

Holography: from QFT to cosmos.

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Worked solutions to exercises.

1.1) For the Hamiltonian constraint, note the powers of N :

$$S = \frac{1}{2\kappa^2} \int d^4x \sqrt{g} \left\{ \frac{1}{N} (E_{ij} E^{ij} - E^2) + \frac{1}{N} (\dot{\Phi} - N^i \Phi_{,i})^2 + \sigma N (-R + g^{ij} \Phi_{,i} \Phi_{,j} + 2\kappa^2 V(\Phi)) \right\}$$

where $E_{ij} = \frac{1}{2} \dot{g}_{ij} - \nabla_{(i} N_{j)}$.For the extrinsic curvature, using $n^\mu = \frac{1}{N} (1, -N^i)$ and $g_{\mu\nu} n^\mu n^\nu = N^2$

$$L_n g_{ij} = n^\mu g_{ij;\mu} + 2g_{\mu(i} n^\mu_{;j)}$$

$$= \frac{1}{N} \dot{g}_{ij} - \frac{N^k}{N} g_{ijk} + 2N_{(i} \left(\frac{1}{N} \right)_{;j)} - 2g_{k(i} \left(\frac{N^k}{N} \right)_{;j)}$$

$$- \frac{2}{N} g_{k(i} N^k_{;j)} = - \frac{2}{N} (N_{(i;j)} - N^k g_{k(i;j)})$$

$$= \frac{1}{N} \dot{g}_{ij} - \frac{2}{N} N_{(i;j)} + \frac{N^k}{N} (2g_{k(i;j)} - g_{ijk})$$

$$\frac{2}{N} N_k \Gamma^k_{ij}$$

$$= \frac{1}{N} \dot{g}_{ij} - \frac{2}{N} \nabla_{(i} N_{j)}$$

and K_{ij} is then half of this.

1.2) The background action is

$$S = \frac{1}{2\kappa^2} \int d^4x a^3 (K_{ij} K^{ij} - K^2 + \dot{\Phi}^2 + \sigma (-R + 2\kappa^2 V))$$

and $K_{ij} = \frac{1}{2} \dot{g}_{ij} = a^2 H \delta_{ij}$ where $H = \dot{a}/a$. The 3-curvature $R = 0$ since $g_{ij} = a^2(z) \delta_{ij}$, and for constant- z slices this is just a rescaling of flat space.

This gives $S = \frac{1}{2\kappa^2} \int dt d^3x \left(-6\dot{a}^2 a + a^3 \dot{\varphi}^2 + 2\sigma a^3 \kappa^2 V \right)$

Varying wrt a and φ $\Rightarrow \begin{cases} 0 = H^2 + 2\frac{\ddot{a}}{a} + \frac{1}{2}\dot{\varphi}^2 + \sigma \kappa^2 V \\ 0 = \ddot{\varphi} + 3H\dot{\varphi} - \sigma \kappa^2 V' \quad (\text{KG eq}) \end{cases}$

The Hamiltonian constraint gives also $0 = 6H^2 - \dot{\varphi}^2 + 2\sigma \kappa^2 V$.

$\Rightarrow 0 = \underbrace{\frac{\ddot{a}}{a}}_{\dot{H}} - H^2 + \frac{1}{2}\dot{\varphi}^2$ 1st Friedmann eq
2nd Friedmann eq

Assuming monotonicity, we can express $H = H(z)$ as a function of φ , let's say $H = -\frac{1}{2}W'(\varphi)$. Then

$$\dot{H} = -\frac{1}{2}W''\dot{\varphi} = -\frac{1}{2}\dot{\varphi}^2 \quad \text{so} \quad \dot{\varphi} = W'$$

$$\text{and } 2\sigma \kappa^2 V = \dot{\varphi}^2 - 6H^2 = W'^2 - \frac{3}{2}W'^2$$

1.3) a) To $\mathcal{O}(h^2)$, $g^{ik}g_{kj} = \delta^i_j$.

In general, $\delta_{\mu\nu}^{\mu} = (g^{\mu\lambda} + \delta g^{\mu\lambda}) (g_{\lambda\nu} + \delta g_{\lambda\nu})$ so $\delta g^{\mu\nu} = -g^{\mu\lambda} g^{\nu\sigma} \delta g_{\lambda\sigma}$

Thus, $\delta g^{\mu\nu}$ is minus what we get by raising $\delta g_{\mu\nu}$ with two background inverse metrics.

b) $K_{ij} = \frac{1}{N} \left(\frac{1}{2}\dot{g}_{ij} - \partial_{(i} N_{j)} \right)$

$= (1 - \delta N) \left(\frac{1}{2} (a^2 (\delta_{ij} + h_{ij}))' - \partial_{(i} N_{j)} + \overset{(0)}{\Gamma}_{ij}^k N_k \right)$ Ne already 1st order

$$= (1 - \delta N) \left(a^2 H \delta_{ij} + a^2 H h_{ij} + \frac{1}{2} a^2 \dot{h}_{ij} - a^2 (\nu_{ij} + \nu_{(ij)}) \right)$$

since $\overset{(0)}{\Gamma}_{ij}^k = \frac{1}{2} a^{-2} \delta^{kl} \left[(a^2 \delta_{li})_{,j} + (a^2 \delta_{lj})_{,i} - (a^2 \delta_{ij})_{,l} \right] = 0$

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$$K_{ij} = a^2 \left[H \delta_{ij} - H \delta N \delta_{ij} + H h_{ij} + \frac{1}{2} \dot{h}_{ij} - v_{,ij} - v_{(ij)} \right]$$

$$\begin{aligned} \text{Now } K^i_j &= g^{ik} K_{kj} = a^2 (\delta_{ik} - h_{ik}) K_{kj} \\ &= H \delta_{ij} - H \delta N \delta_{ij} \left(+ \cancel{H h_{ij}} + \frac{1}{2} \dot{h}_{ij} - v_{,ij} - v_{(ij)} \right) \\ &\quad - \cancel{H h_{ij}} \end{aligned}$$

$$\text{and } K = 3H - 3H\delta N + 3\dot{g} - \partial^2 v \quad (\partial^2 \equiv \partial_i \partial_i)$$

$$\text{c) Momentum constraint is } 0 = \partial_j K^j_i - K_{,i} - \frac{\Phi_{,i}}{N} (\dot{\Phi} - N \dot{\Phi}_{,i})$$

$$\begin{aligned} \Rightarrow 0 &= -H \delta N_{,i} + \frac{1}{2} \dot{h}_{ij,j} - \cancel{\partial^2 v_{,i}} - \frac{1}{2} \partial^2 v_{,i} + \underbrace{\Gamma_{jk}^j K^k_i - \Gamma_{ji}^k K^j_k}_{\text{as } \Gamma_{jk}^{(0)} = 0, \Gamma_{jk}^i \text{ is 1st order, so only need } K^{(0)}_i} \\ &\quad \uparrow \\ &\quad + 3H \delta N_{,i} - 3\dot{g}_{,i} + \cancel{\partial^2 v_{,i}} \end{aligned}$$

$$\text{and } \frac{1}{2} \dot{h}_{ij,j} = \dot{g}_{,i}$$

Also, $\Phi_{,i} = \delta \phi_{,i} = 0$ in conformal gauge.

$$0 = 2H \delta N_{,i} - 2\dot{g}_{,i} - \frac{1}{2} \partial^2 v_{,i} + H \left(\underbrace{\Gamma_{ji}^j}_{0} - \Gamma_{ji}^j \right)$$

$$\text{so } 0 = 2\partial_i (H \delta N - \dot{g}) - \frac{1}{2} \partial^2 v_{,i}$$

$$\left\{ \begin{array}{l} \text{Acting with } \partial^2 \partial_i \Rightarrow \delta N = \dot{g}/H \end{array} \right.$$

$$\left\{ \begin{array}{l} \text{Acting with transverse projector } \Pi_{ij} = \delta_{ij} - \frac{\partial_i \partial_j}{\partial^2} \Rightarrow v_{,i} = 0 \end{array} \right.$$

d) Hamiltonian constraint is

$$0 = \underbrace{-K^i_j K^j_i + K^2}_{\text{use results above, substituting } \delta N = \dot{g}/H \text{ and } v_{,i} = 0} - \underbrace{N^{-2} (\dot{\Phi} - N \dot{\Phi}_{,i})^2}_{\dot{\Phi}^2} + \underbrace{\sigma (-R + g^{ij} \Phi_{,i} \Phi_{,j} + 2K^2 V)}_0$$

Using results from part (b) plus $\delta N = \dot{z}/H$ and $v_i = 0$,

$$\left. \begin{aligned} K &= 3H - \partial^2 v \\ K^i_j &= H\delta_{ij} + \frac{1}{2}\dot{\gamma}_{ij} - v_{,ij} \end{aligned} \right\} -K^i_j K^j_i + K^2 = 6H^2 - 4H\partial^2 v$$

The Hamiltonian constraint is then

$$0 = \underbrace{6H^2 - \dot{\varphi}^2 + 2\sigma K^2 V(\varphi)}_{\text{background Ham. constr.}} - \underbrace{\sigma R + 2\dot{\varphi}^2 \delta N}_{\text{1st order piece}} - 4H\partial^2 v$$

$\nearrow \dot{z}/H$

Using $R = -\frac{4}{a^2}\partial^2 z$ we find $v = \epsilon\partial^{-2}\dot{z} + \frac{\sigma}{a^2 H}z$

where $\epsilon = \frac{\dot{\varphi}^2}{2H^2} = -\frac{\dot{H}}{H^2} = (1/H)'$,

Finally, we can check $R_{ij} = R^k_{ij,k} - R^k_{kji} + R^k_{ikj} - R^k_{jki}$ (quadratic order)

and $R^k_{ij} = \frac{1}{2}g^{kl}(g_{il,j} + g_{jl,i} - g_{ij,l})$

$$= \frac{1}{2}(a^{-2}\delta_{kl})\dot{a}^2(h_{il,j} + h_{jl,i} - h_{ij,l})$$

$$= \frac{1}{2}(h_{ik,j} + h_{jk,i} - h_{ij,k})$$

$$= \gamma_{ij}\delta_{ik} + \gamma_{ik}\delta_{ij} - \gamma_{ik}\delta_{ij} + \frac{1}{2}\gamma_{ik,j} + \frac{1}{2}\gamma_{jk,i} - \frac{1}{2}\gamma_{ij,k}$$

$$R_{ij} = 2\gamma_{ij} - \delta_{ij}\partial^2 z - \frac{1}{2}\partial^2\delta_{ij} - \partial_i(3\gamma_{ij} + \gamma_{ij} - \gamma_{ij})$$

$$= -\gamma_{ij} - \delta_{ij}\partial^2 z - \frac{1}{2}\partial^2\delta_{ij} \quad \text{so } R = a^{-2}\delta^{\mu\nu}R_{\mu\nu}$$

$$= -\frac{4}{a^2}\partial^2 z$$

2.1) In synchronous gauge, the momentum constraint is

$$0 = \partial_j K^j_i + \overset{(1)}{\Gamma}^j_{jk} \overset{(0)}{K}^k_i - \overset{(1)}{\Gamma}^k_{ji} \overset{(0)}{K}^j_k - K_{,i} - \delta\varphi_{,i} \dot{\varphi}$$

↖ as $\overset{(0)}{\Gamma}^i_{jk} = 0$, only need background $\overset{(0)}{K}^i_j$ here

$$K_{ij} = \frac{1}{2} \dot{g}_{ij} = a^2 (H \delta_{ij} + H h_{ij} + \frac{1}{2} \dot{h}_{ij})$$

$$\text{so } K^i_j = a^{-2} (\delta_{jk} - h_{jk}) K^k_i = H \delta_{ij} + \frac{1}{2} \dot{h}_{ij} \quad \text{and } K = 3H + \frac{1}{2} \dot{h}$$

$$\rightarrow 0 = \frac{1}{2} \dot{h}_{ij,j} + H (\overset{(1)}{\Gamma}^j_{ji} - \overset{(1)}{\Gamma}^j_{ji}) - \frac{1}{2} \dot{h}_{,i} - \dot{\varphi} \delta\varphi_{,i}$$

$$\text{Since } \dot{h}_{ij,j} = -2\dot{\varphi}_{,i} + 2\partial^2 \dot{x}_{,i} + \partial^2 \dot{\omega}_{,i} \quad \text{and } \dot{h} = -6\dot{\varphi} + 2\partial^2 \dot{x}$$

$$0 = \dot{h}_{ij,j} - \dot{h}_{,i} - 2\dot{\varphi} \delta\varphi_{,i} = \partial_i (-2\dot{\varphi} + 2\partial^2 \dot{x} + 6\dot{\varphi} - 2\partial^2 \dot{x} - 2\dot{\varphi} \delta\varphi) + \partial^2 \dot{\omega}_{,i}$$

$$\rightarrow \dot{\varphi} = \frac{1}{2} \dot{\varphi} \delta\varphi \quad \text{and } \dot{\omega}_{,i} = 0$$

(b) The Hamiltonian constraint is

$$0 = -K^i_j K^j_i + K^2 - (\dot{\varphi} + \delta\dot{\varphi})^2 + \sigma (-R + g^{ij} \delta\varphi_{,i} \delta\varphi_{,j} + 2\kappa^2 V(\varphi) + 2\kappa^2 V'(\varphi) \delta\varphi)$$

$$= -(3H^2 + H\dot{h}) + (9H^2 + 3H\dot{h}) - (\dot{\varphi}^2 + 2\dot{\varphi} \delta\dot{\varphi}) + \sigma (-R + 2\kappa^2 V + 2\kappa^2 V' \delta\varphi)$$

$$= \underbrace{(6H^2 - \dot{\varphi}^2 + 2\sigma\kappa^2 V)}_{\text{background}} + 2H\dot{h} - 2\dot{\varphi} \delta\dot{\varphi} - \sigma R + 2\kappa^2 V' \sigma \delta\varphi$$

$$\text{From earlier, } \overset{(1)}{R}_{ij} = \overset{(1)}{\Gamma}^k_{j,i} \overset{(0)}{K}^k_j - \overset{(1)}{\Gamma}^k_{ji} \overset{(0)}{K}^j_k = \frac{1}{2} (h_{ik,jh} + h_{jk,ih} - \partial^2 h_{ij}) - \frac{1}{2} (h_{,ij} + h_{j,i} - h_{j,i})$$

$$\text{so } \overset{(1)}{R} = \frac{1}{2} a^{-2} (2h_{ij,jj} - 2\partial^2 h) = a^{-2} (-2\partial^2 \varphi + 2\partial^2 x - \partial^2 (-6\varphi + 2\partial^2 x)) = \frac{4}{a^2} \partial^2 \varphi$$

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$$\Rightarrow \dot{h} = \frac{2\sigma}{a^2 H} \delta^2 \psi + \frac{\dot{\varphi}}{H} \delta \dot{\varphi} - \sigma \frac{\kappa^2 V'(\varphi)}{H} \delta \varphi$$

Since $\dot{h} = -6\dot{\varphi} + 2\partial^2 \dot{\chi} = -3\dot{\varphi} \delta \varphi + 2\partial^2 \dot{\chi}$

$$\Rightarrow \partial^2 \dot{\chi} = \frac{\sigma}{a^2 H} \delta^2 \psi + \frac{\dot{\varphi}}{2H} \delta \dot{\varphi} + \left(\frac{3}{2} \dot{\varphi} - \sigma \frac{\kappa^2 V'(\varphi)}{2H} \right) \delta \varphi$$

2.2) Holographic stress tensor ($\sigma = +1$)

$$\kappa^2 \delta \langle T_{ij} \rangle = (\delta K \delta_{ij} - \delta K^k_j)_{(3)} = \frac{1}{2} (\dot{h} \delta_{ij} - \dot{h}_{ij})_{(3)}$$

$$= \frac{1}{2} \left(\left(\frac{2}{a^2 H} \delta^2 \psi + \frac{\dot{\varphi}}{H} \delta \dot{\varphi} \right) \delta_{ij} + (\dots) \delta \varphi \right.$$

$$\left. - \left(-2\dot{\varphi} \delta_{ij} + 2\dot{\chi}_{,ij} + 2\dot{\varphi} \delta_{(ij)} + \dot{\delta}_{ij} \right) \right)_{(3)}$$

$$- \dot{\varphi} \delta \varphi$$

from
momentum
constraint

$$\dot{\varphi} \approx (\dots) \delta \varphi$$

as momentum constraint $\Rightarrow \dot{\omega}_i = 0$

from Hamiltonian constraint

$$2\dot{\chi}_{,ij} = 2\partial^2 \partial_i \partial_j \left\{ \frac{1}{a^2 H} \psi + \frac{\dot{\varphi}}{2H} \delta \varphi + (\dots) \delta \varphi \right.$$

$$\left. = \frac{1}{2} \left(\left(\frac{2}{a^2 H} \delta^2 \psi + \frac{\dot{\varphi}}{H} \delta \dot{\varphi} \right) \pi_{ij} + (\dots) \delta \varphi - \dot{\delta}_{ij} \right)_{(3)} \right.$$

transverse projector $\pi_{ij} = \delta_{ij} - \frac{\partial_i \partial_j}{\partial^2}$

$$\dot{z} = \left(-\psi - \frac{H}{\dot{\varphi}} \delta \varphi \right)$$

(or in momentum space,

$$= (\dots) \delta \varphi - \frac{H}{\dot{\varphi}} \delta \dot{\varphi}$$

$$\pi_{ij} = \delta_{ij} - \frac{\bar{q}_i \bar{q}_j}{\bar{q}^2}$$

but also, $\dot{z} = \frac{1}{2a^3 \epsilon} \pi^{(3)} = \frac{\bar{\Omega}}{2a^3 \epsilon} z = -\frac{\bar{\Omega}}{2a^3 \epsilon} \psi + (\dots) \delta \varphi$

hence $\delta \dot{\varphi} = \frac{\varphi}{2a^3 \epsilon H} \bar{\Omega} \psi + (\dots) \delta \varphi = \frac{H}{a^3 \dot{\varphi}} \bar{\Omega} \psi + (\dots) \delta \varphi$

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recalling that $\epsilon = \frac{\dot{\varphi}^2}{2H^2}$. Noting also that

$$\pi_{ij} = \frac{1}{4} a^3 \dot{\gamma}_{ij} = \bar{E} \gamma_{ij} \quad \Rightarrow \quad \dot{\gamma}_{ij} = \frac{4\bar{E}}{a^3} \gamma_{ij}$$

we have

$$\bar{K}^2 \delta \langle T_{ij}^i \rangle = \left[\left(\frac{1}{a^2 H} \dot{\gamma} \psi + \frac{\bar{\Omega}}{2a^3} \psi \right) \pi_{ij} - \frac{2\bar{E}}{a^3} \gamma_{ij} + (\dots) \delta \varphi \right]_{-13}$$

or in momentum space,

$$\delta \langle T_{ij}^i(\vec{q}) \rangle = \bar{K}^{-2} \left[\left(\frac{-\vec{q}^2}{a^2 H} + \frac{\bar{\Omega}}{2a^3} \right) \psi \pi_{ij} - \frac{2\bar{E}}{a^3} \gamma_{ij} + (\dots) \delta \varphi \right]_{0;}$$

weight 2 at leading order;
removed with counterterm

Since the scale factor is weight minus one (ie. $a \rightarrow e^z$ as $z \rightarrow \infty$)

$$\delta \langle T_{ij}^i(\vec{q}) \rangle = \bar{K}^{-2} \left[\underbrace{\frac{1}{2} \bar{\Omega}(\omega) \psi(\omega) \pi_{ij}}_{-2B(\vec{q})} - \underbrace{2\bar{E}(\omega) \gamma_{ij}}_{\frac{1}{2}A(\vec{q})} + (\dots) \delta \varphi \right]$$

$$\text{so } \langle T(\vec{q}) T(-\vec{q}) \rangle = 4B(\vec{q}) = -\bar{K}^{-2} \bar{\Omega}(\omega)(\vec{q})$$

$$\langle T_{(q)}^{(s)} T_{(-q)}^{(s')} \rangle = \frac{1}{2} \delta^{ss'} A(\vec{q}) = -2\bar{K}^{-2} \bar{E}(\omega)(\vec{q}) \delta^{ss'}$$

Key point: the stress tensor 2-point function in the dual QFT can be read off from the weight zero pieces of the response functions. These are just the values as $z \rightarrow \infty$ after removing ~~counter~~ any negative weight pieces with counter terms.

$$3) a) \beta = \frac{d\varphi}{d\ln\Lambda} = -\lambda\varphi + 2\pi c\varphi^2 = 2\pi c\varphi(\varphi - \varphi_1) \quad \varphi_1 = \frac{\lambda}{2\pi c}$$

$$\begin{aligned} \ln \Lambda/\Lambda_0 &= -\frac{1}{2\pi c} \int_{\varphi_0}^{\varphi} d\varphi \frac{1}{\varphi(\varphi - \varphi_1)} = -\frac{1}{\lambda} \int_{\varphi_0}^{\varphi} d\varphi \left(\frac{1}{\varphi - \varphi_1} - \frac{1}{\varphi} \right) \\ &= -\frac{1}{\lambda} \ln \frac{(\varphi - \varphi_1)\varphi_0}{(\varphi_0 - \varphi_1)\varphi} = -\frac{1}{\lambda} \ln \left(\frac{1 - \varphi_1/\varphi}{1 - \varphi_1/\varphi_0} \right) \end{aligned}$$

$$\Rightarrow \varphi = \frac{\varphi_1}{1 + \left(\frac{\varphi_1}{\varphi_0} - 1\right)\left(\frac{\Lambda}{\Lambda_0}\right)^{-\lambda}} \rightarrow \frac{\varphi_1}{\left(\frac{\varphi_1}{\varphi_0} - 1\right)\Lambda_0^{\lambda}} \quad \Lambda^{\lambda} \rightarrow \Lambda \rightarrow 0 \quad \varphi = \varphi_1$$

$$\text{hence } \varphi = \frac{\varphi_1}{1 + \frac{\varphi_1}{\varphi} \Lambda^{-\lambda}}$$

b) Under a variation $\delta\Lambda$ of the cut-off lengthscale, assuming the 1-point function $\langle O \rangle_0$ in the UV CFT vanishes, expanding $Z = \langle e^{-\int \varphi O} \rangle_0$ we find

$$\begin{aligned} \delta_{\Lambda} Z &= \delta_{\Lambda} \left(\frac{1}{2} \varphi^2 \Lambda^{-2\lambda} \int d^3x_1 \int d^3x_2 \langle O(x_1) O(x_2) \rangle_0 \right. \\ &\quad \left. - \frac{1}{6} \varphi^3 \Lambda^{-3\lambda} \int d^3x_1 \int d^3x_2 \int d^3x_3 \langle O(x_1) O(x_2) O(x_3) \rangle_0 + \dots \right) \end{aligned}$$

$$= \left(-\varphi \beta \frac{\delta\Lambda}{\Lambda} \Lambda^{-2\lambda} - 2\lambda \cdot \frac{1}{2} \varphi^2 \Lambda^{-2\lambda} \frac{\delta\Lambda}{\Lambda} + \frac{1}{6} \varphi^3 \Lambda^{-3\lambda} \left(\frac{3c}{\Lambda^{3-\lambda}} 4\pi\Lambda^2 \delta\Lambda \right) \right)$$

variation of $\varphi(\Lambda)$ in 2-pt contribution

$$\delta\varphi = -\beta \frac{\delta\Lambda}{\Lambda}$$

variation of explicit $\Lambda^{-2\lambda}$ in 2-pt contribution

$$\times \int d^3x_1 \int d^3x_2 \langle O(x_1) O(x_2) \rangle_0 + \dots$$

collision contribution from 3-point function: use $O O \sim \frac{c}{\Lambda^{3-\lambda}} O$ part of OPE.

The factor of 3 is because there are three distinct collisions ($1 \leftrightarrow 2$, $2 \leftrightarrow 3$, $3 \leftrightarrow 1$). The + sign is because we lose this contribution by increasing Λ (and we had $-\frac{1}{6} \varphi^3 \Lambda^{-3} \int \int \int \langle 000 \rangle_0$ to begin with).

The $4\pi \Lambda^2 \delta\Lambda$ is the shell volume.

$$\delta_n z = \varphi \frac{\delta\Lambda}{\Lambda} \Lambda^{-2} \underbrace{(-\beta - \lambda\varphi + 2\pi C\varphi^2)}_{\text{for } \delta_n z = 0,} \int \delta_{n_1} \delta_{n_2}^3 \langle 0_{n_1} 0_{n_2} \rangle_0 + \dots$$

$$\text{for } \delta_n z = 0, \quad \beta = -\lambda\varphi + 2\pi C\varphi^2.$$

See 1211.4550 and 1308.0331 for further discussion of this system.