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Correlation Plenoptic Imaging

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Standard (classical) imaging

In standard imaging, a thin lens induces a (quasi) one-to-one correspondence between points on the sensor and points of a scene 1 1 1

$$\frac{1}{d} + \frac{1}{D} = \frac{1}{f}$$



The signal at a point *x* on the sensor is proportional to the irradiance



$$I_D(\mathbf{x}) \propto \int_{\text{lens}} \frac{L_D(\mathbf{x}, \mathbf{u}) d^2 u}{\sqrt{\frac{1}{2}}}$$

LIGHT FIELD

Radiance propagated from point u on the lens to point x on the sensor

Plenoptic imaging

Plenoptic imaging aims at reconstructing not only the irrradiance at a fixed distance *D*, but the whole **3-dimensional light field**

REFOCUSING planes beyond the depth of field







From Ren Ng et al. (2005)

- The *image of the object* is focused on the microlens array by the main lens
- Multiple *images of the main lens* are focused on the sensor by the microlenses



Inverse proportionality between spatial and angular resolution

Spatial resolution larger than diffraction limit

Properties of chaotic light

$$\langle a_{\boldsymbol{k}_{1}}^{\dagger} a_{\boldsymbol{k}_{2}} \rangle \propto \delta(\boldsymbol{k}_{1} - \boldsymbol{k}_{2}) \longrightarrow \text{Absence of first-order interference} \langle a_{\boldsymbol{k}_{1}}^{\dagger} a_{\boldsymbol{k}_{2}}^{\dagger} a_{\boldsymbol{k}_{3}} a_{\boldsymbol{k}_{4}} \rangle \propto \delta(\boldsymbol{k}_{1} - \boldsymbol{k}_{3}) \delta(\boldsymbol{k}_{2} - \boldsymbol{k}_{4}) + \delta(\boldsymbol{k}_{1} - \boldsymbol{k}_{4}) \delta(\boldsymbol{k}_{3} - \boldsymbol{k}_{4})$$

Nontrivial correlations emerge from photon indistinguishability

Intensity correlations are related with the second-order correlation function

$$G^{(2)}(\boldsymbol{\rho}_{a},\boldsymbol{\rho}_{b}) = \langle E_{a}^{(-)}(\boldsymbol{\rho}_{a}) E_{b}^{(-)}(\boldsymbol{\rho}_{b}) E_{b}^{(+)}(\boldsymbol{\rho}_{b}) E_{a}^{(+)}(\boldsymbol{\rho}_{a}) \rangle$$

$$= I_{a}(\boldsymbol{\rho}_{a}) I_{b}(\boldsymbol{\rho}_{b}) + \Gamma(\boldsymbol{\rho}_{a},\boldsymbol{\rho}_{b})$$
Directly retrieved by measuring
$$\left| \int d \boldsymbol{k}_{\perp} g_{a}(\boldsymbol{\rho}_{a},\boldsymbol{k})^{*} g_{b}(\boldsymbol{\rho}_{b},\boldsymbol{k}) \right|^{2}$$



The structure of correlation imaging setup weakens the tradeoff between spatial and angular res.

Light-field imaging and refocusing

In the geometrical optics limit, a stationary-phase approximation to the double integral inside $\Gamma(\rho_a, \rho_b)$ yields

$$\Gamma(\boldsymbol{\rho}_{a},\boldsymbol{\rho}_{b}) \sim F\left(-\frac{\boldsymbol{\rho}_{b}}{M}\right)^{2} \left| A\left[\frac{z_{b}}{z_{a}}\boldsymbol{\rho}_{a} - \frac{\boldsymbol{\rho}_{b}}{M}\left(1 - \frac{z_{b}}{z_{a}}\right)\right] \right|^{2}$$

Integration over ρ_b erases information on the object

However, object and source can be decoupled by properly scaling the first argument of the retrieved correlation function:

$$\Gamma\left(\frac{z_a}{z_b}\boldsymbol{\rho}_a - \frac{\boldsymbol{\rho}_b}{M}\left(1 - \frac{z_a}{z_b}\right), \boldsymbol{\rho}_b\right) \sim F\left(-\frac{\boldsymbol{\rho}_b}{M}\right)^2 \left|\underline{A(\boldsymbol{\rho}_a)}\right|^2$$

$$= \left[B_{a^2 - \frac{1}{2}, \frac{1}$$