

Tracking

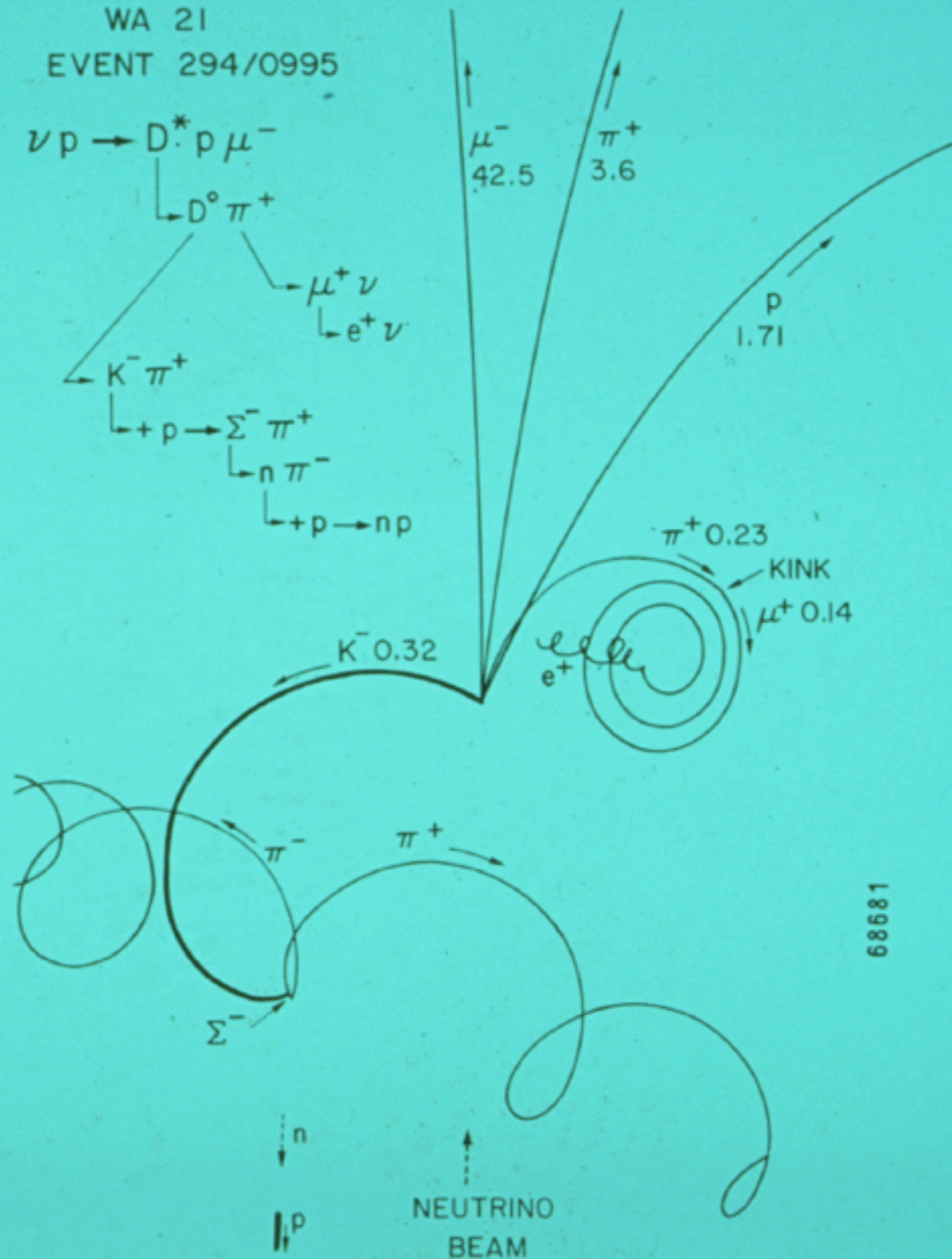
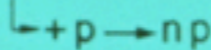
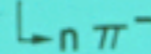
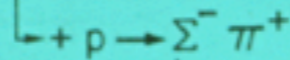
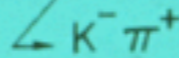
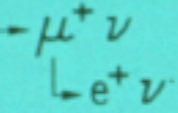
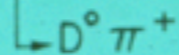
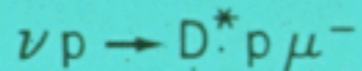
Eugenio Paoloni



AACHEN-BONN-CERN-MUNICH-OXFORD COLLABORATION

WA 21

EVENT 294/0995



68681

MOMENTUM IN GeV/c

Hors D'Oeuvre: Résumé

- ◆ Status report on VXDTF2
- ◆ Status report on other activities
- ◆ Status report on open issues, pending activities

0) Pattern Recognition: Complexity of the Problem

Given a set of 374 clusters
(average Y4s event with background,
present simulation) in how many way
you can partition it in 12 non
overlapping subsets?

11 tracks +

background



StirlingS2 [374, 12] =

8579244752112013445320144183073086694228183791229192130021182058774964\
1436179559446247749968911846831518389612245740728531964526941049795459\
0694653776123576308210237582300645863076213963359103884113699331498842\
4984937253821782188530452612467489774779681511888099214869999009234797\
6489917458180327072450141088926514002010754791696457139830890200629213\
750010468838888233544683418665341555331757337

roughly

8.58 10^{394}

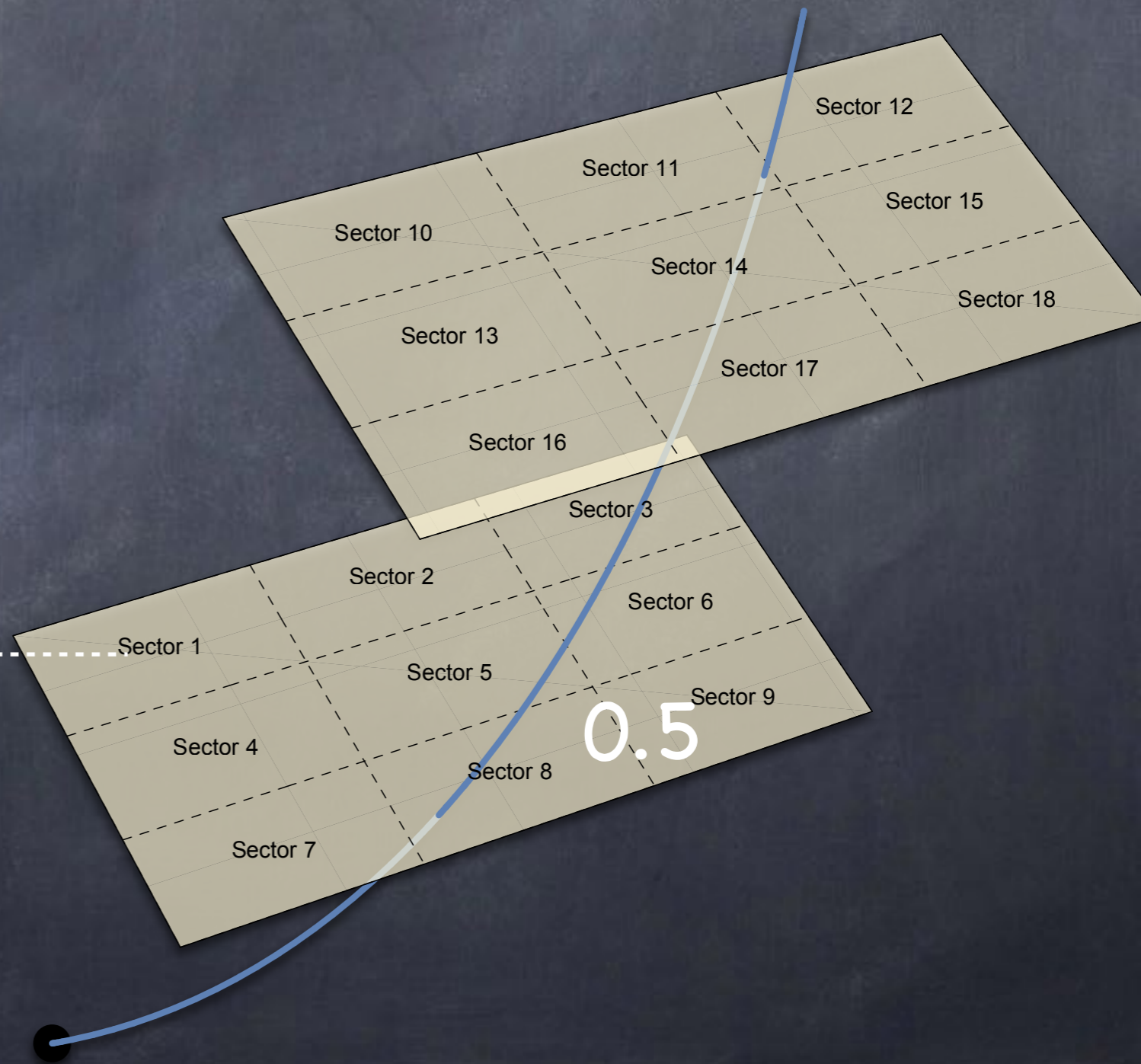
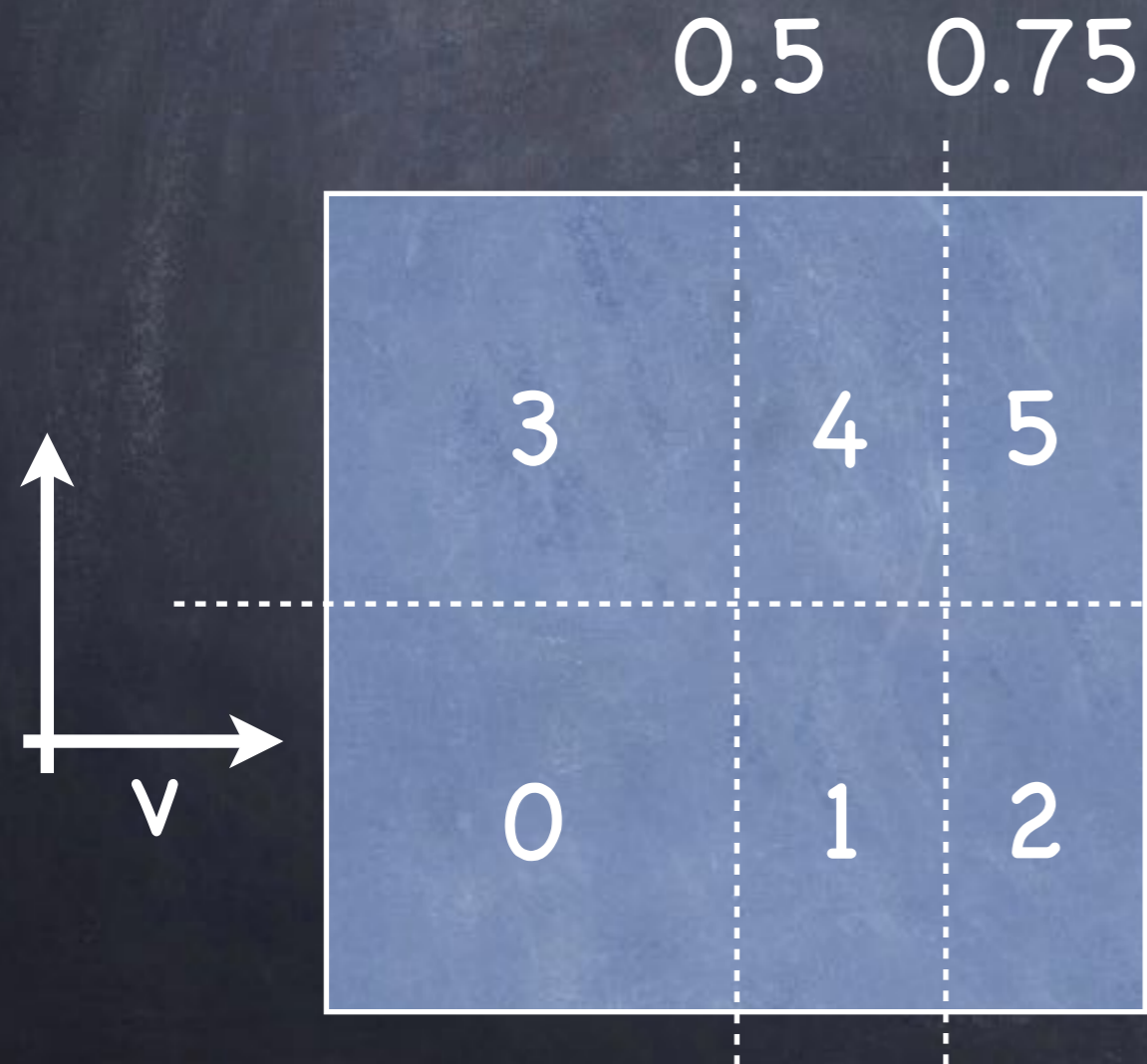
And just a single one of these partitions is the correct one. How to find it in milliseconds?

- Do not consider unlikely combinations
 - Subsets with more than 2 - 4 clusters per layer
 - Subsets whose clusters are scattered over erratically
- Just consider "reasonable combination" to reduce the haystack
 - Can we better define "reasonable combination"?



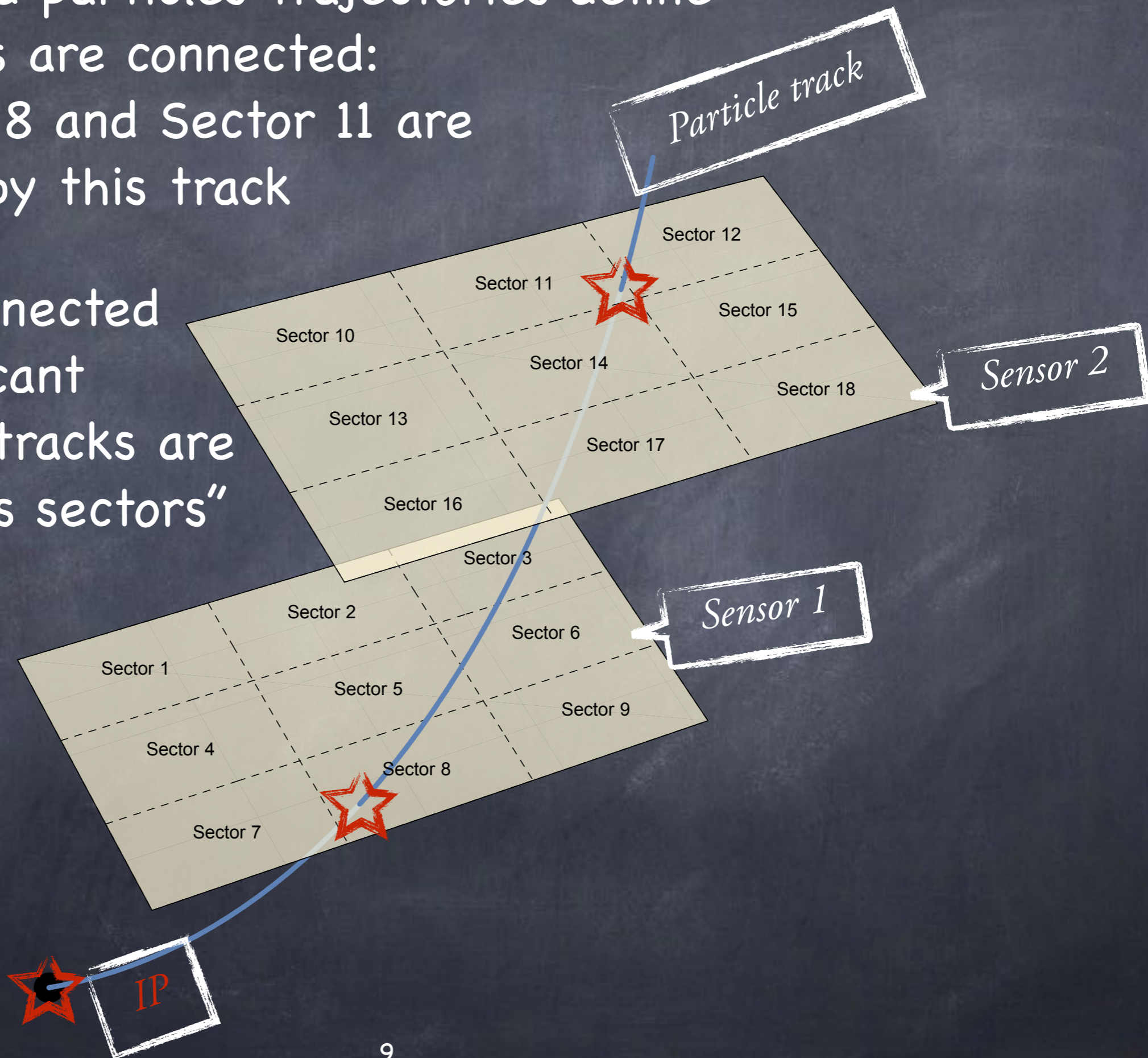
1) The Sector:
Divide et Impera

- We divide the sensor active surface in sectors
- The active surface is mapped to a square
- The square is partitioned in rectangular areas, e.g:



- The charged particles trajectories define how sectors are connected:
E.g: Sector 8 and Sector 11 are connected by this track

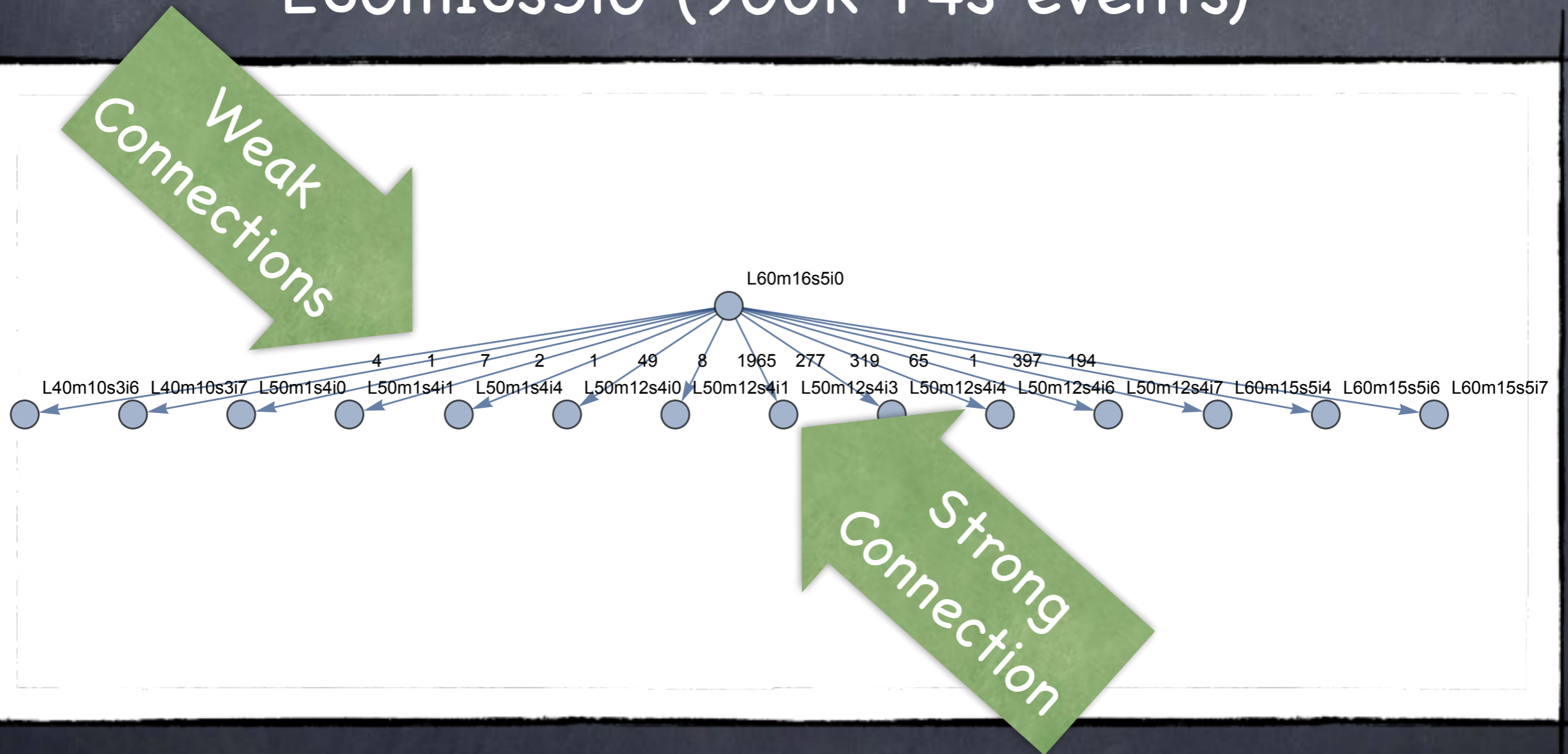
- Sectors connected by a significant number of tracks are said "friends sectors"





The Sector Connection:
Il braccio violento della legge.
AI CINEMA!

Let's have a look at the sectors connected to the sector 0 on the forward sensor on module 16 on layer 6:
L60m16s5i0 (900k Y4s events)



heuristic | hyōō'ristik |

adjective

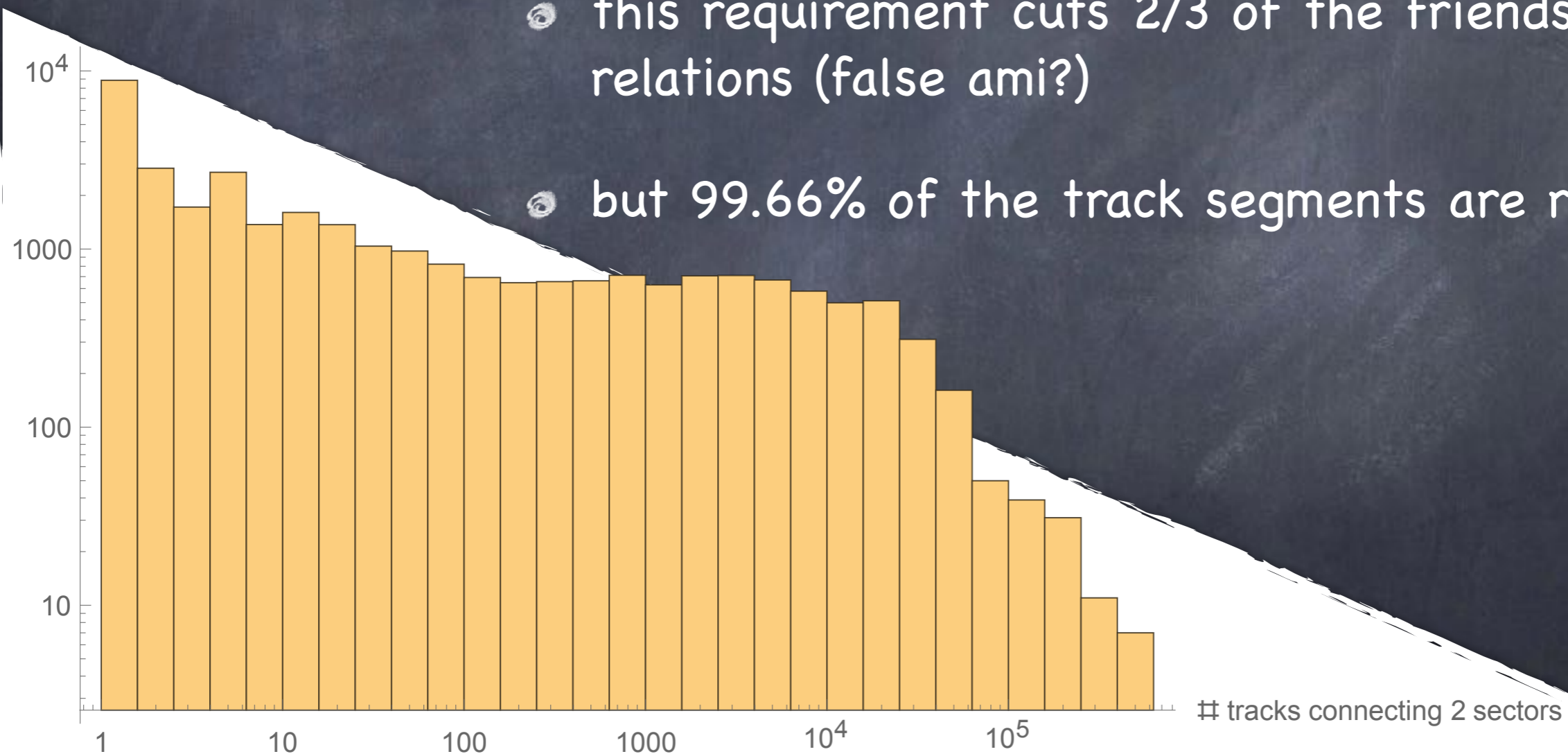
enabling a person to discover or learn something for themselves: a "hands-on" or interactive heuristic approach to learning.

- **Computing** proceeding to a solution by trial and error or by rules that are only loosely defined.

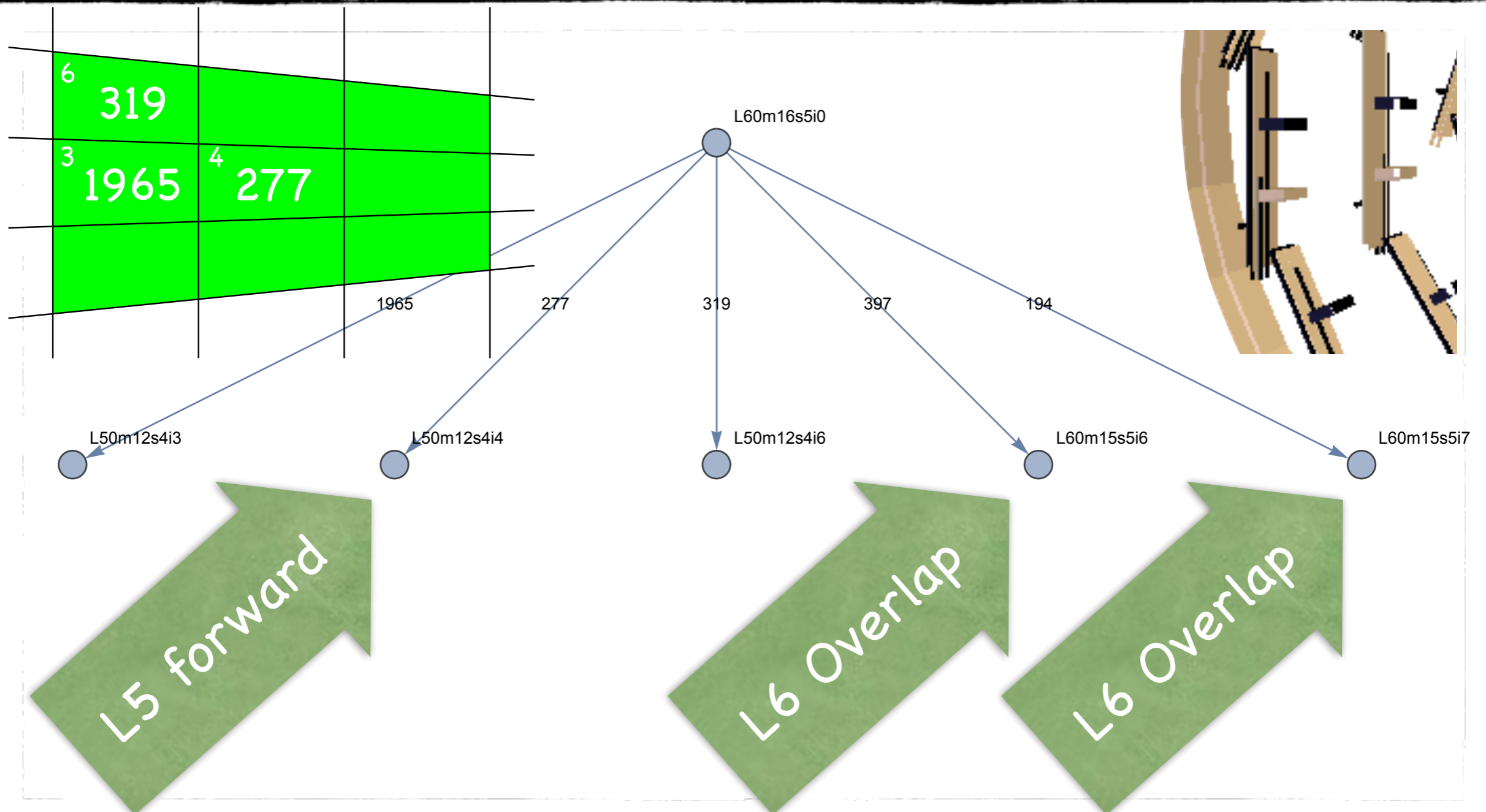
• Let's define "friends" two sectors connected by more than 100 tracks in 900k Y4S events

• this requirement cuts 2/3 of the friendship relations (false ami?)

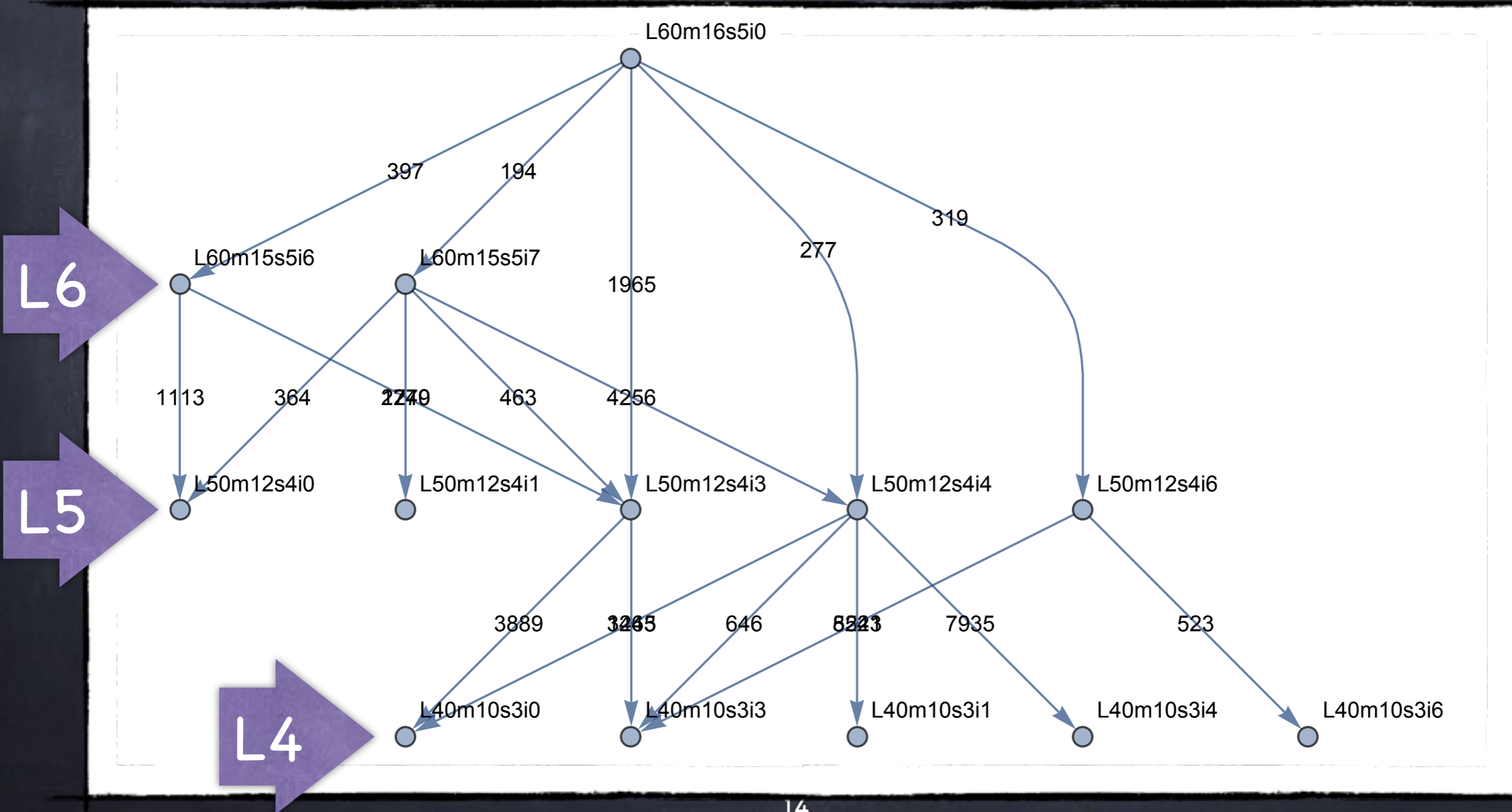
• but 99.66% of the track segments are retained



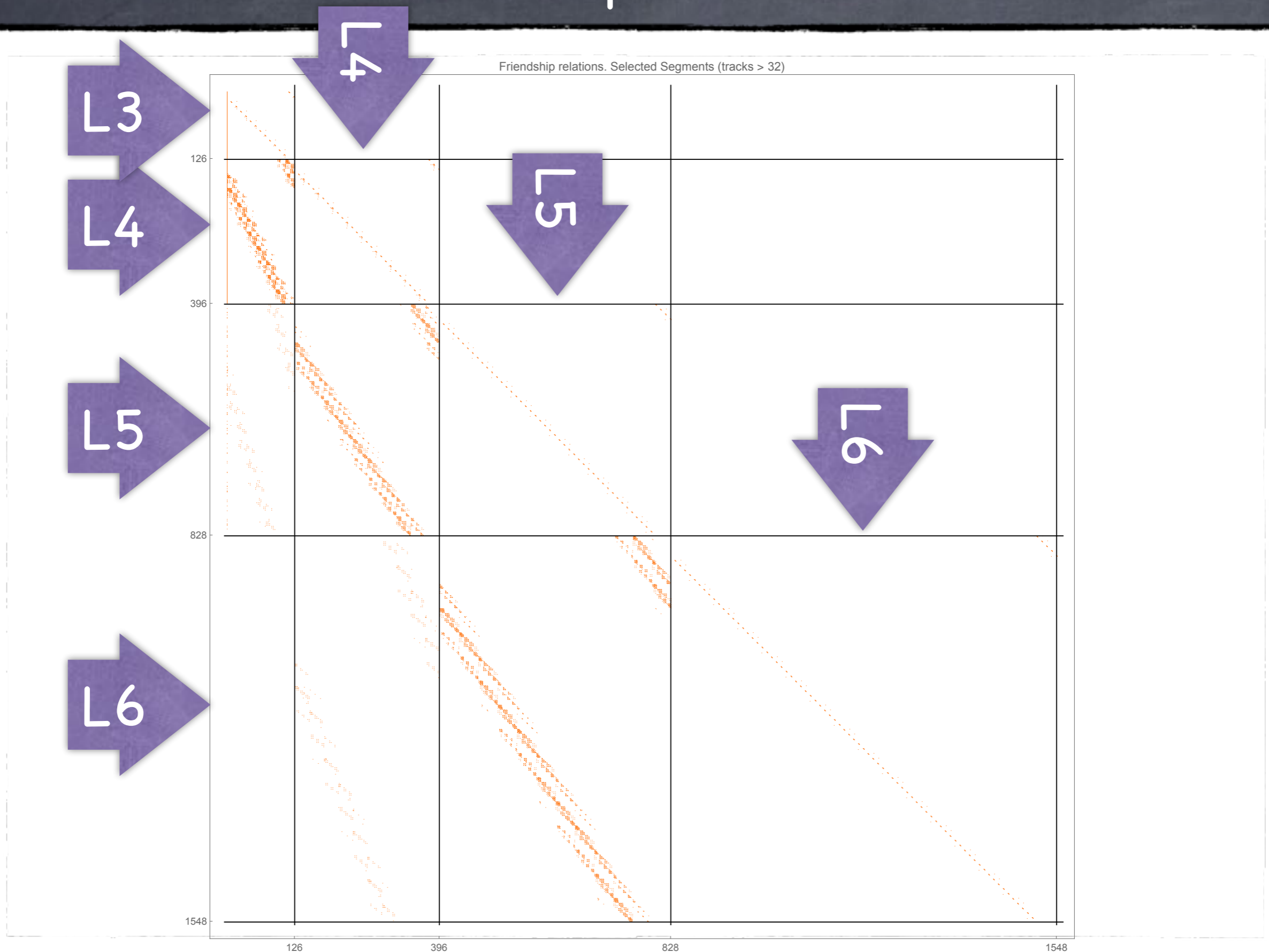
Let's have a look at the sectors connected to the sector 0 on the forward sensor on module 16 on layer 6:
L60m16s5i0 (900k Y4s events)



Let's have a look at the sectors connected to the sector 0 on the forward sensor on module 16 on layer 6:
 L60m16s5i0 (900k Y4s events)



The Friendship relation matrix



Who takes care of the creation of the sectors?

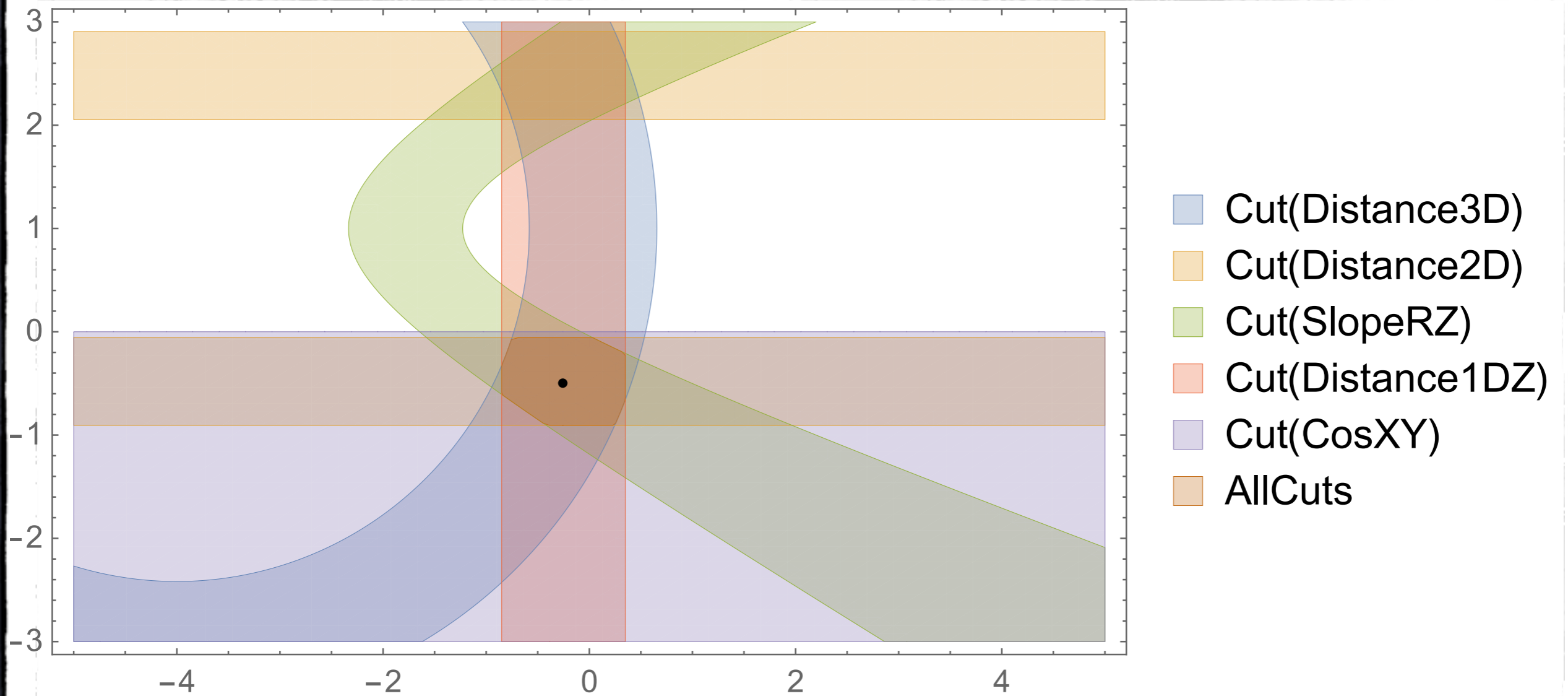
- The SectorMapBootstrapModule in module/vxdtfRedesign
- At present all the sectors are partitioned in the very same way (3x3 / sensor, that is 1548 sectors / SVD)
 - We need to investigate how close to the optimum this is (trade off memory foot print / speed)
 - We can tailor the sector to cope with sensor defects (broken APV, clusters of broken strips, etc.)

3) Filters

Filters for SpacePoints combination

- We define a filter for each pair of friend sectors in order to select reasonable SpacePoints pair combinations (aka Segments).

2 Space point Filters type



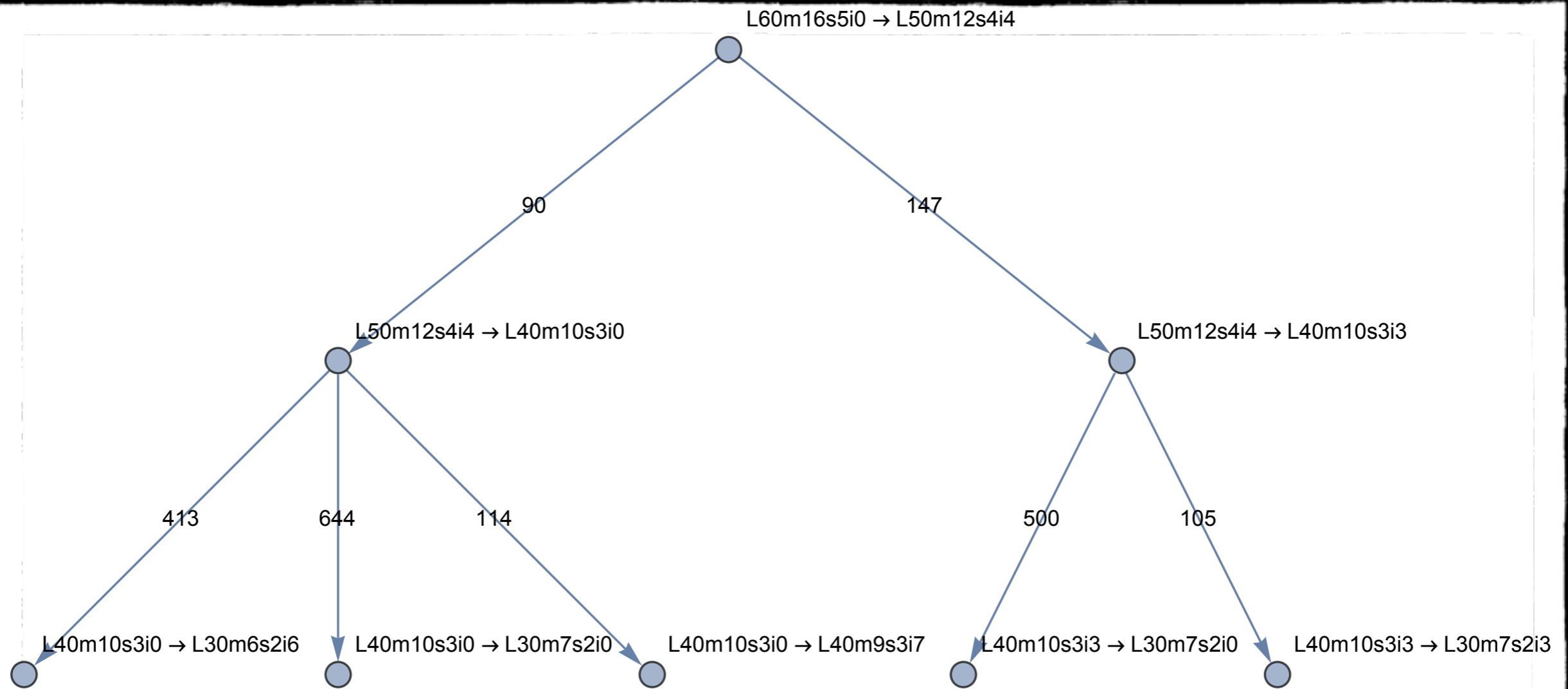
Training

- At present the implementation of the training is not yet very terse
 - One module collects the data from simulated events: `VXDTFTrainingDataCollector`
 - One module merges the data, it defines the friendship relations and it trains the filters: `RawSecMapMerger`

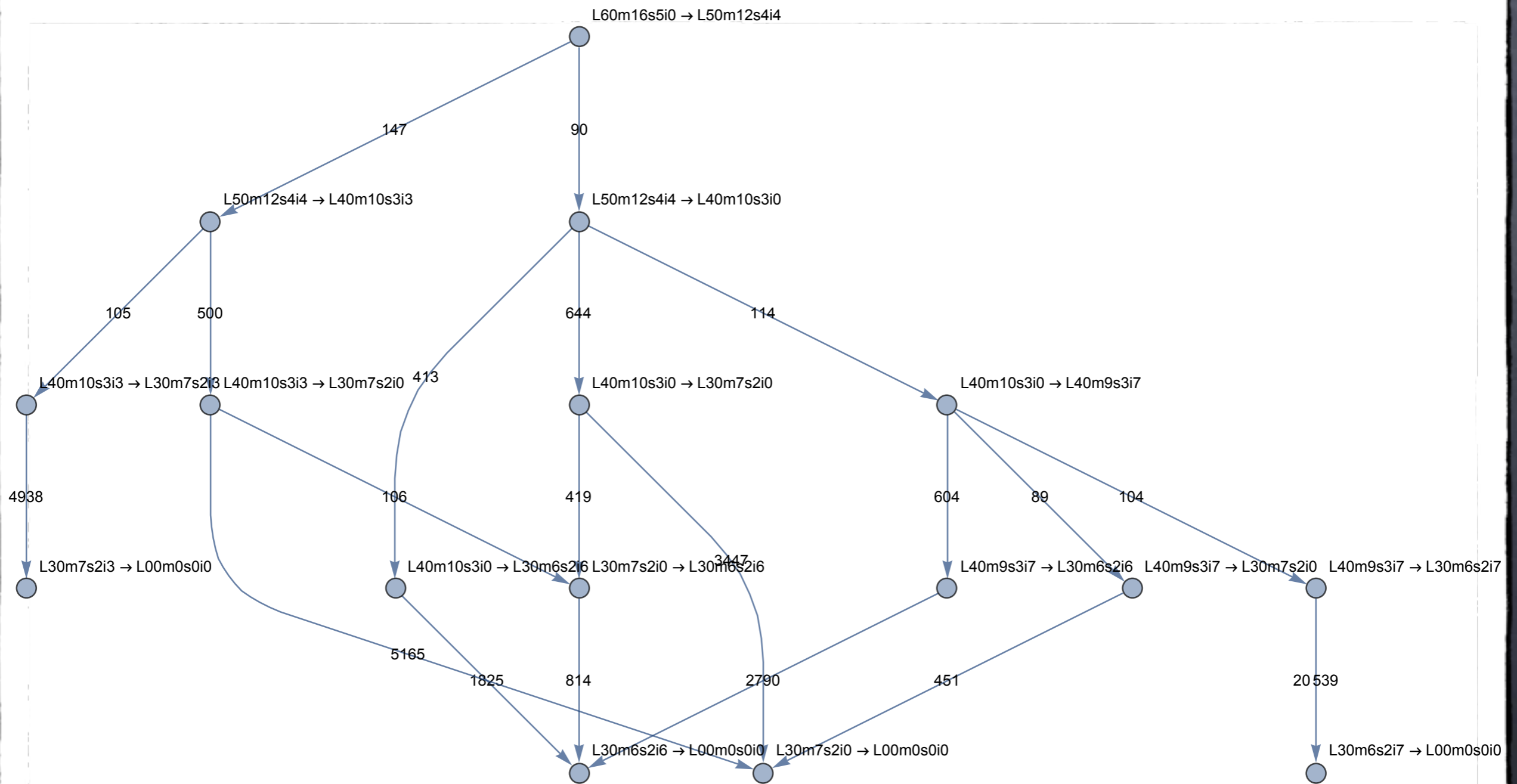
From Segments to Triplets

- Each friendship relation is treated as a node in a graph.
- By a MC sample we define the edges of the graph, i.e. the allowed combinations of segments sharing the mid VXD hit

Let's have a look at the segment connection

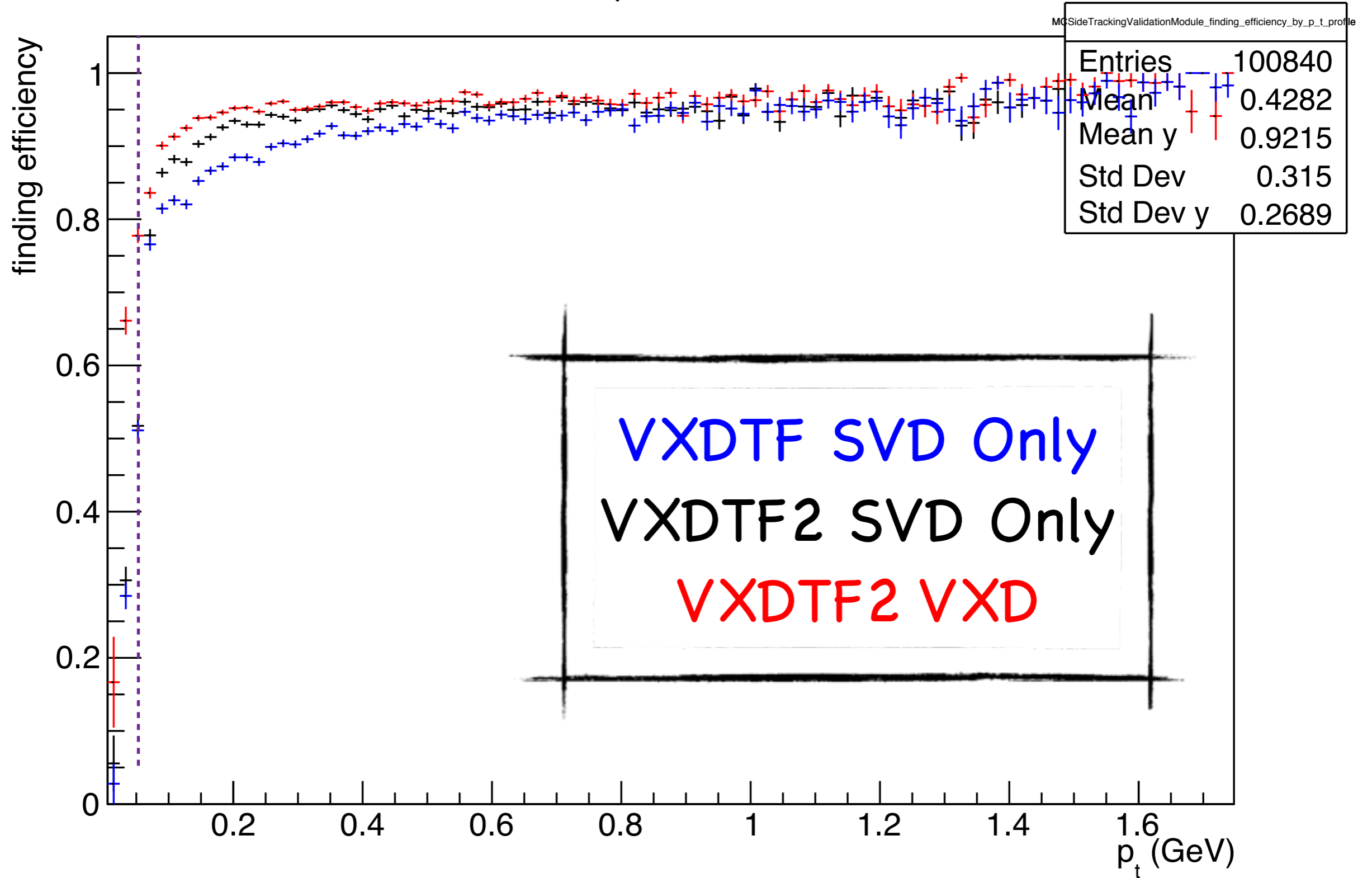


Let's have a look at the segment connection

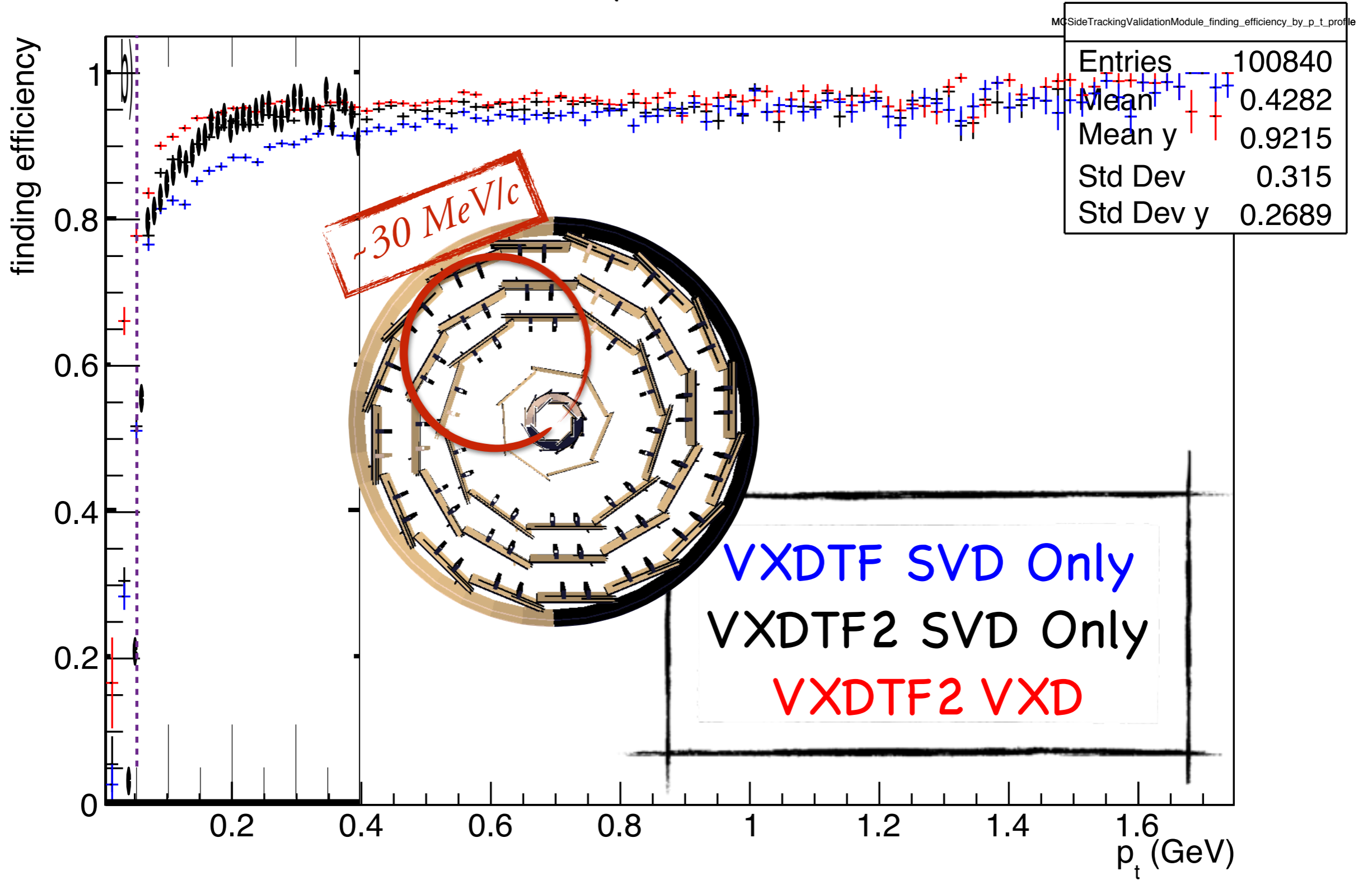


Ok... what are the
performances?

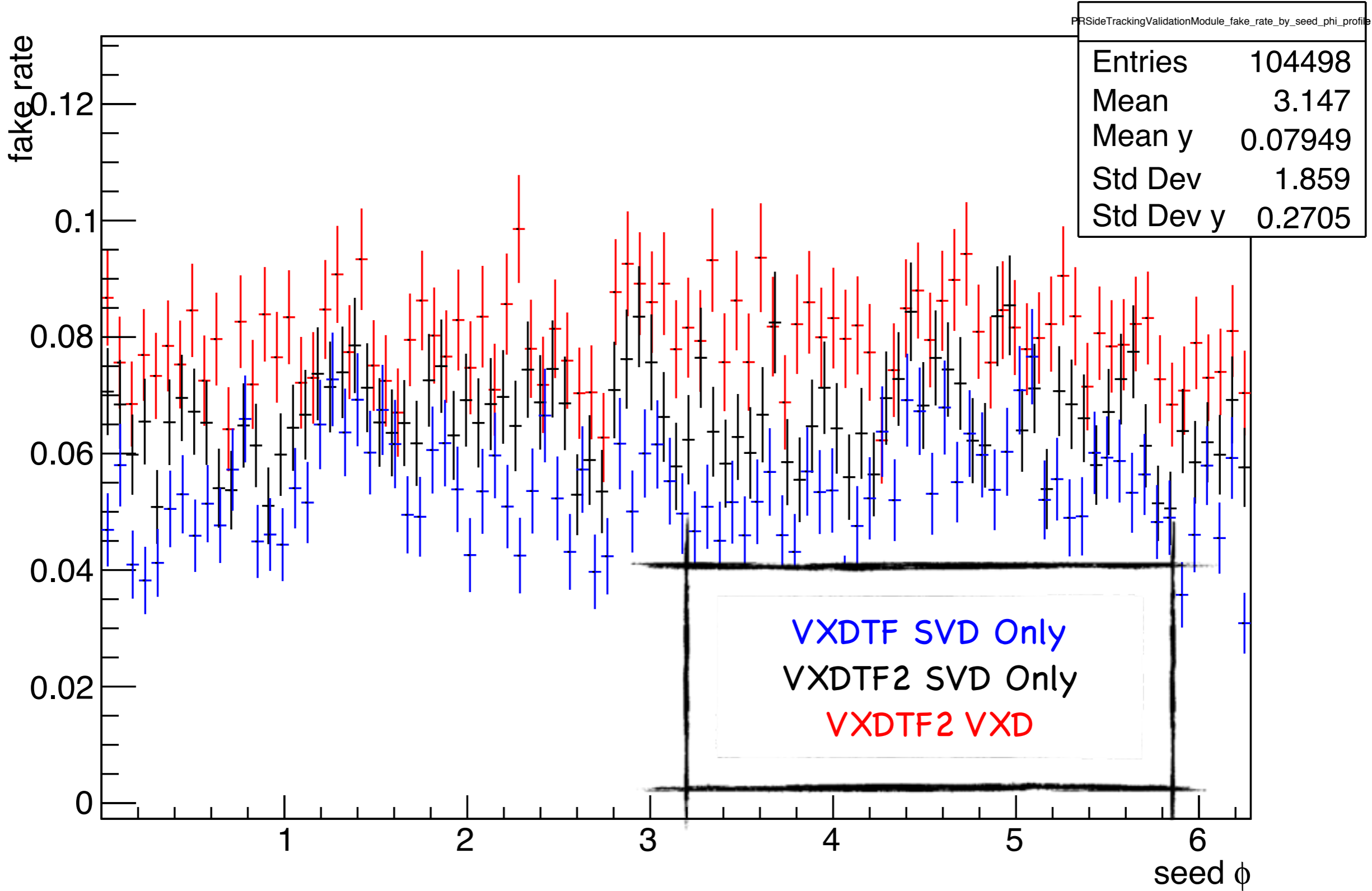
Profile of finding efficiency by p_t from MCSideTrackingValidationModule



Profile of finding efficiency by p_t from MCSideTrackingValidationModule



Profile of fake rate by seed ϕ from PRSideTrackingValidationModule

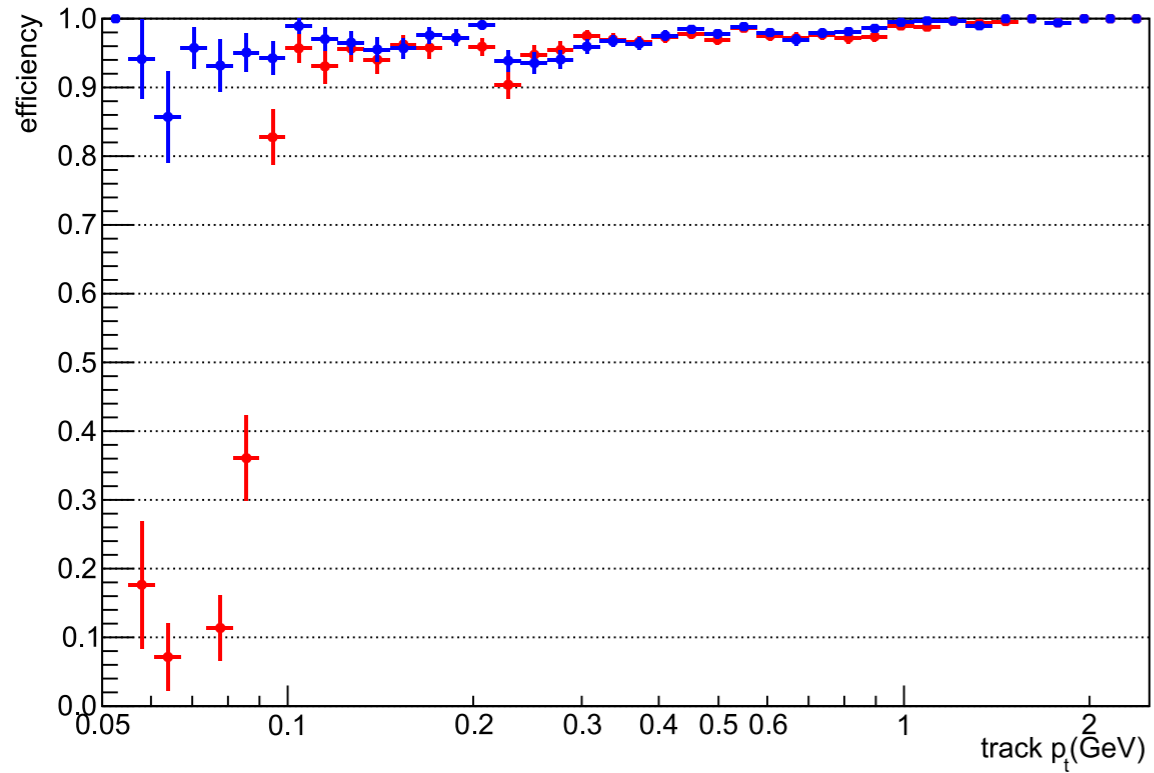


- We are almost there to say "Good farewell VXDTF"
- VXDTF2 will be optional in the next release and standard in the next to next one
- We have to:
 - use the condition database for storing the sector map
 - optimize the training procedure of the VXDTF2
 - test the VXDTF2 resilience against dead channels, dead APV, etc...
 - replicate in BelleII the efficiency studies done in BaBar

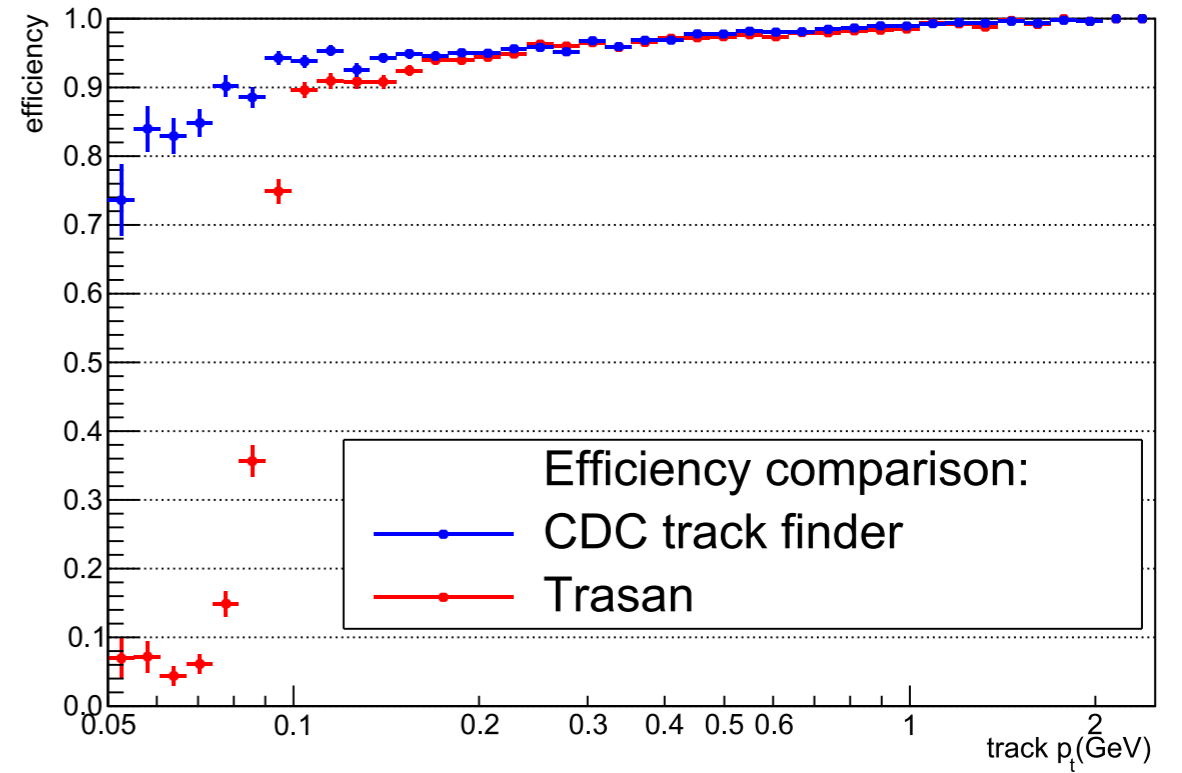
CDC track finding

CDC track finding efficiency vs p_t vs multiplicity

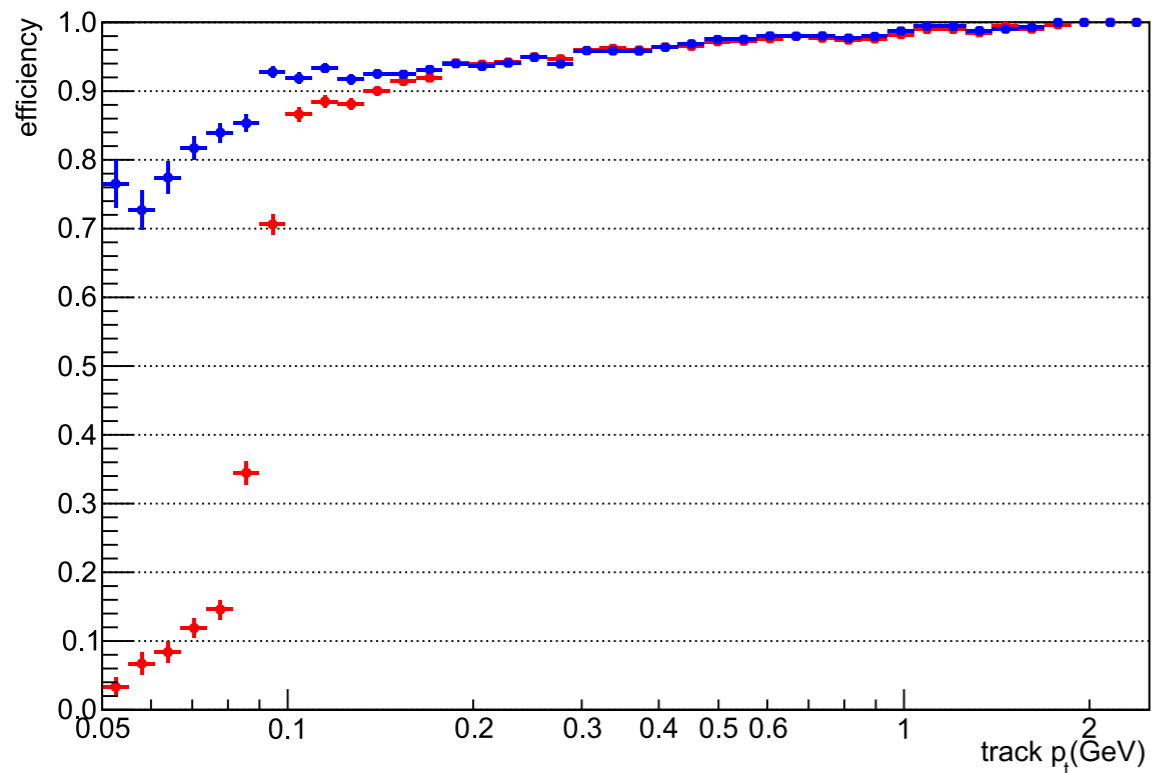
Number of tracks: (1, 7)



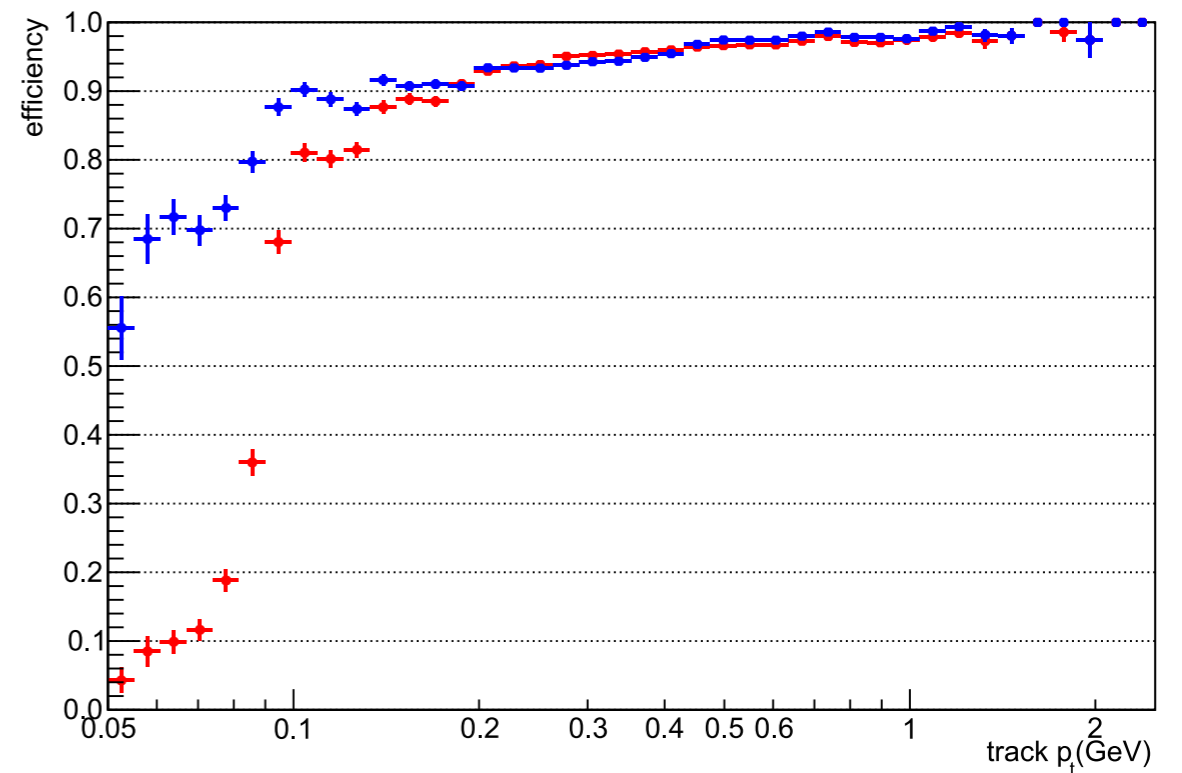
Number of tracks: (8, 11)



Number of tracks: (12, 15)

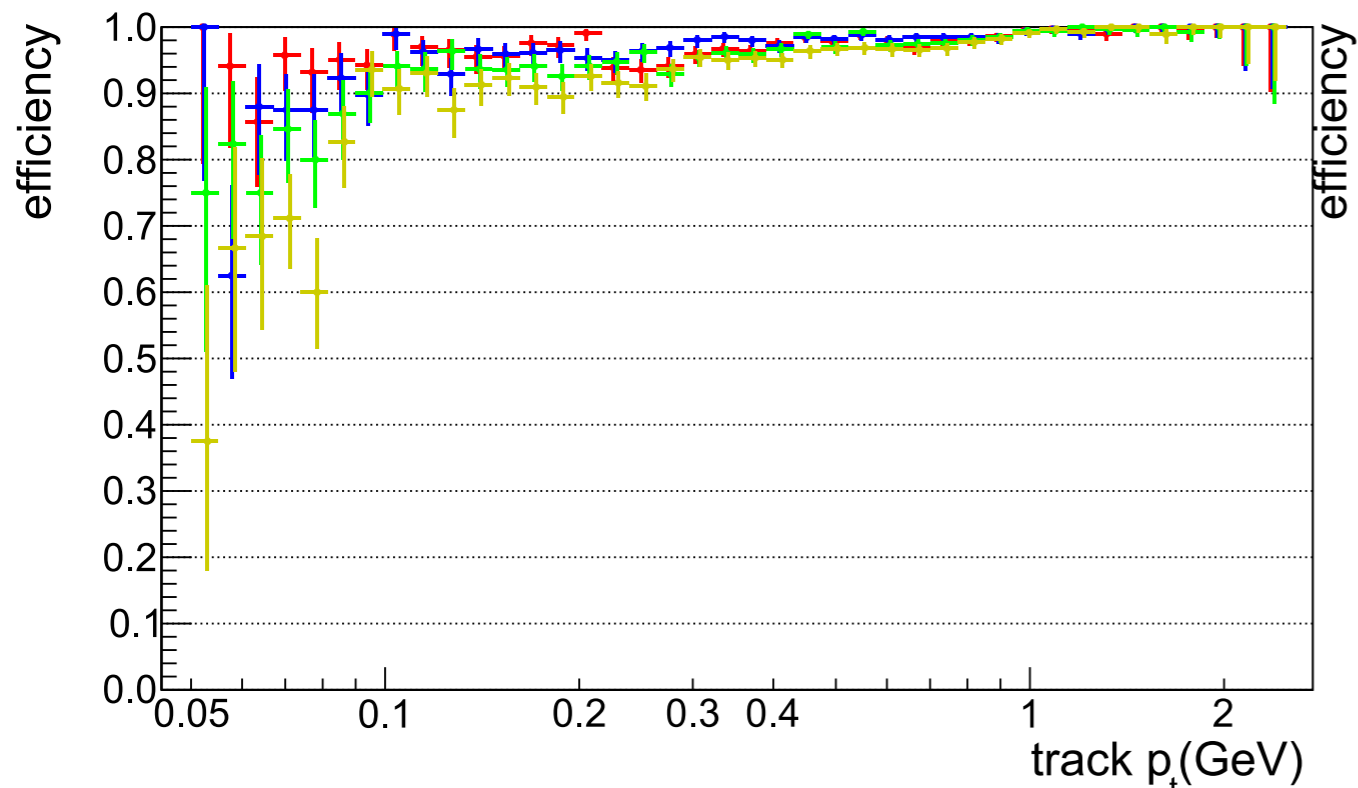


Number of tracks: (16, 29)

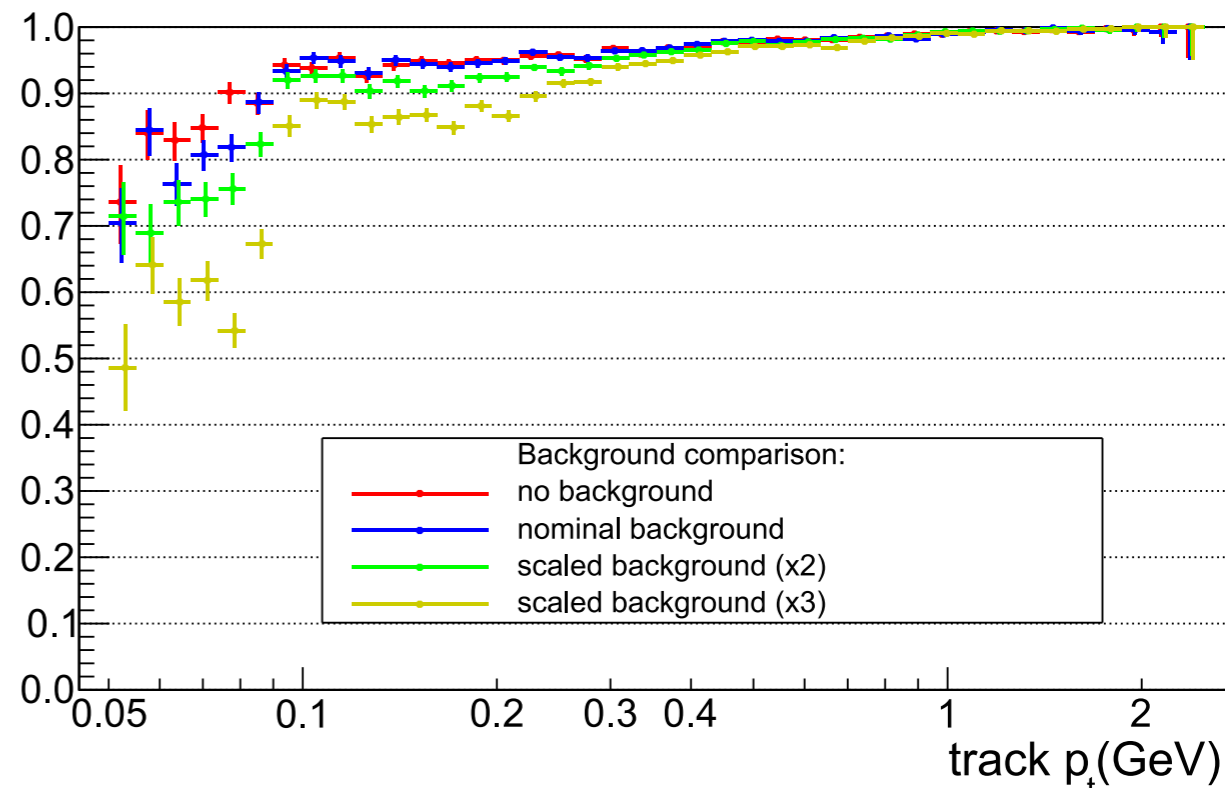


Track finding efficiency vs background rate

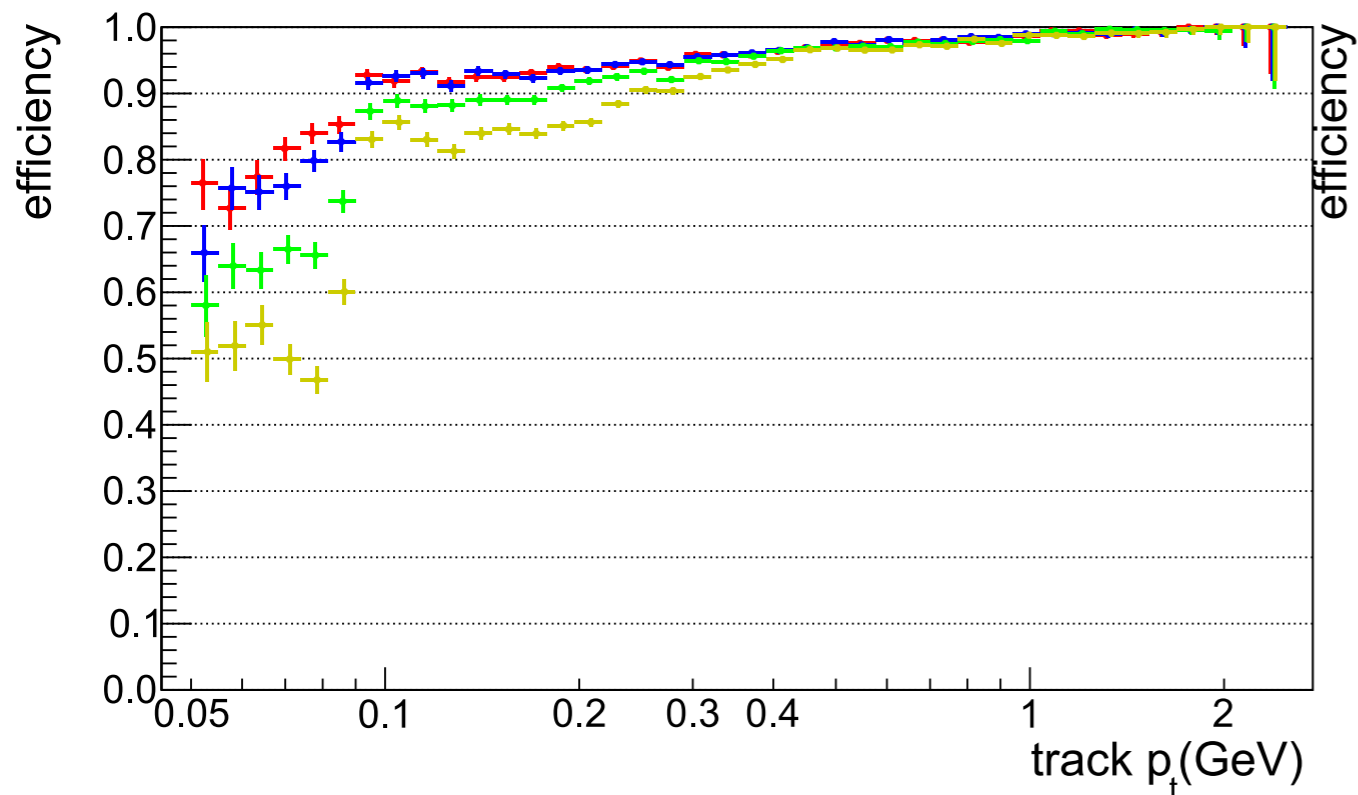
Number of tracks: (1, 7)



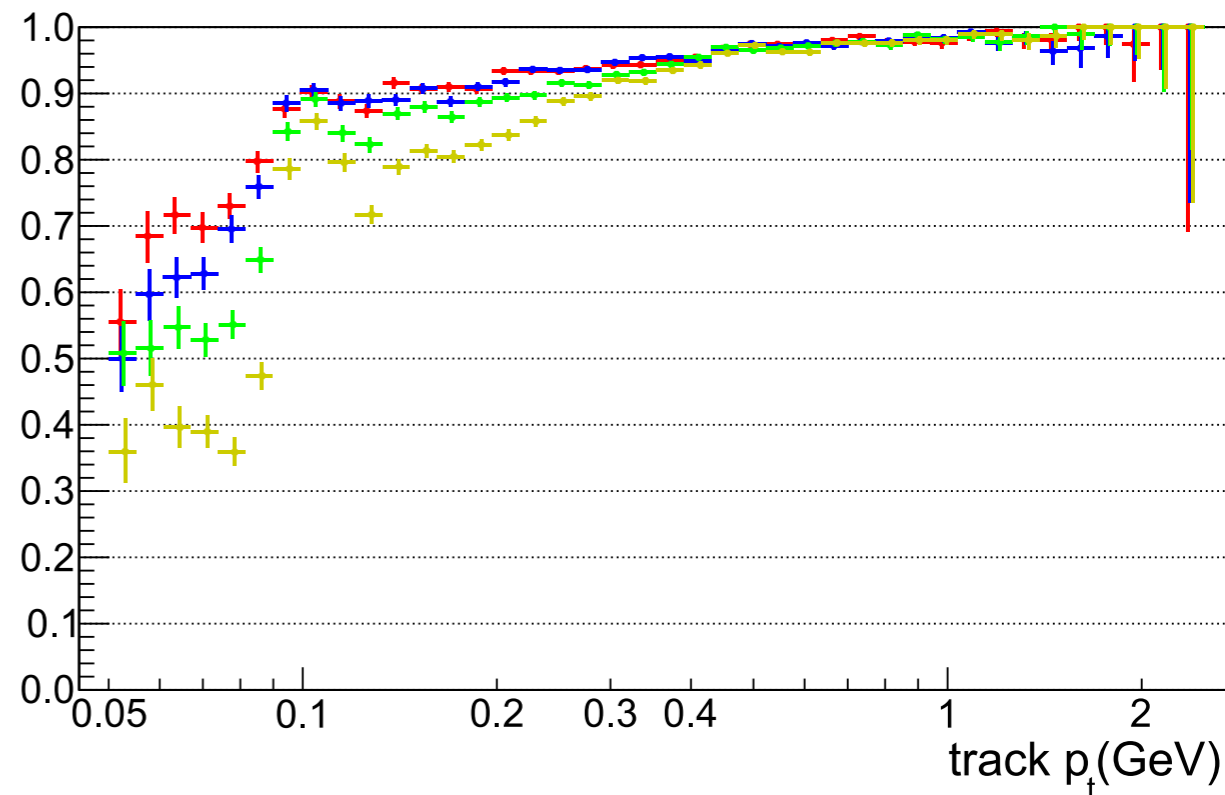
Number of tracks: (8, 11)



Number of tracks: (12, 15)



Number of tracks: (16, 29)



Open issues : ' (

- Multiple mass hypothesis fit is not working as advertised.
- pion mass hypothesis always give the best results ??
- lack of expertise on Genfit2

CKF

A Combinatorial Kalman Filter uses the principles of the Kalman Filter for track finding. Starting with a seed, it adds hits with some kind of Monte Carlo Tree Search algorithm.

First implementation: extrapolate from CDC to VXD (SVD).

- Reduction of fakes
- Reduction of SpacePoint combinations
- Increased finding efficiency

Primary

All MC tracks

MC track has VXD hits

VXD part was found

MC track has CDC hits

CDC part was found

	10325						
	Yes					No	
	10241					84	
	Yes			No			No
	8340			1901			84
	Yes		No	Yes		No	Yes
	7955		385	1622		279	84
	Yes	No	No	Yes	No	Yes	No
	7023	932	385	1321	301	279	38
Merging Efficiency	CKF	Criteria?	CKF	Very bad!	VXDTF Must help	Criteria?	CDCTF Must help

Conclusions

- Lot of work done
- The work done is paying the dividends
- Lot of exciting work to do
- Join the tracking group, work with us!

version 1 svd only

Name	Calls	VMemory(MB)	Time(s)	Time(ms)/Call
RootInput	10000	0	48.05	4.81 +- 18.69
EventInfoPrinter	10000	0	0.02	0.00 +- 0.00
Gearbox	10000	0	0.00	0.00 +- 0.00
Geometry	10000	0	0.00	0.00 +- 0.00
EventCounter	10000	0	0.50	0.05 +- 0.02
SetupGenfitExtrapolation	10000	0	0.01	0.00 +- 0.00
VXDTF	10000	0	45.59	4.56 +- 25.06
RecoTrackCreator	10000	0	3.52	0.35 +- 0.10
MRecoTracksMatcher	10000	0	9.68	0.97 +- 0.32
CombinedTrackingValidationModule (3 modules):	10000	0	0.73	0.07 +- 0.06
EventwiseTrackingValidationModule	10000	0	29.71	2.97 +- 9.97
PRSideTrackingValidationModule	10000	0	130.26	13.03 +- 5.71
MCSideTrackingValidationModule	10000	0	71.11	7.11 +- 2.08
Total	10000	0	353.02	35.30 +- 35.63

VXDTF SVD: 4.56 ms/Events

Name	Calls	VMemory(MB)	Time(s)	Time(ms)/Call
RootInput	10000	0	58.09	5.81 +- 25.98
EventInfoPrinter	10000	0	0.02	0.00 +- 0.00
Gearbox	10000	0	0.00	0.00 +- 0.00
Geometry	10000	0	0.00	0.00 +- 0.00
EventCounter	10000	0	0.56	0.06 +- 0.02
SpacePointCreatorSVD	10000	0	6.24	0.62 +- 0.55
SectorMapBootstrap	10000	0	0.01	0.00 +- 0.00
SegmentNetworkProducer	10000	0	8.02	0.80 +- 2.47
TrackFinderVXDCellMat	10000	0	6.06	0.61 +- 1.16
QualityEstimatorVXDCircleFit	10000	0	1.22	0.12 +- 0.27
SPTCvirtualIPRemover	10000	0	0.04	0.00 +- 0.01
SVDOverlapChecker	10000	0	39.46	3.95 +- 75.36
TrackSetEvaluatorHopfieldNNDEV	10000	0	43.56	4.36 +- 89.43
SPTCmomentumSeedRetriever	10000	0	8.30	0.83 +- 1.67
SPTC2RTConverter	10000	0	4.34	0.43 +- 0.15
MRecoTracksMatcher	10000	0	10.77	1.08 +- 0.45
CombinedTrackingValidationModule (3 modules):	10000	0	0.81	0.08 +- 0.07
EventwiseTrackingValidationModule	10000	0	32.04	3.20 +- 9.87
PRSideTrackingValidationModule	10000	0	145.22	14.52 +- 6.01
MCSideTrackingValidationModule	10000	0	77.16	7.72 +- 2.40
Total	10000	0	462.52	46.25 +- 171.20

VXDTF SVD: 11.7 ms/Events

$\Upsilon(4S)$ event with and without background

Case	$\Upsilon(4S)$ -only	BG-only	$\Upsilon(4S) + \text{BG}$	$\Upsilon(4S) + 2 \times \text{BG}$
L3 strips u/v	49.2/36.7	260.0/121.7	308.1/158.0	562.2/278.8
L3 clusters u/v	11.8/11.8	39.0/37.9	50.3/49.3	87.0/86.1
L3 SPs	26.1	233.9	318.0	791.0
L4 strips u/v	39.4/29.1	120.3/61.2	159.1/90.1	277.8/150.6
L4 clusters u/v	12.7/12.6	29.9/26.7	42.5/39.2	71.8/65.3
L4 SPs	22.5	100.5	143.1	320.4
L5 strips u/v	37.3/28.5	122.7/67.2	160.1/95.8	282.7/162.9
L5 clusters u/v	12.3/12.1	35.0/30.5	47.3/42.7	82.0/72.9
L5 SPs	19.2	99.3	132.3	299.3
L6 strips u/v	38.3/28.6	134.6/76.8	172.9/105.4	307.1/182.0
L6 clusters u/v	12.4/12.2	42.1/36.3	54.4/48.5	96.2/84.5
L6 SPs	17.0	100.8	127.9	283.1
Average strips/layer u/v	164.3/122.8	159.4/81.7	200.1/112.3	1429.8/774.4
Total clusters u/v	49.2/48.7	146.0/131.3	194.4/179.6	337.1/308.9
Total SPs	84.8	534.6	721.3	1693.8
	Signal	Noise		

- ◆ SP : Space Points. “u” is the local $r \phi$ direction. “v” is the local z direction.
- ◆ The combinatorial problem is dominated by background hits

StirlingS2 [85, 12] =

1113945763407827137023789730064528043043368344819719470457284061526615
18248995703170

more than

1.11 10⁸³