LISA Pathfinder and LISA toward a space-based gravitational waves observatory

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Trento Institute for Fundamental Physics and Applications







2016: GW exploration of the Universe has started!











End-to end experimental demonstration of the <u>free fall of test masses</u> at the level required by future space-based GWs observatory like LISA





Performances totally in line with the mission concept in the «Gravitational Universe » selected by ESA for L3 of its Cosmic Vision Program

Gravitational Waves Spectrum



LISA science objectives \rightarrow LISA Mission Requirements \rightarrow LISA payload instrument baseline







lisa pathfinder

Brief LISA description



- 3 identical spacecraft
- 3 arms of 2.5 Million km
- 1 AU , 20-degree trailing Earth orbit
- Triangle rotates and changes
 by ±1.5°, ±20 000 km,±10 m/s



2 Michelson interferometers, heterodyne laser

interferometry in transponder mode

- ➢ 10 pm/√Hz,
- Time Delay Interferometry
- 30 cm telescopes, 2W lasers, 100 pW at

receiver, 1064 nm

Test masses in sub-femto-g free fall
 (3 fm/s²/vHz) of LISA PF



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Covers almost all of the mass-redshift parameter space needed to trace black hole evolution Galaxies host black holes bigger than million solar mass: trace galaxy mergers



Contour plot of constant SNR for the baselin observatory in the plane of total source-fram mass, M, and redshift, z

> wide range of masses observable with high SNR out to high redshift.

> > LISA is a high resolution deep Universe observatory



Stellar-mass BH captured by a massive BH

Probe the dynamics of dense nuclear clusters using EMRIs Explore the fundamental nature of gravity and black holes

- Dozens per year.
- Prove horizon exists.
- Test the no-hair theorem to 1%.
- Masses of holes to 0.1%
- Spin of central BH to 0.001.







Study the formation and evolution of compact binary stars in the Milky Way Galaxy.

- Guaranteed (known) sources at high SNR: verification binaries
- About 20000 double white dwarf binaries resolved
- Discovery of distant/obscured/faint binaries.
- The millions of ultra-compact binaries will form a detectable foreground



Coordinate observation with ground based interferometers and electromagnetic telescopes

Editors' Suggestion

Prospects for Multiband Gravitational-Wave Astronomy after GW150914

Alberto Sesana

Phys. Rev. Lett. 116, 231102 (2016) - Published 8 June 2016



Rates of black hole merger formations inferred from the recent detection of gravitational waves suggest that a future space based facility like eLISA can efficiently inform LIGO and other facilitates about locations of potential black hole mergers



LISA basic «link» concept and performance limit







LISA Pathfinder Concept and Strategy

Most of disturbances are local and can be tested within one satellite!







LISA Pathfinder Concept and Strategy



Most of disturbances are local and can be tested within one satellite!

- Measures differential acceleration noise from stray forces acting on 2 LISA TM
 - Demonstrates the local interferometric measurement of TM acceleration



LISA PF requirement on max differential spurious acceleration

$$S_{\Delta g}^{\frac{1}{2}} \le 30 \frac{fm}{s^2 \sqrt{Hz}} \times \sqrt{1 + \left(\frac{f}{3 \, mHz}\right)^4}$$

 $1 \, mHz \leq f \leq 30 mHz$

Relaxed by a factor 7 relative to LISA to allow for :

- possible more hostile spacecraft environment
- stray effects strictly due to single spacecraft configuration





The L/TP

- Test masses gold-platinum, highly non-magnetic, very dense
- Electrode housing: electrodes are used to exert very weak electrostatic force
- UV light, neutralize the charging due to cosmic rays
- Caging mechanism: holds the test-masses and avoid them damaging the satellite at launch
- Vacuum enclosure to handle vacuum on ground
- Ultra high mechanical stability optical bench for the laser interferometer











United States

LISA Pathfinder Contributions

Norway Det Norske Veritas

Denmark Terma

United Kingdom Airbus Defence & Space, ABSL Power Solutions, SCISYS University of Birmingham, Mullard Space Science Laboratory University of Glasgow, Imperial Callege London

Belgium SpaceBel, Thales Alenia Space

France Thales Alenia Space APC – AstroPorticule et Cosmologie, Paris

Italy Selex ES, Thales Alenia Space Università di Trento – INFN, OHB CGS, Thales Alenia Space

Spain Airbus Defence & Space, ALTER Technology, RYMSA Espacio Instituto de Ciencias del Espacio (CSICIEEC), UPCIEEC, TAGE, UTC. SURC. CAM. Finland

Sweden

RUAG Space

RUAG Space

SRON

Netherlands

Germany

Airbus Defence & Space, IABG, AZUR SPACE Solar Power, ZARM Technik Max Planck Institute for Gravitational Physics (AEI), Leibniz Universität Hannaver, Airbus Defence & Space, Teost-Spacecam, OHB System, IABG

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Austria

RUAG Space, Siemens Magna Steyr

Switzerland

RUAG Space RUAG Space, ETH Zurich, Universität Zurich, HES-SD Valais

Portugal

Critical Software









The real thing!!!









LISA Pathfinder as differential accelerometer





The satellite and TM2 are following TM1

 $o_1 = x_1 - x_{SC} + n_1$

Nulled by the drag free loop

 $o_{12} = x_2 - x_1 + n_{12}$

Nulled by the electrostatic suspension (below 1 mHz)

$$a_{TM_{2}} - a_{TM_{1}} = \frac{f_{TM_{2}}}{m} - \frac{f_{TM_{1}}}{m} + (\omega_{2}^{2} - \omega_{1}^{2})(x_{1} - x_{SC}) + \omega_{2}^{2}(x_{2} - x_{1}) - \frac{F_{ES}}{m}$$

$$\Delta g - (x_{2} - x_{1}) + (w_{2} - w_{1})(x_{1} - x_{SC}) + \omega_{2}(x_{2} - x_{1}) - \frac{m}{m}$$

$$\Delta \hat{g} \equiv \ddot{o}_{12} - \frac{F_{ES}}{m} + \left(\omega_2^2 - \omega_1^2\right) o_1 + \omega_2^2 o_{12}$$
$$= \Delta g + \ddot{n}_{12} + \left(\omega_2^2 - \omega_1^2\right) n_1 + \omega_2^2 n_{12} + n_{F_{ES}}$$





Last published «best estimate» of LPF noise (pre-flight)





Launch, Cruise, Commissioning and ...Science Operations start



- LISA Pathfinder was launched on 3 December 2015 at 04:04UTC
 - Transfer to Lagrange Point 1 (L1) took ~50 days
 - 11 January Switch-on of LISA Technology Package
- ➤ 15 & 16 February Test Mass release → free floating test masses
 - > 1 March Start of Science Operations
 - > NASA DRS joint operations July-December 2016
 - 7 December 2016 mission extension began
 - Switched off in July 2017





First results from LISA Pathfinder

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Centrifugal force correction below 0.5 mHz





All measurements are performed wrt SC reference frame that is a rotating frame



few degrees per day guaded pelonite distribution anten starp triat kers dward tive Eacts C attitude controlle

$$g_{\Omega} = \left(\vec{\Omega}_{SC} \times (\vec{\Omega}_{SC} \times \vec{r}_{TMs})\right) \cdot \vec{e}_x$$

 $\propto \Omega_{qs} \Omega_n$



estimate from Star Trackers

estimate by integrating the torque applied to TMs to hold them with fixed orientation wrt SC

we generate the time series of the centrifugal force.

Not relevant for LISA





Compare with the pre-flight noise bydget

$$\Delta \hat{g} \equiv \ddot{o}_{12} - \frac{F_{ES}}{m} + \left(\omega_2^2 - \omega_1^2\right) o_1 + \omega_2^2 o_{12} - g_\Omega$$

= $\Delta g + \ddot{n}_{12} + \left(\omega_2^2 - \omega_1^2\right) n_1 + \omega_2^2 n_{12} + n_{F_{ES}} + n_g$

$$S_{\frac{F_{ES}}{m}}^{\frac{1}{2}} \simeq \Delta g_{st} \, 2 \, S_{\frac{\delta V}{V}}^{\frac{1}{2}}$$

 $\Delta g_{st} < 20 \text{ nm/s}^2$ **On-flight**

lower force authority →lower actuation noise And at 1mHz is now neglibile







lisa pathfinder

Reducing Δg_{st} by gravitational balance

By means of a protocol based on:

- measurements of the "as-built" position and the mass of all parts (>10000)
 - finite element calculation tool

Updated at different stages of hardware construction ...and correct with balance masses







Spacecraft finite element model



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Compare with the pre-flight noise budget

$$\Delta \hat{g} \equiv \ddot{o}_{12} - \frac{F_{ES}}{m} + \left(\omega_2^2 - \omega_1^2\right) o_1 + \omega_2^2 o_{12}$$
$$= \Delta g + \ddot{n}_{12} + \left(\omega_2^2 - \omega_1^2\right) n_1 + \omega_2^2 n_{12} + n_{F_{ES}}$$



Brownian noise due to residual gas pressure

$$S_{gas_d}^{\frac{1}{2}} = \left(\frac{2Ps^2}{m^2}\sqrt{\frac{512\,m_0k_BT}{\pi}}\left(1+\frac{\pi}{8}\right)\right)^{\frac{1}{2}}$$



Pre-flight estimation: 2 μ Pa

The noise floor In flight could be explained by ~10 μPa of H₂O decreasing in time



UNIVERSITÀ DEGLI STUDI DI TRENTO ➢ Brownian noise reduces in time and by decreasing the temperature → decrease the outgassing rates
→ decrease in pressure around the test masses

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Brownian noise of about 1 μ Pa residual gas of H₂O

Final published results: February 2018

 10^{-5}

 10^{-4}



Residual gas Brownian noise



 10^{-3}

Frequency [Hz]

 10^{-2}





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LTPDA 3.0.12.ops (R2015b), 2017-07-11 00:44:52.225 UTC, LPF_DA_Module: 8a04b9f, ltpda: 88427c3, iplotPSD

BUT noise budget (conservative) explains less than half noise (power) at low frequencies

Further stray forces investigations for LISA

Possible noise sources at very low frequency:

- Low frequency magnetic fluctuations.
- Fluctuations of GRS-TM relative position with T.
- Spontaneous outgassing.
- Small-scale surface potential fluctuations.
- Pressure fluctuations in the tanks.
- Outgassing of the spacecraft.

Possible sources of glitches:

- No torque, environmental, diagnostic coincidences. No change Δg DC.
- Thermo-mechanical liberated gas outburst requires 10 nPa on top of μPa.
- Possibly testable on ground with torsion pendulum.

Free fall performance consolidation

 Gravitational Reference Sensor physical properties and their on-ground verification strategy need to be consolidated in order to guarantee the same level of performance also on the final observatory.

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 Measurement, calibration, and mitigation of some known force sources will be required also in LISA → transfer of LISA Pathfinder stray accelerations measurement and suppression strategies to the LISA mission design.

LISA performances assessment





Laser interferometry

- for the drag-free control has been developed and tested in LISA PF
- Ground based demonstrator
- Inter-spacecraft laser interferometry: Laser Ranging Interferometer will be demonstrated on GRACE Follow-On mission using elements inherited from LISA technology development efforts.
- GRACE Follow-On is a US-German joint project
- Targeted to launch May 22, 2018 !!!!



LISA Instrument

- The Gravitational Reference Sensor with the test-mass
 The Optical Bench with:
 - Local interferometer
 - Spacecraft to spacecraft interferometer
 - Telescope for the spacecraft to spacecraft interferometer



LISA long arm interferometry challenges

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Precision million km spacecraft to spacecraft precision ranging

High stability telescopes High accuracy phase-meter and frequency distribution High accuracy frequency stabilization (incl. TDI)

Telescope Pointing

LISA moving optical subassemblies (MOSAs): telescope+ optical bench + GRS





courtesy of Airbus D&S

LISA Mission Schedule

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- At the end of 2016: Call for mission project addressing the science of the "Gravitational Universe" was issued by ESA
- An international collaboration of scientists called "LISA Consortium" submitted a proposal in January 2017
- Beginning 2017 ESA started CDF study
- Mission selection in June 2017
- Mission Definition Review in Nov 2017

Phase A , industrial implementation studies 2018-2020

- Mission adoption 2020-2022
- **Launch 2030-2034**

Parallel competitive industrial studies for mission design just startet !

THALES-ALENIA (Torino)

ASTRIUM



The LISA Consortium: 12 EU Member States +US

www.lisamission.org/proposal/LISA.pdf

LISA Consortium

Led by K.Danzmann

In parallel with the mission study, the Consortium will:

support the definition of the payload, the requirements and the performances.

support ESA System Engineering Office

deliver the integrated and tested science instrument at the heart of the payload, lasers and telescopes, will be procured by ESA or provided by NASA

Active Science Working Groups

- Astrophysics;
- Cosmology;
- Fundamental Physics;
- LISA Data Challenges;
 - Simulation;
- Advocacy and Outreach

interface with the science community interested in LISA



LISA Organigram in PHASE A

Communication Personnel provided Advice Reporting

Thank you !!!

https://www.elisascience.org/



EXTRA SLIDES

At very low frequencies the spacecraft is a rotating reference frame – Part I



At very low frequencies the spacecraft is a rotating reference frame – Part II

$$\Delta g(t) = a_{12} - \lambda f_{2,cmd} + \omega_2^2 o_{12} + \Delta \omega^2 o_1 +$$

 $-\vec{\omega} \times (\vec{\omega} \times \vec{r_{12}}) \cdot \hat{\imath}$ Centrifugal

 $-(\vec{\omega} \times \vec{v_{12}}) \cdot \hat{i}$ Coriolis

 $-(\overrightarrow{\omega} \times \overrightarrow{r_{12}}) \cdot \hat{\iota}$ Euler

Ω̂~ 10⁻¹⁰ - 10⁻¹¹ rad s⁻²/sqrt(Hz)
 @ 0.1 mHz

		Estimated $\pm \sigma$	
	before	from	after
Parameter	$19 \ \mathrm{June} \ 2016$	$19 \mbox{ to } 25 \mbox{ June } 2016$	$25 \ \mathrm{June} \ 2016$
$\delta\phi \ ({ m mrad})$	$-0.47~\pm~0.03$	$-0.40~\pm~0.03$	$-0.39~\pm~0.02$
$\delta\eta \ ({\rm mrad})$	$-0.066~\pm~0.007$	$-0.032~\pm~0.003$	$-0.137~\pm~0.003$



Courtesy of D. Vetrugno

Glitches in the data were detected



Statistics and characteristics

- Observationally indistinguishable from quasi impulse on TMs.
- Duration: few seconds hours (rare).
- Arrival: 0.8/day (Poissonian).
- Impulse: about 10 pm/s.
- Model: double exponential, single amplitude.

Da Gerhard

New features compared to LPF

- Armlength 2..3 Mio km
 → use of telescopes, ≈100 pW received power
- Velocity ±10 m/s → Doppler ± 10 MHz
 → heterodyne inteferometry at 5...25 MHz
- Armlength variation ±1% = 20000...30000 km,
 → Time Delay Interferometry to cancel frequency noise
- Need for very stable sampling clocks, passively synchronized betwen 3 spacecraft
 - \rightarrow clock noise transfer with GHz sidebands on laser beams
- Angle variations ±1.5°
 → Pointing mechanism, two options
- Point-Ahead Angle ±6 µrad
 → Point Ahead Angle Actuator Mechanism (PAAM)
- Absolute ranging of armlengths and data transfer between the arms
 → additional weak spread spectrum code modulation on laser beams

Sub-femto-g differential accelerometry: orders of magnitude improvement in the field of experimental gravitation





- SO 2 Trace the origin, growth and merger history of massive black holes across cosmic ages
- SO 3 Probe the dynamics of dense nuclear clusters using extreme mass-ratio inspirals (EMRIs)
- SO 4 Understand the astrophysics of stellar origin black holes
- SO 5 Explore the fundamental nature of gravity and black holes
- SO 6 Probe the rate of expansion of the Universe
- SO 7 Understand stochastic GW backgrounds and their implications for the early Universe and TeV-scale particle physics
- SO 8 Search for GW bursts and unforeseen sources

LISA: a high resolution, deep Universe observatory





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From laboratory experiments to LISA Pathfinder:

9(Class.	Quantum	Grav.	28	(2011)	094002
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F Antonucci et al

 Table 2.
 Leading sources of differential force-per-unit-mass disturbances and their PSD values at 1 mHz.

Source	PSD (fm $s^{-2} Hz^{-1/2}$)	Estimated from
Actuation, <i>x</i> -axis	7.5 (0.8) ^a	Measurement of flight-model electronics stability
Brownian	7.2	Measurement with torsion pendulum
Magnetics	2.8	Measurement of magnetic field stability
Stray voltages	1.1	Upper limit from the torsion pendulum test campaign
Laser radiation pressure	0.7	Measurement of laser power stability
Force from dynamics of other DoF	0.4	From simulated dynamics of DoF other than x, and estimated worst-case values of $\overrightarrow{\delta D}$ and $\overrightarrow{\delta C}$
Thermal gradient effects	0.4	Upper limit from the torsion pendulum test campaign
Self-gravity noise	0.3	Upper limit from thermo-elastic stability simulations
Noisy charge	0.1	Upper limit from the charge simulation and measured voltage balance
Coupling to SC motion via force gradients	0.1	From the estimation of stiffness and simulated SC jitter
Total	10.9 (7.9) ^a	Root square sum

^a The values within parentheses refer to the free-flight mode. See the text for explanation.

Table 3. Leading sources of optical metrology disturbances, and their PSD values at 30 mHz.

Source	PSD (pm $Hz^{-1/2}$)	Remarks
Phase noise	4	End-to end measurement on the ground, including transmission through optical windows
Pick-up of motion along degrees of freedom different from <i>x</i>	1.6	Analysis based on the simulation of imperfections and the measurement of alignments of the optical bench
Total	4.3	Root square sum



