓ Construction of a detector prototype
 - ✓ Laboratory test with radioactive sources
 - ✓ Beam tests
- ✓ Reasonable fraction of charmed particles decays inside the detector
 - Possibility to identify particles without momentum???



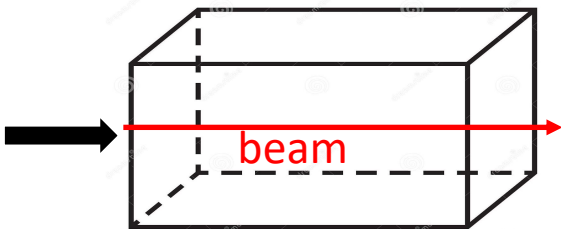
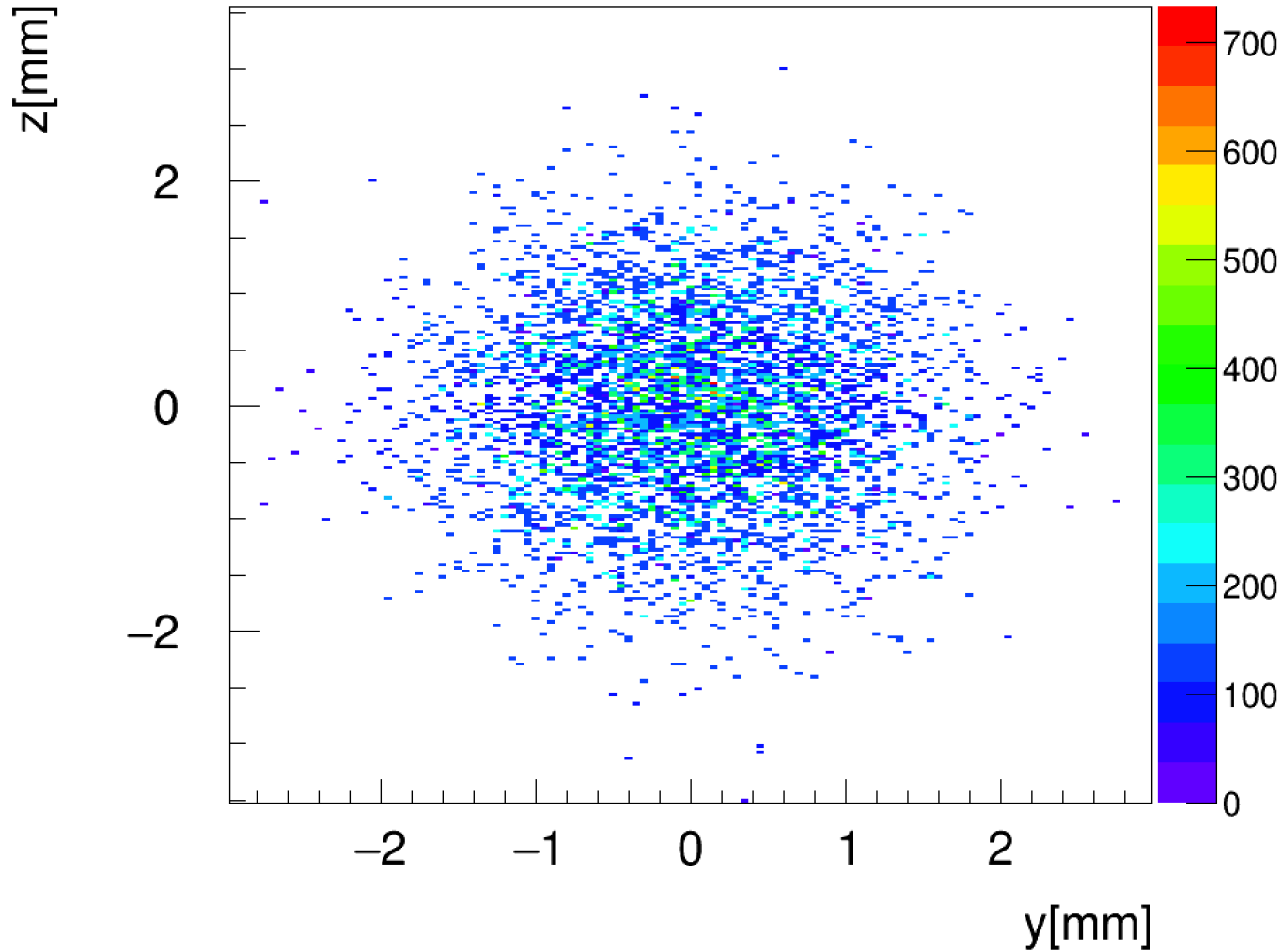


Thanks
for your attention



Backup slides

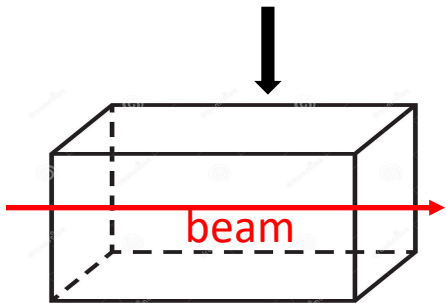
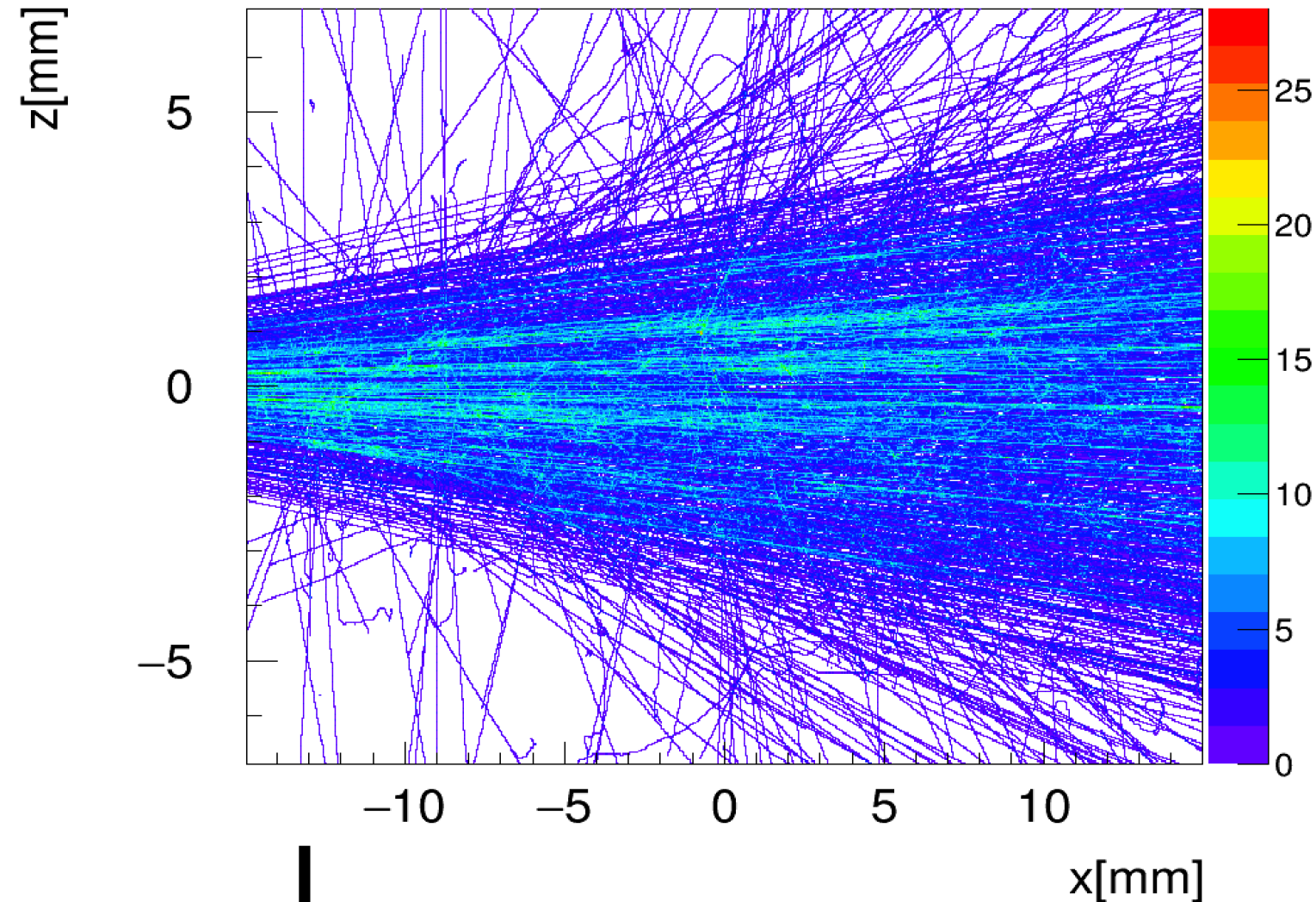
Generation point of primary protons



Pixel chamber: Geant4 simulation

- 400 GeV protons:
 - Production coordinates generated with a gaussian distributions with $\mu=0$ and $\sigma=0.8$ mm

Top view of the stack



Pixel chamber: Geant4 simulation

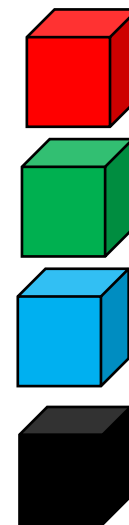
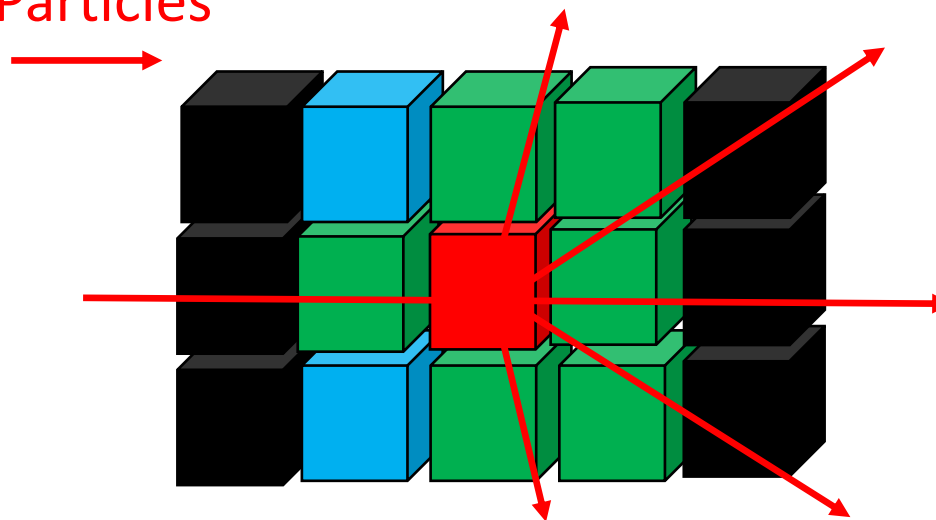
- 400 GeV protons:
 - Momentum direction components generated with a gaussian distribution with center in the production point and $\sigma=0.2$

Algorithm: track finding

First passes:

- Look for pixels' neighbors
- Check which neighbors have a hit
- Consider a point as noise if:
 - Number of neighbors < 2
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Particles

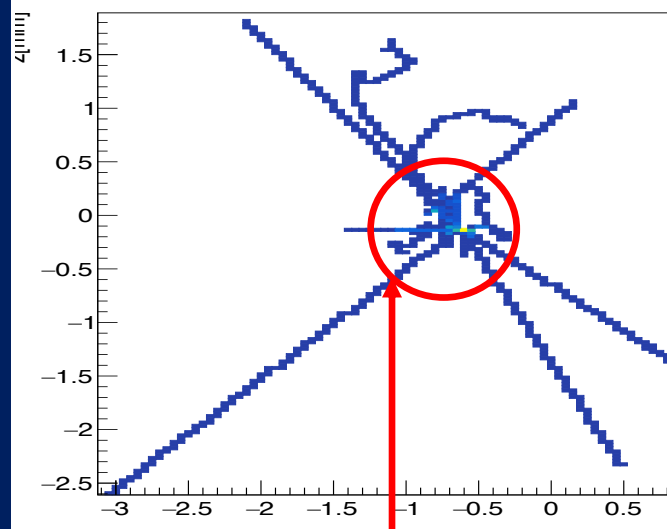


Considered pixel
with a hit

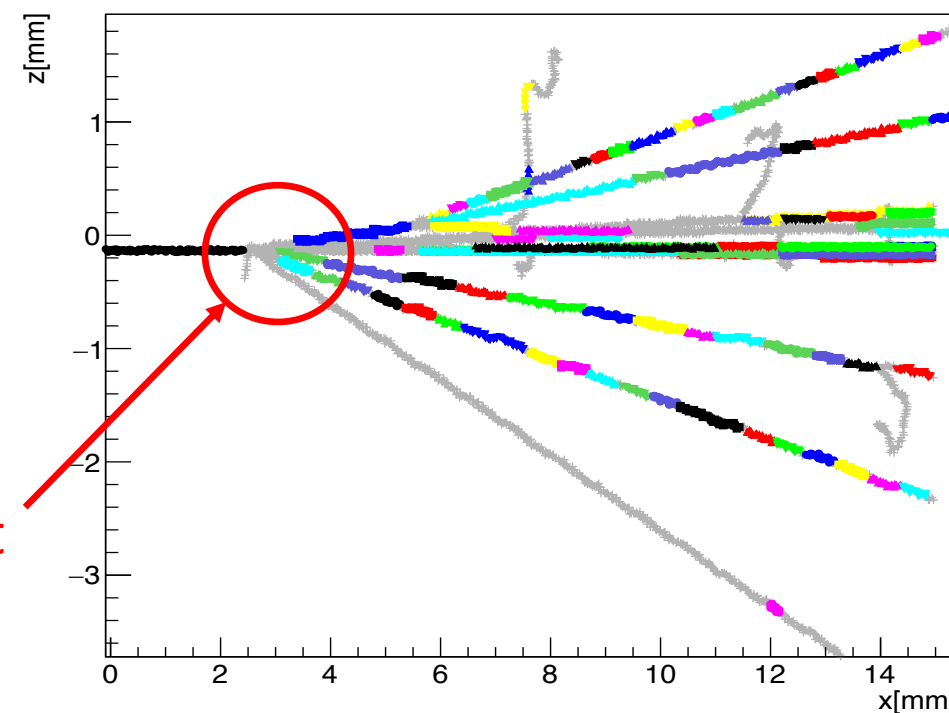
Neighbour with a hit

Neighbour without
hit

Not a neighbour



Interaction vertex point
with large number of
hit neighbors

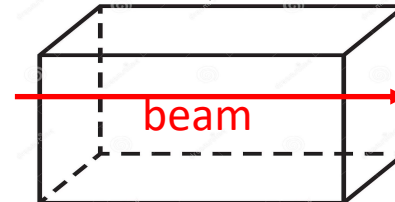
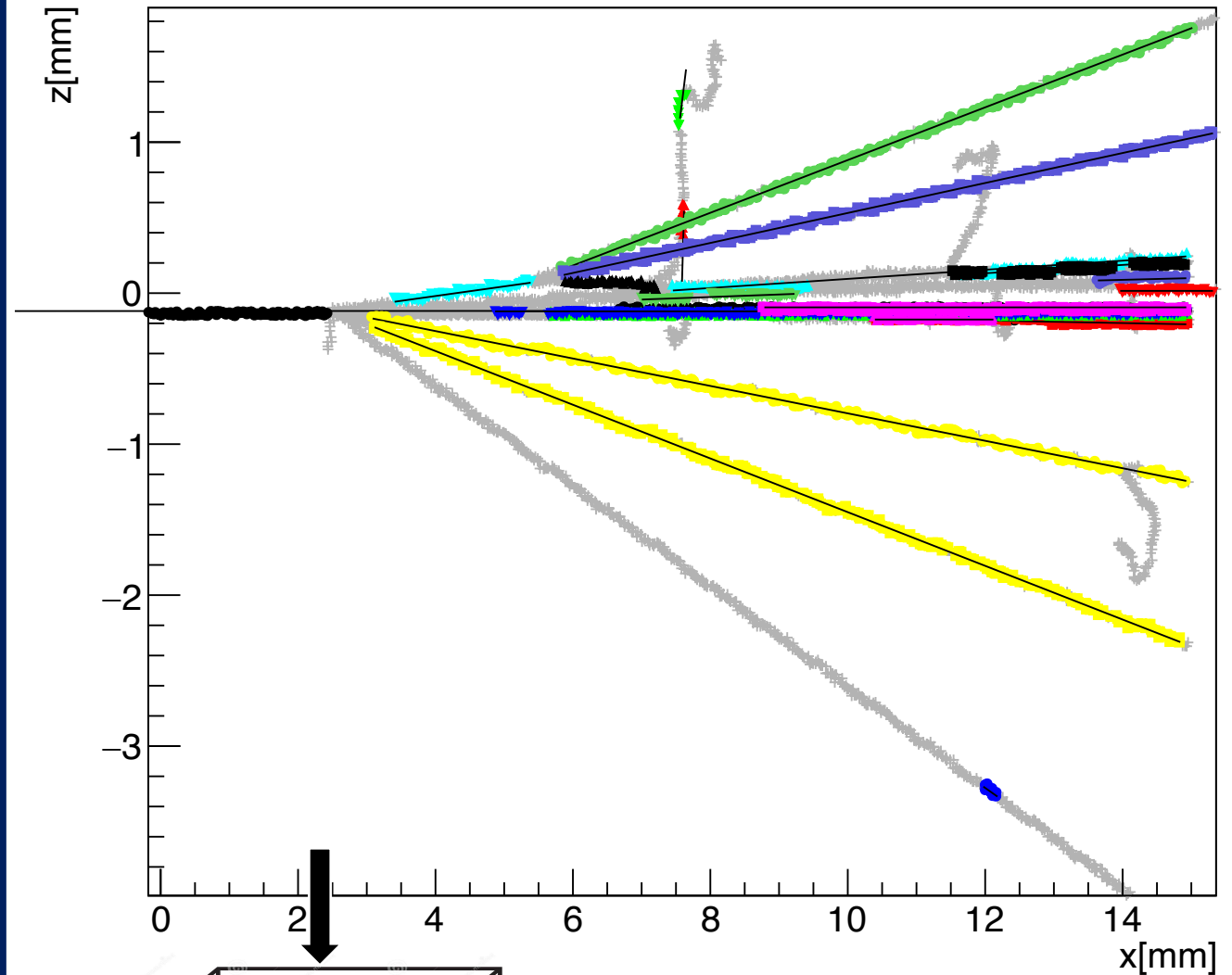


Algorithm: track finding

Fit and merge

- Fit all reconstructed tracks with straight lines
- Look for compatible straight lines
- Merge compatible linear clusters

Reconstructed tracks:
Fit and merge

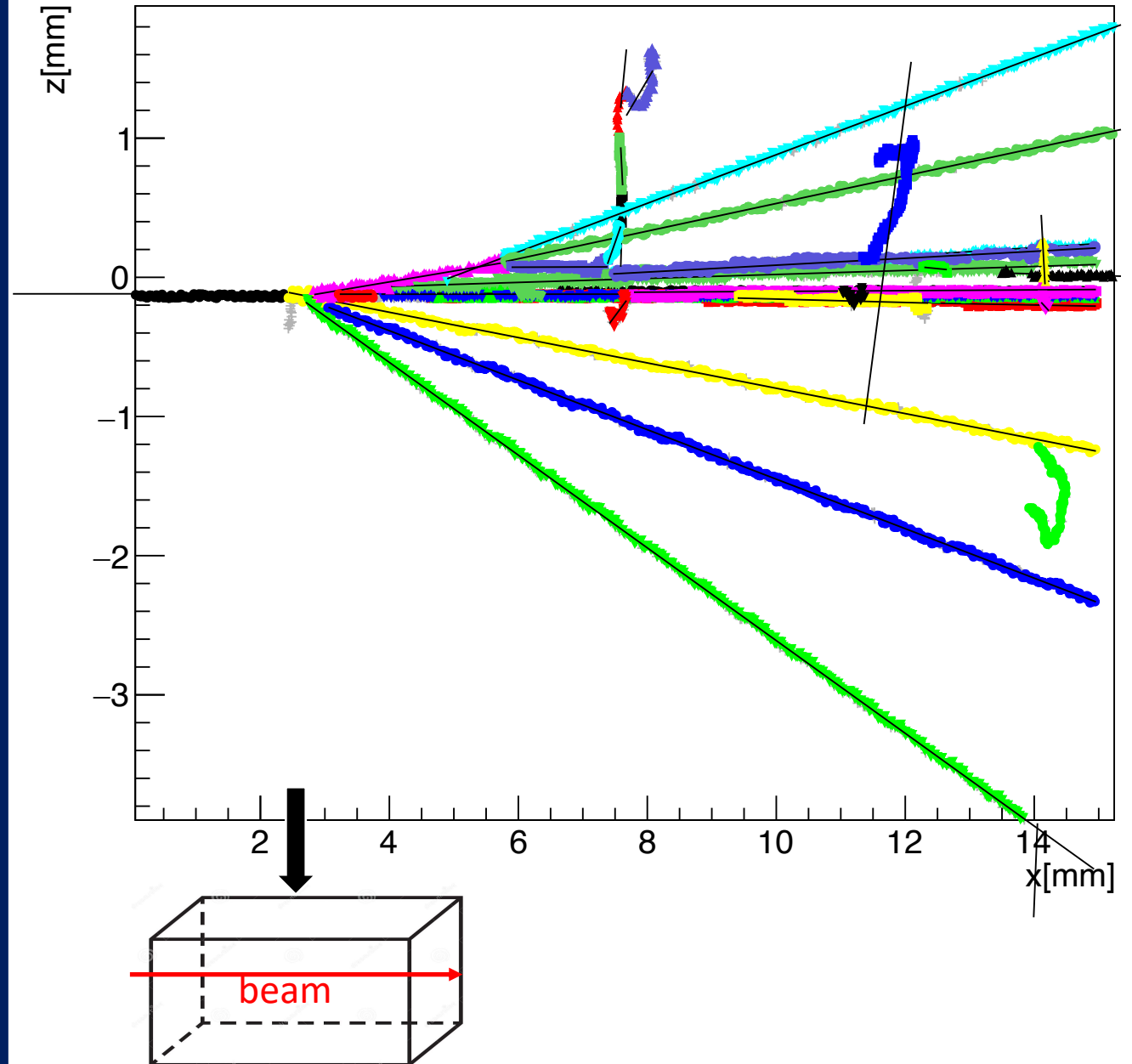


Algorithm: track finding

Noise check

- Look if noise points are compatibles with some linear cluster
- New clusterization for residual noise points
- Last fit

Reconstructed tracks:
Satisfactory reconstruction of most of the tracks

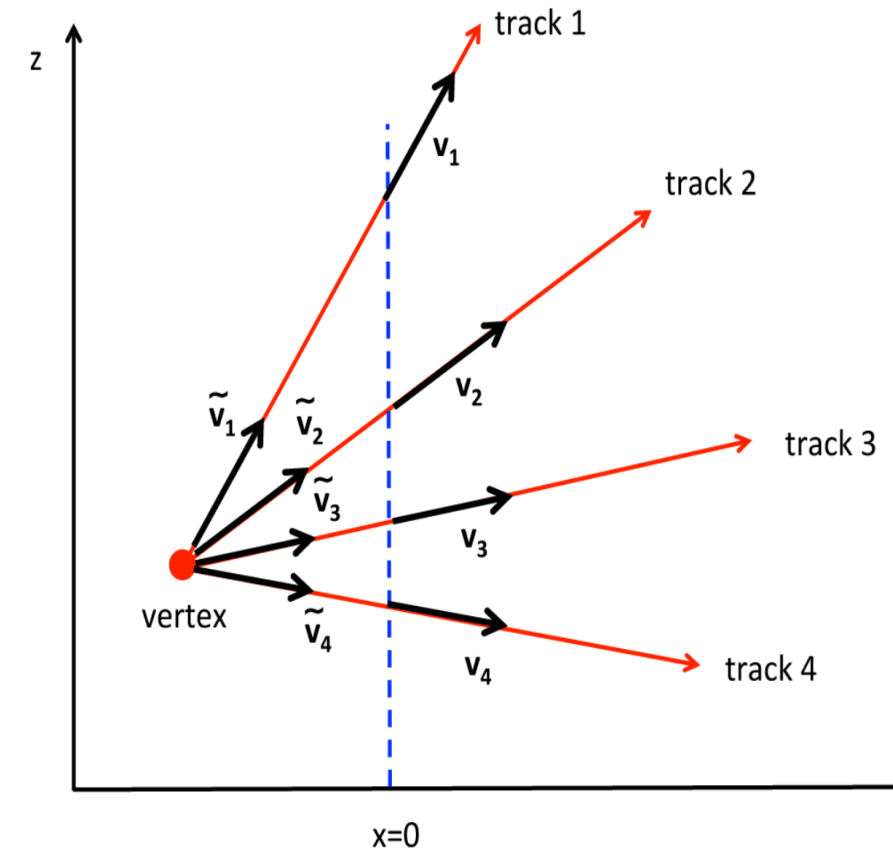


Algorithm: vertex finding

Vertex reconstruction

- New fit to find vertices (under study):
 - Fitted tracks are fitted again with new model:
 - New fit lines have to cross the same point
 - Starting from the proton track, tracks are used for the new fit
 - If the fit with a new track has $\chi^2 > 2$ the track is rejected

Track fit	$x_p = p[0]$	Model	$x_v = p[0]$
	$v_x = p[1]$		$y_v = p[1]$
	$y_p = p[2]$		$z_v = p[2]$
	$v_y = p[3]$		$t_{xm} = \frac{v_x}{v_y} = p[3]$
	$z_p = p[4]$		$t_{ym} = \frac{v_z}{v_y} = p[4]$
	$v_z = p[5]$		$t_{zm} = \frac{v_z}{v_x} = p[5]$



$$\chi^2 = \sum_{tracks} \frac{(y_{0p} - y_{0mod})^2}{\sigma_{y0}^2} + \frac{(z_{0p} - z_{0mod})^2}{\sigma_{z0}^2} + \frac{(t_x - t_{xmod})^2}{\sigma_{tx}^2} + \frac{(t_y - t_{ymod})^2}{\sigma_{ty}^2} + \frac{(t_z - t_{zmod})^2}{\sigma_{tz}^2}$$