Outline

- Motivation
  - α_s extraction (see Vincent's talk)
  - Soft drop thrust
  - Bottom-up soft drop (BUSD)

- Fixed-order (EVENT2)
  - Other event shapes
  - Local BUSD vs Global BUSD
  - Modification of observables

- Monte Carlo (Pythia)
  - Reduction in NP effects

Introduction

- Some α_s-extractions contaminated by N.P. effects
  - Often determined by event shapes from LEP
  - Results in tension with lattice QCD
- Soft drop useful for reduction of N.P. effects
  - Invented and mostly used for LHC

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- Some α_s-extractions contaminated by N.P. effects
  - Often determined by event shapes from LEP
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- Soft drop useful for reduction of N.P. effects
  - Invented and mostly used for LHC
- Is soft drop natural for event shapes?
  - Event shapes are event-wide parameters (global)
  - Soft drop is locally applied groomer
- Generalized grooming scheme for event shapes?
  - Akin to CAESAR/ARES

Soft-Drop algorithm

- $\frac{\min(E_1,E_2)}{E_1+E_2} > z_{\text{cut}}\left(1-\cos(\theta_{12})\right)^{\beta/2}$ for e^+e^-
- $\frac{\min(p_{T1},p_{T2})}{p_{T1}+p_{T2}} > z_{\text{cut}}\left(\frac{\Delta R_{12}}{R}\right)^{\beta}$ for pp

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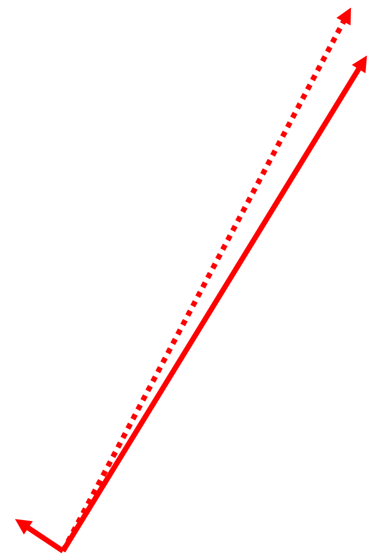

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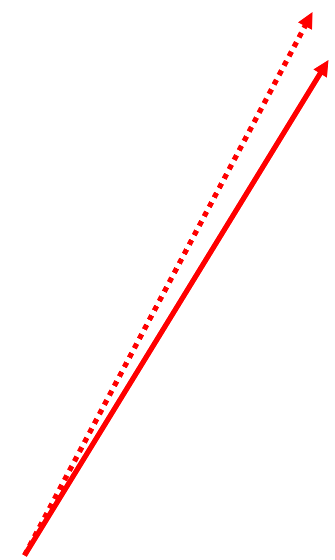

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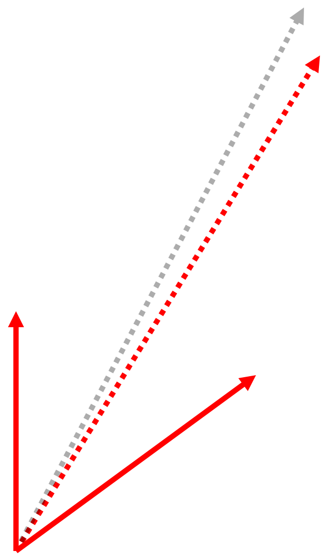

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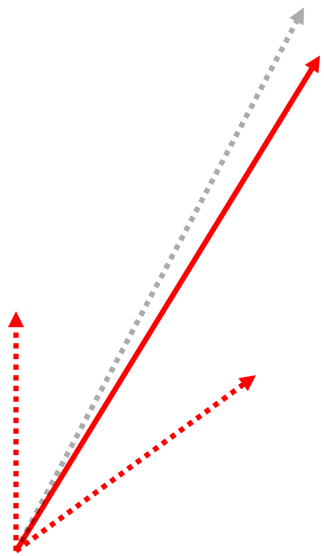

Larkoski, Marzani, Soyez, Thaler: Soft Drop (2014)

Soft-Drop Thrust

- For an event ε, thrust is defined to be

$$T = \max_{\vec{n}} \left(\frac{\sum_{i \in \varepsilon} |\vec{n} \cdot \vec{p}_i|}{\sum_{i \in \varepsilon} |\vec{p}_i|} \right)$$

- Soft-Drop thrust is defined as:

$$T_{\mathrm{SD}} = \max_{\vec{n}} \left(\frac{\sum_{i \in \varepsilon_{\mathrm{SD}}} |\vec{n} \cdot \vec{p}_i|}{\sum_{i \in \varepsilon_{\mathrm{SD}}} |\vec{p}_i|} \right)$$

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- Soft-Drop thrust is defined as:
    1. Calculate the the thrust axis
    2. Divide event into left/right hemispheres
    3. Apply soft-drop on each hemisphere separately
    4. The remaining particles constitute soft-dropped event $\varepsilon_{\mathrm{SD}}$

$$T_{\mathrm{SD}} = \max_{\vec{n}} \left(\frac{\sum_{i \in \varepsilon_{\mathrm{SD}}} |\vec{n} \cdot \vec{p}_i|}{\sum_{i \in \varepsilon_{\mathrm{SD}}} |\vec{p}_i|} \right)$$

Soft-Drop Thrust (Redefined)

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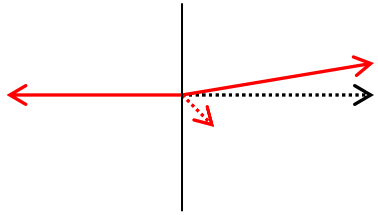

Expect: $T = 1$ for 2-particle back-to-back event

- Small problem: consider 3-particle event..
  - $q\bar{q}$g with $E_g \ll E_q \approx E_{\bar{q}}$
  - E_g groomed away

Soft-Drop Thrust (Redefined)

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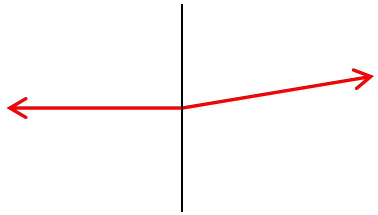


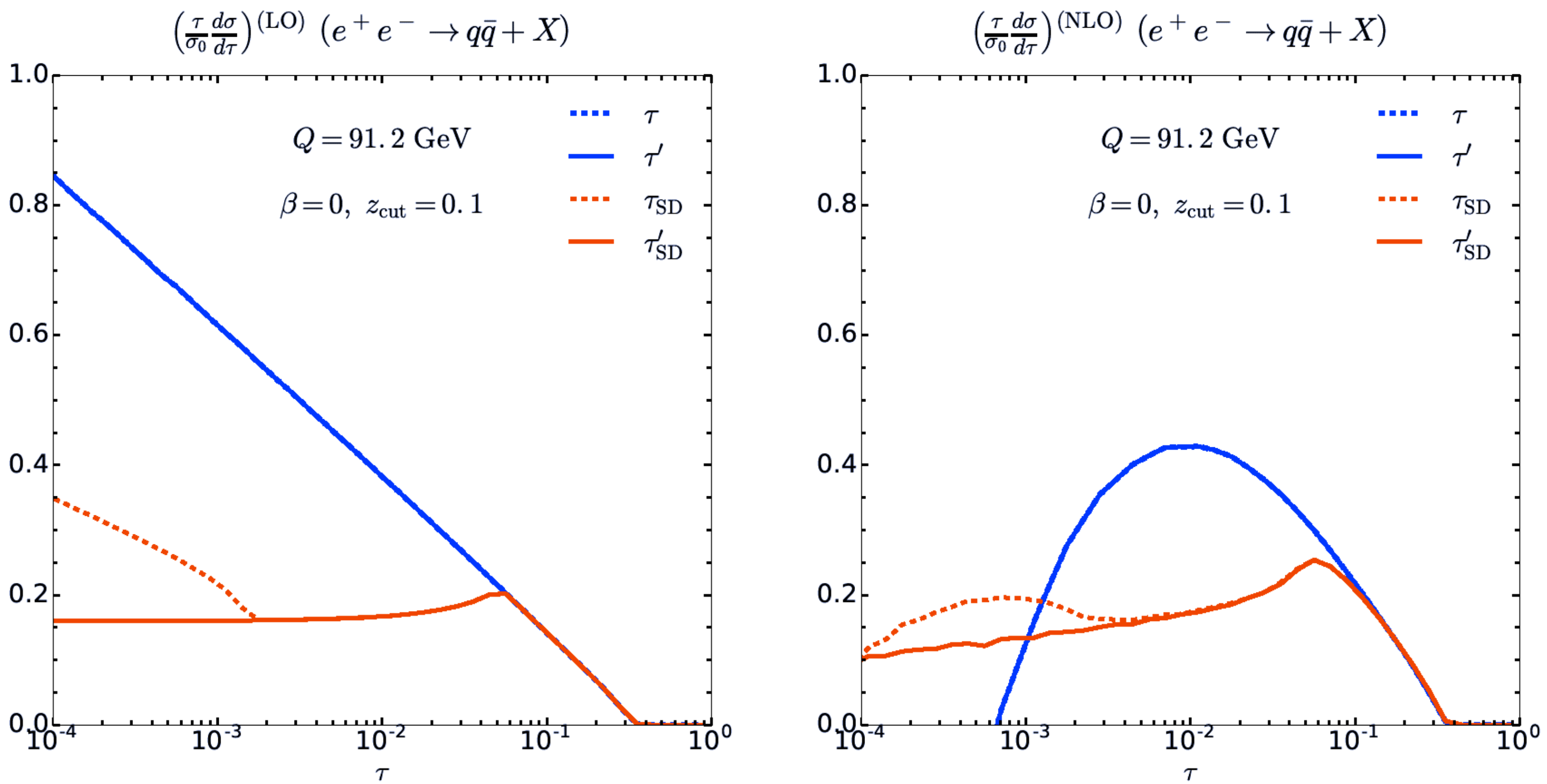
Expect: $T = 1$ for 2-particle back-to-back event

- Small problem: consider 3-particle event..
  - $q\bar{q}\mathrm{g}$ with $E_g \ll E_q \approx E_{\bar{q}}$
  - E_g groomed away
  - $T_{\mathrm{SD}} \neq 1$ for remaining 2-particle event (bad!!!)
  - Redefine:

$$T'_{\mathrm{SD}} = \frac{\sum_{i\in\mathcal{H}^{\mathrm{L}}_{\mathrm{SD}}} |\vec{n}_L\cdot\vec{p}_i|}{\sum_{i\in\varepsilon_{SD}} |\vec{p}_i|} + \frac{\sum_{i\in\mathcal{H}^{\mathrm{R}}_{\mathrm{SD}}} |\vec{n}_R\cdot\vec{p}_i|}{\sum_{i\in\varepsilon_{SD}} |\vec{p}_i|}$$

- $\vec{n}_{\mathrm{L}}$ and $\vec{n}_{\mathrm{R}}$ are jet axes.
- $\mathcal{H}^L, \mathcal{H}^R$ are left and right hemispheres

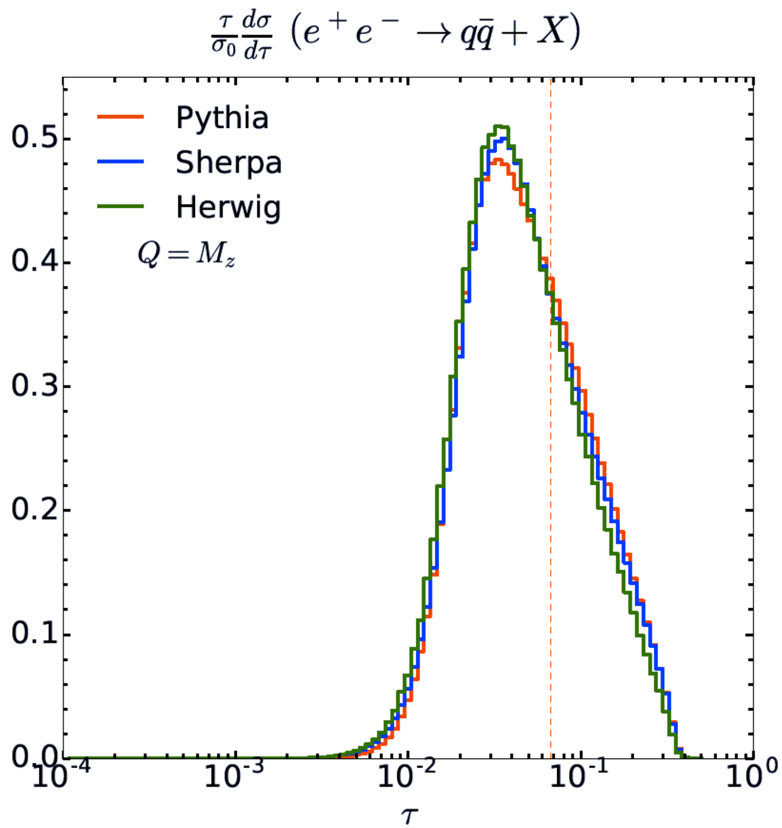
Fixed Order

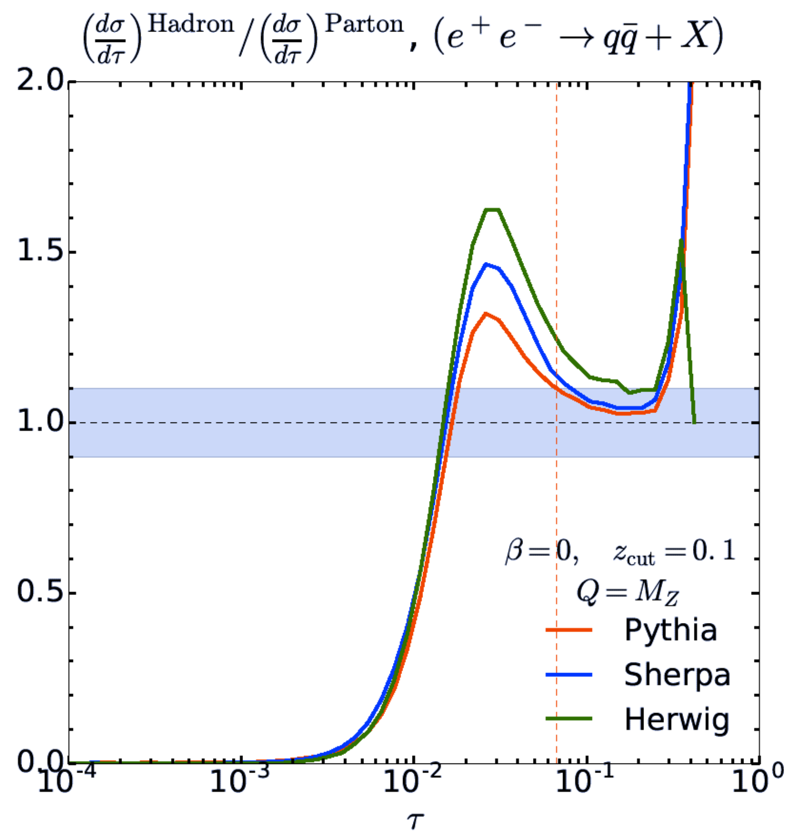


JB, Marzani, Theeuwes
Soft Drop Thrust (2018)

Note: $\tau = 1 - T$

Parton Shower





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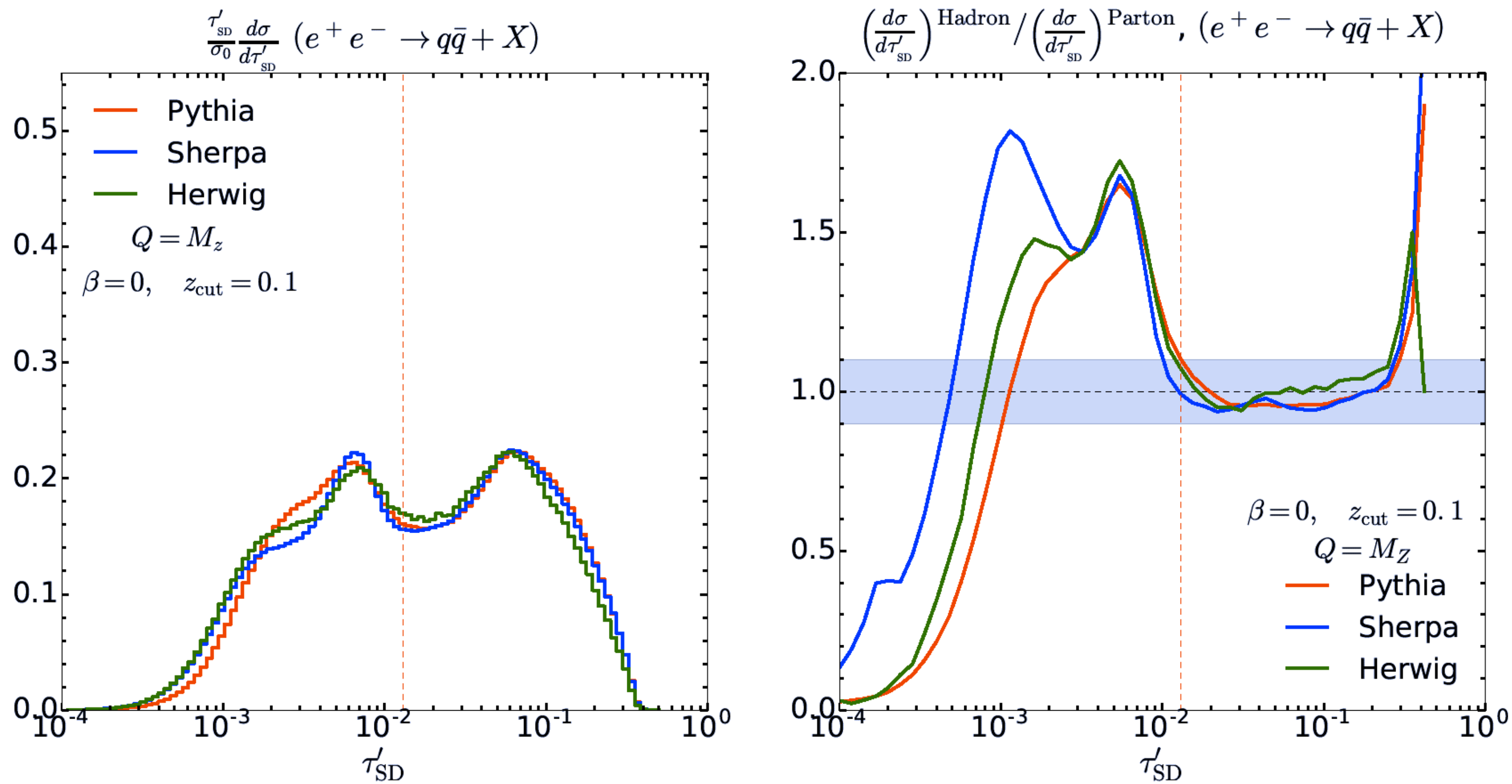

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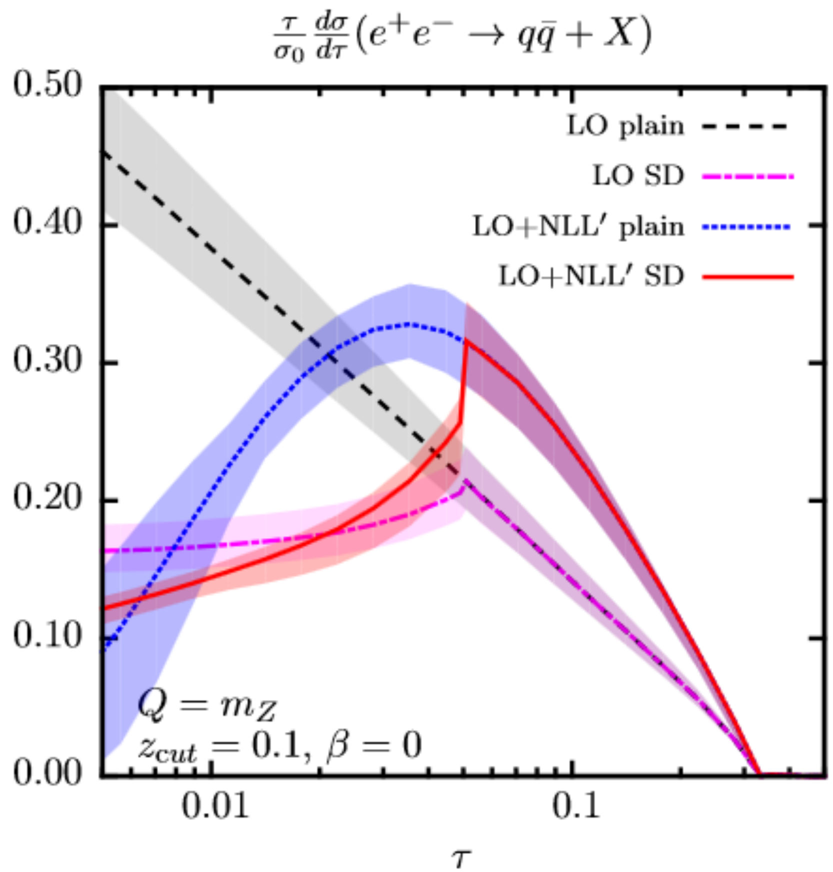
Resummation+Matching



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Bottom-up soft drop

- $\frac{\min(E_1,E_2)}{E_1+E_2} > z_{\text{cut}}\left(1-\cos(\theta_{12})\right)^{\beta/2}$ for e^+e^-
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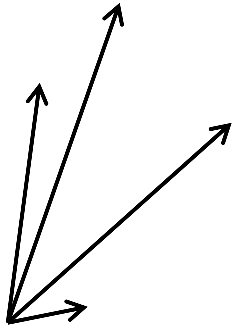

Dreyer, Necib, Soyez, Thaler: Recursive Soft Drop

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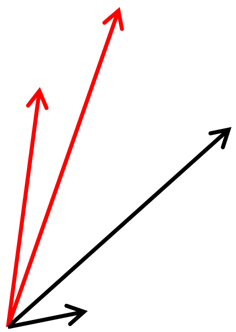

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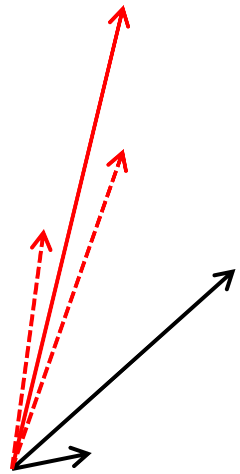

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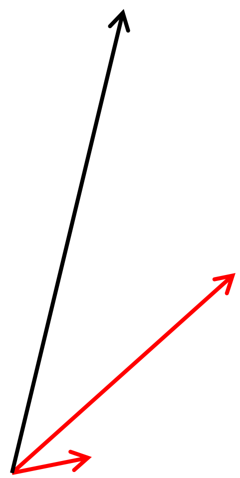

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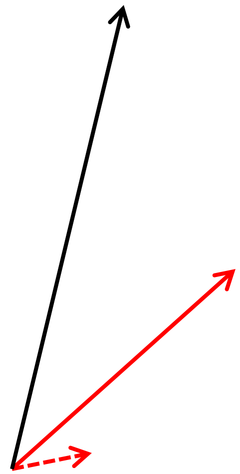

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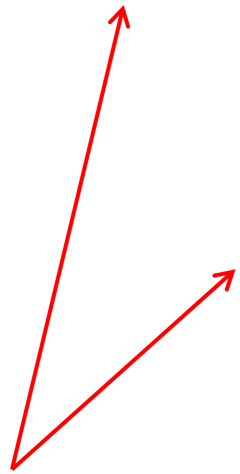

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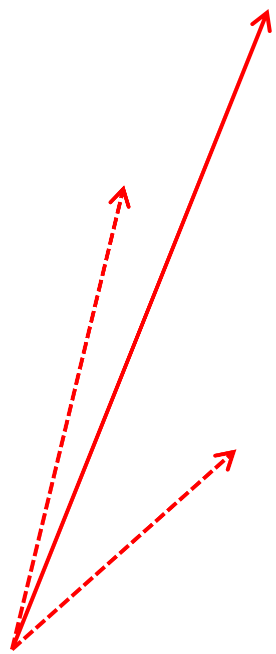

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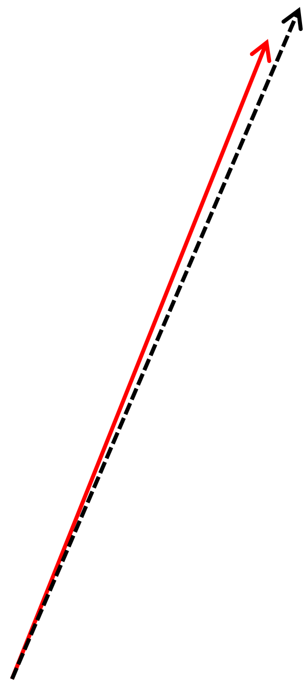
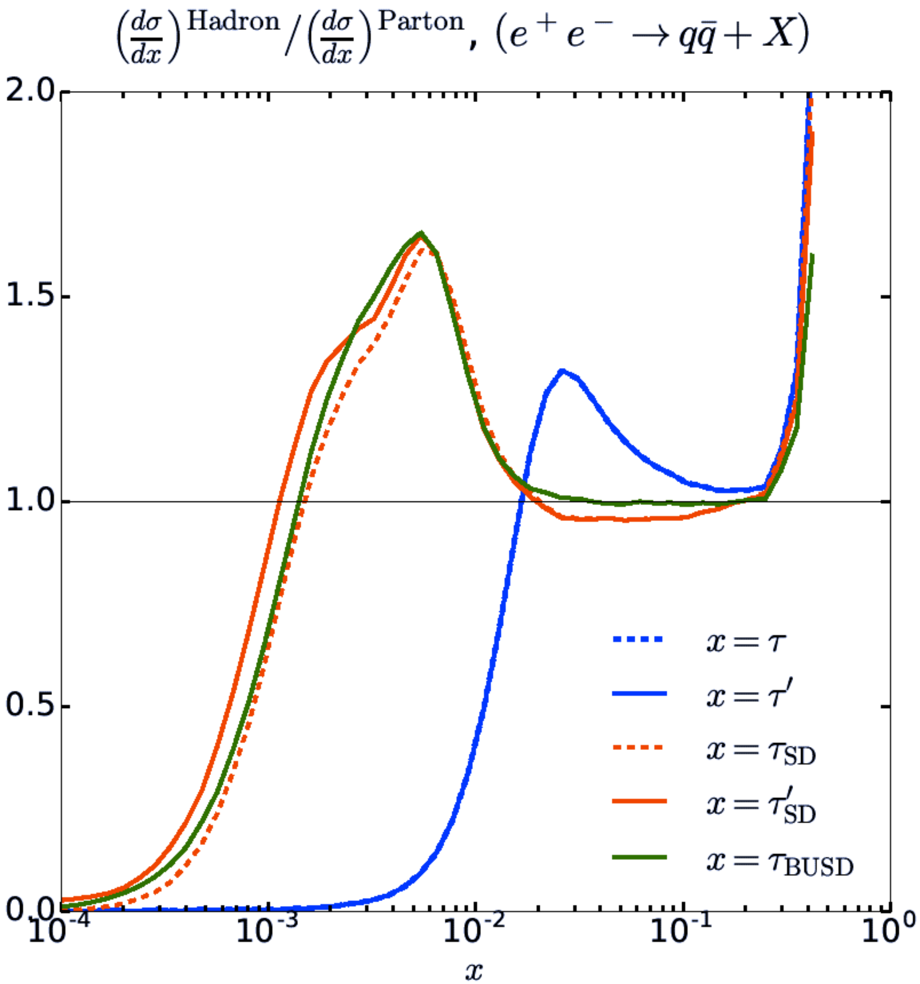


Dreyer, Necib, Soyez, Thaler: Recursive Soft Drop

Bottom-up soft drop thrust



τ is naïve definition

τ' is new definition

New definition matches old in region of interest

Soft drop is more resilient against hadronization!
(Global BUSD even better)

$$T'_{\text{SD}} = \frac{\sum_{i \in \mathcal{H}^{\text{L}}_{\text{SD}}} |\vec{n}_L \cdot \vec{p}_i|}{\sum_{i \in \varepsilon_{SD}} |\vec{p}_i|} + \frac{\sum_{i \in \mathcal{H}^{\text{R}}_{\text{SD}}} |\vec{n}_R \cdot \vec{p}_i|}{\sum_{i \in \varepsilon_{SD}} |\vec{p}_i|}$$

Other event shapes

Thrust

- $\tau = \min_{\vec{n}} \left(1 - \frac{\sum_{i \in \varepsilon} |\vec{n} \cdot \vec{p}_i|}{\sum_{i \in \varepsilon} |\vec{p}_i|} \right)$

Other event shapes

Thrust, Jet broadening

- $\tau = \min_{\vec{n}} \left(1 - \frac{\sum_{i \in \varepsilon} |\vec{n} \cdot \vec{p}_i|}{\sum_{i \in \varepsilon} |\vec{p}_i|} \right)$

- $B = B_L + B_R = \frac{1}{2} \frac{\sum_{i \in \mathcal{H}L} |\vec{n} \times \vec{p}_i|}{\sum_{i \in \varepsilon} |\vec{p}_i|} + \frac{1}{2} \frac{\sum_{i \in \mathcal{H}R} |\vec{n} \times \vec{p}_i|}{\sum_{i \in \varepsilon} |\vec{p}_i|}$

Other event shapes

Thrust, Jet broadening, C-parameter

- $\tau = \min_{\vec{n}} \left(1 - \frac{\sum_{i\in\varepsilon} |\vec{n}\cdot\vec{p}_i|}{\sum_{i\in\varepsilon}|\vec{p}_i|} \right)$
- $B = B_L + B_R = \frac{1}{2}\frac{\sum_{i\in\mathcal{H}L} |\vec{n}\times\vec{p}_i|}{\sum_{i\in\varepsilon}|\vec{p}_i|} + \frac{1}{2}\frac{\sum_{i\in\mathcal{H}R} |\vec{n}\times\vec{p}_i|}{\sum_{i\in\varepsilon}|\vec{p}_i|}$
- $C = 3\frac{\sum_{i\leq j\in\varepsilon}|\vec{p}_i||\vec{p}_j| \sin^2\theta_{ij}}{\left(\sum_{i\in\varepsilon}|\vec{p}_i|\right)^2}$

Other event shapes

Thrust, Jet broadening, C-parameter, and heavy hemisphere jet mass

- $\tau = \min_{\vec{n}} \left(1 - \frac{\sum_{i\in\varepsilon} |\vec{n}\cdot\vec{p}_i|}{\sum_{i\in\varepsilon}|\vec{p}_i|}\right)$

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- $C = 3\frac{\sum_{i\leq j\in\varepsilon}|\vec{p}_i||\vec{p}_j| \sin^2\theta_{ij}}{\left(\sum_{i\in\varepsilon}|\vec{p}_i|\right)^2}$

- $\rho = \max(\rho_L, \rho_R)\,; \quad \rho_i = \frac{m_i^2}{E_i^2}$

Local vs Global BUSD

- Local BUSD clusters a single *jet* into one C/A tree
- Global BUSD clusters the entire *event* into one C/A tree

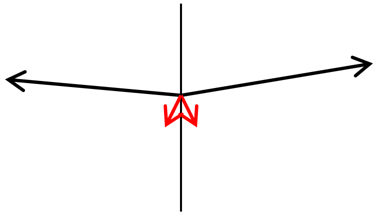
Local vs Global BUSD

- Local BUSD clusters a single *jet* into one C/A tree
- Global BUSD clusters the entire *event* into one C/A tree
- Split event shapes into two hemispheres
  - -Apply BUSD to each hemisphere independently (Local BUSD)
- Or: apply BUSD to entire event (Global BUSD)

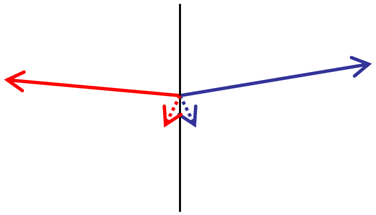
Local vs Global BUSD

- Local BUSD clusters a single *jet* into one C/A tree
- Global BUSD clusters the entire *event* into one C/A tree
- Split event shapes into two hemispheres
  -Apply BUSD to each hemisphere independently (Local BUSD)
- Or: apply BUSD to entire event (Global BUSD)
- Local BUSD slightly more aggressive (at Fixed order)

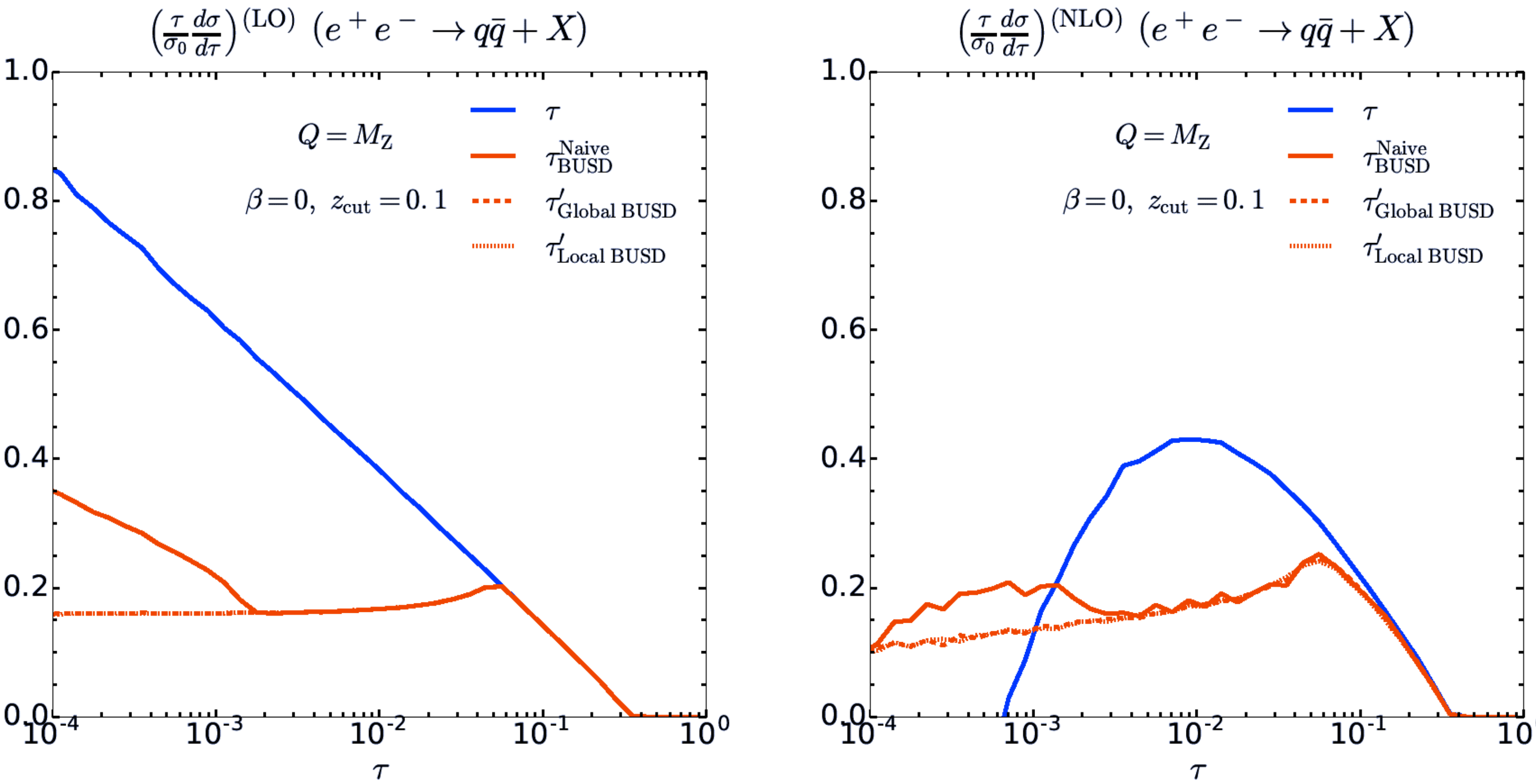
Global:



Local:

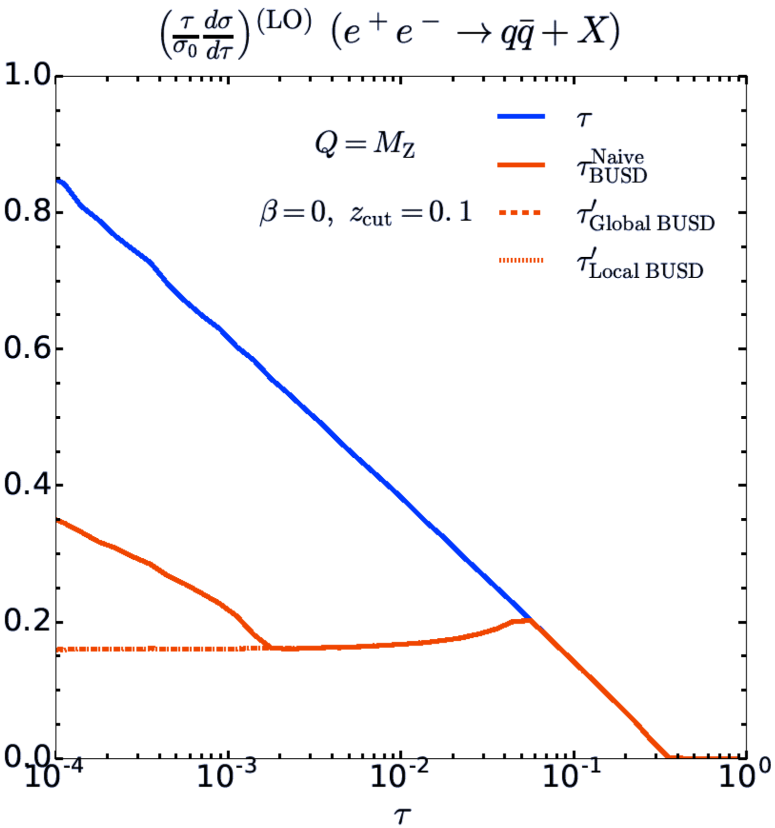


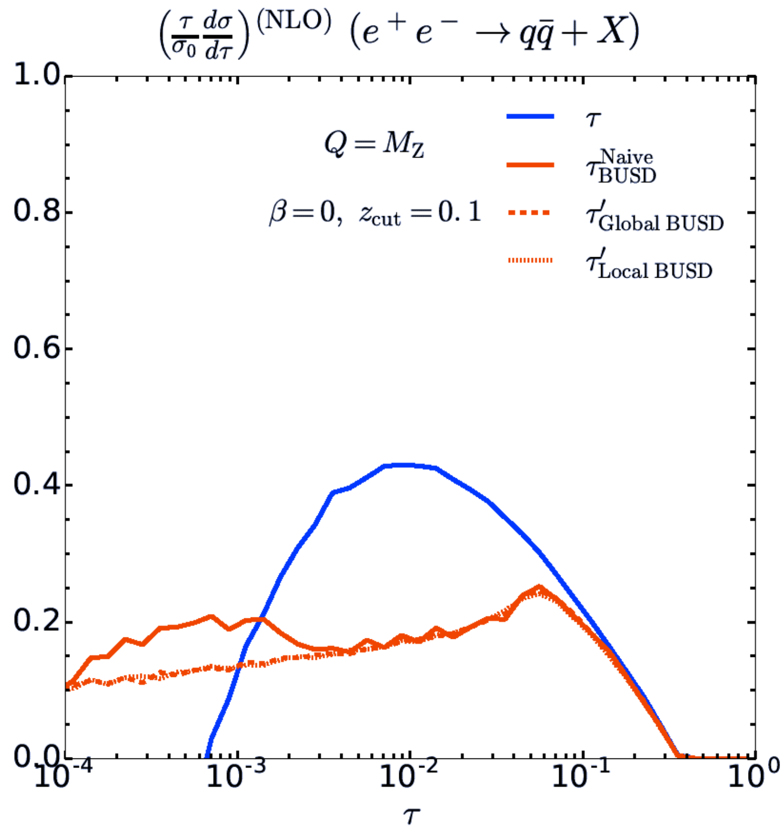
EVENT2



NB: Naïve BUSD is Global BUSD on old definition

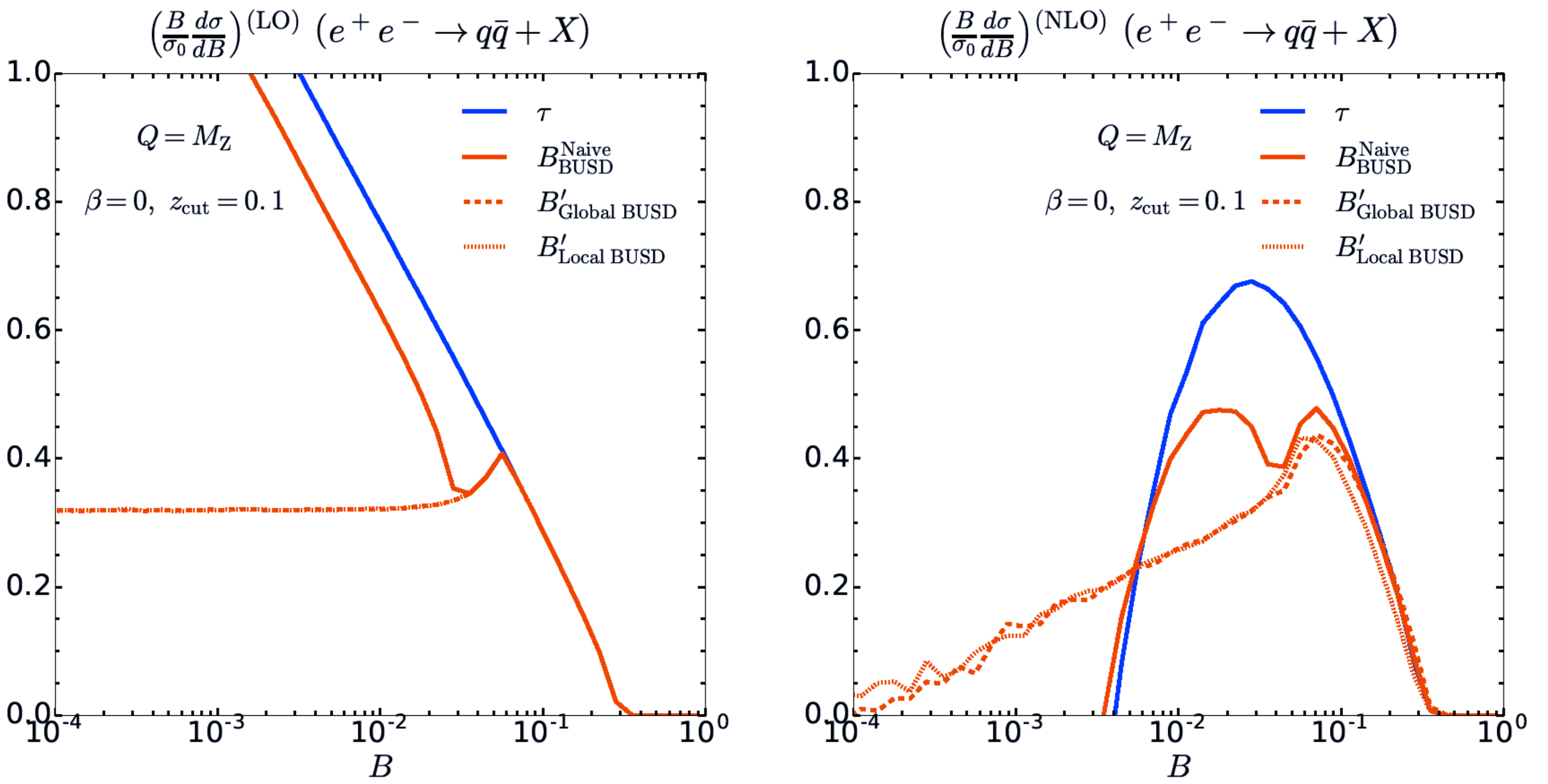
EVENT2





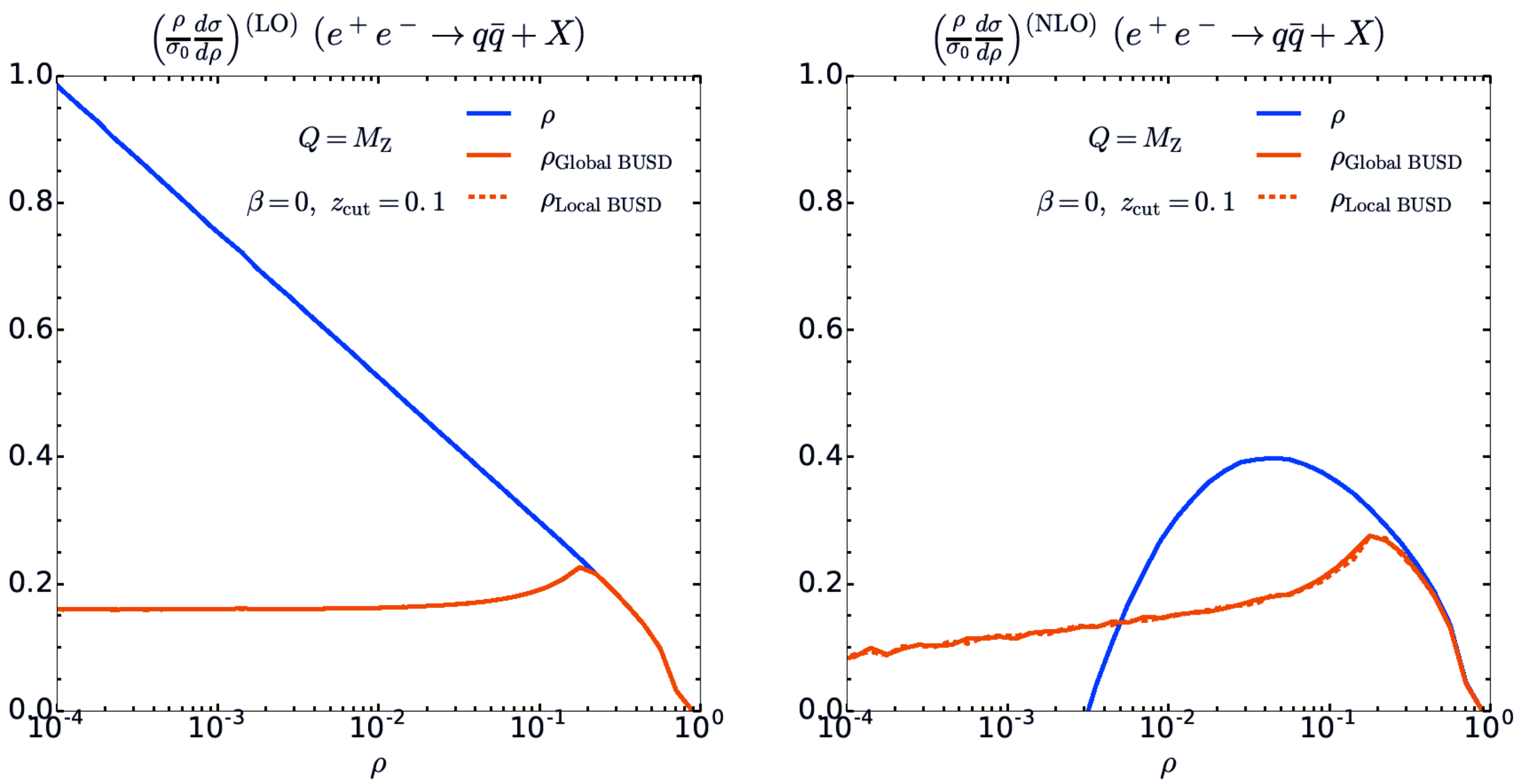
- Single log expectance broken with BUSD
- Same fix as regular SD
- Local & Global BUSD perform very similarly!

EVENT2



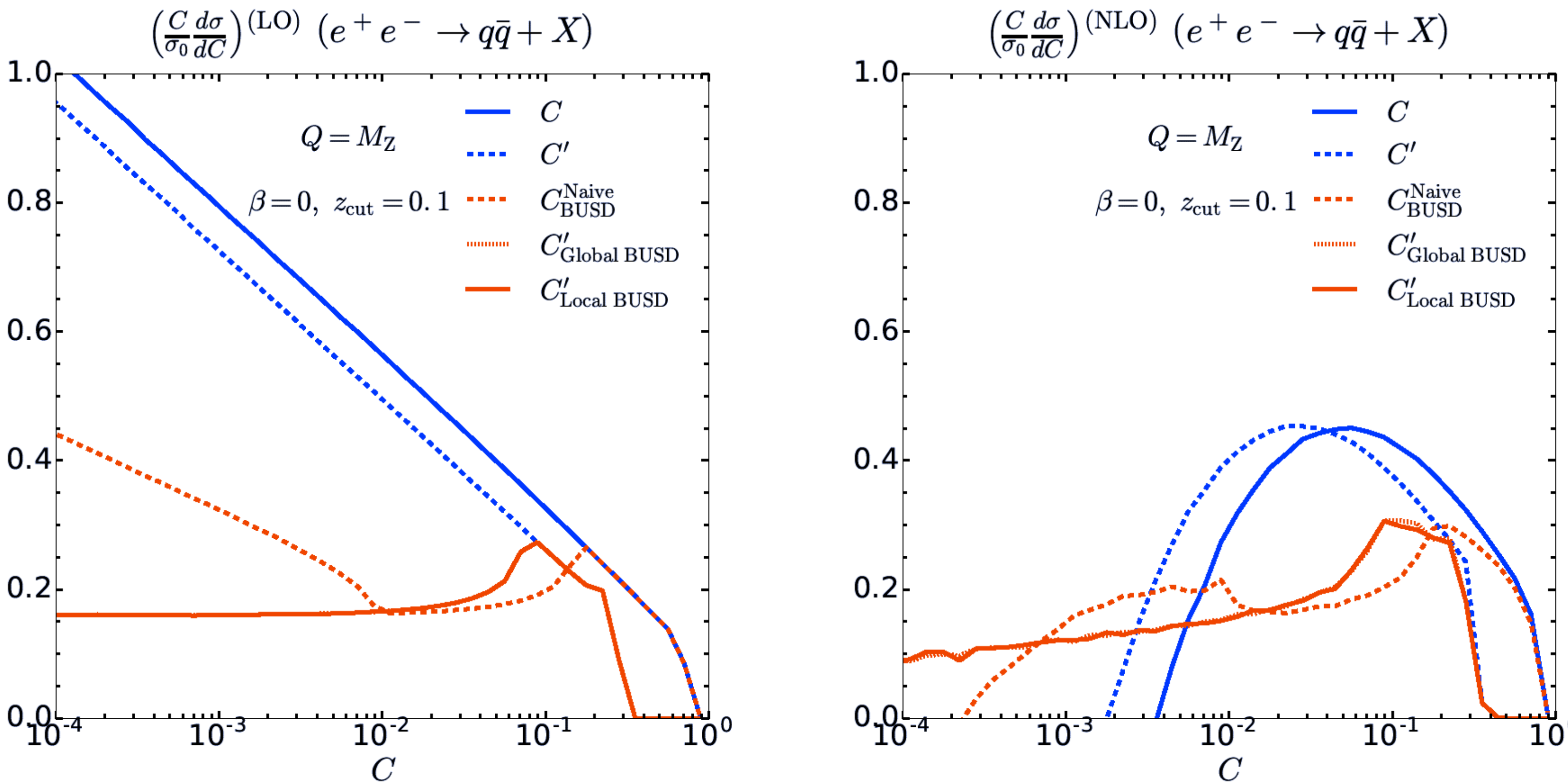
- Single log expectance also broken with broadening
- Same fix as thrust
- Difference b/w Global & Local BUSD more pronounced

EVENT2



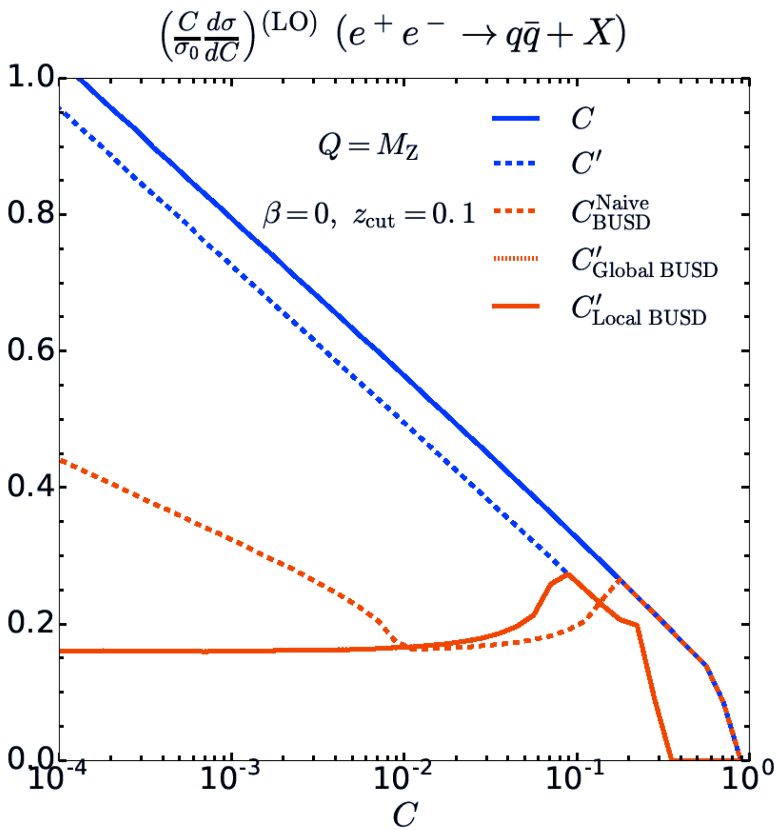
Single log expectance holds!

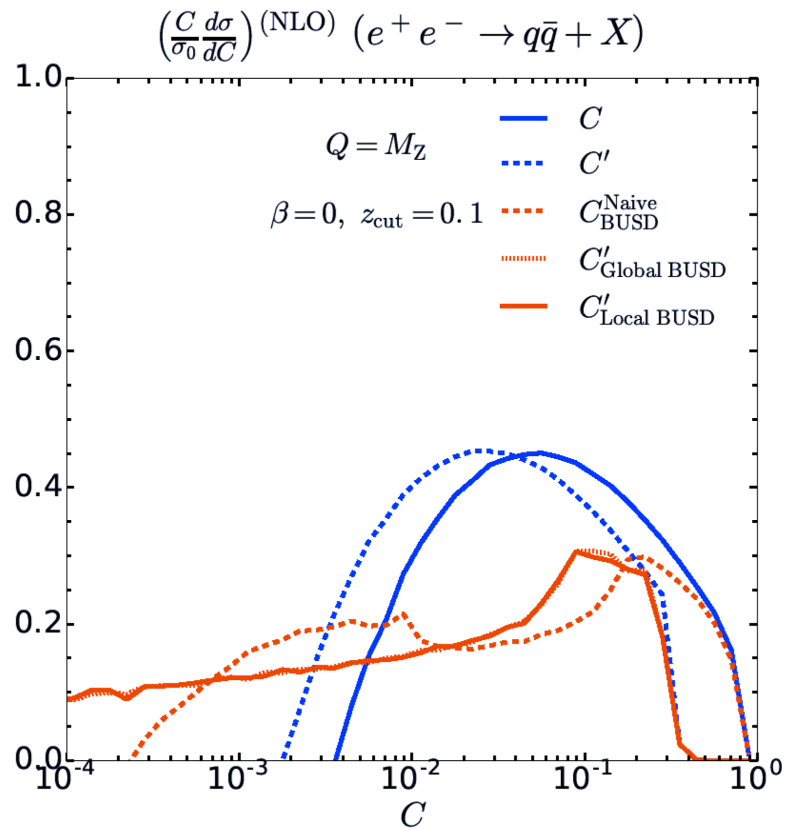
EVENT2



$$C' = 3\,\frac{\sum_{i\le j\in\mathcal{H}^{L}_{BUSD}} |\vec{p}_i||\vec{p}_j|\sin^2\theta_{ij}}{\left(\sum_{i\in\varepsilon_{BUSD}} |\vec{p}_i|\right)^2} + 3\,\frac{\sum_{i\le j\in\mathcal{H}^{R}_{BUSD}} |\vec{p}_i||\vec{p}_j|\sin^2\theta_{ij}}{\left(\sum_{i\in\varepsilon_{BUSD}} |\vec{p}_i|\right)^2}$$

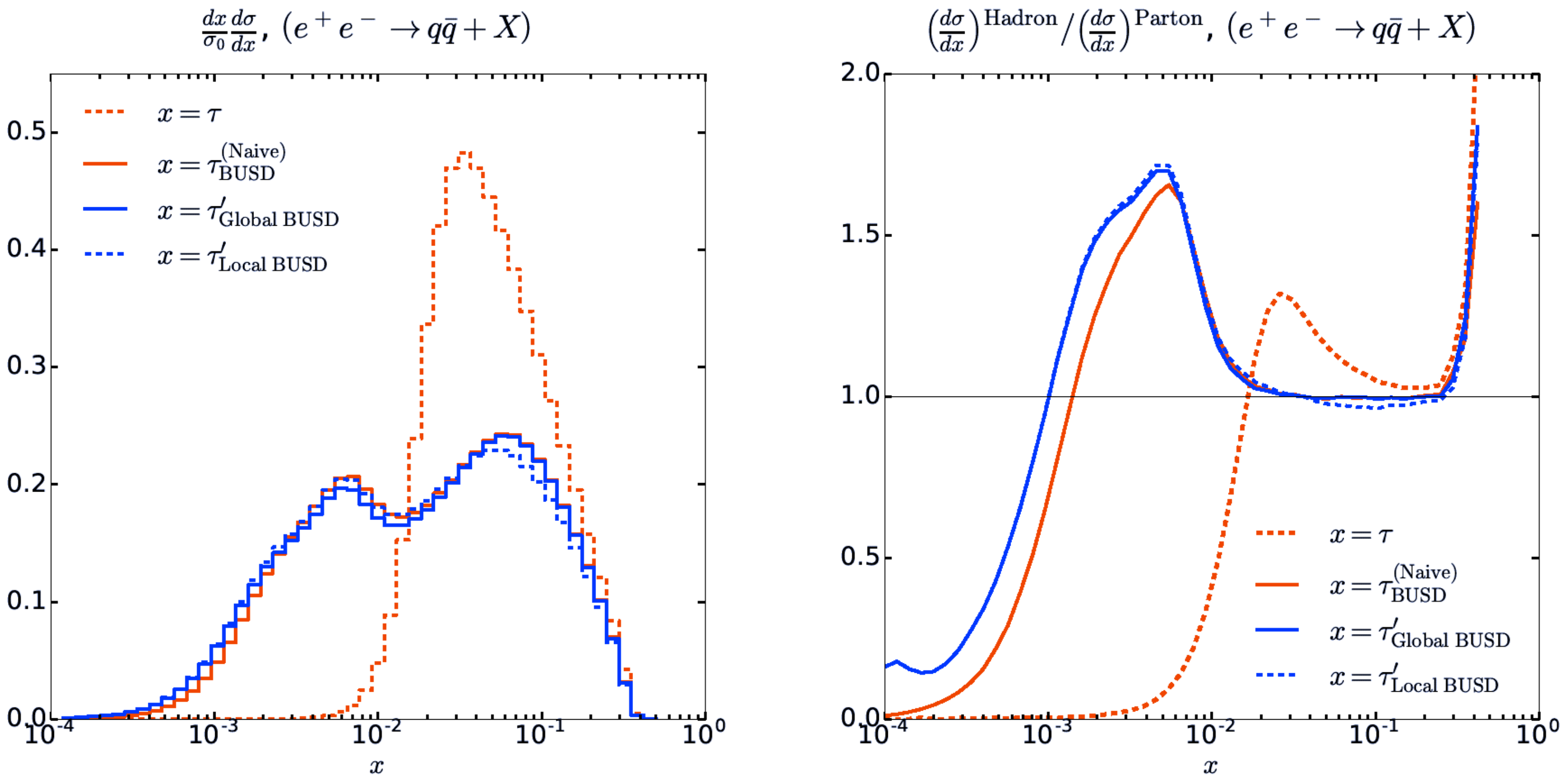
EVENT2





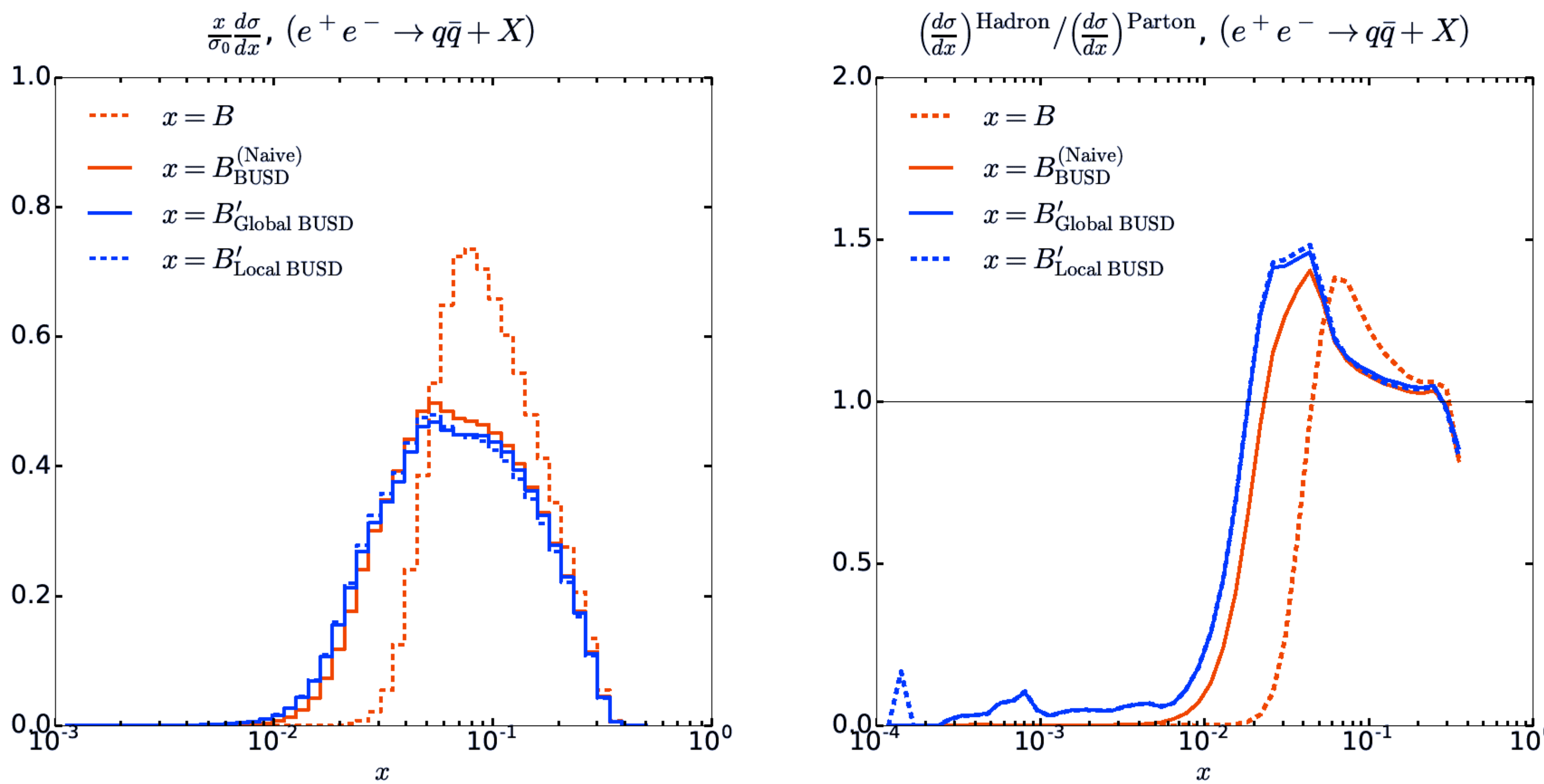
- Single log expectance broken with regular C
- Single log expectance holds with C'!
- … but comes at price of extra kink in ungroomed C' ☹

Pythia



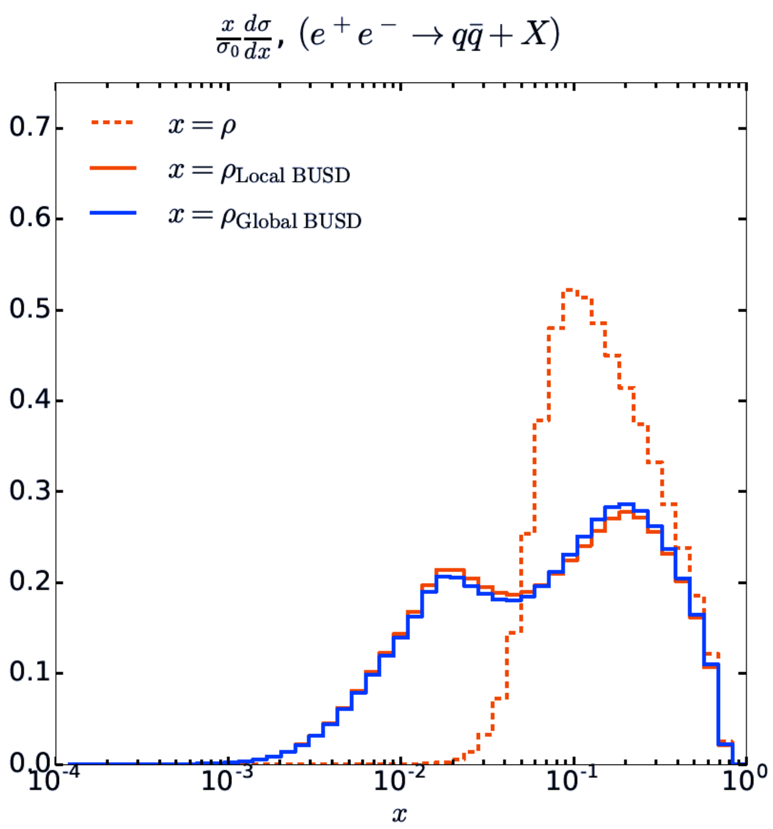
Global BUSD performs better than Local BUSD

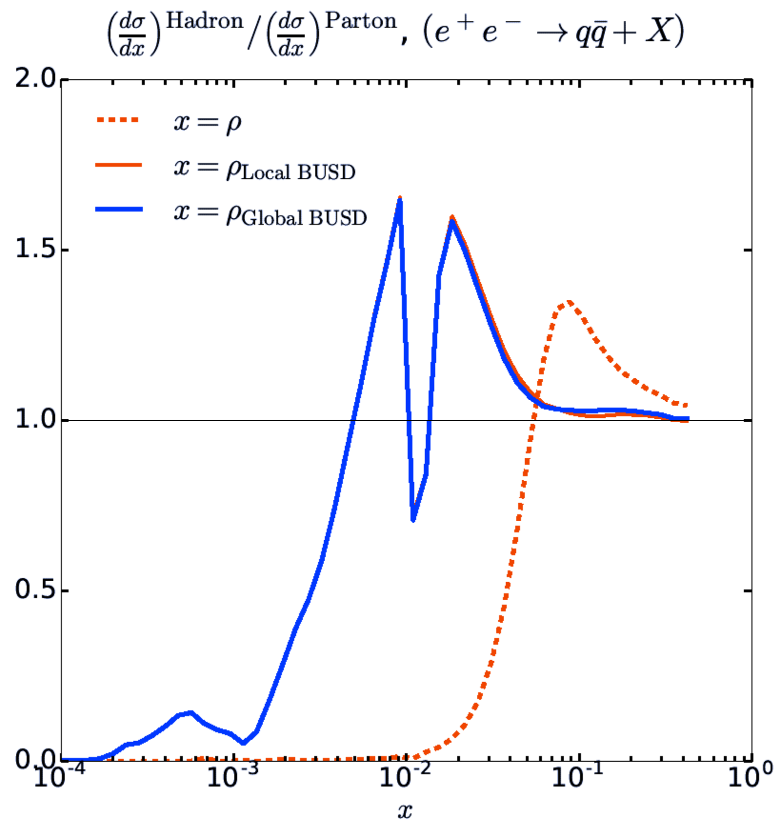
Pythia



- BUSD gives modest improvement
- Broadening in general not good with soft drop?

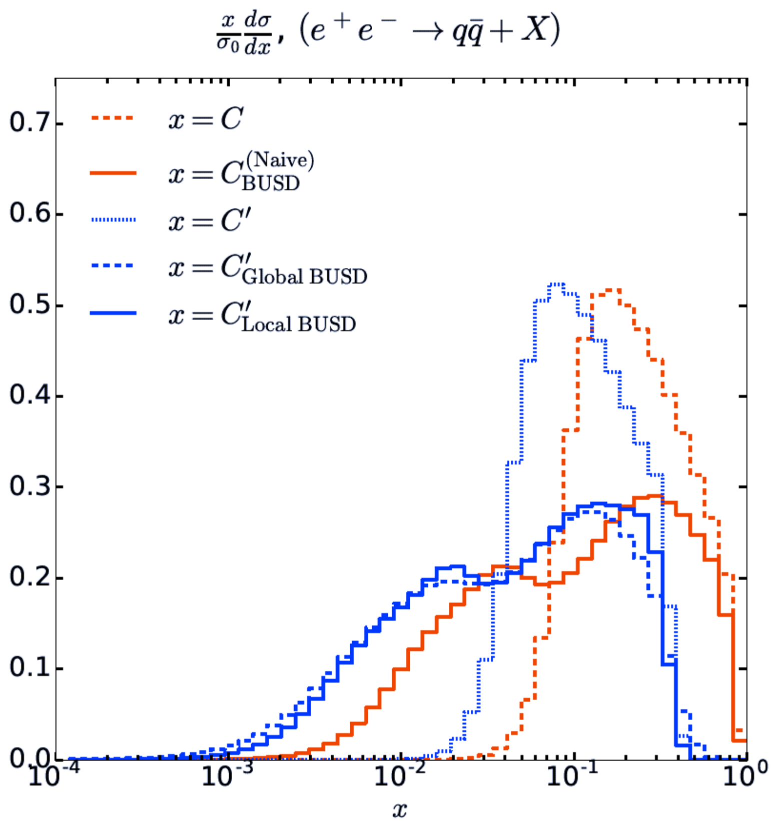
Pythia

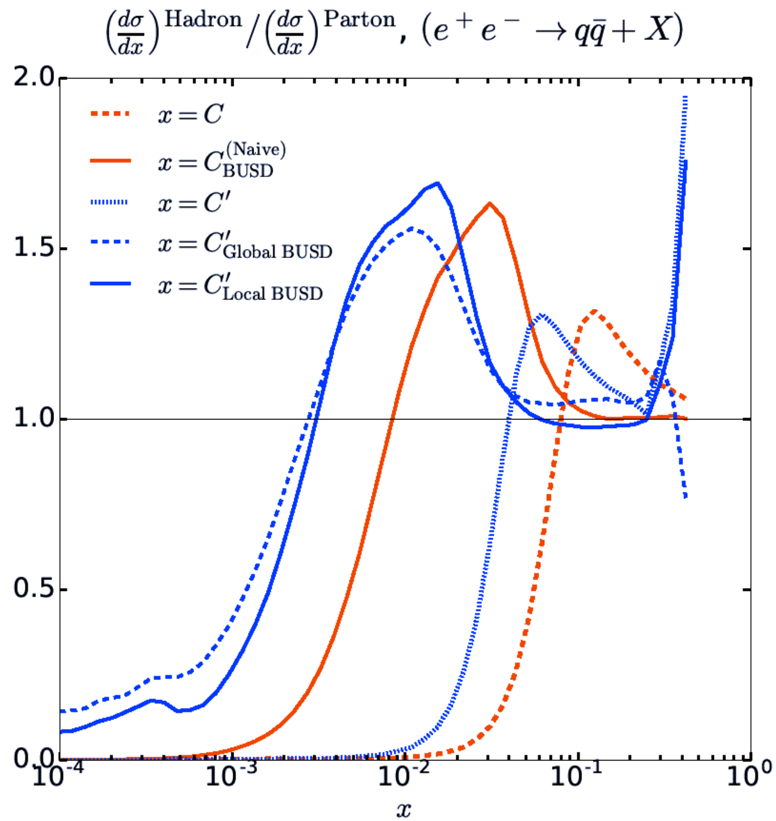




Local BUSD better than Global BUSD

Pythia





- C with naïve BUSD is best
- Local BUSD preferred for C'

Conclusions

- Need a way to groom general event shapes
  - BUSD is a natural choice
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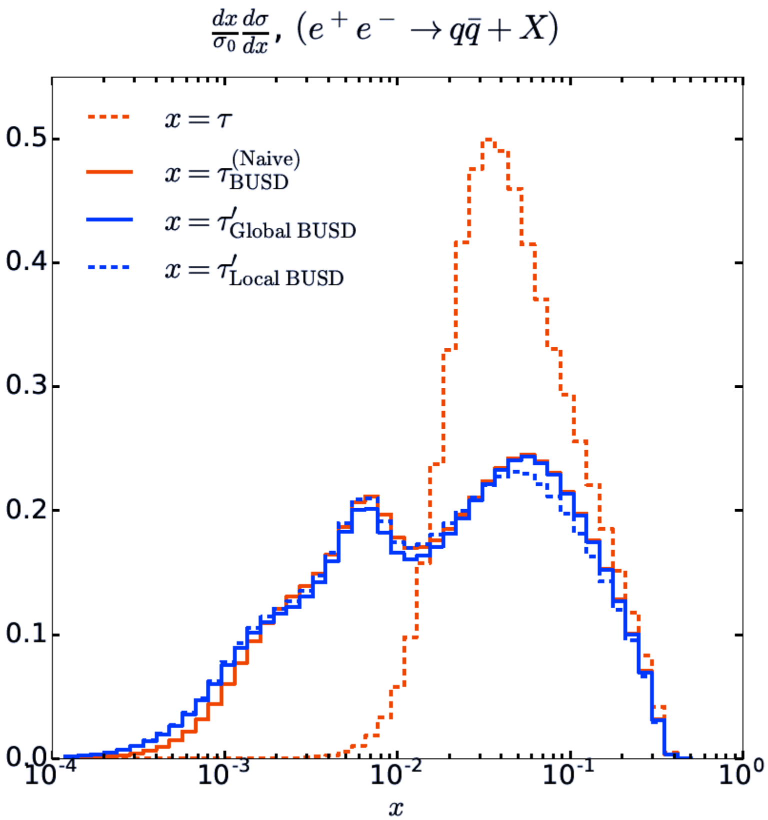
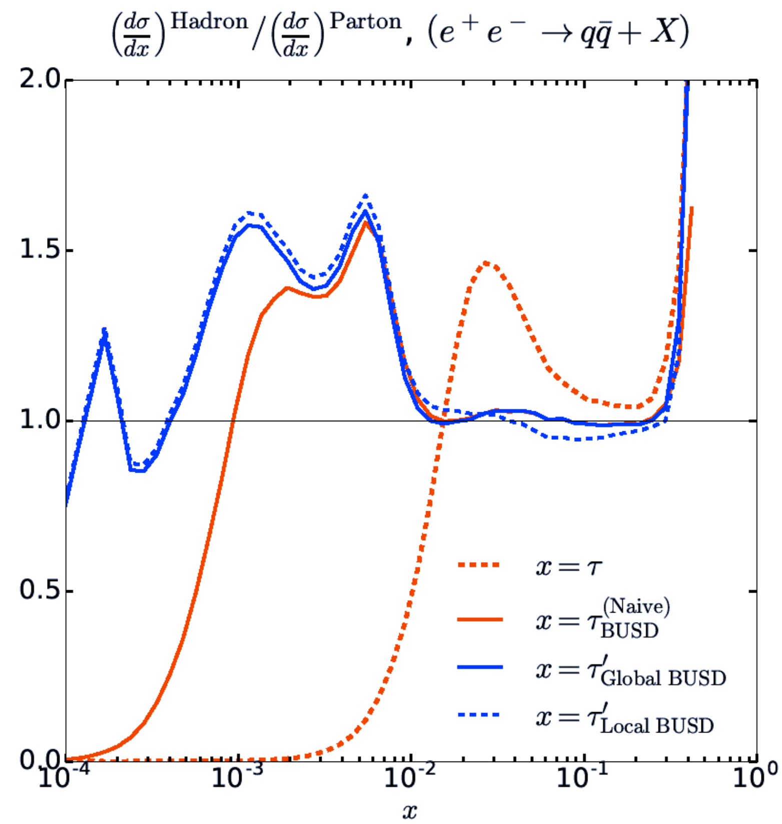
Thank you for your attention!!

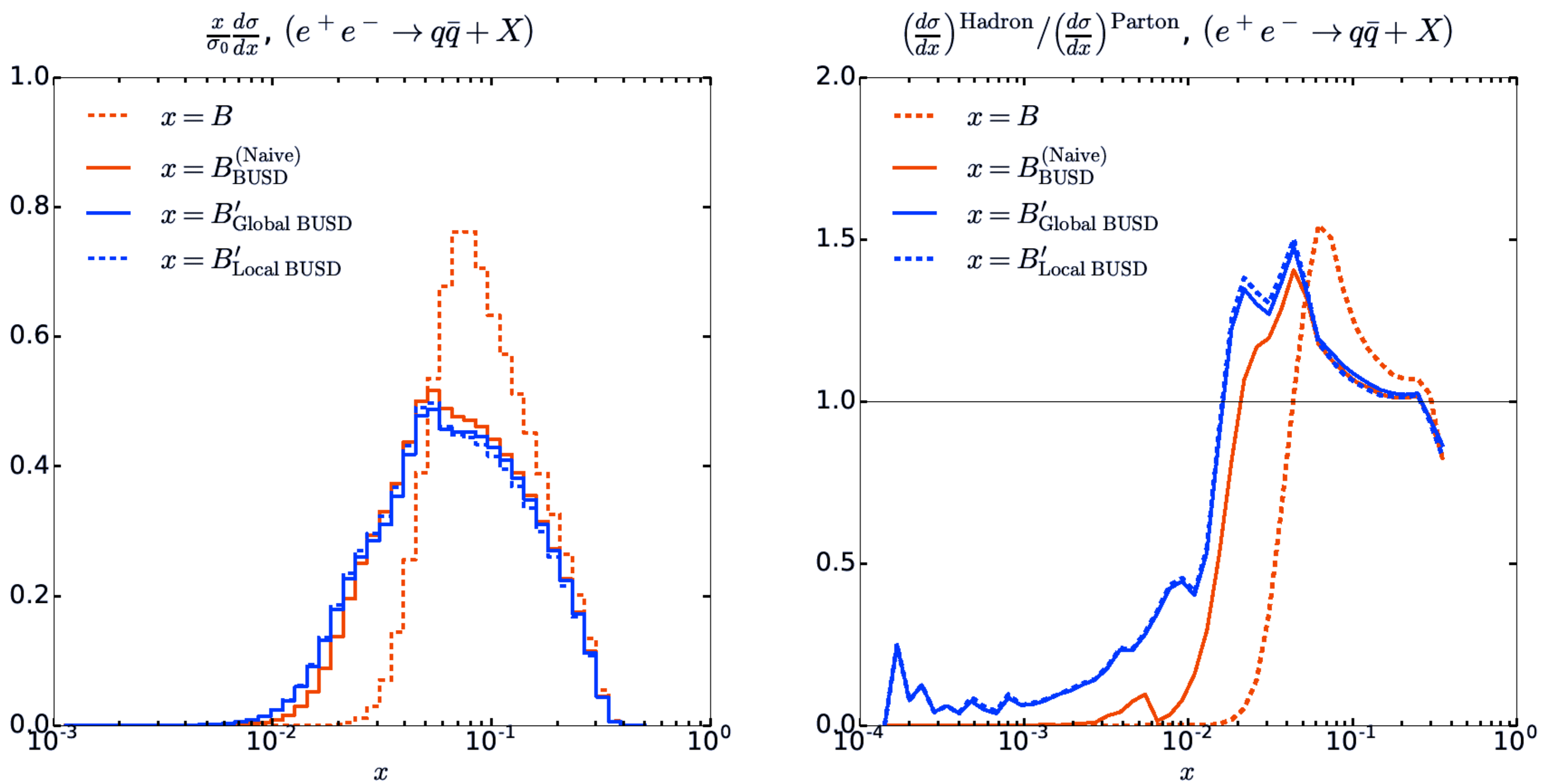
Backup Slides

Sherpa plots

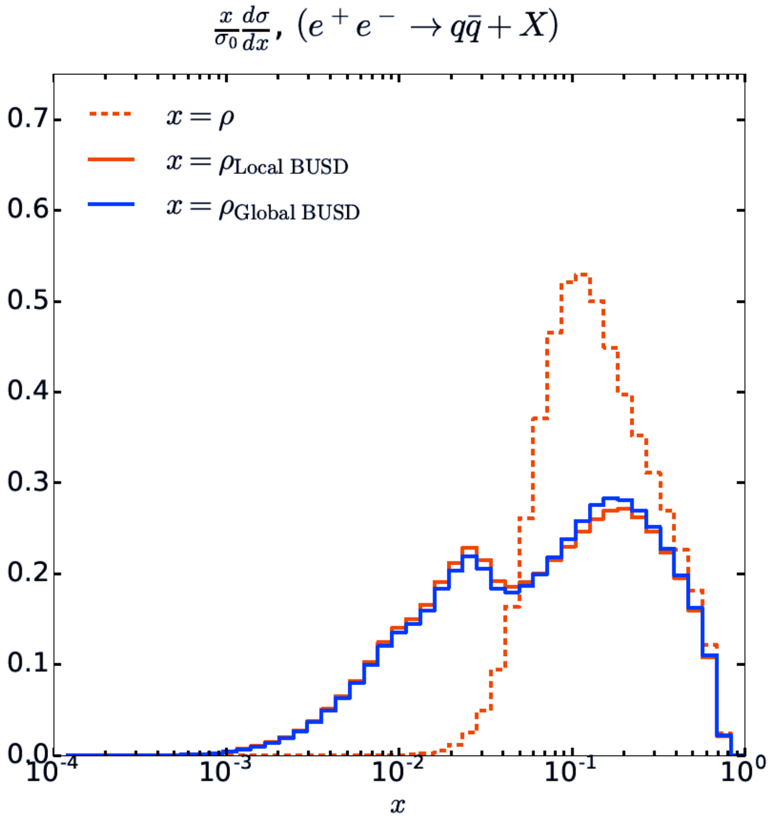


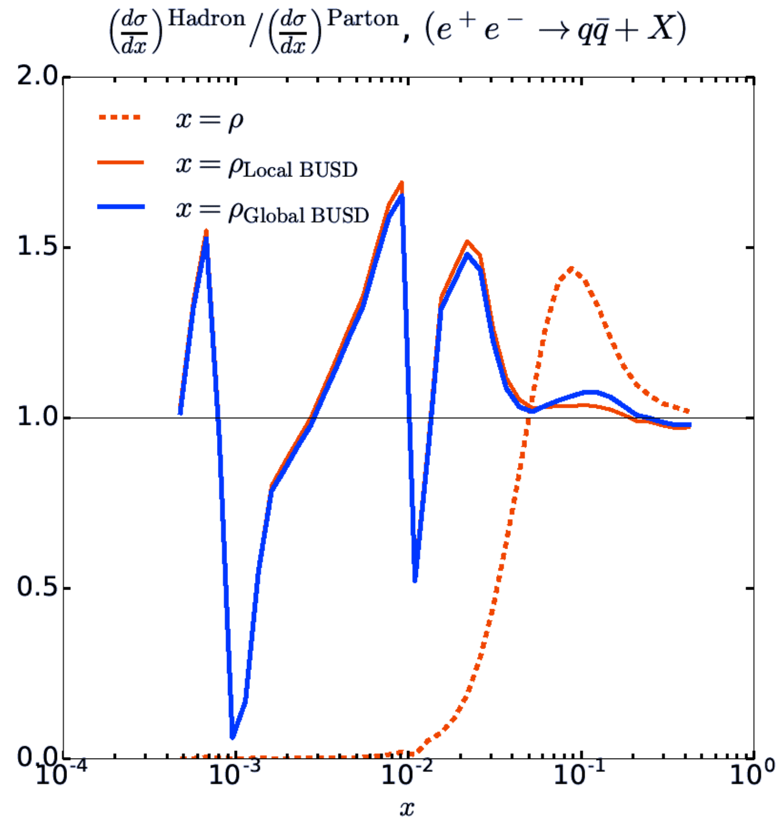


Sherpa plots



Sherpa plots





Sherpa plots