

TRK-POG ready for 2017 (?)

Operation Tasks: development(?)

- The new pixel should be completely transparent to any task using Tracks and Vertices (PixelTracks included)
 - At most more stringent quality criteria can be set requiring for instance one more pixel-hit
 - Reminder: also no dyn-ineff anymore!
 - The solution of the VFP issue should also allow to be more strict in the strip as well, if needed

Operation Tasks: who

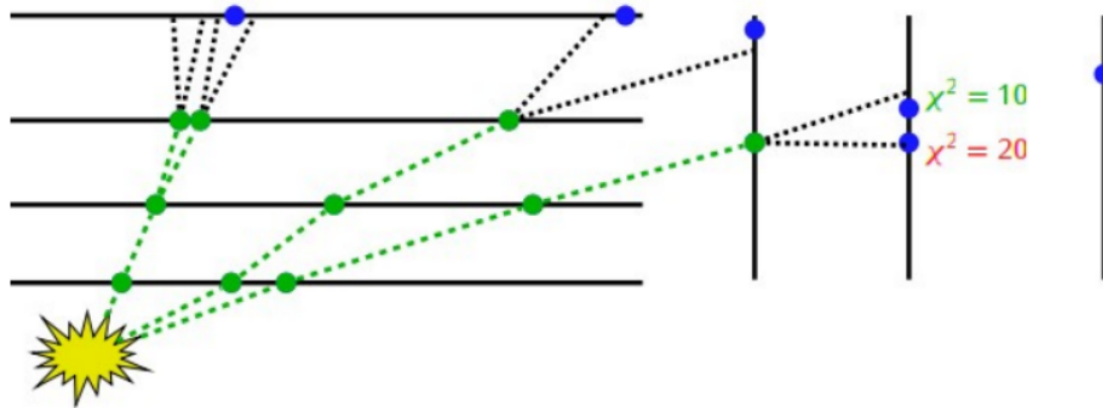
- Online Beamspot:
 - Vacant, asked collaboration to help
- Offline Beamspot:
 - Covered
- Validation (data/MC)
 - Covered
- Efficiency/Resolution
 - Covered
- DQM
 - Covered

What new in tracking?

- Essentially a completely new seeding “step”
 - New algorithms
 - New framework
- Still discovering issues inherited from the far past
 - Clean solutions will not appear before the summer

Triplet Propagation

Propagate 1-2-3 triplet to 4th layer and search for compatible hits using a fast algorithm



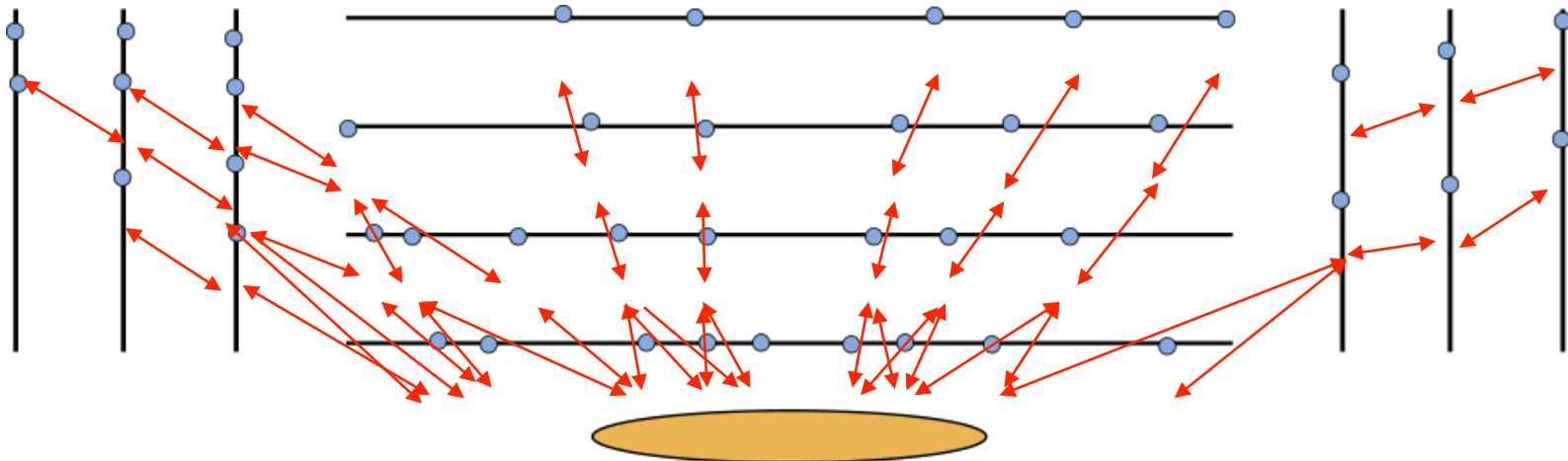
Natural continuation of the current approach from pairs to triplets

Variant: “Pixel seed extension”

- 0 code development (0 innovation, likely 0 “regression w/r/t phase0)
- Seeded by triplets from layers 1-2-3
- Use Kalman filter for the propagation
- In pattern recognition, stop trajectory propagation if no 4th pixel hit right after the seed

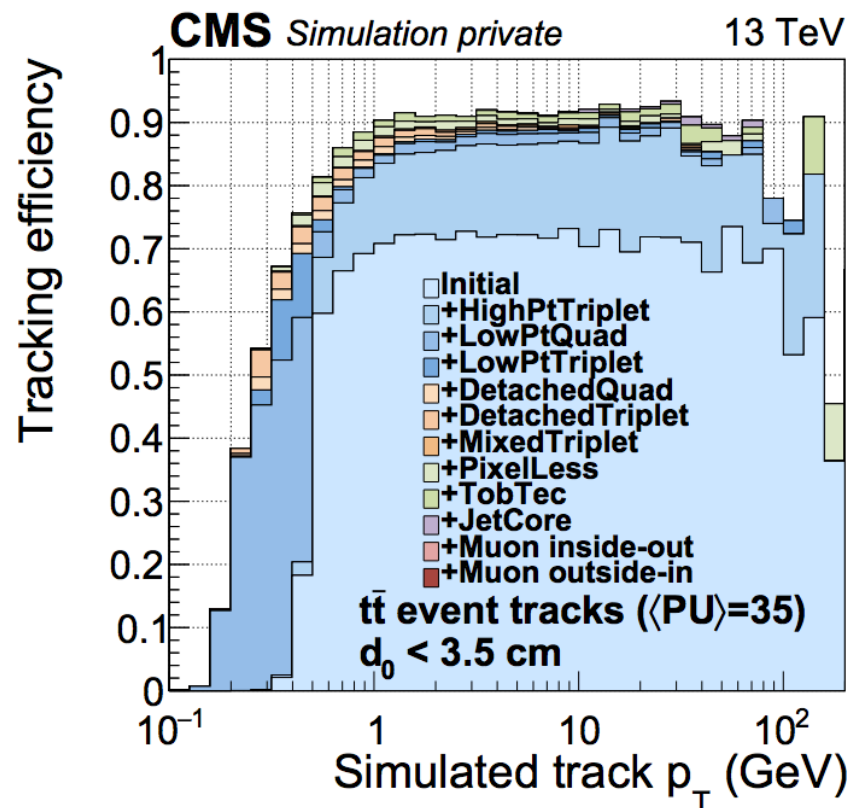
Cellular Automaton (CA)

- The CA is a track seeding algorithm designed for parallel architectures
- It requires a list of layers and their pairings
 - A graph of all the possible connections between layers is created
 - Doublets aka Cells are created for each pair of layers (compatible with a region hypothesis)
 - Fast computation of the compatibility between two connected cells
 - No knowledge of the world outside adjacent neighboring cells required, making it easy to parallelize



M. Kortelainen

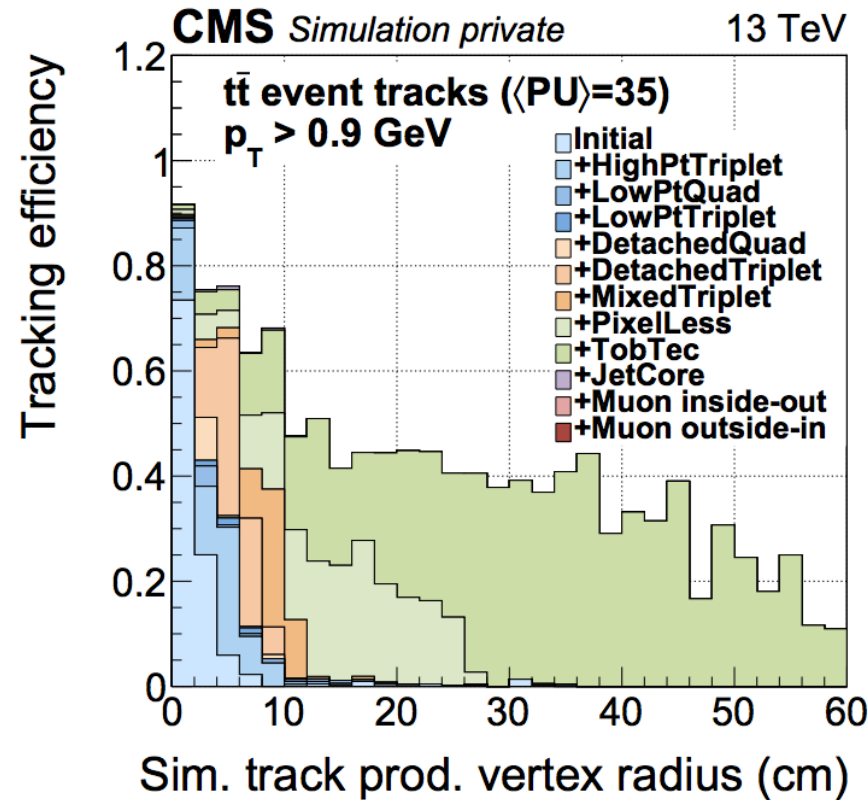
step name	seeding	target track
Initial	pixel quadruplets ³⁾	prompt, high p_T
LowPtQuad	pixel quadruplets ²⁾	prompt, low p_T
HighPtTriplet	pixel triplets	prompt, high p_T recovery
LowPtTriplet	pixel triplets	prompt, low p_T recovery
DetachedQuad	pixel quadruplets ²⁾	displaced--
DetachedTriplet	pixel triplets	displaced-- recovery
MixedTriplet	pixel+strip triplets	displaced-
PixelLess	inner strip triplets	displaced+
TobTec	outer strip triplets	displaced++
JetCore	pixel pairs in jets	high p_T jet
Muon inside-out	muon-tagged tracks	muon
Muon outside-in	standalone muon	muon



- 2) Triplet propagation
- 3) Pixel seed extension

- Currently using 2016 track selection MVA out of the box
 - With cut-based selection for HighPtTriplet and LowPtTriplet
- MVA retraining for 2017 almost finished
 - Expected to be finalized by first week of February

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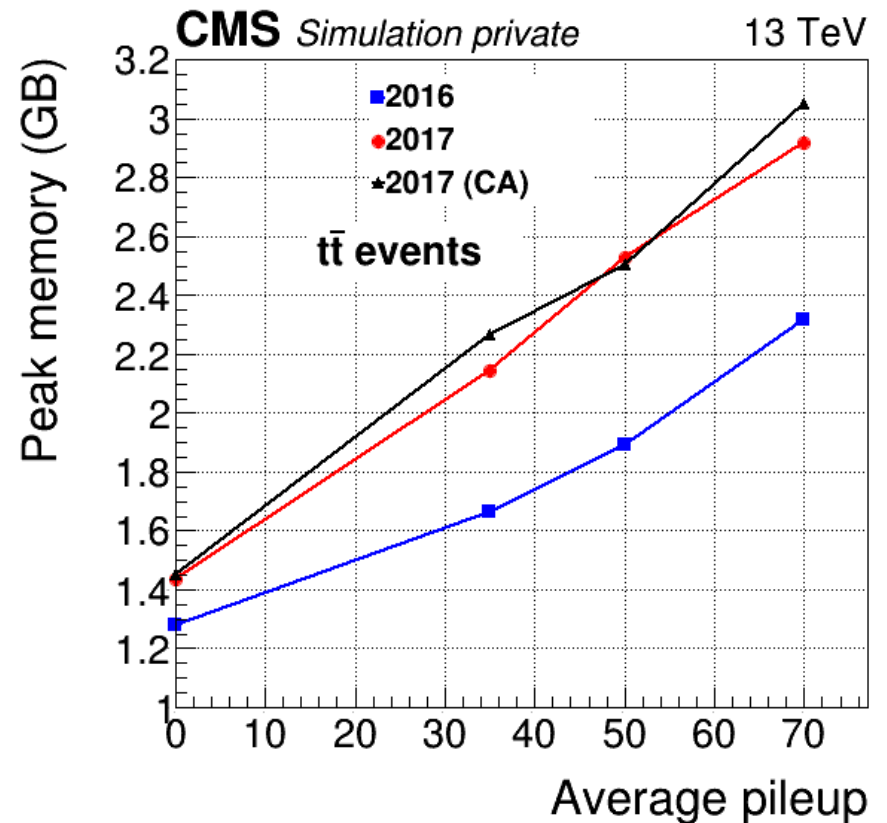
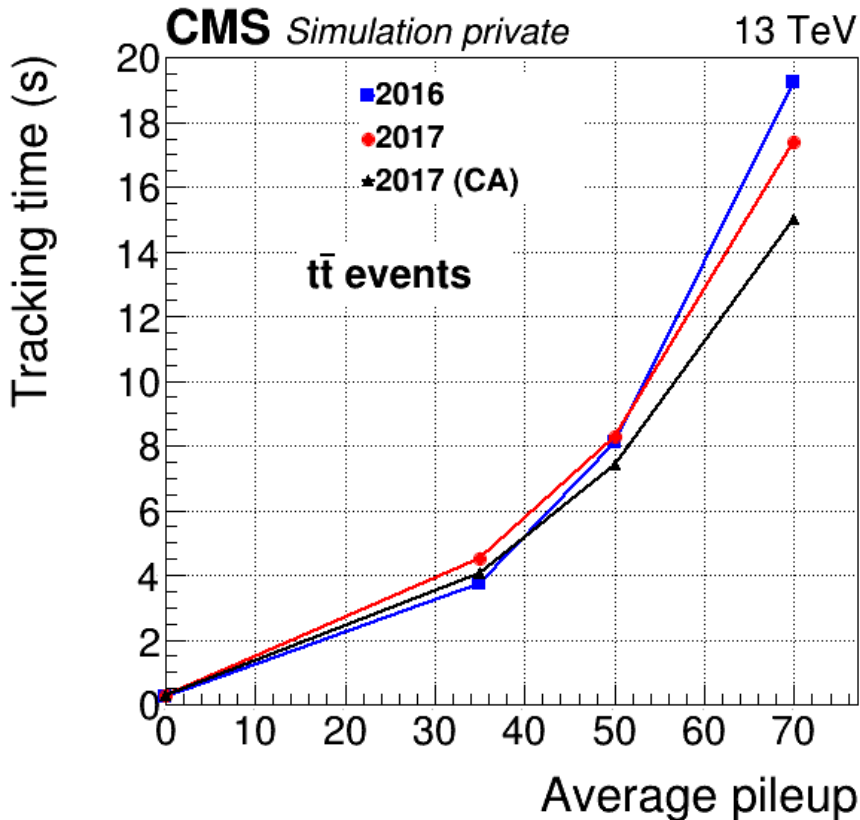
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Mostly for reference

PERFORMANCE

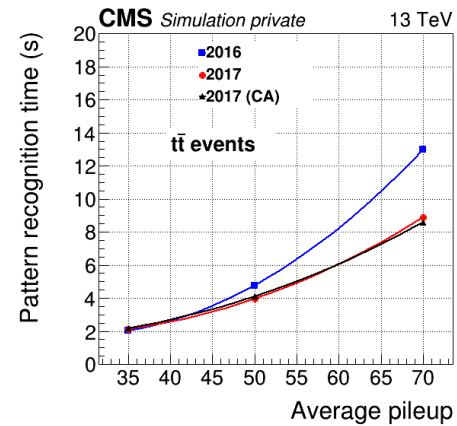
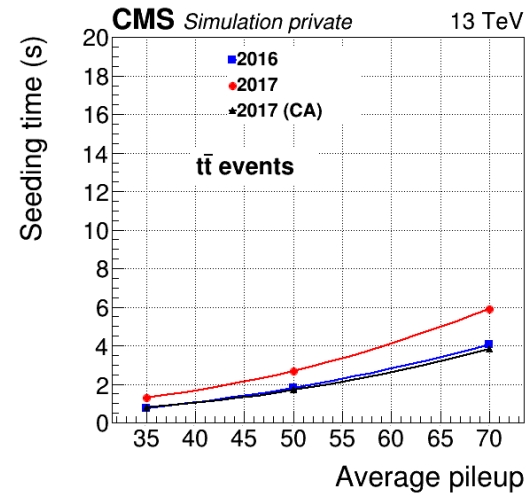
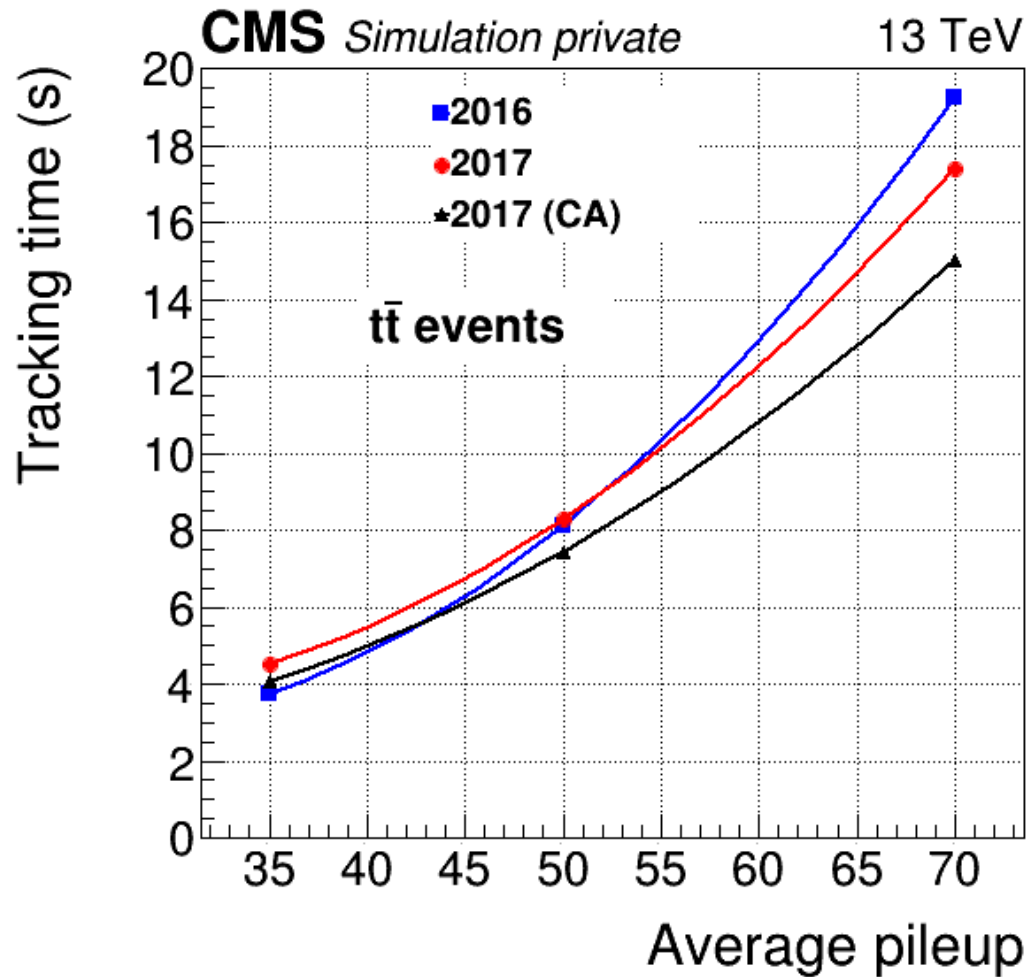
Time & Memory

4 Threads, tracking only, No Validation, DQM, Output



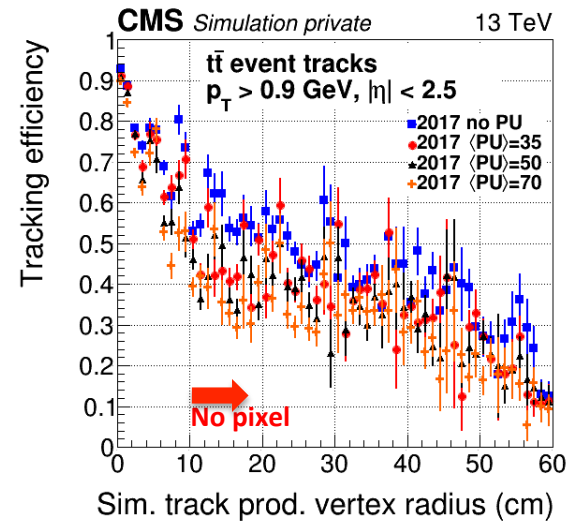
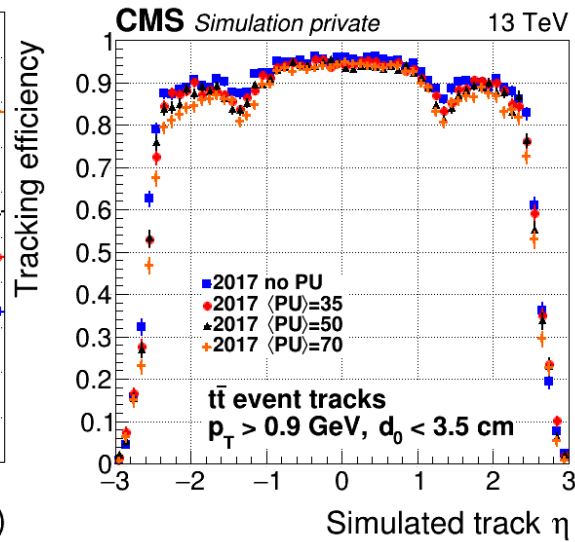
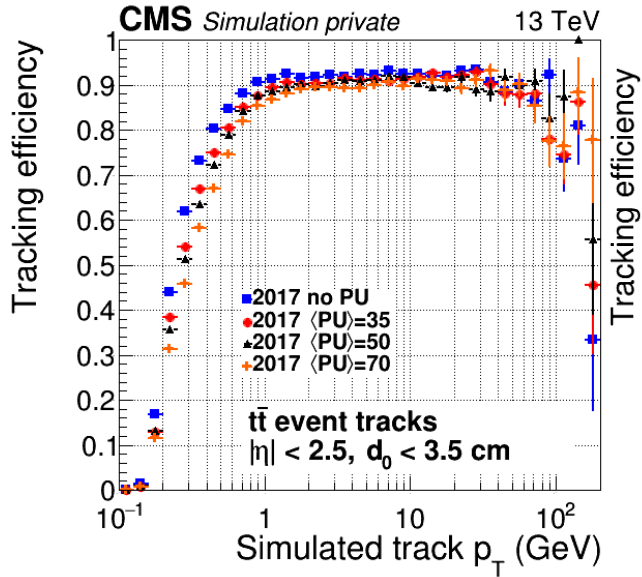
Despite an increase in seeding time, the higher accuracy of quadruplets eventually reduces combinatorics in pattern-recognition producing a significant gain in timing. No free lunch though: memory increase is sizable and action to reduce the memory footprint shall be welcome

Timing

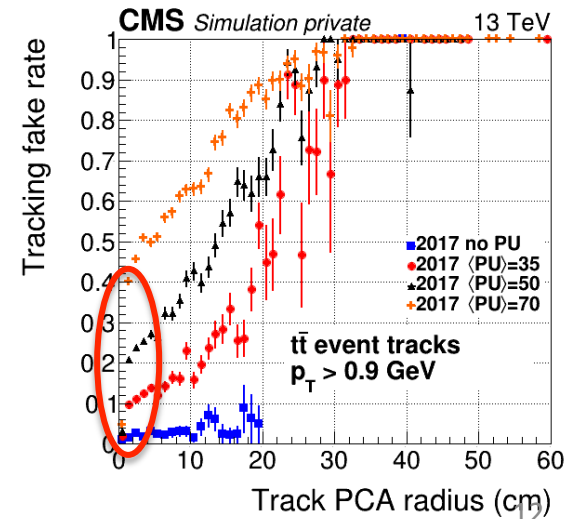
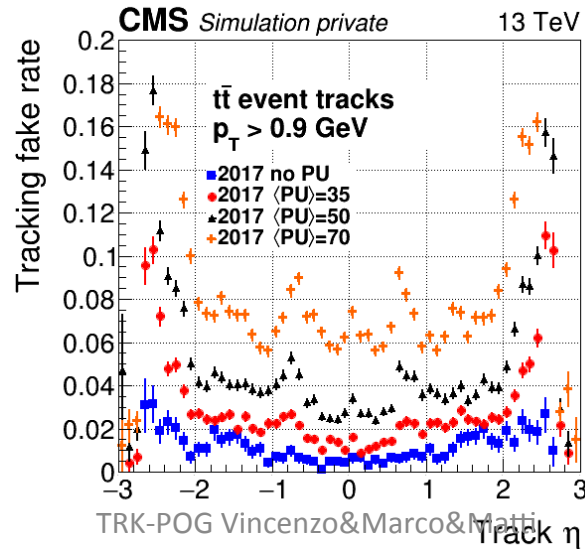
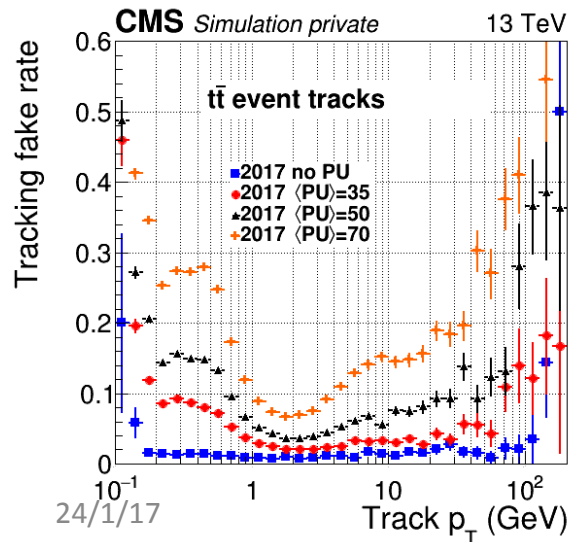


As PU increase CA become advantageous

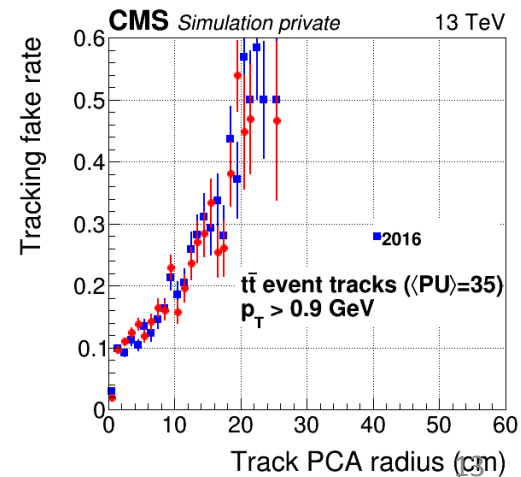
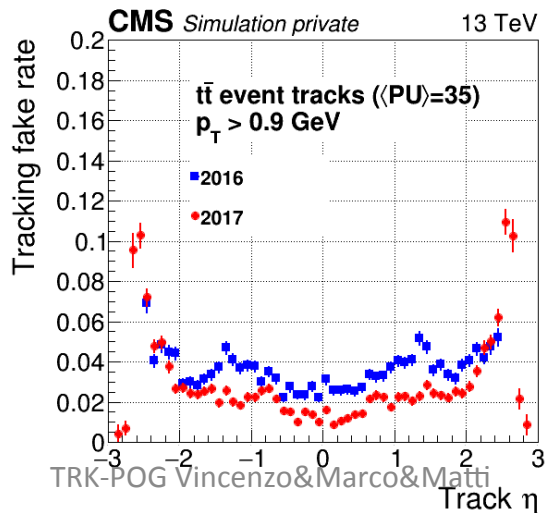
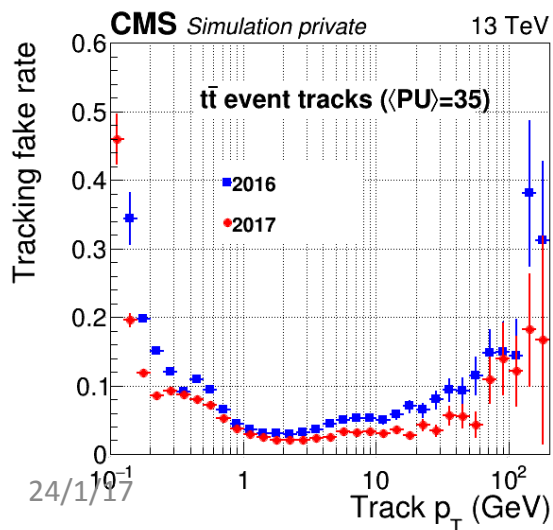
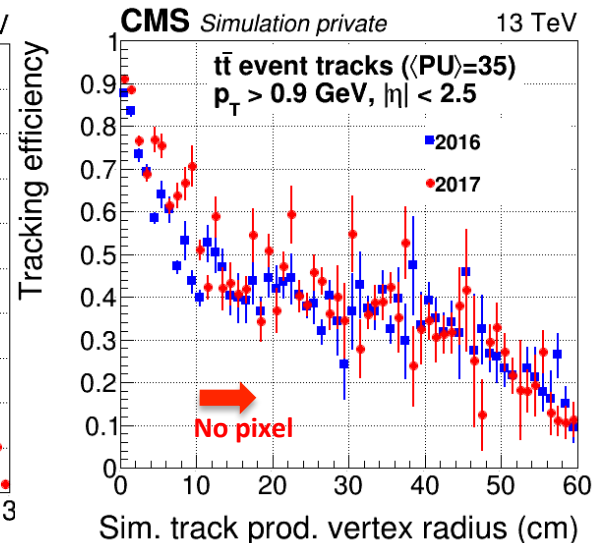
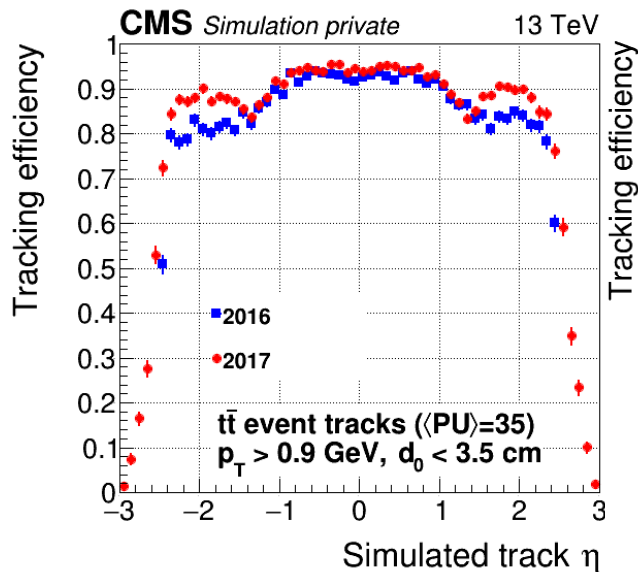
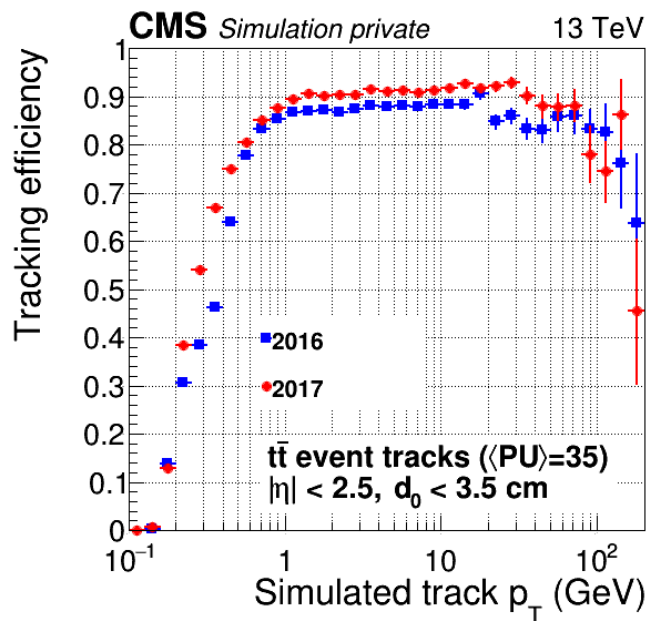
Performance : vs PU



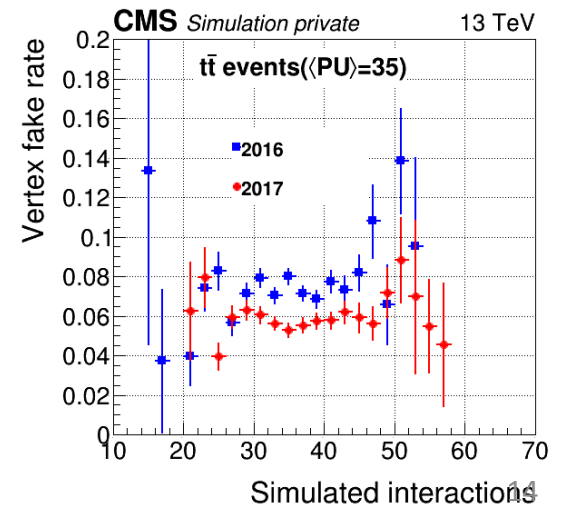
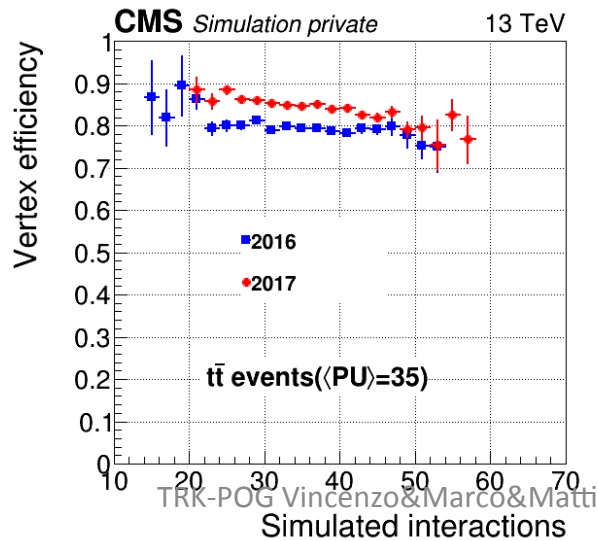
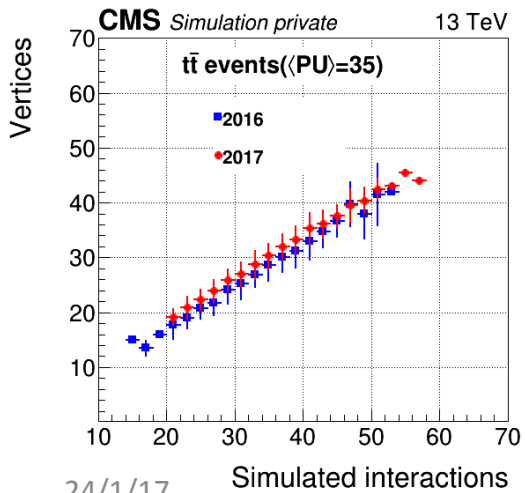
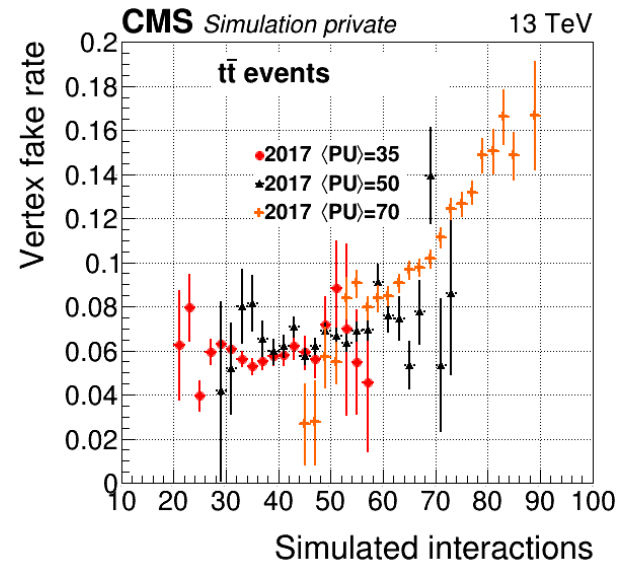
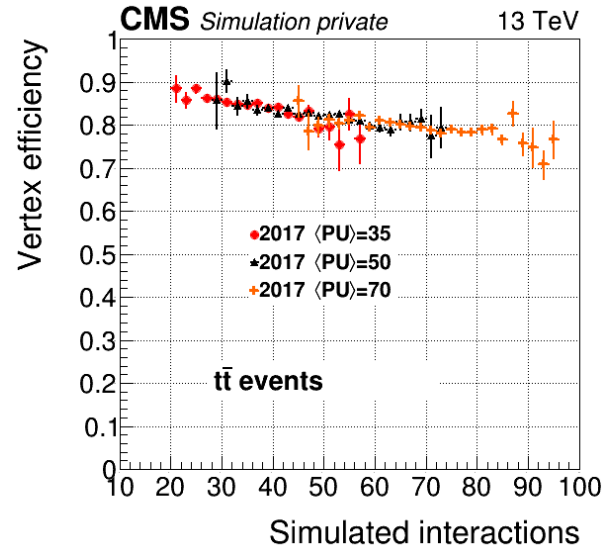
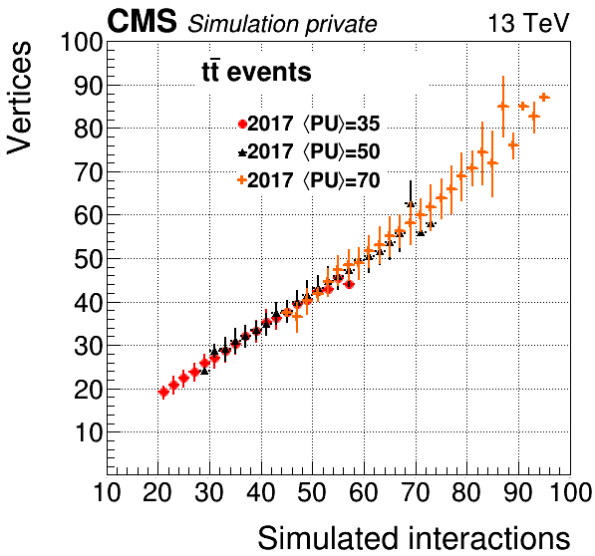
Efficiency ok, fake rate starts to explode for PU>50, in particular for R>1cm



vs 2016

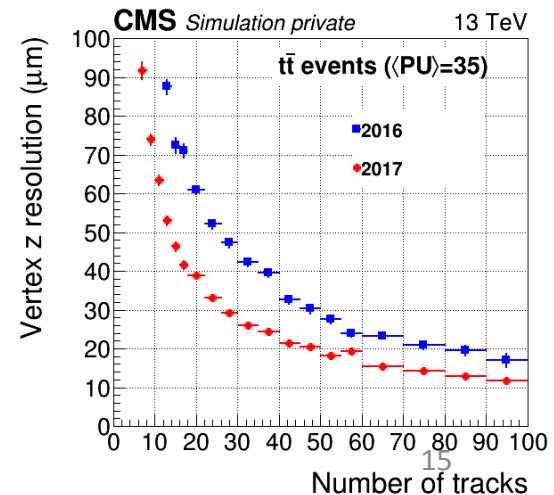
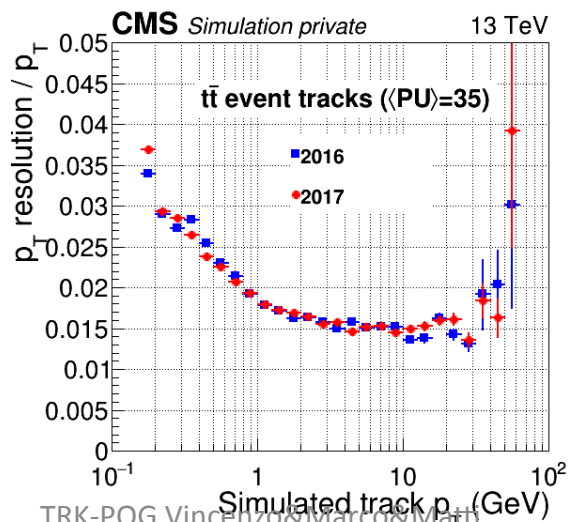
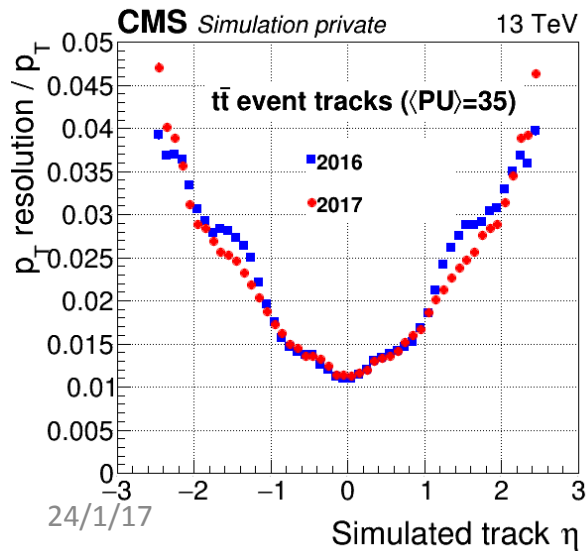
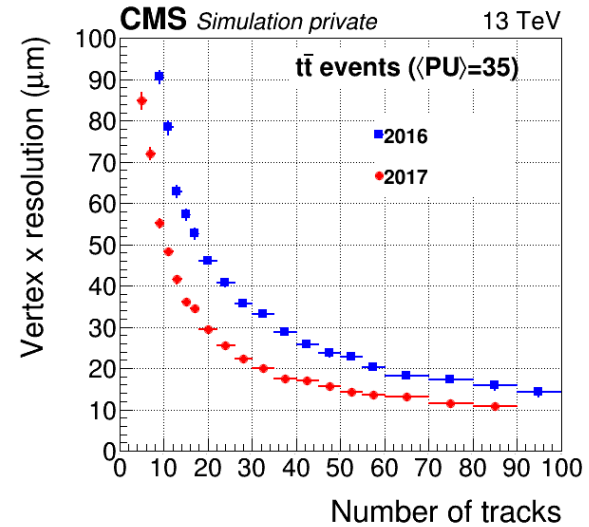
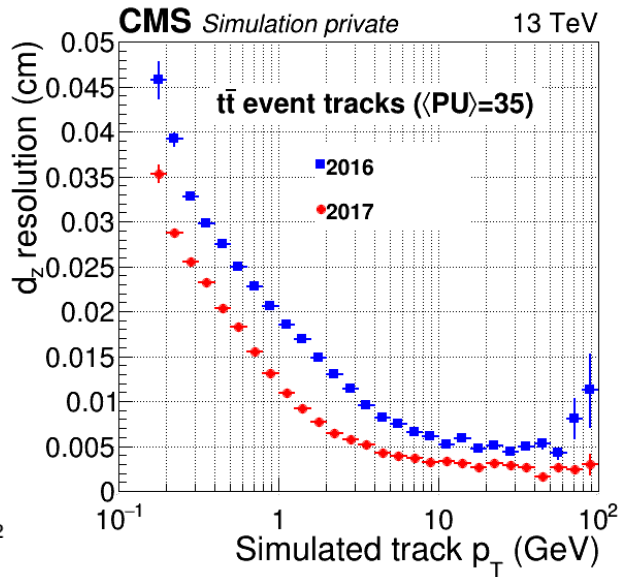
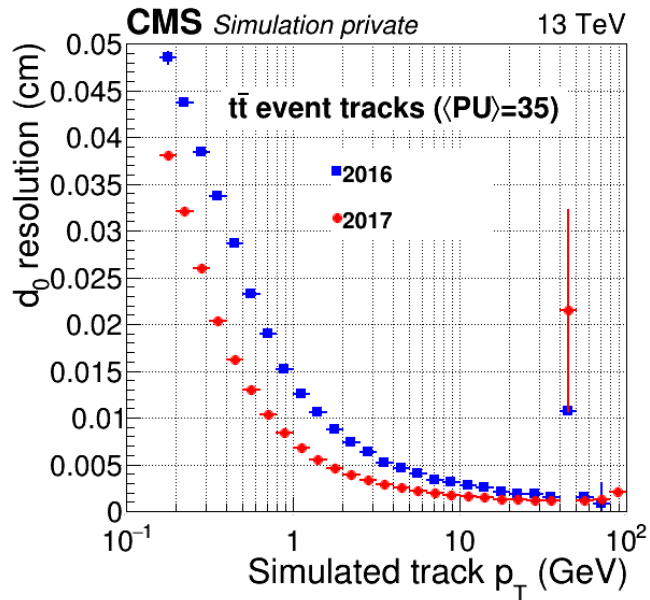


Vertex



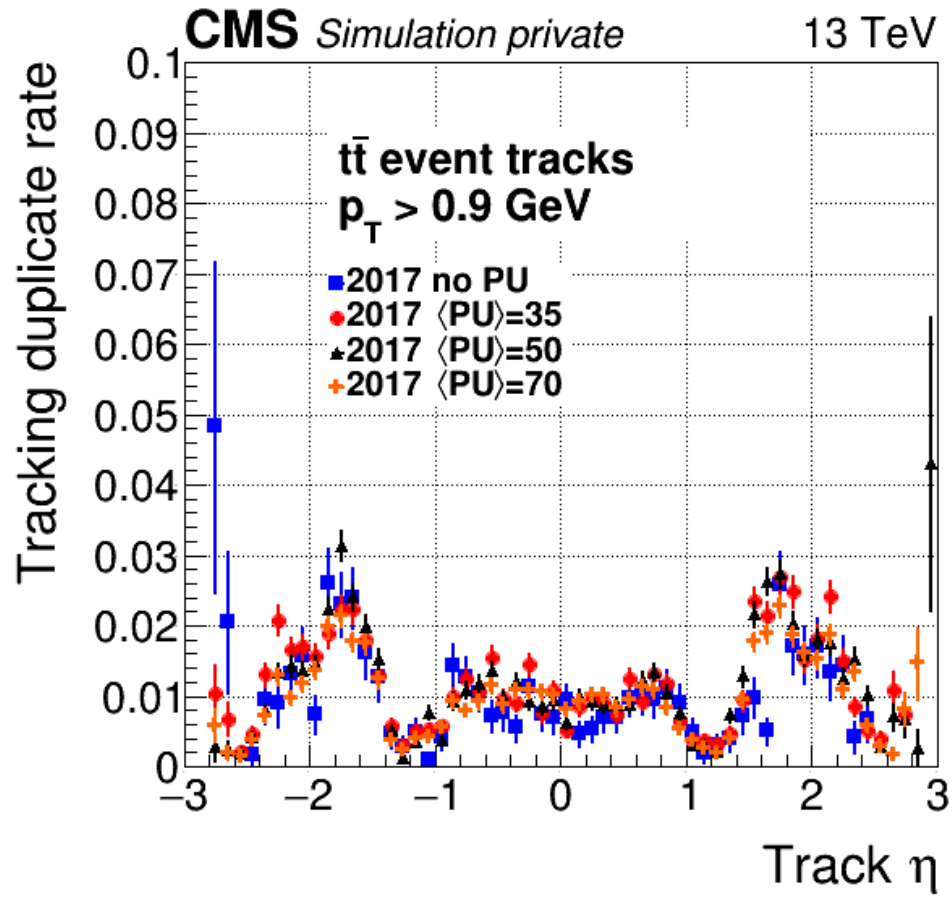
Resolution

Tracks & Vertices



OPEN ISSUES

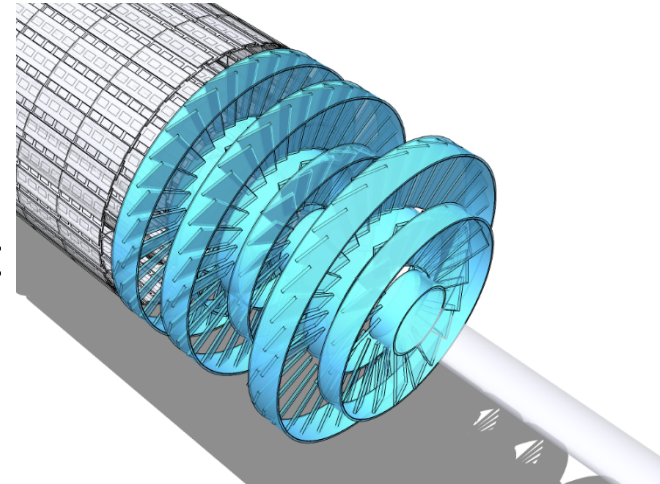
Duplicates



Duplicates

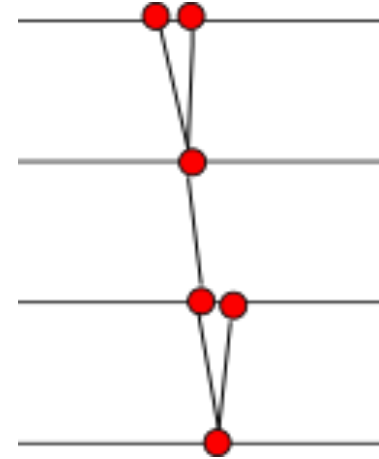
Quadruplets seeding brings in duplicate tracks

- Type I: Mainly due to the module overlaps (mostly in the FPix)
 - “with great hermeticity comes great duplicate rate”
 - Does not depend on which quadruplet seeding algorithm is used
- Type II: due to track shortening
 - A quadruplet is found in the pixel which fails to propagate in the strips
 - The remaining hits in the strips could lead to a track in the pixelLess step (or not)



Type I: Solution and mitigation

- Long-term solution:
 - Instead of using the CA for producing quadruplets, “fishbone” seeds can be produced to account for module overlaps
- Short-term mitigation:
 - Enhance the capability of the duplicate merger (ongoing by Matti)

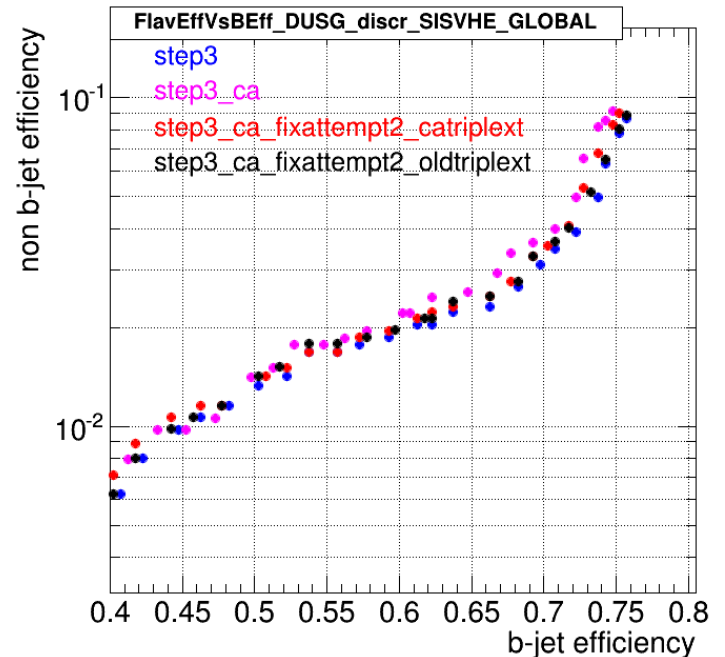
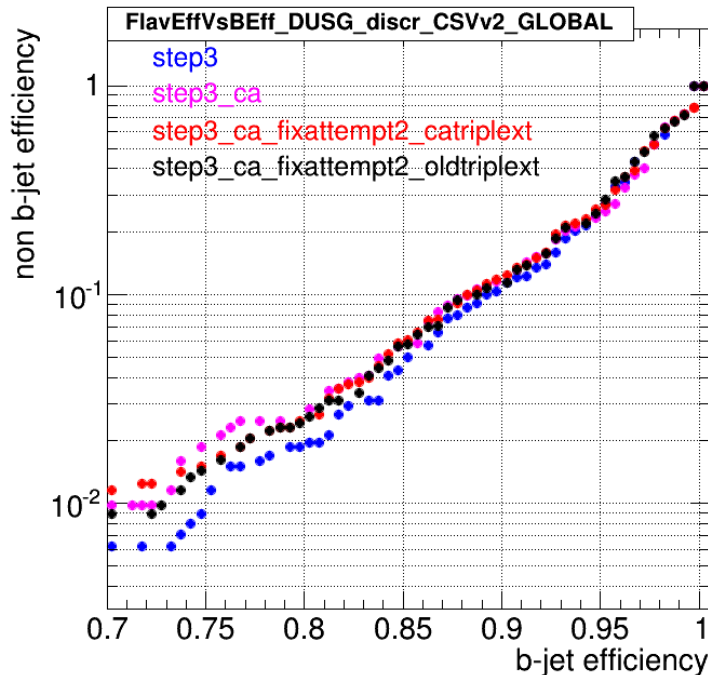


Type II: Solution and mitigation

- A type II duplicate/inefficiency appears in the building process
 - **It is a symptom of a deeper (more disturbing) issue!**
- The same quadruplet can lead to different built tracks depending on the TrackingRegion of the iteration
 - The evaluation of the error in the initialKinematics depends on the region's originRadius and on a "*multiplier*"
 - The Cellular Automaton is more efficient in finding displaced tracks even in "prompt" iterations (thanks to the x-y compatibility)
 - Building quadruplets does not really need to take into account the beam-spot, as four pixel hits can already provide a good-enough fit
- Type II inefficiency is one of the causes of inefficiency in tracks from B-hadrons
- Long-term solution: decouple the computation of the initialKinematics from the region
 - Use a proper fit of the seed
- Mitigation: modify the *multiplier* in quadruplet iterations to take into account the CA x-y plane extra tolerance
- In contact with BTV

B-Tag inefficiency

- Still under investigation
 - little understanding of the driving forces in b-tag estimators
- Exacerbated by CA
- Possible cause: one “wrong” hit in seed?
 - Global track params mostly ok BUT impact-param



Failure scenarios

- Still in the doing
- No plan to use PixelPair in seeding
 - Unless major permanent failure
- Experience shows that relaxing cuts does not help
 - Just increase fake rate
- We need to implement the use of “Inactive detector” information at seeding time and propagate that information to Ckf

“Commissioning scenarios”

- Pixel-less tracking (strip-Only)
 - Not at High PU
 - Forget beamspot
- Strip-less tracking (Pixel-Only)
 - Ok
- Large misalignments
 - More fakes
- Consecutive inactive (largish-section of) layers
 - Inefficiency & fakes (may affect MET as well)
 - In pixel or TIB1/2 : bad data at HighPU

Short term plan (February)

- Finalize MVA
- Mitigate Duplicates
- Finalize Seeding Strategy
 - Move to CA (still in tuning)
- Retune Vertexing
- Reduce Memory footprint

Medium term Plan (summer?)

- Implement a proper fit of Seeds
 - Use it as “initial kinematics” in Ckf
- Detect inactive/missing layers at seeding time and propagate the info to Ckf
- Fishbone seeding
- New MVA for high PU (Deep Learning?)

In reality
Cope with reality

Summary

- TRK-POG is essentially ready for 2017 commissioning
- Still missing responsible of Online Beamspot
- Baseline reconstruction with good performance up to PU 70 in the release
- Innovation in Seeding is uncovering (possibly old) issues
 - Aiming at 0 regression is not necessary progress....
- Improvements in tracking are expected for the summer and eventually later on
- Ready to face reality

BACKUP

Time & Memory

One Thread
Including Validation and DQM

