

# Spectroscopic Simulations for the Euclid Mission

## Relative In-Flight Flux Self-Calibration

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Probing the Universe with Multimessenger Astrophysics

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Università  
di Genova

# Spectroscopic Redshift Measurement

The measurement of spectroscopic redshift involves:

- 1 Dispersion of light → NISP instrument (**C. Sirignano's** talk)
- 2 Spectra Extraction
- 3 Identification of the emission lines



# The Spectroscopic Flux Calibration

The precision of the redshift measurement dramatically depends on a **complete calibration** of the scientific instruments.

The response of NISP spectroscopic channel is not uniform and it will degrade with time due to:

- dust pitting
- radiation damage
- material outgassing

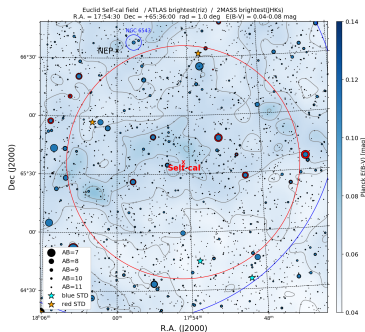
→ an in-flight calibration program has been specifically developed to determine and monitor the evolution of the response of the instrument with great accuracy.



# The Self-Calibration Field

Euclid will monthly observe the same sky area, called **Self-Calibration field**:

- Circular field of  $\sim 3.2 \text{ deg}^2$
- Near the North Ecliptic Pole (NEP)
- It provides both a sufficient number of stars and a low background level from the galactic disk



*Credits: Euclid Consortium.*

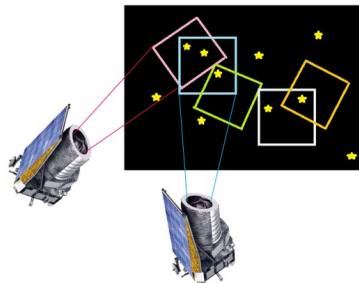


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# The in-flight Self-Calibration Procedure

- The self-calibration is based on the **multiple observations** of the same sources at different positions in the focal plane
- **Self-Calibration** → does not require the knowledge of the flux
- **Relative** → reconstruction of the response function up to a uniform scale factor



# Simulation of the Self-Calibration Survey

The simulation of the entire Self-Calibration survey is required to validate the pipelines and optimize the procedure.

- 1 Spectroscopic and realistic simulations → Euclid's official code
- 2 Spectra extraction → Euclid's official code
- 3 Reconstruction of the response function → general method<sup>1</sup>

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<sup>1</sup> S. Davini al. *A Proposal for Relative In-flight Flux Self-calibrations for Spectro-photometric Surveys*

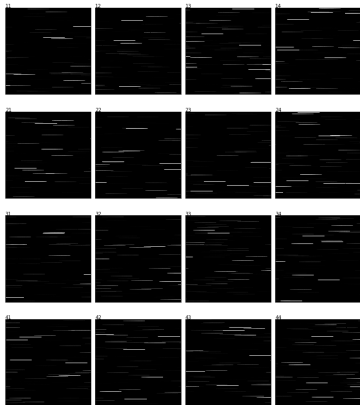


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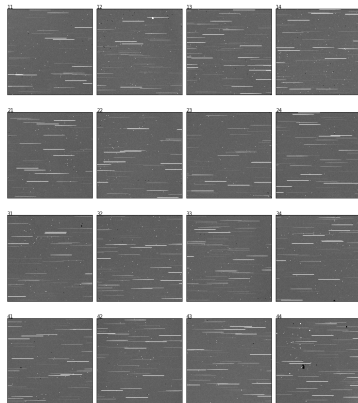
# Spectroscopic and Realistic Simulations

- spectroscopic mode: **overlapping of spectra**



# Spectroscopic and Realistic Simulations

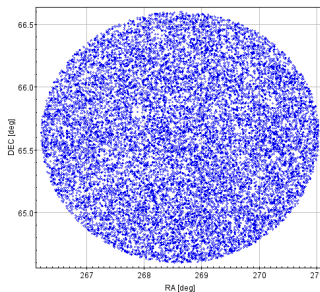
- spectroscopic mode: **overlapping of spectra**
- introduction of **systematic effects**
  - Readout noise
  - Dark current
  - Bad pixels
  - Zodiacal light





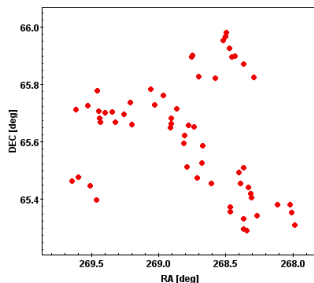
# Spectroscopic and Realistic Simulations

- spectroscopic mode: **overlapping of spectra**
- introduction of **systematic effects**
- realistic **catalogs** of sources



# Spectroscopic and Realistic Simulations

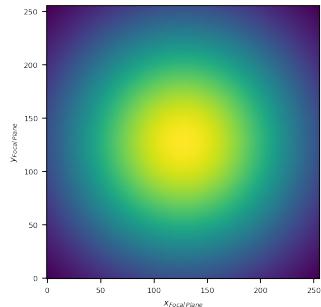
- spectroscopic mode: **overlapping of spectra**
- introduction of **systematic effects**
- realistic **catalogs** of sources
- optimized **pointing** sequence
  - 60 exposures
  - Monte Carlo approach
  - Proper sampling of all spatial scales observed in the survey



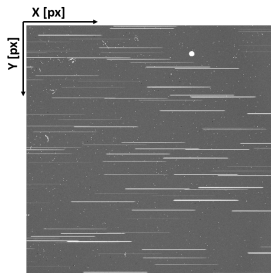
[ I. Rizzo, S. Caprioli, F. Passalacqua, S. Davini, M. Schirmer. *Selection of the Best Pointing Pattern for the Self-Calibration Procedure of the Euclid Satellite*, In Preparation. ]

# Spectroscopic and Realistic Simulations

- spectroscopic mode: **overlapping of spectra**
- introduction of **systematic effects**
- realistic **catalogs** of sources
- optimized **pointing** sequence
- different **response functions**

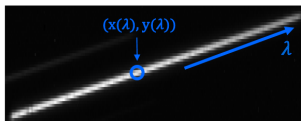


## 1 Pre-Processing



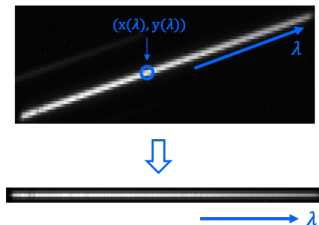
# Spectra Extraction

- 1 Pre-Processing
- 2 Spectra Location



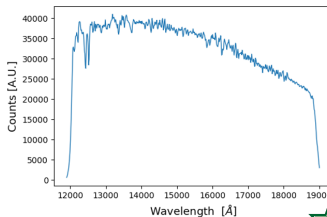
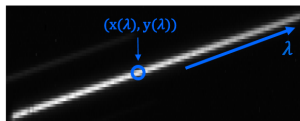
# Spectra Extraction

- 1 Pre-Processing
- 2 Spectra Location
- 3 2D counts



# Spectra Extraction

- 1 Pre-Processing
- 2 Spectra Location
- 3 2D counts
- 4 1D counts



DIAPYRIS/SPD  
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MISUR



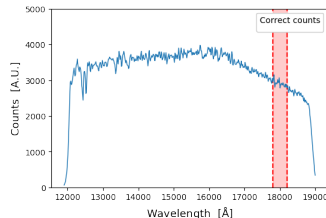
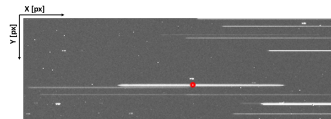
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# Reconstruction of the Response Function

- 1 Location of each observed source:  
**center** of the spectrum
- 2 Extraction of the counts  $\rightarrow$  **integration**  
of the counts in a range of  $\sim 400 \text{ \AA}$
- 3 Reconstruction of the response function  
 $\rightarrow \chi^2$  **minimization**

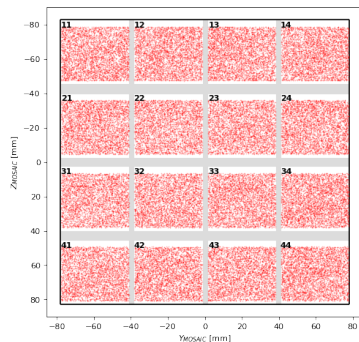


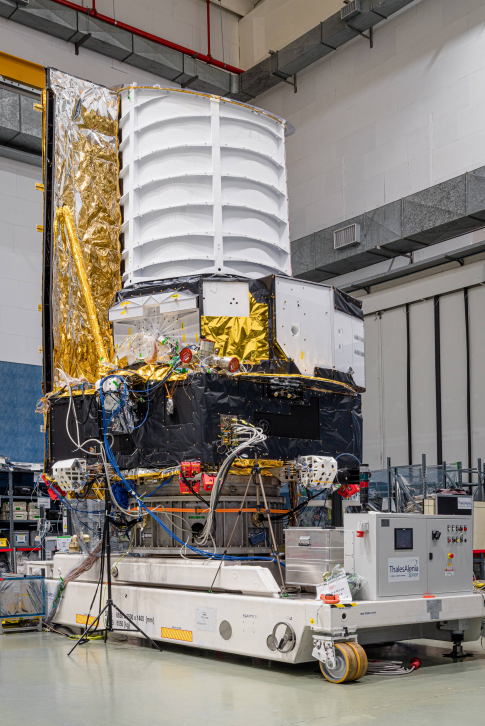
Different extraction ranges  $\rightarrow$  response function as a function of the wavelength



# Preliminary Results and Outlooks

- The large number of sources and observations allows the entire focal plane to be sampled
- So far, we have reconstructed uniform response functions
- We are increasing the precision to be able to reconstruct non-uniform response functions





*Thank you  
for your attention*

Credits:  
Thales Alenia Space



# Reconstruction of the Response Function

$$\chi^2 = \sum_k \sum_{i \in k} \frac{(c_{i(k)} - \hat{f}(x_i, y_i | \mathbf{q}) r_k t_i)^2}{\sigma_{i(k)}^2}$$

Index:

- $k$ :  $k$ -th source
- $i$ :  $i$ -th exposure
  
- $c$  measured counts
- $\hat{f}$  : reconstructed response function
- $(x, y)$ : position on the focal plane
- $\mathbf{q}$ : parameters of the response function
- $r$ : measured rates of the source
- $t$ : exposure time
- $\sigma^2$ : variance (Poisson + noise)