

## objective

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We want a simple (ideal) natural generalization of 2 body kinematics, something in the same spirit for more bodies. We want as input:

• The masses.

Invitation

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- Define unambiguosly a particular fragmentation.
- Constrict all but one of the particles @ the end of the fragmentation in the lab system.

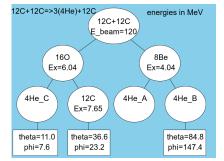
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We need a data structure (a tree) to do this. Then somehow do kinematics on the tree.

#### BRT and solutions



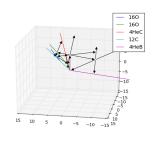
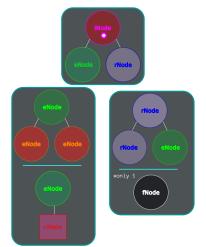


Figure: Look at the gif

To solve the BRT is to assign to every node at least one lab velocity (or also  $v_cm$ ) vector.

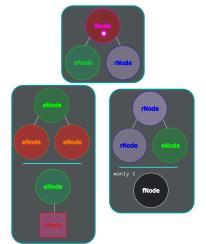
### BRT structure



- essentially 2 types of structures.
- self similar.
- leaf structure.

Strategy: solve it locally. Propagate info between nodes.

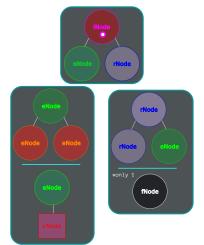
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### **BRT** structure

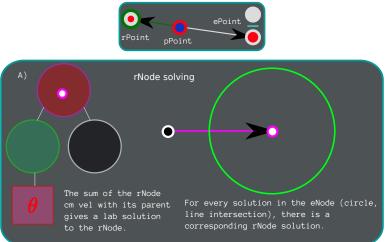


- essentially 2 types of structures.
- self similar. We'll need recursion.
- leaf structure.

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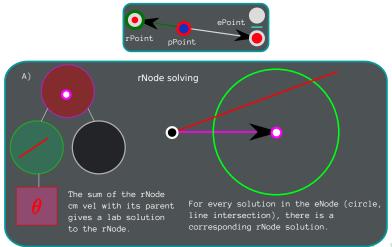
# binary example

We must abstract into node notation.



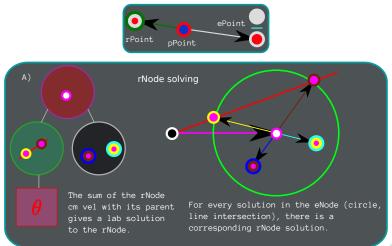
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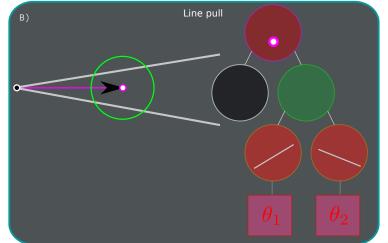
# binary example

We must abstract into node notation. Two solutions.



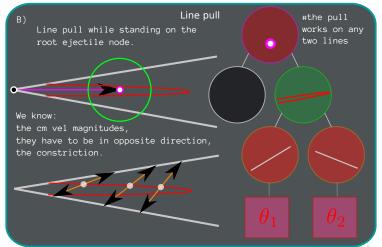
# ternary example

intersect with what?!



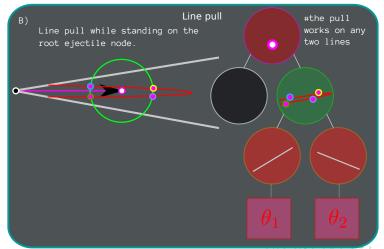
## ternary example

## gifAnim



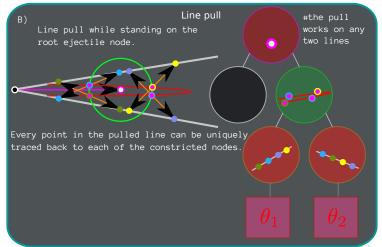
## ternary example

#### 4 solutions?!



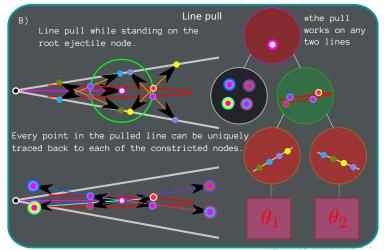
## ternary example

#### 4 solutions?! it's invertible!

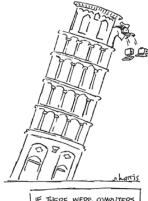


## ternary example

#### 4 solutions?! it's invertible!



### Come to my poster!!



IF THERE WERE COMPUTERS IN GALILEO'S TIME

- Generalization of the algorithm.
- Experimental data of a ternary reaction (PRC).
  4 solution case.
- Software (still in alpha).
- Discuss more generalizations.
- Discuss potential applications.