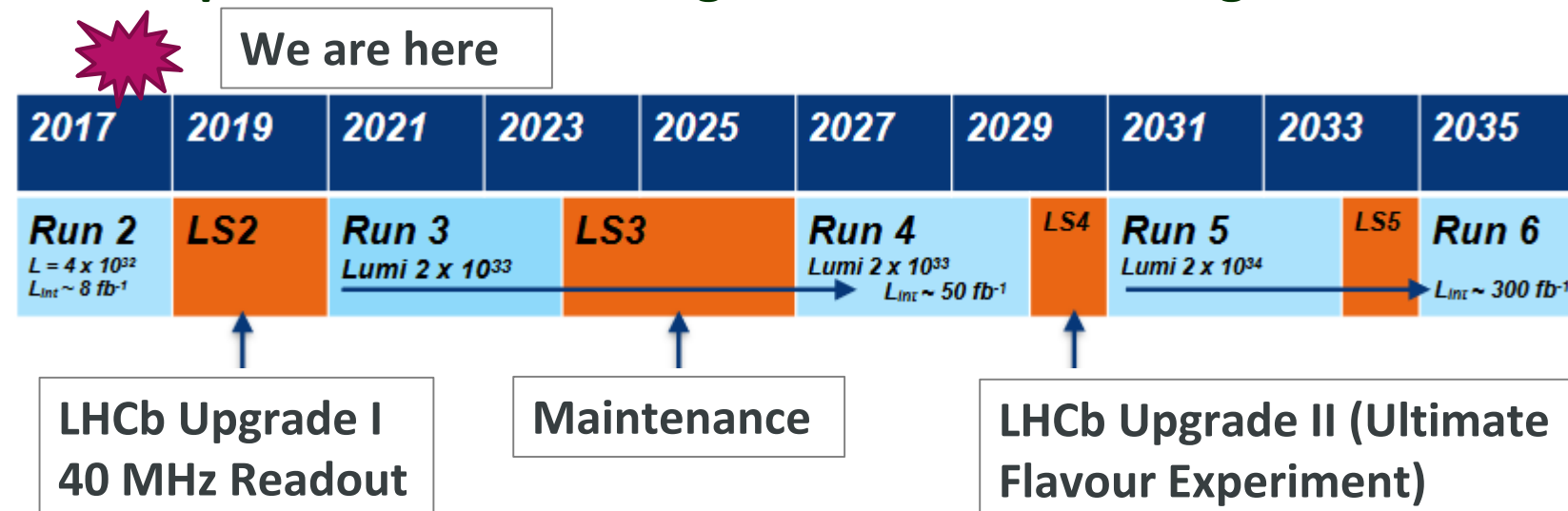


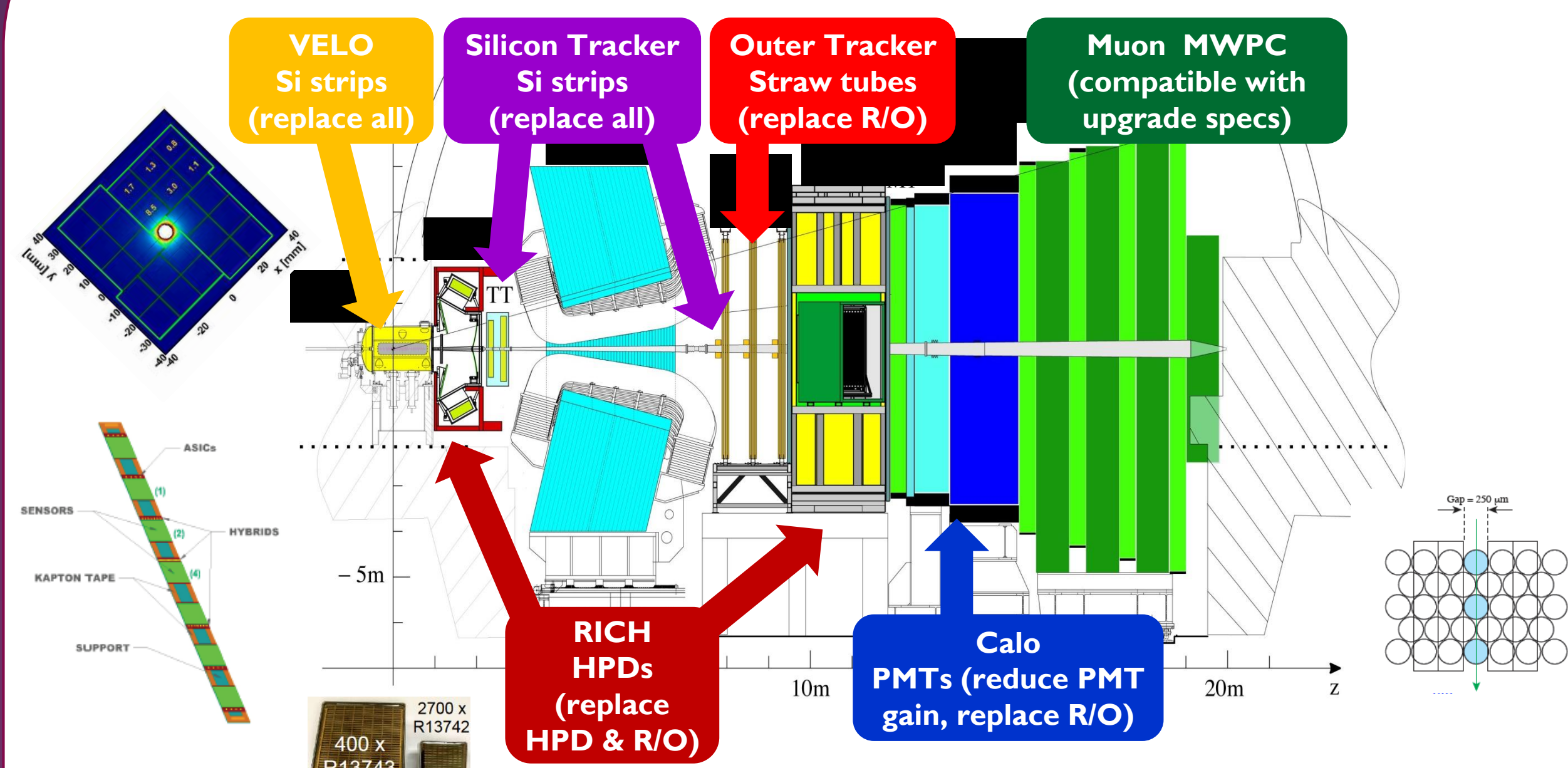
LHCb Upgrade Plan

- Installation planned for the Long Shutdown 2 starting in 2019



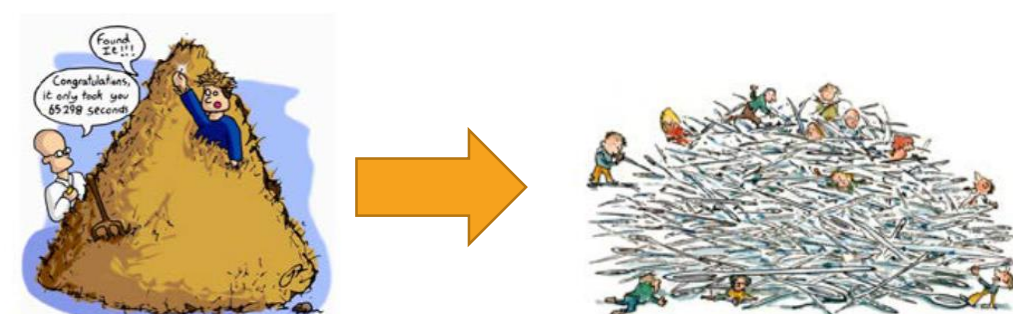
- Need to remove hardware trigger (L0), i.e., move from the full detector readout done @1 MHz to 40 MHz one
- The upgraded LHCb must cope with up to five times higher inst. luminosity relative to Run II ($\mathcal{L} = 2 \cdot 10^{33} \text{ cm}^{-2}\text{s}^{-1}$)
- Triggerless readout with the **full software trigger** that requires real-time calibration and alignment
- Offline-like reconstruction run in real time
- Use Run II trigger system as a testbed for new techniques for Run III
- Huge Challenge, but we are on track!**

Our „new” detector



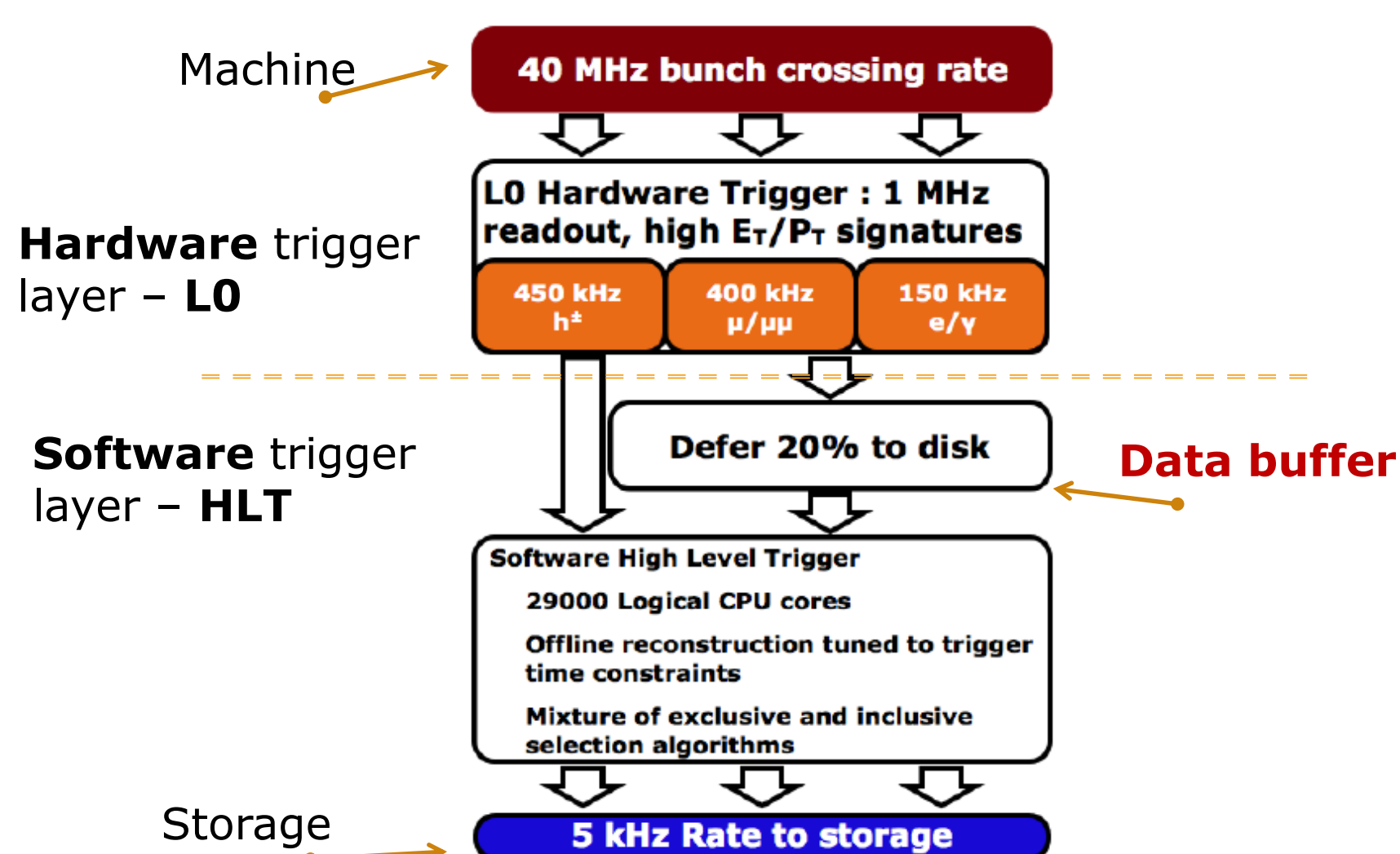
- Completely new tracking system – pixel vertex detector, new strip and scintillating fibre trackers
- New custom made electronics capable to process data on-detector at machine clock (40 MHz)

LHCb Trigger (R)Evolution



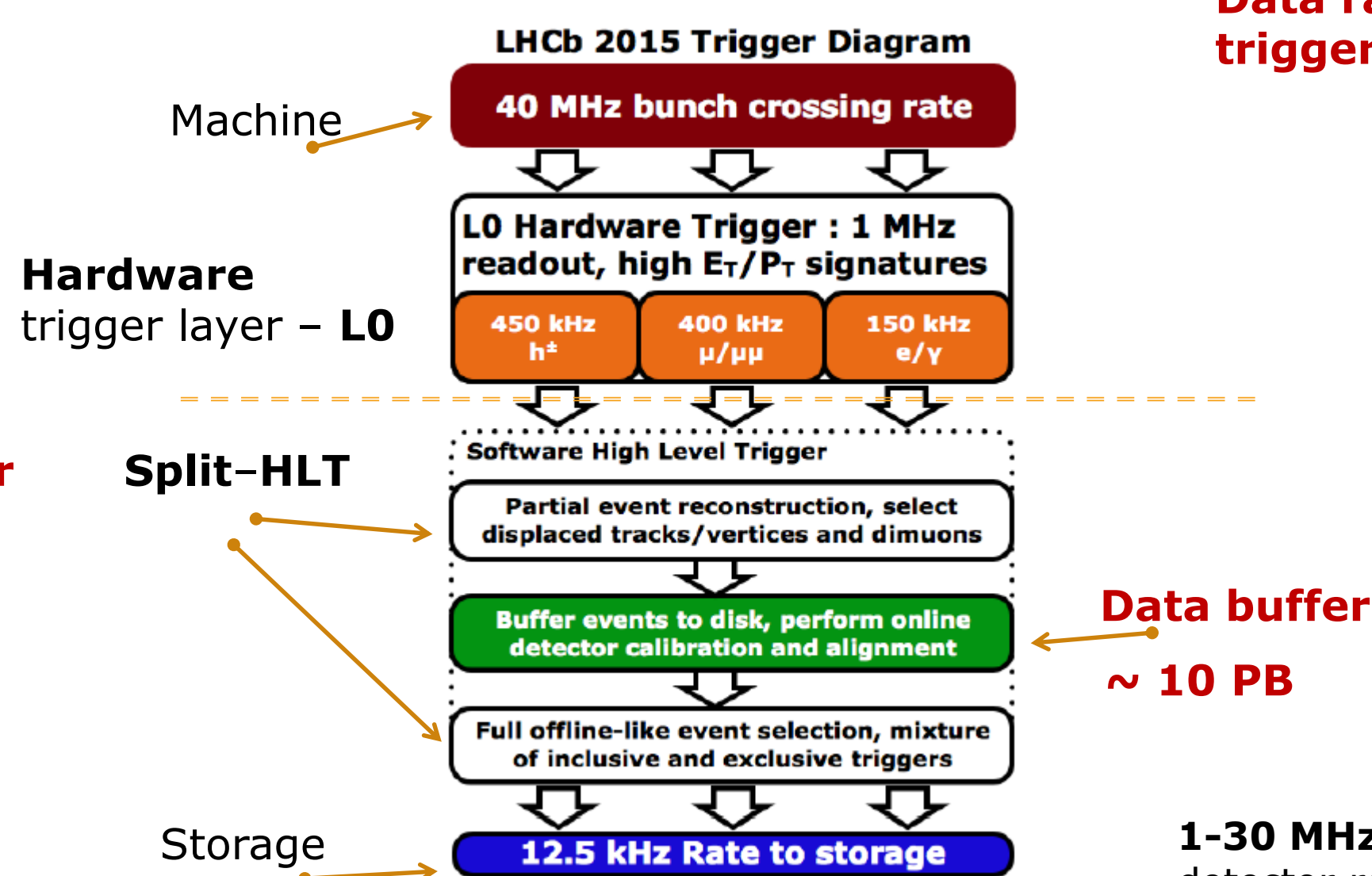
Upgrade luminosity means no trivial background rejection:
every event contains a beauty, charm or hyperon decay.
Signal categorisation instead of background rejection.

Run I evolution from 2 to 5 kHz



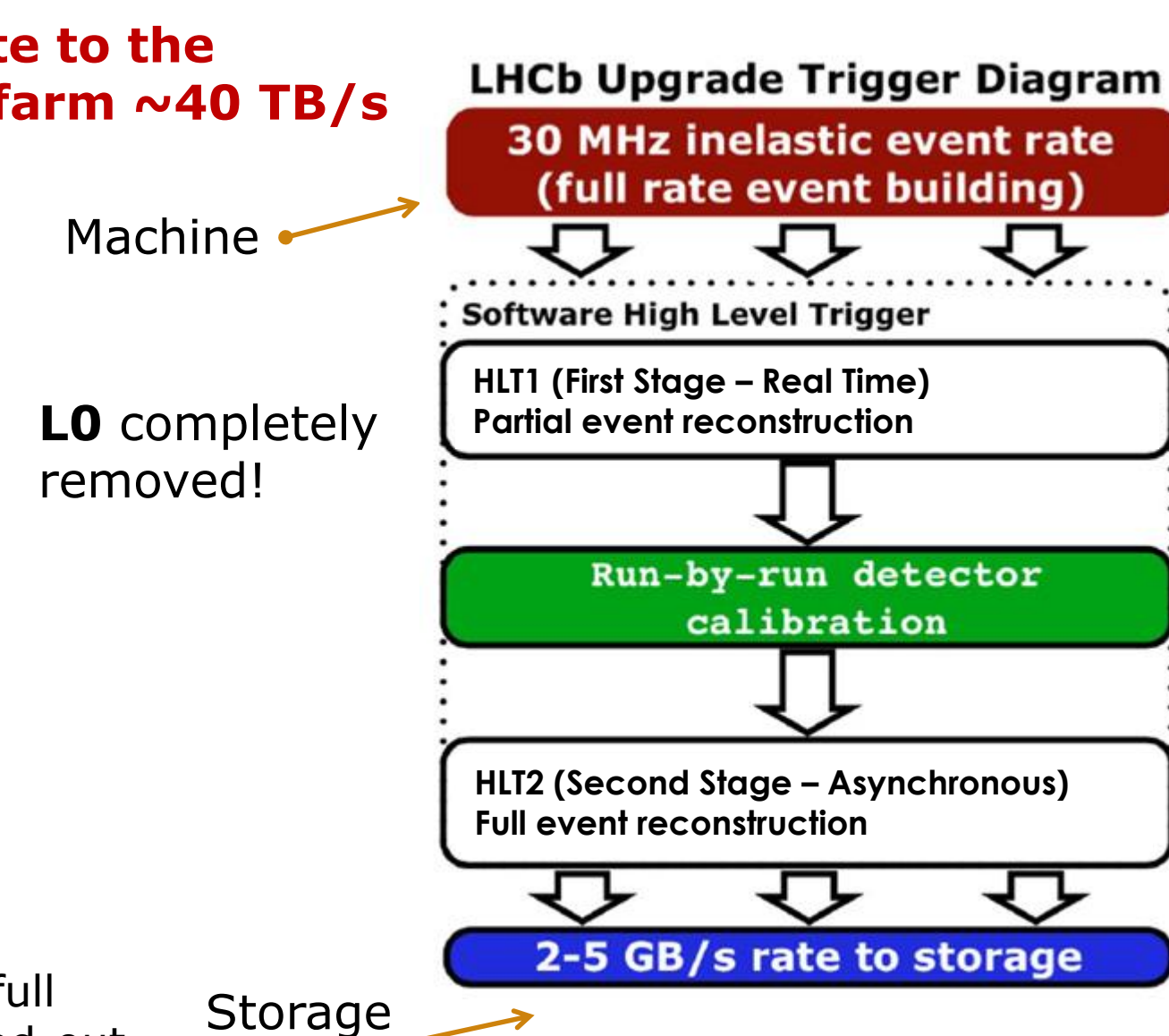
- 1.1 MHz full detector read-out
- Data partially deferred

Current Run II trigger system



- 1.1 MHz full detector read-out
- HLT is split, real-time calibration and alignment
- Offline-like quality tracking and selections in trigger

Run III (upgraded) trigger

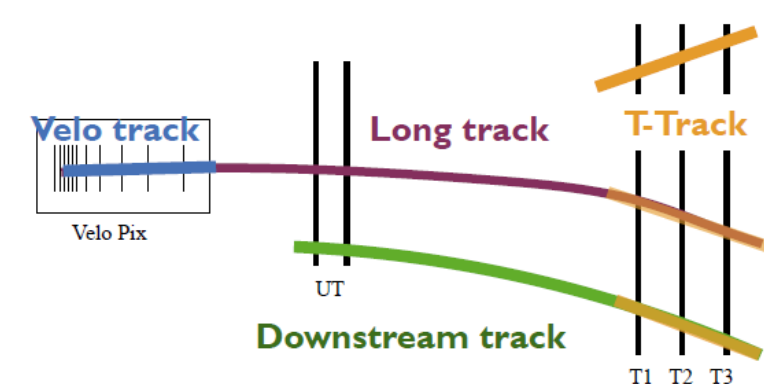


- 30 MHz full detector read-out
- Full-software system
- Time constraints crucial!

Latest developments for upgrade Trigger

HLT1

- Partial event reconstruction only
 - Data preparation for tracking (unpacking/reformatting)
 - Track reconstruction
 - Initial pre-selection to reduce the rate to 500 – 1000 kHz



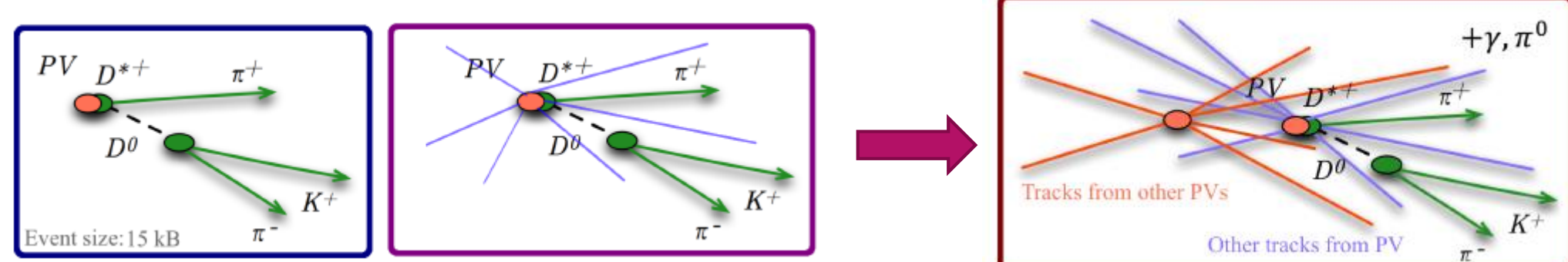
HLT2

- Full event reconstruction
 - Tracking performance with the offline quality
 - Particle identification information available based on fill-by-fill calibration – background rejection
 - Offline quality event selections

- Calibration process takes $\mathcal{O}(\text{minutes})$
- Data stored in the buffer can be parked for $\mathcal{O}(\text{days})$

TURBO

- Facing the inevitable – finite budget for computing resources – TURBO data stream
 - Cannot afford to **store all raw data offline**
 - Cannot afford to **re-process** (e.g., offline reconstruction)



Being fast and smart

Concurrent s/w framework

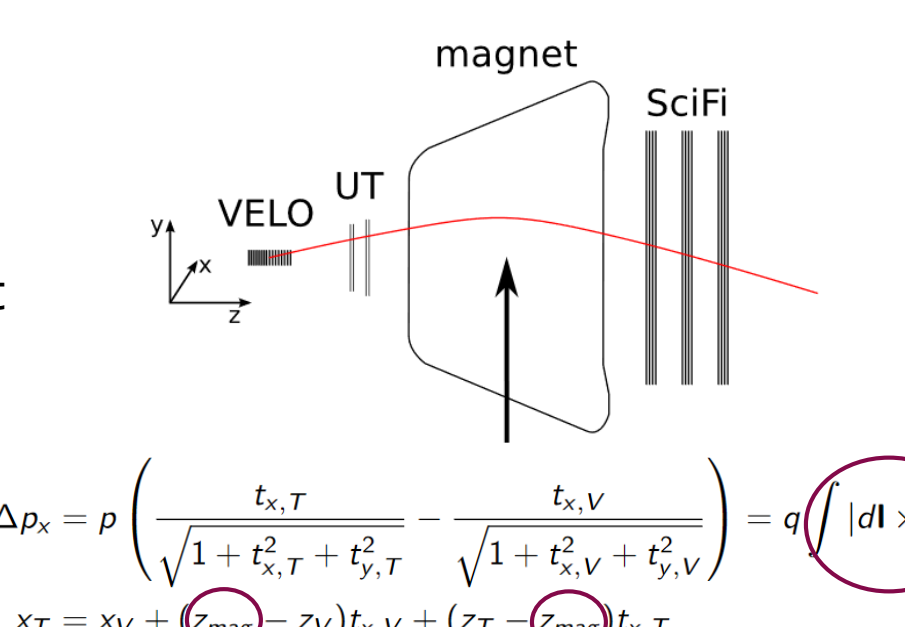
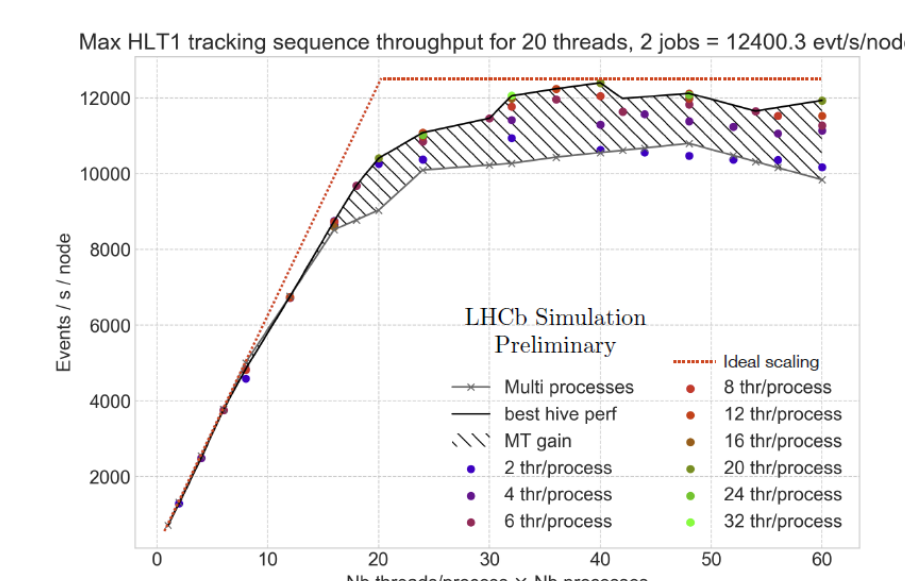
- Multi-threaded framework using task-based model
 - Use commercially available multi-core CPU architectures
 - Better scalability in memory usage
 - Initial tests show ~20% extra speed-up in the reconstruction

Parametrised Kalman Fitter

- Kalman filter approach for tracking very successful, but
 - Very CPU intensive matrix algebra (can be sped-up)
 - Material locator still remains – memory intensive, cannot be easily reduced
- The possible solution is **parametrised** Kalman
- Reduce complicated field propagation and material lookup using a handful of parameters $\mathcal{O}(20)$

Simplified Geometry

- The full detector model is very complex $\mathcal{O}(10^6)$ volumes
 - Navigating through such structure can be very slow
 - Provide much simpler model ($\mathcal{O}(30)$ volumes) with large volumes filled with mixed materials that give the same multiple scattering and energy loss



$$\Delta p_x = p \left(\frac{t_{x,T}}{\sqrt{1+t_{x,T}^2+t_{y,T}^2}} - \frac{t_{x,V}}{\sqrt{1+t_{x,V}^2+t_{y,V}^2}} \right) = q \left(\int |d\mathbf{l} \times \mathbf{B}| \right)$$

$$x_T = x_V + (z_{mag} - z_V) t_{x,V} + (z_T - z_{mag}) t_{x,T}$$

