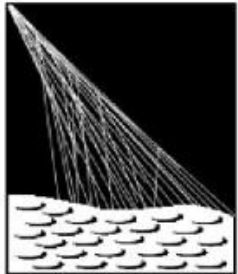


The AUGER Raman LIDAR



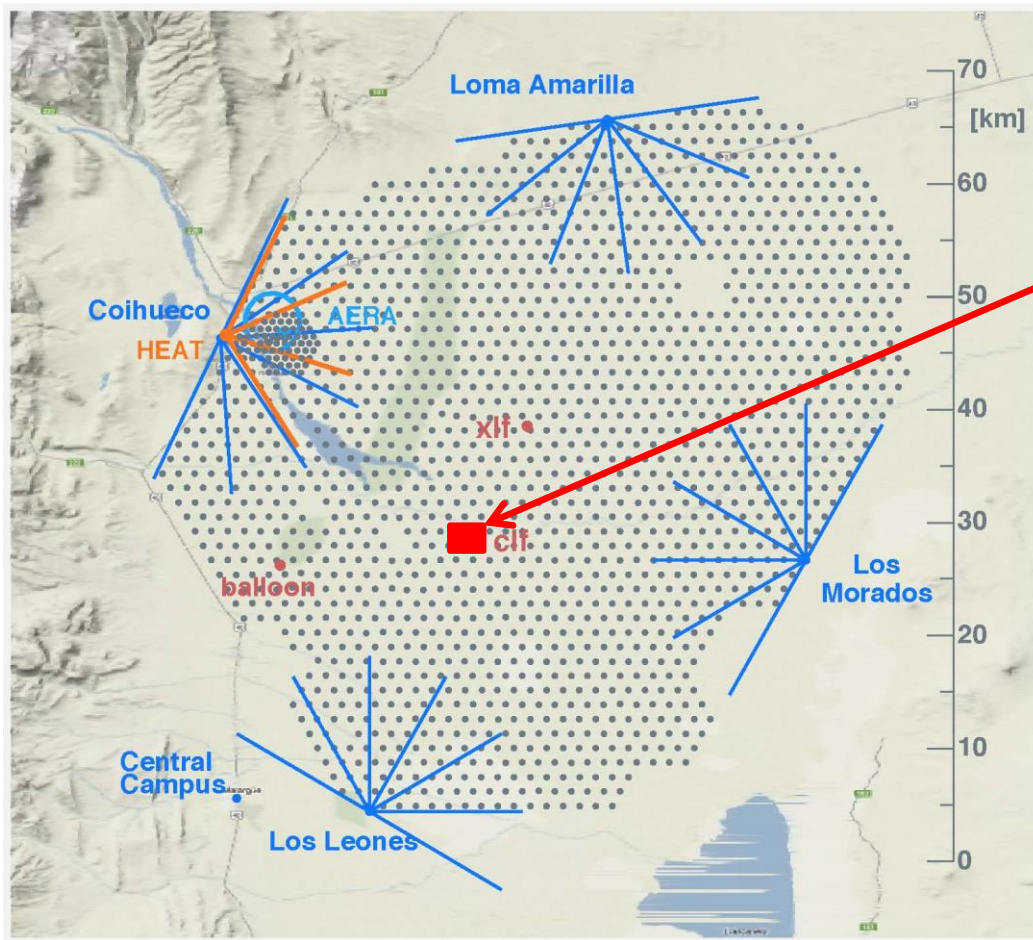
PIERRE
AUGER
OBSERVATORY

CRLF



Raman LIDAR (RL)

The RL system samples vertically the part of the atmosphere **above the CRLF site**, and the retrieved VAOD profiles have a **representativeness** of the aerosol optical transmission in the atmosphere over the Observatory.



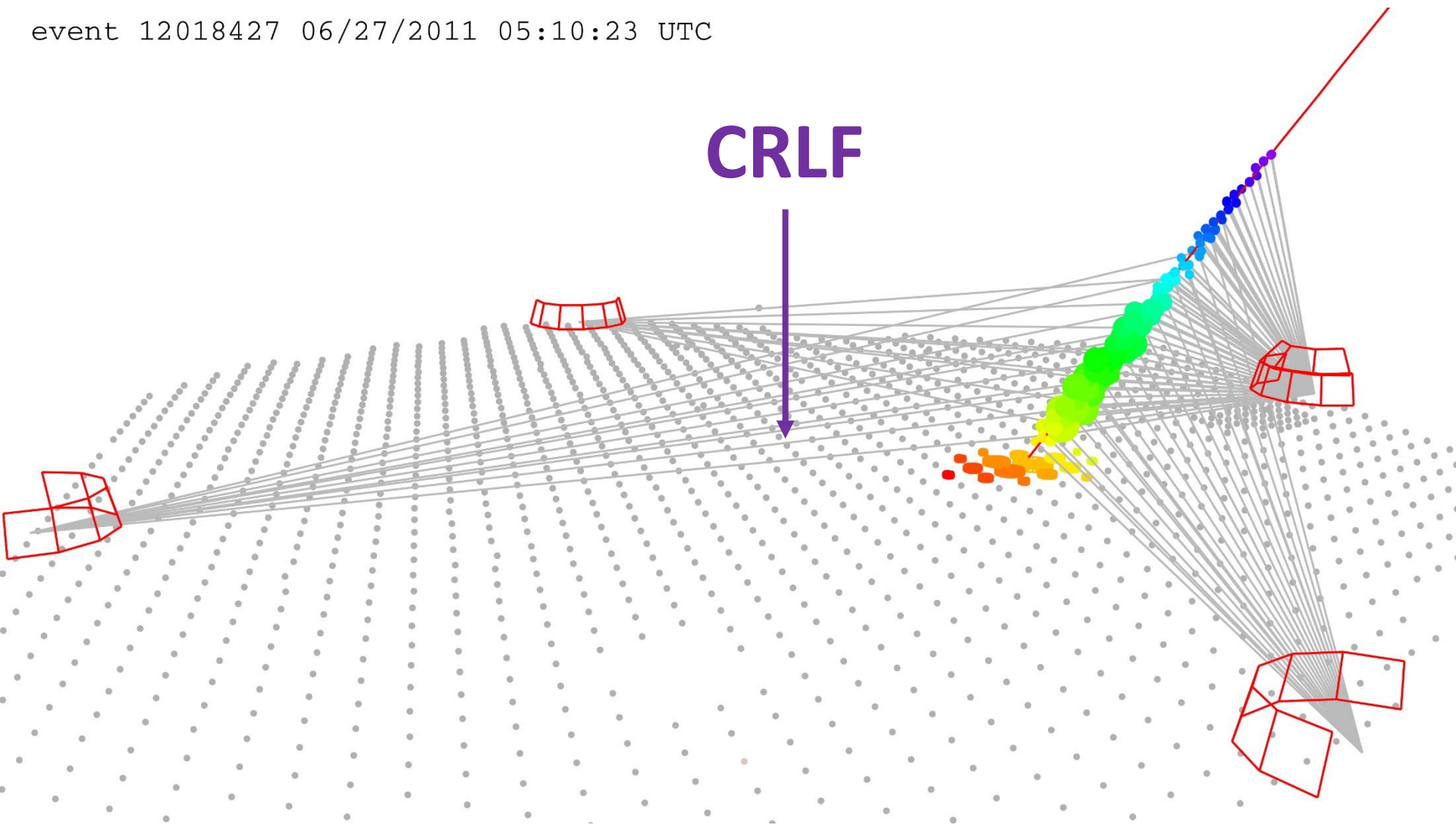




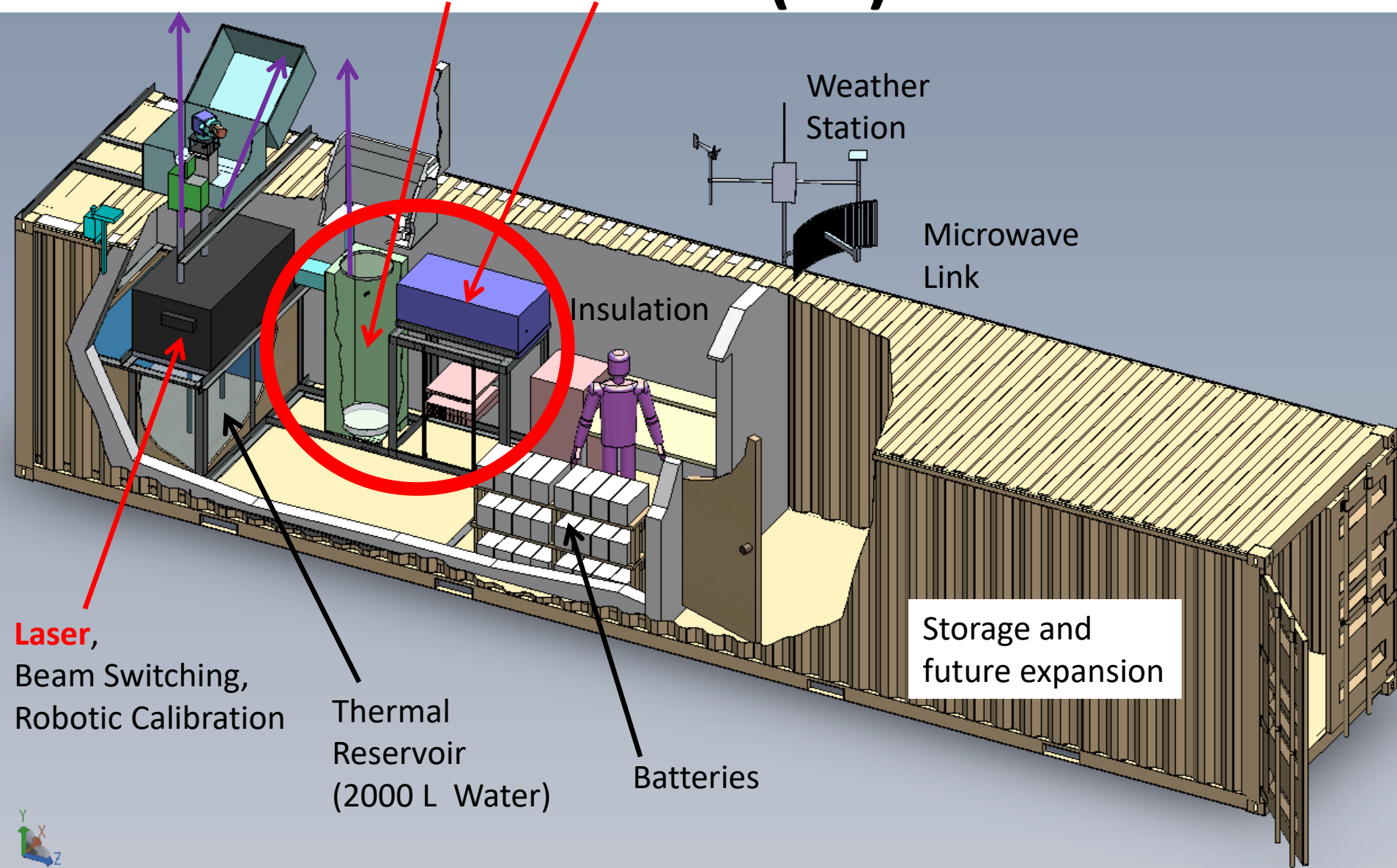


event 12018427 06/27/2011 05:10:23 UTC

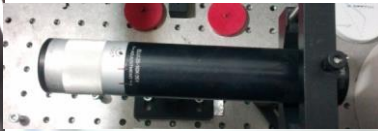
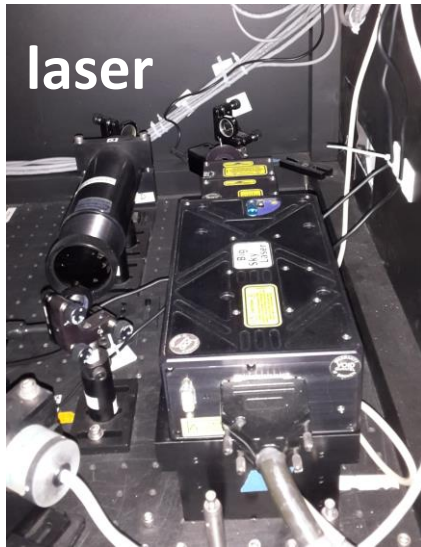
CRLF



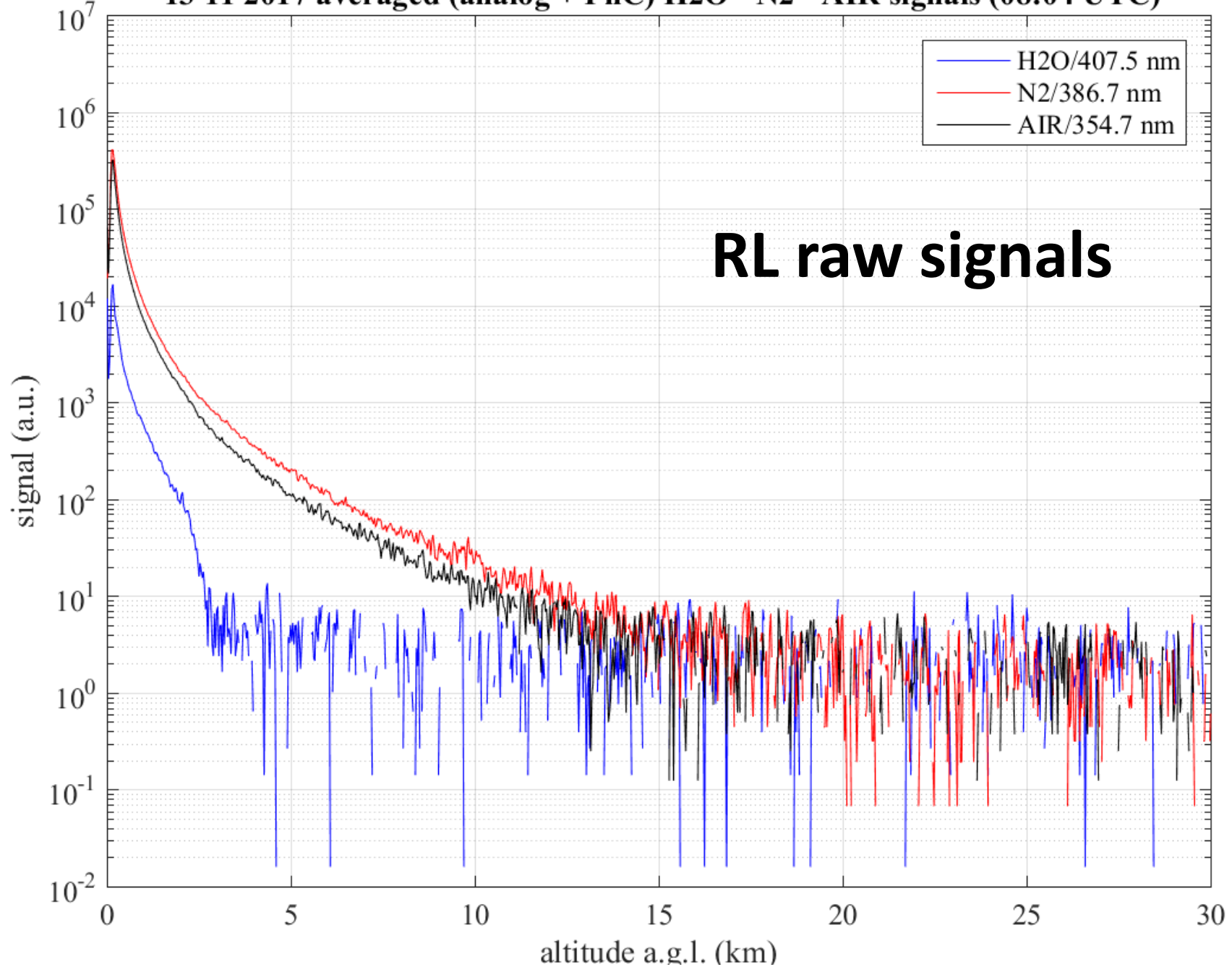
Raman LIDAR (RL)



Raman LIDAR (RL)



13 11 2017 averaged (analog + PhC) H2O - N2 - AIR signals (08:04 UTC)



RL raw signals

Outline:

Performance

Cost

Maintenance

Data

Technical documentation

Science

Some considerations & Summary

Interesting contents in the backup slides ...

Performance

The system is **automatic** and it is run at Central Raman Laser Facility (**CRLF**) during the **FD shift periods** in 3 time windows of about 15 minutes **before**, **during** and **after** (**BDA**) the daily FD shift.

- RAMAN shots: Next bays need to be close from 1:30 to 1:50 local time:

- Los Leones: Bay 4
- Los Morados: Bay 4
- Loma Amarilla: Bay 3
- Coihueco: Bay 3

[...]

[...]

The programmed measurements have been regularly taken. The RL database cover a period between **September 2013** to **present**:

2013-2017

- 2601 measurements of vertical aerosol optical depth profile;
- 2488 measurements of the vertical aerosol volume backscatter profile;
- 1804 measurements of the vertical water vapour mixing ratio profile;

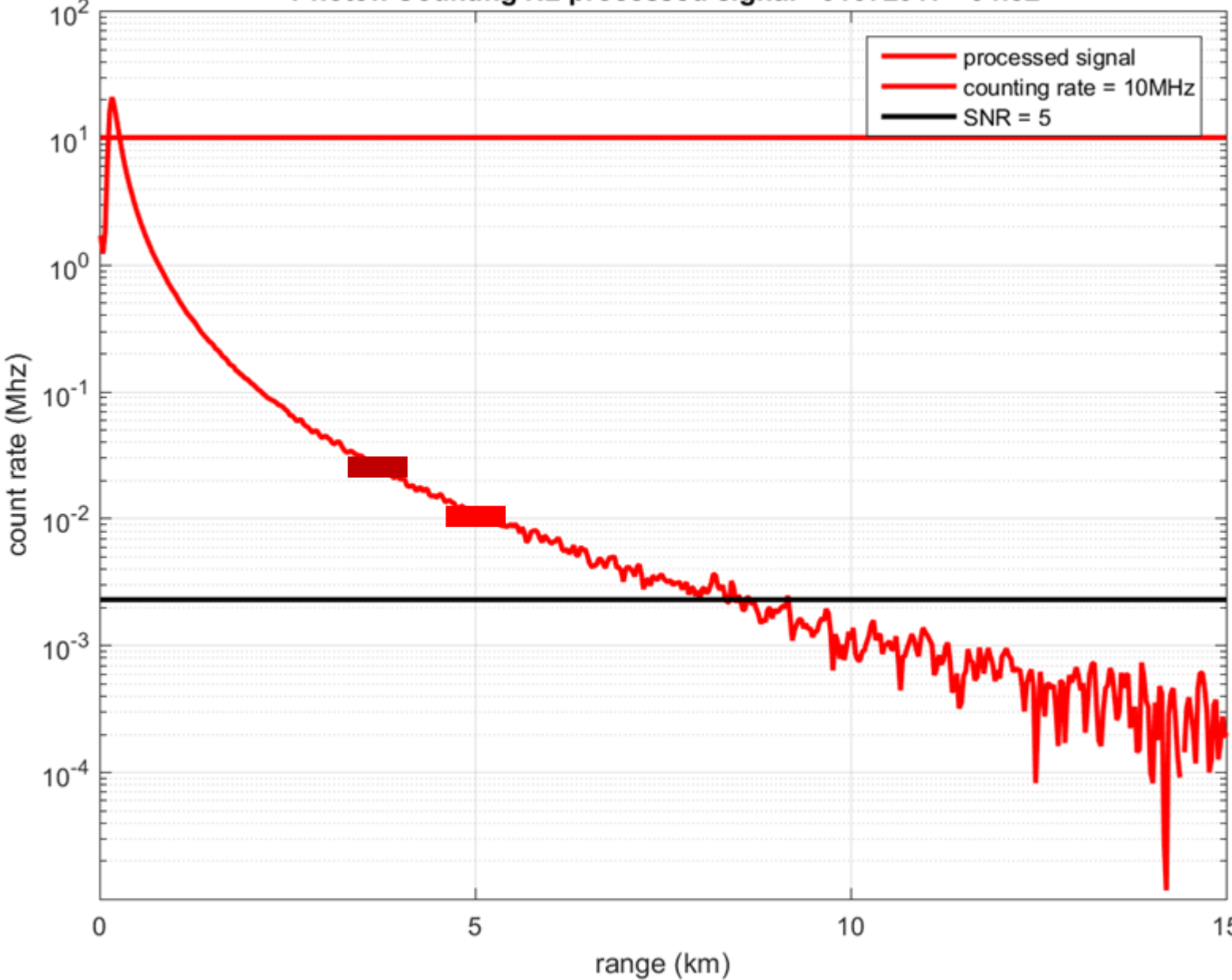
and the current BDA schedule of the observations has started since **October 2014**.

some “metrics” to assess the RL long term performances
September 2013 December 2017

Performance

RL N2 SIGNAL

Photon Counting N2 processed signal - 01072017 - 04:32

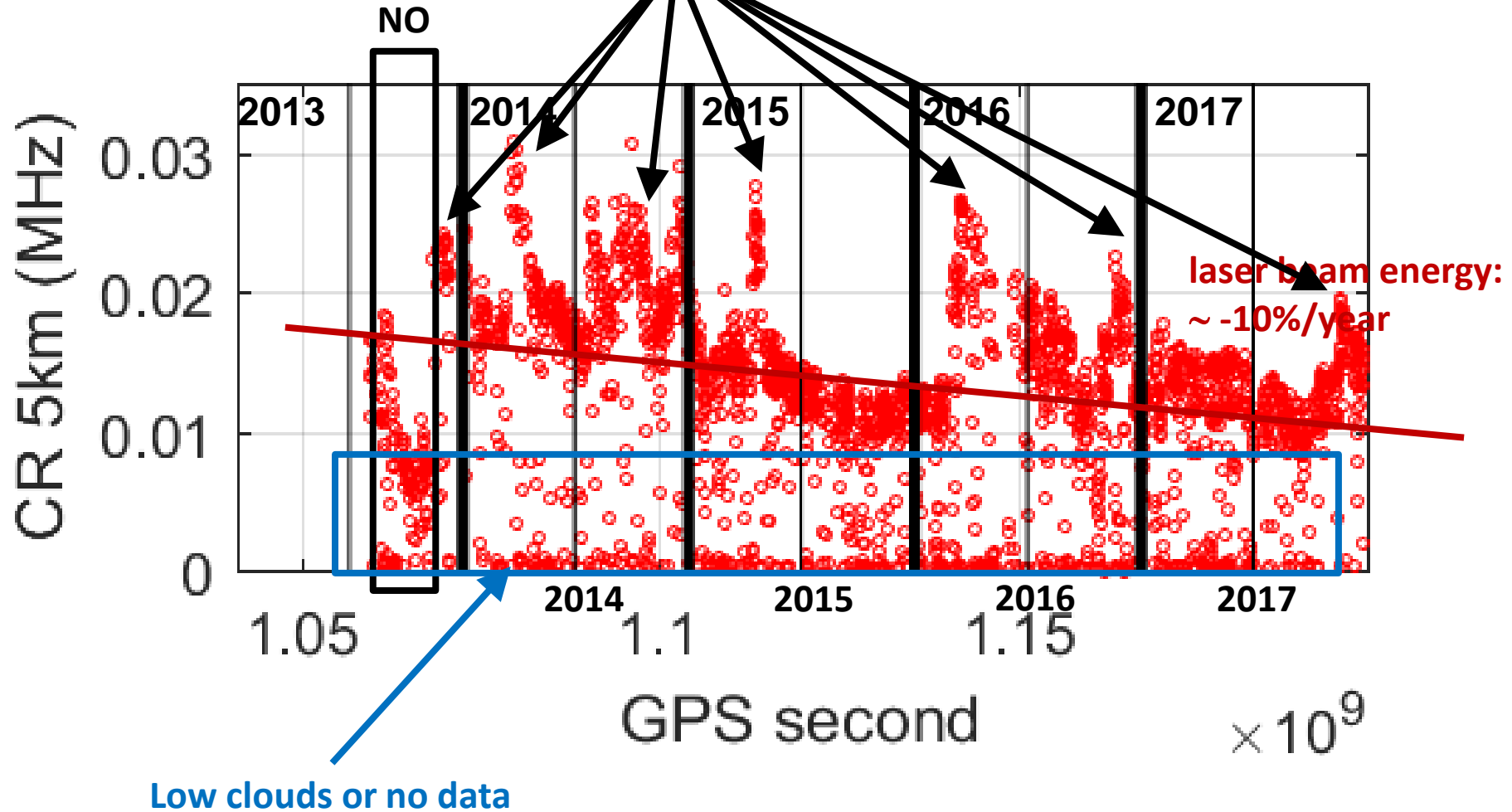


**N2 SIGNAL LEVEL
at 5 km a.g.l.**

CLEANING exit window
and/or telescope mirror

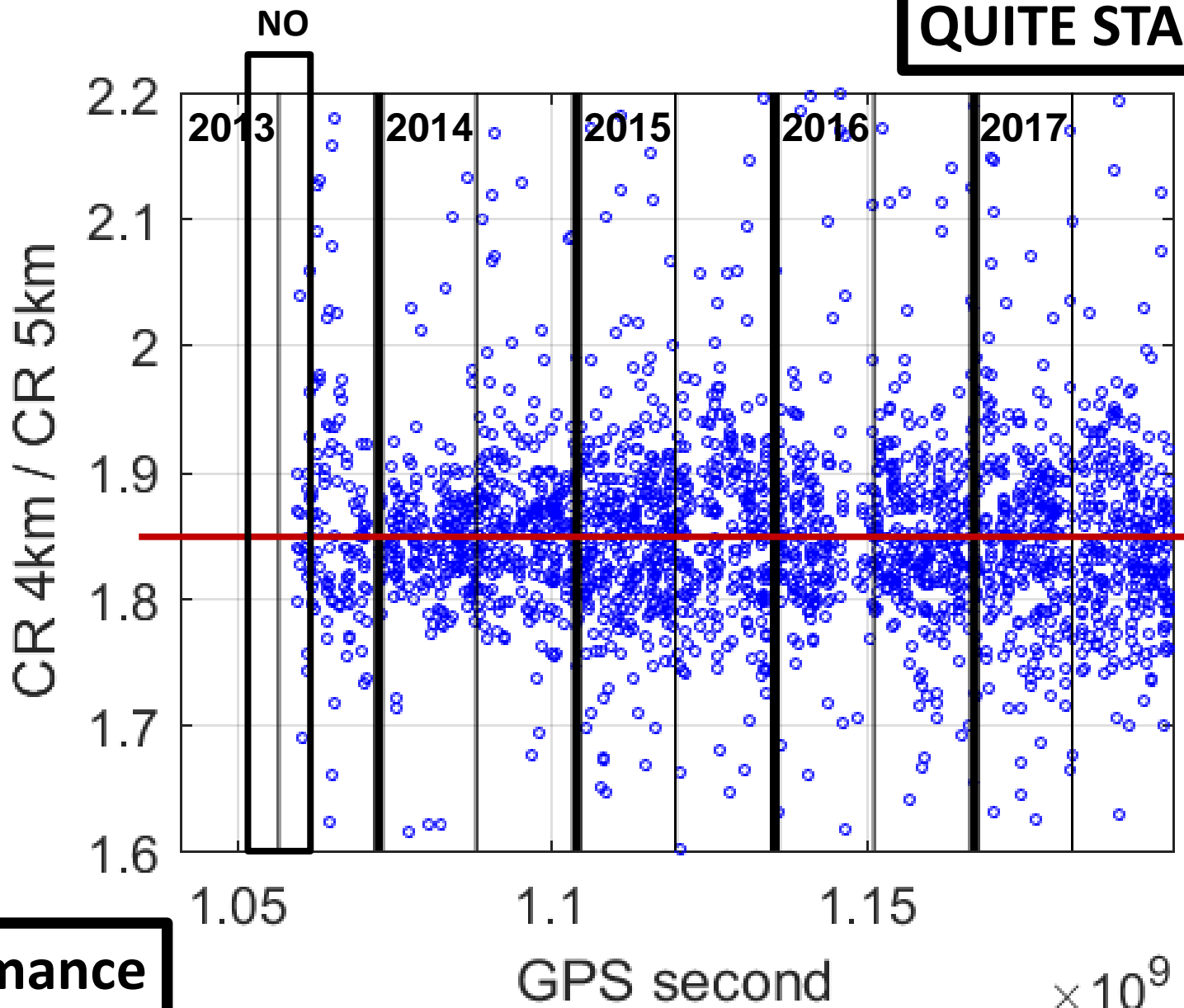
Nov 2013
Mar 2014
Nov 2014

Feb 2015
Mar 2016
Nov 2016
Nov 2017



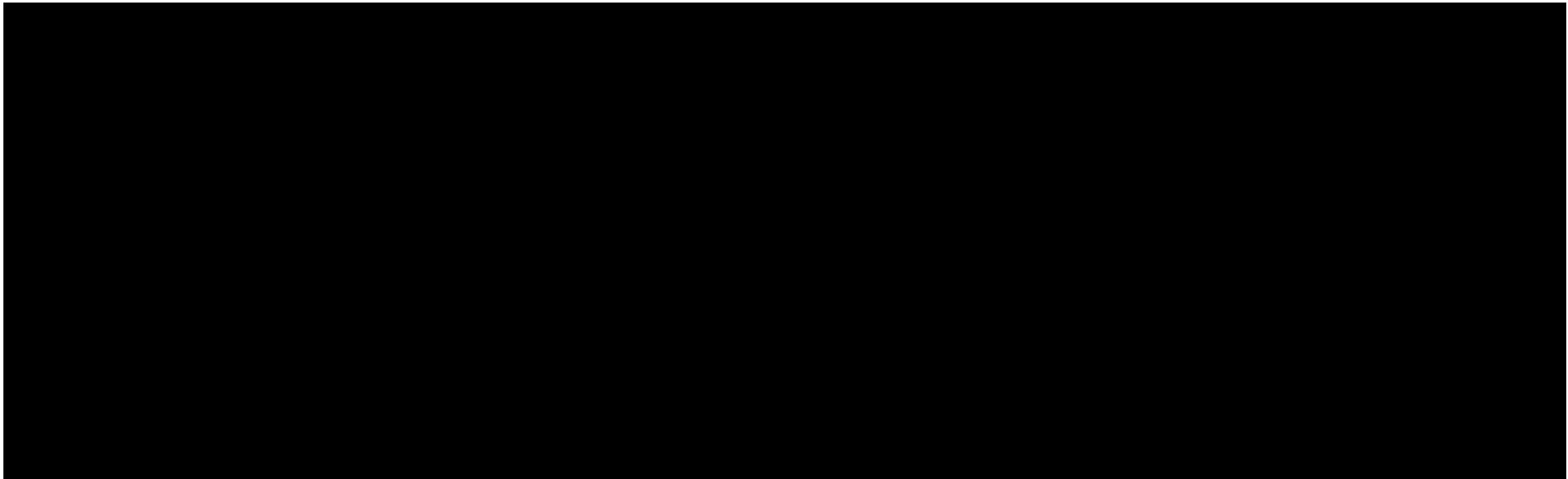
Performance

RATIO OF N2 SIGNAL LEVELS at 4 km a.g.l. and 5 km a.g.l.



Performance

Cost



Maintenance

Once a month, the local staff is taking care of the regular maintenance at CRLF, [...].

[...], 2 times per year, scientists travel to RL site to support **special** activities on RL system and sub-systems (i.e., the **optical alignments of the laser transmitter and of the receiver bench, and the status of the detectors**).

Data

INFN/L'Aquila is also responsible of the analysis of the RL data.

RAW DATA (real-time)

the N2 RL signals are in:

http://cetemps.aquila.infn.it/osservatorio/CLRF_raman_lidar/RL_data/N2_signals/

they are used (usable) to estimate the VAOD profiles

Filenames: **L_N2_DDMMYYYY_hhmm.dat** or **L_N2_GPSsecond.dat** (in **.../GPS_second/**)

Format: **[altitude agl (km)] [pre-processed signal a.u.]**

raw vertical resolution: **30 m**

Data period: **2013, 2014, 2015, 2016 and 2017**

The next release of RL data and software ...

**Raw signals, codes (C++) and documentations.
with the help of several colleagues**

Technical documentation

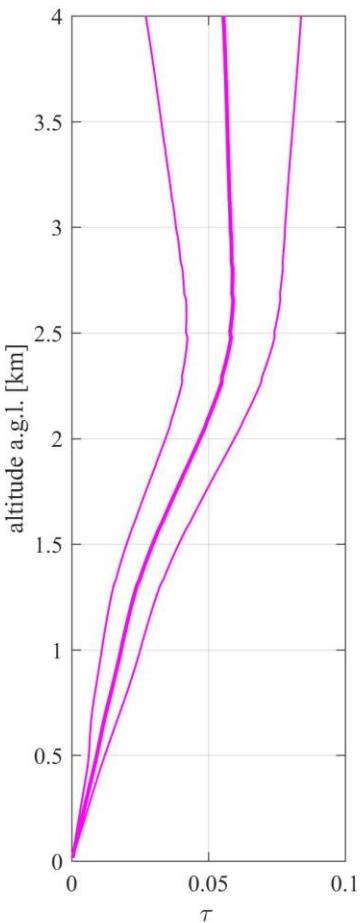
RL system description in paper:

Joint Elastic Side-Scattering Lidar and Raman Lidar Measurements of Aerosol Optical Properties in South East Colorado, Journal of Instrumentation 12(03):P03008, March 2017, DOI: [10.1088/1748-0221/12/03/P03008](https://doi.org/10.1088/1748-0221/12/03/P03008)

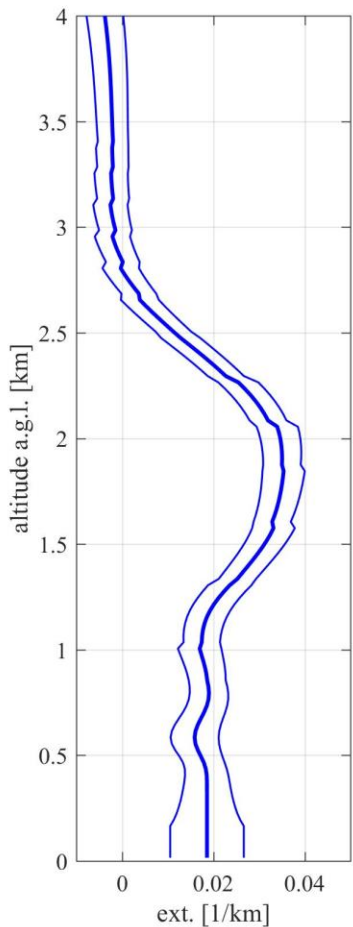
Drawings and users' manuals.

12 min run during FD shift

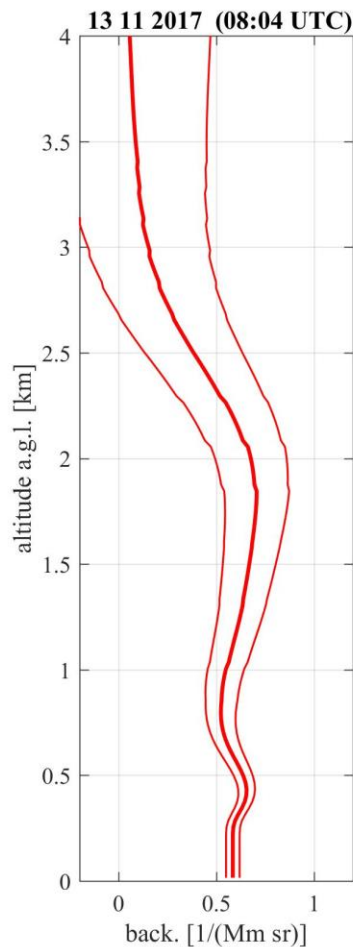
VAOD



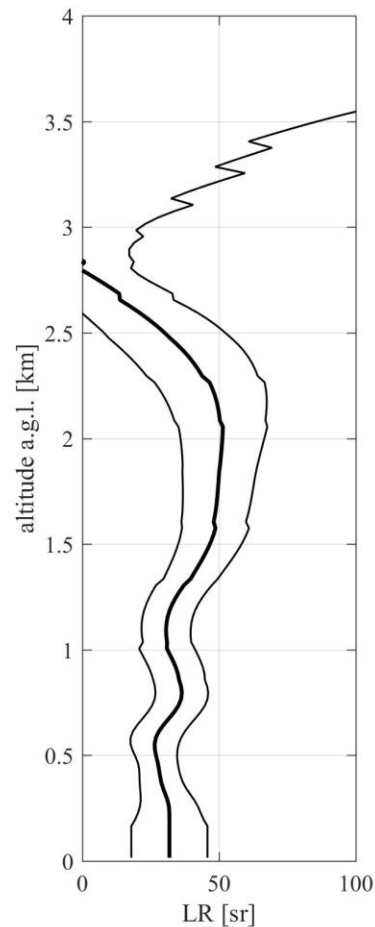
aerosol
extinction



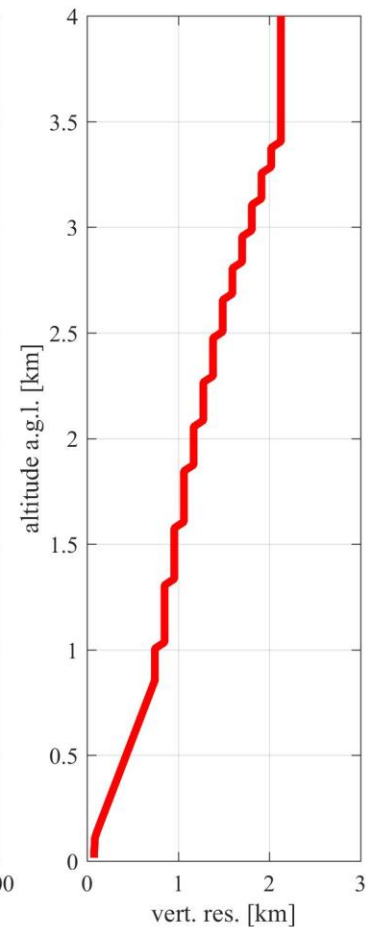
aerosol
backscatter



lidar
ratio

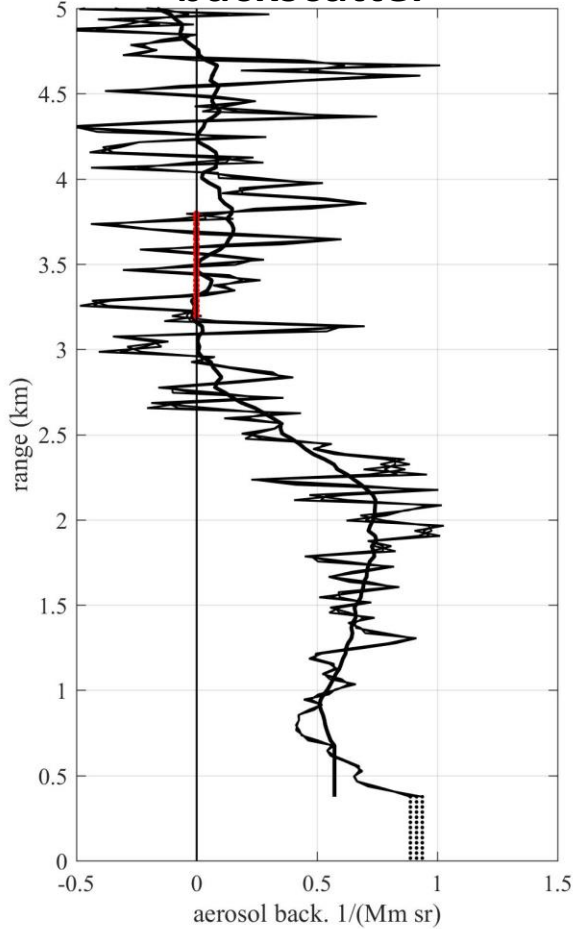


vertical
resolution



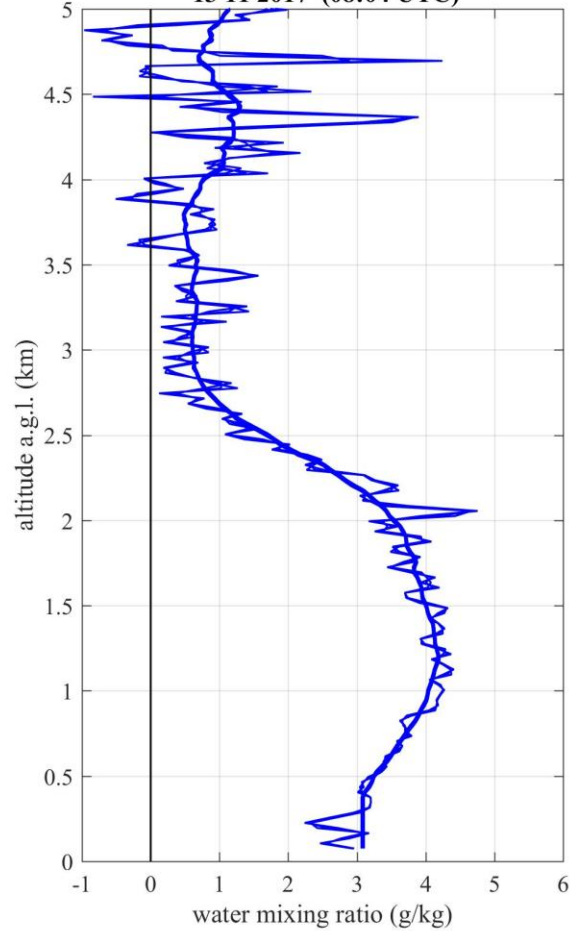
13/11/2017 08:04 – 08:16 UTC

aerosol
backscatter

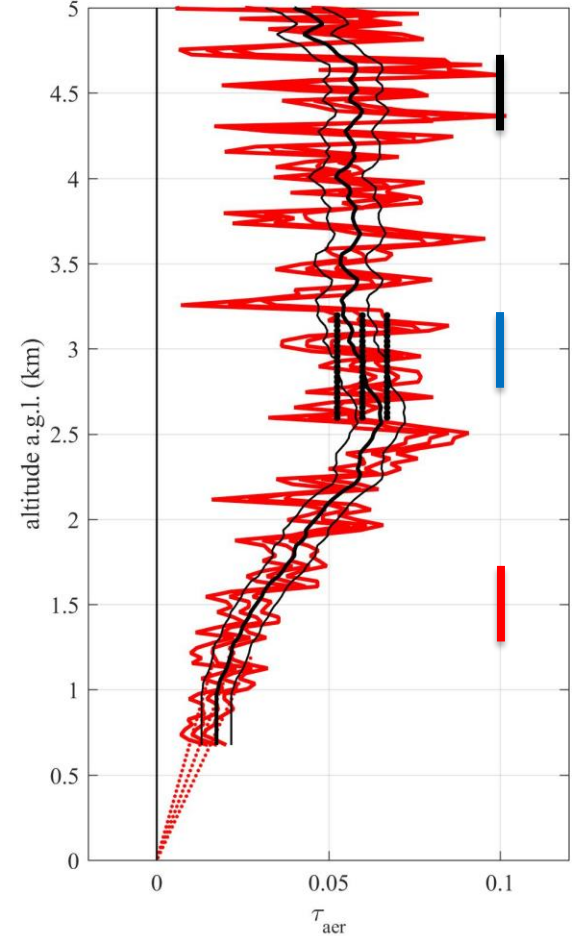


[H₂O]

13 11 2017 (08:04 UTC)

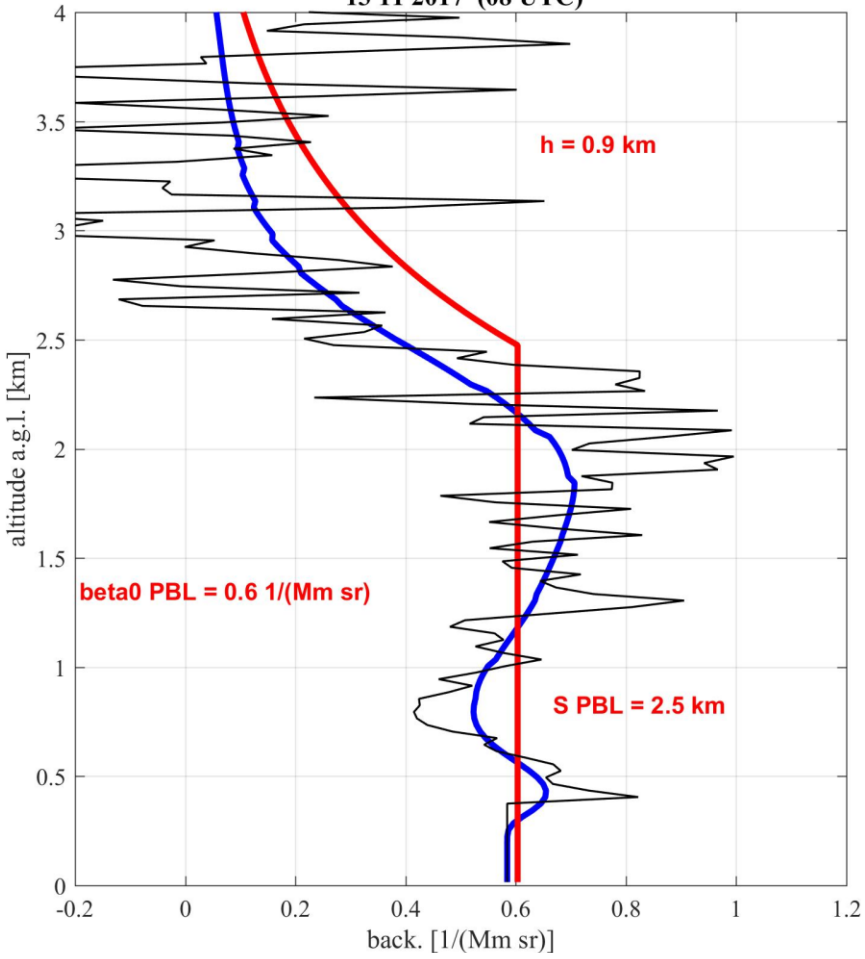


VAOD



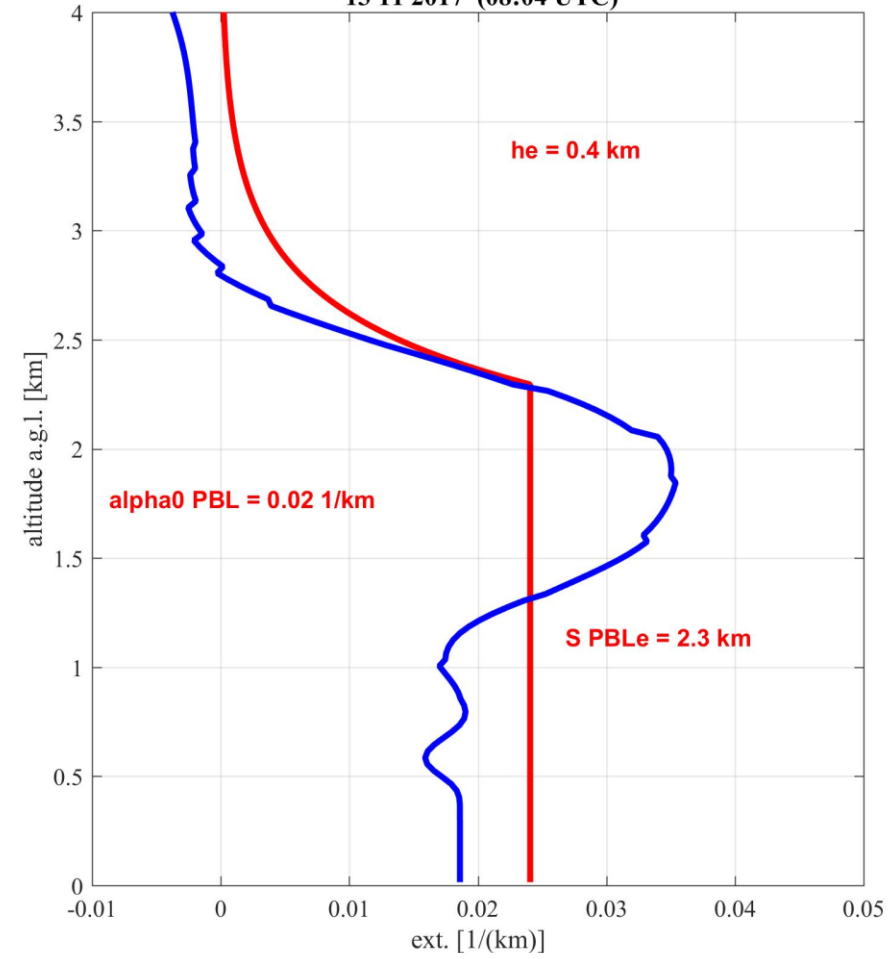
13/11/2017 08:04 – 08:16 UTC

13 11 2017 (08 UTC)



aerosol backscatter

13 11 2017 (08:04 UTC)



aerosol extinction

aerosol model ...

PBL height and transition zone to free troposphere

VAOD data selection:

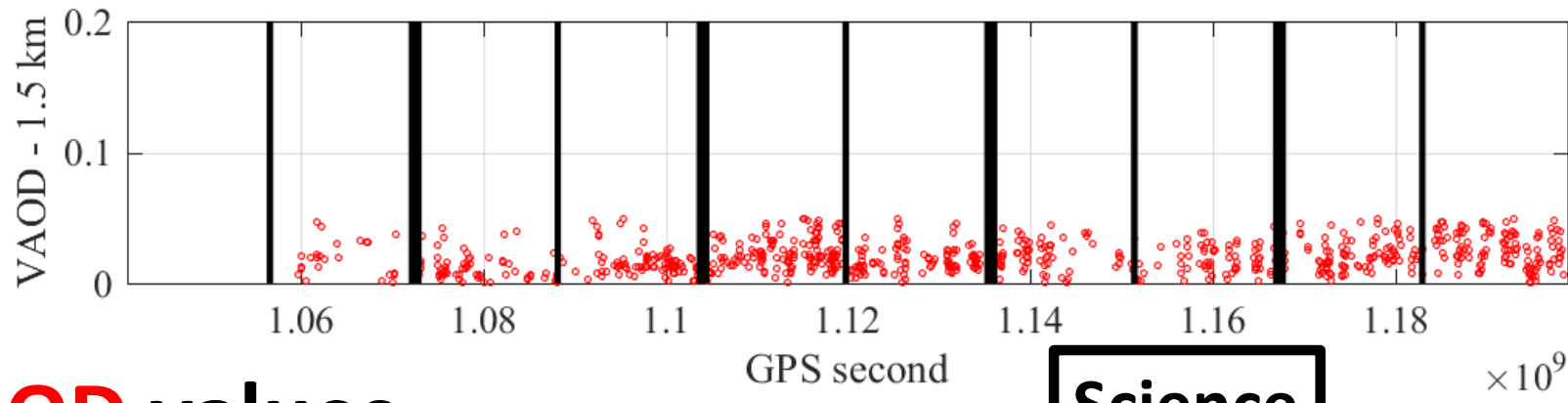
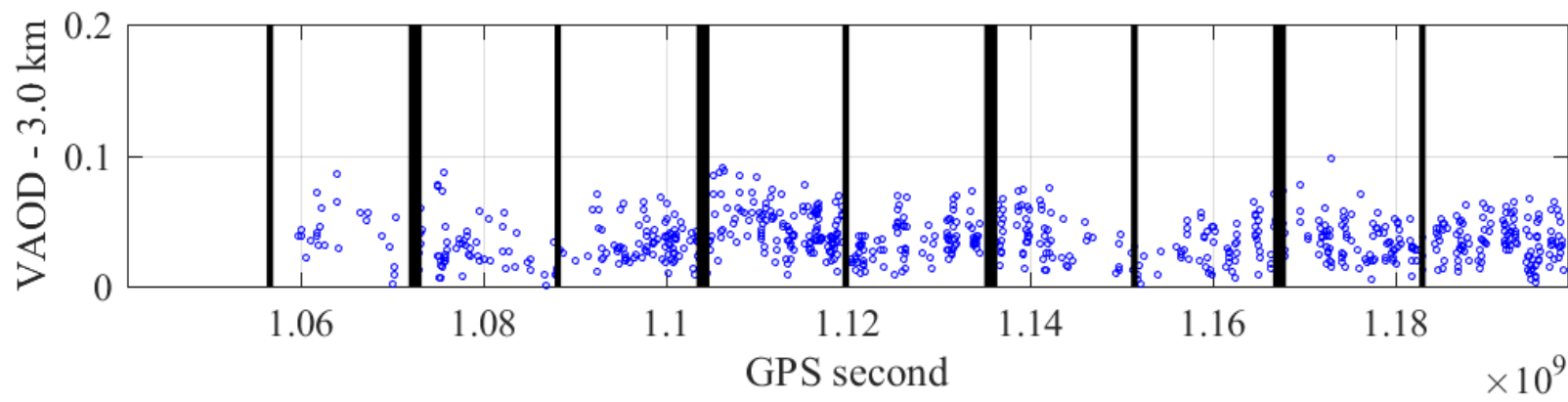
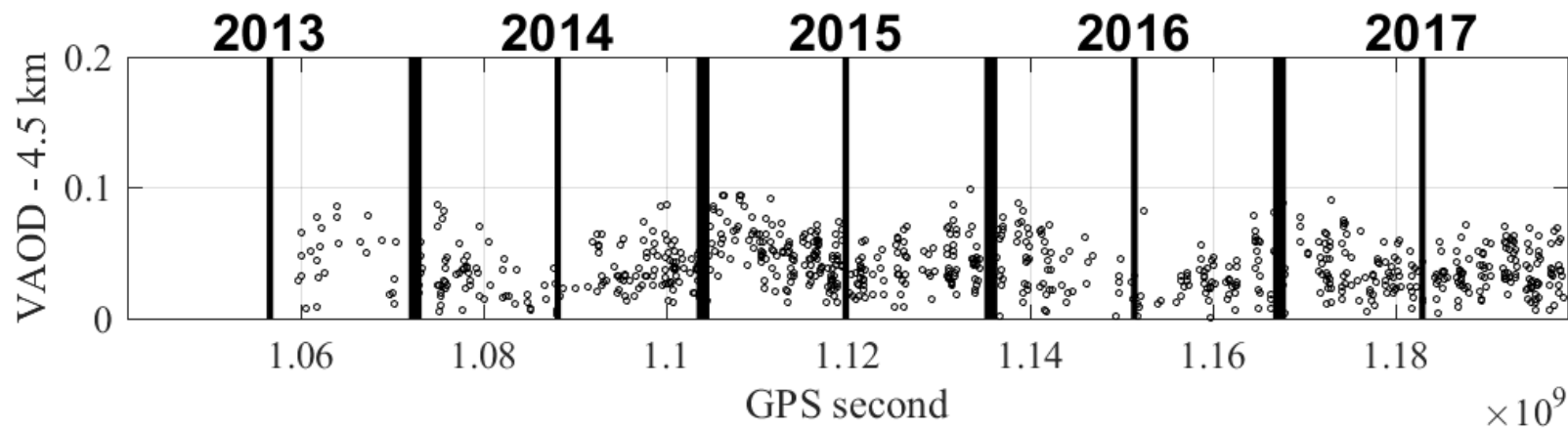
simple criteria

$0 < \text{VAODvalue@1.5km} < 0.05$

$0 < \text{VAODvalue@3.0km} < 0.10$

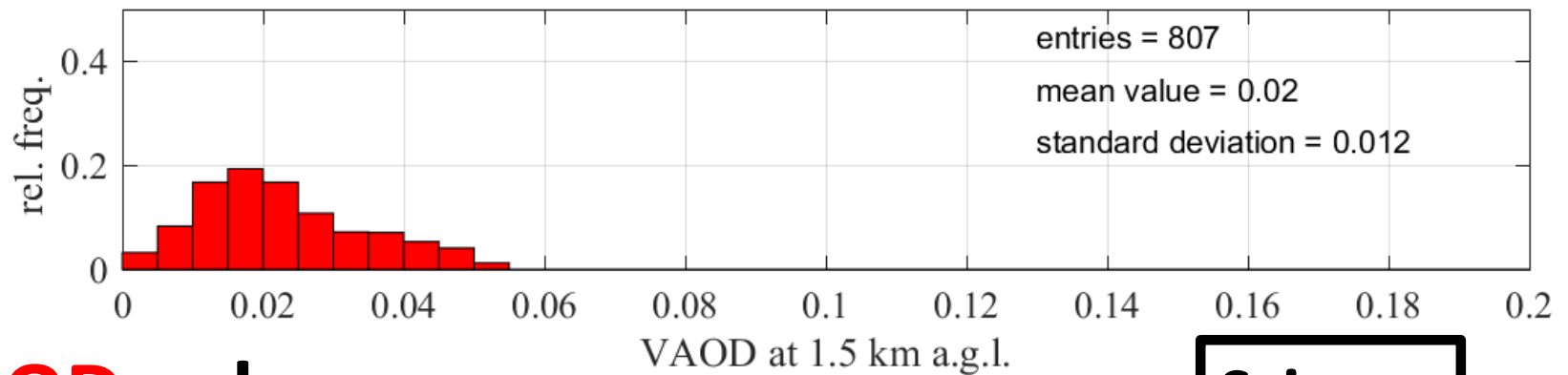
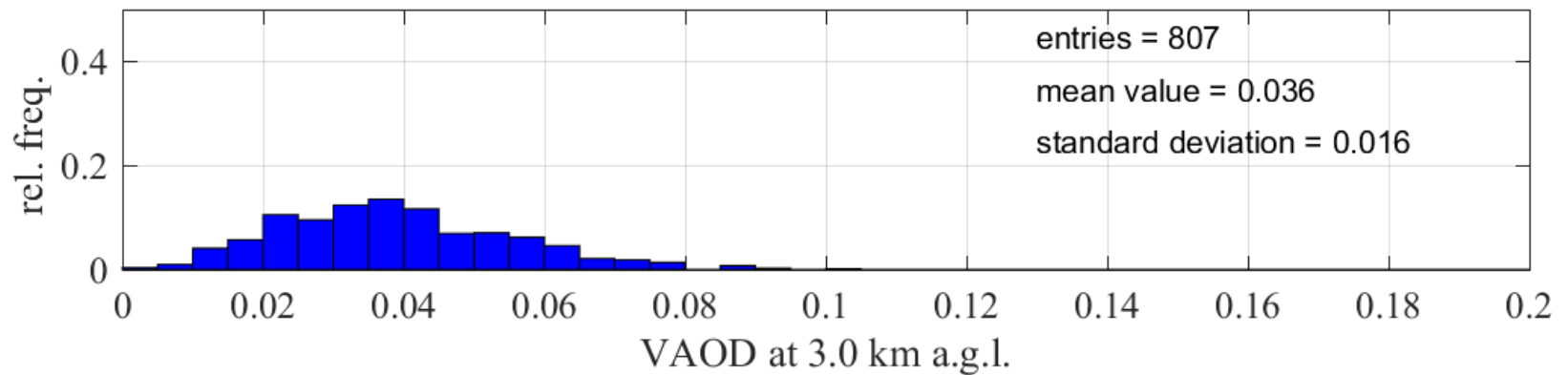
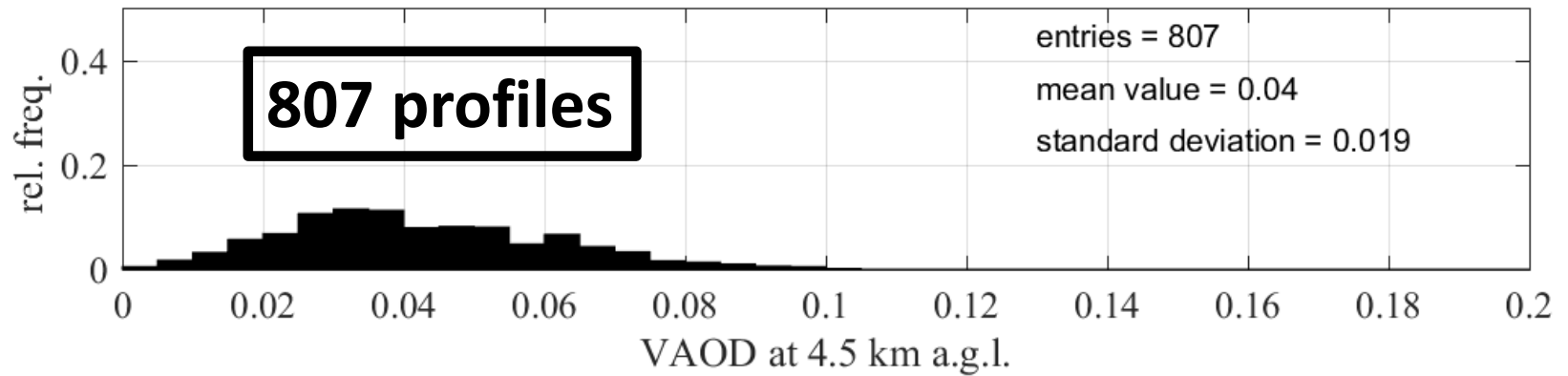
$0 < \text{VAODvalue@4.5km} < 0.10$

Quality cuts and cloud masking.

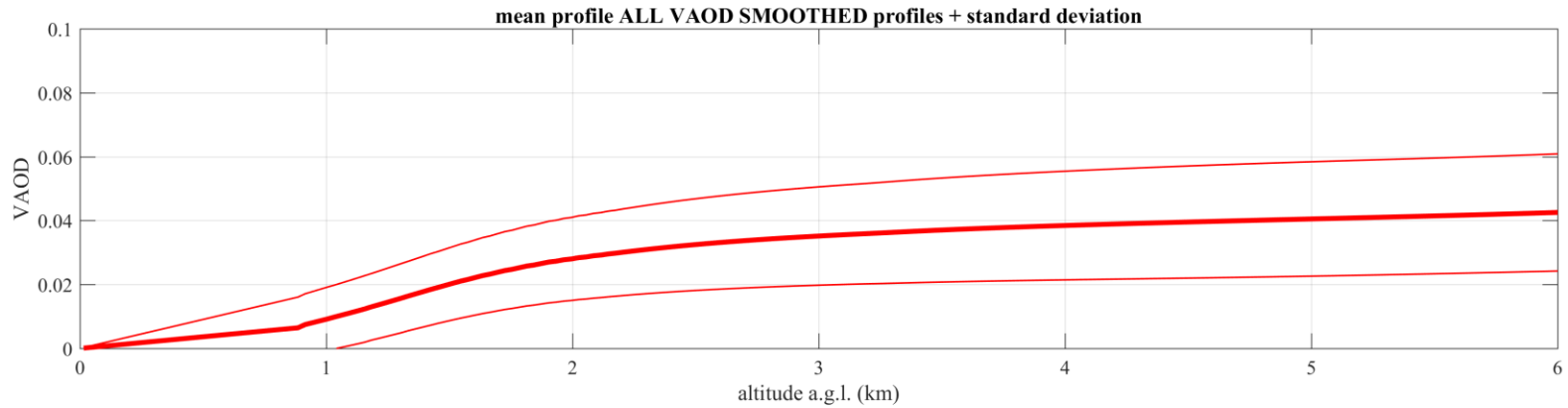
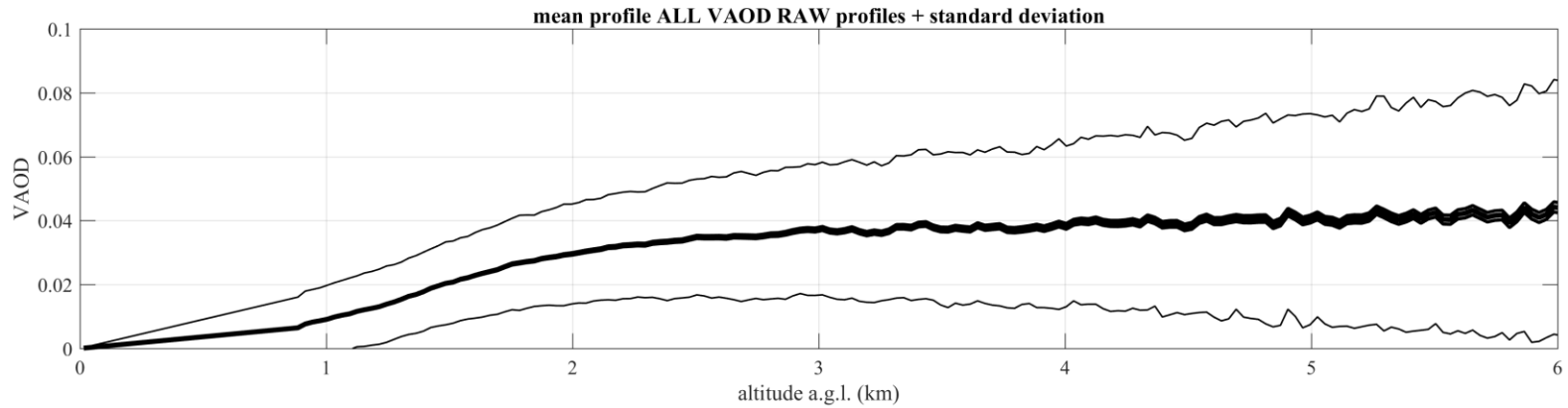


VAOD values

Science

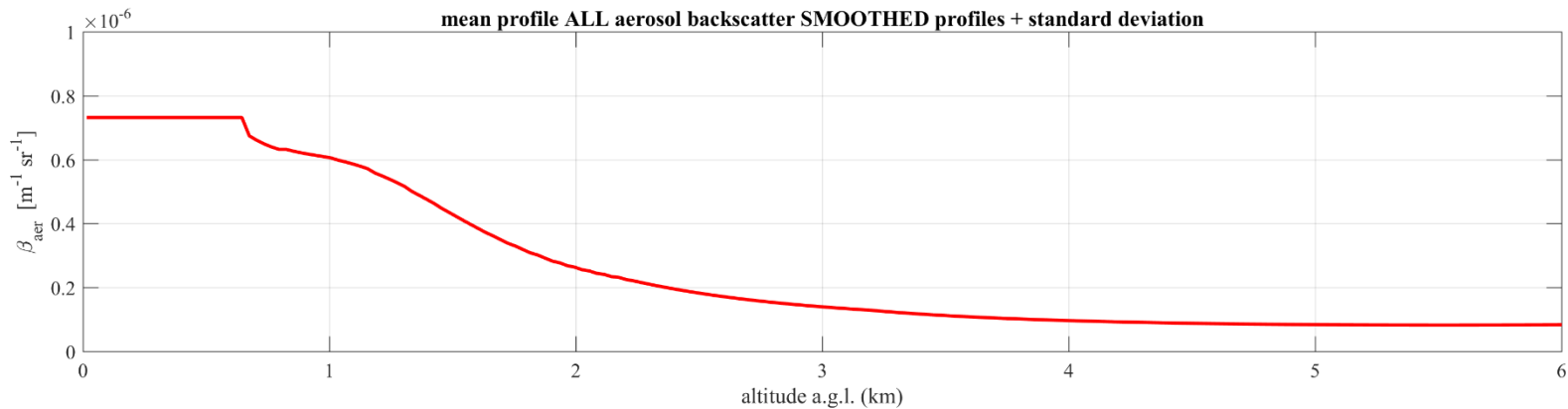
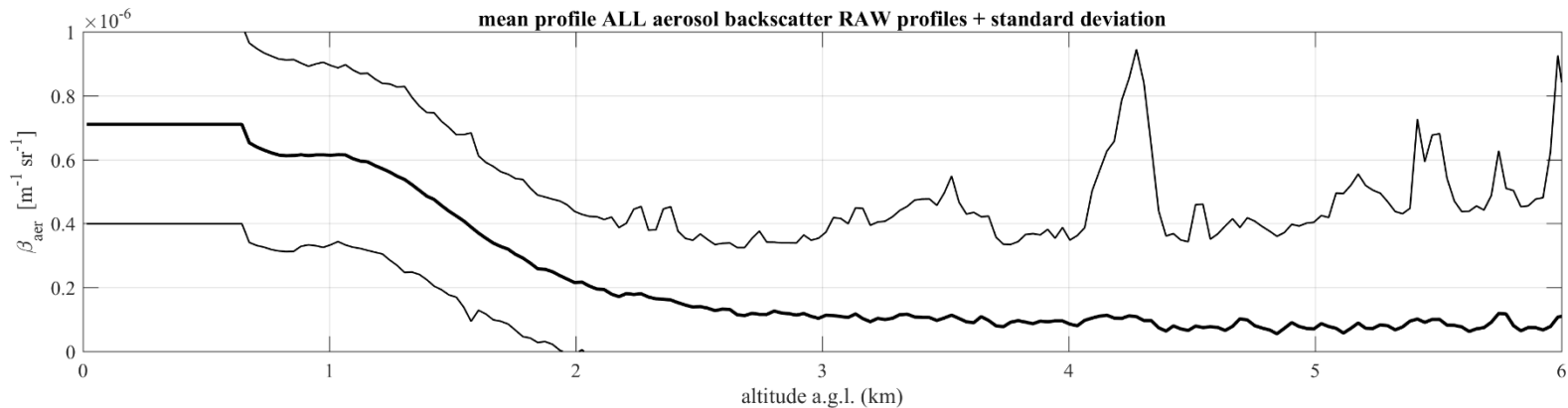


Mean profiles all NOV2013-DEC2017



VAOD

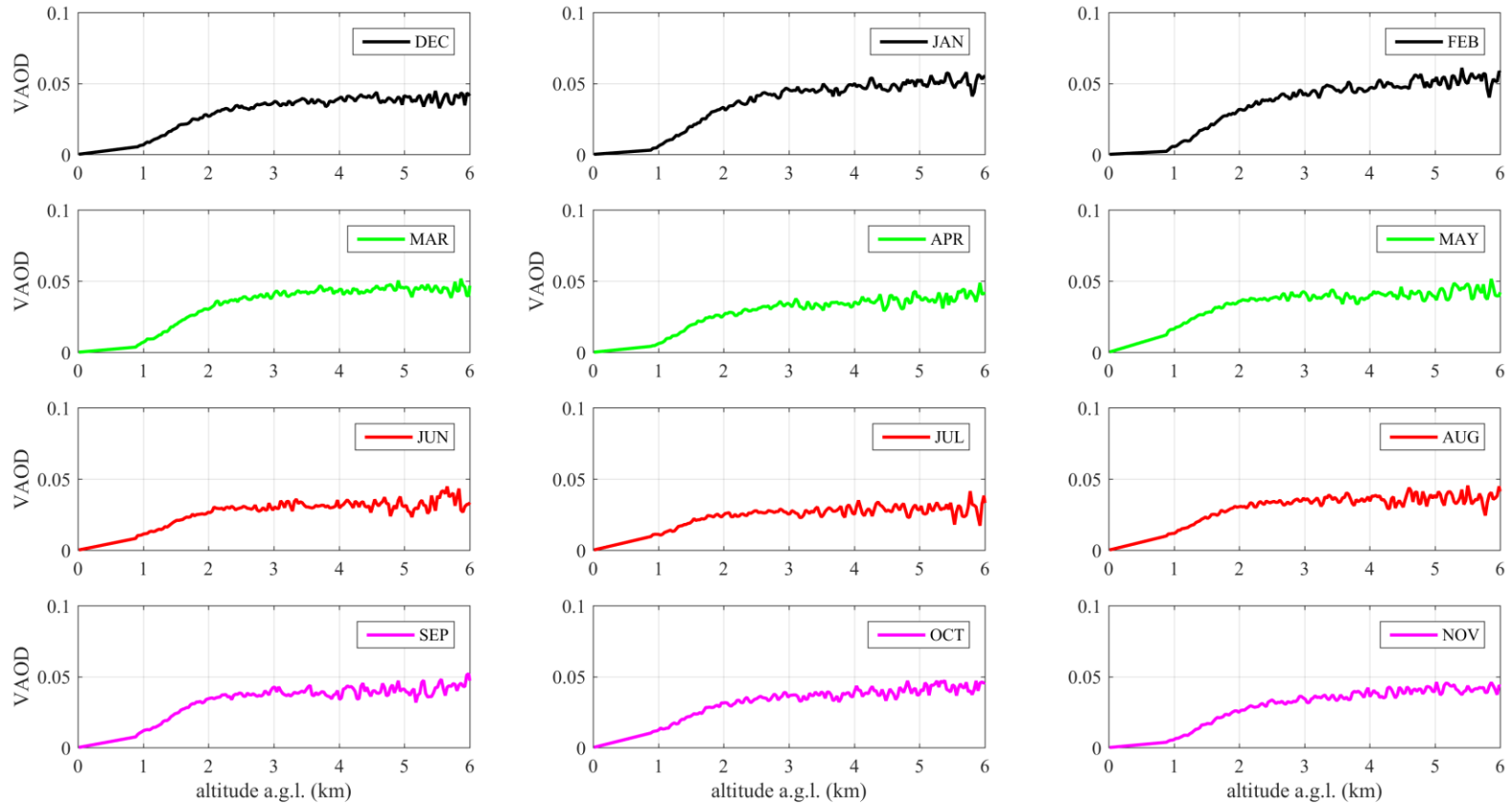
Mean profiles all NOV2013-DEC2017



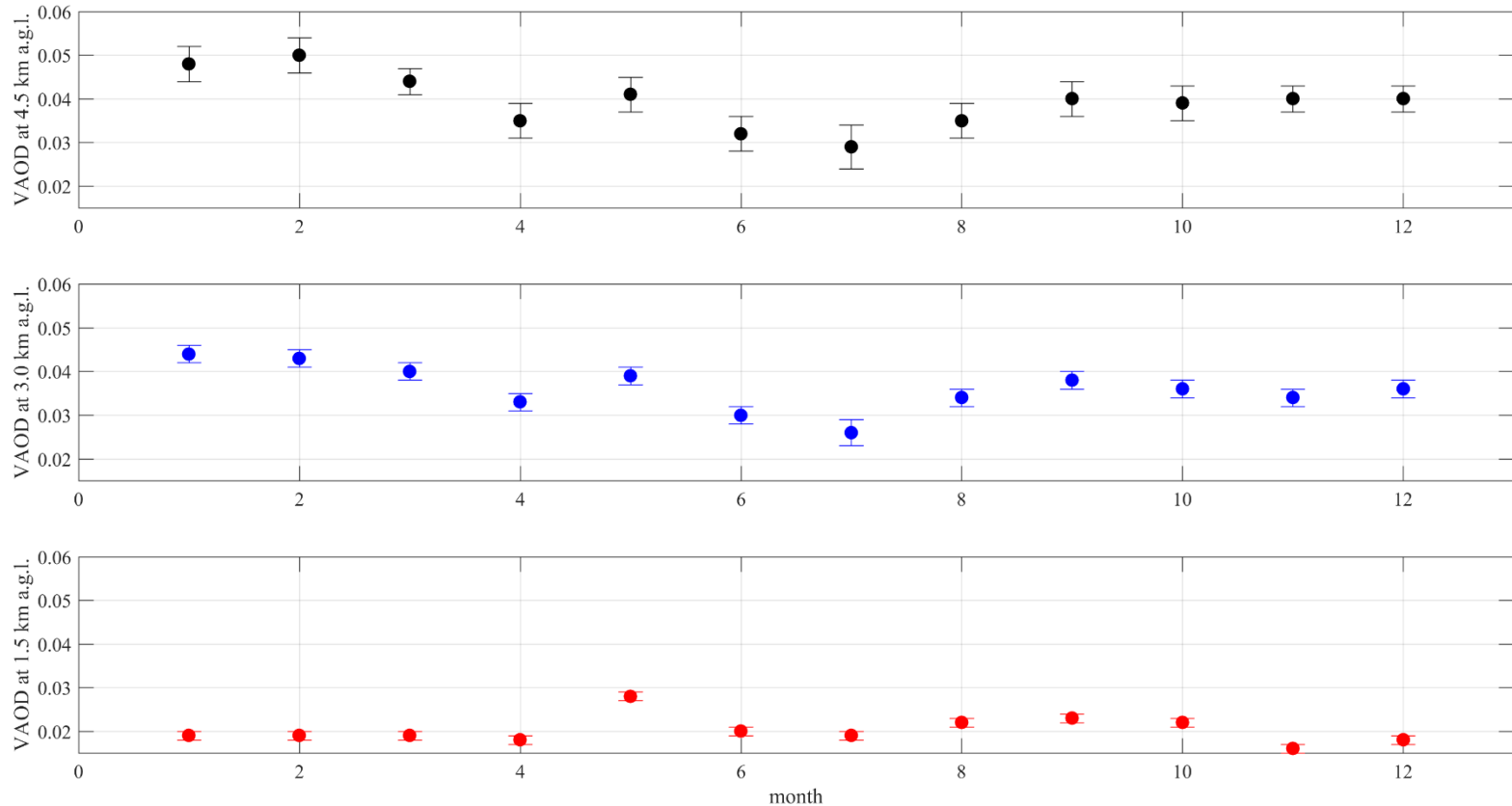
aerosol backscatter

760 profiles

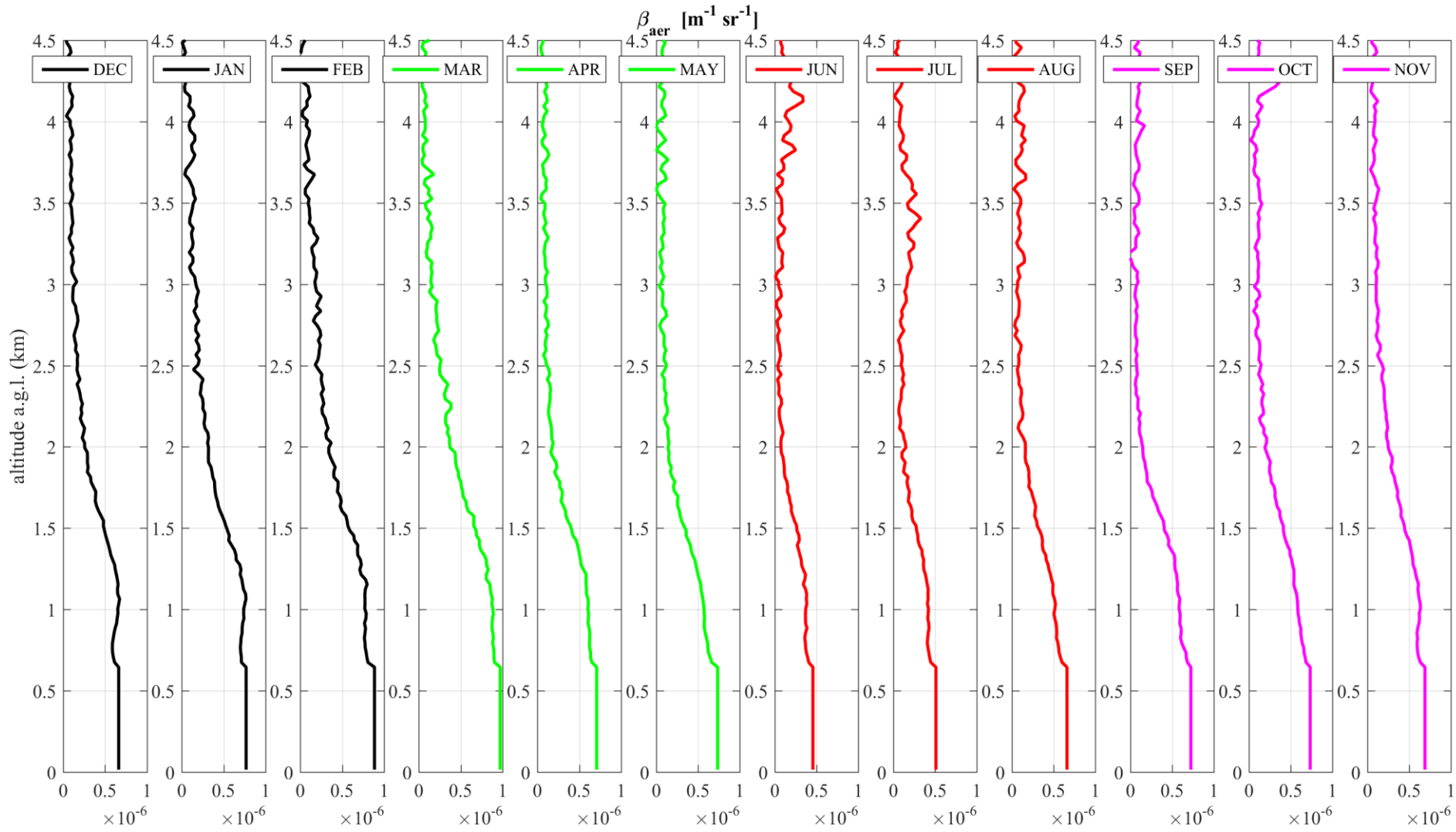
Monthly mean profiles - VAOD



Monthly mean values – VAOD values



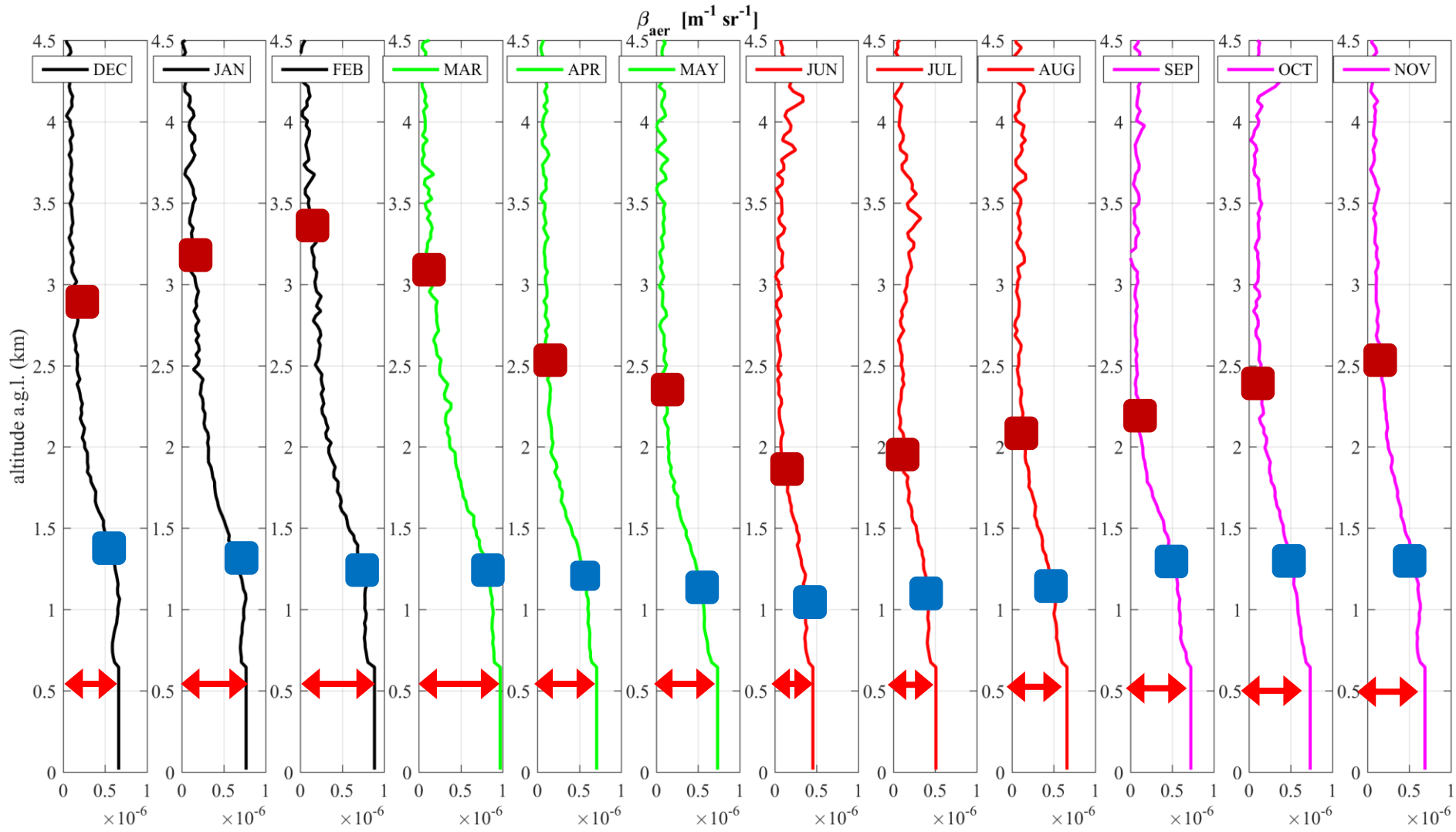
Monthly mean profiles - backscatter



Science

all NOV2013-DEC2017

Monthly mean profiles - backscatter

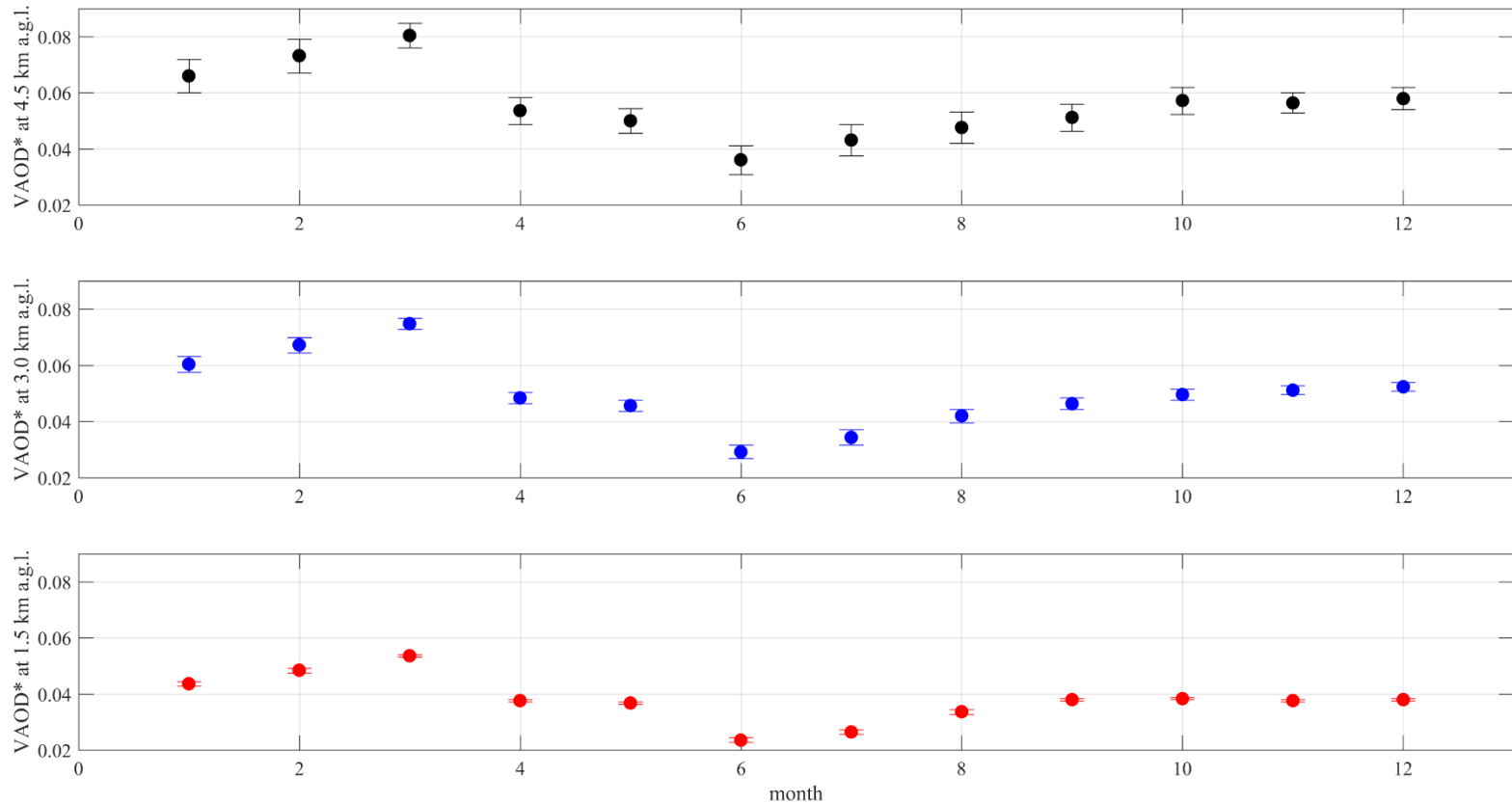


Science

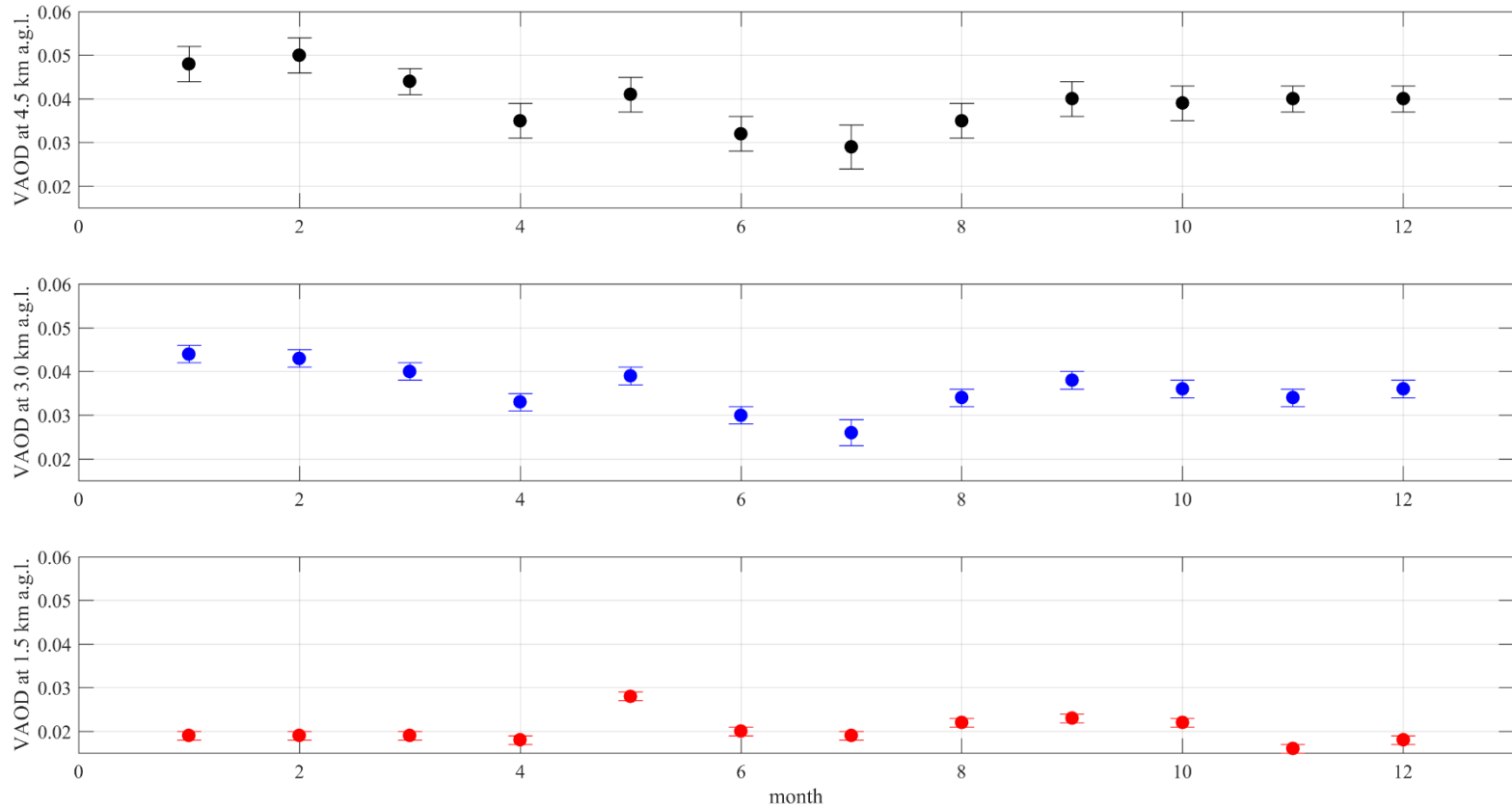
all NOV2013-DEC2017

Monthly mean values – VAOD* values

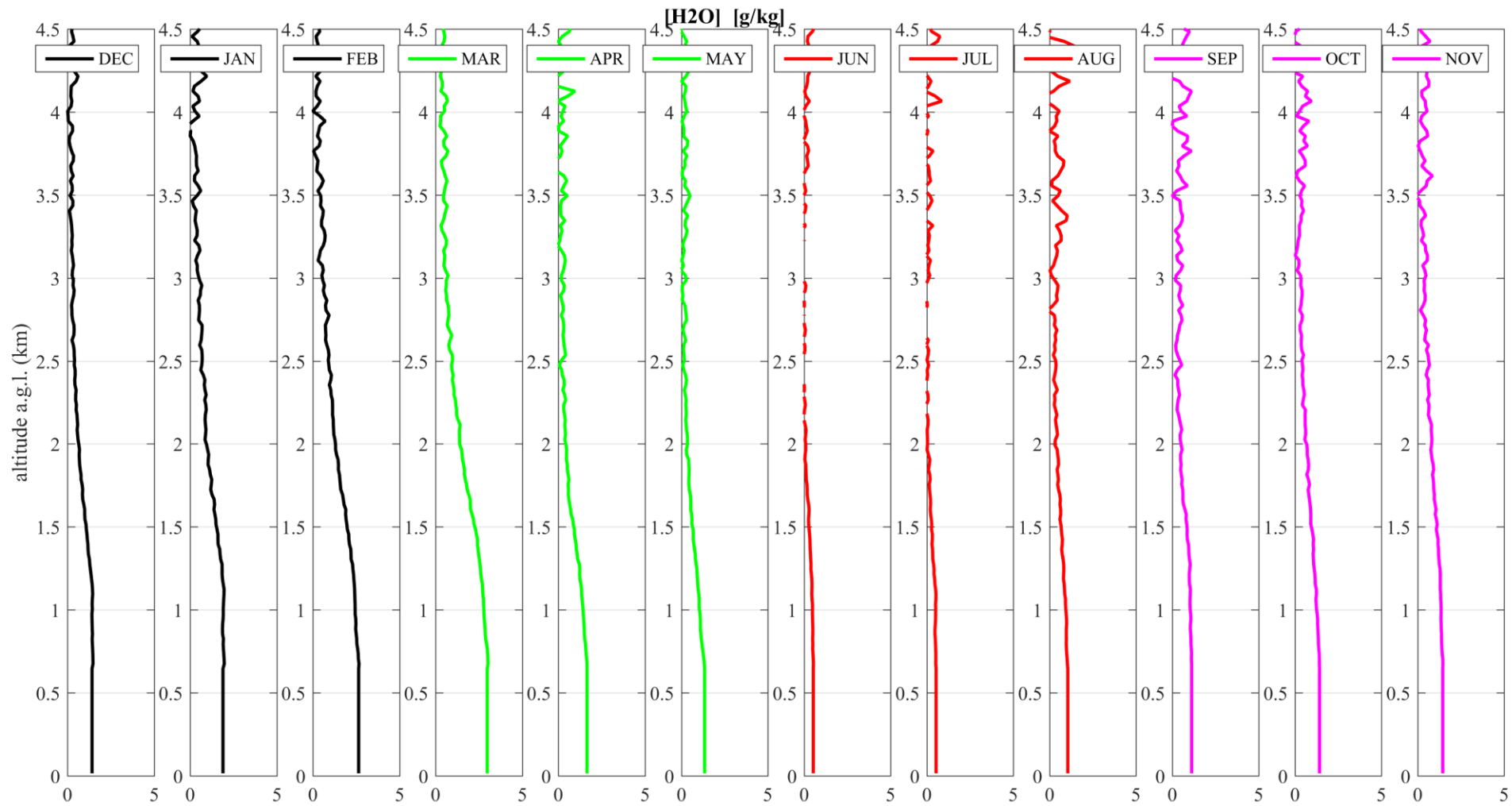
Using int. backscatter x lidar ratio (40 sr)



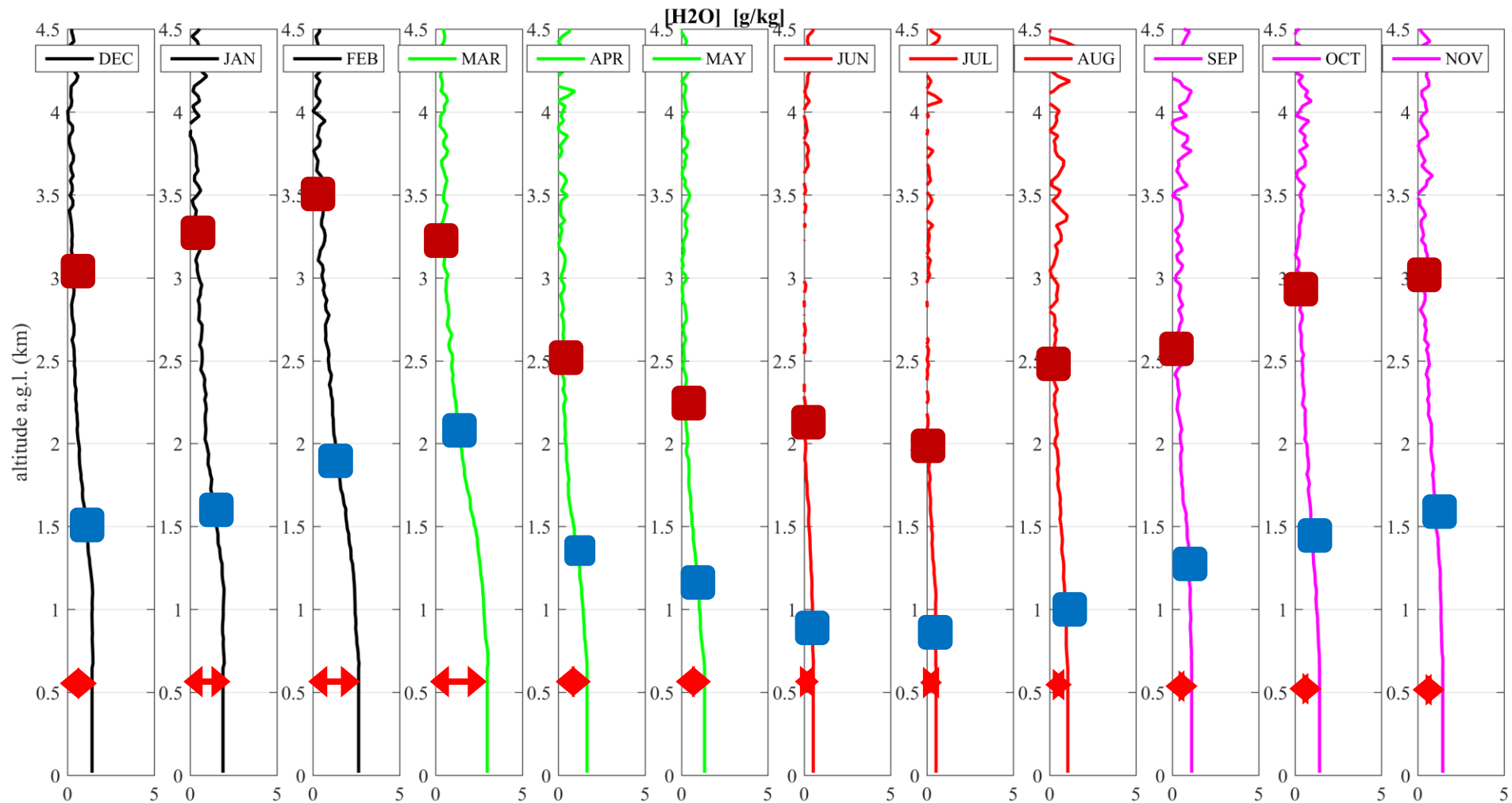
Monthly mean values – VAOD values



Monthly mean profiles – water vapour



Monthly mean profiles – water vapour



Science

all NOV2013-DEC2017

Considerations & SUMMARY

The AUGER RL can continue to run in the present mode, its impact on FD data taking seems negligible.

Other strategies of measurements can easily implemented.

Improvements in RL optics

Laser lifetime

Considerations & SUMMARY

RL VAOD database

gpstime

max_quota_db

min_quota_cloud

altitude (a.s.l.)

alfa

alfa_min_uncorrelated

alfa_max_uncorrelated

alfa_min_correlated

alfa_max_correlated

vaod

vaod_min_uncorr

vaod_max_uncorr

vaod_min_corr

vaod_max_corr

data at a resolution of 200 m, up to **max_quota_db**.

alfa = aerosol extinction coefficient

correlated = systematic

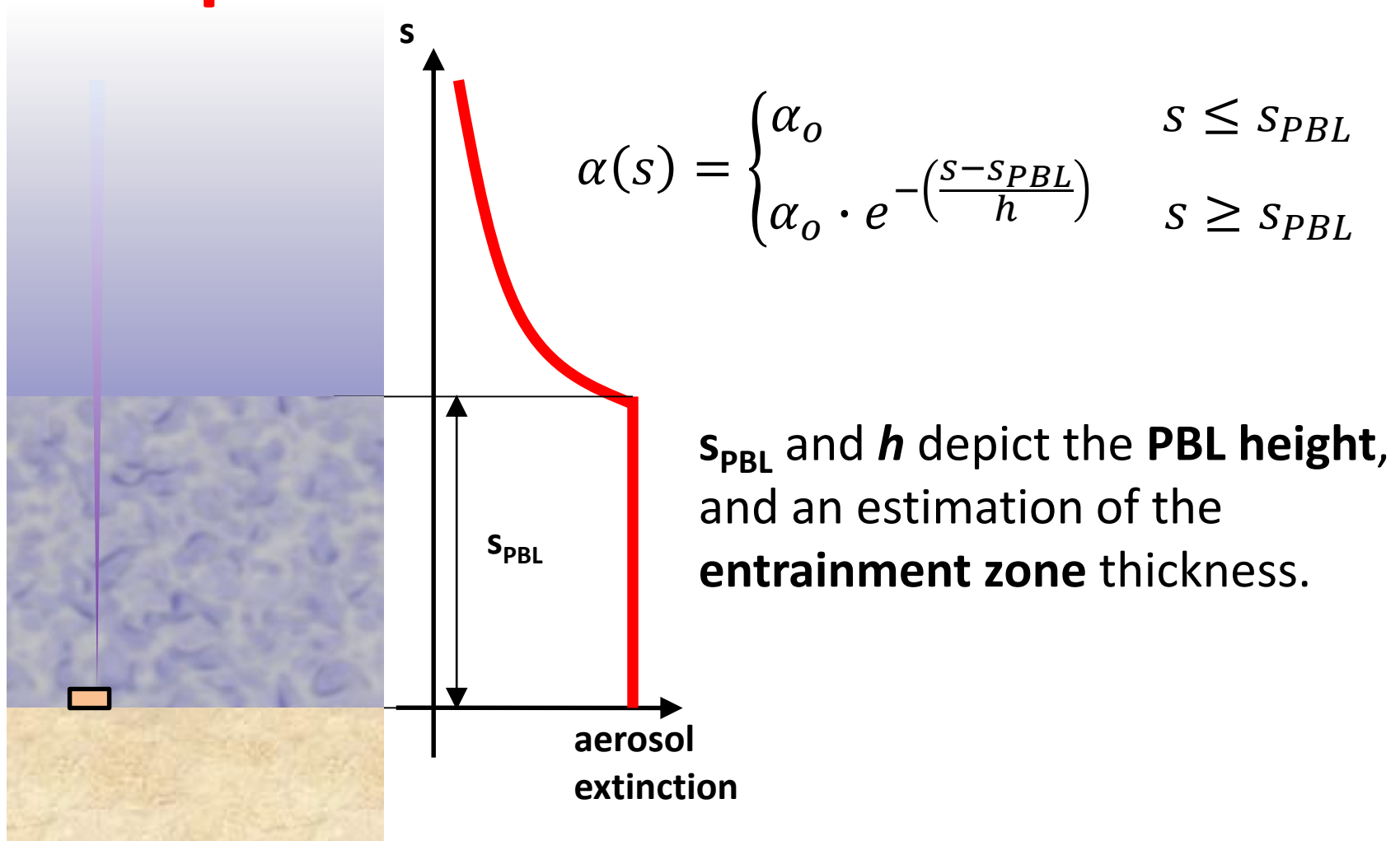
uncorrelated = statistical

Considerations & SUMMARY

- RL is measuring the aerosol optical properties at 355 nm since November 2013;**
- the RL data analysis is documented and reproducible;**
- the shape of the measured vertical profiles of the aerosol backscatter and extinction suggest a simple model of the aerosol vertical distribution;**
- the measured vertical profiles of the aerosol backscatter and extinction show, as expected, a seasonal dependence;**
- the database of the raw RL signals, and RL vertical profiles of the aerosol backscatter, VAOD, (and water vapour) will be made available with all the documentations and analysis programs;**
- maybe it is time for a paper describing RL data;**
- [...] comparison with other techniques;**

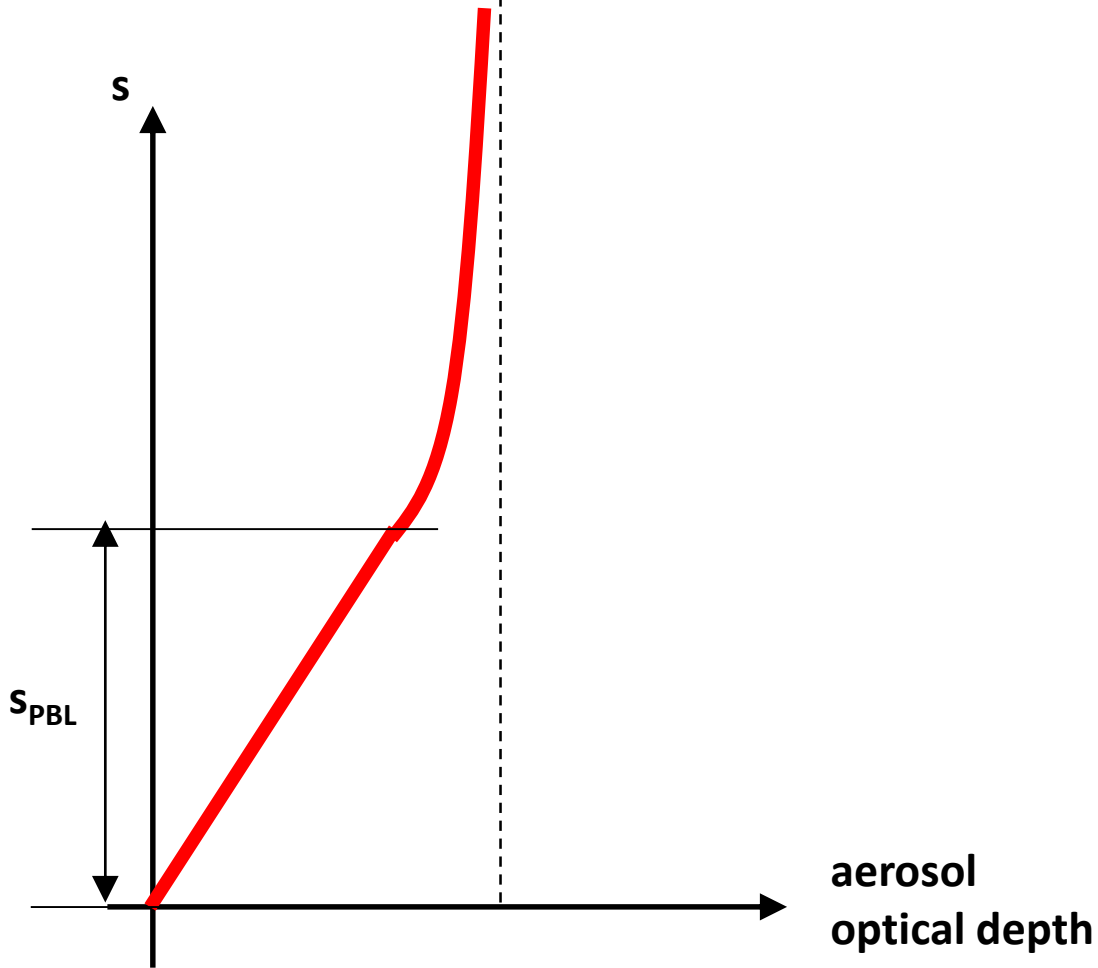
BACKUP slides #1

3 parameters aerosol model



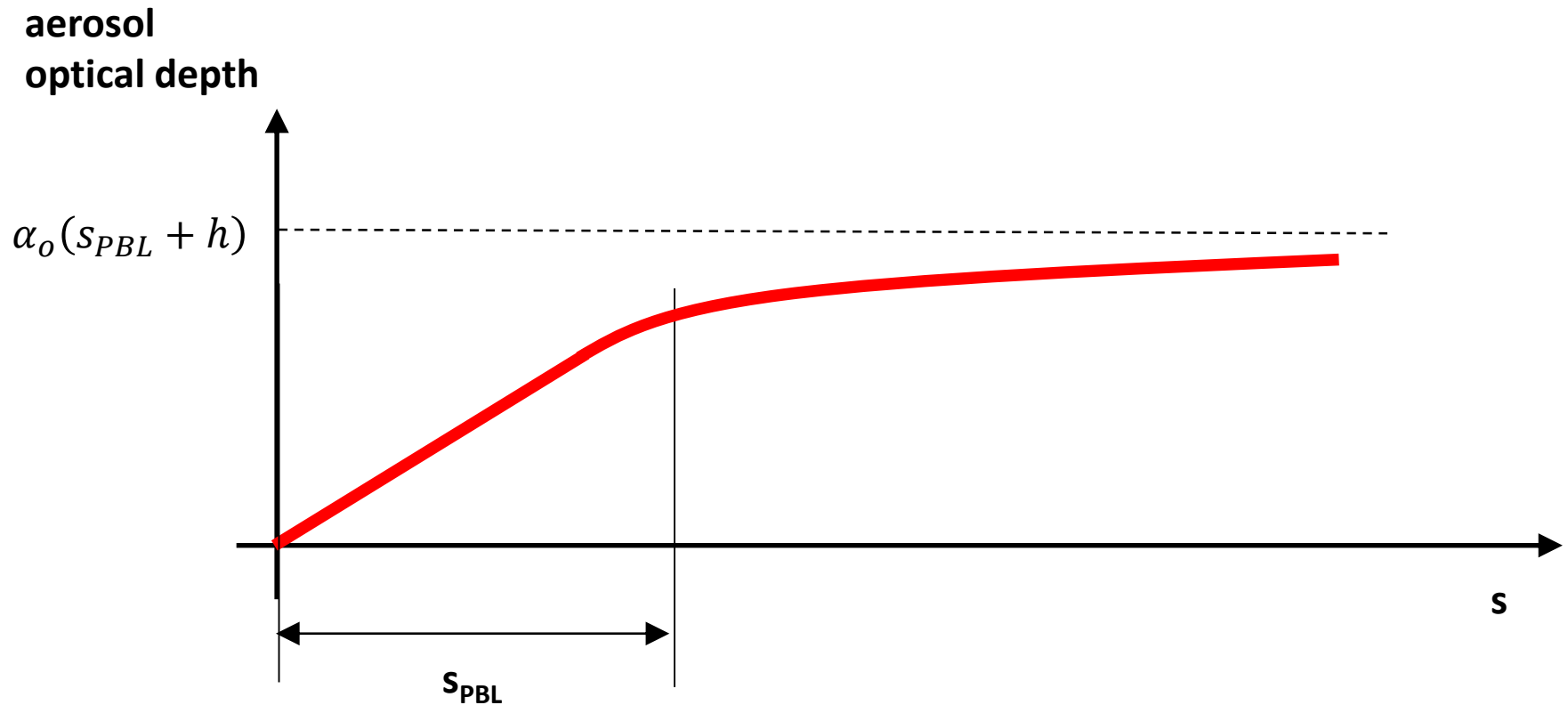
3 parameters aerosol model

$$\tau(s) = \begin{cases} \alpha_o s & s \leq S_{PBL} \\ \alpha_o (S_{PBL} + h) - \alpha_o h \cdot e^{-\left(\frac{s-S_{PBL}}{h}\right)} & s \geq S_{PBL} \end{cases}$$



3 parameters aerosol model

$$\tau(s) = \begin{cases} \alpha_o s & s \leq S_{PBL} \\ \alpha_o (S_{PBL} + h) - \alpha_o h \cdot e^{-\left(\frac{s-S_{PBL}}{h}\right)} & s \geq S_{PBL} \end{cases}$$



BACKUP slides #2

Raman LIDAR sensitivity

**Raman LIDAR sensitivity:
minimum measurable VAOD at 355 nm
~ 0.005**

Raman LIDAR sensitivity

Rayleigh night is the night without aerosols!



Lord Rayleigh

Raman LIDAR sensitivity

$VAOD \sim 0.005$

$T = \exp(-VAOD)$



Lord Rayleigh

Raman LIDAR sensitivity

$VAOD \sim 0.01$

$T = \exp(-VAOD)$



Lord Rayleigh

Raman LIDAR sensitivity

$VAOD \sim 0.05$

$T = \exp(-VAOD)$



Lord Rayleigh

Raman LIDAR sensitivity

$VAOD \sim 0.1$

$T = \exp(-VAOD)$



Lord Rayleigh

Raman LIDAR sensitivity

$VAOD \sim 0.2$

$T = \exp(-VAOD)$

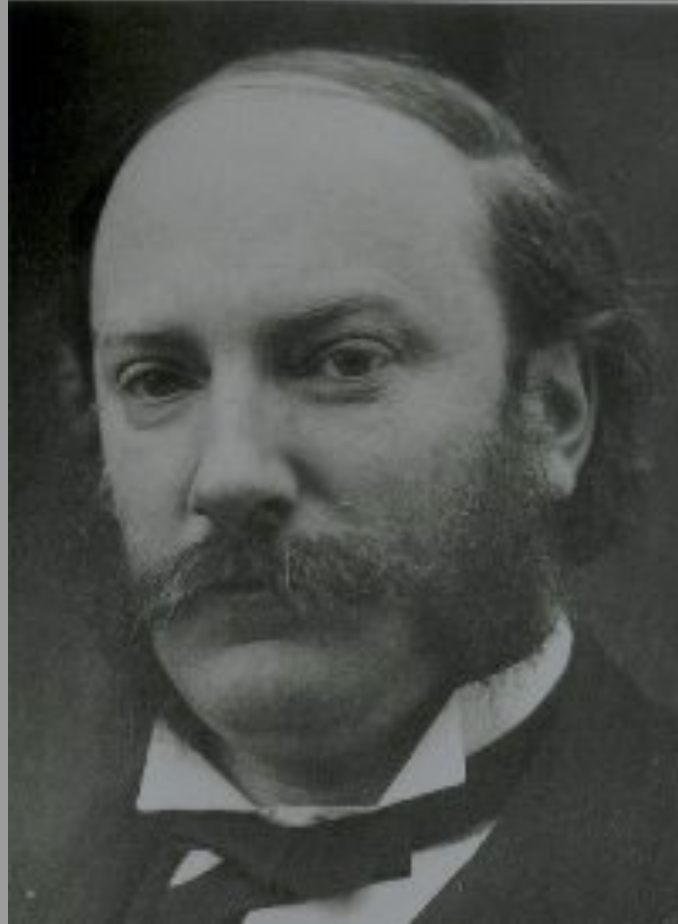


Lord Rayleigh

Raman LIDAR sensitivity

$VAOD \sim 0.5$

$T = \exp(-VAOD)$



Lord Rayleigh

BACKUP slides #3

Raman LIDAR

Vertical Aerosol Optical Depth $\tau_{aer}(s)$ sources of errors

$$\tau_{aer}(s) = \frac{\log \left(\frac{C \cdot s^2 L_R(s)}{T_{mol}(s) \cdot T_{mol}^R(s) \cdot n_{mol}(s)} \right)}{1 + \left(\frac{\lambda_o}{\lambda_R} \right)^k}$$

constant → C

range scale → s^2

N_2 Raman backscatter → $L_R(s)$

optical properties of molecular atmosphere → k

Angstrom exponent → k

RANDOM/STATISTICAL

SYSTEMATIC

ALL HAVE BEEN ESTIMATED

Raman LIDAR

Vertical Aerosol Optical Depth $\tau_{aer}(s)$

estimations of the errors

12 min standard acquisition: $N_{laser} \text{ shots} \sim 24000$; $\Delta t_{bin} = 200 \text{ ns}$

RANDOM/STATISTICAL

$$\Delta\tau_{aer}(s) \Big|_{L_R(s)} \leq \pm 0.01 \quad (s \leq 3 \text{ km})$$

$$\Delta\tau_{aer}(s) \Big|_B \leq \pm 0.003 \quad (s \leq 3 \text{ km})$$

$$\Delta\tau_{aer}(s) \Big|_{calib} \leq \pm 0.004$$

Raman LIDAR

Vertical Aerosol Optical Depth $\tau_{aer}(s)$

estimations of the errors

12 min standard acquisition: $N_{laser} \text{ shots} \sim 24000$; $\Delta t_{bin} = 200 \text{ ns}$

IMPORTANT SYSTEMATICS

t_o is the delay between the reference trigger pulse and the output of laser pulse.

$\Delta\tau_{aer}(s)|_{t_o}$ it can be important. It has been measured. To be checked periodically;

(laser output jitter) $\Delta\tau_{aer}(s)|_{t_o} \leq \pm 0.001$

Assuming that GDAS is representing well the atmosphere over PAO.

The seasonal and hour to hour variations of the molecular number density is generally larger than its indetermination. We are ready to use the GDAS hourly profiles.

$$\Delta\tau_{aer}(s)|_{mol} \leq \pm 0.005$$

Raman LIDAR

Vertical Aerosol Optical Depth $\tau_{aer}(s)$

estimations of the errors

12 min standard acquisition: $N_{laser} \text{ shots} \sim 24000$; $\Delta t_{bin} = 200 \text{ ns}$

$$\Delta\tau_{aer}(s) \Big|_{LR(s)} \leq \pm 0.01 \quad (s \leq 3 \text{ km})$$

$$\Delta\tau_{aer}(s) \Big|_B \leq \pm 0.003 \quad (s \leq 3 \text{ km})$$

$$\Delta\tau_{aer}(s) \Big|_{calib} \leq \pm 0.004$$

$$\Delta\tau_{aer}(s) \Big|_{t_o} \leq \pm 0.001$$

$$\Delta\tau_{aer}(s) \Big|_k \leq \pm 0.02 \cdot \tau_{aer}(s)$$

$$\Delta\tau_{aer}(s) \Big|_{mol} \leq \pm 0.005$$

$$\Delta\tau_{aer}(s) \Big|_{tot} \leq \pm \mathbf{0.012}$$

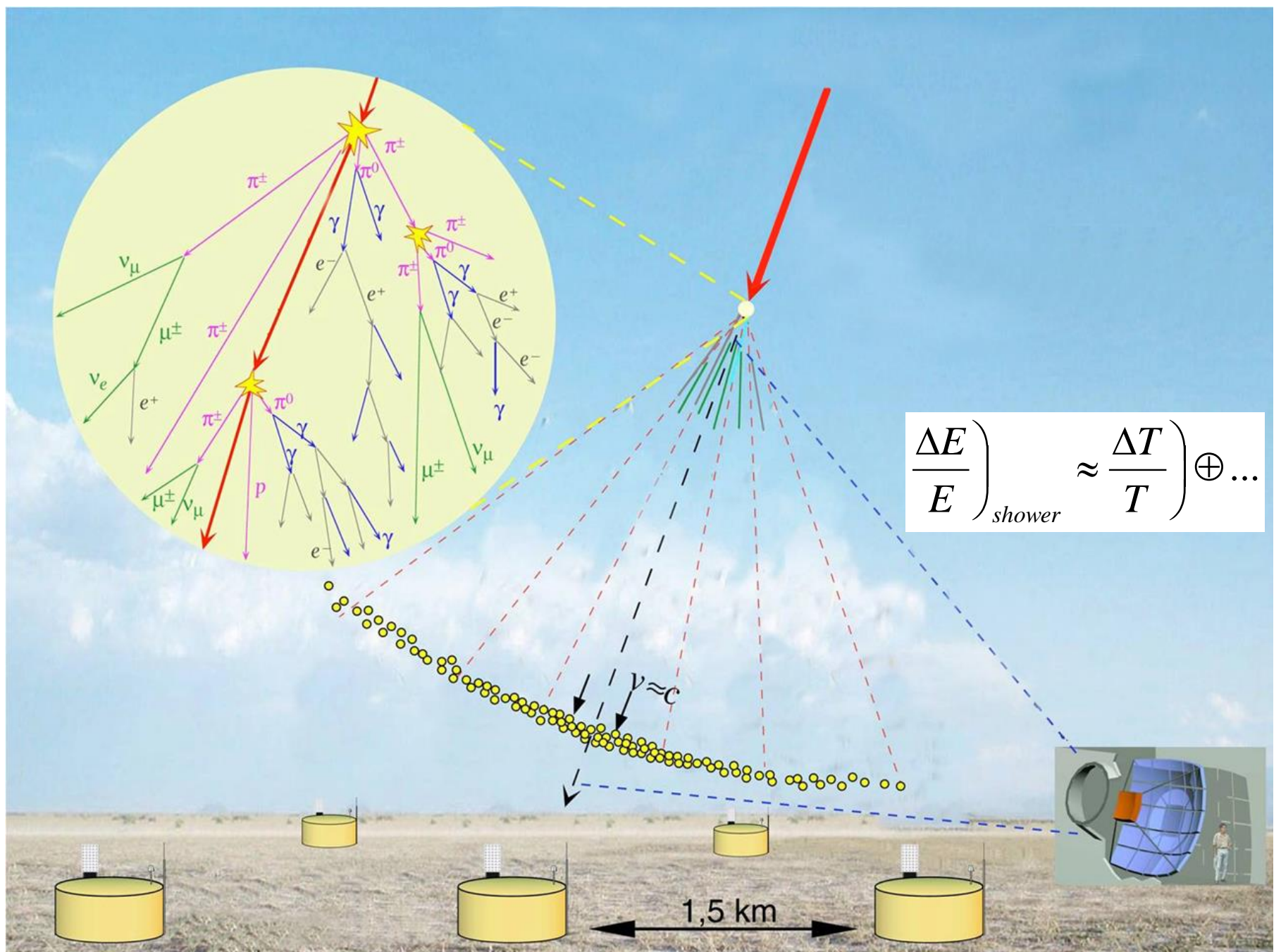
bin to bin

$$s \leq 3 \text{ km}$$

$$\tau_{aer}(s) \sim 0.05$$

It can be lower if a model of VAOD is fitted to the data.

BACKUP slides #4



$$\left. \frac{\Delta E}{E} \right)_{shower} \approx \left. \frac{\Delta T}{T} \right) \oplus \dots$$

