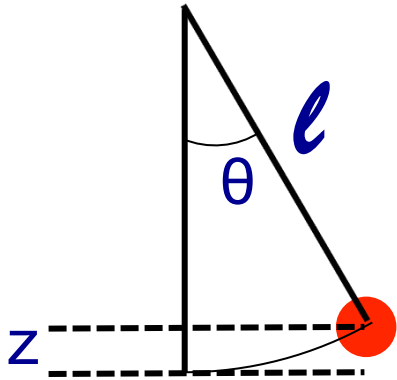


## Example of application of Lagrangian and Hamiltonian formalism: the pendulum



$$U = mgz = mgl(1 - \cos\theta)$$

$$T = \frac{1}{2}mv^2 = \frac{1}{2}m\ell^2\dot{\theta}^2$$

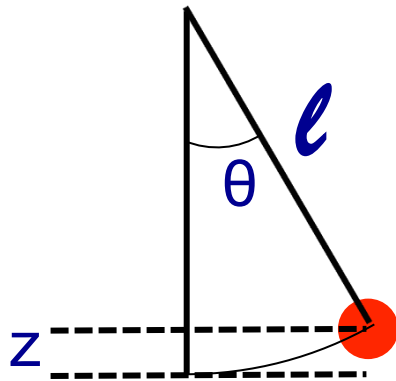
$$L = T - U = m\ell \left[ \frac{\ell\dot{\theta}^2}{2} - g(1 - \cos\theta) \right]$$

$$P_\theta = \frac{\partial L}{\partial \dot{\theta}} = m\ell^2\dot{\theta}$$

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{\theta}} \right) - \frac{\partial L}{\partial \theta} = 0 \quad \longrightarrow \quad m\ell \left[ \frac{d}{dt} (\ell\dot{\theta}) + g \sin\theta \right] = 0$$

$$\ell\ddot{\theta} + g \sin\theta = 0$$

## Example of application of Lagrangian and Hamiltonian formalism: the pendulum



$$U = mgz = mgl(1 - \cos\theta)$$

$$T = \frac{1}{2}mv^2 = \frac{1}{2}m\ell^2\dot{\theta}^2$$

$$H = T + U = mgl(1 - \cos\theta) + \frac{1}{2}m\ell^2\dot{\theta}^2$$

As variables let's consider  $\theta$  and its canonical momentum  $P_\theta = m\ell^2\dot{\theta}$   
(see previous page)

$$\rightarrow H = mgl(1 - \cos\theta) + \frac{P_\theta^2}{2m\ell^2} \quad \dot{\theta} = \frac{\partial H}{\partial P_\theta} = \frac{P_\theta}{m\ell^2} \quad \dot{P}_\theta = -\frac{\partial H}{\partial \theta} = -mgl \sin\theta$$

$$\dot{P}_\theta = m\ell^2\ddot{\theta} = -mgl \sin\theta$$

$$\ell \ddot{\theta} + g \sin\theta = 0$$