

# IPHC Detector Lab activity and scanning table upgrade

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# IPHC detector Lab activity

- Training and working on triple cryostats
- CATs
- Scanning table upgrade before a complete scan of an AGATA capsule for Bart's thesis

# Triple cryostat ATC14

ATC14 : IN2P3 cryostat

1 February 2019 : delivery @ IPHC

18-19 February : @ IPHC assembly and test  
of the electronics thangs to the dummies

18- 20 March : @ IKP assembly of A015, B010 & C013  
electrical tests and vacuum leak test

8-10 April : test in cold condition

17 April : repair at room temperature and dismounting of B010

May : B009 detector mounting, test and delivery at GANIL



# Triple cryostat ATC14

## Encountered problems while working on ATC14

### Symptoms :

- Missing segments
- Very weak signals
- Oscillations
- Noisy segments
- Offsets increasing with HV

- Due to :
- Soldering defaults on a 6FETs-card or on the  $\frac{1}{2}$  moon-card
  - Broken HV resistor on a Core card
  - Bad preamp card
  - Leakage current on B010 (had to be replaced)

Some problems are detected at room temperature, but most of it in cold conditions, so it took several cooling /warming cycles to fix everything



# Triple cryostat ATC1

ATC1 failed late last year

16-18 January : problems of Core and oscillations of capsules B and C are fixed

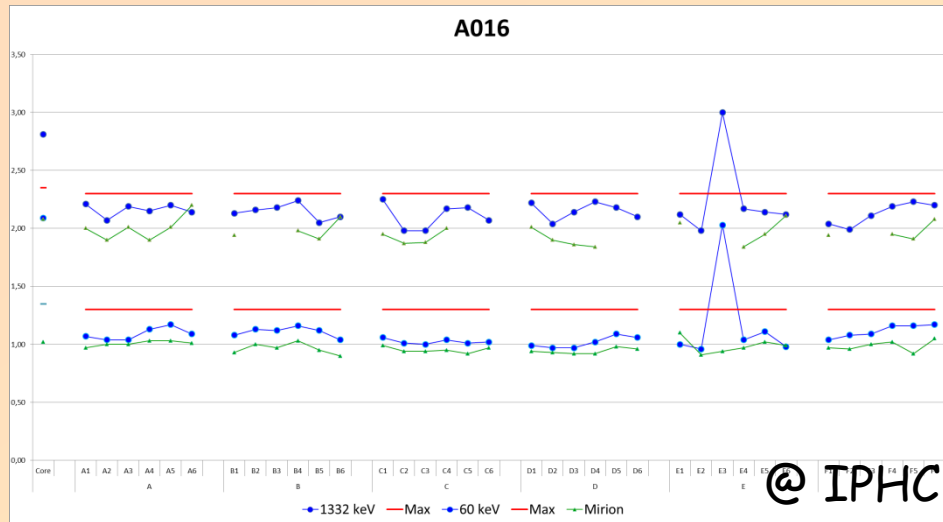
March : failed again

May : disassembly of the 3 capsules : all sent to Saclay to fix the HV problem

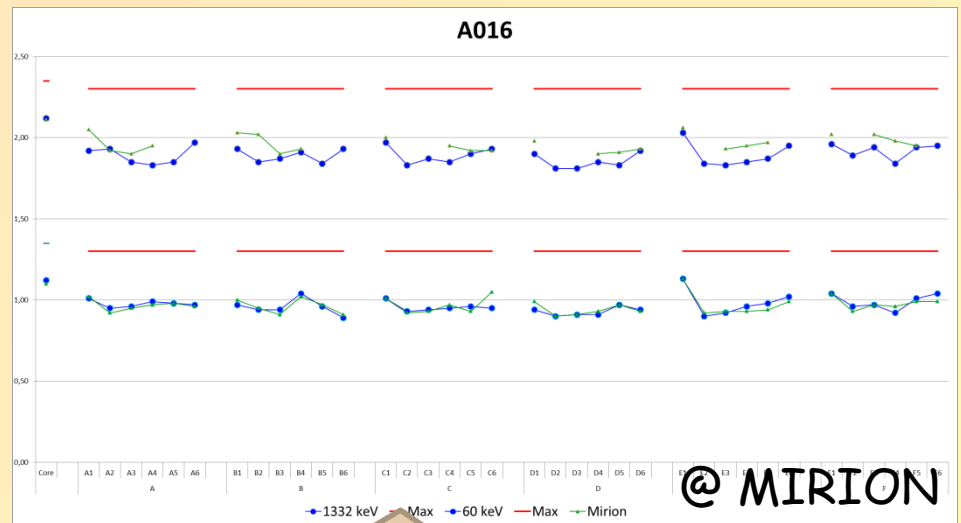
Cryostat refurbished by CTT

→ ATC1 ready to be transported at IPHC for assembly of 3 capsules  
A016 already in Strasbourg and 2 being repaired at Mirion

# A016 Acceptance Test



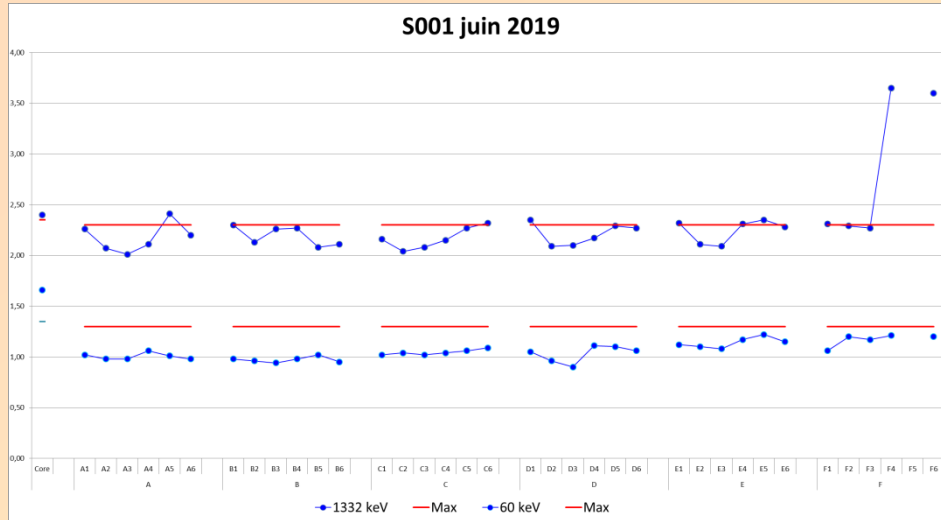
→ Leakage current on E3



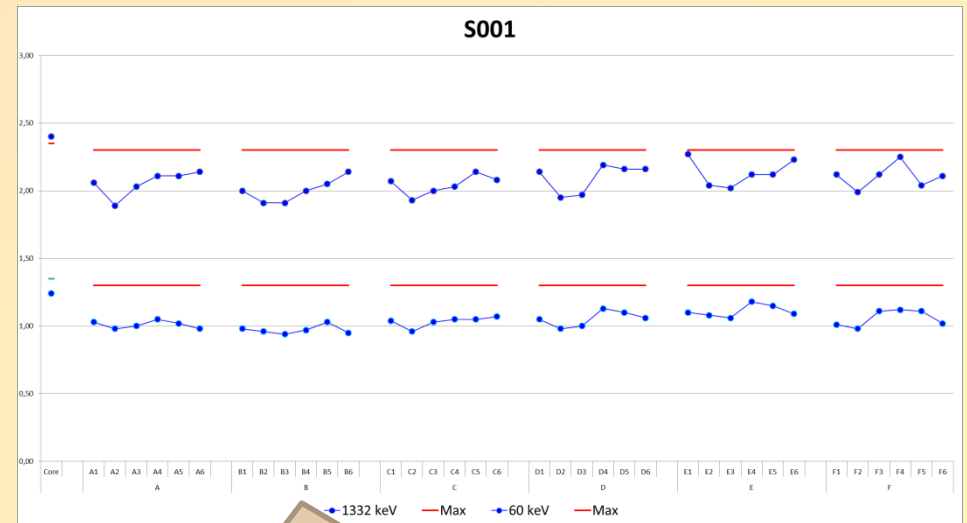
Repaired @ MIRION

→ very good resolutions

# S001 Performance test before scanning



→ Very high count rate on F5



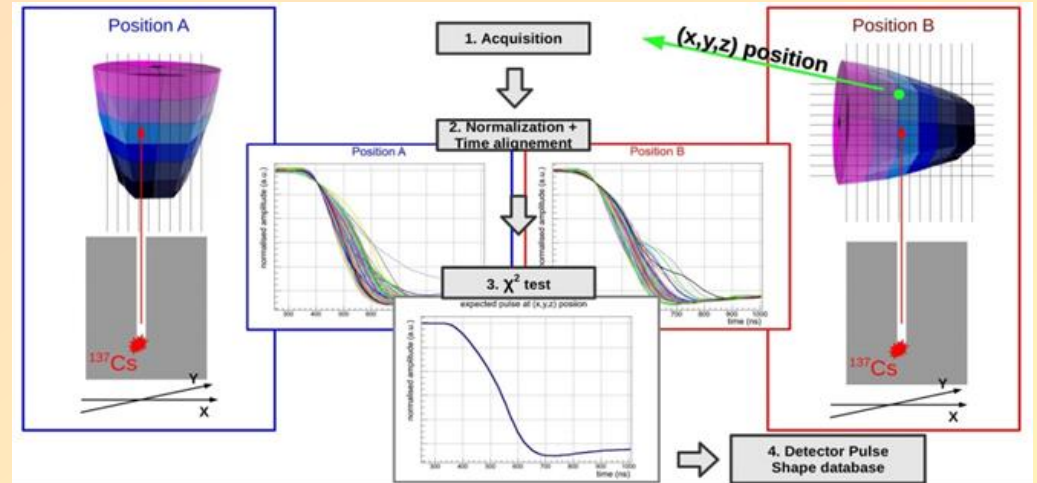
Feedback wire problem  
inside our test  
cryostat

→ Good performance  
but slightly too high  
Core resolution

# Scanning Table upgrade

Principle of our scanning table

→ PSCS method

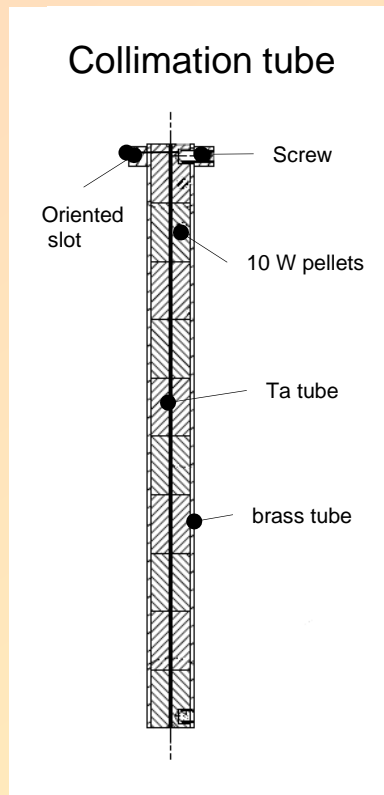


To be more precise at the crossing point it was necessary to:

- Decrease in collimation diameter
- Increase in the number of steps in the rotation of the detector
- Improve the LabView programs correlating acquisition, positioning of the source and cooling.

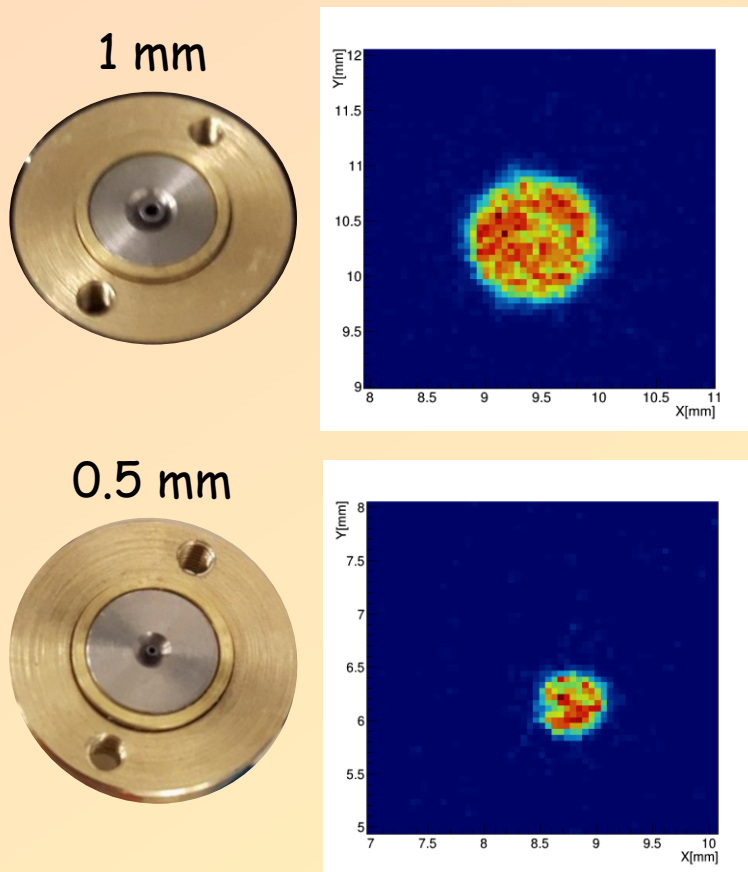
# Scanning Table upgrade - 3 interchangeable collimators

Replacement of the fixed 1.5 mm diameter hole by removable collimation tubes of 1 mm, 0.5 mm and 0.2 mm



# Scanning Table upgrade - 3 interchangeable collimators

Size verification and positioning repeatability in the W castle  
for the 1mm and 0.5 mm collimators with a  $50 \times 50 \mu\text{m}^2$  FitPIX position detector\*



Size	positioning repeatability
$\varnothing 0.91 \text{ mm} \pm 0.002$	$15 \mu\text{m}$
$\varnothing 0.52 \text{ mm} \pm 0.020$	$49 \mu\text{m}$

→ The values are in the expected specification

Shift of the 2 collimator centers :  $155 \mu\text{m}$

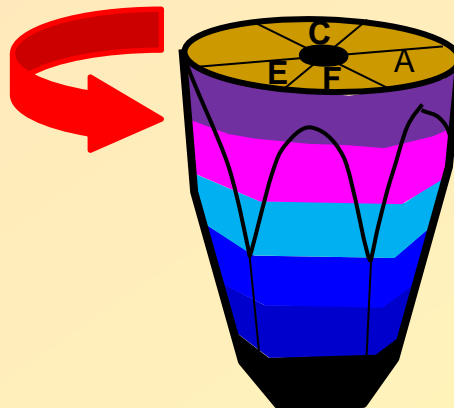
\* Mirion detector

# Scanning Table upgrade - adjustment frame



## Modification of the rotation ring

- ✓ For the pre-adjustment of the EF segmentation axis parallel to Y axis  
→ From a  $90^\circ$  to a  $30^\circ$  fix pitch rotation to pre-adjust
- ✓ for the fine adjustment  
→ From  $\pm 10^\circ$  to  $20^\circ$  continuous rotation

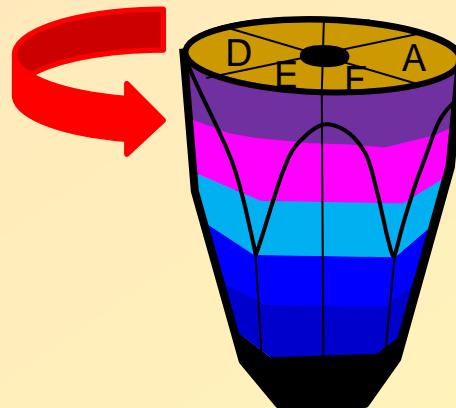


# Scanning Table upgrade - adjustment frame



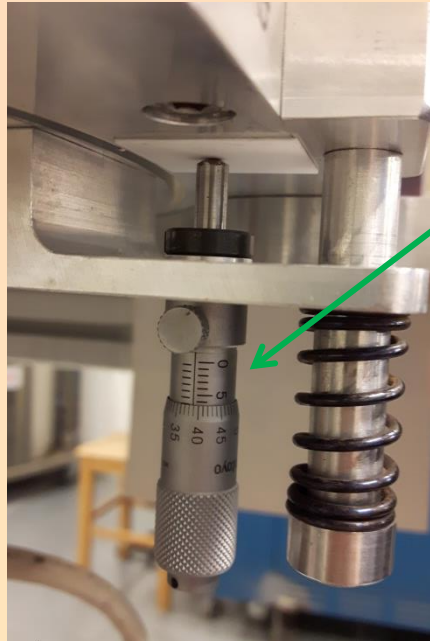
## Modification of the rotation ring

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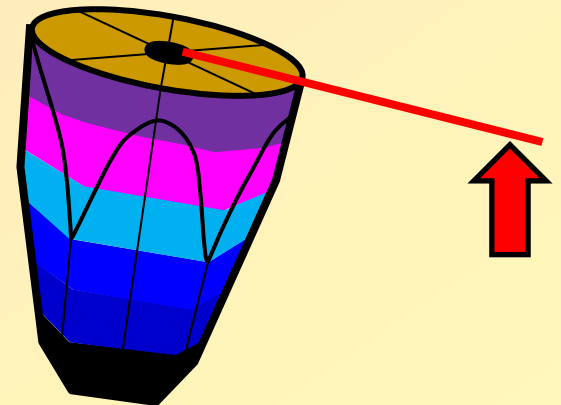
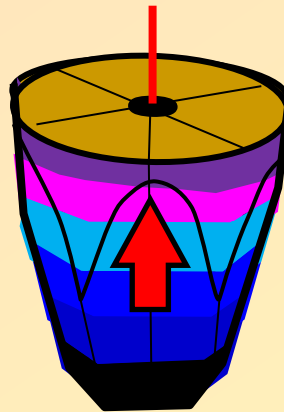
→ theoretical accuracy :  $0.12^\circ$   
S001 adjustment :  $0.04^\circ$

# Scanning Table upgrade - adjustment frame

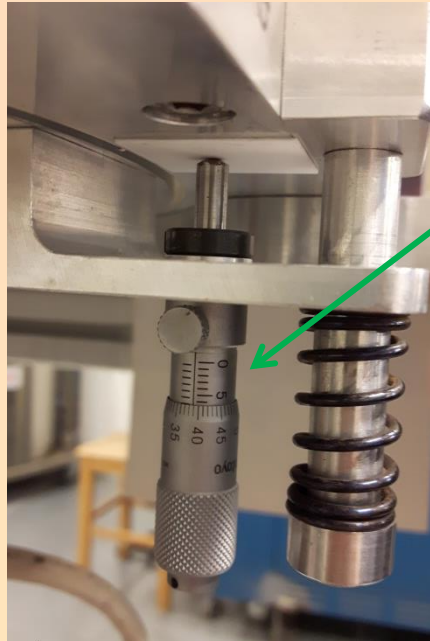


Micrometric screws

→ adjustment of the X & Y tilts parallel to the Z axis

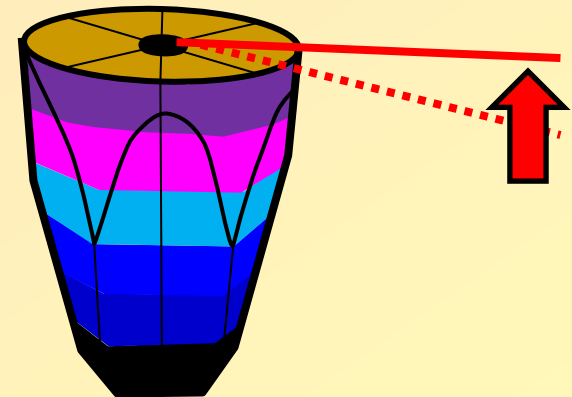
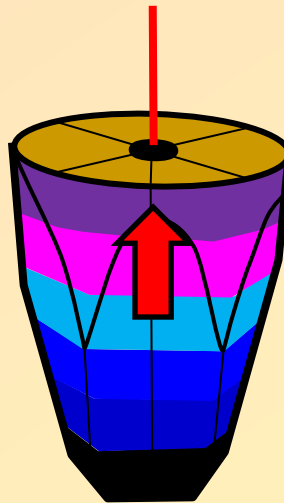


# Scanning Table upgrade - adjustment frame



Micrometric screws

→ adjustment of the X & Y tilts parallel to the Z axis



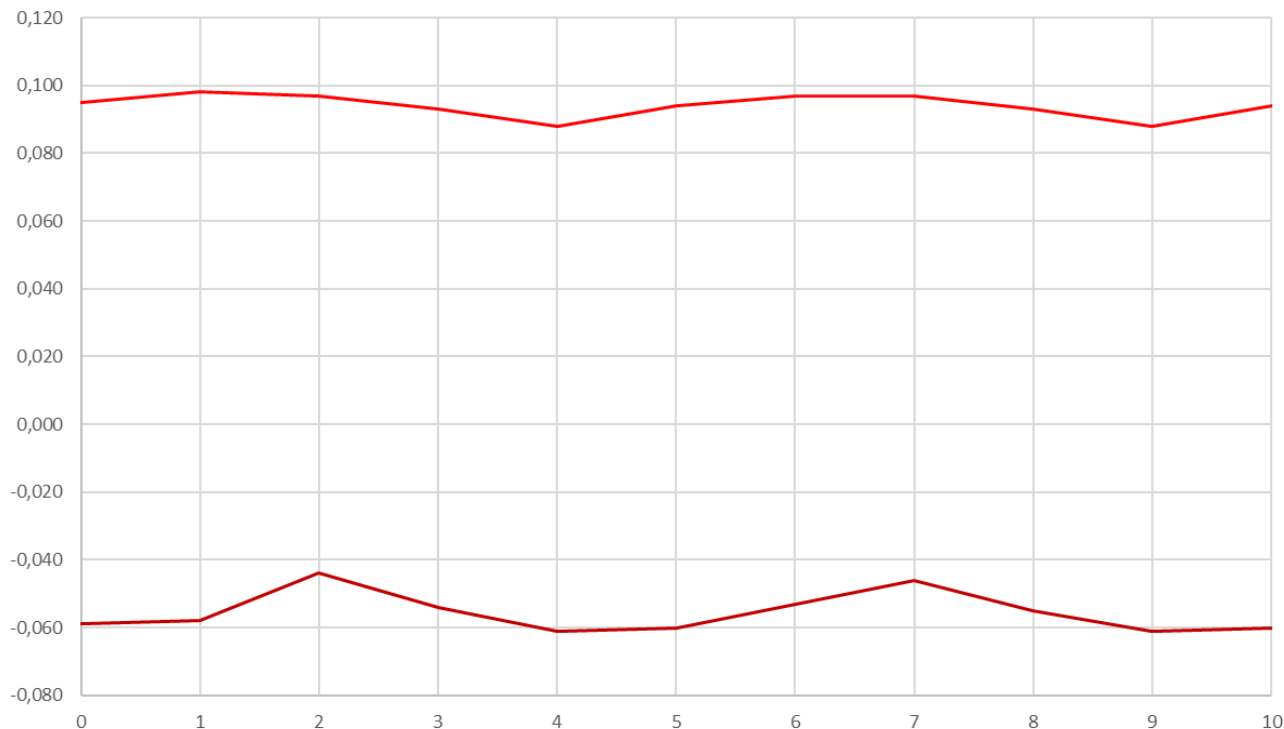
S001 adjustment on Y:  $0.048^\circ$

on X:  $0.014^\circ$

→ Less than  $100\mu\text{m}$  between the front and the back of the detector

# Scanning Table upgrade - scanning soft improvement

Difference between the real and the requested positions  
scan of 10 mm - steps of 1 mm

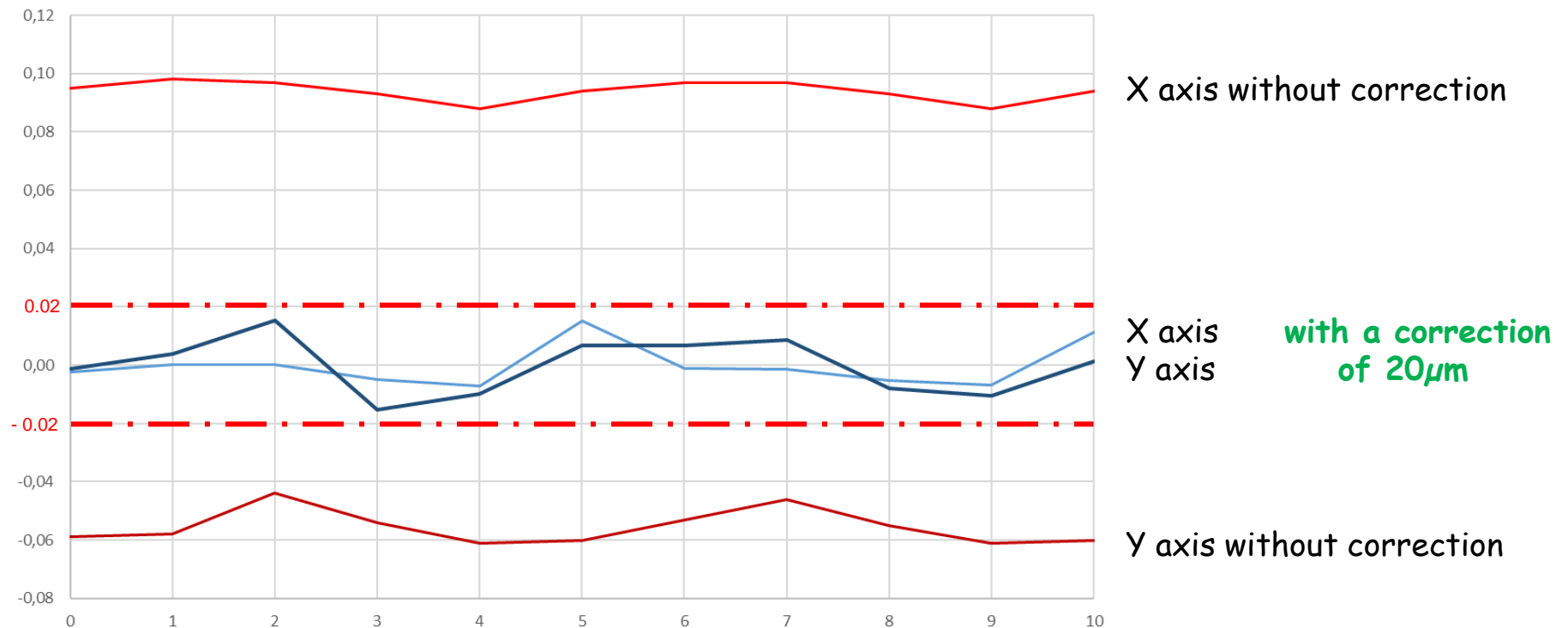


X axis without correction

Y axis without correction

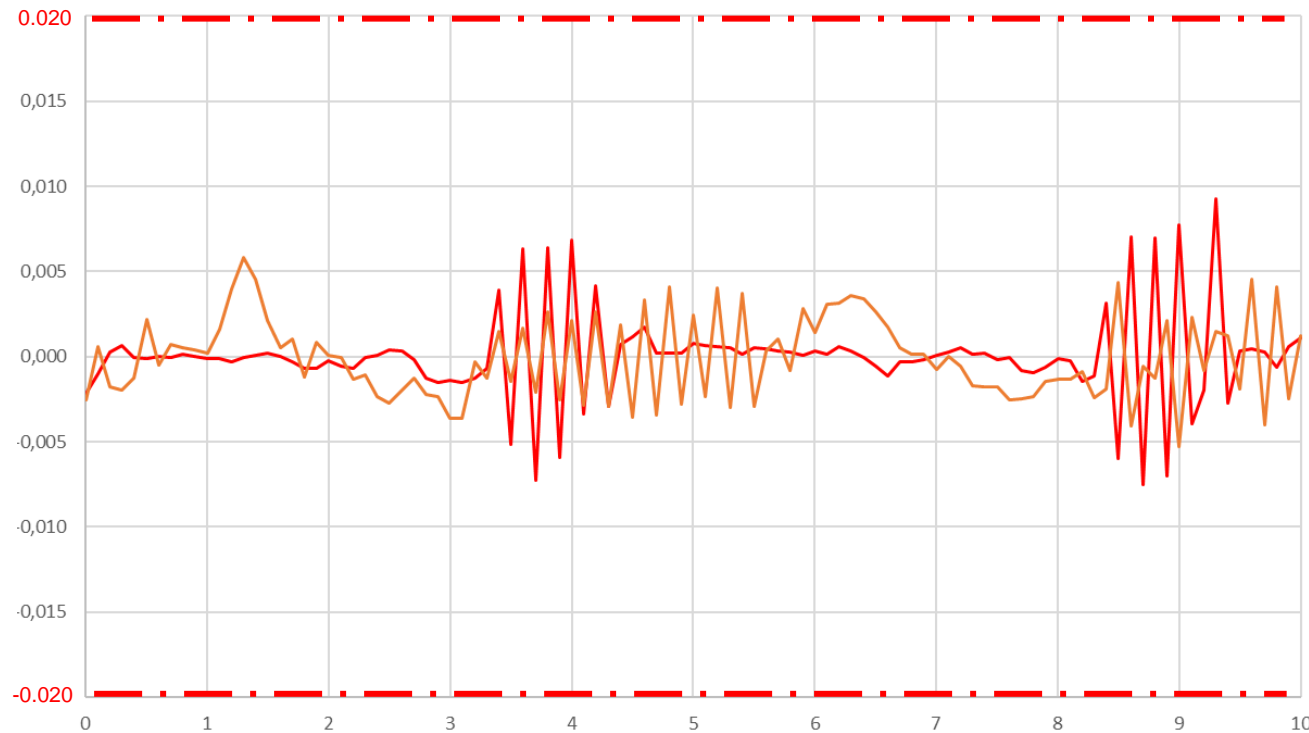
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# Scanning Table upgrade - scanning soft improvement

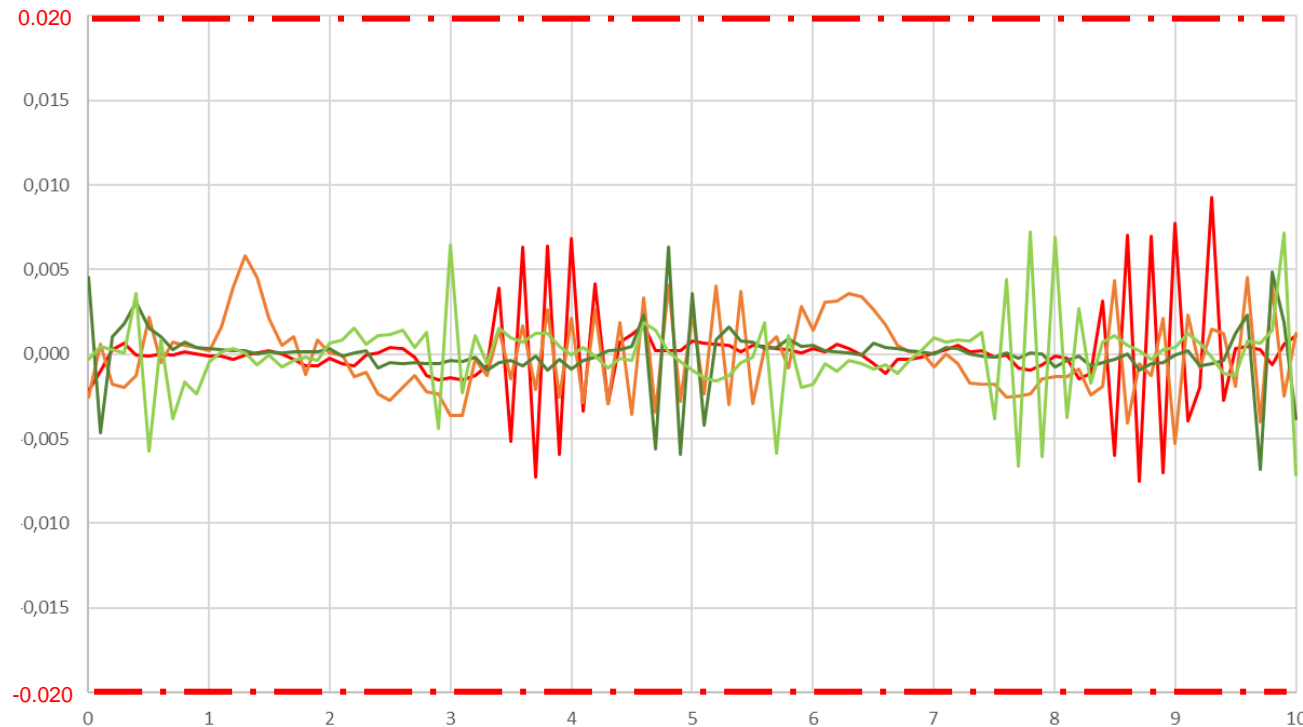
Difference between the real and the requested positions  
with a correction of  $20\mu\text{m}$   
steps of  $0.1\text{ mm}$  X axis (red) - Y axis (orange)



The accuracy is much better than  $20\mu\text{m}$

# Scanning Table upgrade - scanning soft improvement

Difference between the real and the requested positions  
with a correction of  $20\mu\text{m}$   
steps of 0.1 mm X axis (red and green) Y axis (orange and light green)



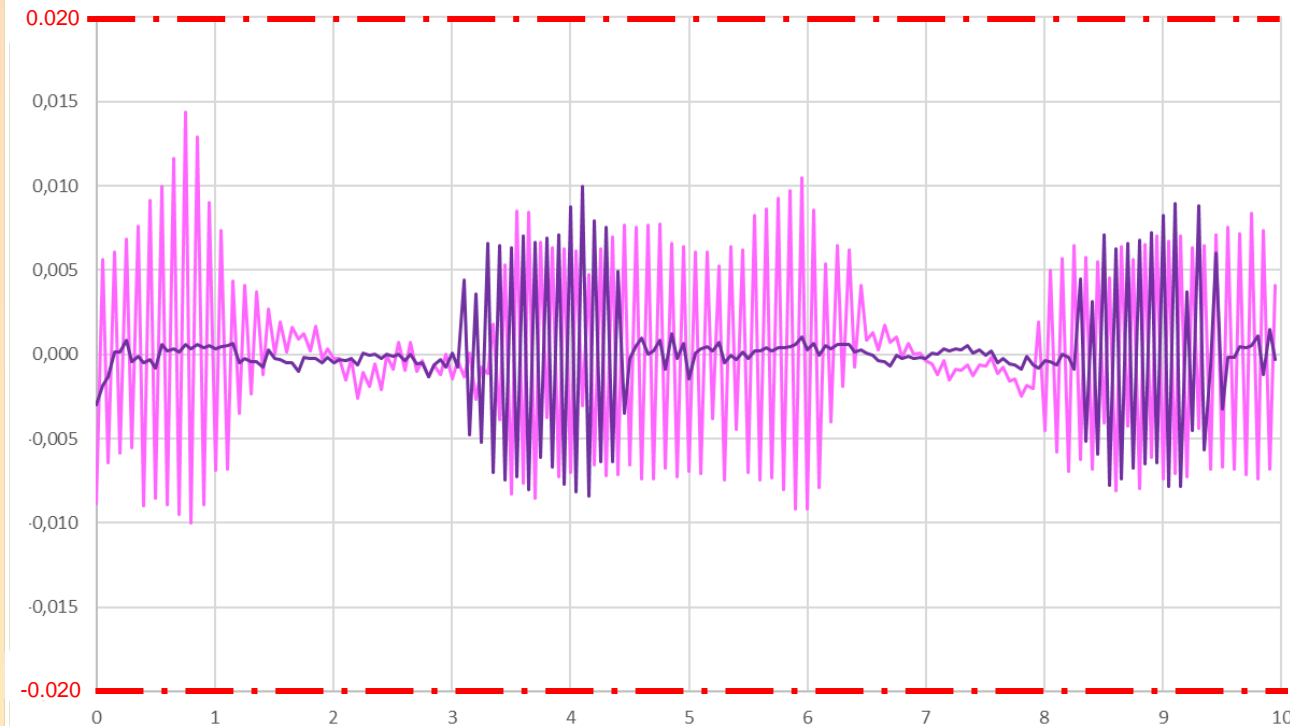
The accuracy is much better than  $20\mu\text{m}$

The scans were performed in both directions

→ The irregularities are not related to the optical scales

# Scanning Table upgrade - scanning soft improvement

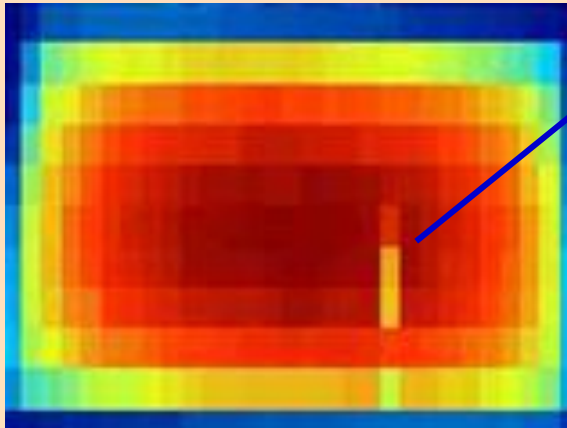
Difference between the real and the requested positions  
with a correction of  $20\mu\text{m}$   
steps of  $0.05\text{ mm}$  X axis (purple) - Y axis (pink)



More irregularities but

accuracy largely  
satisfactory

# Scanning Table upgrade - autofill soft improvement



Disturbance during the bubbling time of filling

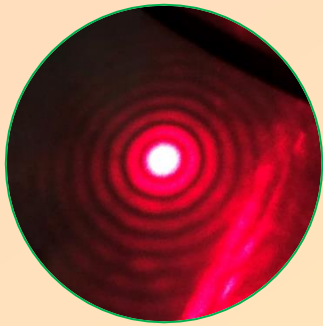
→ No acquisition during a filling and the following 10'

But the data taking for one position cannot be interrupt

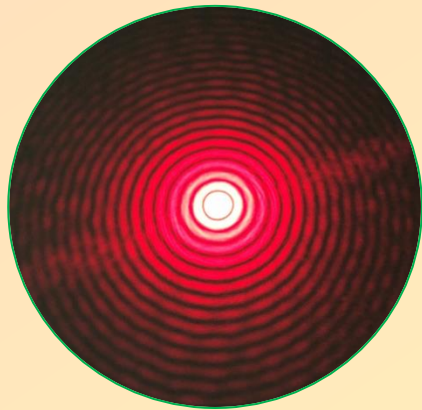
Collimator Ø	Source	Acquisition time	
1.5 mm	Cs 0.6 GBq	1 to 3 mn	Filling delayed
1 mm	Cs 1.85 GBq	3 to 6 mn	Acquisition delayed
0.5 mm	Cs 1.85 GBq	30 to 60 mn	Acquisition delayed

→ Scans of several days with long acquisition times are possible without disturbance  
Currently a scan of 270 points of 1 hour is running for 12 days in total autonomy

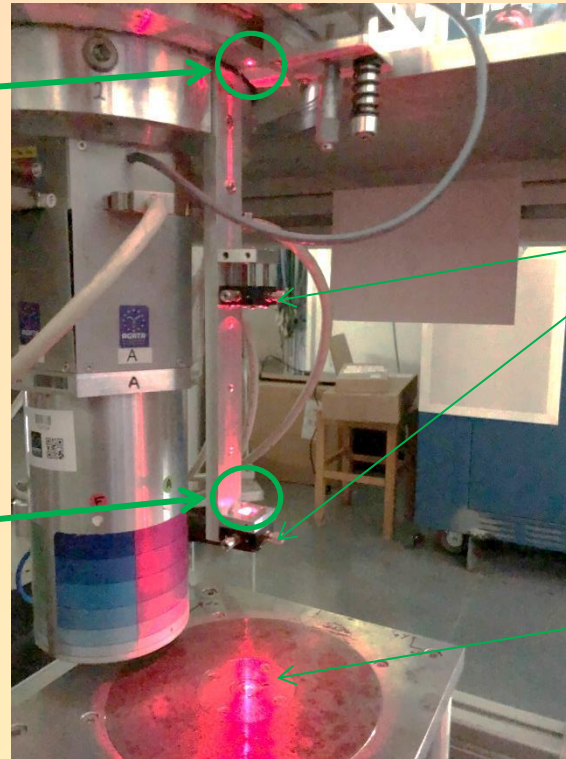
# Scanning Table upgrade - Laser realignment



Airy spot behind the hole of  $50\mu\text{m}$



Airy spot behind the hole of  $200\mu\text{m}$



Target holes of  $200\mu\text{m}$  and  $50\mu\text{m}$  attached on the detector to represent the position of the capsule

Laser beam passing through the collimator and the holes

→ Transition from vertical to horizontal position while insuring a crossing point precision of  $300\mu\text{m}$

# Conclusion

## Next steps

- Assembling ATC1 autonomously
- Completing the scanning of S001 capsule with high precision
- Performing scans of other detectors.

Thank you for your attention!

# Scanning Table upgrade - scanning soft upgrade

Difference between the real and requested position  
With a correction of  $20\mu\text{m}$   
Step of 1mm (blue) and 0,02 mm (purple)

