Nonlinear response and fluctuations of a driven tracer particle in simple model fluids

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Outline of the talk

• Driven tracer particle in a lattice gas

In collaboration with

- O. Bénichou, P. Illien,
- G. Oshanin, R. Voituirez

Université Pierre et Marie Curie, Paris 6



PRL (2014), PRE (2016), PRL (2018), JPCM (2018)

• Nonlinear response of an inertial particle in a steady flow

In collaboaration with Fabio Cecconi, Andrea Puglisi and Angelo Vulpiani ISC-CNR, Univ. Sapienza, Roma

PRL (2016), EPJE (2017), JPCM (2018)



Nonlinear response of a driven tracer

Rheological properties in soft matter from the microscopic motion of colloidal tracers

Puertas & Voigtmann (2014), Squires & Mason (2010)

Active microrheology: tracer particle (TP) driven by an external force F

Applications: complex fluids, gels, glasses, living cells, granular systems,...



Characteristic curve: Force-Velocity relation, V vs F

Nonlinear response of a driven tracer

Rheological properties in soft matter from the microscopic motion of colloidal tracers

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Active microrheology: tracer particle (TP) driven by an external force F

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→ Characteristic curve: Force-Velocity relation, V vs F

Nonlinear response regime: increasing the applied force can reduce the probe's drift velocity in the force direction

► Negative differential mobility



Driven tracer in a hard-core lattice gas

(N-1) hard-core particles, symmetric exclusion process, average waiting time τ^*



Tracer driven by a force Fasymmetric exclusion process, average waiting time T

Density $\rho = \frac{N}{V}$

Tracer jump probabilities, local detailed balance

$$p_{\nu} = \frac{e^{(\beta/2)\boldsymbol{F}\cdot\boldsymbol{e}_{\nu}}}{\sum_{\mu} e^{(\beta/2)\boldsymbol{F}\cdot\boldsymbol{e}_{\mu}}}$$
$$\nu = \pm 1, \dots, \pm d \quad \boldsymbol{F} = F\boldsymbol{e}_{1}$$

 $(0 | \mathbf{a}) \mathbf{n}$

Force-velocity relation?

Master Equation for
$$P(\mathbf{R}_{TP}, \eta; t)$$

$$\partial_t P(\mathbf{R}_{TP}, \eta; t) = \mathcal{L}_{\text{bath}} P + \mathcal{L}_{TP} P$$

 $oldsymbol{R}_{TP}$ tracer position

 η obstacle configuration

Master Equation for
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 \mathbf{R}_{TP} tracer position
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Decoupling approximation
 $\langle \eta(\mathbf{R}_{TP} + \boldsymbol{\lambda})\eta(\mathbf{R}_{TP} + \mathbf{e}_{\nu}) \rangle \approx \langle \eta(\mathbf{R}_{TP} + \boldsymbol{\lambda}) \rangle \langle \eta(\mathbf{R}_{TP} + \mathbf{e}_{\nu}) \rangle$
for $\boldsymbol{\lambda} \neq \mathbf{e}_{\nu}$
 $V(F) \equiv \frac{d\langle \mathbf{R}_{TP} \cdot \mathbf{e}_1 \rangle}{dt} = \frac{1}{2d-*} (A_1 - A_{-1})$

$$V(F) \equiv \frac{d(2e_{11} - e_{17})}{dt} = \frac{1}{2d\tau^*} (A_1 - A_{-1})$$

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for $\boldsymbol{\lambda} \neq \boldsymbol{e}_{\nu}$
$$V(F) \equiv \frac{d\langle \boldsymbol{R}_{TP} \cdot \boldsymbol{e}_{1} \rangle}{dt} = \frac{1}{2d\tau^{*}} (A_{1} - A_{-1})$$

Nonlinear system of equations

$$A_{\nu} = 1 + \frac{2d\tau^{*}}{\tau} p_{\nu} \left[1 - \rho - \rho (A_{1} - A_{-1}) \frac{\det C_{\nu}}{\det C} \right]$$

Solution for V(F) for arbitrary values of the parameters

Comparison with Monte Carlo numerical simulations









For τ^* large enough ("slow" obstacles), traps are sufficiently long lived to slow down the TP when F is increased \longrightarrow NDM

Criterion for negative differential mobility

Parameter space: time scales τ^*/τ and density ρ



Physical mechanism: coupling between density and time scales ratio

Fluctuations and diffusion coefficient

Variance of the tracer

$$\frac{\mathrm{d}}{\mathrm{d}t}\sigma_X^2(t) = -\frac{2\sigma}{\tau} \left[p_1 \tilde{g}_{\mathbf{e}_1}(t) - p_{-1} \tilde{g}_{\mathbf{e}_{-1}}(t) \right] + \frac{\sigma^2}{\tau} \left\{ p_1 \left[1 - k_{\mathbf{e}_1}(t) \right] + p_{-1} \left[1 - k_{\mathbf{e}_{-1}}(t) \right] \right\}$$

Correlation between tracer and bath particles

$$\widetilde{g}_{\boldsymbol{r}} \equiv \langle (X_t - \langle X_t \rangle)(\eta_{\boldsymbol{r}} - \langle \eta_{\boldsymbol{r}} \rangle) \rangle$$

Diffusion coefficient $D \equiv \frac{1}{2d} \lim_{t \to \infty} \frac{\mathrm{d}}{\mathrm{d}t} \sigma_X^2(t)$

Decoupling approximation

$$\langle \eta_{\boldsymbol{r}} \eta_{\boldsymbol{r}'} \rangle \simeq \langle \eta_{\boldsymbol{r}} \rangle \langle \eta_{\boldsymbol{r}'} \rangle \langle \delta X_t \eta_{\boldsymbol{r}} \eta_{\boldsymbol{r}'} \rangle \simeq \langle \eta_{\boldsymbol{r}} \rangle \langle \delta X_t \eta_{\boldsymbol{r}'} \rangle + \langle \eta_{\boldsymbol{r}'} \rangle \langle \delta X_t \eta_{\boldsymbol{r}} \rangle$$

Enhanced diffusivity induced by crowding interactions



PART II: nonlinear response of an inertial tracer

Model: inertial tracer in a steady cellular flow, with external force



Force-velocity relation



Negative differential mobility

Force-velocity relation



"Phase diagram"



Conclusions

Nonlinear response of a driven tracer can reveal anomalous behaviors

- Lattice gas model
 - Analytical approach
 - Negative differential mobility
 - Enhanced diffusivity induced by crowding
- Inertial particles in steady laminar flows
 - Absolute negative mobiliy

References

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Anomalous force-velocity relation of driven inertial tracers in steady laminar flows
Cecconi, Puglisi, AS, Vulpiani,
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Thank you for your attention!

Active Ornstein Uhlenbeck Particle

Colored noise with persistence time τ_A

$$\dot{w}_x = \frac{w_x}{\tau_A} + \frac{\sqrt{2D_0}}{\tau_A}\xi_x \qquad \dot{w}_y = \frac{w_y}{\tau_A} + \frac{\sqrt{2D_0}}{\tau_A}\xi_y$$

 $\tau_A \rightarrow 0$ Uncorrelated noise

 $\tau_A \rightarrow \infty$ Deterministic (zero-noise) dynamics



Active Ornstein Uhlenbeck Particle

Absolute negative mobility



Strong external force $\epsilon = 2e^{-\beta F/2} \ll 1$ $p_1 = 1 - \epsilon$ $p_{-1} = O(\epsilon^2)$ $p_{\mu \neq \pm 1} = \frac{\epsilon}{2d - 2}$

Force-velocity relation: $V(F) = \frac{\text{mean distance}}{\text{mean time of free flight + mean trapping time}}$

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Mean distance between two obstacles $1/\rho$

Mean duration of free flight $\tau/[
ho(1-\epsilon)]$

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Mean distance between two obstacles $1/\rho$

Mean duration of free flight $\tau/|\rho(1-\epsilon)|$

$$1/\tau_{\rm trap} = 3/(4\tau^*) + \epsilon/\tau$$

away

obstacle steps tracer steps in a transverse direction



$$V(F) = \frac{1-\epsilon}{\tau + 4\rho(1-\epsilon)\frac{\tau^*}{3+4\epsilon\tau^*/\tau}}$$

Criterion for NDM $\tau^*/\tau \gtrsim \rho^{-1/2}$

0.9

0.6

V(F)

$$V(F) = \frac{1 - \epsilon}{\tau + 4\rho(1 - \epsilon)\frac{\tau^*}{3 + 4\epsilon\tau^*/\tau}}$$

Criterion for NDM $\tau^*/\tau \gtrsim \rho^{-1/2}$

Physical mechanism: a large force
reduces the flight time between two consecutive encounters with bath particles;
increases the escape time from traps created by surrounding obstacles



NDM

For τ^* large enough ("slow" obstacles), traps are sufficiently long lived to slow down the TP when F is increased

Generalized Einstein relation





Generalized Einstein relation



Generalized Einstein relation Baiesi, Maes, Wynants J.Stat.Phys. (2010)

Nonequilibrium extra-term

$$\mu_0 = \frac{1}{T} [D_x(F=0) - C_{x\Phi}(F=0)]$$

$$C_{x\Phi}(F) = \lim_{t \to \infty} \frac{1}{2Tt} \langle [x(t) - x(0)] \Phi(t) \rangle_{c,F}$$

$$\Phi(t) = \int_0^t U_x[x(s), y(s)] ds$$



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Possible physical mechanism

Typical trajectory for $D_0 = 0$

- The motion is realized along preferential "channels"
- Both inertia and noise activate random transitions between the channels



Possible physical mechanism

Typical trajectory for $D_0 = 0$

- The motion is realized along preferential "channels"
- Both inertia and noise activate random transitions between the channels





→ F=0.065

The tracer is pushed from region A (downstream channel) to region B (upstream channel)

F=0.04With a smaller or larger force, the particle avoids the adverseF=0.09region B and continues its run along downstream channels

Master Equation for
$$P(\mathbf{R}_{TP}, \eta; t)$$
 \mathbf{R}_{TP} tracer position
 $\partial_t P(\mathbf{R}_{TP}, \eta; t) = \mathcal{L}_{\text{bath}} P + \mathcal{L}_{\text{TP}} P$ η obstacle configuration
Tracer velocity $V(F) \equiv \frac{d\langle \mathbf{R}_{TP} \cdot \mathbf{e}_1 \rangle}{dt} = \frac{1}{2d\tau^*} (A_1 - A_{-1})$

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 $A_{\nu} \equiv 1 + \frac{2d\tau^*}{\tau} p_{\nu} (1 - k(\mathbf{e}_{\nu}))$

Density profile around the tracer $k(\lambda;t) = \sum_{\mathbf{R}_{TP},\eta} \eta(\mathbf{R}_{TP} + \lambda)P(\mathbf{R}_{TP},\eta;t)$ $\mathbf{R}_{TP,\eta} \land \mathbf{C}_{\text{occupation variable}}$

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Density profile $k(\lambda;t) = \sum_{\mathbf{R}_{TP},\eta} \eta(\mathbf{R}_{TP} + \lambda)P(\mathbf{R}_{TP},\eta;t)$ around the tracer $k(\lambda;t) = \sum_{\mathbf{R}_{TP},\eta} \eta(\mathbf{R}_{TP} + \lambda)P(\mathbf{R}_{TP},\eta;t)$

$$2d\tau^* \partial_t k(\lambda; t) = \sum_{\mu} \left(\nabla_{\mu} - \delta_{\lambda, \mathbf{e}_{\mu}} \nabla_{-\mu} \right) k(\lambda; t) \\ + \frac{2d\tau^*}{\tau} \sum_{\nu} p_{\nu} \langle [1 - \eta(\mathbf{R}_{TP} + \mathbf{e}_{\nu})] \nabla_{\nu} \eta(\mathbf{R}_{TP} + \lambda) \rangle$$

Decoupling approximation *General* solution



Tracer velocity
$$V(F) \equiv \frac{d\langle \mathbf{R}_{TP} \cdot \mathbf{e}_1 \rangle}{dt} = \frac{1}{2d\tau^*} (A_1 - A_{-1})$$

$$A_{\nu} = 1 + \frac{2d\tau}{\tau} \left[1 - \rho - \rho (A_1 - A_{-1}) \frac{\det C_{\nu}}{\det C} \right]$$

Significant dependence on the choice of transition probabilities?

General form of transition rates $k(\boldsymbol{x}, \boldsymbol{y}) = \psi(\boldsymbol{x}, \boldsymbol{y})e^{S(\boldsymbol{x}, \boldsymbol{y})/2}\delta(K.C.)$

$$\quad \longrightarrow \quad \psi(\boldsymbol{x},\boldsymbol{y}) = \psi(\boldsymbol{y},\boldsymbol{x}) \ge 0$$

Symmetric (kinetic) part

 $\implies S(\boldsymbol{x}, \boldsymbol{y}) = -S(\boldsymbol{y}, \boldsymbol{x})$

Antisymmetric part

General form of transition rates $k(\boldsymbol{x}, \boldsymbol{y}) = \psi(\boldsymbol{x}, \boldsymbol{y})e^{S(\boldsymbol{x}, \boldsymbol{y})/2}\delta(K.C.)$

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 Symmetric (kinetic) part

 $S(\boldsymbol{x}, \boldsymbol{y}) = -S(\boldsymbol{y}, \boldsymbol{x})$ Antisymmetric part

Local detailed balance imposes a constraint on the antisymmetric part C(x) = C(x)

$$S(\boldsymbol{x}, \boldsymbol{y}) \propto \text{entropy flux} \quad \Longrightarrow \quad S(\boldsymbol{x}, \boldsymbol{x} + \boldsymbol{e}_{\nu}) = \beta \boldsymbol{F} \cdot \boldsymbol{e}_{\nu}$$

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Local detailed balance imposes a constraint on the antisymmetric part $S(\boldsymbol{x}, \boldsymbol{y}) \propto \text{entropy flux} \implies S(\boldsymbol{x}, \boldsymbol{x} + \boldsymbol{e}_{\nu}) = \beta \boldsymbol{F} \cdot \boldsymbol{e}_{\nu}$

Arbitrary choice for the symmetric part

Leitmann & Franosch, $\psi(\boldsymbol{x}, \boldsymbol{x} + \boldsymbol{e}_{\nu}) = 1/\tau [e^{\beta F/2} + e^{-\beta F/2} + 2]$ Bénichou et al.

Basu & Maes

$$\begin{cases} \psi(\boldsymbol{x}, \boldsymbol{x} + \boldsymbol{e}_{\nu}) = 1/2\tau [e^{\beta F/2} + e^{-\beta F/2}] & \text{for } \nu = \pm 1\\ \psi(\boldsymbol{x}, \boldsymbol{x} + \boldsymbol{e}_{\nu}) = 1/4\tau & \text{for } \nu = \pm 2 \end{cases}$$

independent of F in the transverse direction

Role of the transition probabilities

$$p_{\nu} = \frac{e^{(\beta/2)\boldsymbol{F}\cdot\boldsymbol{e}_{\nu}}}{\sum_{\mu} e^{(\beta/2)\boldsymbol{F}\cdot\boldsymbol{e}_{\mu}}}$$

(Leitmann & Franosch, Bénichou et al.)



One obstacle can create a long lived trap

 $p_{\uparrow} = p_{\downarrow} = \frac{1}{4}$ independent of F (Basu & Maes)



No trapping effect at linear order in the density

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No trapping effect at linear order in the density

Different choices significant macroscopic differences (Baiesi et al. PRE (2015))

Warning: how to define microscopic transition rates out of equilibrium?

Criterion for negative differential mobility

Parameter space: time scales τ^*/τ and density ρ



NDM is robust, but the phase chart is different

Absolute negative mobility



the GER is verified, showing strong negative and positive differential mobilities just before and just after the minimum

Master Equation for $P(\boldsymbol{R}_{TP},\eta;t)$ \boldsymbol{R}_{TP} tracer position η obstacles configuration

$$\partial_{t} P(\boldsymbol{R}_{TP}, \eta; t) = \frac{1}{2d\tau^{*}} \sum_{\mu=1}^{\omega} \sum_{\boldsymbol{r} \neq \boldsymbol{R}_{TP} - \boldsymbol{e}_{\mu}, \boldsymbol{R}_{TP}} [P(\boldsymbol{R}_{TP}, \eta^{\boldsymbol{r}, \mu}; t) - P(\boldsymbol{R}_{TP}, \eta; t)] \\ + \frac{1}{\tau} \sum_{\mu=1}^{d} p_{\mu} \{ [1 - \eta(\boldsymbol{R}_{TP})] P(\boldsymbol{R}_{TP} - \boldsymbol{e}_{\mu}, \eta; t) \\ - [1 - \eta(\boldsymbol{R}_{TP} + \boldsymbol{e}_{\mu})] P(\boldsymbol{R}_{TP}, \eta; t) \}$$

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 $A_{\nu} \equiv 1 + \frac{2d\tau^*}{\tau} p_{\nu} (1 - k(\mathbf{e}_{\nu}))$
Density profile $k(\lambda; t) = \sum \eta(\mathbf{R}_{TP} + \lambda) P(\mathbf{R}_{TP}, \eta; t)$

 $\boldsymbol{R}_{TP}, \eta$

PART II: nonlinear response of an inertial tracer

Transport properties of particles of non-negligible mass in fluids

Sedimentation, dispersion of pollutants, rain formation in clouds...

Inertia implies non-trivial deviations from the trajectory of fluid particles

Strongly inhomogeneous distributions Preferential concentration





Steady cellular flow

