

Cosmic Explorer Length Sensing and Control R&D

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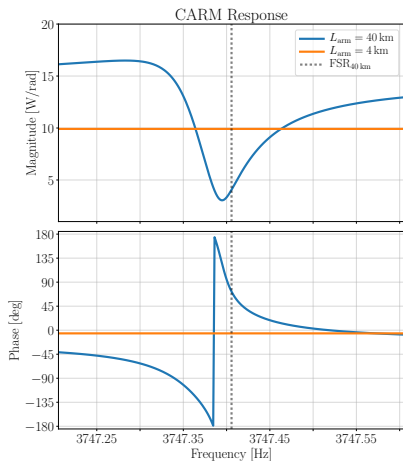
May 22, 2019

Overview

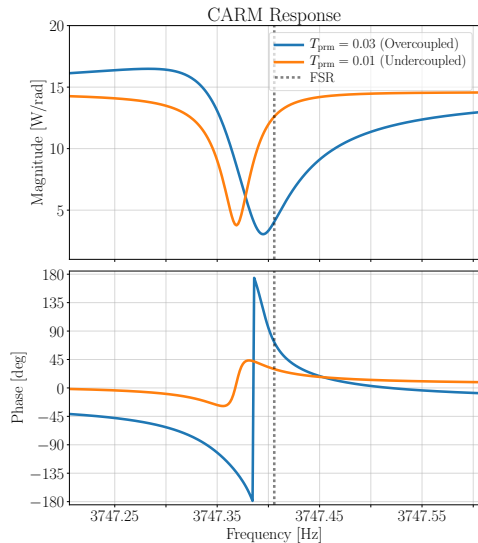
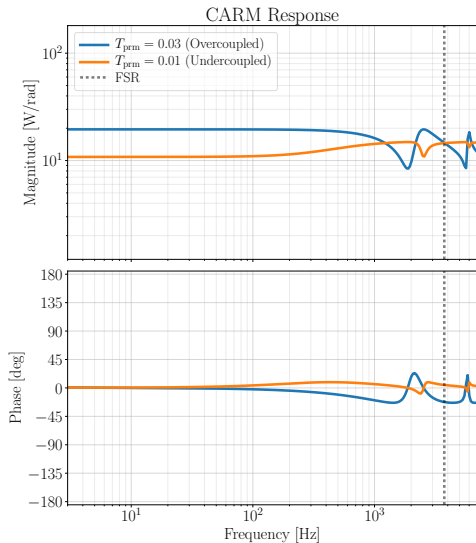
1. Frequency stabilization
2. Noise budget with technical noises
3. Radiation pressure actuator

Frequency Stabilization

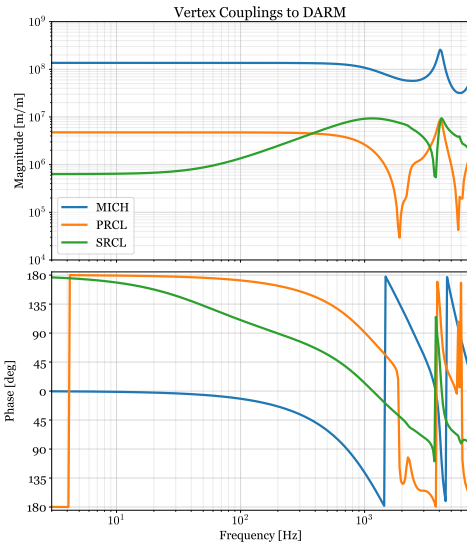
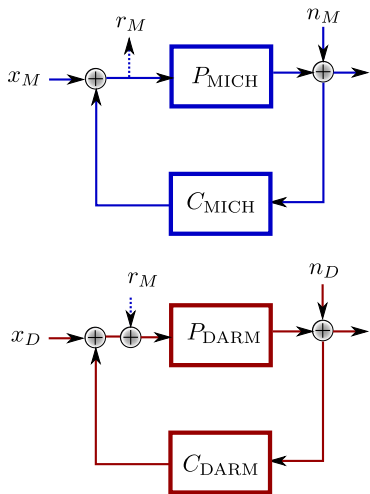
- ▶ In LIGO, the laser frequency is stabilized in three steps. In the last step the frequency is stabilized to the common arm length of the interferometer with a loop with a bandwidth of about 20 kHz.
- ▶ FSR of LIGO is 37.5 kHz but for CE is 3.75 kHz.
- ▶ Right half-plane zeros at the FSR makes this difficult to control.



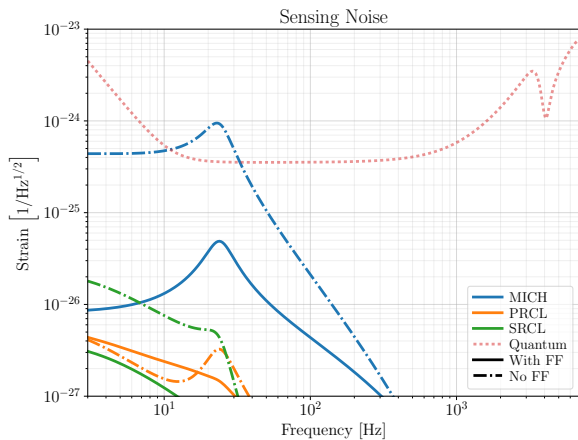
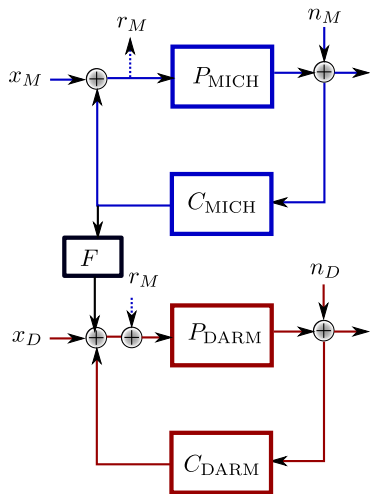
Undercoupling leads to left half plane zeros



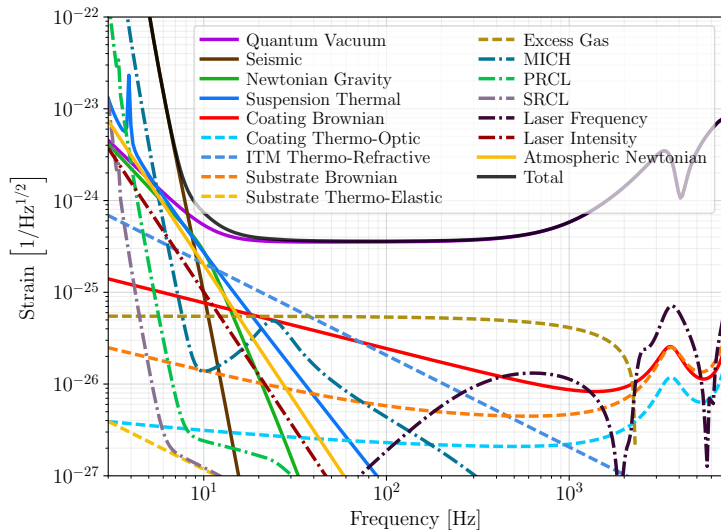
Cross Coupling of Vertex Degrees of Freedom



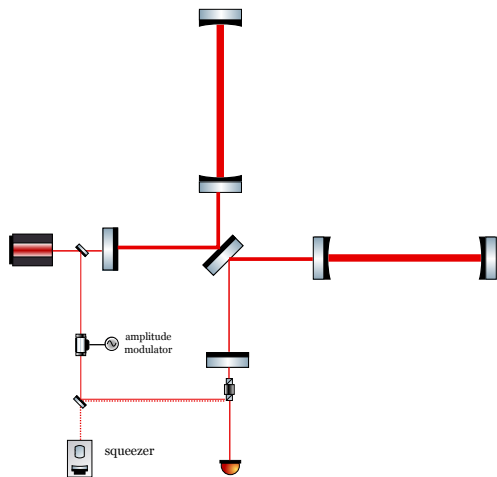
Feedforward Subtraction



CE Noise Budget with Technical Noises



Radiation Pressure Actuator



- ▶ Inject amplitude modulated light through the dark port.
- ▶ Actuation strength

$$\Delta L_- = \frac{7 \text{ fm}}{f^2} \left(\frac{320 \text{ kg}}{M} \right) \sqrt{\left(\frac{P_{\text{arm}}}{1 \text{ MW}} \right) \left(\frac{P_a}{1 \text{ nW}} \right) \frac{\delta P_a}{P_a}}$$