



# 3D Silicon Radiation Sensors

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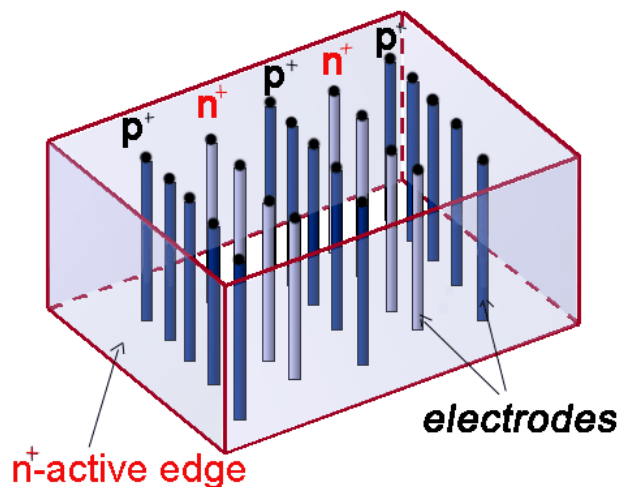


# Outline

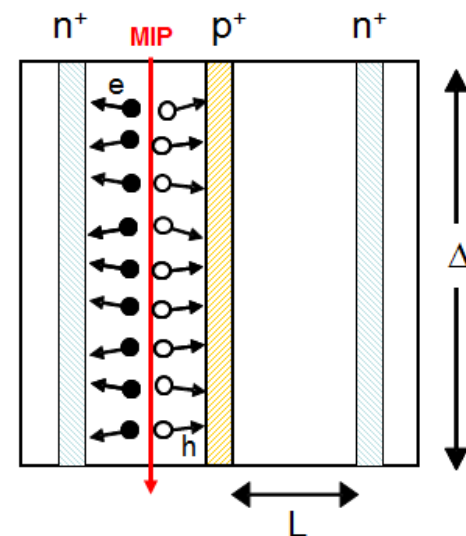
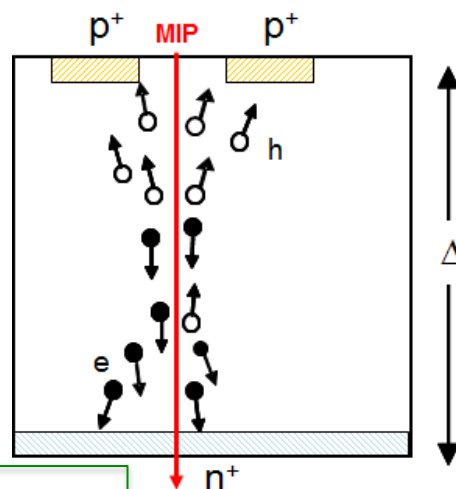
- Introduction
  - Overview of 3D sensors properties and technologies
- The ATLAS IBL project
- On going developments for HL-LHC
- 3D sensors for timing
- Conclusions

# 3D radiation sensors

S. Parker et. Al. NIMA 395 (1997) 328



Electrode distance ( $L$ ) and active substrate thickness ( $\Delta$ ) are decoupled  $\rightarrow L \ll \Delta$  by layout



## ADVANTAGES:

- Low depletion voltage (low power diss.)
- Short charge collection distance:
  - Fast response rise
  - Less trapping probability after irr.
- Lateral drift  $\rightarrow$  cell "shielding" effect:
  - Lower charge sharing
  - Low sensitivity to magnetic field
- Active edges

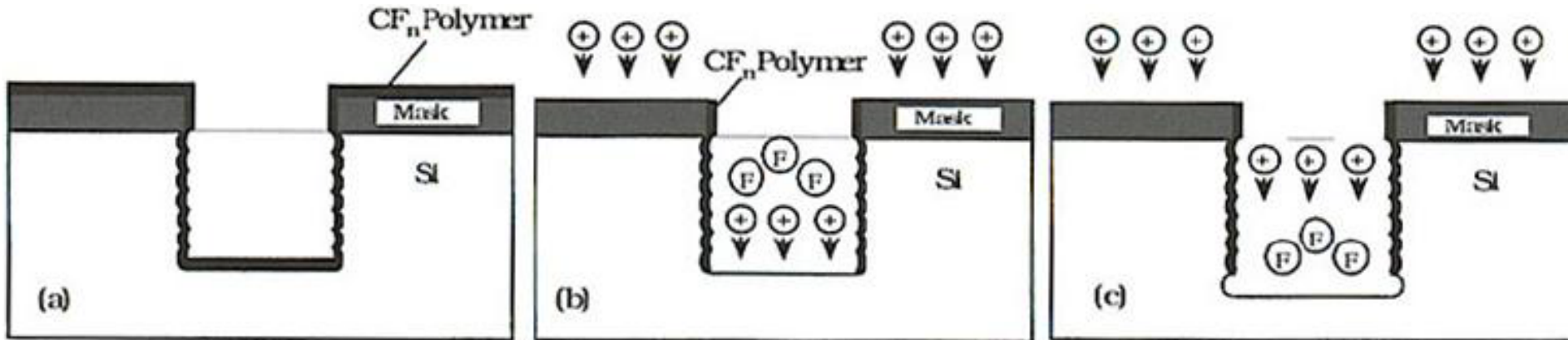


## HIGH RADIATION HARDNESS

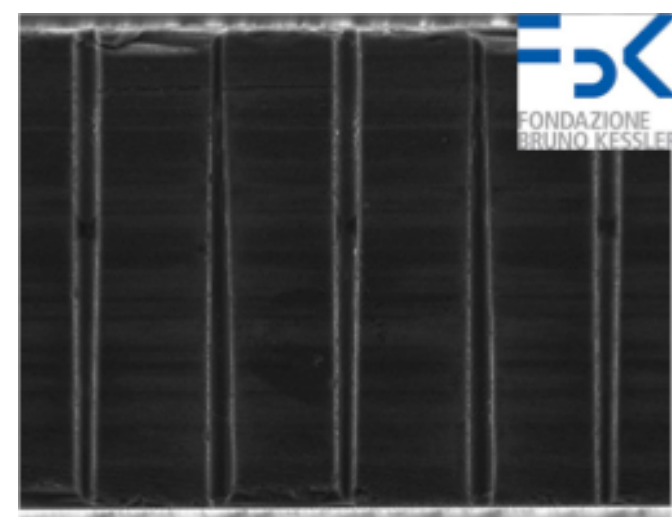
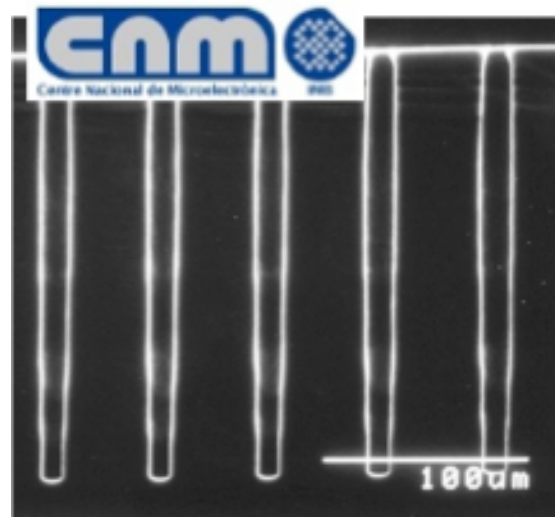
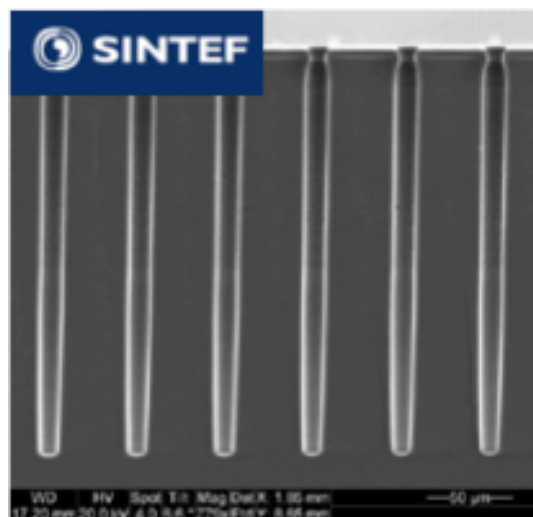
## DISADVANTAGES:

- Non uniform spatial response (electrodes and low field regions)
- Higher capacitance with respect to planar ( $\sim 3\text{-}5\times$  for  $\sim 200\text{ }\mu\text{m}$  thickness)
- Complicated technology (cost, yield)

# Key technology: DRIE by the Bosch process



- Alternating etch cycles ( $SF_6$ ) and passivation cycles ( $C_4F_8$ )
- High aspect ratio (>20:1 or better for trenches) and good uniformity



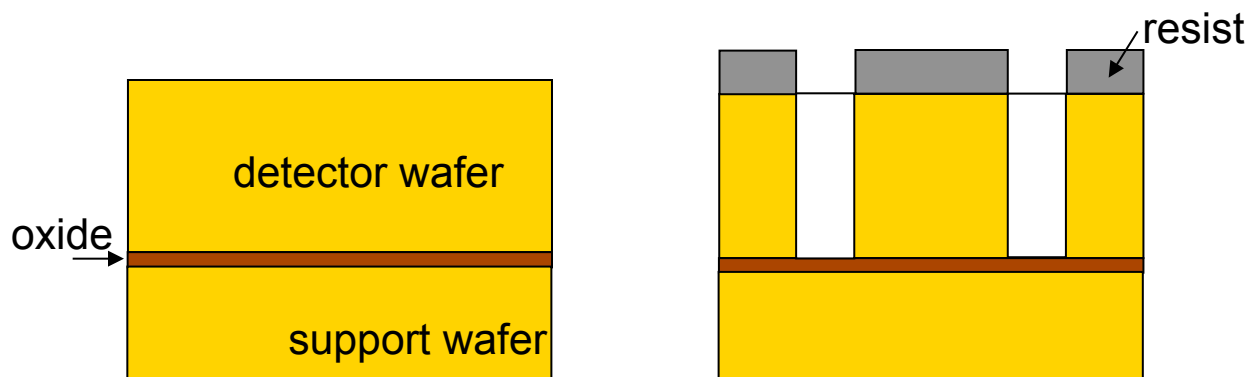


# Original full-3D process

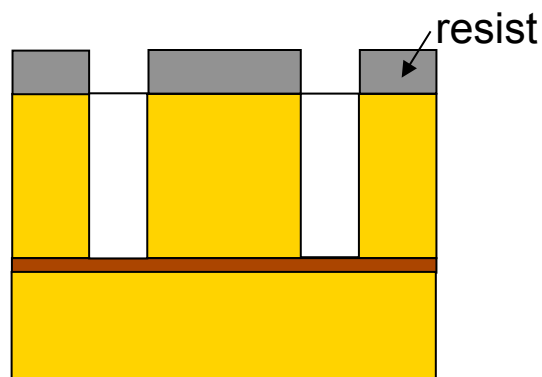
C. Kenney et al., IEEE TNS, vol. 46, n. 4 (1999) 1224

T.E. Hansen et al., JINST 4 (2009) P03010

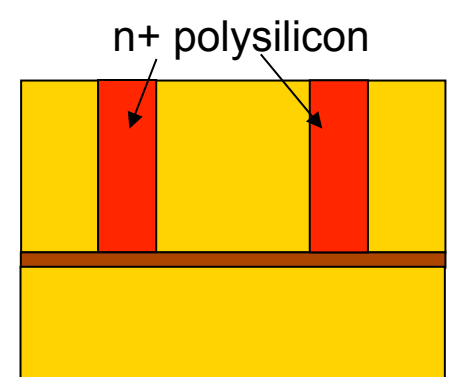
**3DC**ONSORTIUM



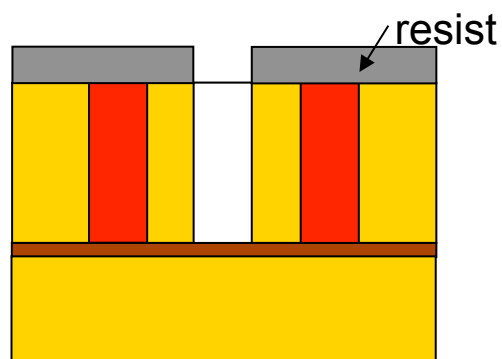
1) wafer bonding



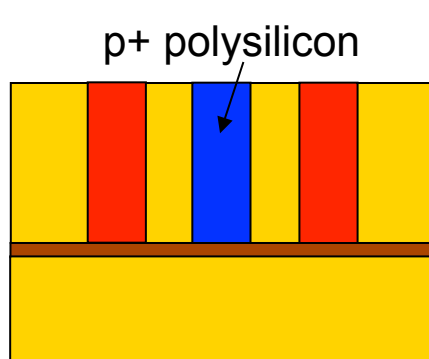
2) n+ hole definition and etching



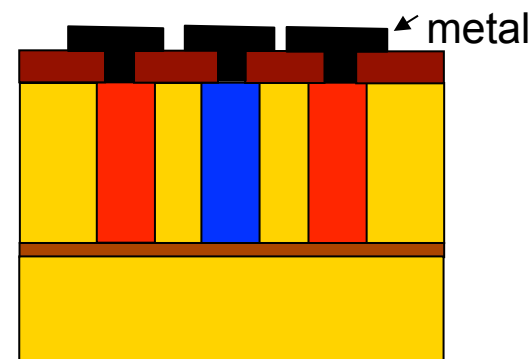
3) hole doping and filling



4) p+ hole definition and etching



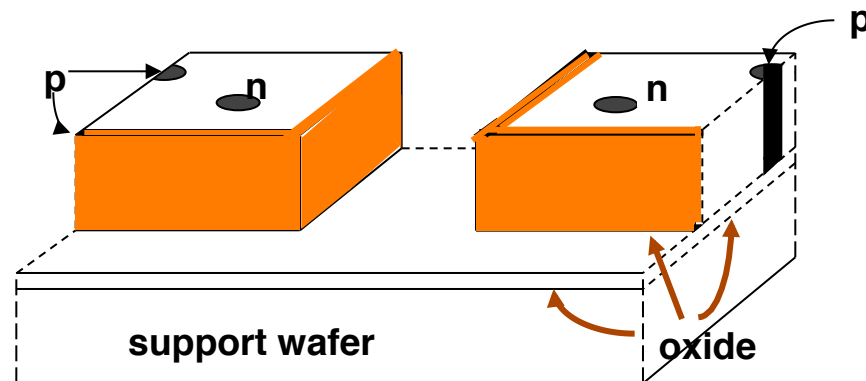
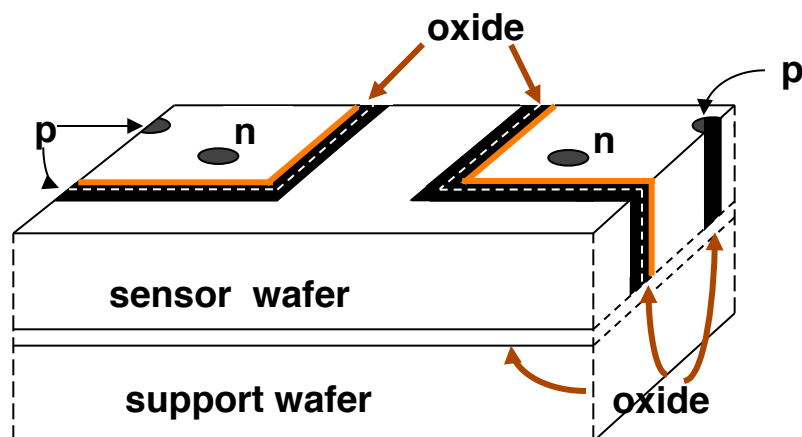
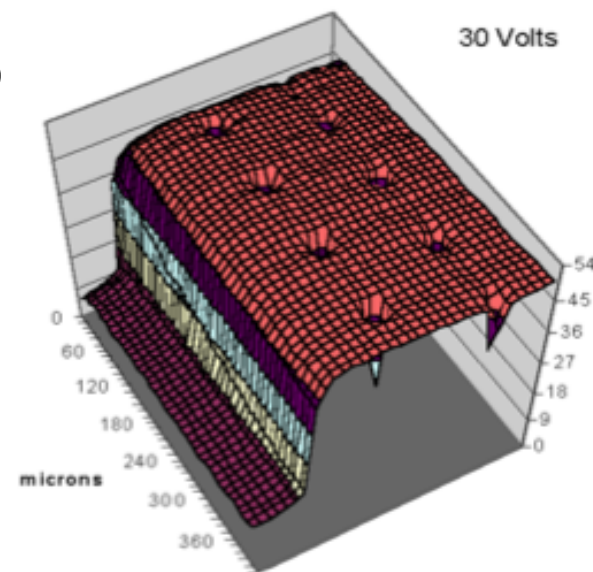
5) hole doping and filling



6) Metal deposition and definition

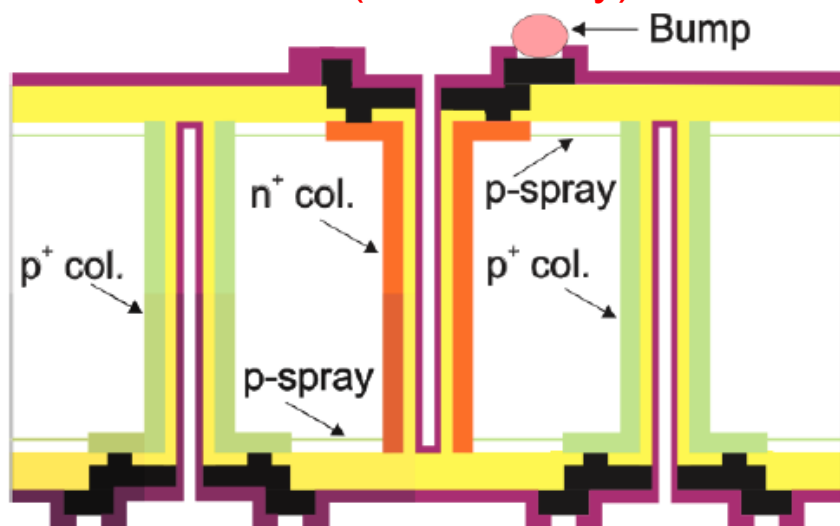
## Active edges

- First introduced at Stanford as an extension of 3D sensor technology, later applied to planar sensors
- Cut lines are not sawed but etched with DRIE & doped as electrodes, arbitrary shapes possible
- Sensitivity up to a few  $\mu\text{m}$  from the physical edge, at the expense of additional process complication



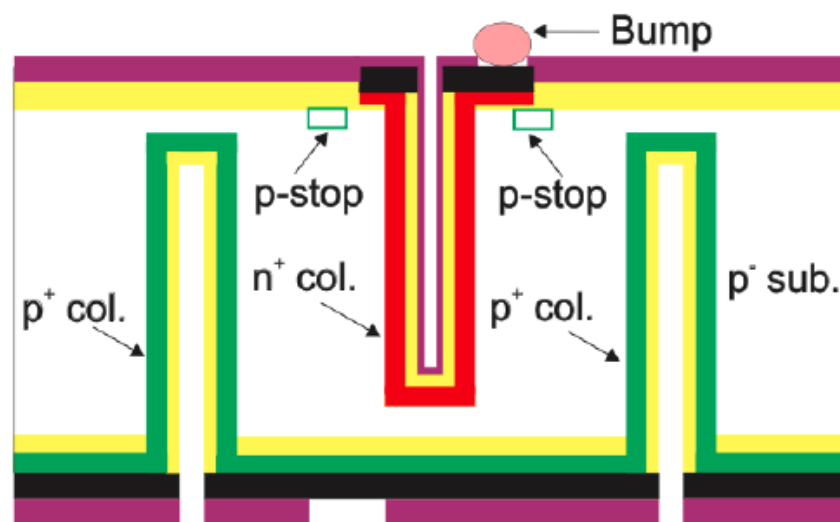
# Double-sided 3D sensors

FBK (Trento, Italy)



oxide metal passivation  
p- Si p+ Si n+ Si

CNM (Barcelona, Spain)



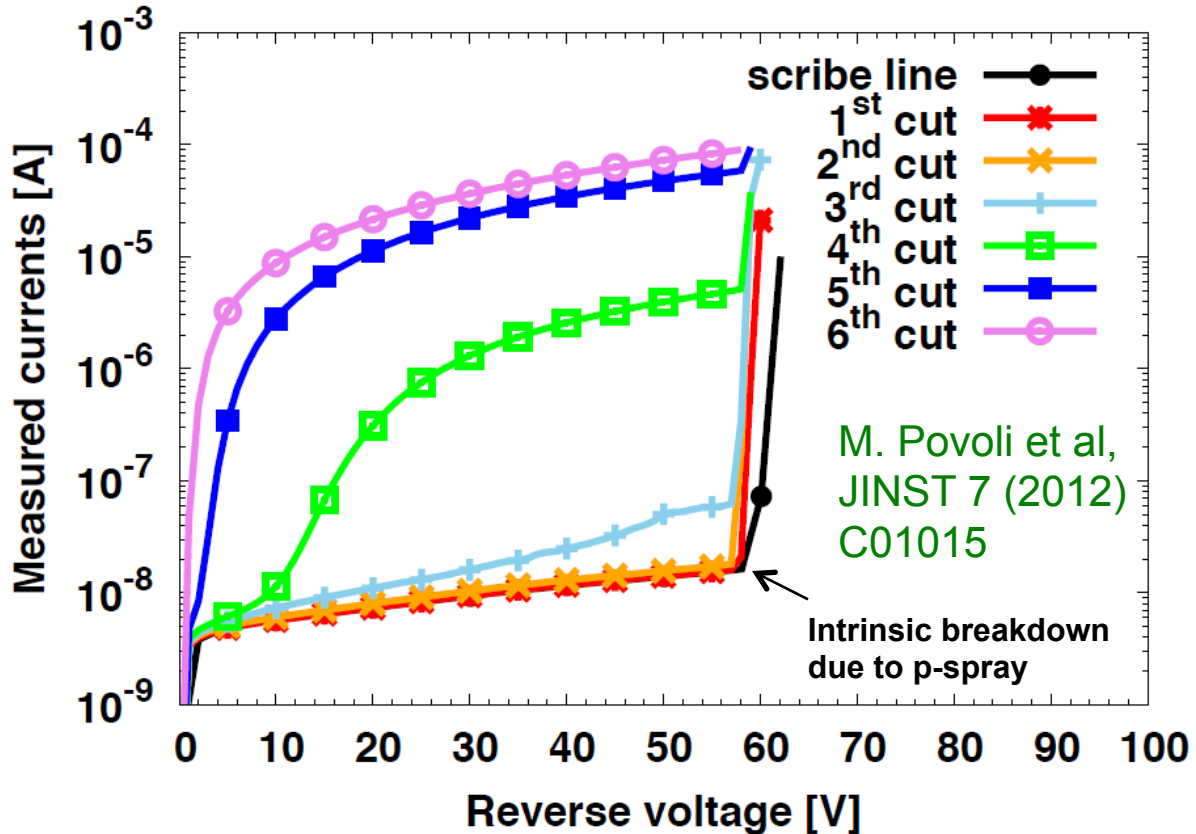
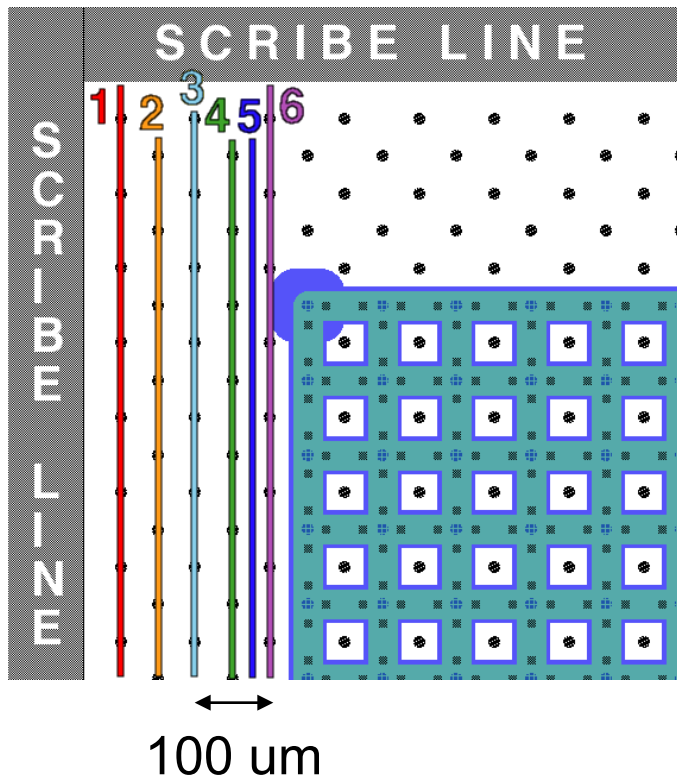
oxide metal passivation  
p- Si p+ poly-Si n+ poly-Si p+ Si

A. Zoboli et. al., IEEE TNS 55(5) (2008), 2775  
G. Giacomini, et al., IEEE TNS 60(3) (2013) 2357

G. Pellegrini et. al. NIMA 592(2008), 38  
G. Pellegrini et. al. NIMA 699(2013), 27

- Do not use support wafer → reduced process complexity
- Back-side accessible → Easier assembly within a detector system
- Active edge not feasible → Slim edge

# Slim edge in double-sided 3D sensors



- Repeated cuts starting from scribe-line, each one closer to the active area (the 6<sup>th</sup> cut dices the last row of ohmic columns of the active area)
  - Devices can be safely operated up to the 3<sup>rd</sup> cut (i.e., with only one row of ohmic columns beyond the active area)
- There's room for design optimization (dead region < 100 micron)

# 3D Signal Efficiency: a comparison

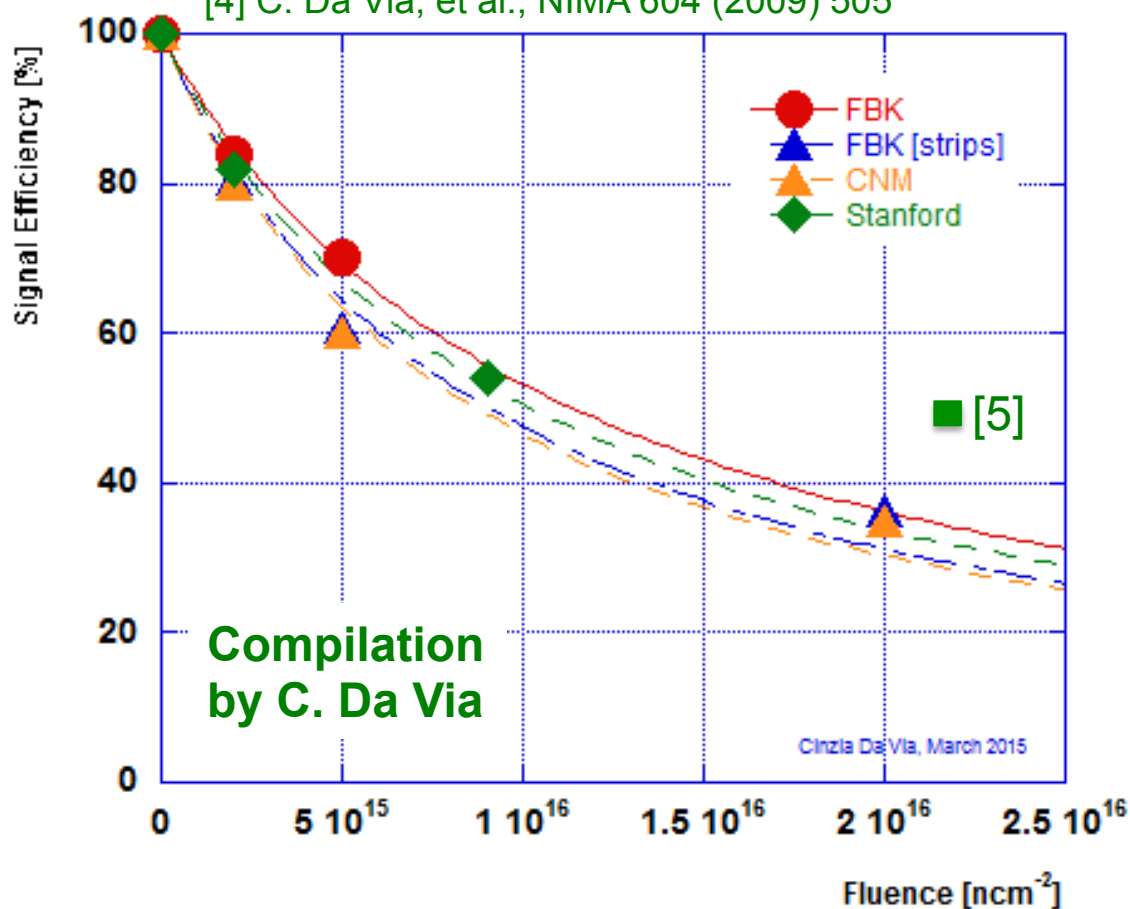
Data from:

[1] ATLAS IBL Collaboration, JINST 7 (2012) P11010

[2] G.-F. Dalla Betta, et al., NIMA 765 (2014) 155

[3] M. Koehler et al. NIMA 659 (2011) 272

[4] C. Da Via, et al., NIMA 604 (2009) 505



Signal Efficiency =  
Ratio of max. signal  
after irradiation  
and before irradiation

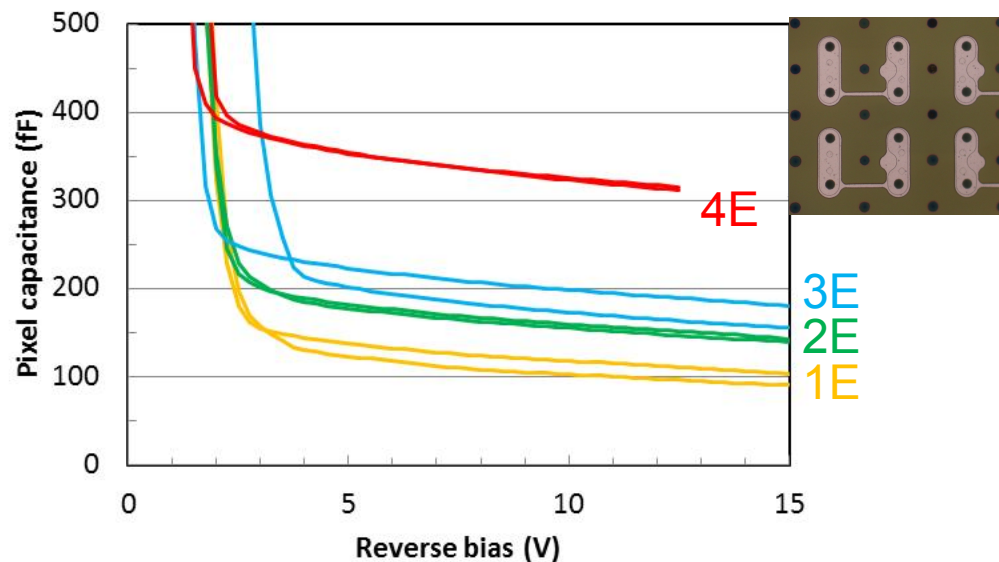
$$SE = \frac{1}{1 + 0.6L \frac{K_{\tau}}{v_D} \Phi}$$

C. Da Via, S. Watts,  
NIMA 603 (2009) 319

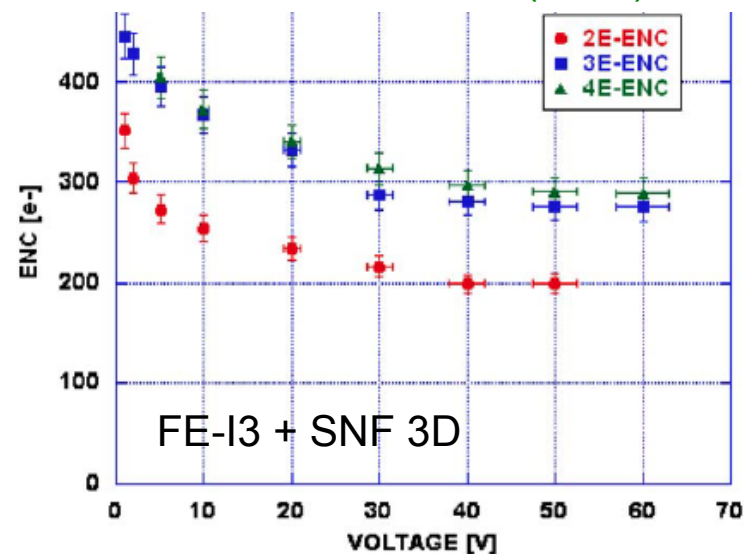
[5] I. Haughton et al.,  
NIMA 806 (2016) 425



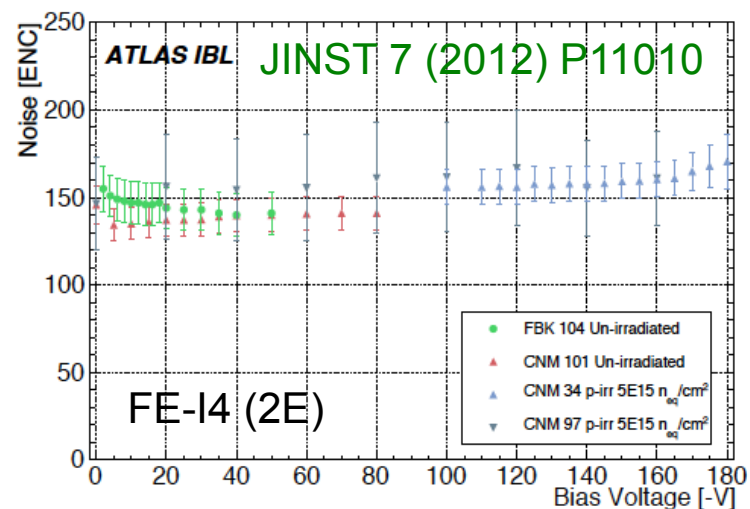
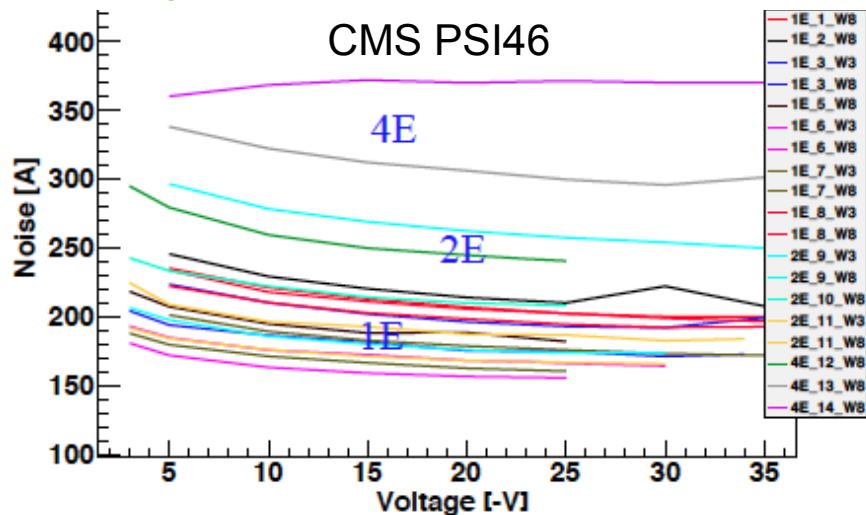
# Capacitance and noise



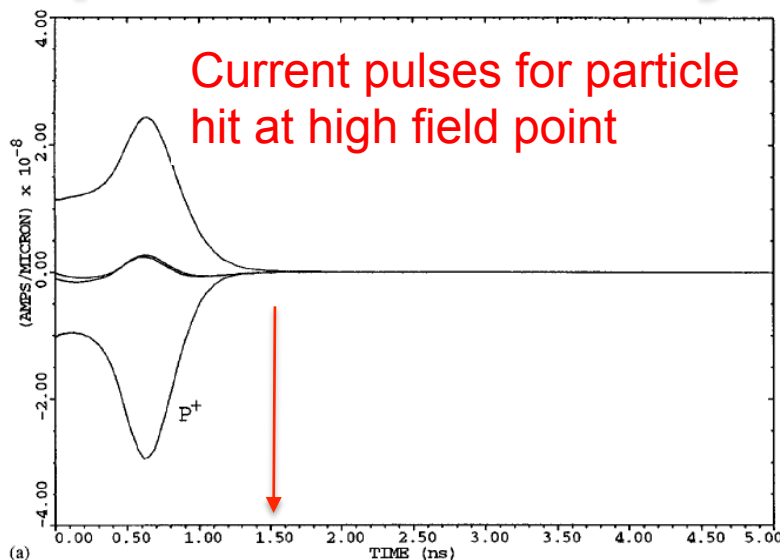
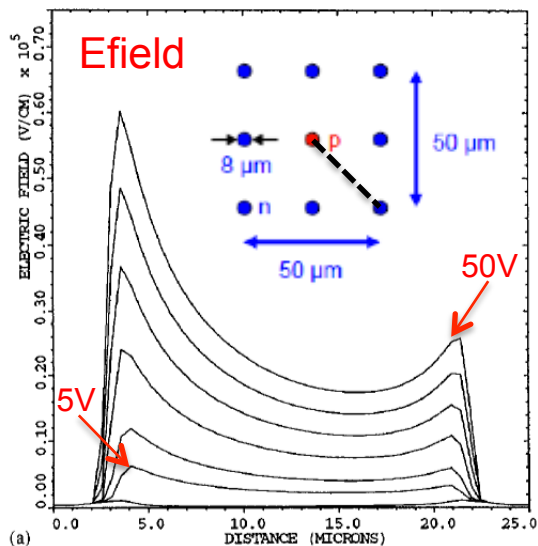
C. Da Via et al. NIMA 604 (2009) 505



E. Alagoz et al. JINST 7 (2012) P08023

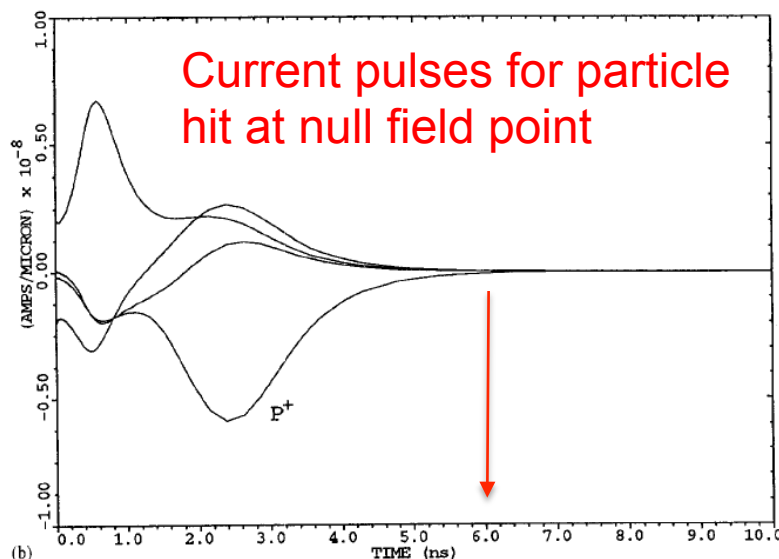
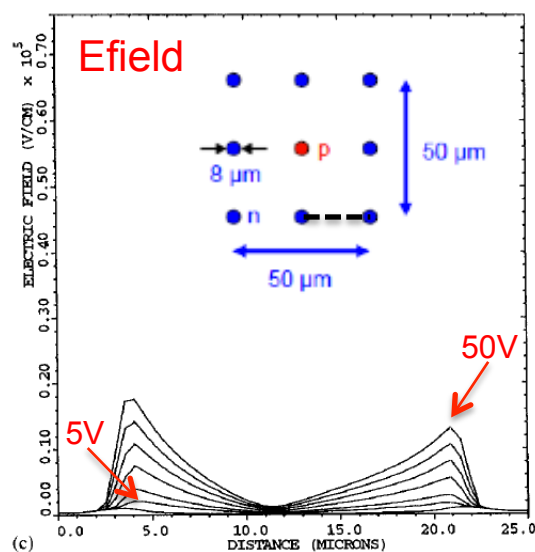


# Null field points and delayed signals



**S. Parker et al.**  
**NIMA395 (1997) 328**

- 3D structure implies null field points in between columnar electrodes of the same doping type
- Carriers generated at null field points first have to diffuse before drifting, thus delaying signals
- This can be improved with trenched electrodes, but at the expense of higher capacitance and reduced geometrical efficiency

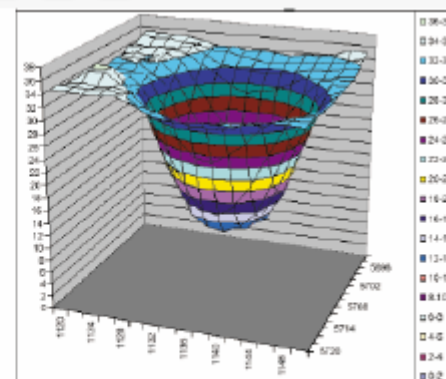
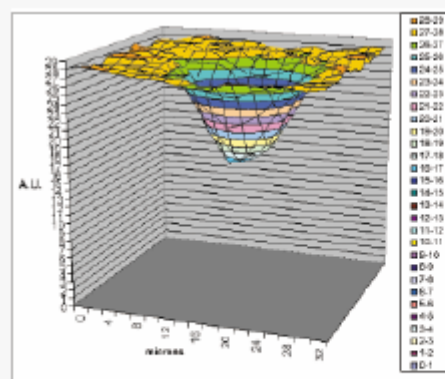
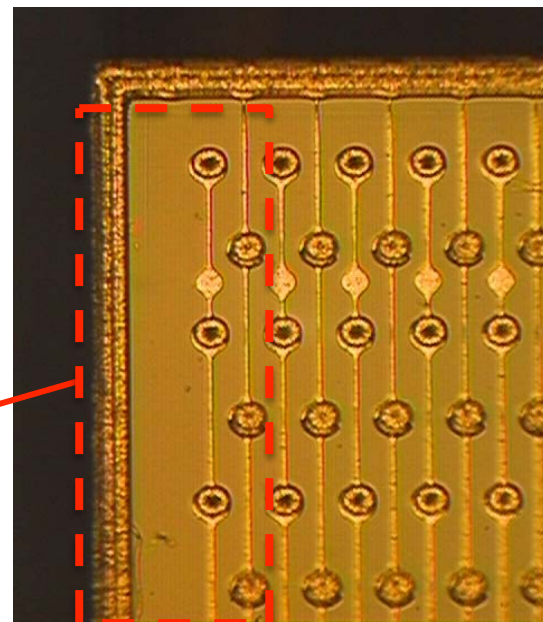
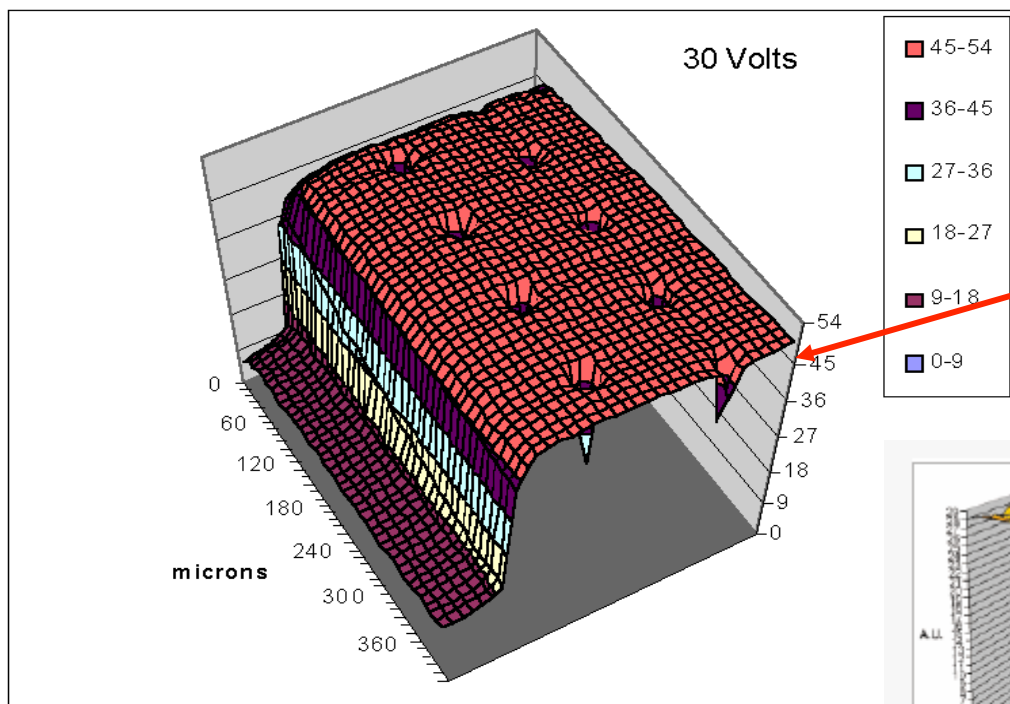




# Poly-Si electrode inefficiency

J. Hasi, PhD thesis, Brunel, 2004

Electrode response using 12 keV X-ray beam  
(ALS at LBNL), beam size  $\sim 2\mu\text{m}$



- Diffusion, lifetimes (poly-Si grain sizes)
- Oxide barrier effect at the interfaces ...
  - Replace  $\text{POCl}_3$  with  $\text{PH}_3$
  - Replace  $\text{BBr}_3/\text{O}_2$  with  $\text{B}_2\text{H}_6$

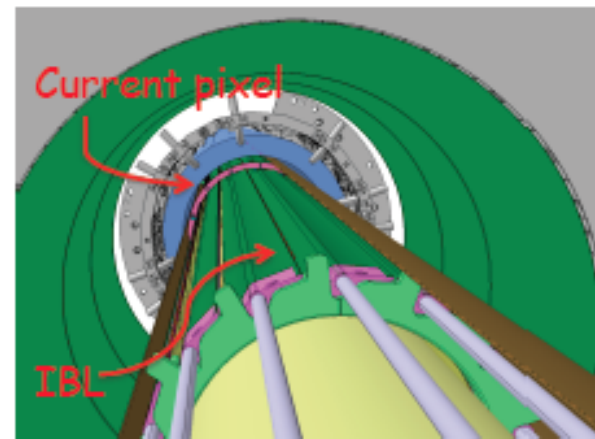


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- Introduction
  - 3D sensors and related technologies
- The ATLAS IBL project
- On going developments for HL-LHC
- 3D sensors for timing
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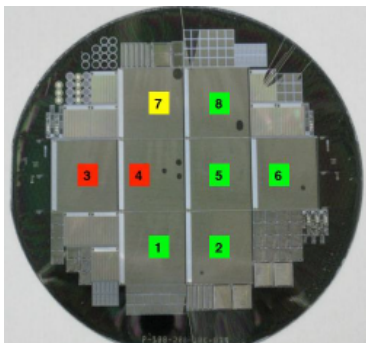
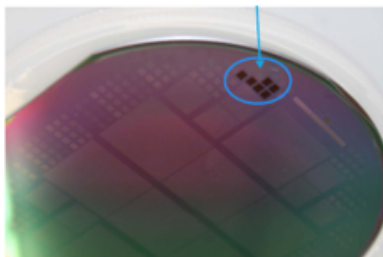
# The ATLAS 3D Sensor Collaboration

- Approved by CERN in 2007 for the “Development, Testing and Industrialization of Full-3D Active-Edge and Modified-3D Silicon Radiation Pixel Sensors with Extreme Radiation Hardness”.
- It includes **18 Institutions and 4 processing facilities**: SNF, SINTEF, CNM, and FBK.
- Major efforts devoted to the **Insertable B-Layer (IBL) of the ATLAS detector at LHC**:
  - First application of 3D sensors in a High Energy Physics experiment
  - First medium volume production accomplished in due time and with reasonably good yield

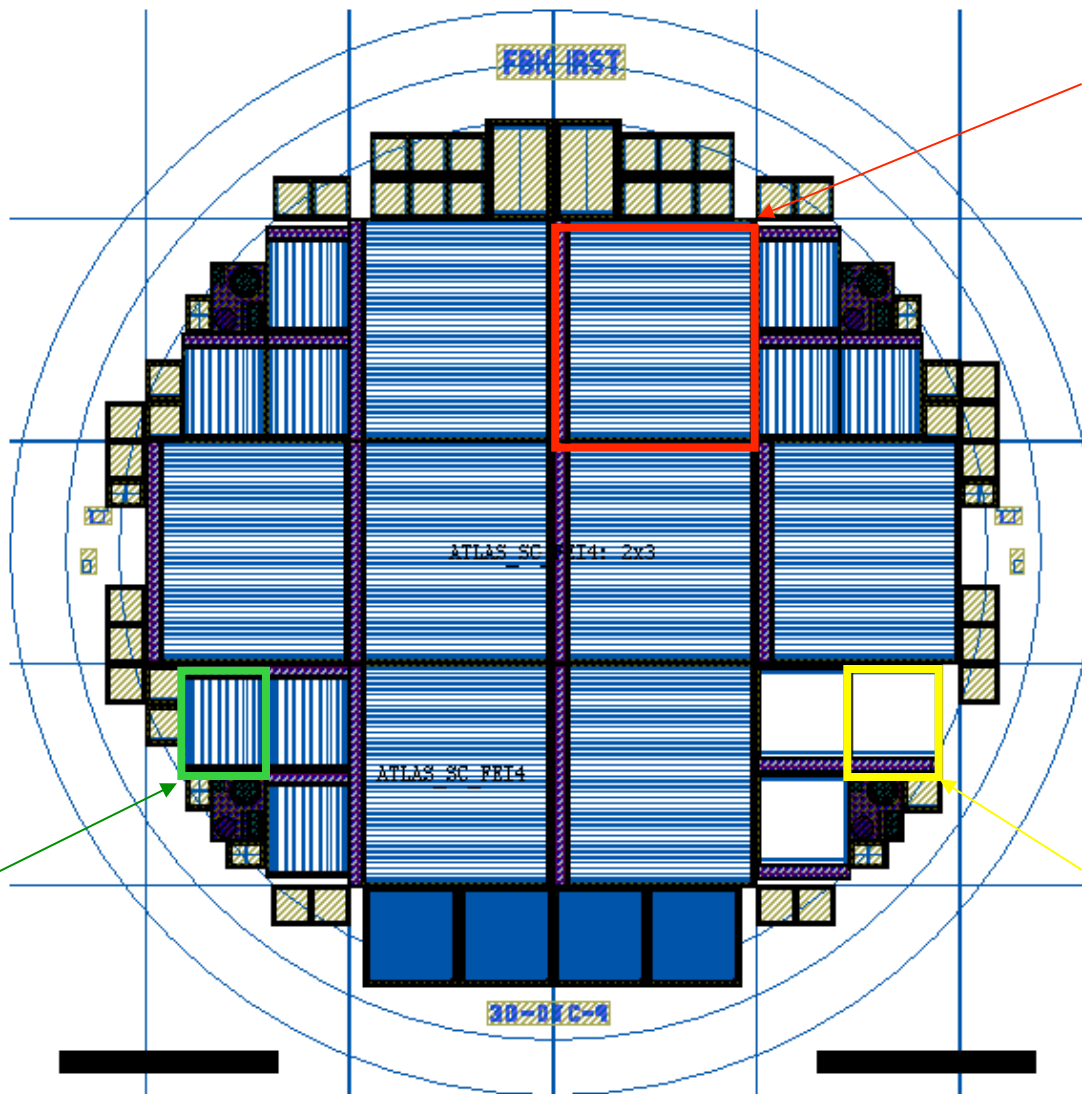


# ATLAS IBL 3D common floor-plan

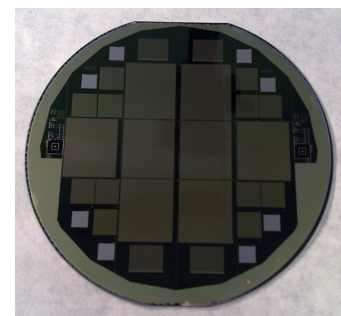
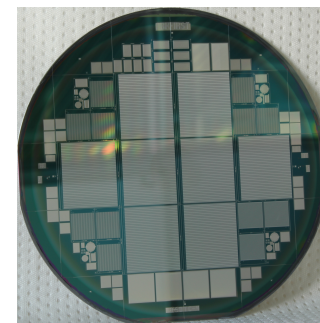
Test structures at the periphery



FE-I3 (9x)



FE-I4 (8x)



CMS (3x)

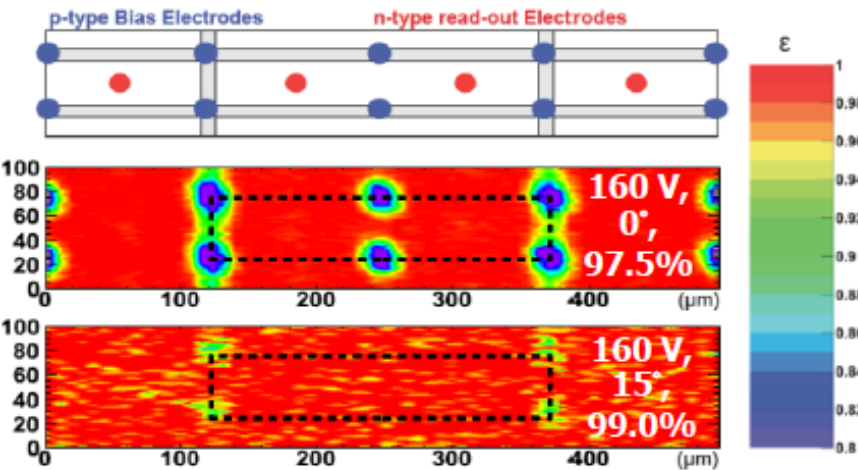


# IBL 3D Performance – Radiation Hardness

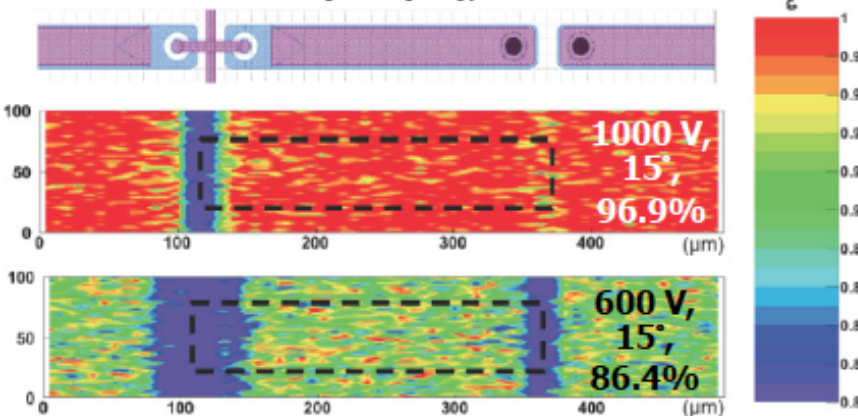
J. Lange, PIXEL 2015

## Sub-Pixel Efficiency at $5 \times 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$

CNM 3D Sensors (230  $\mu\text{m}$ ), Thr. 1500 e



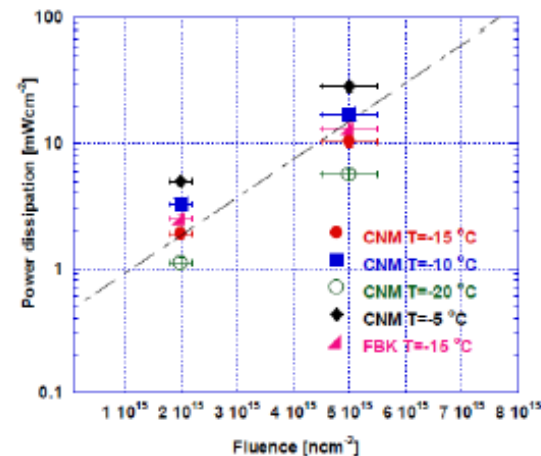
Planar Sensors (200  $\mu\text{m}$ ), Thr. 1400-1600 e



ATLAS IBL Coll., JINST 7 (2012) P11010

- Radiation hardness tested up to  $5 \times 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$
- 3D sensors
  - **Fully efficient at 160 V** and 15° angle
  - Mean efficiency 1-2% lower at normal incidence due to columns
  - Power dissipation  $< 15 \text{ mW}/\text{cm}^2$  at  $T = -15^\circ \text{C}$
- Planar sensors
  - Need 1000 V for similar efficiency
  - Power dissipation  $\sim 90 \text{ mW}/\text{cm}^2$  at  $T = -15^\circ \text{C}$

→ **operational advantage for 3D sensors**





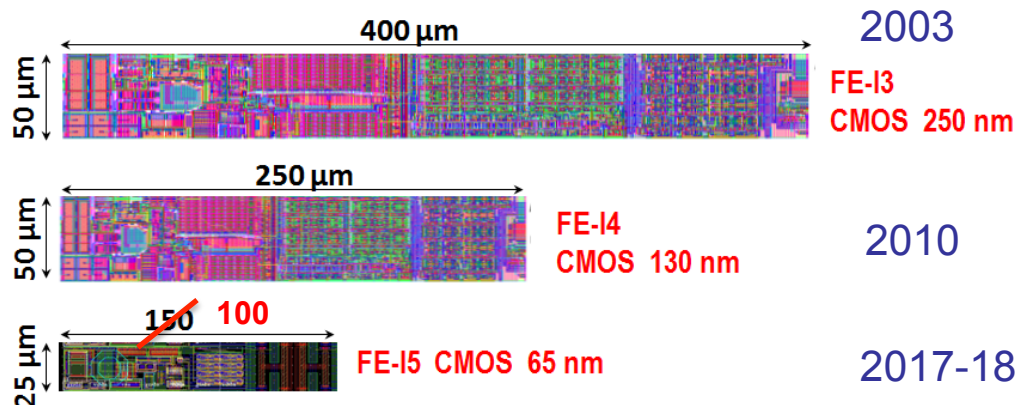
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# Pixel Roadmap LHC → HL-LHC

N. Wermes, 9<sup>th</sup> TN Workshop (Genova, 2014)

ATLAS roadmap → Pixel Size



Increased luminosity requires

- higher hit-rate capability
- increased granularity
- higher radiation tolerance
- lighter detectors

Next ROC generation (RD53 65 nm)

50x50  $\mu\text{m}^2$  and 25x100  $\mu\text{m}^2$  pixels

$C_{\text{DET}} \leq 100$  fF

$I_{\text{leak}} \leq 10$  nA/pixel (no amp. comp.)

Threshold:  $\sim 1000$  electrons

## Implications for 3D sensors

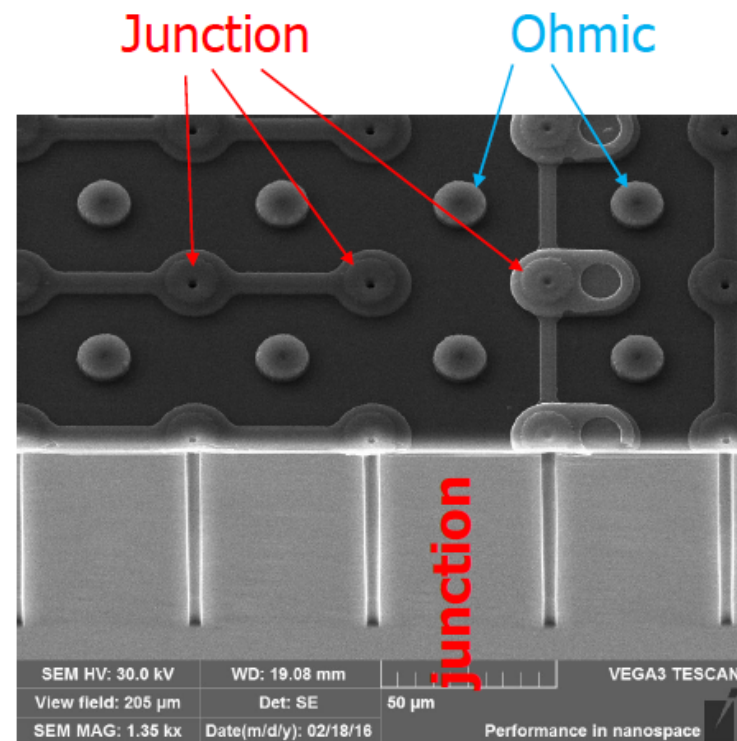
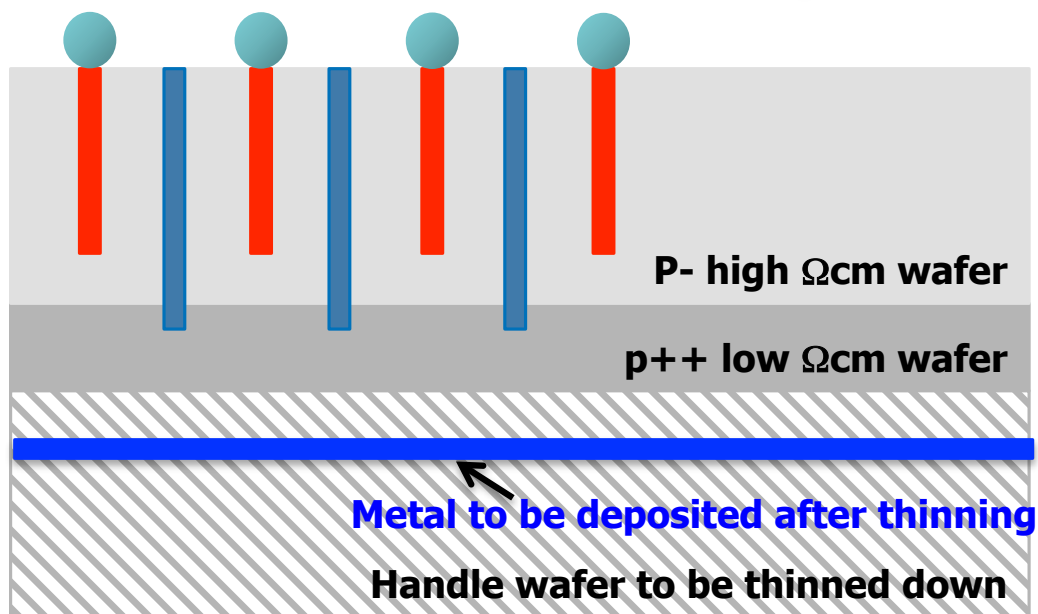
Modified technology/design for:

- thinner sensors
- narrower electrodes
- reduced electrode spacing
- very slim (or active) edges

- HL-LHC ATLAS and CMS Pixel TDR: 2017
- 3D pixels are an option for the innermost layers



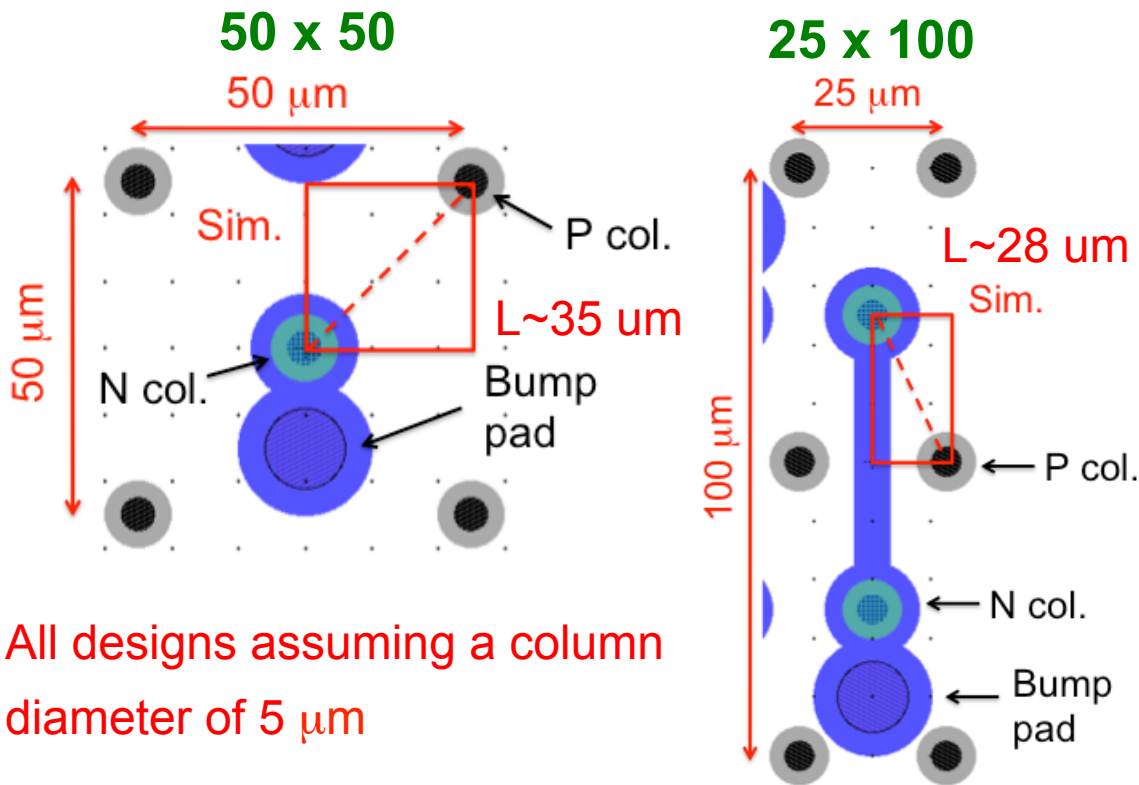
## New 3D pixels: fabrication



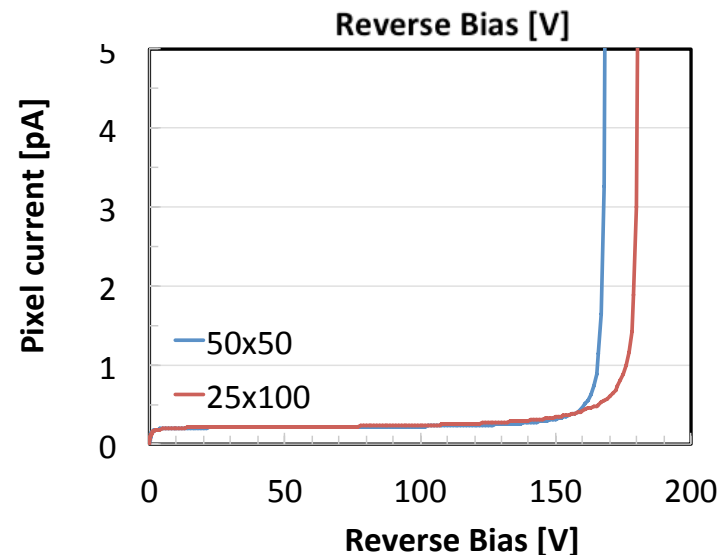
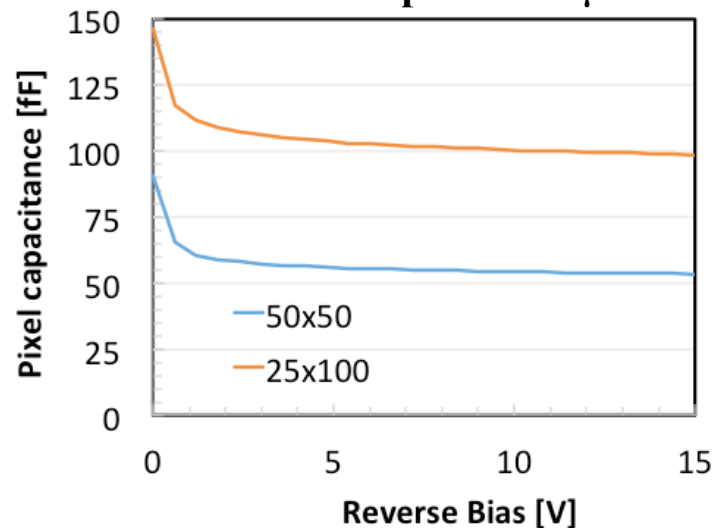
- Thin sensors on support wafer (SiSi)
- Ohmic columns/trenches depth  $>$  active layer depth (for bias)
- Junction columns depth  $<$  active layer depth (for high  $V_{bd}$ )
- Reduction of hole diameters to  $\sim 5 \mu\text{m}$
- Holes (at least partially) filled with poly-Si

**INFN-FBK**  
**“RD\_FASE2”**  
**Project (CSN1)**

# New 3D pixels: design and simulations



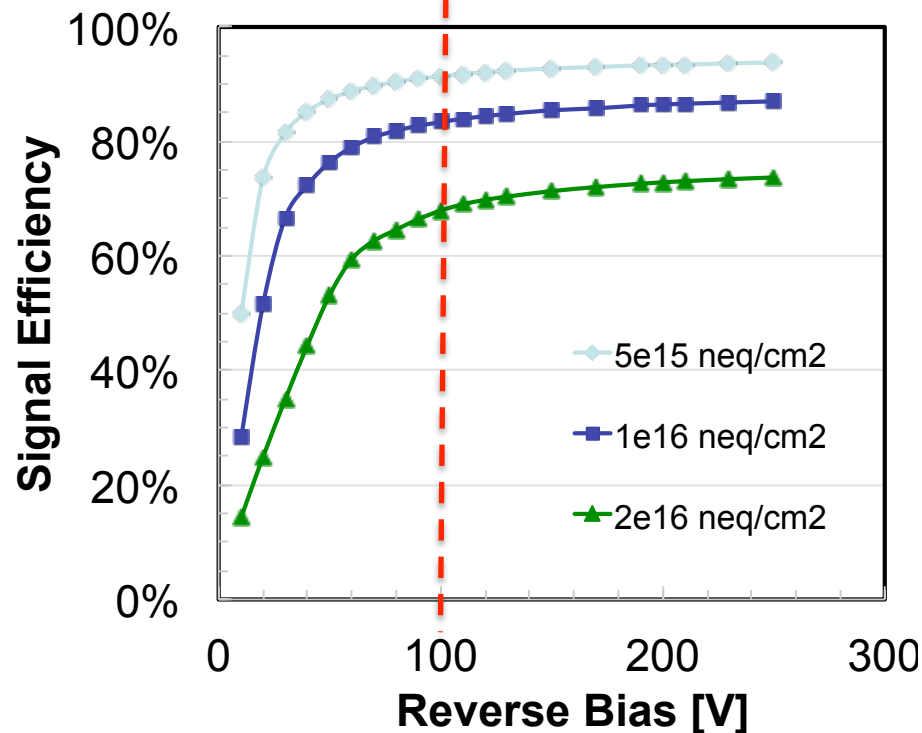
Thickness = 150  $\mu\text{m}$   
N+ col. depth = 130  $\mu\text{m}$



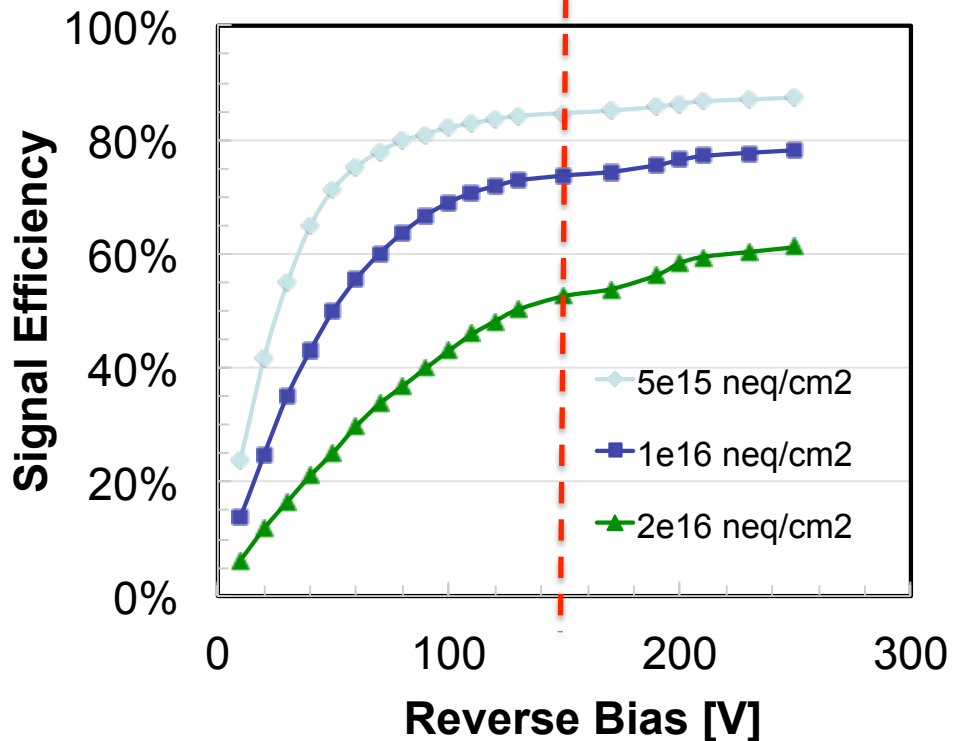
- 50x50 design safe, 25x100 is difficult ... too little clearances (new ideas for bump pad to be tested)
- Capacitance compatible with RD53 specs
- Initial breakdown voltage high enough

# Simulated signal efficiency (preliminary)

25 x 100 (2E)



50 x 50 (1E)

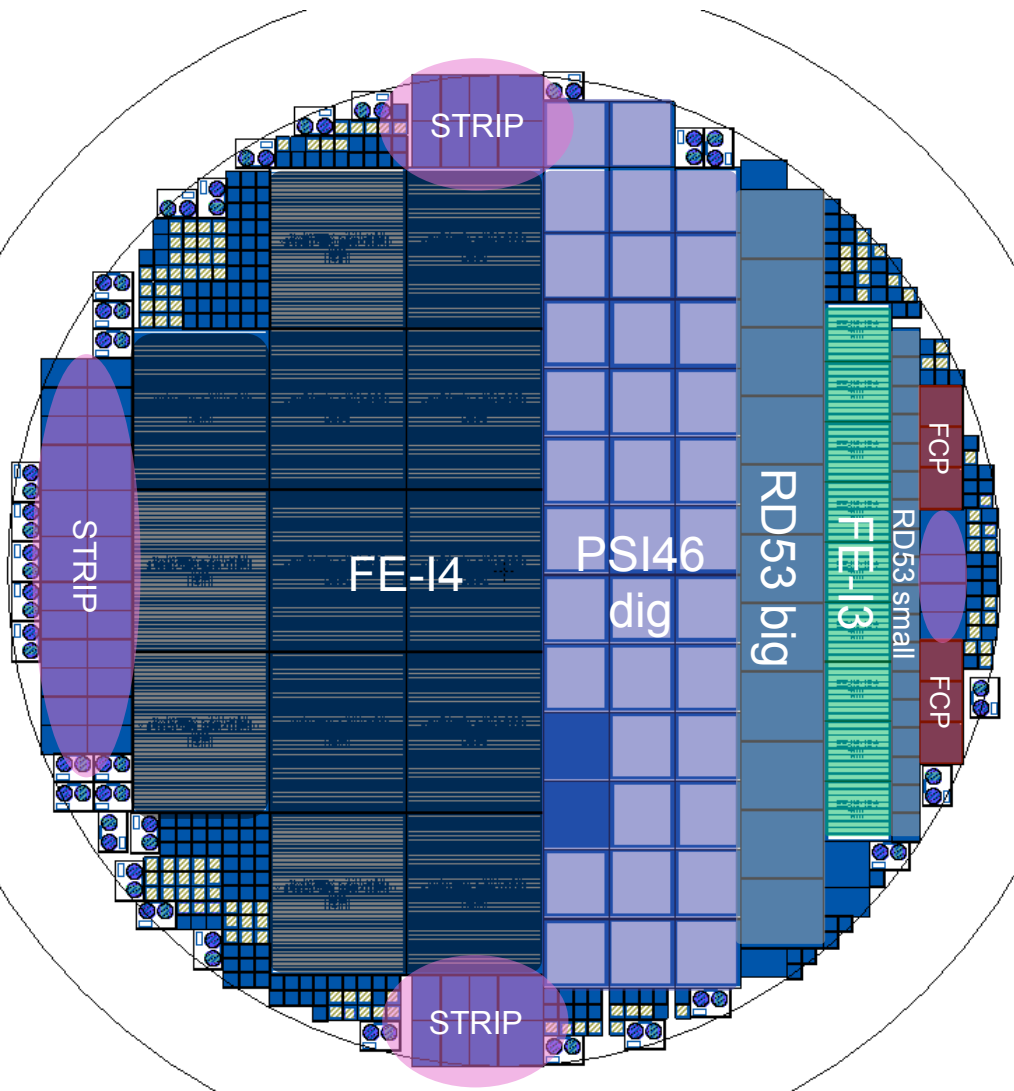


- New 3-trap level “Perugia” model [D. Passeri et al. \(doi:10.1016/j.nima.2015.08.039\)](https://doi.org/10.1016/j.nima.2015.08.039)
- 1  $\mu\text{m}$  thick ( $\sim 2d$ ) slice, with MIP vertical hits at many different points
- 20-ns integration of current signals  $\rightarrow$  normalization to injected charge  $\rightarrow$  average
- Higher Signal Efficiency at lower  $V_{\text{bias}}$  in 25x100 (2E), as expected due to smaller  $L$

# 3D Pixel Wafer Layout

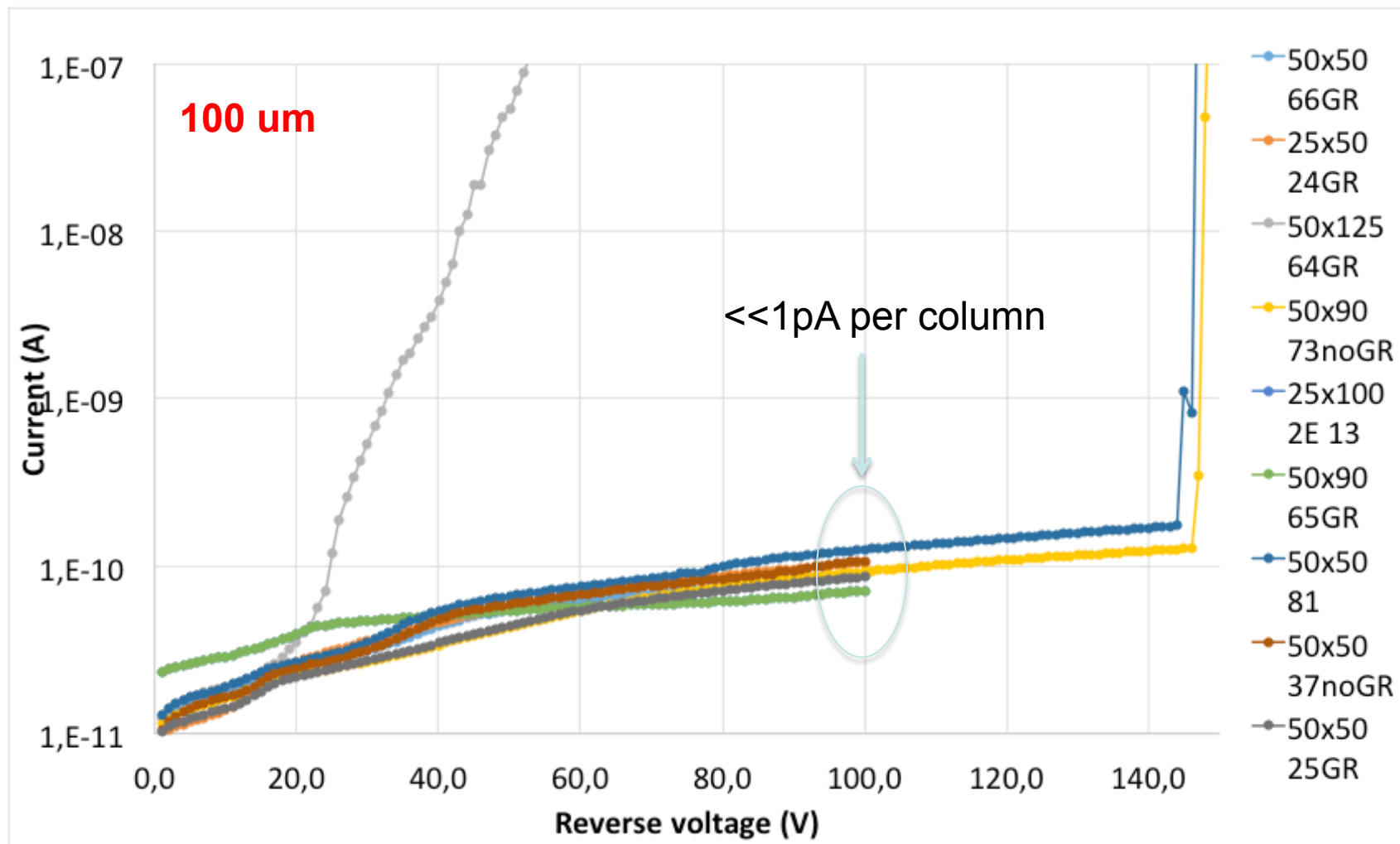
Many different pixel geometries and pitch variations:

- **FE-I4**
  - 50 x 250 (2E) std
  - 50 x 50 (1E)
  - 25 x 100 (1E and 2E)
  - 25 x 500 (1E)
- **FE-I3**
  - 50 x 50 (1E)
  - 25 x 100 (1E and 2E)
- **PSI46dig**
  - 100 x 150 (2E and 3E) std
  - 50 x 50 (1E and 2E)
  - 50 x 100, 100 x 100 (2E + 4E)
  - 50 x 100, 100 X 150 (2E + 6E)
  - 25 x 100 (1E and 2E)
- **FCP**
  - 30 x 100 (1E)
- **RD53**
  - 50 x 50 (1E)
  - 25 x 100 (1E)
  - 25 x 100 (2E)

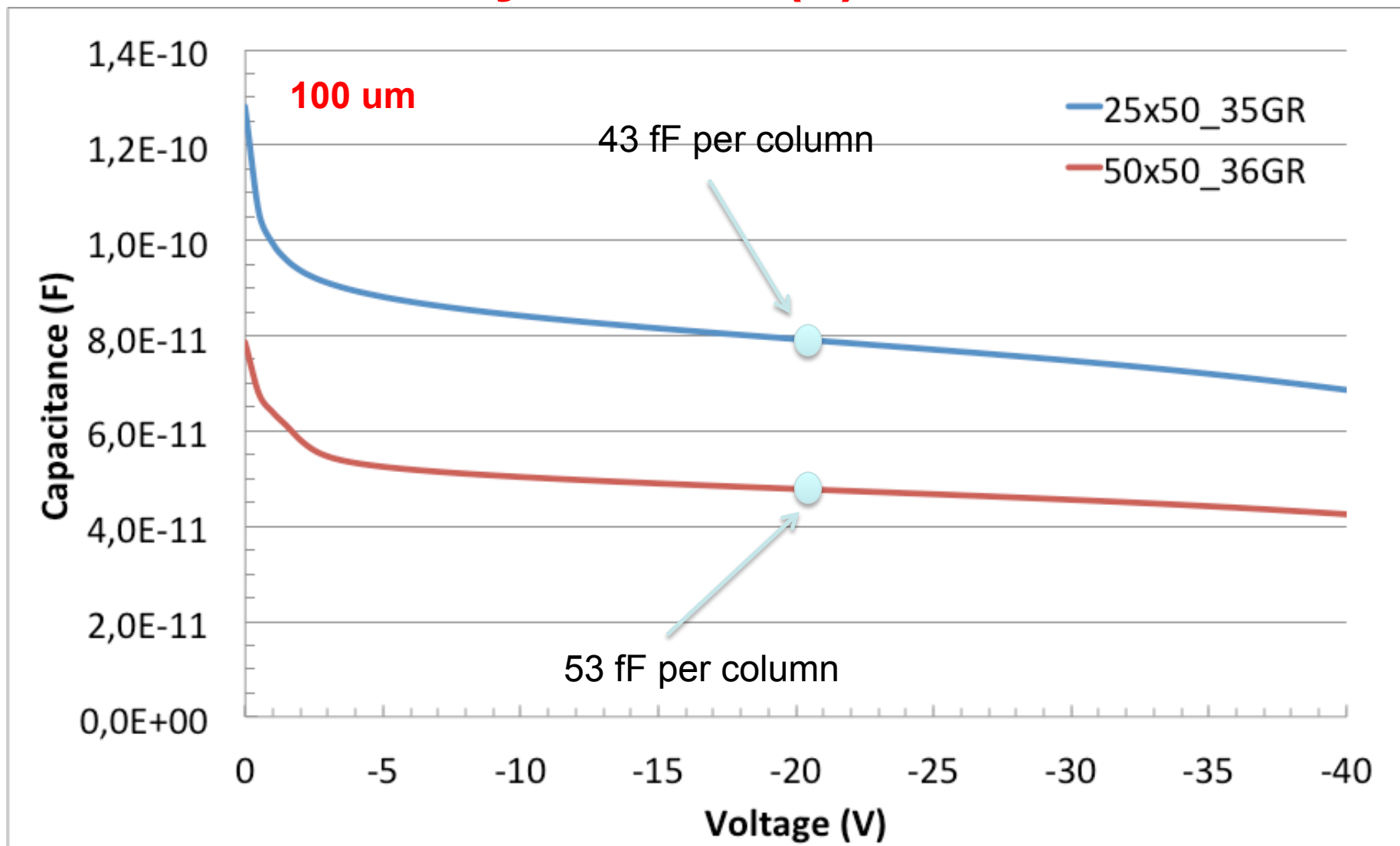


+ Test structures (strip, diodes, etc)

# Preliminary results (1): W48 diode IV

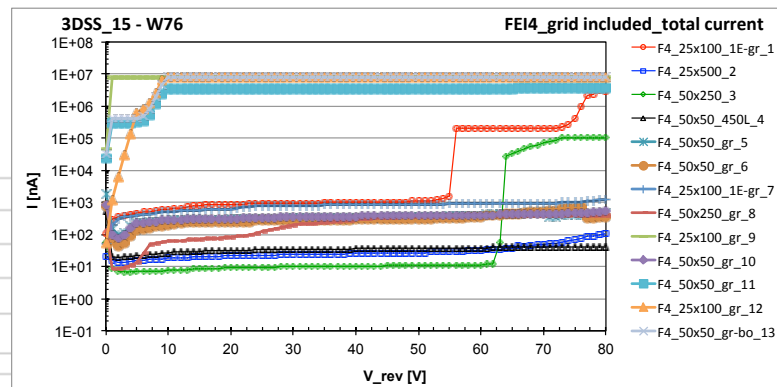
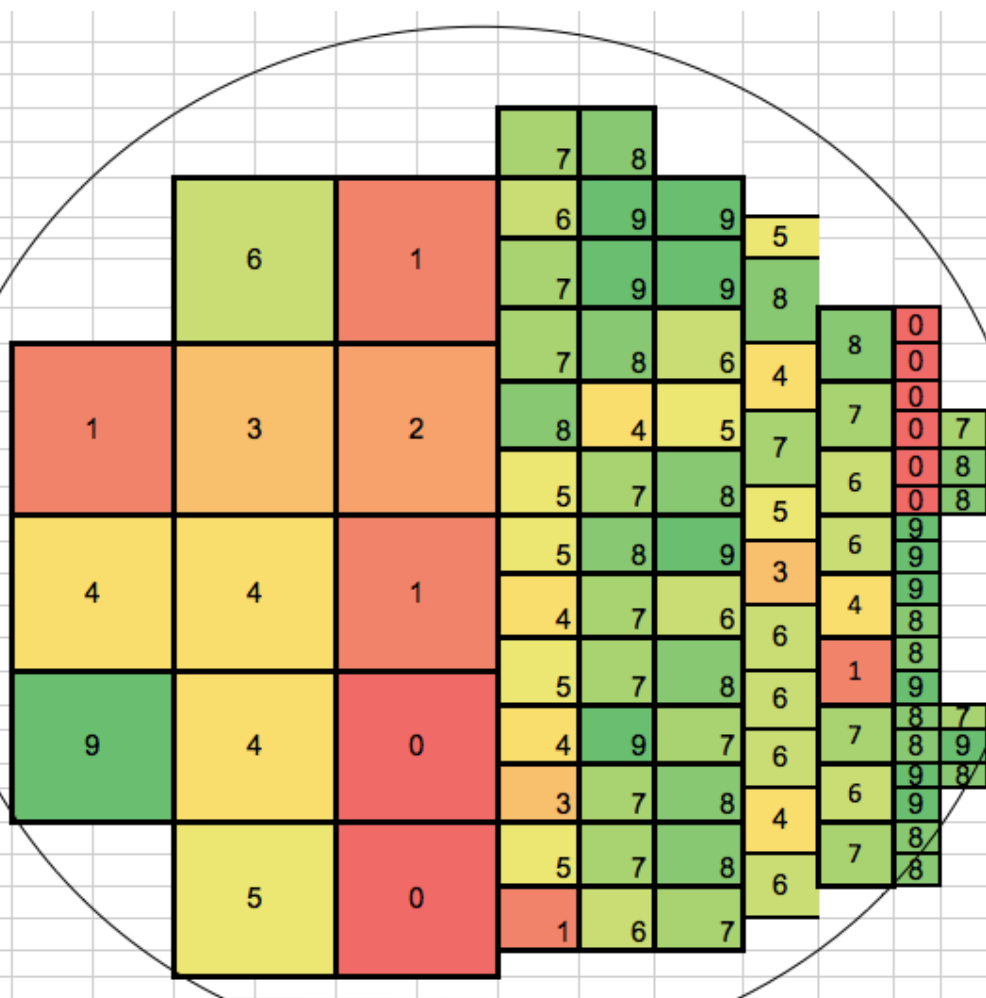


## Preliminary results (2): W48 diode CV



# Automatic tests

Numbers of good detectors per type on 9 wafers



- Good electrical characteristics in terms of leakage current, breakdown voltage and capacitance, in good agreement with simulations
- Process Yield ~38% on large sensors (FEI4), >60% on all others
- Best two wafers (76&78) at Selex for bump bonding





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di Trento

G.-F. Dalla Betta

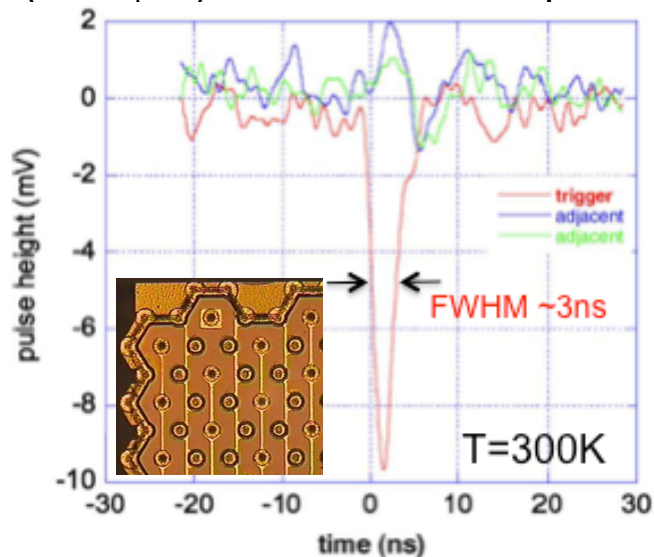
27

Bologna, June 10, 2016

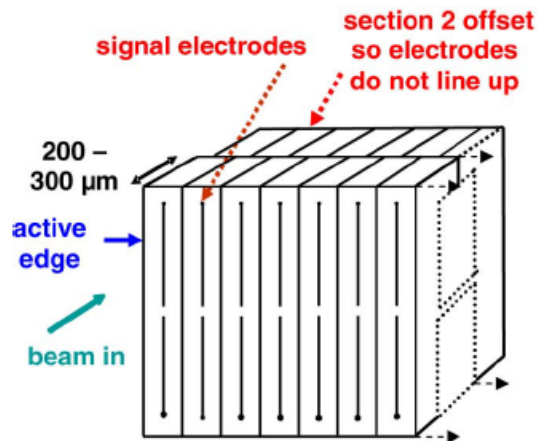


# Timing with 3D

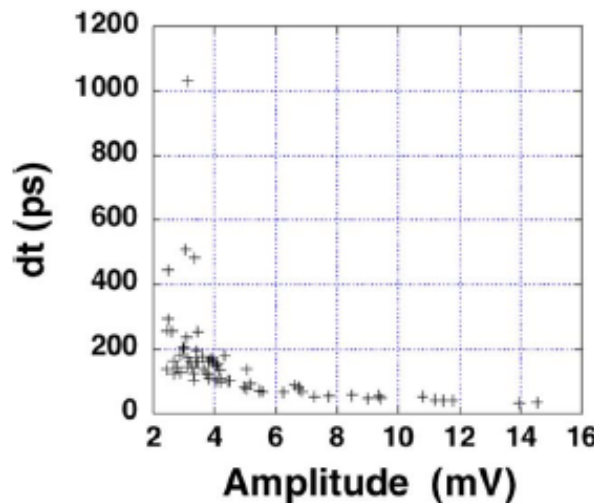
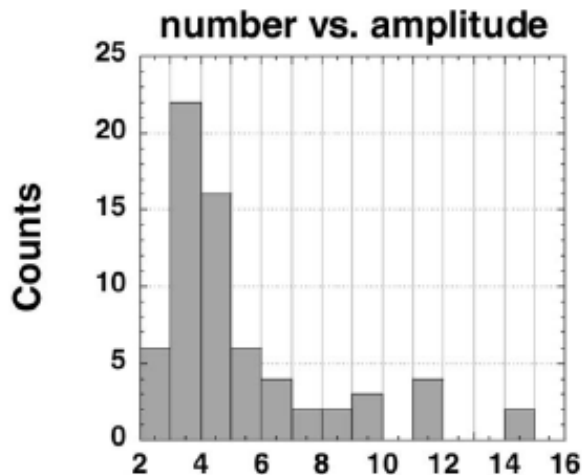
So far tested with hex-cell 3D's  
( $L=50\mu\text{m}$ ) & fast current amplifier



Best choice: trrenched detectors



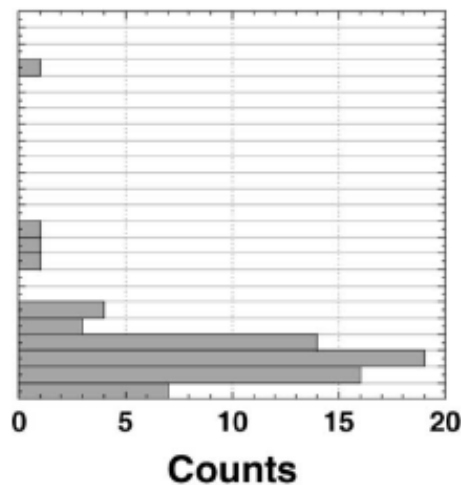
S. Parker et al. IEEE  
TNS 58(2) (2011) 404



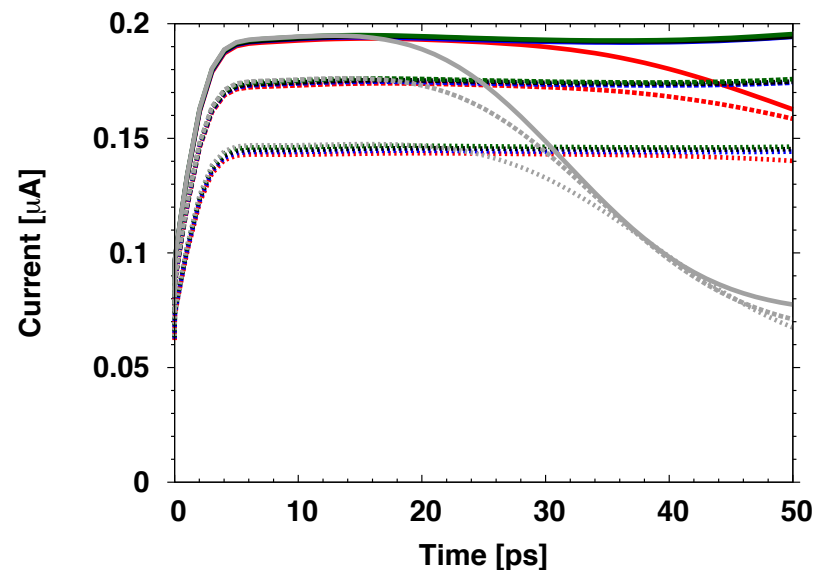
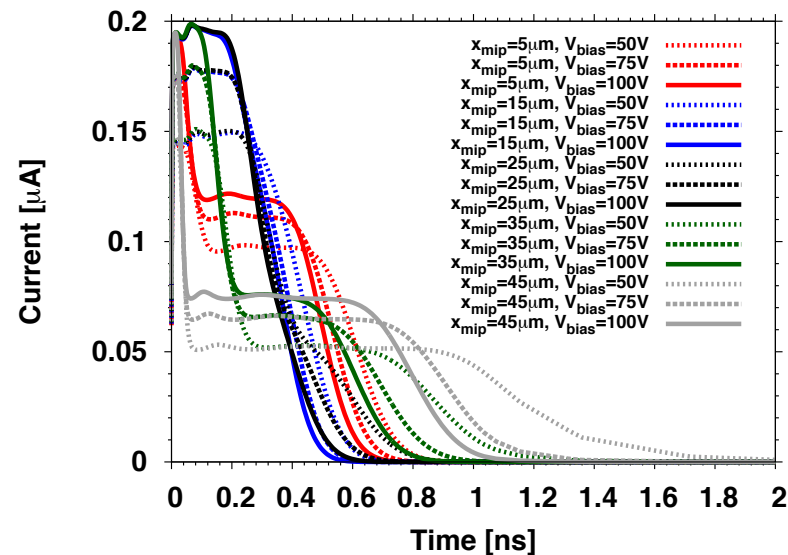
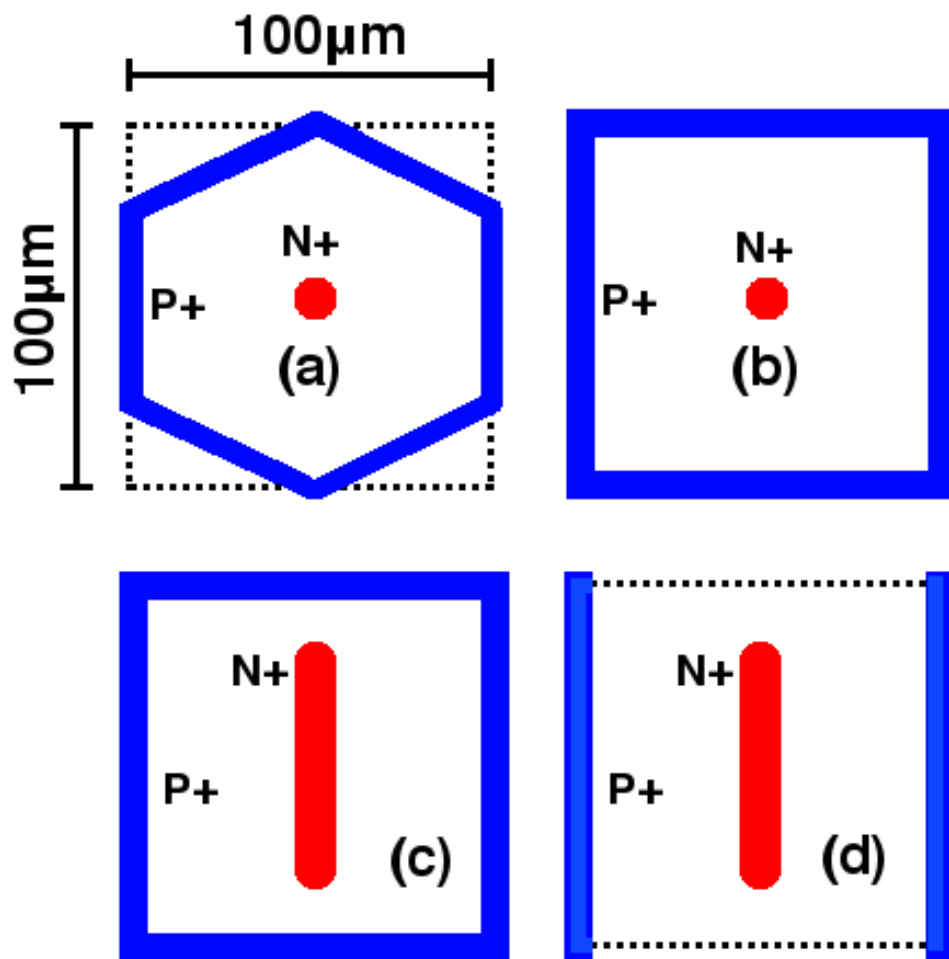
- Off-line analysis of recorded waveforms
- Timing resolution from 177 ps to 31ps
- Limited by front-end noise



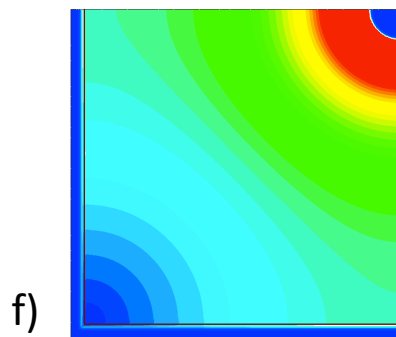
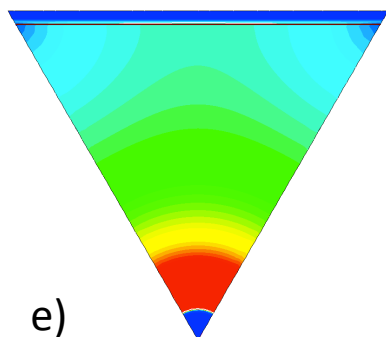
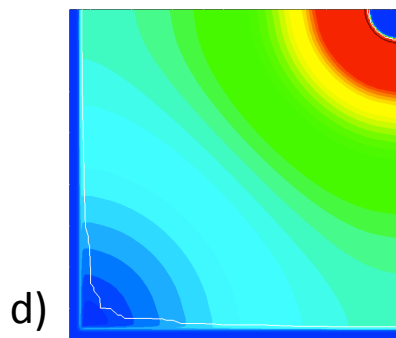
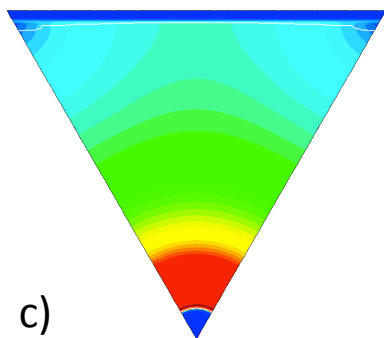
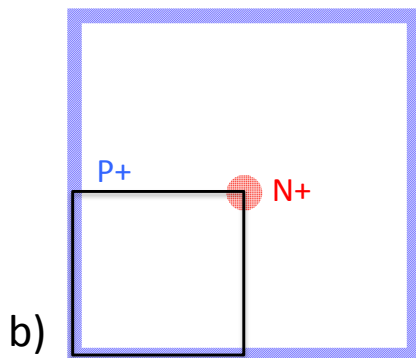
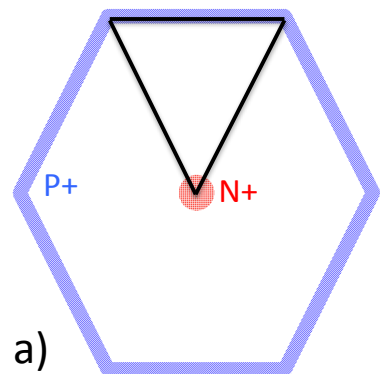
number vs. dt



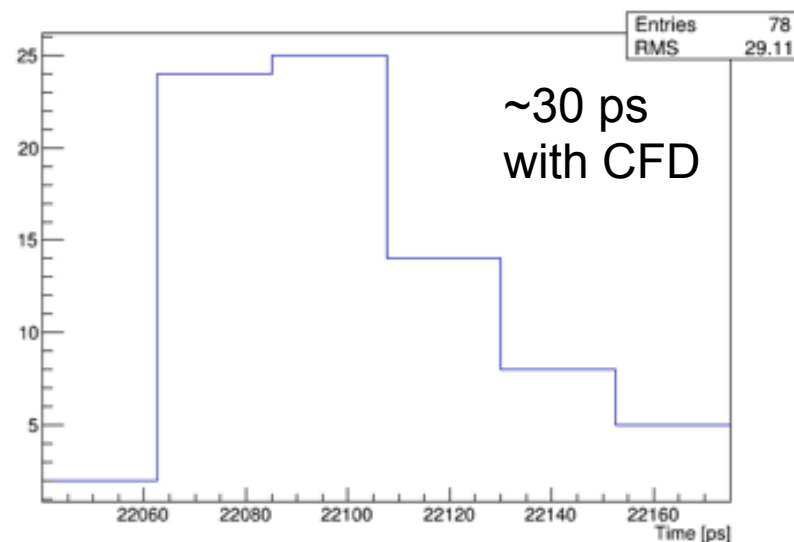
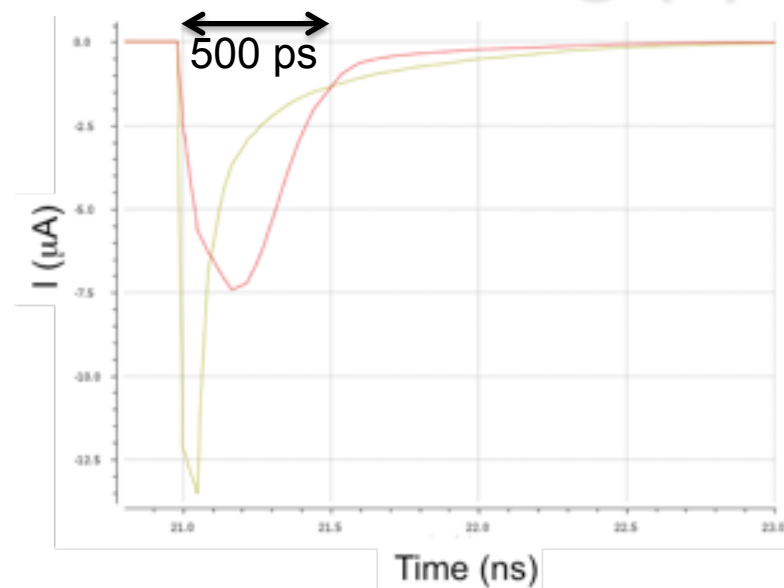
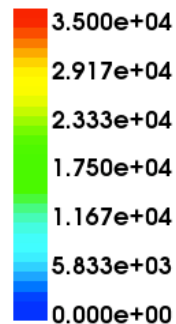
# New Trenched-3D pixels for timing (1)



# New Trenched-3D pixels for timing (2)



Electric  
Field  
Intensity  
(V/cm)





## Conclusions

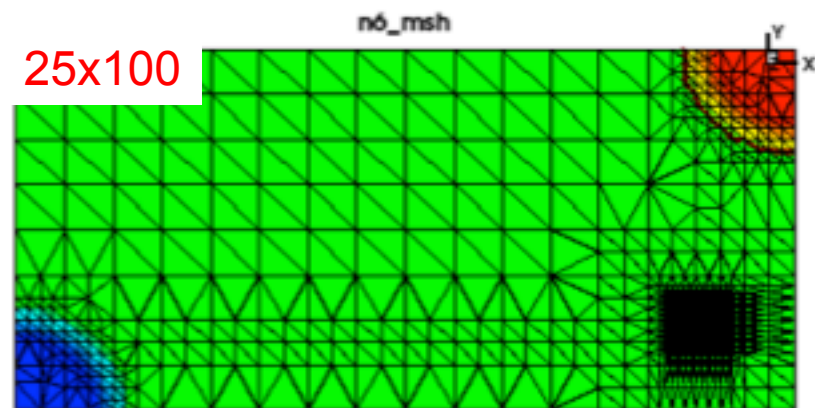
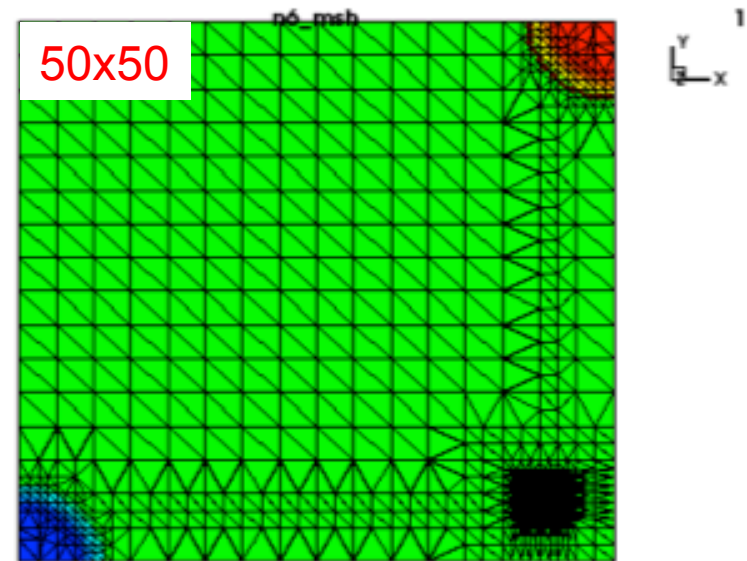
- Very impressive progress has been recently achieved in 3D radiation sensors, boosted by the ATLAS IBL project:
  - Experimental confirmation of superior radiation tolerance with relatively low power dissipation
  - Demonstration of medium volume productions
- These accomplishments paved the way for using 3D sensors in pixel detector upgrades at HL-LHC, for which a new generation of 3D pixels is being developed
- Despite their significant potential, 3D sensors fast signal properties have so far not been exploited.
- An R&D effort in this direction is worth, and it can partially benefit from on-going technological developments



# Back-Up Slides

# CCE simulation approach

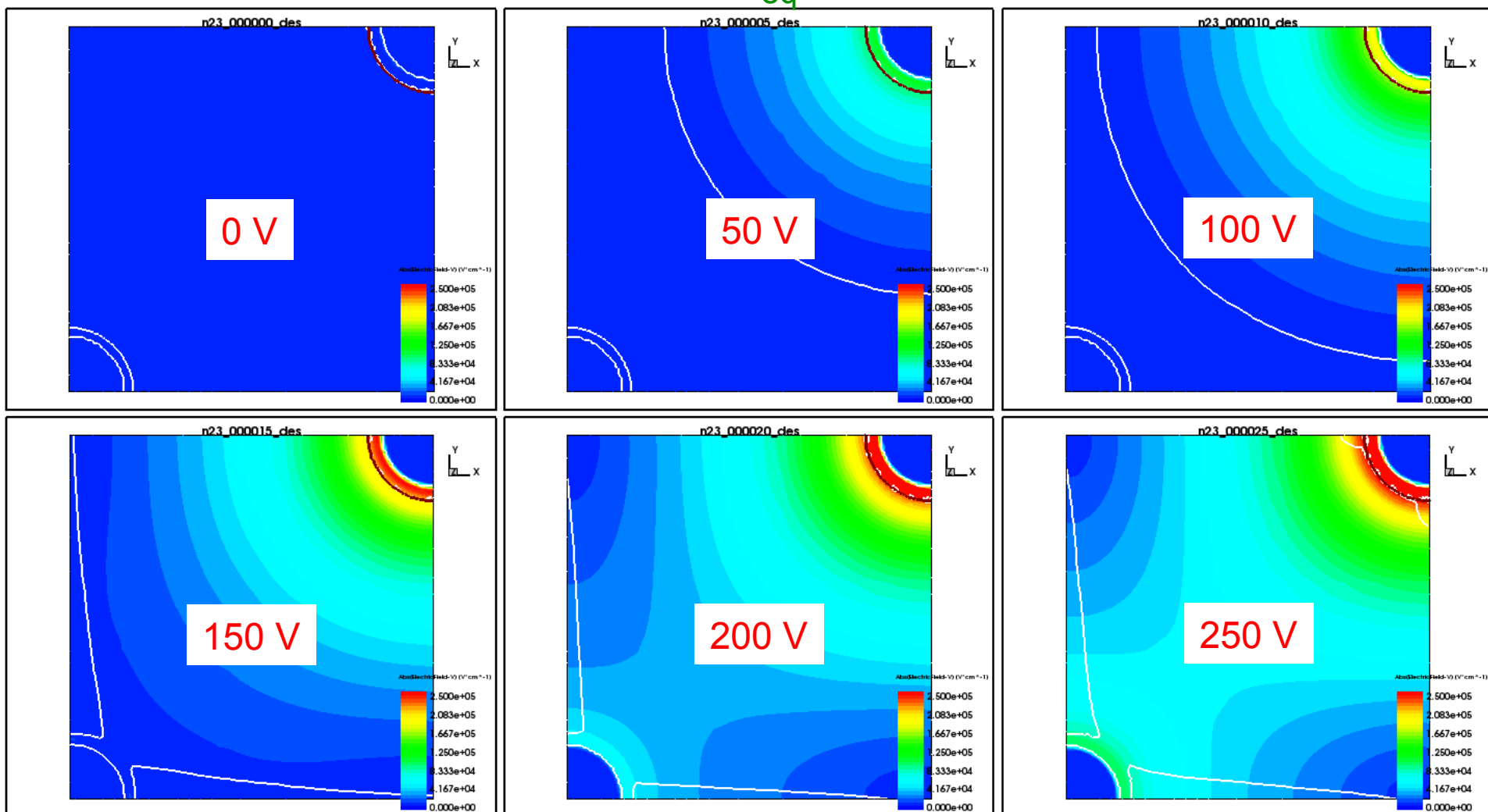
- Simplified simulation domain ( $\sim 2d$ ):  
1  $\mu\text{m}$  thick slice (1/4 or 1/8 of pixel)
- MIP (heavy ion model): vertical hits at several different positions evenly distributed and representing different electric field values
- Impact ionization model not active
- Avoiding boundaries: no charge sharing
- 20-ns integration of current signals
- Normalization to injected charge
- Repeat at different bias voltage
- Average charge over all hit positions





# 50x50: electric field 2d (preliminary)

$$2 \times 10^{16} n_{eq}/\text{cm}^2$$



# Charge multiplication by design in 3D sensors

Exploiting high fields in thin 3D structures with small inter-electrode spacing

*M. Povoli et. al.,  
To be published*

