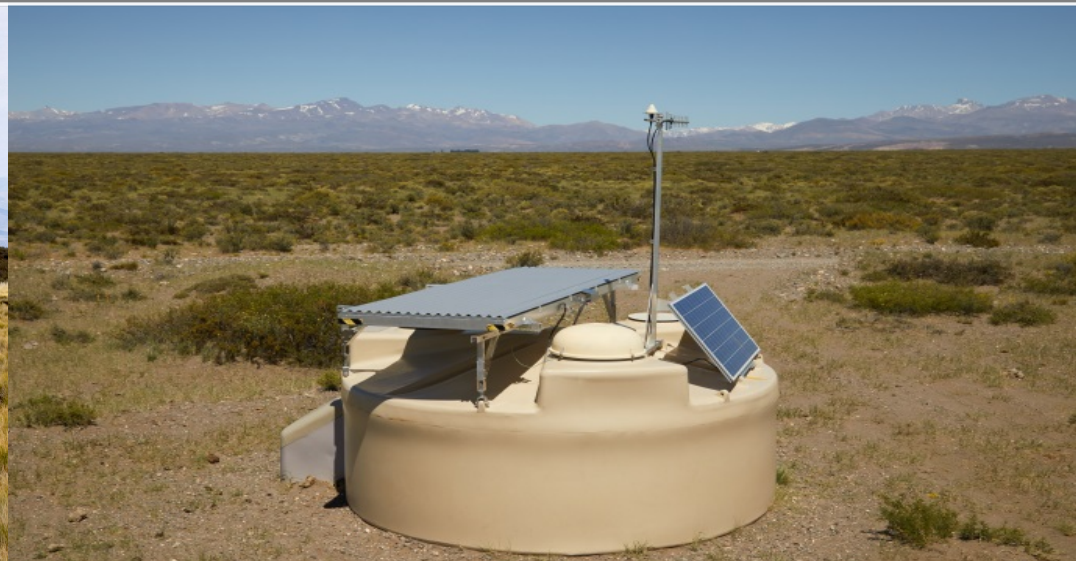


# Atmospheric Monitoring at a Cosmic Ray Observatory – a long-lasting endeavour

B. Keilhauer for the Pierre Auger Collaboration

AtmoHEAD - ATmospheric MOnitoring for High Energy Astroparticle Detectors - Anacapri, 24. – 26. September 2018



# Atmospheric Monitoring Installations

## Aerosols – content and properties:

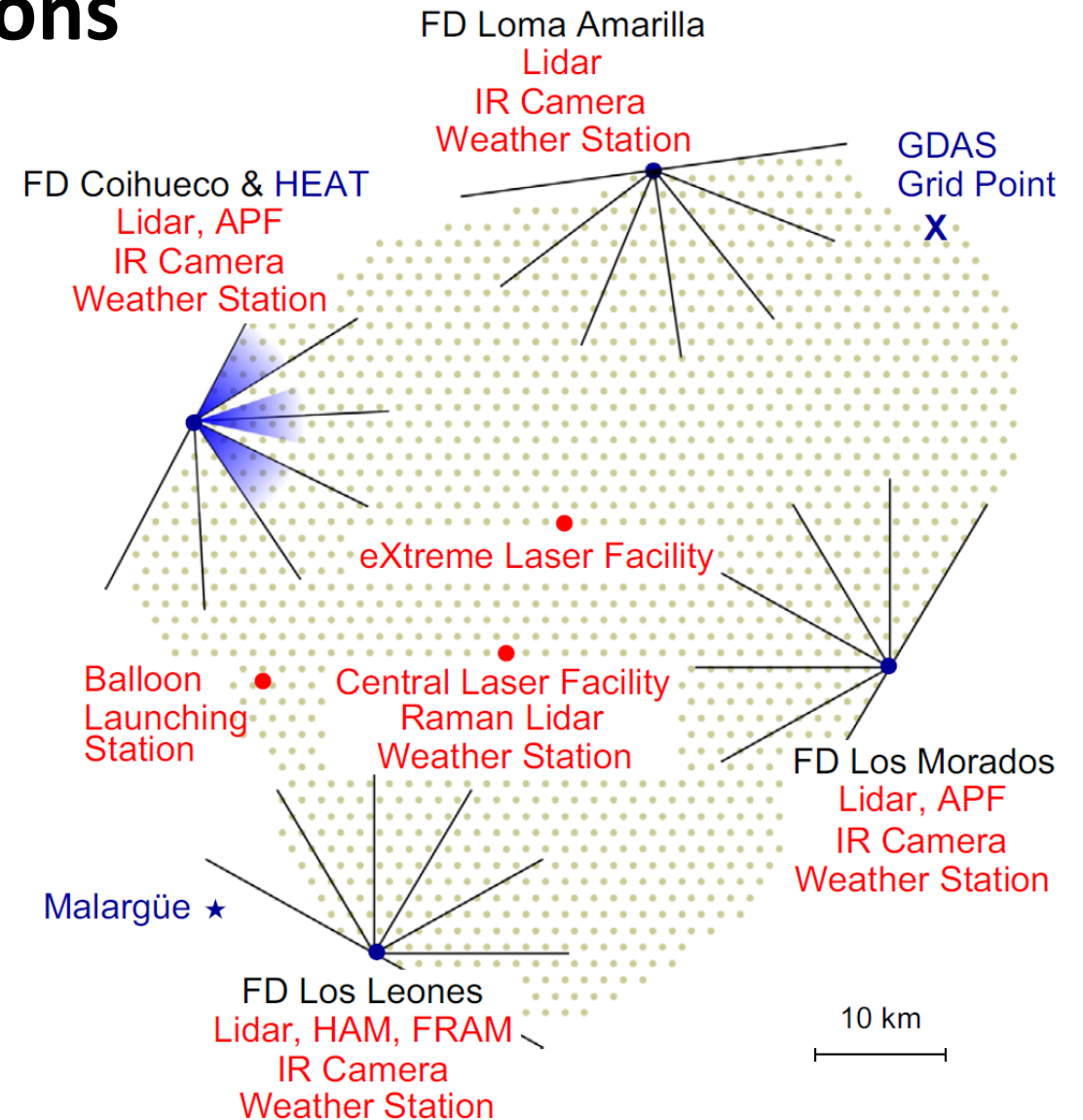
- CLF / XLF
- Elastic lidars
- Raman lidar
- Horizontal Attenuation Monitor HAM
- Aerosol Phase Function Monitor APF
- Ph(F)otometric Robotic Atmospheric Monitor FRAM

## Clouds:

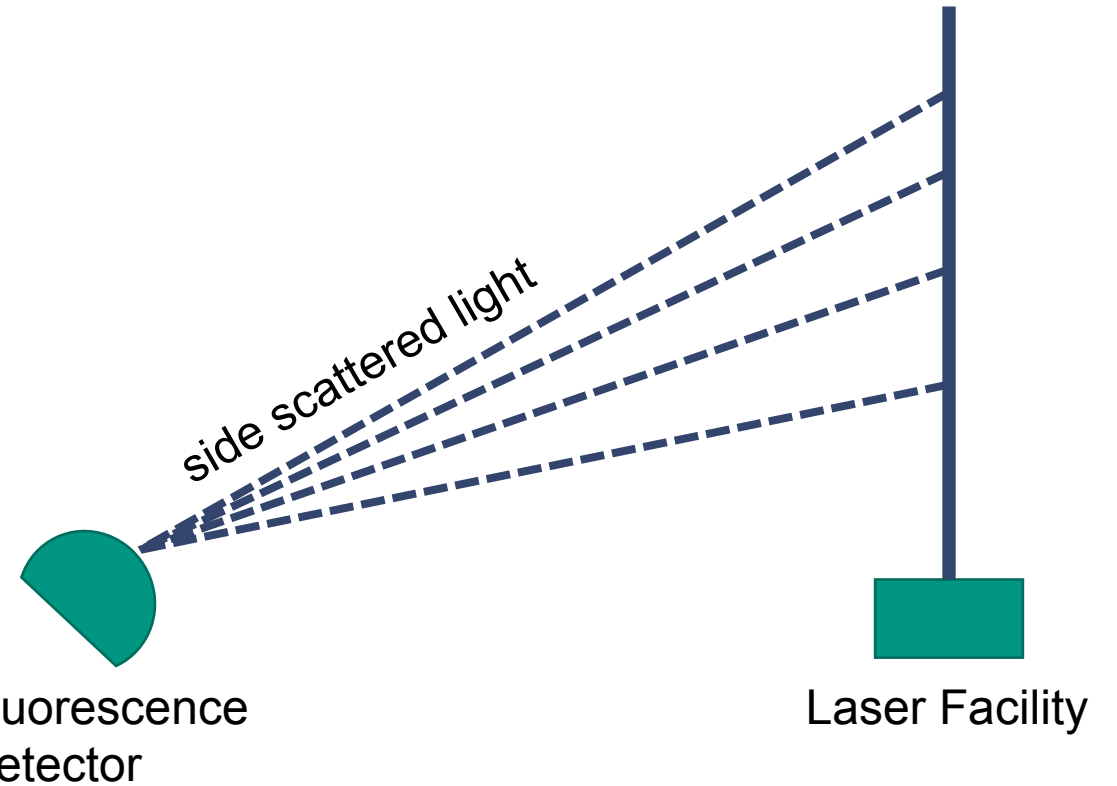
- IR Cameras
- Elastic lidar
- CLF / XLF

## State variables:

- Weather stations
- Formerly: radio soundings



# CLF / XLF



- vertical aerosol optical depth VAOD profiles



# CLF / XLF

## Operating scheme:

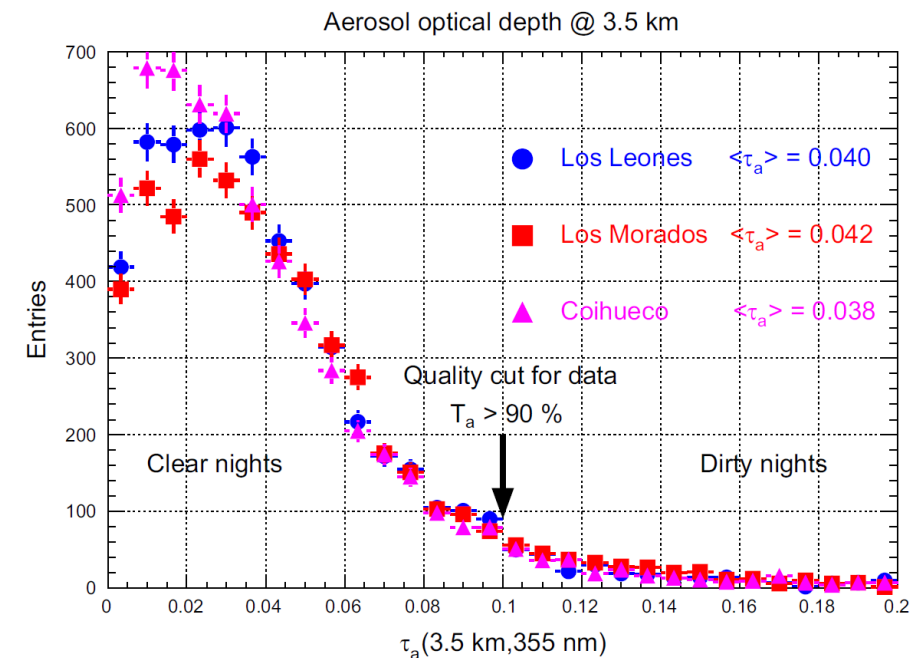
- During FD data taking
- 50 vertical laser shots every 15 min.
- Fully automated operation
- Check of data output by FD shifters

## Data output

- Hourly averages of VAOD profiles
- CLF data since 2004
- XLF data since 2009
- Standard aerosol information of cosmic ray event reconstruction

## Challenges:

- Regular maintenance
- High costs of spare parts
- Sophisticated data analysis which is done quite manually

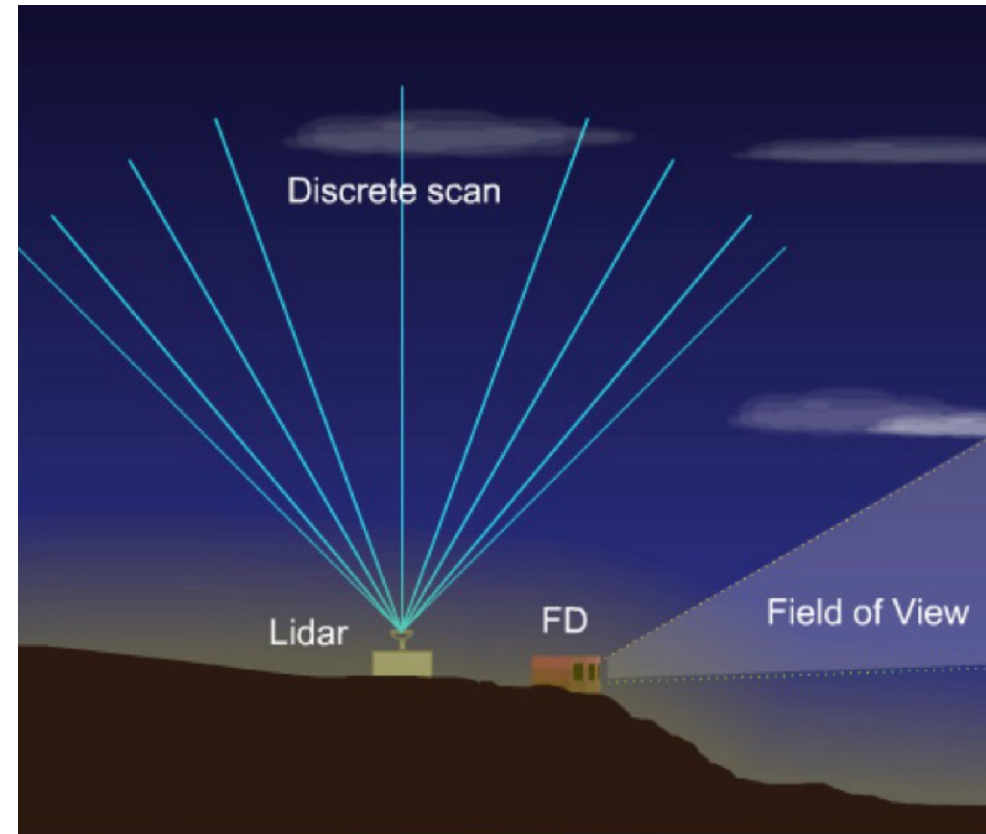


Data from Jan 2004 to Dec 2010

# Elastic lidars



- Cloud base heights
- vertical aerosol optical depth VAOD profiles



# Elastic lidars

## Operating scheme:

- During FD data taking
- discrete and continuous scanning patterns
- FD shifters need to start, check, and finish data taking
- Scanning patterns are automated

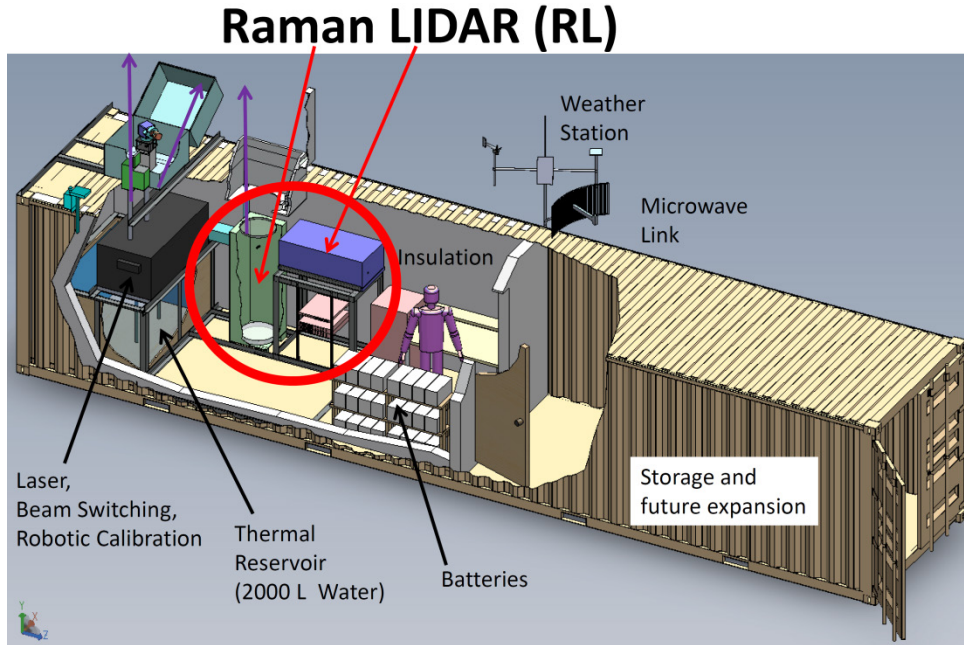
## Data output

- Currently only cloud base heights
- VAOD profiles possible, typically behind FOV of FD telescopes
- Standard cloud base height information of cosmic ray event reconstruction

## Challenges:

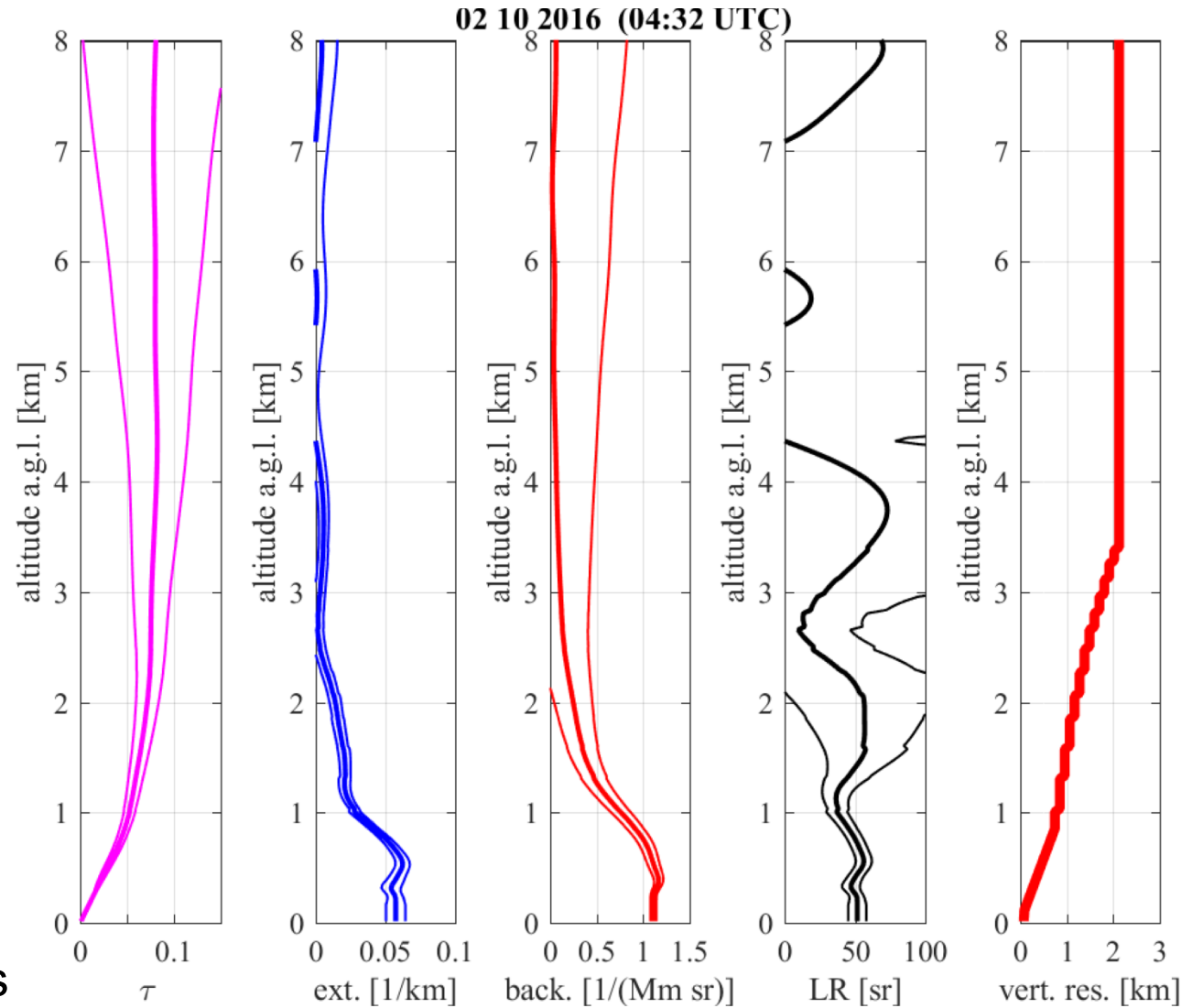
- Delicate alignment of optical system
- Lidar scans either behind FOV of FD or a balance between FD taking and lidar scans has to be found
- Regular maintenance
- High costs of spare parts
- Sophisticated data analysis which is done quite manually

# Raman lidar



integrated in the CLF

➤ vertical aerosol optical depth VAOD profiles



# Raman lidar

## Operating scheme:

- During FD data taking
- 3 windows of 15 min: before, during, and after FD data taking
- ⇒ 15 min veto for FD data taking in FOV
- Fully automated operation
- Check of data output by L'Aquila group

## Data output

- VAOD profiles
- data since 2013
- Currently used for cross-checks with CLF

## Challenges:

- Regular maintenance
- High costs of spare parts
- Sophisticated data analysis which is done quite manually

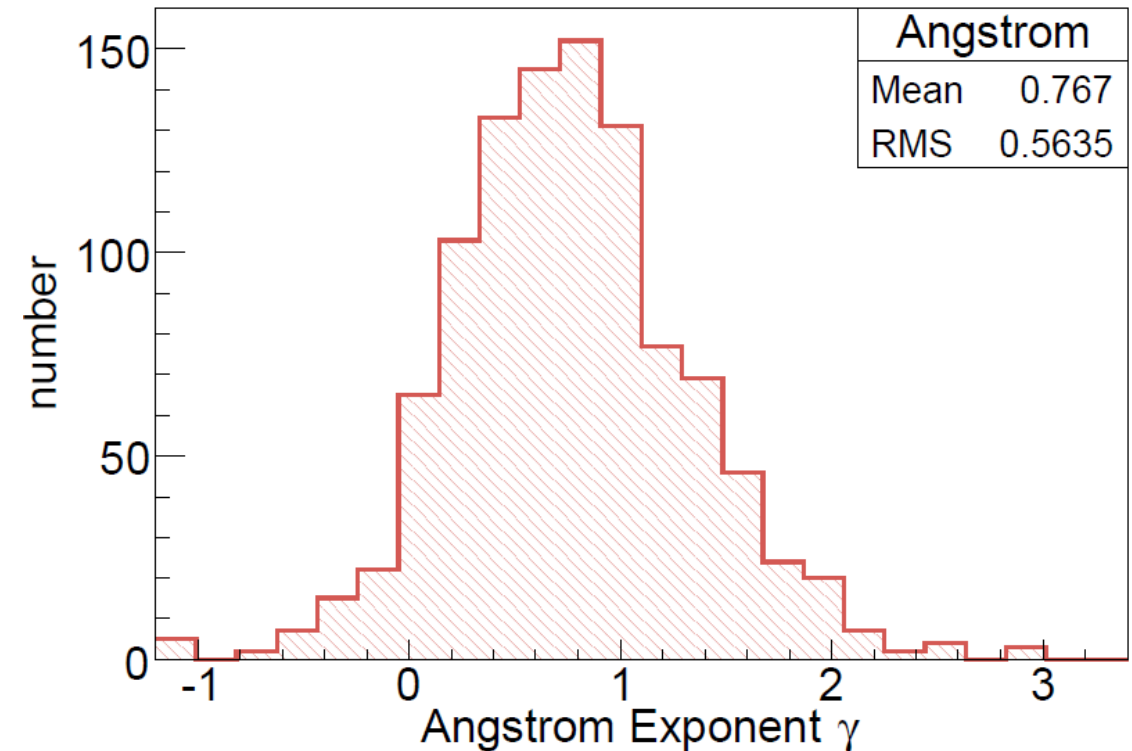


# Horizontal Attenuation Monitor HAM

- high intensity discharge lamp at Coihueco
- CCD camera at FD Los Leones, about 45 km distance
- 5 wavelengths between 350 nm and 550 nm

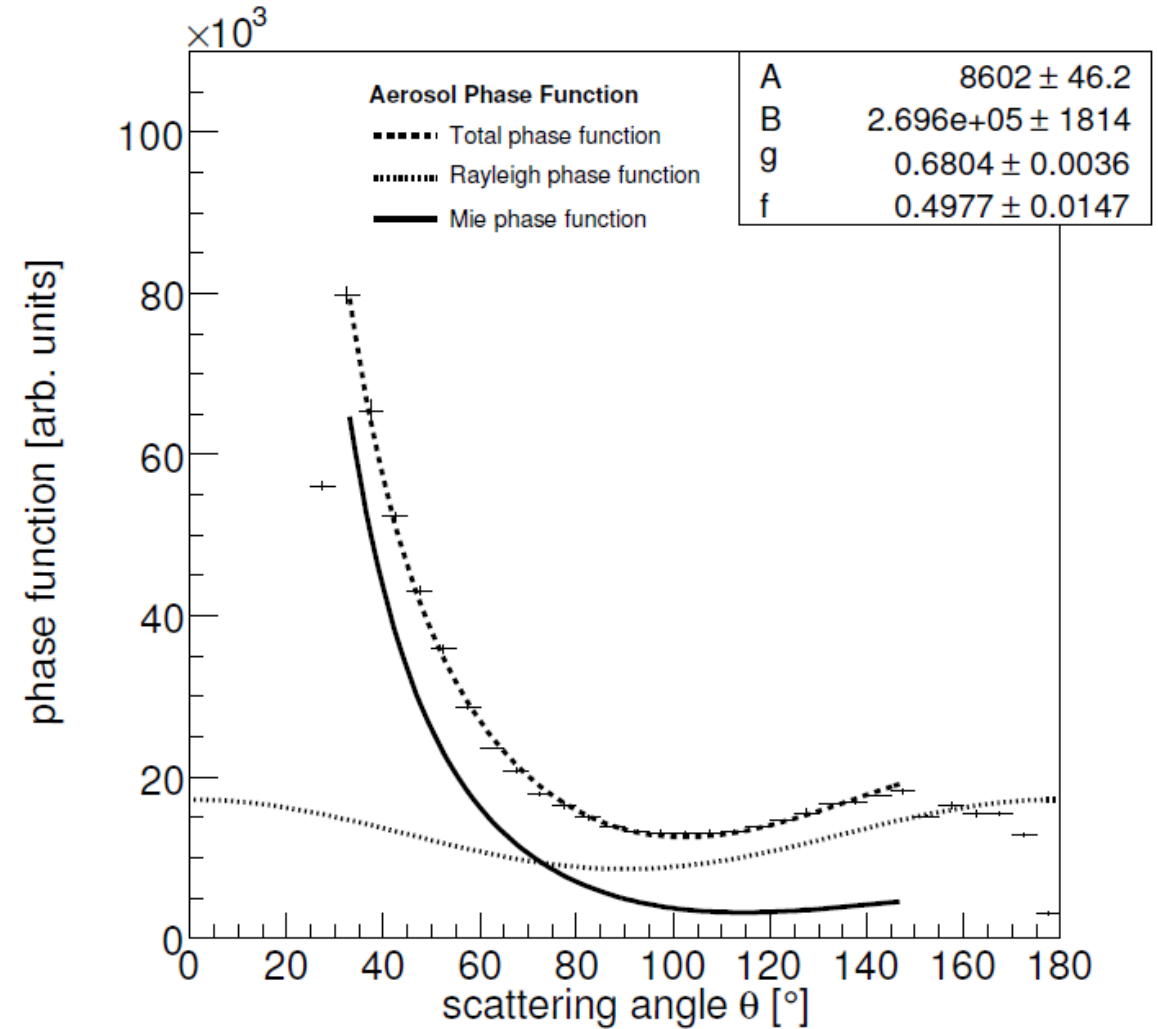
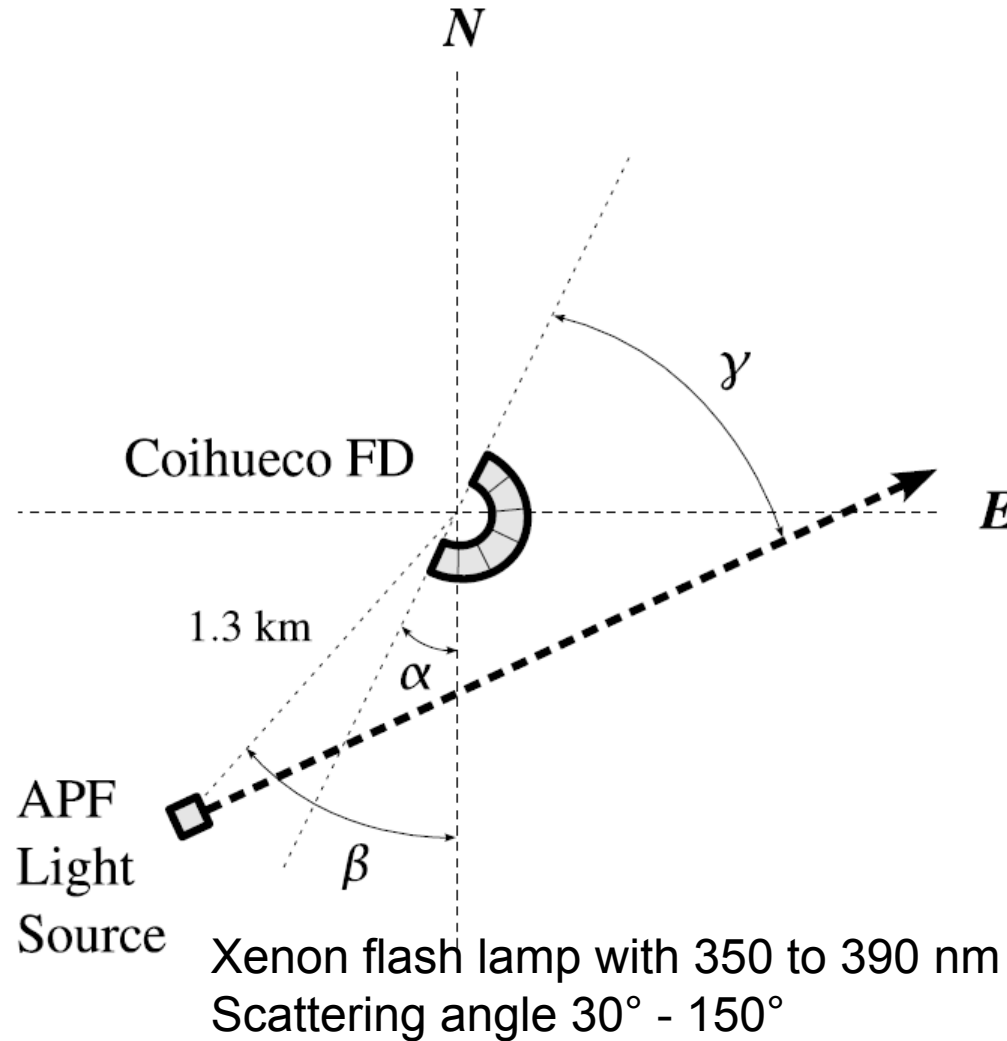
## Data output

- Ångstrom exponent
- $\tau(\lambda) = \tau_0 \cdot \left(\frac{\lambda_0}{\lambda}\right)^\gamma$
- averaged  $\gamma$  factor is used in the cosmic ray event reconstruction



Data from Jul 2006 to Feb 2007

# Aerosol Phase Function Monitor APF



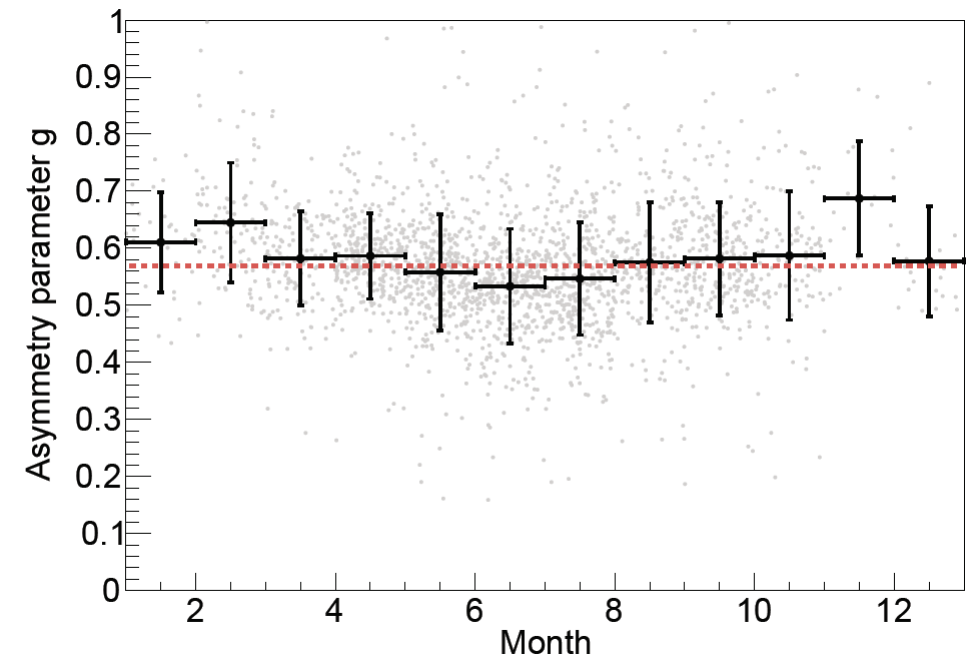
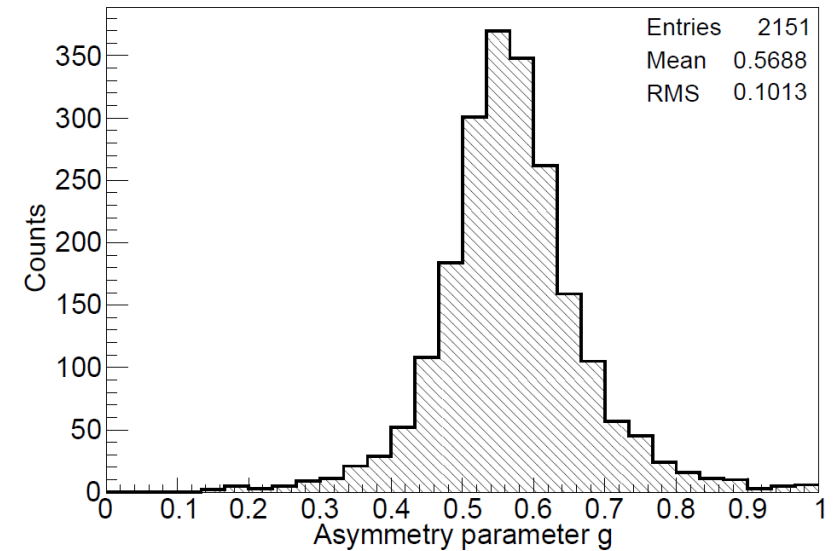
# Aerosol Phase Function Monitor APF

## Operating scheme:

- During FD data taking
- At 2 FD sites
- Fully automated operation

## Data output

- Horizontal scattered light between  $30^\circ$  and  $150^\circ$
- Average value for  $g$ , describes the asymmetry of scattering, derived
- This averaged  $g$  factor is used in the cosmic ray event reconstruction

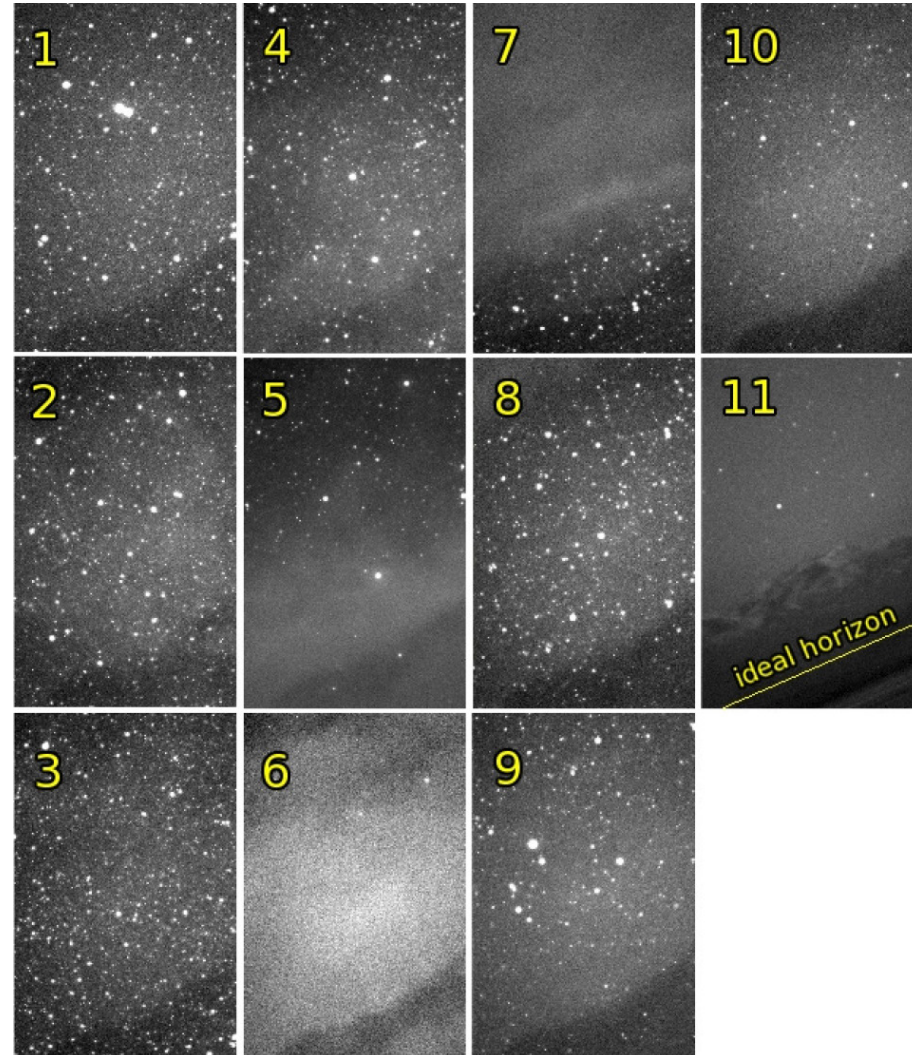


Data from 2011 to 2015

# Ph(F)otometric Robotic Atmospheric Monitor FRAM



➤ Integral extinction





# Ph(F)otometric Robotic Atmospheric Monitor FRAM

## Operating scheme:

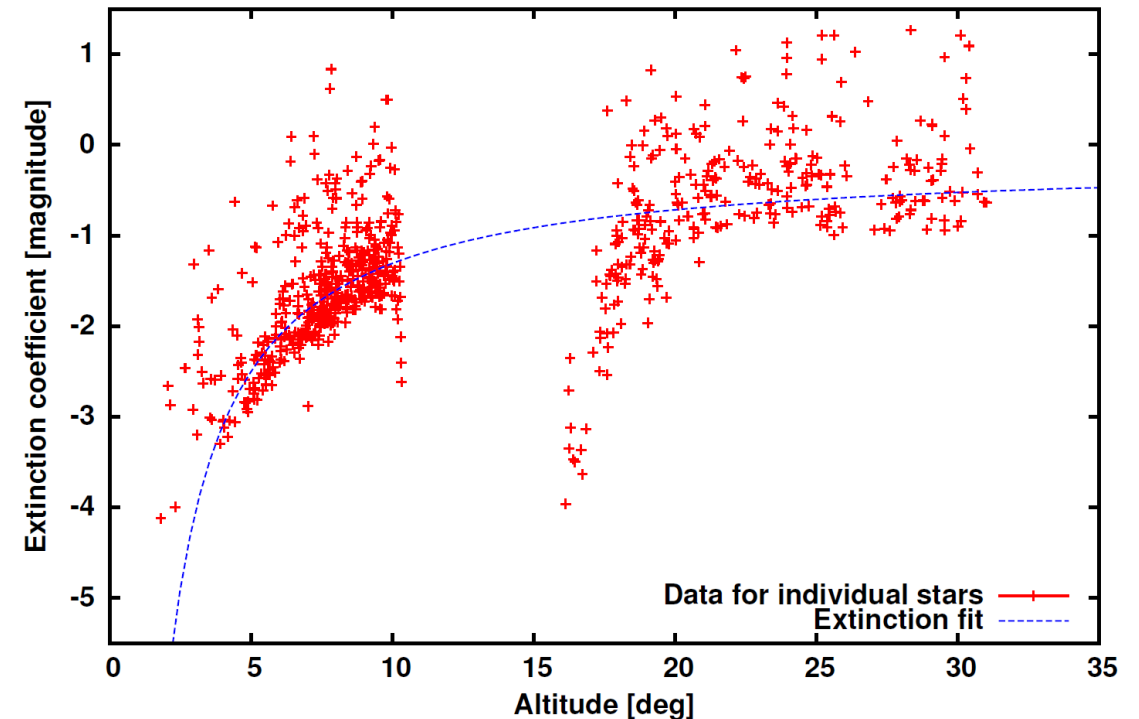
- During FD data taking
- Fully automated operation
- Continuous data taking and particular triggers for ,shoot-the-shower‘
- Check of data output by Prague group

## Data output

- Extinction data for ,double bump‘ events
- Ångstrom exponent
- Recently AOD
- Data since 2006

## Challenges:

- Regular maintenance
- Sophisticated data analysis which is done quite manually



# Atmospheric Monitoring Installations

## Aerosols – content and properties:

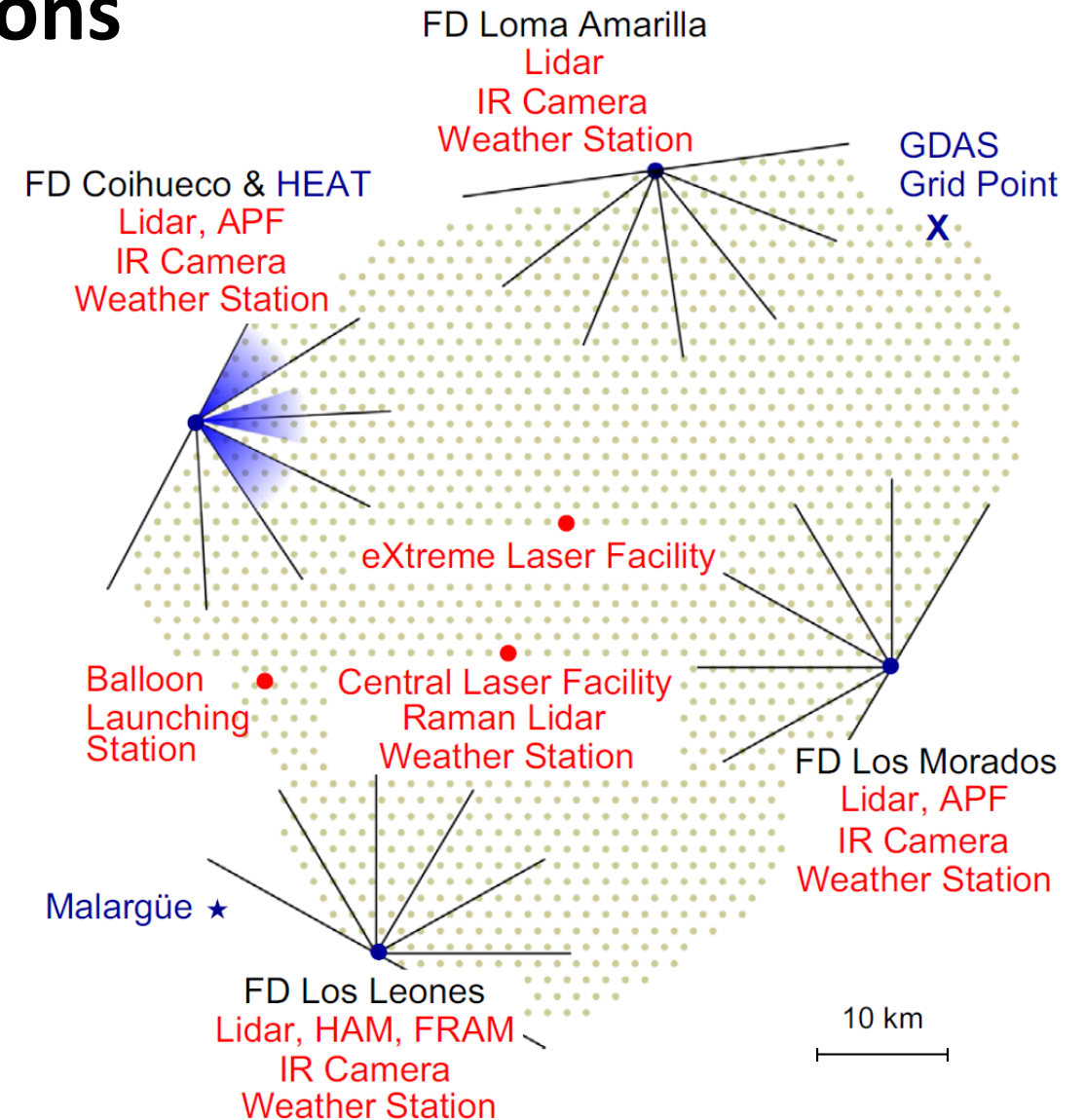
- CLF / XLF
- Elastic lidars
- Raman lidar
- Horizontal Attenuation Monitor HAM
- Aerosol Phase Function Monitor APF
- Ph(F)otometric Robotic Atmospheric Monitor FRAM

## Clouds:

- IR Cameras
- Elastic lidar
- CLF / XLF

## State variables:

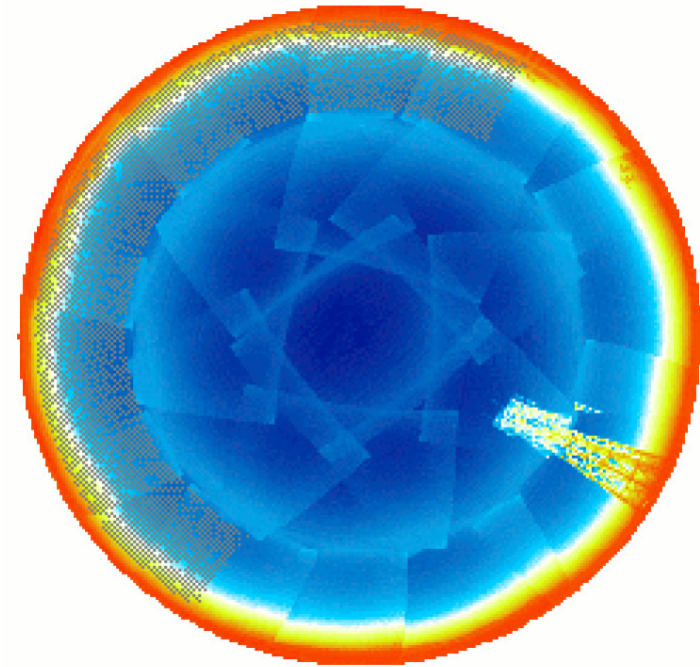
- Weather stations
- Formerly: radio soundings



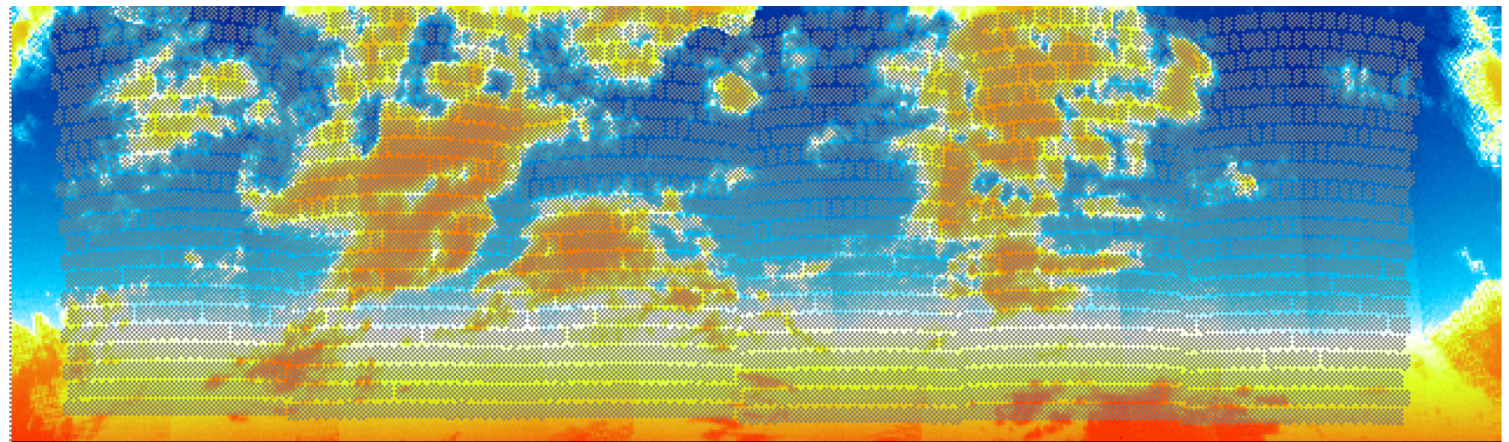
# Infrared cloud cameras



- Cloud cover



Hemisphere picture



Clouds in the FOV of a FD



# Infrared cloud cameras

## Operating scheme:

- During FD data taking
- Fully automated operation
- Every 15 min. full hemisphere
- Every 5 min. in FOV of FD

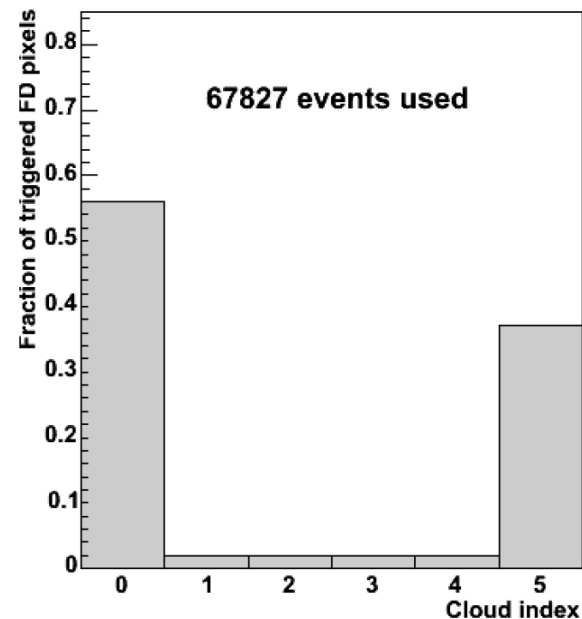
## Data output

- Standard cloud cover information of cosmic ray event reconstruction
- Data since 2004

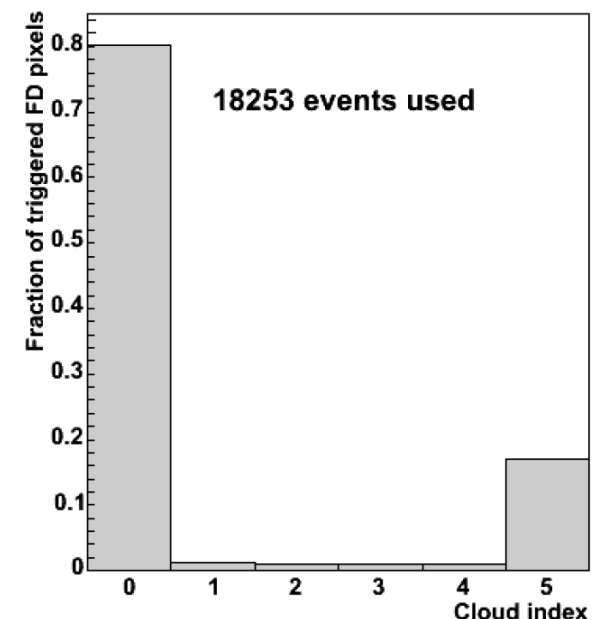
## Challenges:

- Regular maintenance
- Sophisticated data analysis which is done quite manually

CI triggered pixel distribution



CI triggered pixel distribution (LIDAR)





# Weather Stations

- At each of the four FD sites and at the CLF
- Atmospheric state variables

## Data output

- Every 5 min. T, p, u, wind information
- Derived data density, atmospheric depth, water vapour
- Fully automated scripts to process the data for use in the cosmic ray event reconstruction

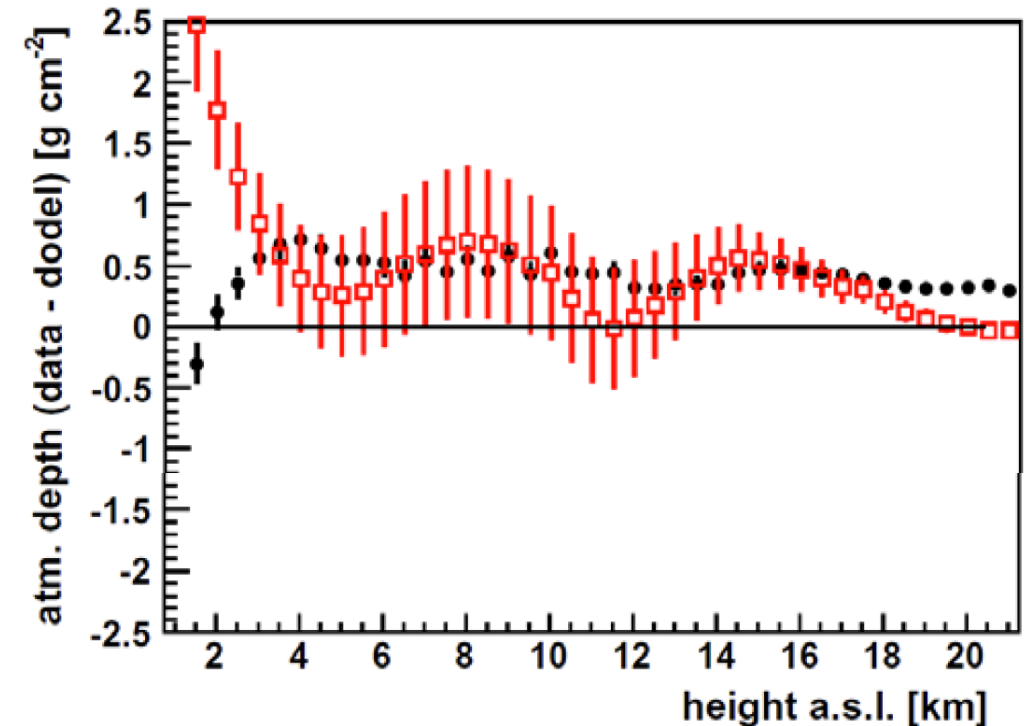


# Radio Soundings – Atmospheric Profiles

- 331 radio soundings of state variables
- Data between 2002 and 2010
- Used to validate GDAS

## Data of GDAS

- Every 3 hours
- At 23 constant pressure levels
- Fully automated scripts to process the data for use in the cosmic ray event reconstruction



# Impact on the Energy Reconstruction

<b>Systematic uncertainties on the energy scale</b>	
Absolute fluorescence yield	3.4%
Fluor. spectrum and quenching param.	1.1%
Sub total (Fluorescence yield - sec. 2)	<b>3.6%</b>
Aerosol optical depth	3% ÷ 6%
Aerosol phase function	1%
Wavelength depend. of aerosol scatt.	0.5%
Atmospheric density profile	1%
Sub total (Atmosphere - sec. 3)	<b>3.4% ÷ 6.2%</b>
Absolute FD calibration	9%
Nightly relative calibration	2%
Optical efficiency	3.5%
Sub total (FD calibration - sec. 4)	<b>9.9%</b>
Folding with point spread function	5%
Multiple scattering model	1%
Simulation bias	2%
Constraints in the Gaisser-Hillas fit	3.5% ÷ 1%
Sub total (FD profile rec. - sec. 5)	<b>6.5% ÷ 5.6%</b>
Invisible energy (sec. 6)	<b>3% ÷ 1.5%</b>
Stat. error of the SD calib. fit (sec. 7)	<b>0.7% ÷ 1.8%</b>
Stability of the energy scale (sec. 7)	<b>5%</b>
<b>Total</b>	<b>14%</b>

# Conclusion

- Observatories run for many years up to few decades
- Atmospheric monitoring systems have to be designed for **long-term operations**, for **low staff assignment** during continuous operation, and for **low maintenance effort**
- In the designing phase of an observatory, the requirements for the atmospheric monitoring have to be defined carefully:
  - What data are needed in what precision, format, and which time intervalls?
  - How fast have these data to be available for cosmic ray data analyses?
  - How much of redundancy is aimed for?
  - Is the planning, installation, and design of analyses procedures of atmospheric monitoring systems fast enough to meet the needs of the observatory?
- It is recommended to rely on **robust, most simple**, and **sufficiently automatized** atmospheric monitoring systems for use at cosmic ray observatories, because of their long-term operation at typically quite remote sites.