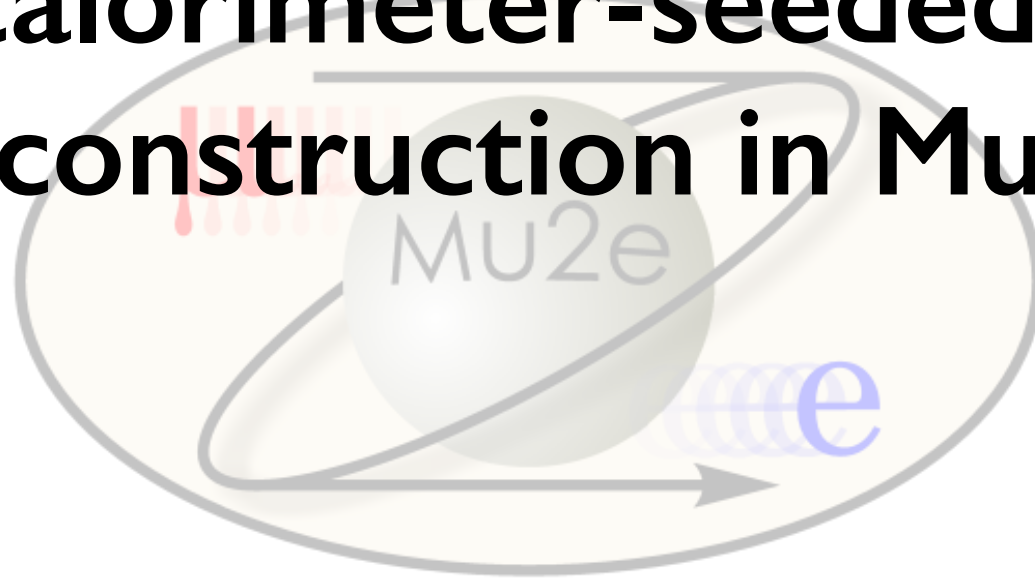


# The calorimeter-seeded track reconstruction in Mu2e



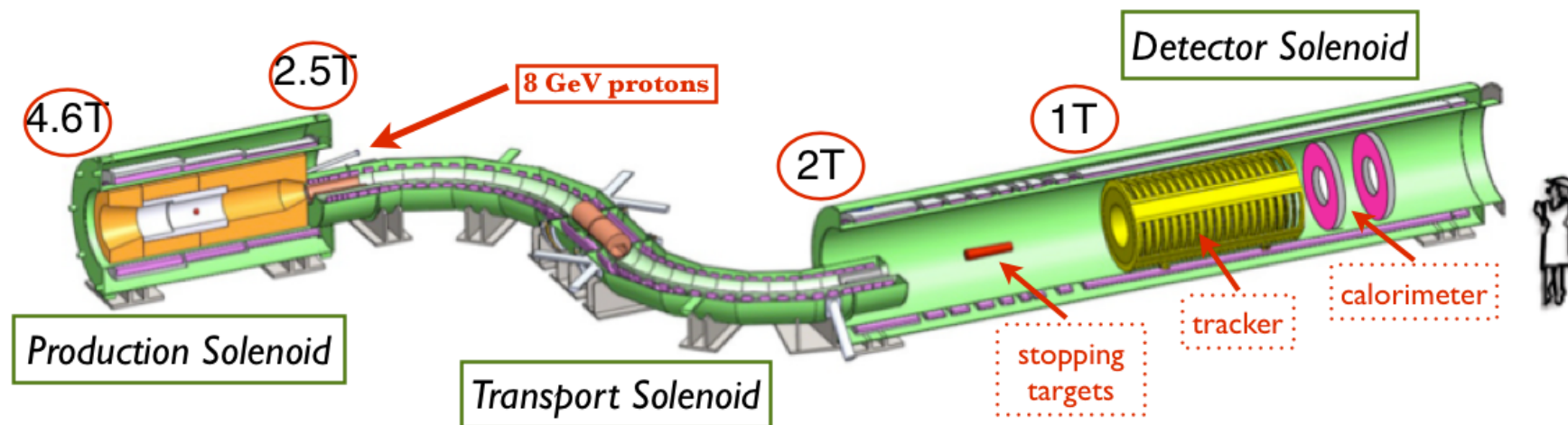
G. Pezzullo  
INFN of Pisa, Italy

- **Production Solenoid:**

- ➔ Proton beam strikes target, producing mostly pions
- ➔ Graded magnetic field contains backwards pions/muons and reflects slow forward pions/muons

- **Detector Solenoid:**

- ➔ Capture muons on Al target
- ➔ Measure  $p$  in the tracker and  $E, t, x$  in the calorimeter
- ➔ Graded field increases CE detector acceptance:  $\sim 70\%$

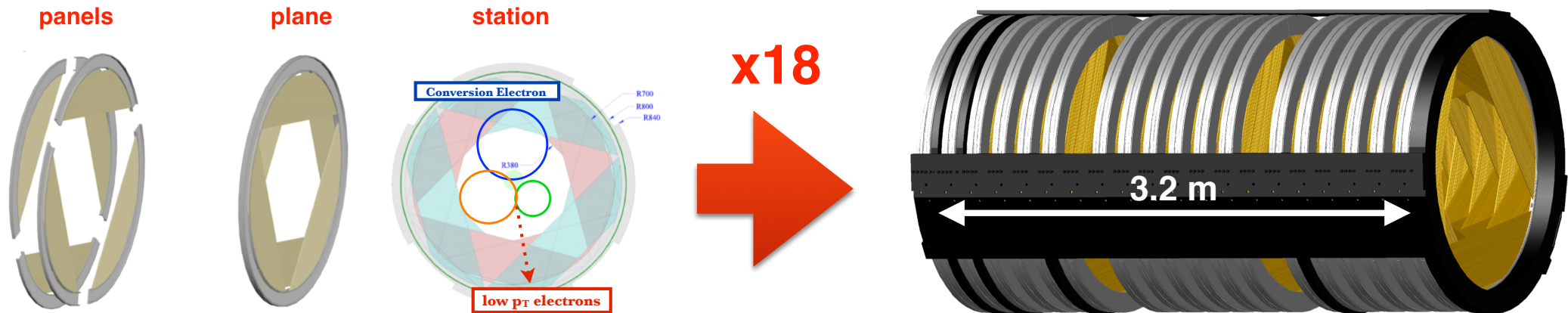


- **Transport Solenoid:**

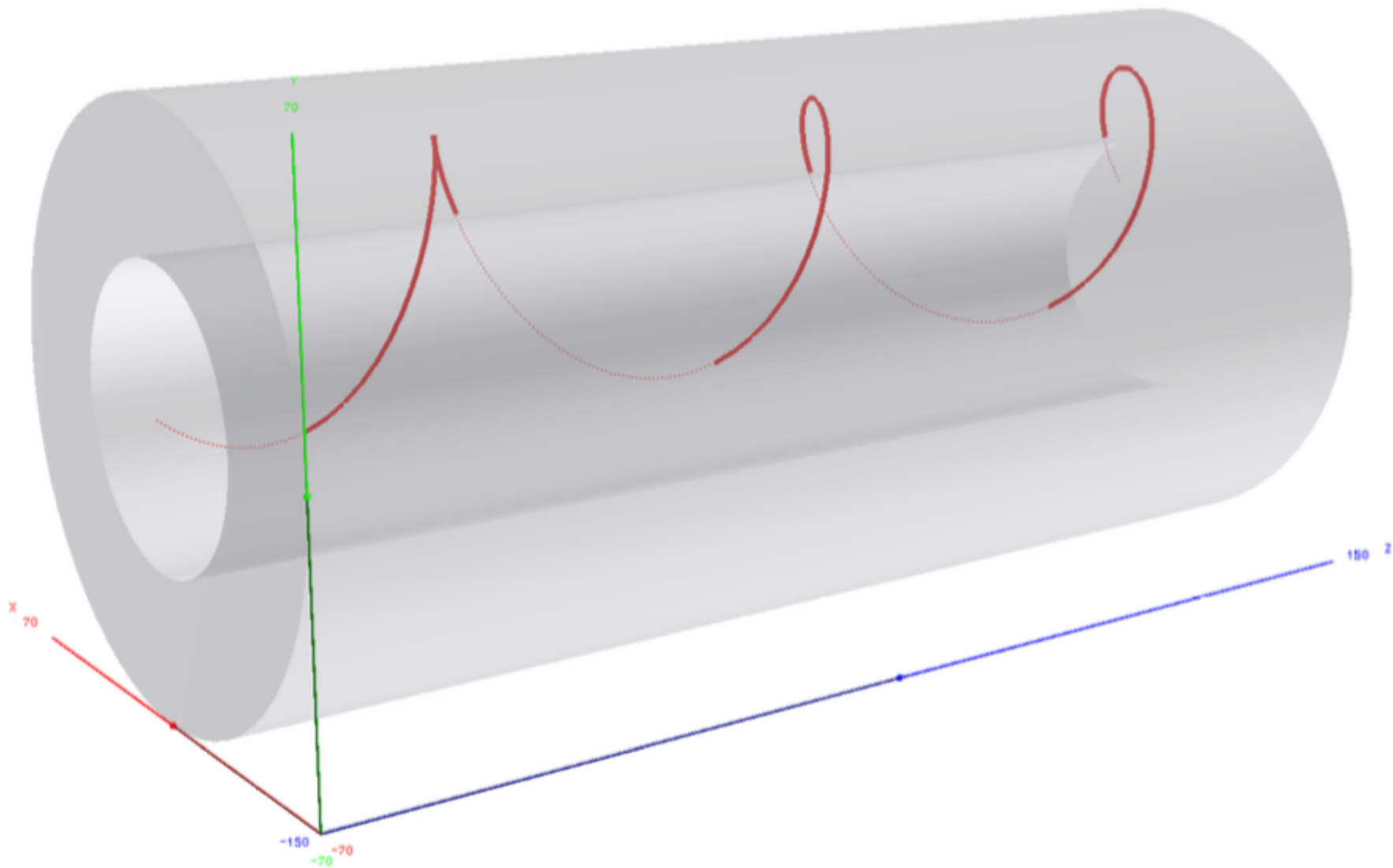
- ➔ Select low momentum, negative muons

- 18 stations with straws transverse to the beam
- Straw technology employed:
  - ✓ 5 mm diameter, 15  $\mu\text{m}$  Mylar walls
  - ✓ 25  $\mu\text{m}$  Au-plated W sense wire
  - ✓ 80/20 Ar/CO<sub>2</sub> with HV  $\sim$  1500 V
- Inner 38 cm un-instrumented:
  - ✓ blind to beam flash
  - ✓ blind to  $>99\%$  of the DIO spectrum

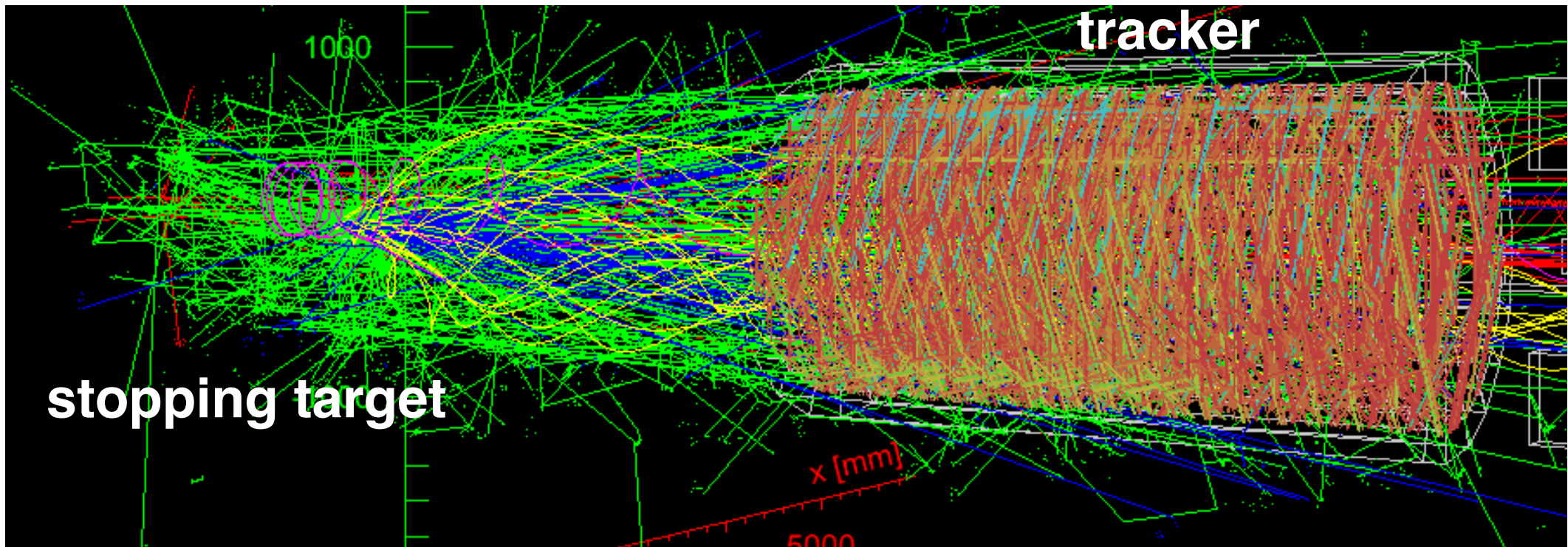
straw tube



- **Our signal:**  $e^-$  with  $p \sim 105 \text{ MeV}/c$  coming from the Al target



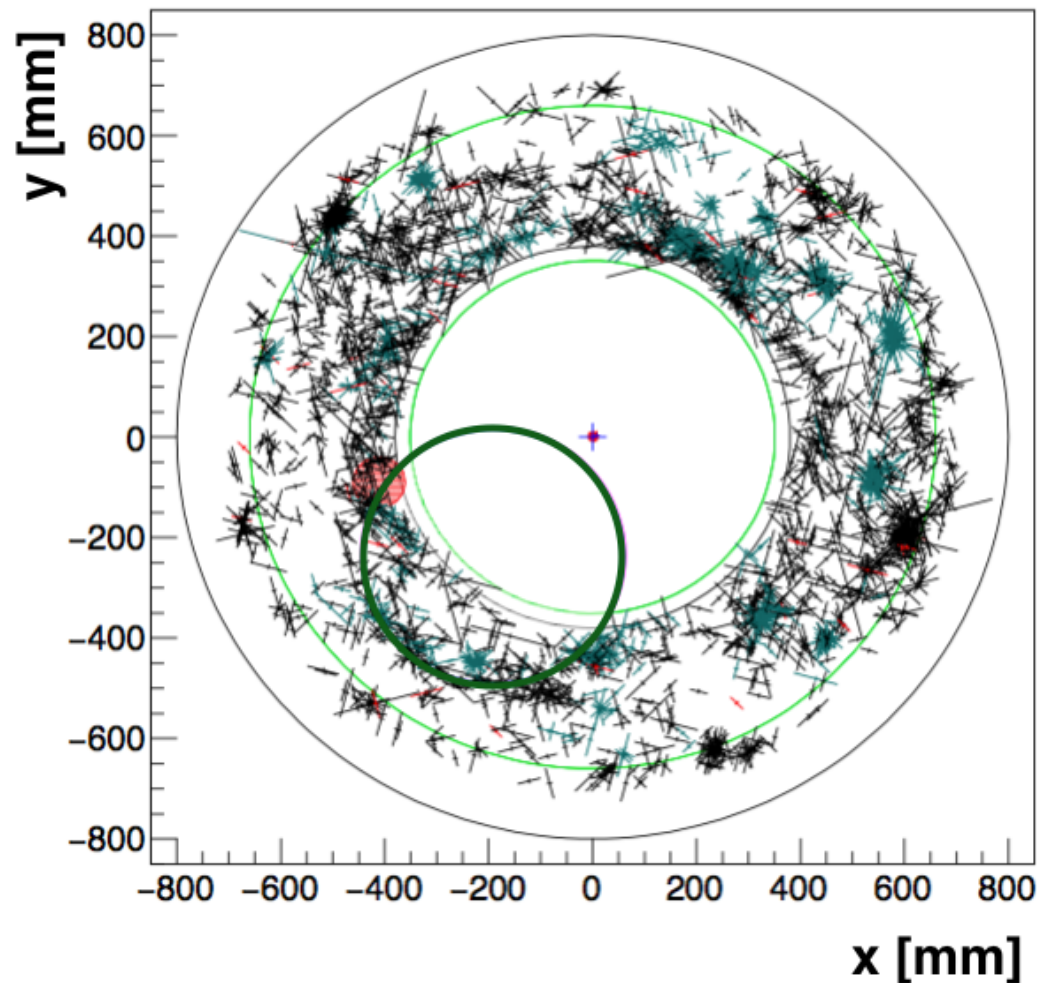
- $\mu$ - beam produces secondaries via brems, nuclear capture, etc



**1 bunch event = 1.7  $\mu$ s**

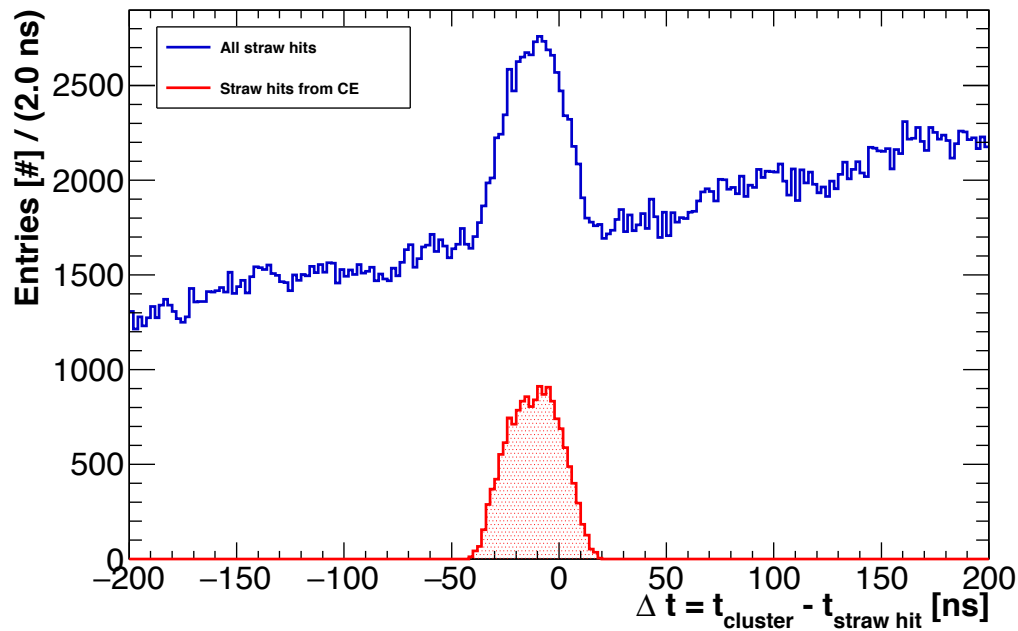


- Hits from background sources complicate the track search
- Calorimeter information helps the track search

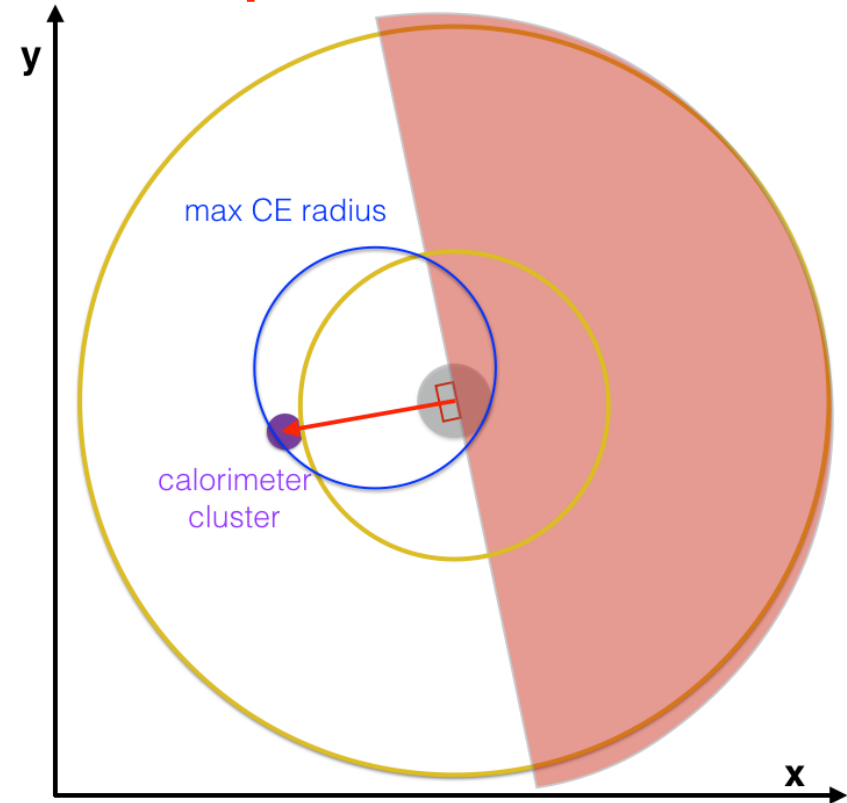


- Cluster time and position are used for filtering the straw hits:
  - ✓ time window of  $\sim 80$  ns
  - ✓ spatial correlation

**time window**

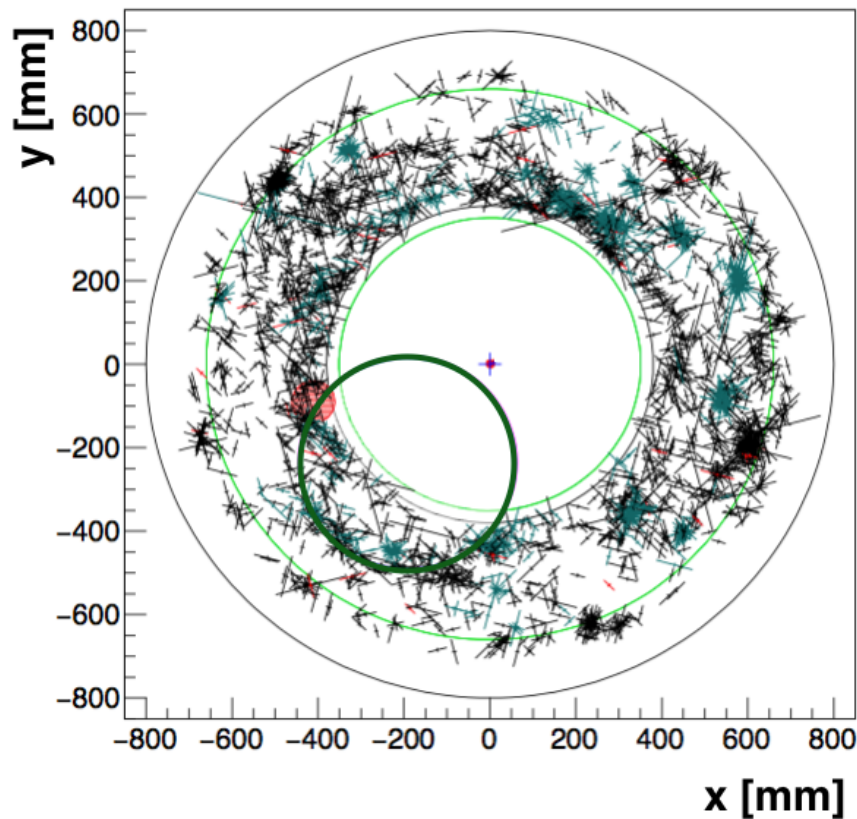


**spatial correlation**

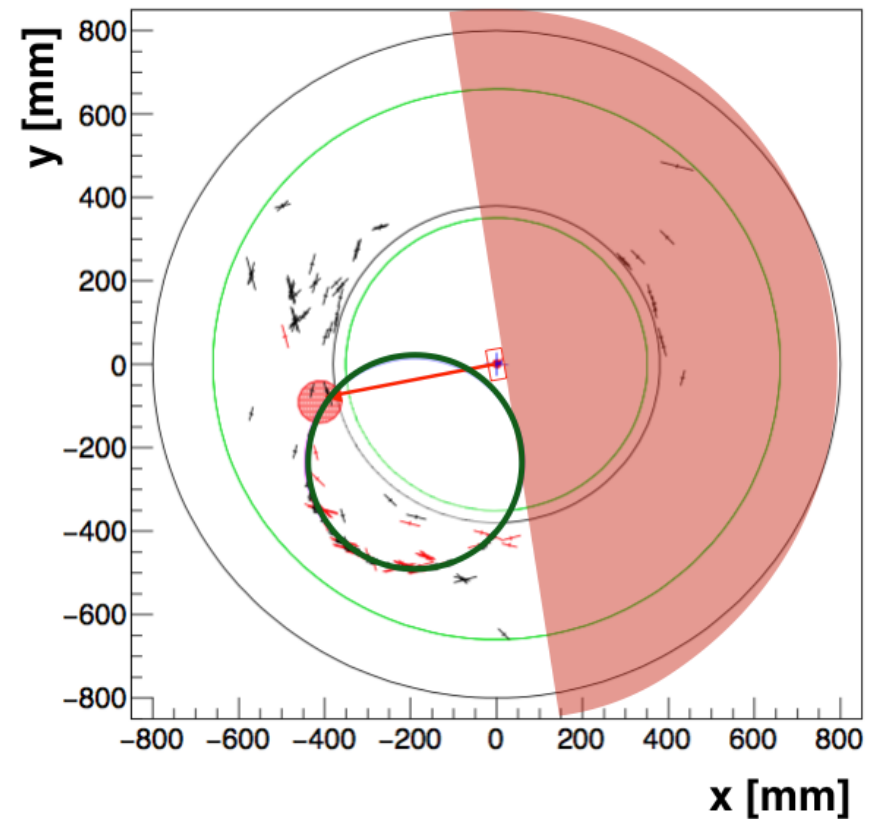


- Cluster time and position are used for filtering the straw hits:
  - ✓ time window of  $\sim 100$  ns
  - ✓ spatial correlation

no selection



calorimeter selection

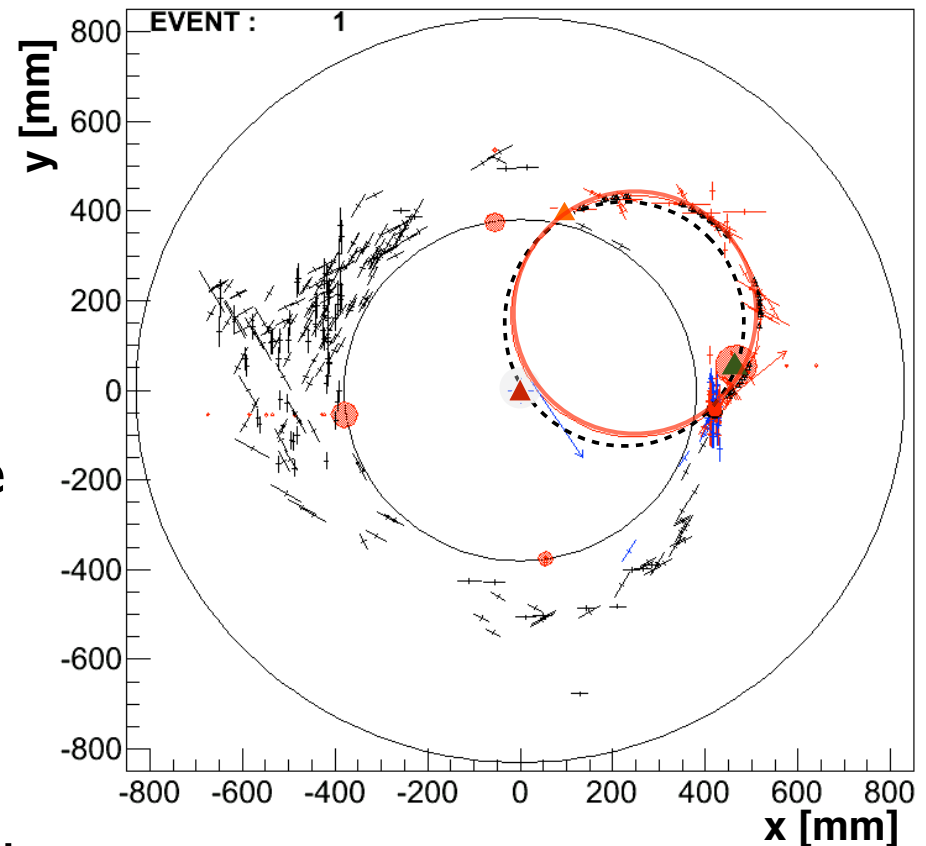


- black crosses = straw hits, red circle = calorimeter cluster,  
green line = CE track



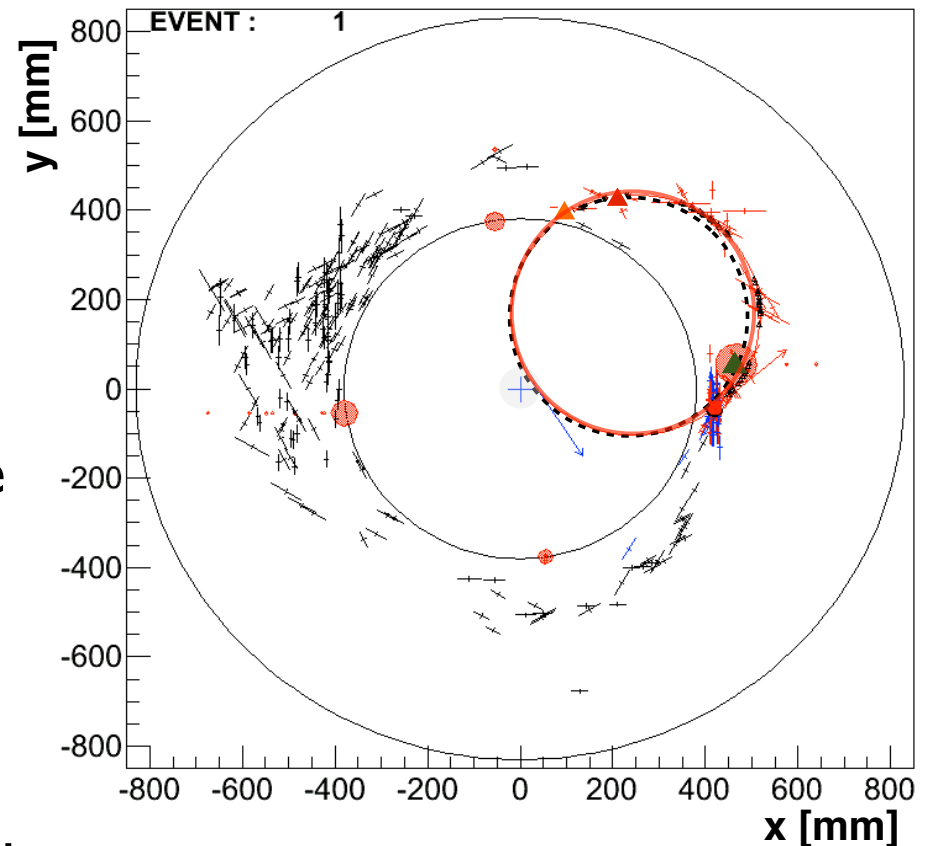
To identify the right pattern of hit we apply the following procedure:

1. Select a triplet with the **calo cluster position**, one **tracker hit** and the **solenoid center**
2. calculate helix parameters (dashed line is the reco circle, red one is the true trajectory)
3. loop over all the hits and includes those which are close to the helix
4. As soon as the second straw hit is found, the solenoid center is dropped in step 1 and the procedure re-starts.
5. adjust the helix parameters as the search progresses

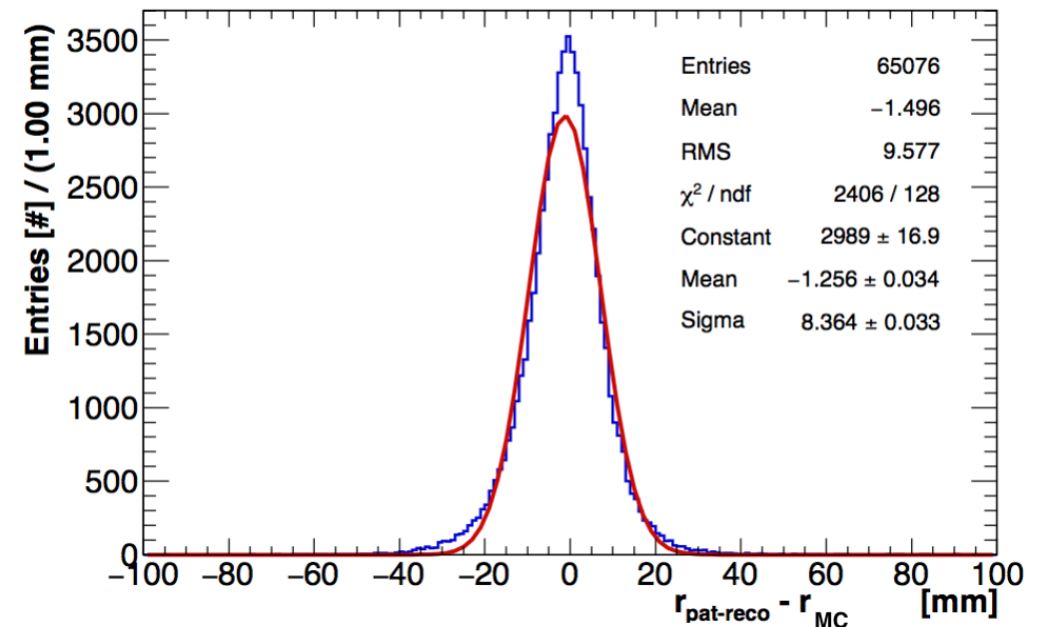
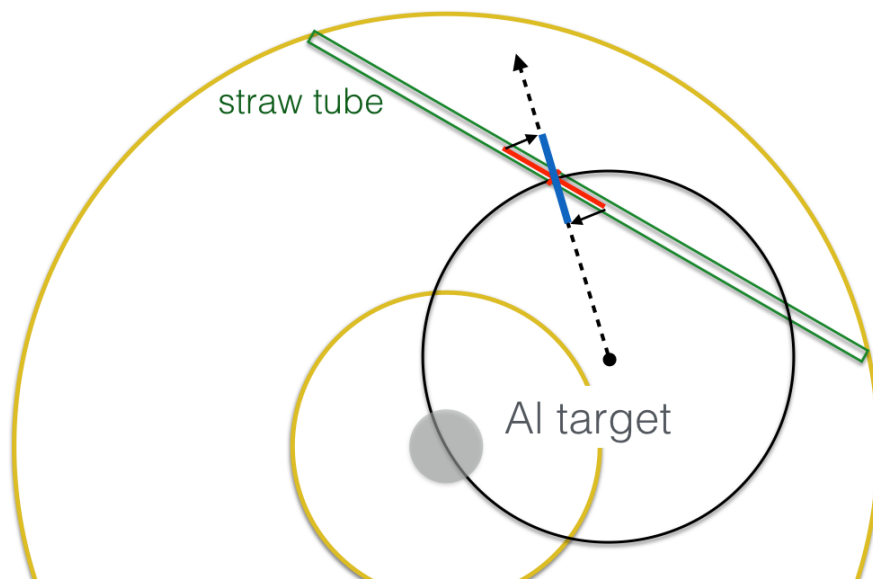


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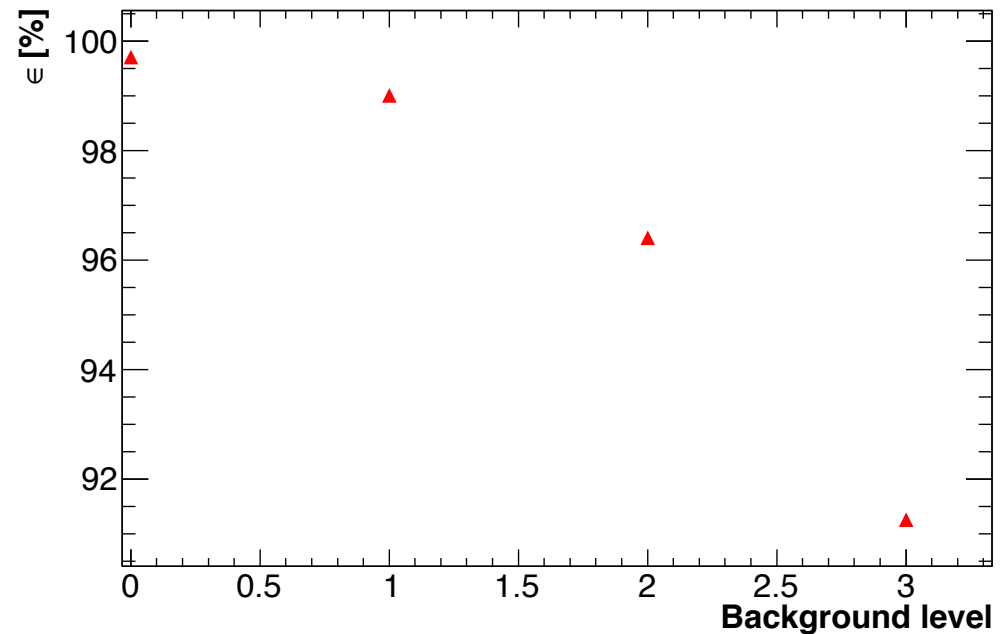
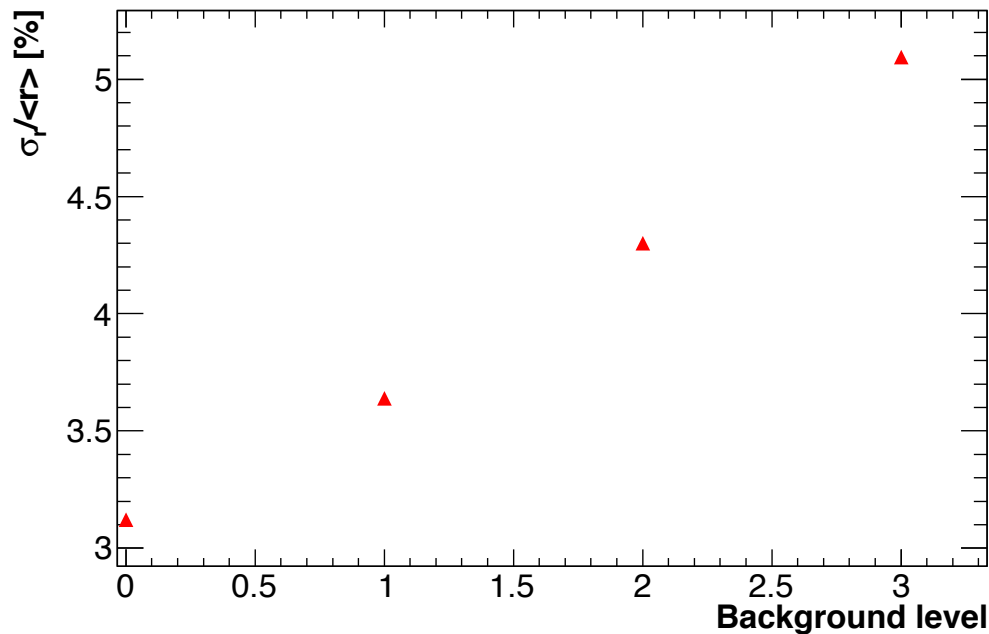
1. Select a triplet with the **calo cluster position**, one **tracker hit** and the **solenoid center**
  2. calculate helix parameters (dashed line is the reco circle, red one is the true trajectory)
  3. loop over all the hits and includes those which are close to the helix
  4. As soon as the second straw hit is found, the solenoid center is dropped in step 1 and the procedure re-starts.
  5. adjust the helix parameters as the search progresses
- At the end the helix with the largest number of hits is selected

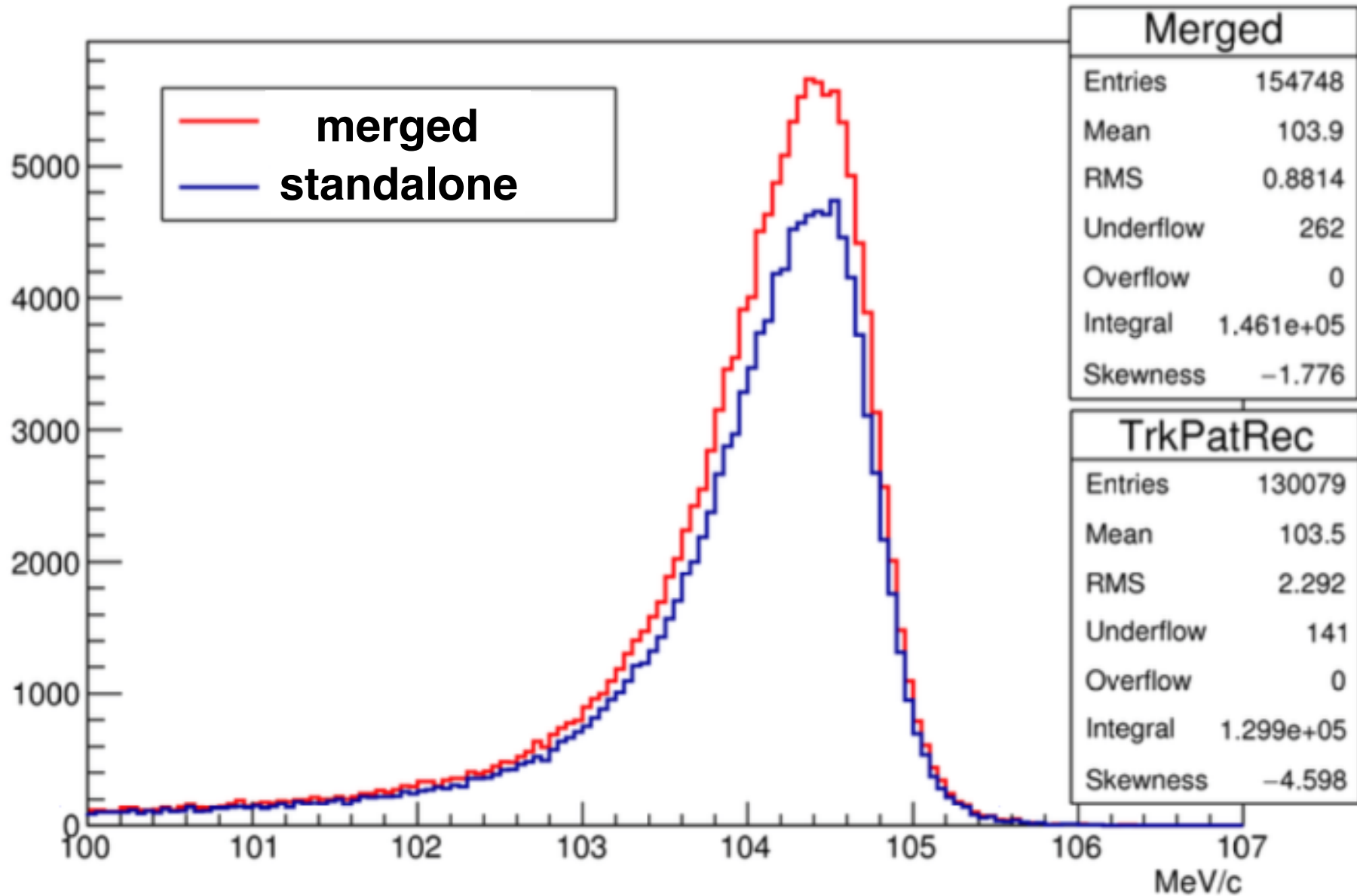


- Reduced Least Square Method for performing the circle fit
- Errors are projected along the radial direction of the trajectory

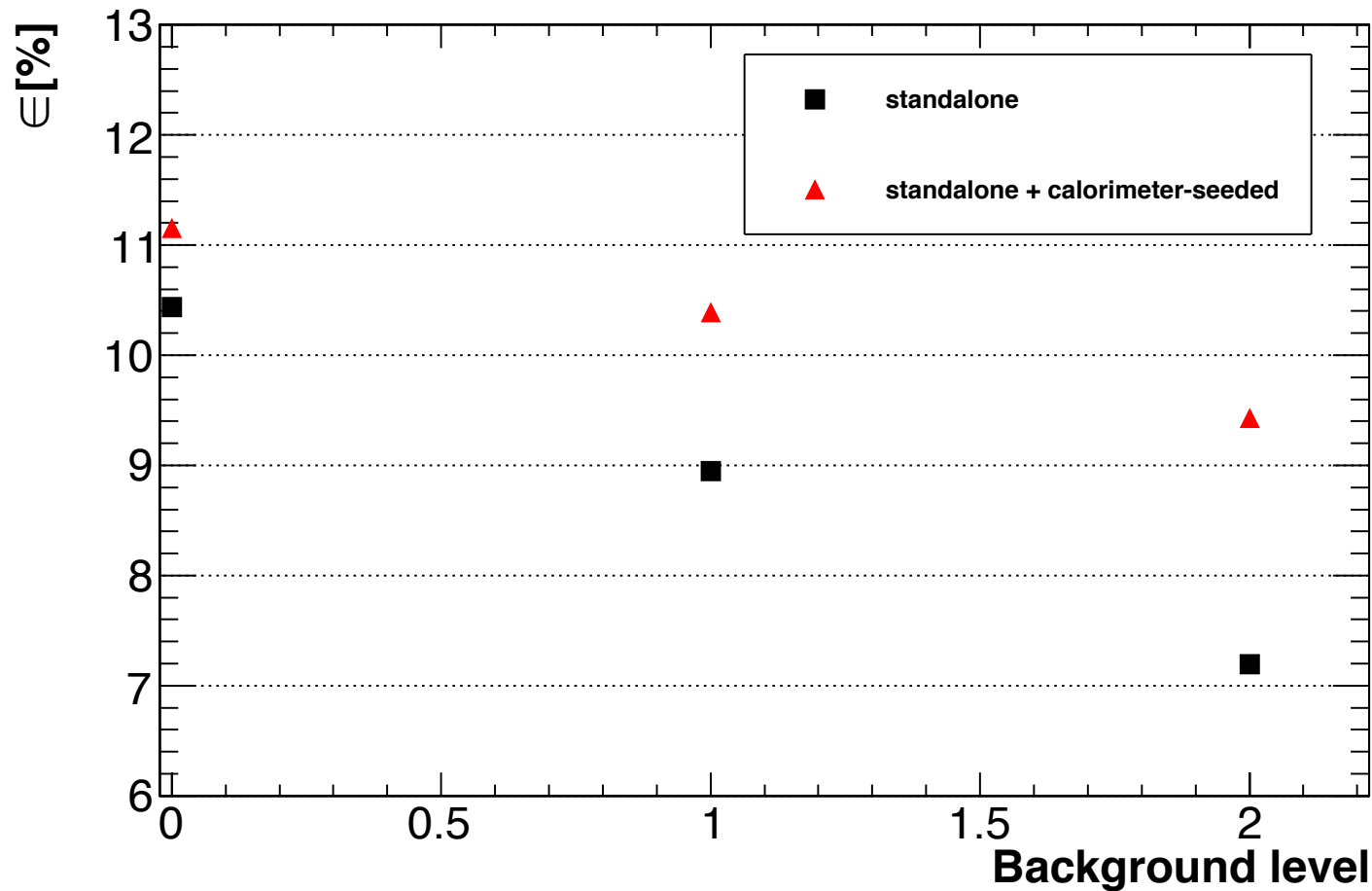


- Resulting radius resolution  $\sigma_r/\langle r \rangle \sim 3.6\%$  for CE
- Efficiency normalized to events with  $E > 50$  MeV &  $N_{\text{straw-hit}} \geq 15$
- Resulting efficiency  $\sim 99\%$





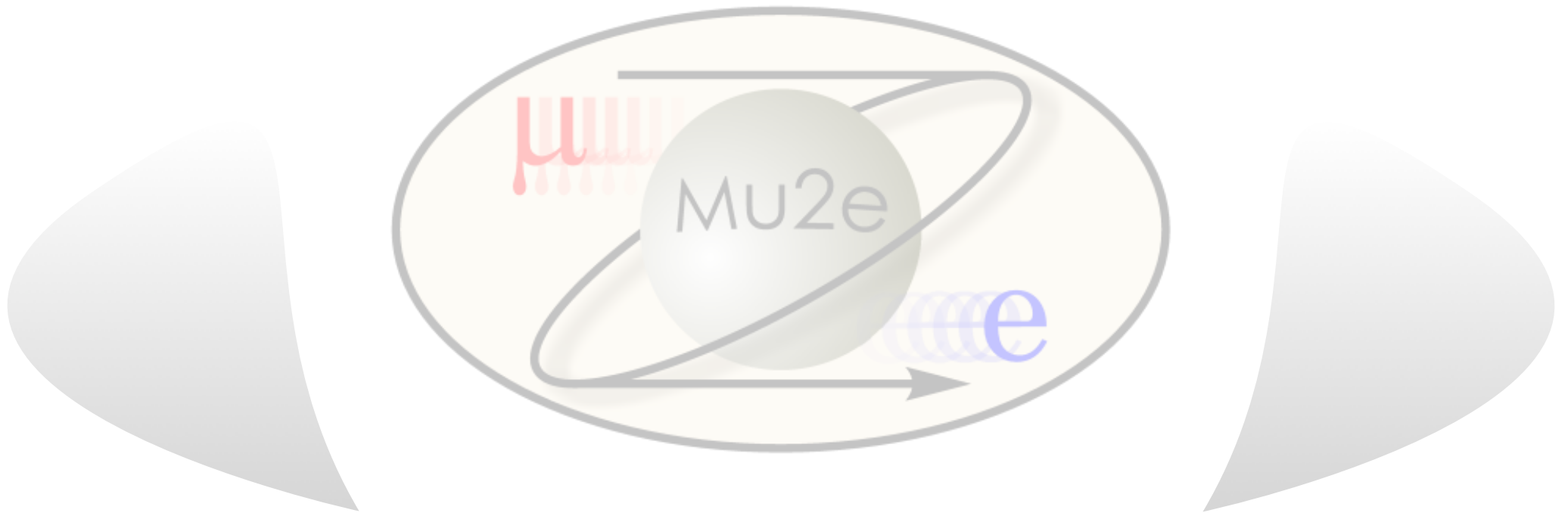




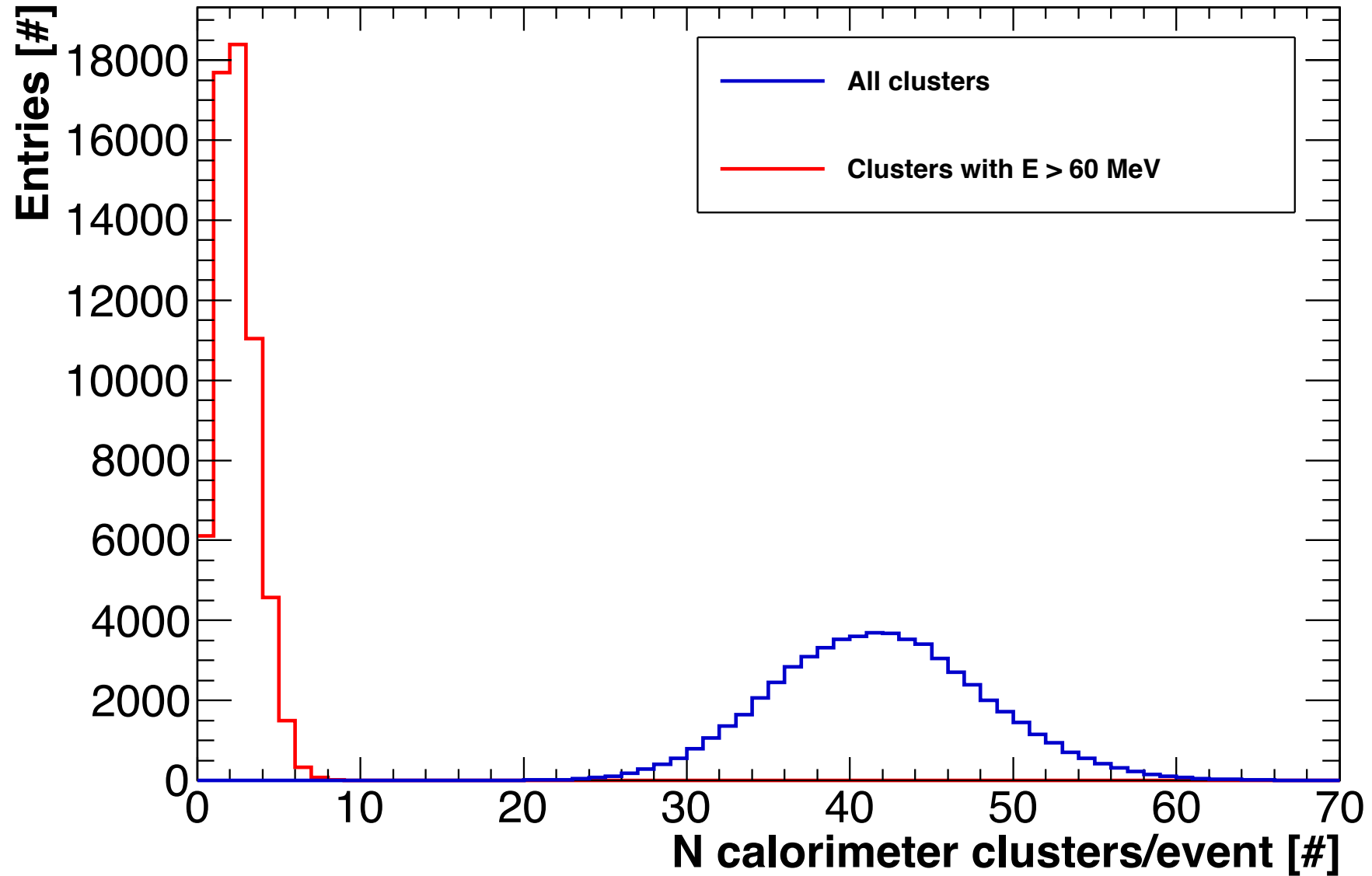
- $\epsilon$  evaluated using tracks passing quality cuts &  $103.85 < p < 105.1$  MeV/c
- $\epsilon$  improved by  $\sim 15\%$  (relative) and is more robust wrt the background
- An additional 5% (relative) by optimizing LR ambiguity algorithm

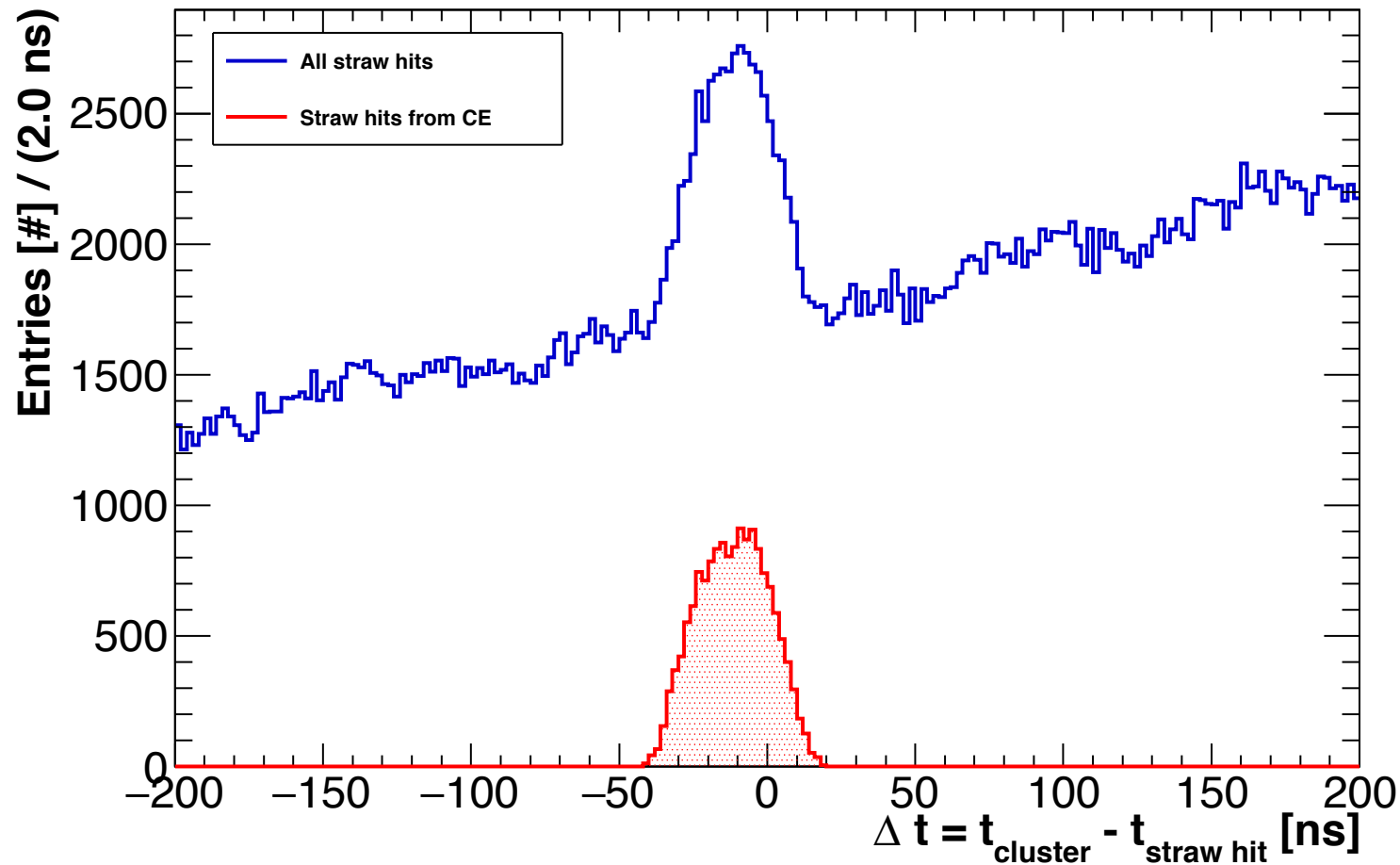
- The calorimeter improves the track reconstruction efficiency and makes it more robust
- The calo-seeded pattern recognition shows good performance at the trigger level (see Stefano Di Falco's talk)
- The algorithm is well integrated within the Mu2e reconstruction code
- Paper under internal review
- Furthermore improvements are under discussion in the tracking group:
  - ➔ merging the standalone and calo-seeded hit pre-selection algorithms
  - ➔ including the calorimeter cluster info in the Kalman filter

# backup slides



# MUSE Calorimeter cluster occupancy

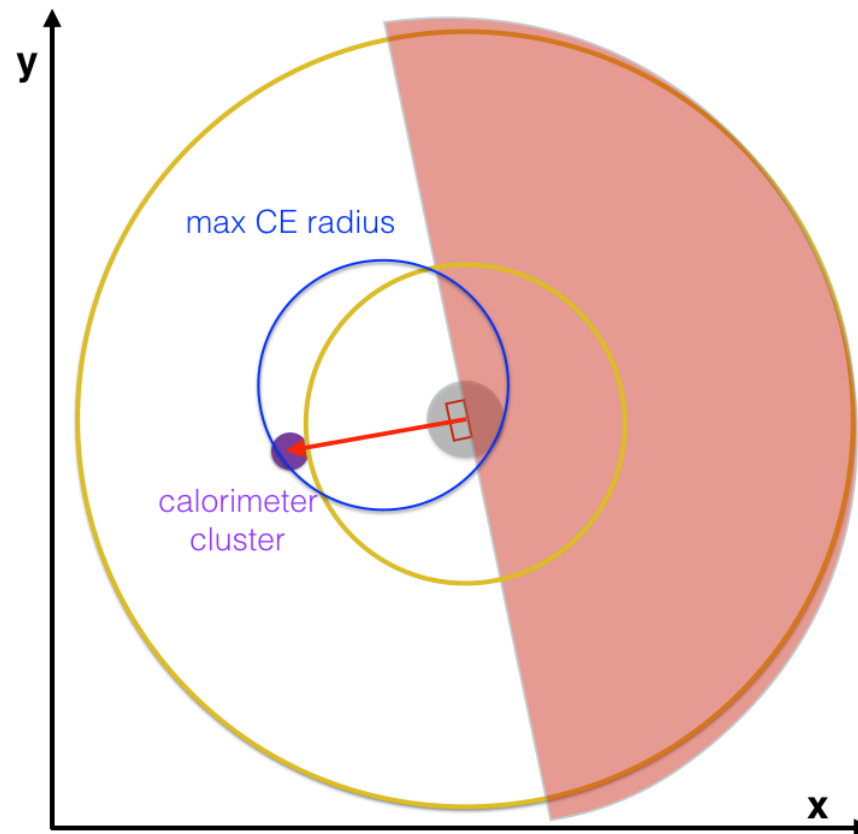




- Average tof from middle of the tracker to the calorimeter  $\sim 8$  ns
- Mean drift time  $\sim 20$  ns
- Difference of these two numbers is consistent with the peak position

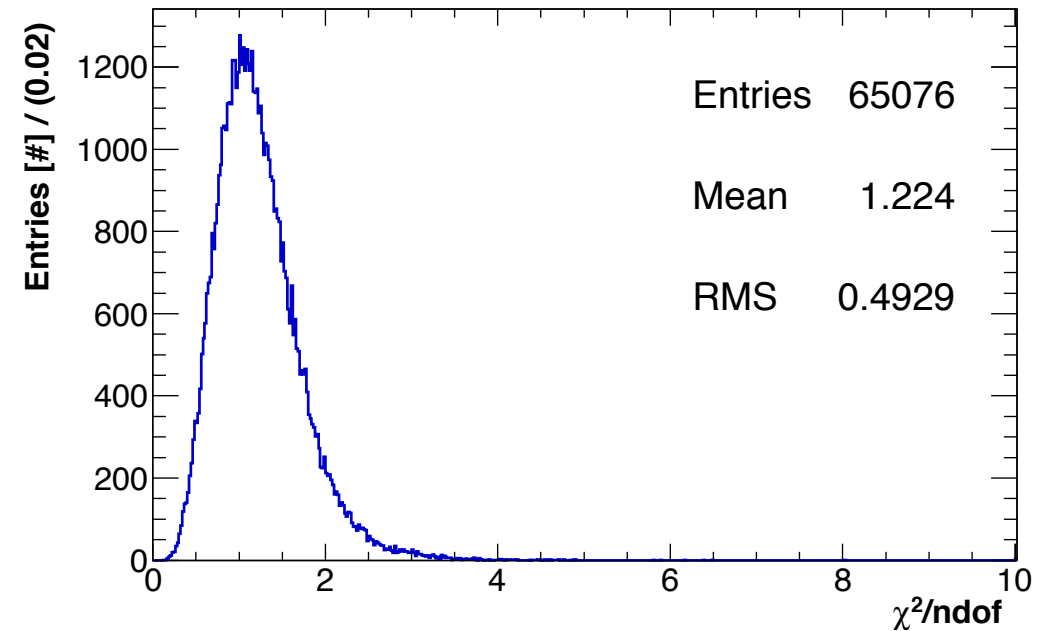
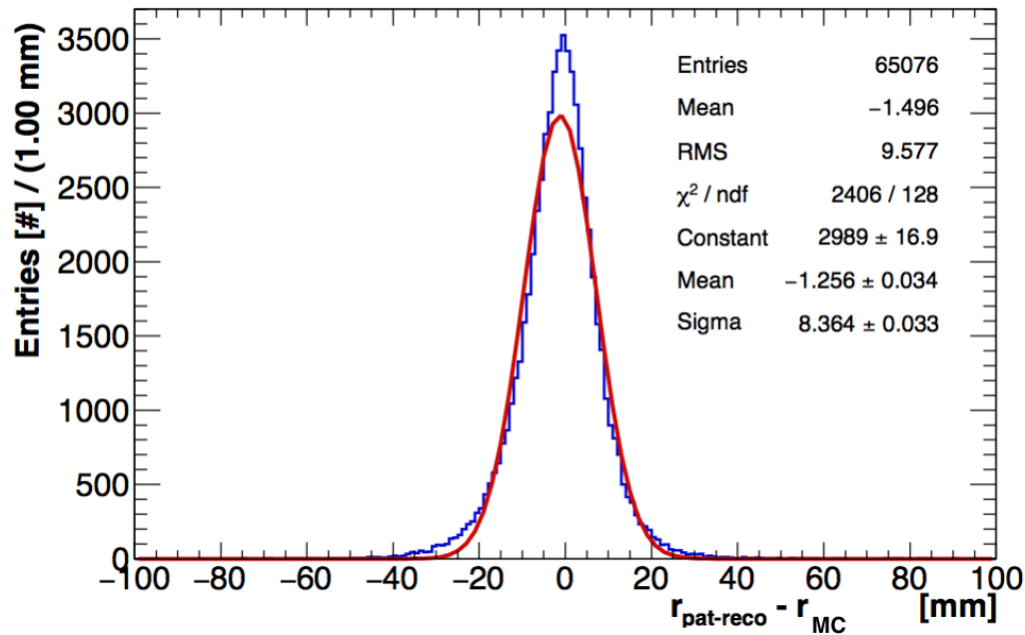


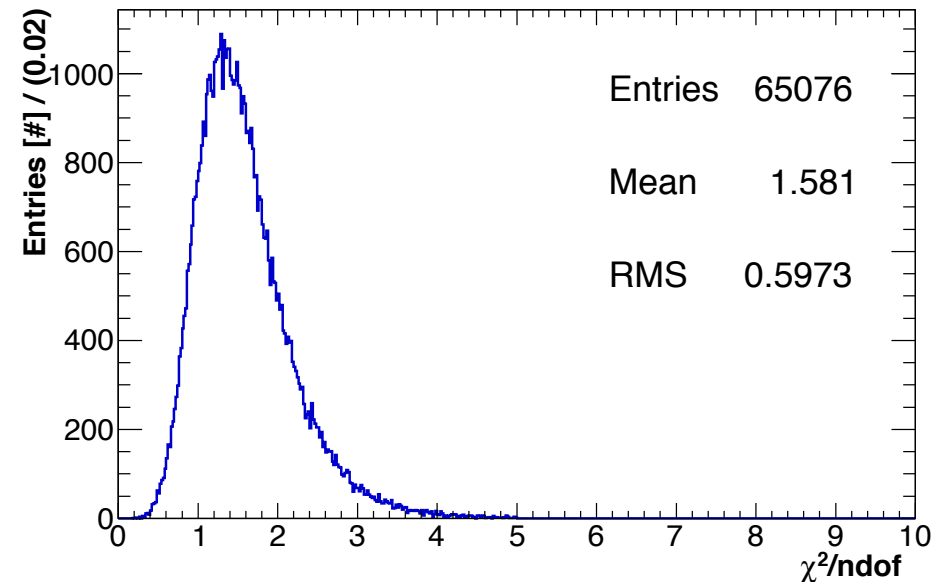
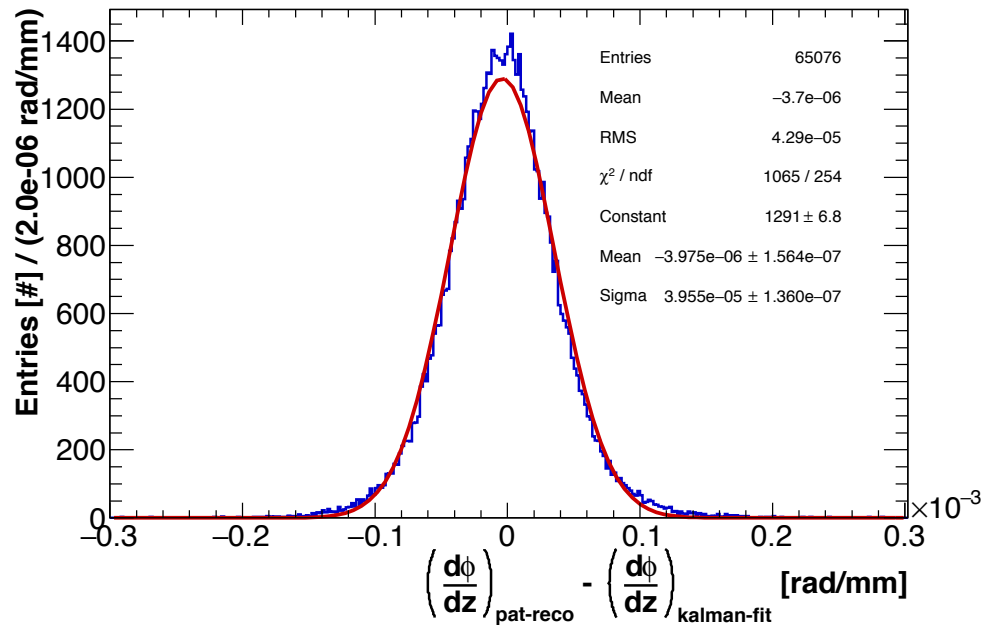
# MUSE Cluster position selection

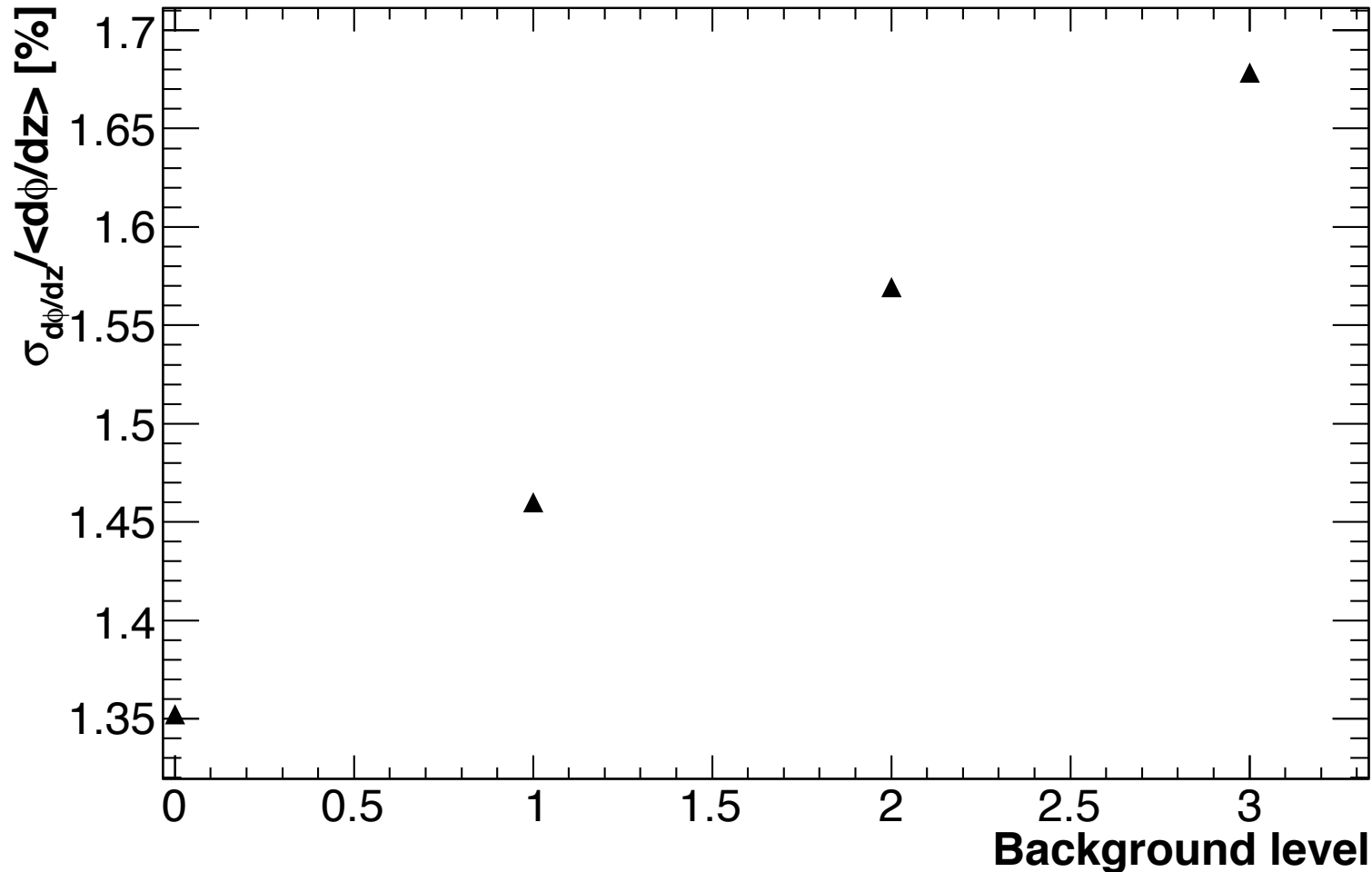


- Graded magnetic field between the stopping target and the tracker limits the CE pT
- Cluster position identifies the semi-plane where the CE track relies

- Reduced Least Square Method for performing the circle fit
- Errors are assigned using the straw orientation wrt the helix center

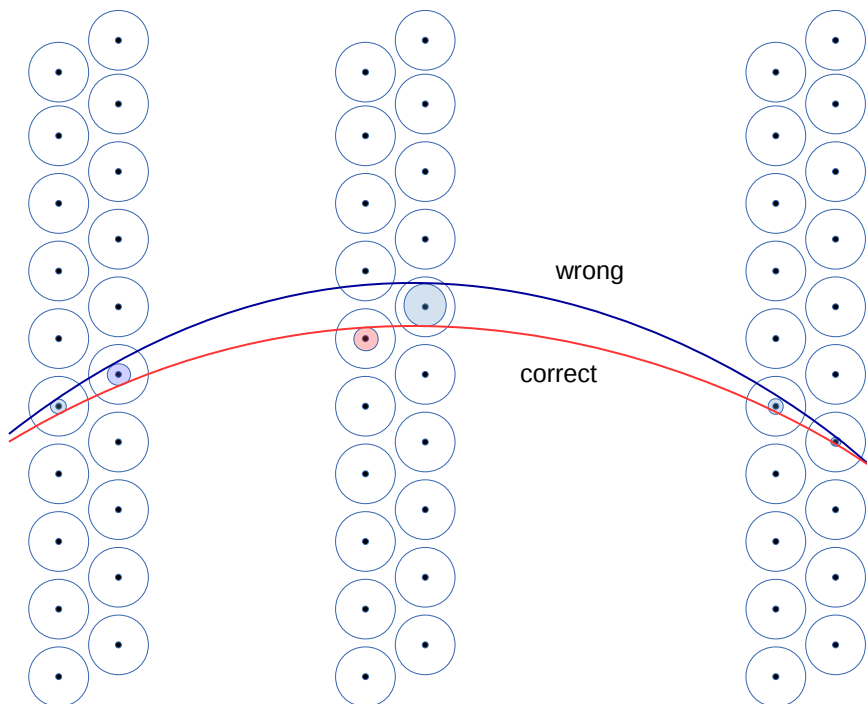




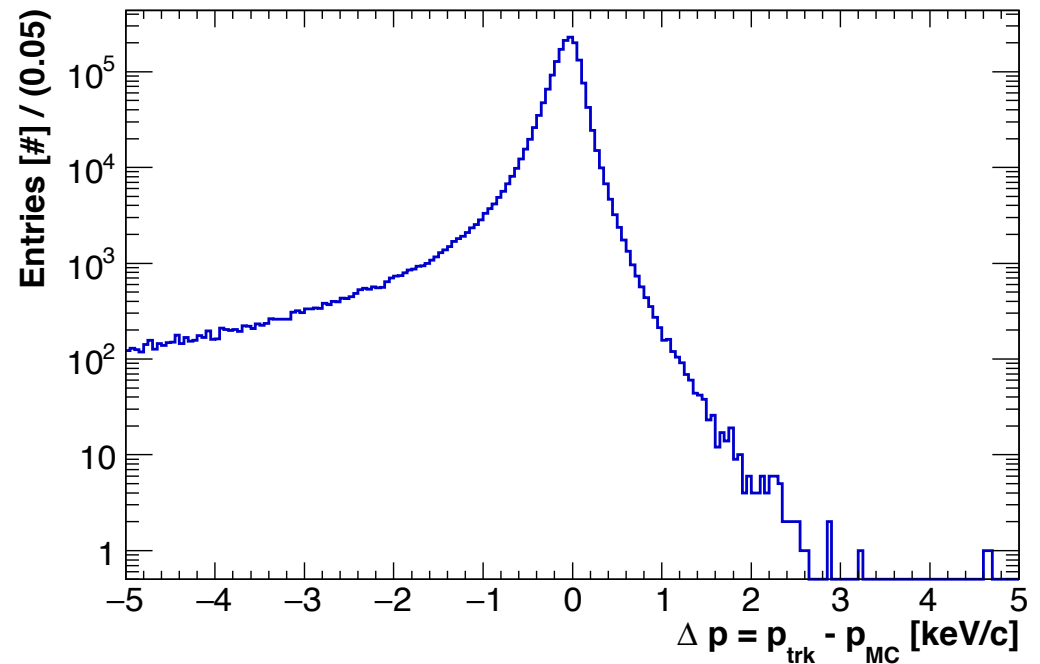


- Resulting  $d\phi/dz$  resolution  $\sigma_{d\phi/dz} / \langle d\phi/dz \rangle \sim 1.45$  % for CE

- Crucial in the final reconstruction is the “left-right” ambiguity resolution
- Drift sign mis-assignment impacts on the high-side tail

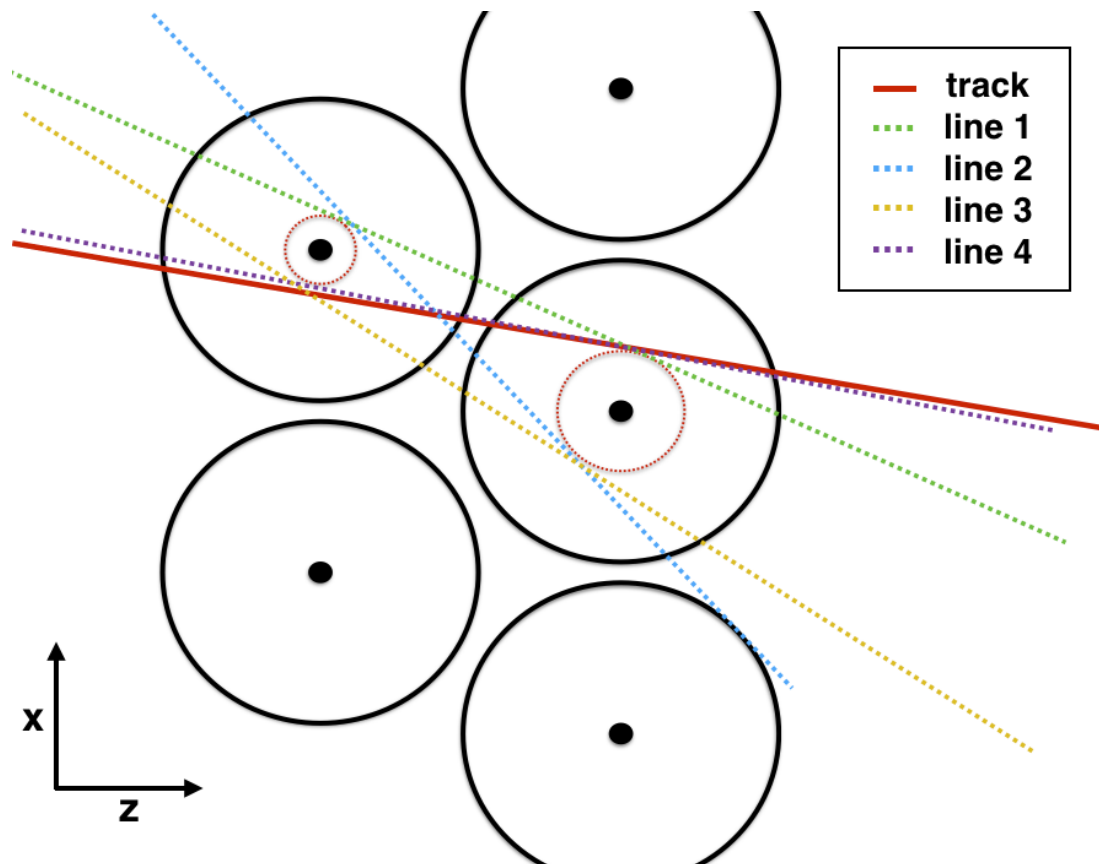


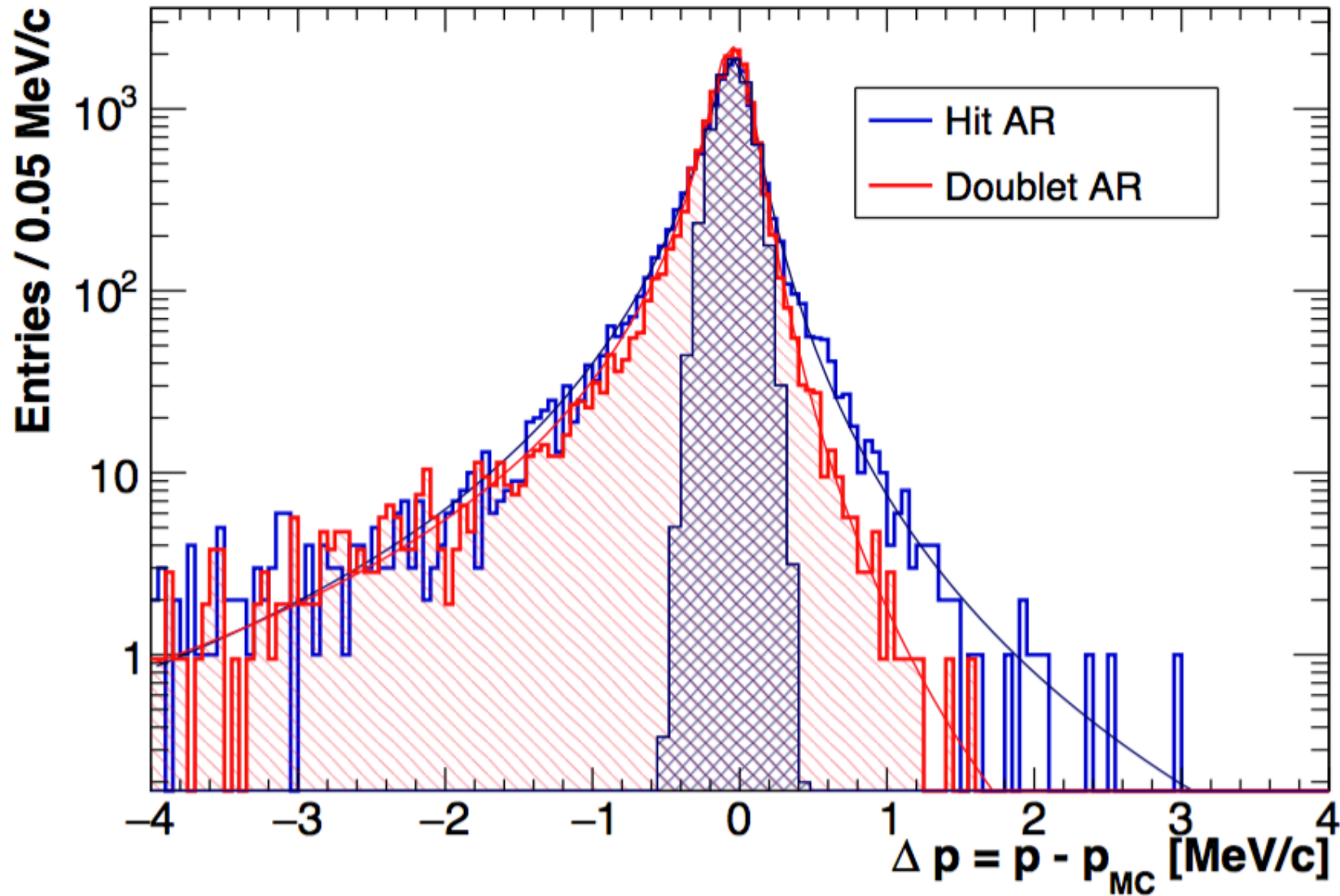
**CE  $\Delta p$  @ tracker entrance**



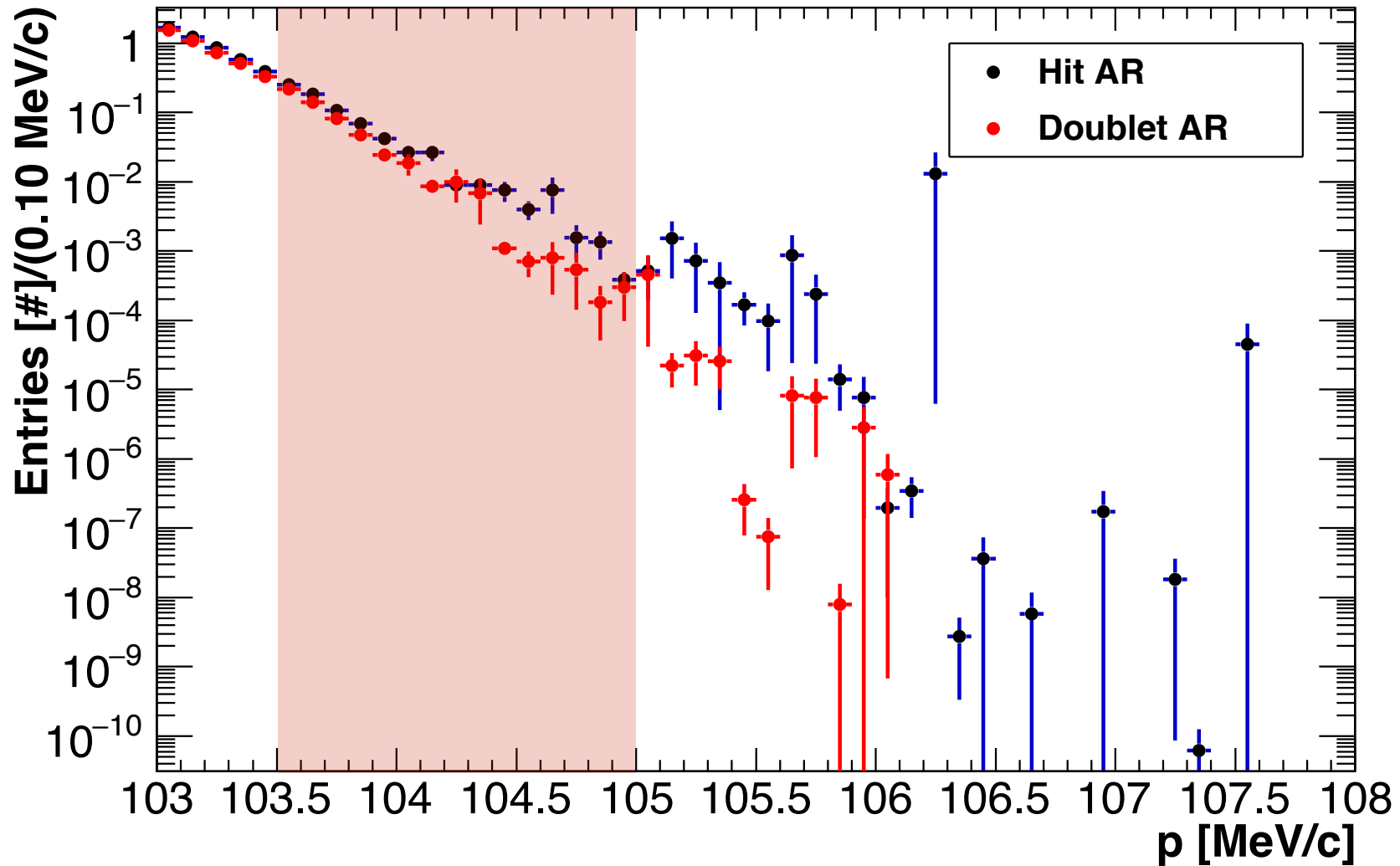


- The tracker is composed of 2-layers panels
- With  $\sim 80\%$  probability a track has 2 or more hits in a panel (**doublet**)
- Drift radii define 4 possible local track slopes that are used to find the correct drift directions



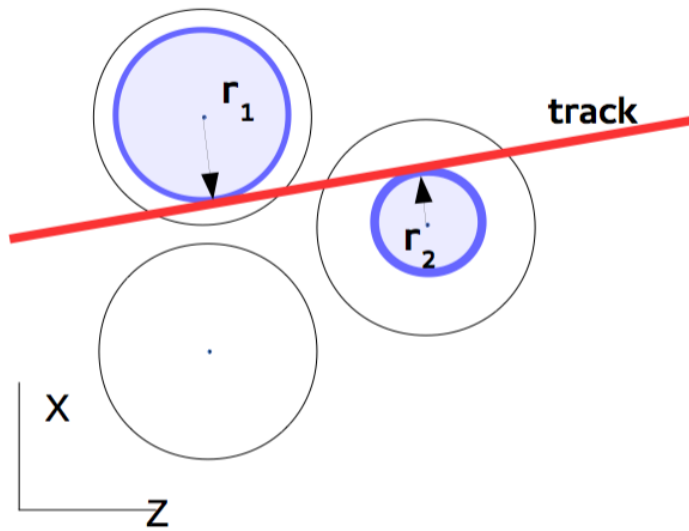


- Events with  $\Delta p > 1 \text{ MeV/c}$  reduced by a factor 5

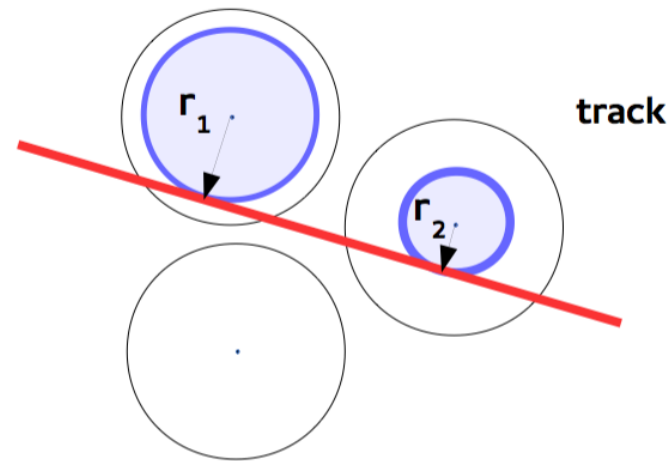


- Events with  $p$  in  $[103.5, 105]$  MeV/c reduced by factor 1.8

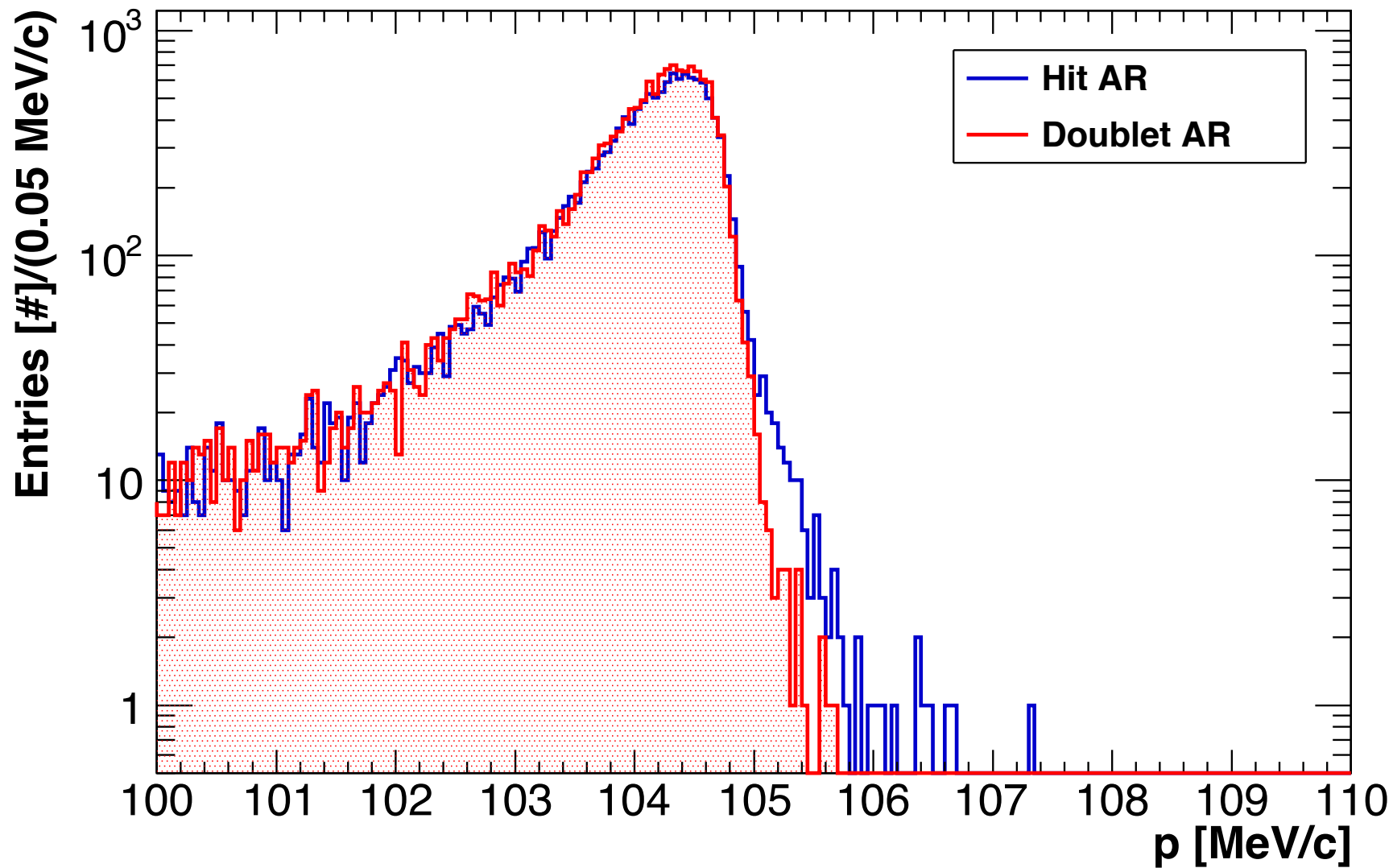
**opposite signs**

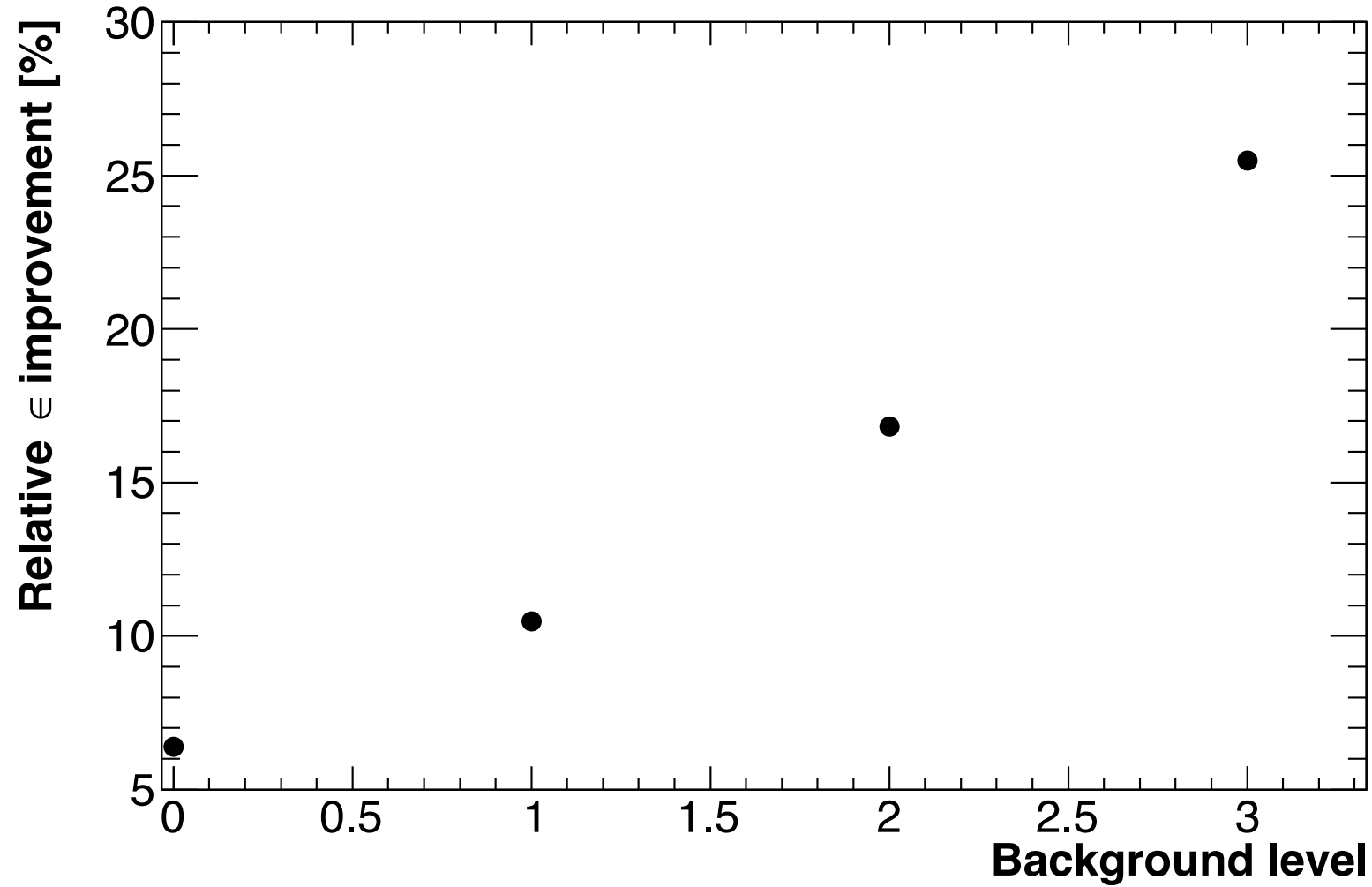


**same signs**



# MUSE CE momentum spectrum





# MUSE Mu2e track reconstruction



The Mu2e track reconstruction has several specific features:

- a CE makes 2-3 full turns in the tracker
- **time dependence** of the track-hit position:

$$r_{\text{drift}} = v_{\text{drift}} \cdot (t_{\text{measured}} - T_0 - t_{\text{flight}})$$

The **track reconstruction** is factorized into 2 main steps:

1. **Track finding**: provides a set of straw hits consistent with a track candidate
2. **Kalman based fitter**: performs the final reconstruction

The **track finding** uses two algorithms:

- A. **Standalone**: relies only on the tracker information
- B. **Calorimeter-seeded**: seeds the track search using the reco cluster