

# Introduction History of Raman



### story of Raman Scattering

In 1928, C. V. Raman discovers that small changes occur the frequency of a small portion of the light scattered by molecules.

The changes reflect the vibrational properties of the molecule.

C.V. Raman was awarded the Nobel Prize in Physics in 1930 for his discovery.



Sir Chandrasekhara Venkata Raman





### volution of Raman System





#### aman papers vs other techniques

	Nature	Science	Royal Chemistry Society	Journal of Applied Physics	journal Pharmaceutical review	Earth and planetary science	total
NMR	39 800	354 000	221 000	594 000	519 000	1 200	1 729 000
Raman	12 400	159 000	119 000	596 000	188 000	1 360	1 075 760
XRD	5 860	166 000	171 000	171 000	79 600	3 610	597 070
FTIR	3 080	141 000	101 000	150 000	127 000	1 310	523 390
XPS	3 290	86 800	84 100	108 000	71 300	78	353 568
SIMS	152	5 310	419	8 110	1 370	70	15 431
CLSM	903	5 720	3 340	1 850	2 330	38	14 181

#### Raman spectroscopy is extremely versatile!

#### mparison of FTIR and Raman Spectroscopy



#### Advantages of Raman over FTIR:

- Avoids many interferences from solvents, cells and sample preparation methods
- Better selectivity, peaks tend to be narrow
- Depolarization studies possible, enhanced effects in some cases
- Can detect IR-inactive vibrational modes

#### Advantages of FTIR over Raman:

- Raman can suffer from laser-induced fluorescence and degradation
- Raman lines are weaker, the Rayleigh line is also present
- Raman instruments are generally more costly
- Spectra are spread over many um in the IR but are compressed into several nm (20-50 nm) in the Raman

Final conclusion – they are complementary techniques!

#### man Spectroscopy: Informations





### arbon Allotrope



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# Basic Components of Raman system



#### aman Spectrometer





# Laser source



### Which laser shall I choose?

# The relationship of the signal intensity with laser wavelength:

 $I_{\rm Raman} \propto 1/\lambda^4$ 



Choose short wavelength laser for each sample ?

Theoretically YES. However, considering instrument response, green is the most common laser.



#### void Fluorescence Influence



Fluorescence emission will stay with the same wavelength (nm). Raman will stay with the same wavenumber(cm<sup>-1</sup>).



### fo from Different Depths



 $\mathsf{D}_\mathsf{p}\text{-}\mathsf{penetration}$  depth

K-extinction coefficient



#### hy so many laser choices

- **1.** To avoid fluorescence interference
- 2.To avoid black body interference
- 3. To probe at different depths



4. To benefit from Resonance



# Sampling optics / Microscope



### ampling Geometry

 Theoretically, Raman scattering can be observed from any angle. Practically and historically, three angles were favored; 0°, 90° and 180°.



### ° Collection = Forward scattering



#### Transmission Raman (forward scattering)

- No spatial resolution
- Volume measurement
- No information about component distribution
- Good statistical representation of the whole <u>sample</u>
- e.g. Transmission Raman of Capsules







### **30 °Collection = back-scattering**



#### Raman Microspectroscopy (back-scattering)

#### **Illumination Collection**



- Surface measurement
- Measurements of distribution of different components possible (Rama mapping)
- High spatial resolution
- As a whole, good statistical representation of the surface (limited by the penetration depth)









#### anparent Sample





For transparent samples, low N.A. lens enables - Large sampling volume → increases sensitivity





#### hromatic objective



#### HORIBA Scientific Mirror based design :



We observe the sample image and the laser spot on the same plan.

Lens based design :





Optimized on sample image

Optimized on laser spot

The positioning of the measurement point is t in X and Y, and almost impossible in Z.

#### PERFECT TOOL FOR UV-RAMAN MEASUREMENTS Unique design from HORIBA!



# Confocality



# rue Confocal Microscope

#### Advantages of confocal Raman:

- ✓ Tremendous improvement of axial resolution (~2  $\mu$ m)
- ✓ Better lateral resolution (<1µm)
- ✓ Efficient reduction of fluorescence interference

Applications:

- Minute samples quantities micron and sub-micron particles
- Thin films and multilayer samples
- Inclusions in matrices
- IMAGING : phases and components distribution (copolymers, compc)

Raman signal emitted from out of focus regions Ompc

The confocal pinhole acts as an adjustable spatial filter allowing a precise selection of the analyzed volume.

Only LabRAM HR evolution has a continuously adjustable pinhole



### nfocality for fluid inclusions



The semi-confocal and the confocal modes enable to get less interference from the matrix signal (quartz) and improve the signal for each fluid: water in semi-confocal mode,  $CO_2$  gas in confocal mod

#### gh lateral Resolution=diffraction limit





TGX calibration grating Mikromasch



Measurement time 240s, 10201 points, 24 ms/points, 0.1um step 633nm , 100X/0.9, swift









# **Raman imaging**



### hat is Raman mapping?



Images at fixed spectral pos



### ow to make Raman Mapping?

For each point, the Raman spectrum is acquired.

The data cube is then analyzed with Raman band information (e.g. band position, bar width, band shift, etc.)



### **3D Imaging**





#### Description:

XYZ volume map of expanded polymer bead in matrix.

System:	LabRAM HR
Laser:	660 nm
Grating:	300 gr/mm
Objective:	x100
Acq. Time:	0.8 s x 1
Step X:	1 μm
Step Y:	1 µm
Step Z:	1 μm
No. pixels:	186,992
-	(62X x 58Y x 52Z)

Bead

Matrix

Oil (Immersion objective)



# Filters

#### avelength Selector

Rayleigh is 10<sup>9</sup>~10<sup>12</sup> higher than Raman Method to filtrate Rayleigh:

- Filter
  - Edge
  - Notch
  - VBG
- Monochromator-Dispersive Raman
  - Dispersion by Prism
  - Dispersion by Grating
- Michelson Interferometer FT-Raman





### otch filter & edge filters



- A finite life time
- Stokes and Anti-Stokes Raman

A virtually infinite life time

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· Stokes Raman only

There is a cost advantages to use dielectric edge filter due to good cut-off and no aging, but An Stokes-Raman is not obtainable.

Notch dielectric filters are available but their cut-off is not as good as holographic Notch filters.



### tra Low Frequency Applications

#### **Examples**

- ULF bands of protein molecule.
- "Boson peak" in amorphous glasses to study the liquidglass transition.
- ULF vibration modes in minerals and organic materials, such as sulfur and L-Cystine.
- Radial breathing mode of carbon nanotubes and quantum dots.
- Shear mode of graphene.
- Relaxation modes in liquids, binary mixtures and solutions.
- Acoustic modes

### tration with Volume Bragg Gratings BGs)

Ultra low frequency detection by VBGS:

- Down to 10 cm<sup>-1</sup>
- Both stokes and anti-stokes
- Easy to make ULF on single stage spectrometers.
- VBGs filters replace substractive monochromator filtering









#### **ULF Results**



P. H. Tan, State Key Laboratory for SL and Microstr., Institute of Semiconductors, Beijing, P. R. China K. Brunner, University Wurzburg, Germany

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Scientific



#### Key points/Lock-out specs

- Preserves high throughput advantage of single stage spectrographs (favoring sensitivity, mapping speed...)
  - 3 BNF on the Raman path have a transmission >70% @ 633 nm
  - In comparison, standard edge filter has a transmission of about 95%
- Allows measurements down to 10 cm<sup>-1</sup> (sometimes less depending on λexc & sample reflectivity/scattering efficiency)
- Stokes and anti-stokes features measured simultaneously
- Allows to measure the entire Raman/PL range



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# Spectrometers



### **Dectral Resolution**





### hy is high resolution required?



The Stress of Si can be characterized by the peak In this case, the max shift is 0.5 cm<sup>-1</sup> which requires a HIGH SPEC RESOLUT



Distribution of Si stress from Raman mapping

Image of Si chip



Raman spectra



### Detection



#### aman Detection Device History





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#### Human Eyes

#### **Photosensitive Plate**





CCD

PMT



The choice of a multi channel detector depends on:

- Spectral range (UV, Vis, NIR)
- Spectral resolution (pixel size)
- Sensitivity (QE of front vs. back illuminated detectors)
- Raman or Luminescence (etaloning in back illuminated cameras)
- Long or short integration time (TE versus LN<sub>2</sub> cooling)



### **LabSpec 6** Spectroscopy Suite

### owerful!



- Spectrum database searching\*
  - Chemical identification within seconds
- Multivariate Analysis (MVA)\*
  - Obtain results, fast
- ParticleFinder\*
  - Automated particle location and characterization
- 3D Surface and Volume display\*
  - Full display capabilities for 2D and 3D data
- MultiWell high throughput screening\*
  - Fast analysis of well plates and microtitre plates

\* Optional modules







### LabSpec6: EasyNav package

"Easily navigate through high power microscopic images in an easy and sharp manner and acquire sharp Raman images"



#### EasyNavTM package is more than just tracking!





#### NavMap<sup>™</sup>=Navigation Map

- takes low mag image of sample
- instantly know where you are on your sample
- easier to navigate, click & pan directly on the low mag NavMap image, no need for joystick anymore for enhanced user experience

#### NavSharp<sup>™</sup> =Sharp Navigation

NavSharp<sup>1</sup>

 real time tracking of the focus based on video image competes with Renishaw LiveTrack, but much faster





#### ViewSharp<sup>™</sup>=Viewing Sharply

- another add-on compared to LiveTrack; builds the complete image in focus
- gives an instant 3D topography of the sample
- much faster than autofocus of laser at each point
- 0.2µm XYZ resolution with 100X image

### ViewSharp example



#### 3D - Raman image

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#### Image processing

2D and 3D image display modes

#### Sodium sulfide crystal forms









### **3D Surface/volume display**

Advanced display module for

- 2D images as 3D surfaces
- 3D volumes

Full display control

Lighting | rotation | transparency | slicing



#### IORIBA Scientific ONE Raman solution for everyONE



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