



Sensors and Energy Harvesting for Untethered Transducers

Vittorio Ferrari



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*Our teachers are not those who teach us,
they are those whom we learn from.*



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Sensors and Energy Harvesting for Untethered Transducers

Vittorio Ferrari

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- ◆ Marco Demori
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- ◆ Fabrizio Cerini
- ◆ Marco Baù
- ◆ Mehedi Masud
- ◆ Simone Dalola
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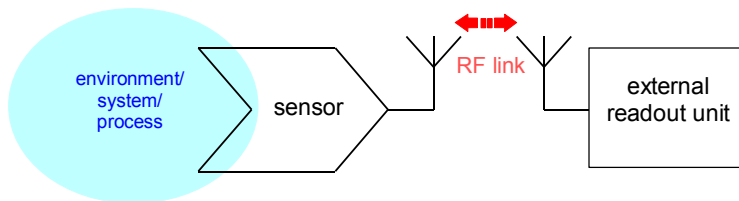
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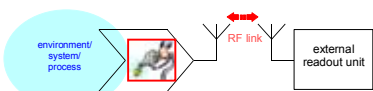
Contents

- **Introduction and Motivation**
- Piezoelectric Resonant Sensors with Contactless Interrogation
- Piezoelectric Energy Harvesting from Vibration and Motion
- Conclusions
- *Back to the roots*

Untethered (Stand-Alone) Transducers



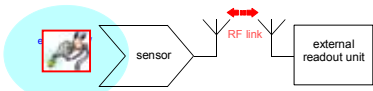
- Assuming that the external readout unit is energetically self-sufficient ... → the sensor needs **power supply**



- Power supply **internal** to the sensor (on-board)



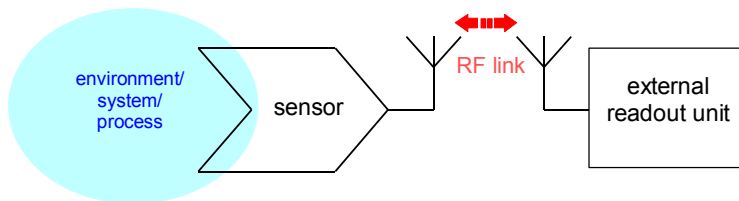
- Power supplied by the **external** readout unit



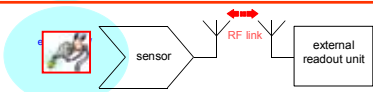
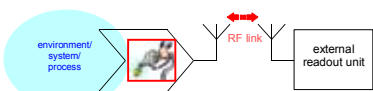
- Power harvested from the **surrounding ambient**

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Untethered (Stand-Alone) Transducers



- Assuming that the external readout unit is energetically self-sufficient ... → the sensor needs **power supply**



Passive sensors with contactless short-range signal transmission

piezoelectric effect

Energy harvesting from external sources

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Piezoelectric Sensors and MEMS

Table 1. Summary of the important techniques and typical properties of the piezoelectric thin films currently in use in MEMS.

Material	Deposition method	Deposition rate/film thickness	Substrate temp. (°C)	Reported piezoelectric properties
AlN/z-LiNbO ₃ [26]	dc magnetron sputtering	6 nm min ⁻¹	200	$k = 0.14-0.17$
AlN/Pt(1 1 1) [19]	Pulsed dc magnetron sputtering	0.4 μm	400	$e_{31,f} = 1.0 \text{ pC m}^{-2}$, $d_{33,f} = 3.4 \text{ pC N}^{-1}$, $\tan(\delta) = 0.002$, $k = 0.23$
AlN [27]	Reactive sputtering	1 μm	300	$e_{31,f} = -0.58 \text{ pC m}^{-2}$, $d_{33,f} = 3.56 \text{ pC N}^{-1}$, $k = 0.25$
AlN/Si(1 1 1) [28]	Metal organic chemical vapor deposition	130-250 nm	1050-1190	$d_{33} = 5.47-6.56 \text{ pm V}^{-1}$
AlN/Si(1 1 1) [29]	Pulsed laser deposition	43-18 nm min ⁻¹	500-920	-
ZnO/Pt [30]	Sol-gel	-	650, 700	$d_{33} = 17.11 \text{ pm V}^{-1}$
ZnO/glass (Corning 7059) [31]	RF magnetron sputtering	18 nm min ⁻¹	200	$k = 0.25-0.26$
ZnO/Si(0 0 1) [32]	RF magnetron sputtering	22 nm min ⁻¹	Room temperature	-
ZnO/glass [33]	Pulsed laser deposition	45.8 nm	250	-
PZT/Pt(1 1 1)/Ti/SiO ₂ /Si [34]	Chemical solution method	0.25-6 μm	700 (Sinter)	$e_{31,f} \approx -7 \text{ pC m}^{-2}$, $d_{33,f} = 150 \text{ pC N}^{-1}$, $\tan(\delta) = 0.05-0.02$
PZT/LSMO/Si [35]	Hybrid powder sol-gel	~5 μm	800 (Sinter)	$d_{33,f} = 340 \text{ pC N}^{-1}$, $\tan(\delta) = 0.02$
PZT/Si/SiO ₂ /Ti/TiO ₂ /Pt [36]	Diol-based chemical solution deposition	4.1 μm	-	$e_{31,f} = 7.29 \text{ pC m}^{-2}$, $\tan(\delta) = 0.023$
PZT/Ti/SiO ₂ /Si(100) [37]	Pulsed laser deposition	1-3 μm	700	-

S. Tadiadapa, K. Mateti, *Meas. Sci. Technol.*, **20**, (2009).

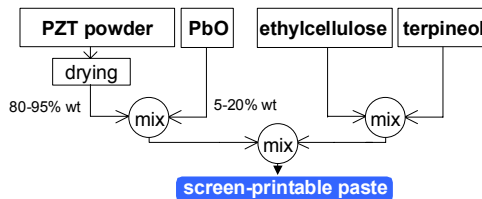
- We are considering low-cost deposition processes for:
 - ◆ lead zirconate titanate (PZT) films with thickness 10÷100 μm
 - ◆ different substrates (ceramics, metals, silicon, plastics, textiles)

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PZT Thick Films by Screen Printing

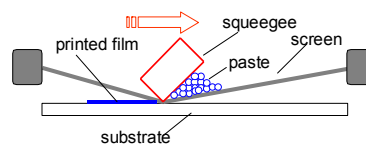
- PZT paste composed of:

- ◆ Active powder
- ◆ Binder
- ◆ Vehicle



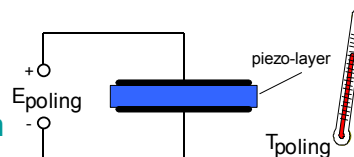
- Screen printing:

- ◆ Substrates:
 - Alumina (Al₂O₃)
 - Metals
 - Silicon



- ◆ Electrodes:
 - PdAg, or other metals

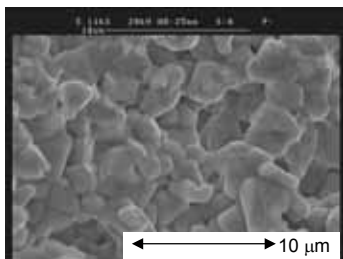
- Drying + Firing @ 950°C - 20 min
- Poling: 2÷5 MV/m @ 150°C - 30 min



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Properties of PZT Thick Films

- The films have fairly high porosity
- Properties differ from corresponding bulk ceramics



Ferroperm PZ26 powder (hard material)

parameter	BULK CERAMIC	THICK FILM
rel. permittivity ϵ^T/ϵ_0	1300	570
piezoelectric coeff. d_{33} [pC/N]	290	100
density ρ [g/cm ³]	7.7	5
elastic modulus Y_{33}^D [GPa]	90	30

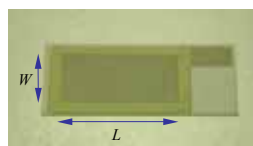
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Low-Curing-Temperature PZT Ink

- ◆ Mixture between PZT powder and polymeric binder
- ◆ Curing: (10 min @ 150°C)
- ◆ Electrodes: Ag polymeric ink
- ◆ Poling: (10 min @ 4 MV/m @ 130°C)

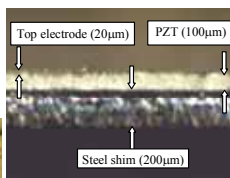
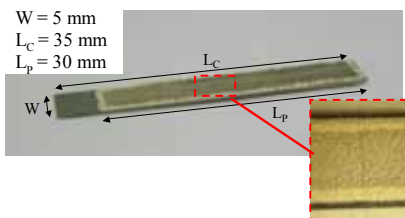
Alumina substrate

W = 18 mm
L = 31 mm
Film Thickness = 125 μm



Harmonic steel substrate

W = 5 mm
L_c = 35 mm
L_p = 30 mm



PET (PolyEthyleneTerephthalate) substrate



parameter	BULK CERAMIC	THICK FILM
rel. permittivity ϵ^T/ϵ_0	4100	100
density ρ [g/cm ³]	7.5	4.5
piezoelectric coeff. d_{33} [pC/N]	590	< 10

Piezokeramica-APC 856 powder (soft material)

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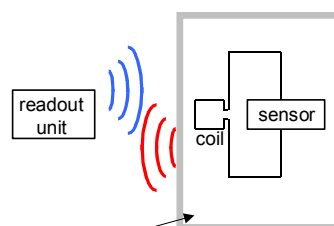
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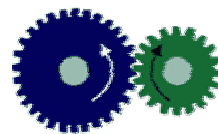
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Contactless Interrogation Sensors

- **Goal:**
Investigate on devices and techniques to enable proximity interrogation of battery-less sensing elements based on micro-electromechanical resonators



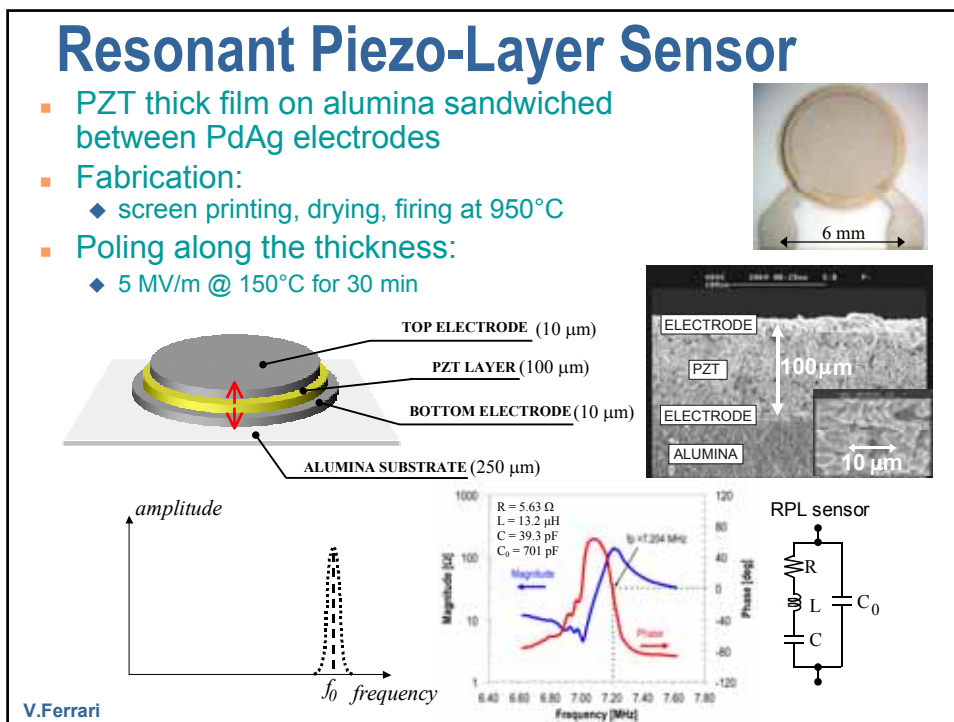
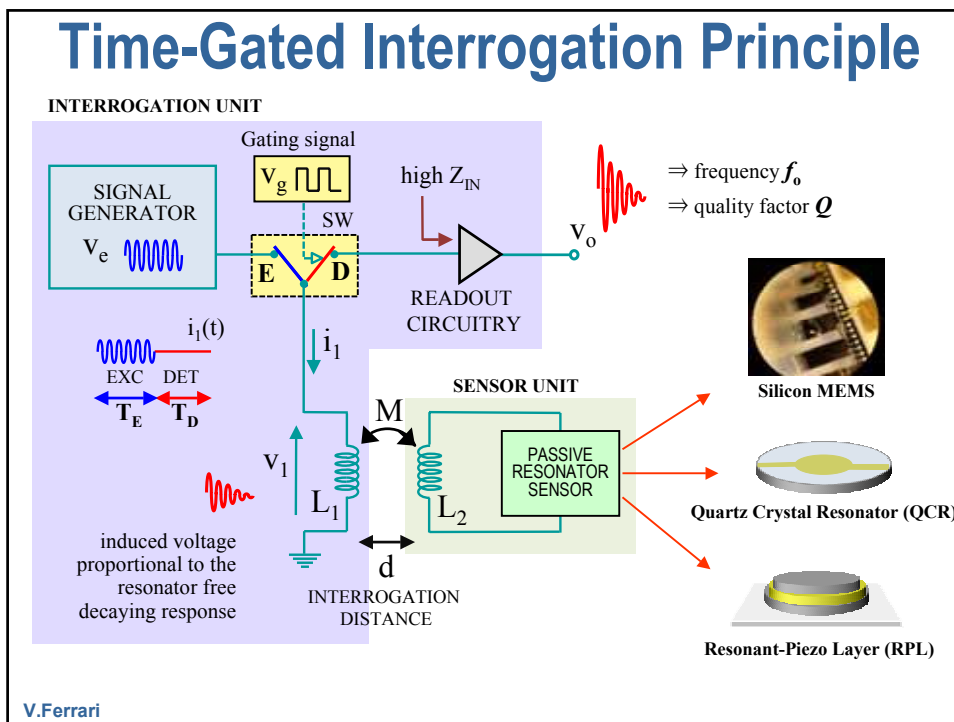
Nonaccessible volume,
hostile environment,
hermetic package.



- **Sensors can:**
 - ◆ sense physical quantities (temperature,...)
 - ◆ be functionalized towards bio-chemical quantities

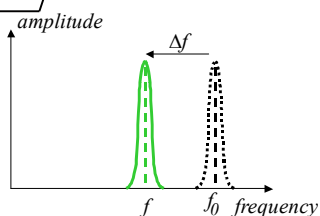
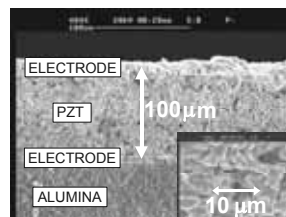
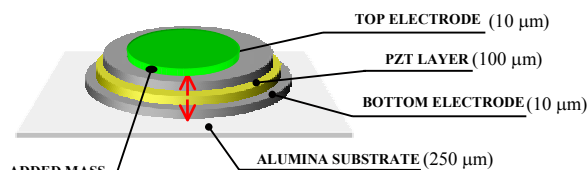
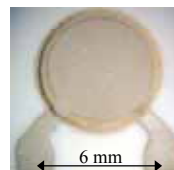


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Resonant Piezo-Layer Sensor

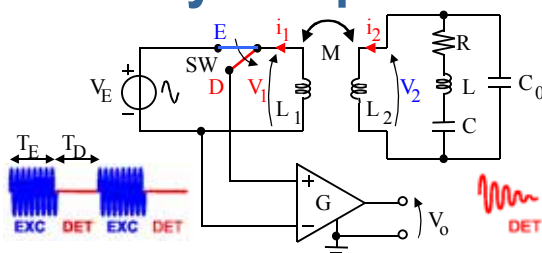
- PZT thick film on alumina sandwiched between PdAg electrodes
- Fabrication:
 - ◆ screen printing, drying, firing at 950°C
- Poling along the thickness:
 - ◆ 5 MV/m @ 150°C for 30 min



- The mass-sensitive response can be exploited for **gravimetric chemical detection**

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Theory of Operation



$$Z_m = sL + R + 1/sC$$

$$Z_2 = sL_2 + R_2$$

$$\alpha_m = R/2L \quad \alpha_e = R_2/2L_2$$

$$\omega_{dm} = \sqrt{1/LC - \alpha_m^2} = \sqrt{\omega_s^2 - \alpha_m^2}$$

$$\omega_{de} = \sqrt{1/L_2C_0 - \alpha_e^2}$$

- In the detection phase **DET**, considering that:
 - ◆ initial conditions in M are negligible, port 1 has high impedance

$$I_2 = \frac{V_m(0) + sV_e(0)Z_mC_0}{Z_m(1 + sC_0Z_2) + Z_2} = \frac{[v_C(0)/s - Li_L(0)] + v_{C_0}(0)Z_mC_0}{Z_m(1 + sC_0Z_2) + Z_2} \quad V_1 = sMI_2$$

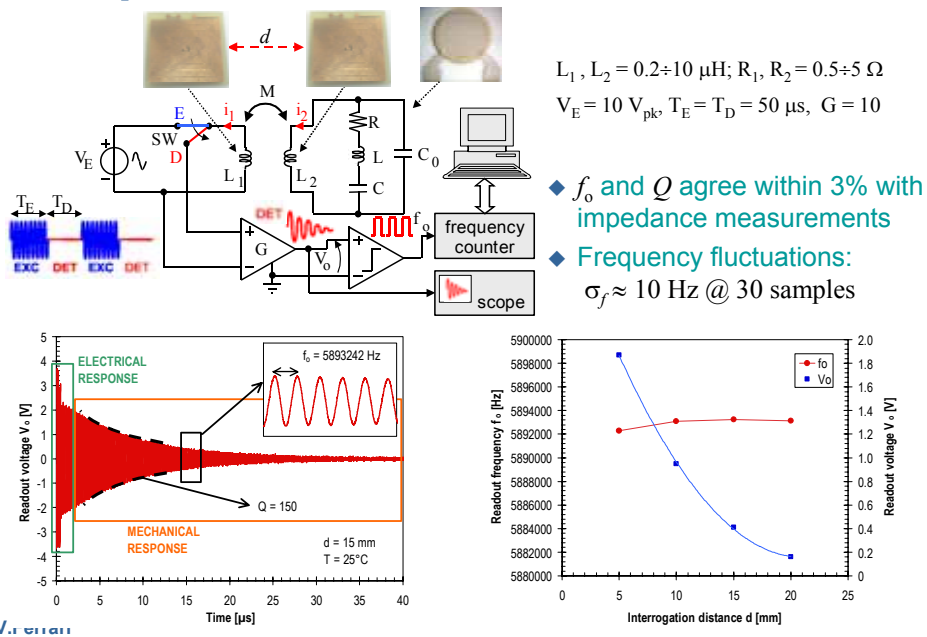
- Assuming Z_2 negligible compared to $Z_m(1 + sC_0Z_2)$:

- ◆ Sum of two damped cosines at ω_{de} and ω_{dm}
- ◆ Electrical cosine decay is fast
- ◆ M only acts as a scaling factor

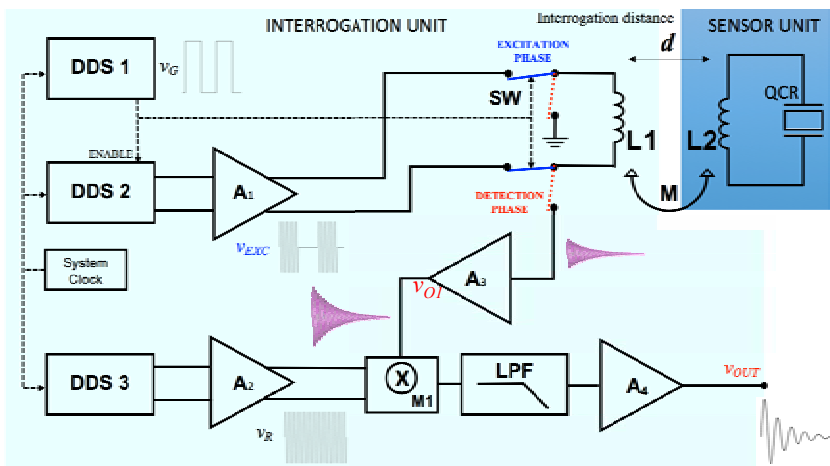
$$V_o(t) = GM \left[A_e e^{-\alpha_e t} \cos(\omega_{de} t - \theta_e) + A_m e^{-\alpha_m t} \cos(\omega_{dm} t - \theta_m) \right]$$

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Experimental Results



Down-Mixing of Ringing Signal



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M. Ferrari et al., Prof. Euroensors 2016, (2016).

Autocorrelation Analysis

Autocorrelation analysis block
for frequency and Q-factor estimation

Frequency down-mixing of the readout signal $v_{O1}(t)$
 Decaying response:

$$v_{O1}(t) = MA_m A_3 \exp(-\alpha_m t) \cos(2\pi f_{dm} t + \theta_m)$$
 Reference signal:

$$v_R(t) = A_2 \cos(2\pi f_R t)$$
 Resulting low-pass filtered and amplified signal $v_{OUT}(t)$:

$$v_{OUT}(t) = MA_{OUT} \exp(-\alpha_m t) \cos(2\pi f_{OUT} t + \theta_m)$$

$$f_{OUT} = f_{dm} - f_R$$

Output frequency f_{OUT} can be shifted in the range compliant with the ADC sampling rate by varying f_R

$$R_{xx}(\tau) = \frac{1}{4} (MA_{OUT})^2 e^{-\alpha_m |\tau|} \left[\alpha_m^{-1} \cos(2\pi f_{OUT} \tau) + \frac{\alpha_m \cos(2\pi f_{OUT} \tau + 2\theta_m) - 2\pi f_{OUT} \sin(2\pi f_{OUT} \tau + 2\theta_m)}{(\alpha_m)^2 + (2\pi f_{OUT})^2} \right]$$

V.Ferrari M. Ferrari et al., Prof. Eurosensors 2016, (2016).

Contactless Temperature Sensor

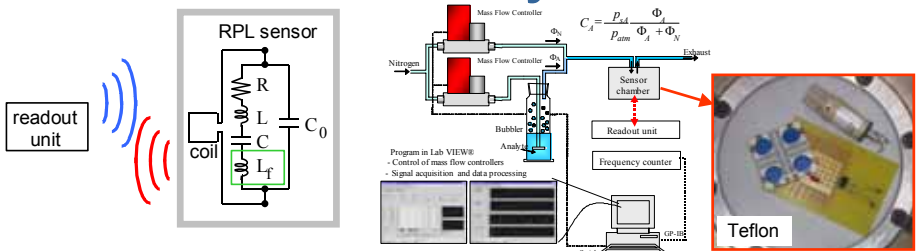
- Sensor substrate heated at temperature T
- Readout made from a distance $d = 1.5$ cm

Temperature [°C]	Readout frequency f_o [MHz]
25	7.216
30	7.213
40	7.203
50	7.193
60	7.183
70	7.173
80	7.163

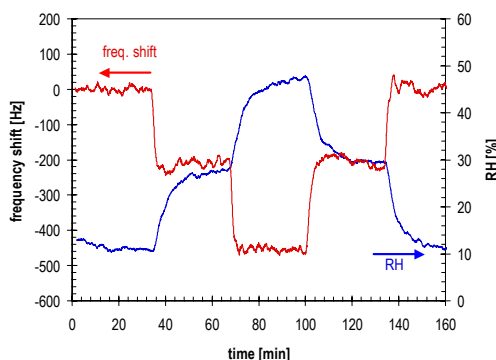
- ◆ f_o agrees within 10% with impedance measurements
- ◆ Resolution better than 0.05°C

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Contactless Humidity Sensor



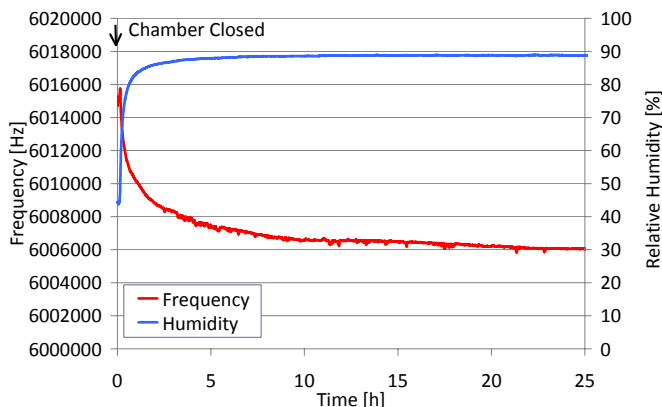
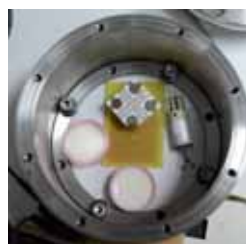
- RPL sensor coated with a PVP (Polyvinylpyrrolidinone) hygroscopic film
- Readout made from outside the sensor chamber
- Comparison with RH reference sensor (Gefran T6000)



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Test on Milk

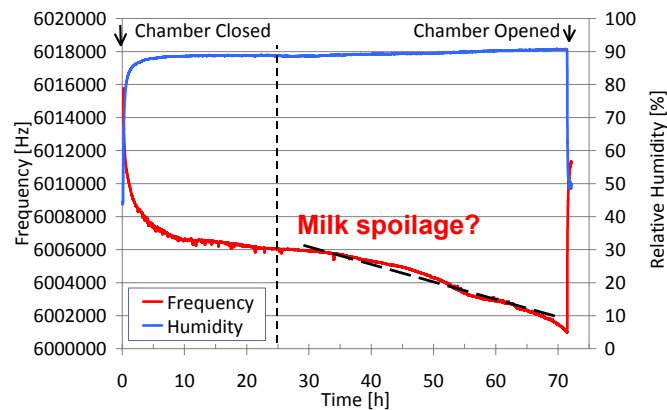
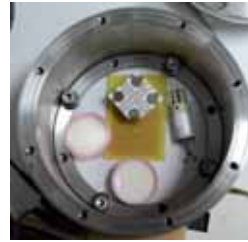
- ◆ In the steel test chamber @ room T:
 - RPL sensor functionalized with PEA coating (PolyEthylhexylAcrylate)
 - Raw (unpasteurized) milk
- ◆ Sensor interrogated from outside the test chamber



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Test on Milk

- ◆ In the steel test chamber @ room T:
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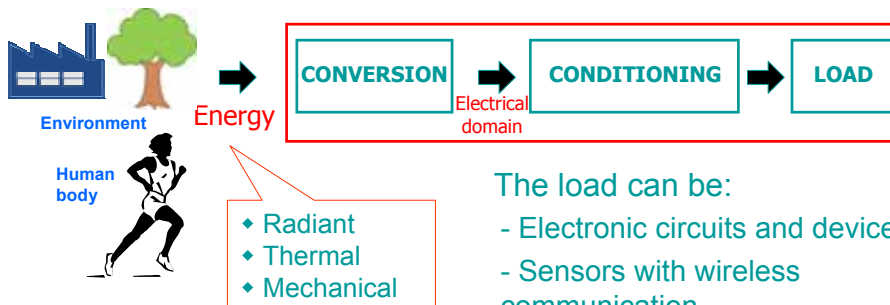
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Energy Harvesting

- Principle: Energy is extracted from the surroundings



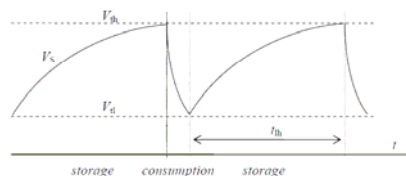
- Radiant
- Thermal
- Mechanical

The load can be:

- Electronic circuits and devices
- Sensors with wireless communication

→ **Autonomous Sensors**

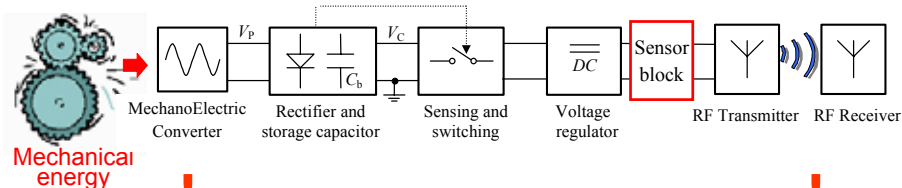
- If available power is insufficient for continuous operation → **Intermittent operation**



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Autonomous Sensors with RF Link

- The converted energy is stored and intermittently used to trigger a radio-frequency (RF) transmitter



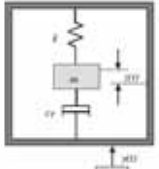
! No battery, no internal power sources !

- Best-of-class RF transceivers consume around 5 mW (*)
- Typical average power required from the harvester is **100 μ W** depending on the communication duty cycle

* ISSCC 2015: Imec, Holst Centre and Renesas

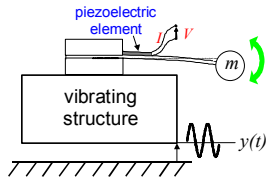
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Resonant Converters and Limitations



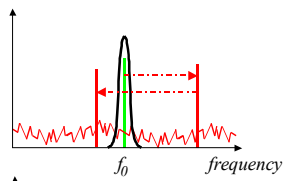
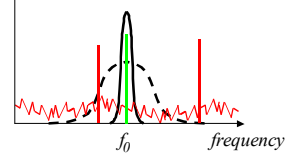
$$P_d = \frac{mY^2\omega_n^3}{4\zeta_T}$$

$$P_{max} = m\zeta_t\omega_n^3Z_{max}^2$$



C.B. Williams, R.B. Yates, *Sens. Actuat. A* 52, 8-11 (1996).

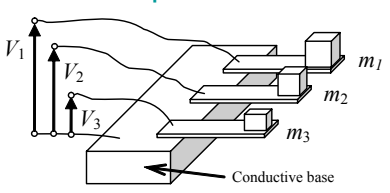
- ◆ Maximum power at resonance
- Operation at resonance is problematic to guarantee with frequency-varying vibrations and is considerably sub-optimal for wideband noise
- Lowering the converter quality factor increases bandwidth, but worsens peak response

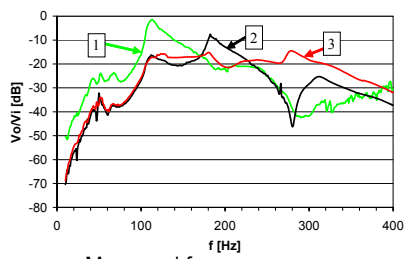
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Multi-Frequency Converter Array

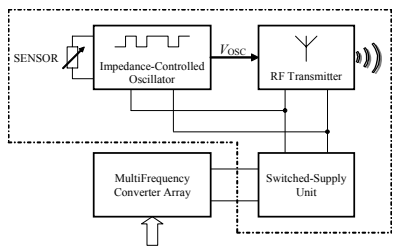
- Multiple differently-tuned converters combined to obtain a wider equivalent bandwidth:



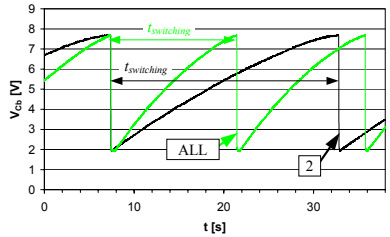
Bimorph commercial cantilevers (RS 285–784):
15mm × 1.5mm × 0.6 mm,
 $m_1 = 1.4$ g, $m_2 = 0.7$ g, $m_3 = 0.6$ g.



Measured frequency response.



M. Ferrari et al., *Sens. Actuat. A* 142, 329-335 (2008).

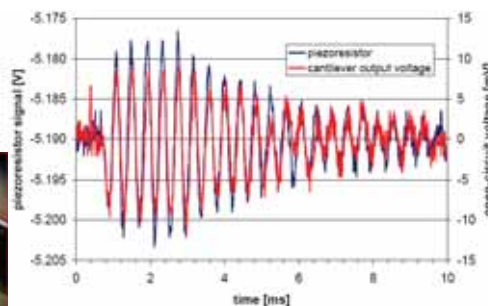
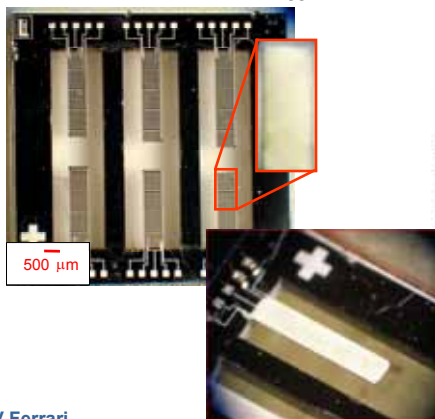
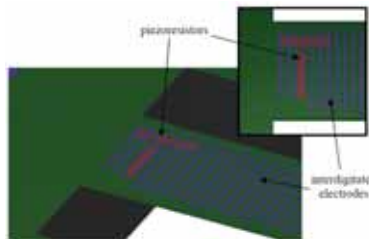


Measured voltage across the storage capacitor.

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MEMS Implementation of a MFCA

- Design: University of Brescia
- Fabrication: CNM, Barcelona
- PZT paste: MEGGIT/Ferroperm
- Screen-printed PZT film
- IDT electrodes (d_{33} mode)

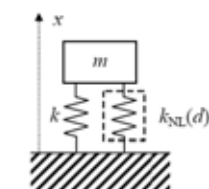
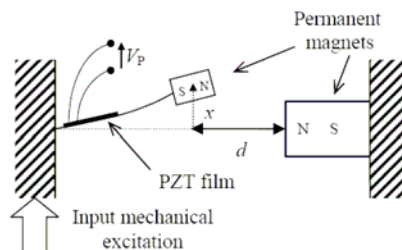


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Nonlinear Converter

Collaboration with Univ. Catania (S. Baglio) and Univ. Perugia (L. Gammaitoni)

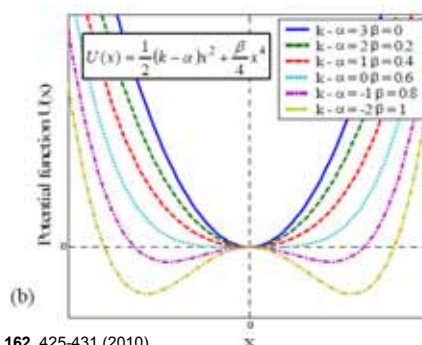
- Bistability** is exploited to amplify displacement induced by **broadband vibrations**
- For decreasing values of d :
 - Quasi linearity
 - Nonlinearity
 - Bistability



$$m\ddot{x} + (k - k_{NL})x = 0$$

$$k_{NL}(d) = \alpha - \beta x^2$$

$$F_{NL}(d) = \alpha x - \beta x^3$$

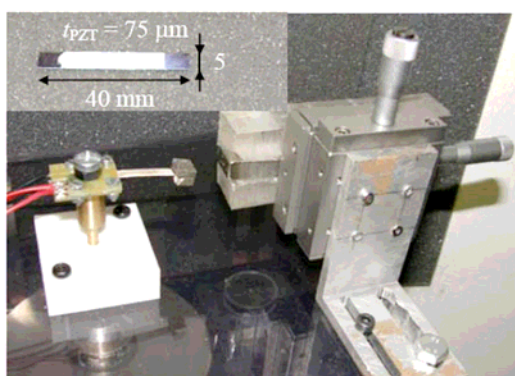


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M. Ferrari et al., Sens. Actuat. A 162, 425-431 (2010).

Nonlinear Converter: Experiment

- Bimorph cantilever beam fabricated with:
 - ◆ Stainless steel substrate (thickness 200 μm)
 - ◆ Low-curing-temperature PZT films
- White-noise excitation filtered in the bandwidth 1-100 Hz

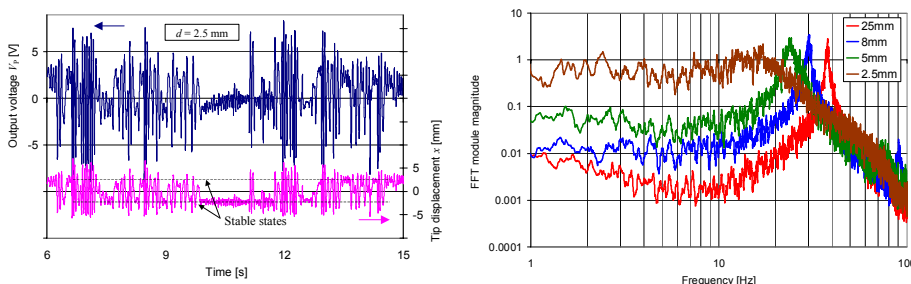


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M. Ferrari et al., *Sens. Actuat. A* **162**, 425-431 (2010).

Nonlinear Converter: Results

- For suitably low gap d , jumps occur between stable states
- The output voltage spectrum broadens and V_{Prms} increases



$a_{rms} = 0.3 g$

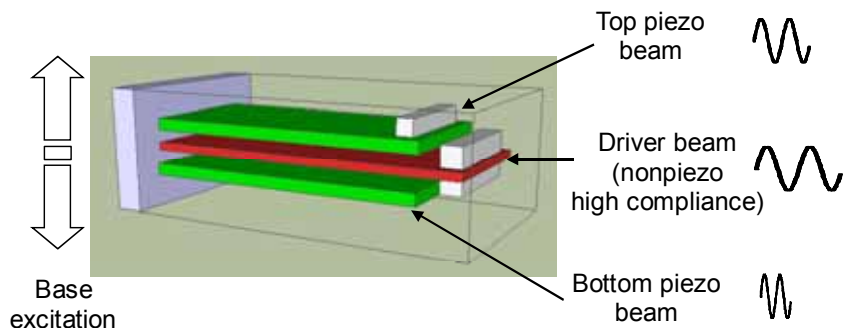
Distance d [mm]	rms output voltage V_{Prms} [V]
25	4.27
5	6.11
2.5	7.99

- ◆ Complex dynamics, see: S.C. Stanton et al., *Physica D* **239**, 640-653 (2010).
G. Sebald et al., *Smart Mater. Struct.* **20**, (2011).

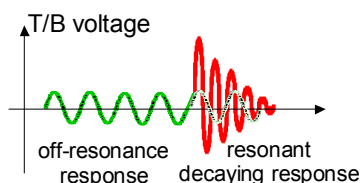
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M. Ferrari et al., *Sens. Actuat. A* **162**, 425-431 (2010).

Impact Multi-Beam Converter



- Low-frequency off-resonance vibrations are converted into resonant decaying response

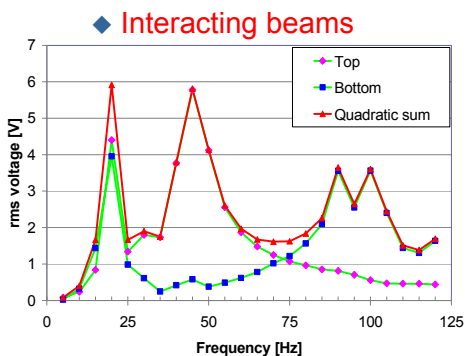
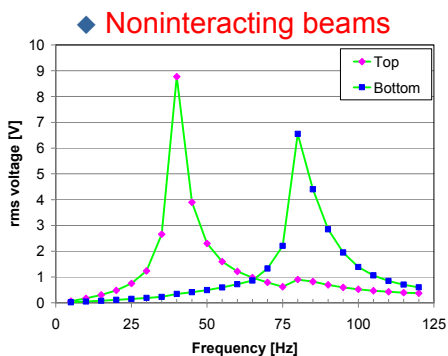
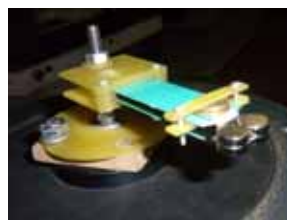


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F. Cerini et al., *Transducers - Eurosensors*. (2013).

Experimental Results: Sinusoidal

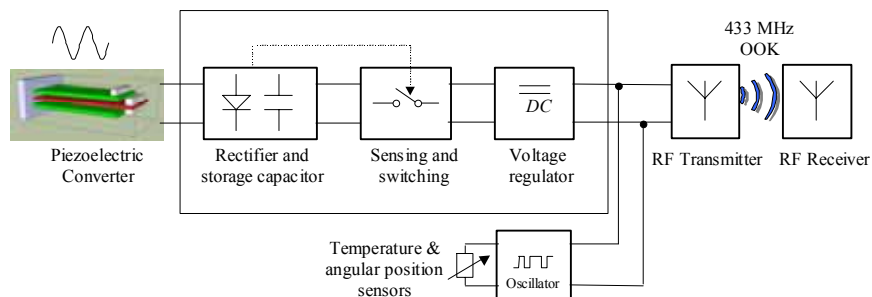
- EH mounted on the shaker (Brüel & Kjær Vibration exciter type 4808)
- Swept-frequency excitation of the shaker ($a_{pk} = 1 \text{ g @ } 50 \text{ Hz}$)



- Power on matched load: $1 \div 2 \text{ mW}$

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Experimental Results



- Handheld EH intentionally shaken
- RF transmissions start after 10 to 15 s and repeat every few seconds under moderate to forcible shaking

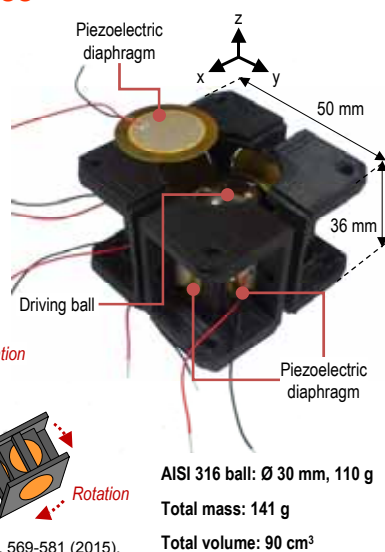
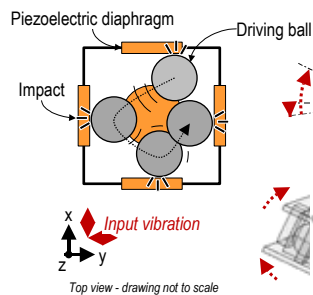


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F. Cerini et al., *Transducers - Eurosensors*. (2013).

Ball-Impact Piezoelectric Converter

- Six piezoelectric disks as faces of a cube
→ Multi-Degree-of-Freedom response
- Ball impacts on piezo disks and performs frequency-up conversion
- Impacts occur also for rotation and inclination

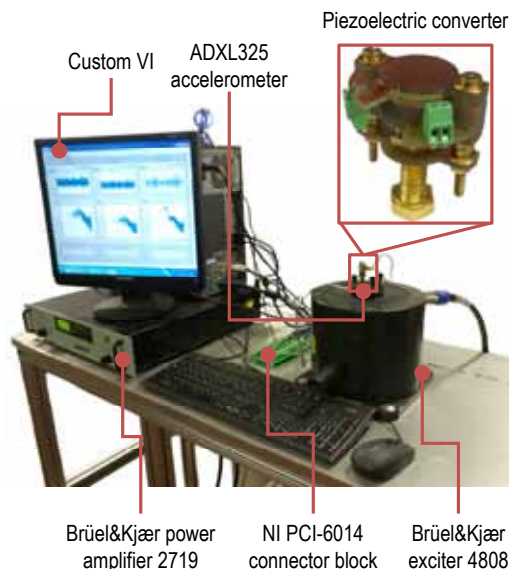


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D. Alghisi et al., *Sens. Actuat. A* 233, 569-581 (2015).

Characterization Set-Up

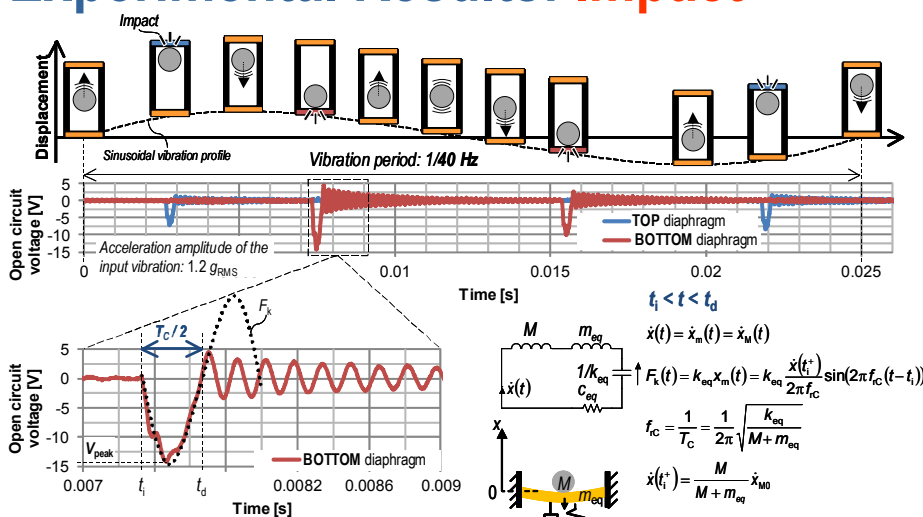
- Sinusoidal vibrations with user-selectable acceleration amplitude and frequency.
- Band-pass white noise vibrations with user-selectable acceleration amplitude and bandwidth.
- Closed-loop control of the z-axis RMS acceleration amplitude.
- Automated measurement for statistical post-processing.



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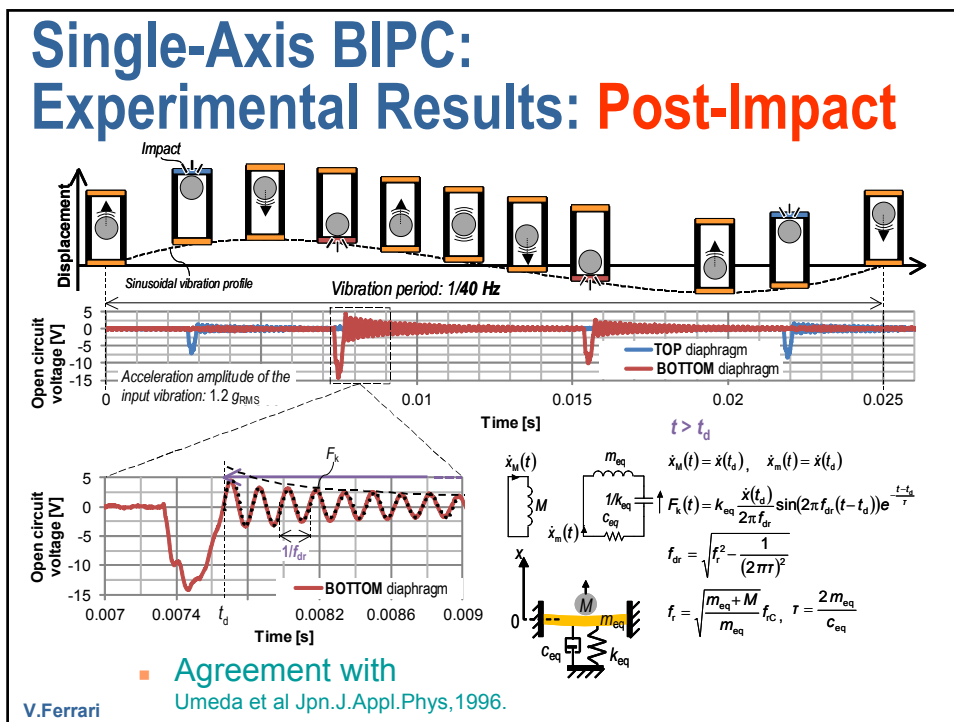
D. Alghisi et al., Sens. Actuat. A 233, 569-581 (2015).

Single-Axis BIPC: Experimental Results: Impact



- Agreement with Umeda et al Jpn.J.Appl.Phys,1996.

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EH from Human Motion

- Goal:
 - Investigate on mechanical EH to power wearable electronics and sensors
 - ◆ Assess performances in different body positions
 - ◆ Select the preferable converter principle

Forearm


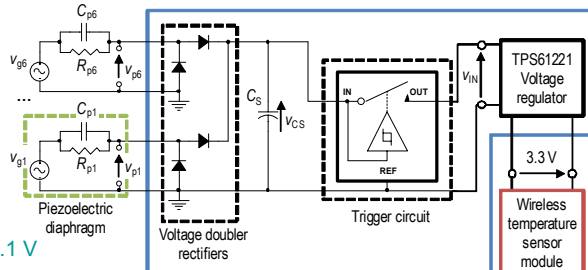
Waist belt

Shoe

Ankle

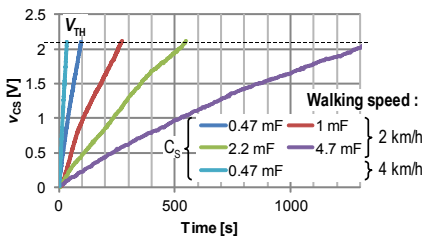
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Ball-Impact Piezoelectric Converter

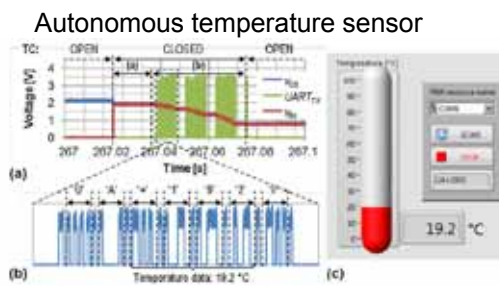
- Electronics for discontinuous operating mode:
 Trigger circuit $V_{TH} = 2.1\text{ V}$, $V_{TL} = 1.1\text{ V}$
 - Wireless temperature sensor module:

Energy requirement for measurement & transmission: $\sim 1\text{ mJ}$



Walking speed :
 2 km/h : 0.47 mF, 1 mF
 4 km/h : 2.2 mF, 4.7 mF

Autonomous temperature sensor



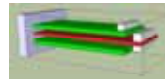
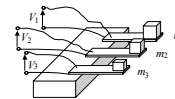
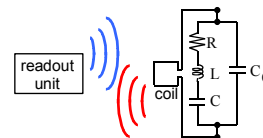
D. Alghisi et al., Sens. Actuat. A 233, 569-581 (2015).

Contents

- Introduction and Motivation
- Piezoelectric Resonant Sensors with Contactless Interrogation
- Piezoelectric Energy Harvesting from Vibration and Motion
- **Conclusions**
- *Back to the roots*

Conclusions

- PZT thick films on different substrates confirmed as versatile elements for **sensors** and **energy harvesting**
- Piezoelectric film resonators with **short-range contactless interrogation** demonstrated as **passive sensors**
- Promising approaches investigated for piezoelectric energy harvesting from **broadband vibrations**:
 - ◆ Multi-Frequency converter arrays
 - ◆ Nonlinear converters
 - ◆ Impact converters
 - ◆ Multi-DoF converters



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Contents

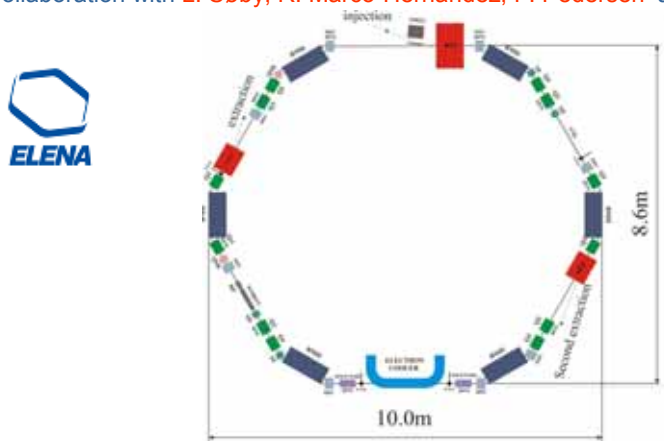
- Introduction and Motivation
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- Conclusions
- **Back to the roots**

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Low-Noise Preamp for BPMs

- Extra Low ENergy Antiproton (ELENA) project at CERN
 - Cascaded to AD ring to decelerate antiprotons to 100 keV for experiments on antimatter

Collaboration with L. Søby, R. Marco-Hernandez, F. Pedersen at CERN.

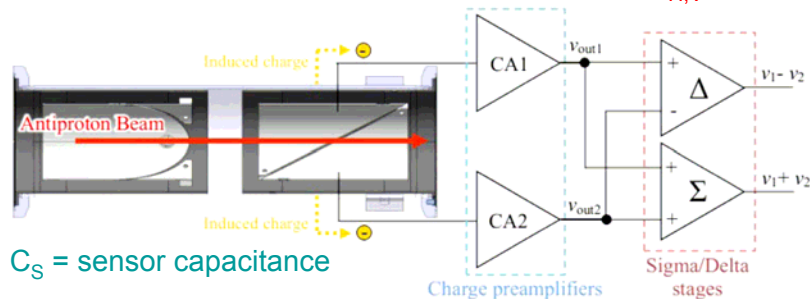


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L. Søby, et al., Proc. IPAC'15, 1061-1064, (2015).

Low-Noise Preamp for BPMs

- Extra Low ENergy Antiproton (ELENA) project at CERN
 - Cascaded to AD ring to decelerate antiprotons to 100 keV for experiments on antimatter
- Electrostatic shoebox beam position monitors (BPM) for horizontal (H) & vertical (V) measurements ($S_{H,V} \approx 110 \mu\text{V}/\text{mm}$)



C_S = sensor capacitance

- Requirements for position and Schottky measurements:
 - RTI noise density $v_{iN} = 0.5 \text{ nV}/\sqrt{\text{Hz}}$ @ $C_S = 20 \text{ pF}$;
 - $\text{BW} = 100 \text{ Hz} \div 40 \text{ MHz}$; $\text{SNR} = 6$ @ $\Delta_{H,V} = 1 \text{ mm}$

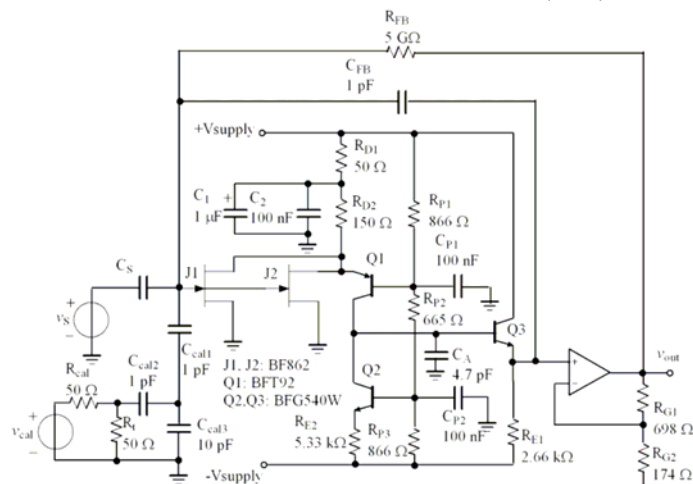
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M. Baù, et al., Procedia Engineering, 120, 1229-1232 (2015).

Low-Noise Preamp for BPMs

- Noise-matched JFET-input charge-sensitive preamplifier
- “Cold” feedback resistor R_{FB} [1]

[1] R. Bassini, C. Boiano A. Pullia, IEEE Trans. Nucl. Sci. 49 (2002).



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◆ Midband voltage gain $A_V @ C_S = 20 \text{ pF} = 100 \text{ (40 dB)}$



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